

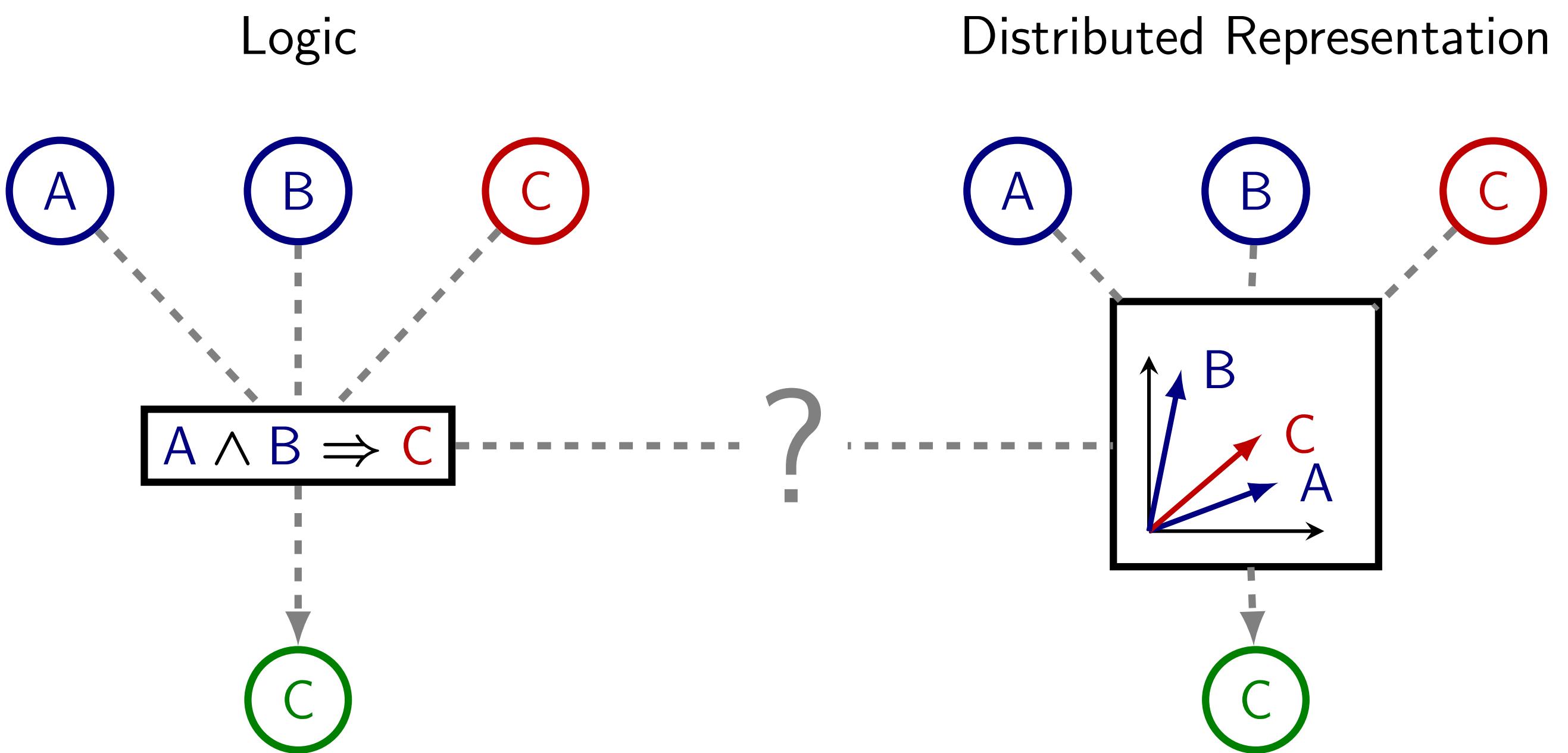
Low-dimensional Embeddings of Logic

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Motivation



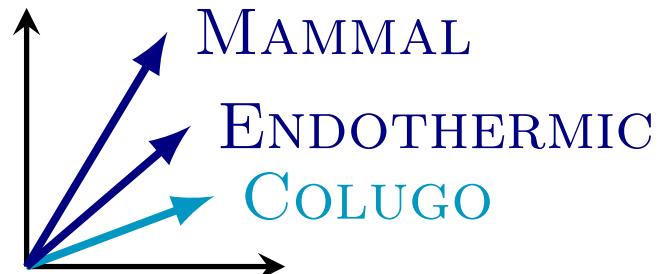
- Captures richness
- Supports complex reasoning
- Fails to generalize

- Enables generalization
- Very efficient
- Limited reasoning

Generalized Reasoning

- "Colugos are arboreal gliding mammals that are found in Southeast Asia."
- MAMMAL(COLUGO)
- "All mammals are endothermic."
- $\forall x : \text{MAMMAL}(x) \Rightarrow \text{ENDOTHERMIC}(x)$
- Reasoning...
- ENDOTHERMIC(COLUGO)

I wish I had a distributed model...



Debugging Distributed Representations

- "Colugos are arboreal gliding mammals that are found in Southeast Asia."
- MAMMAL(COLUGO)
- "All mammals are endothermic."
- $\forall x : \text{MAMMAL}(x) \Rightarrow \text{ENDOTHERMIC}(x)$
- Reasoning...
- ENDOTHERMIC(COLUGO)

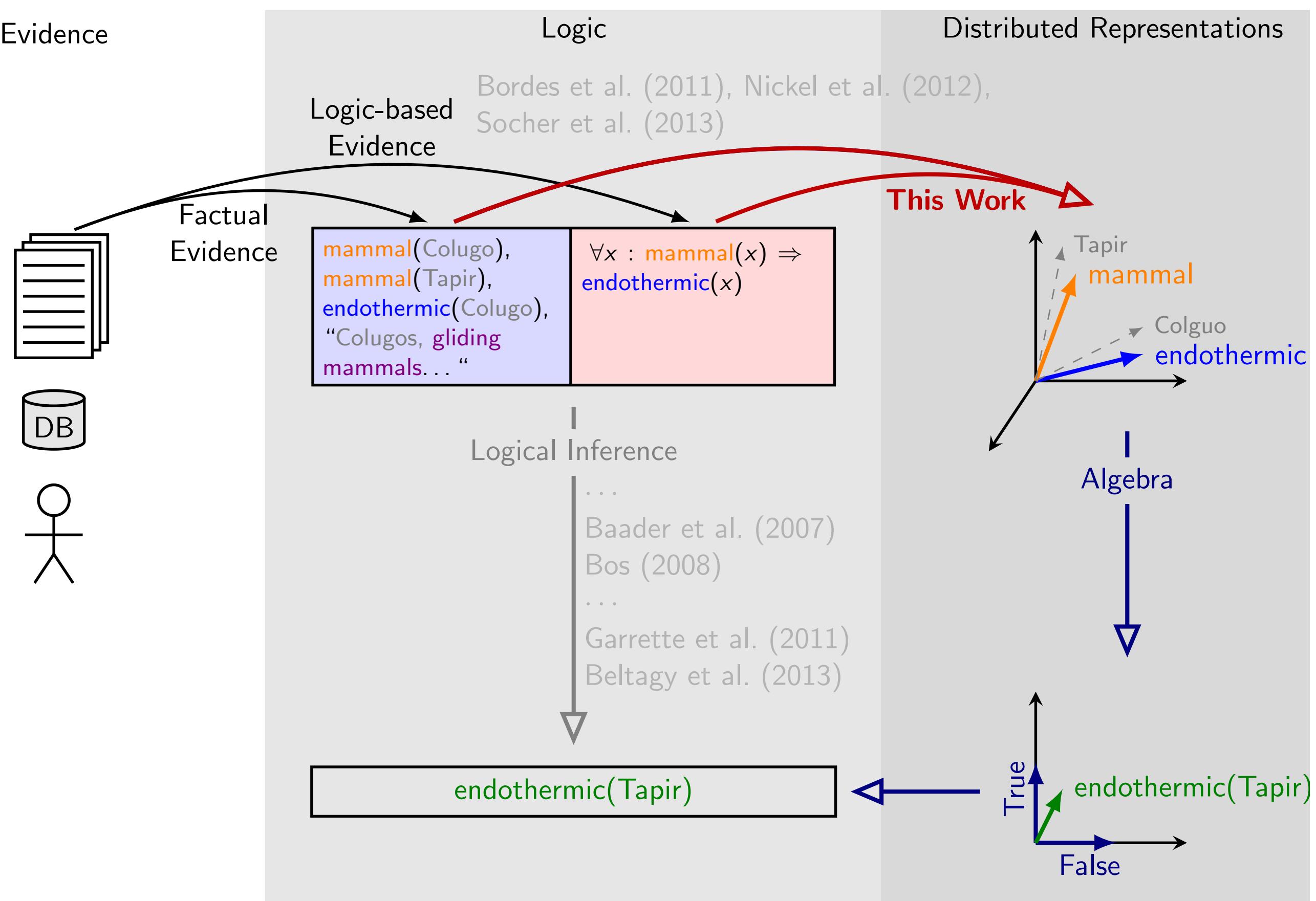
I wish I could fix this with...

$$\begin{aligned} \forall x : \text{HASFEATHERS}(x) &\Rightarrow \neg \text{MAMMAL}(x) \\ \forall x : \text{ANIMAL}(x) &\Rightarrow \text{ENDOTHERMIC}(x) \oplus \text{ECTOTHERMIC}(x) \end{aligned}$$

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Overview



Propositional Logic

Propositional Logic

Logic	Logical Tensor Calculus (Grefenstette, 2013)
[true]; [false]	$\begin{bmatrix} 1 \\ 0 \end{bmatrix}; \begin{bmatrix} 0 \\ 1 \end{bmatrix}$
[¬]; [∧]; [⇒]	$\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}; \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 \end{bmatrix}; \begin{bmatrix} 1 & 0 & 1 & 1 \\ 0 & 1 & 0 & 0 \end{bmatrix}$
[¬A]	$\begin{bmatrix} \neg A \end{bmatrix}$
[A ∧ B]	$\begin{bmatrix} A \end{bmatrix} \times_1 \begin{bmatrix} B \end{bmatrix}$
[A ⇒ B]	$\begin{bmatrix} A \end{bmatrix} \times_1 \begin{bmatrix} B \end{bmatrix}$
[A ∧ ¬B ⇒ ¬C]	$\begin{bmatrix} A \end{bmatrix} \times_1 (\begin{bmatrix} A \end{bmatrix} \times_2 \begin{bmatrix} \neg B \end{bmatrix}) \times_2 \begin{bmatrix} \neg C \end{bmatrix}$

Example

$$\begin{aligned} [\Rightarrow] \times_1 [\text{true}] \times_2 [\text{false}] &= \begin{bmatrix} 1 & 0 & 1 & 1 \\ 0 & 1 & 0 & 0 \end{bmatrix} \times_1 \begin{bmatrix} 1 \\ 0 \end{bmatrix} \times_2 \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \\ \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \times_2 \begin{bmatrix} 0 \\ 1 \end{bmatrix} &= \begin{bmatrix} 0 \\ 1 \end{bmatrix} = [\text{false}] \end{aligned}$$

Constants, Predicates, Quantifiers

	One-Hot Representation (Grefenstette, 2013)	Distributed Representation
[COLUGO]	$\begin{bmatrix} 0 & 0 & 1 & 0 & \dots & 0 & 0 \end{bmatrix}^T$	$\begin{bmatrix} ? & ? & ? \end{bmatrix}^T$
[MAMMAL]	$\begin{bmatrix} 0 & 0 & 1 & 0 & \dots & 0 & 1 \end{bmatrix}$	$\begin{bmatrix} ? & ? & ? \end{bmatrix}$
[MAMMAL(COLUGO)]	[MAMMAL][COLUGO]	[MAMMAL][COLUGO]
$\forall x \in X : F(x)$	$\begin{cases} [\text{true}] & \text{if } X = \{x \mid F(x) = [\text{true}]\} \\ [\text{false}] & \text{otherwise} \end{cases}$	$\frac{1}{ X } \sum_x [F(x)]$
$\exists x \in X : F(x)$	$\begin{cases} [\text{true}] & \text{if } \{x \mid F(x) = [\text{true}]\} > 0 \\ [\text{false}] & \text{otherwise} \end{cases}$	$[\neg \forall x \in X : \neg F(x)]$

Objective

$$\min_{[e] \in \mathcal{E}, [r] \in \mathcal{R}} \sum_{(Q, \gamma) \in \mathcal{K}} \mathcal{L}([Q], \gamma)$$

Toy Example

Before training		
MAMMAL	ENDOTHERMIC	VERTEBRATE
CHIMPANZEE	1.0	1.0
KOALA	1.0	1.0
COLUGO	1.0	?
KAGU	?	1.0
DODO	?	1.0

After training		
MAMMAL	ENDOTHERMIC	VERTEBRATE
CHIMPANZEE	1.0	1.0
KOALA	1.0	1.0
COLUGO	1.0	0.1
KAGU	0.1	0.9
DODO	0.1	1.0

After training with formulae

$\forall x \in X : [\Rightarrow] \times_1 ([\text{MAMMAL}][x]) \times_2 ([\text{ENDOTHERMIC}][x])$		
MAMMAL	ENDOTHERMIC	VERTEBRATE
CHIMPANZEE	1.0	0.9
KOALA	1.0	0.9
COLUGO	0.9	(0.1)
KAGU	0.1	1.0
DODO	0.0	1.0

Future Work

- What are the theoretical limits of embedding logical formulae in vector spaces?
- What are efficient ways of injecting quantified formulae without iterating over all elements of a domain?
- Can we provide provenance of proofs of answers?