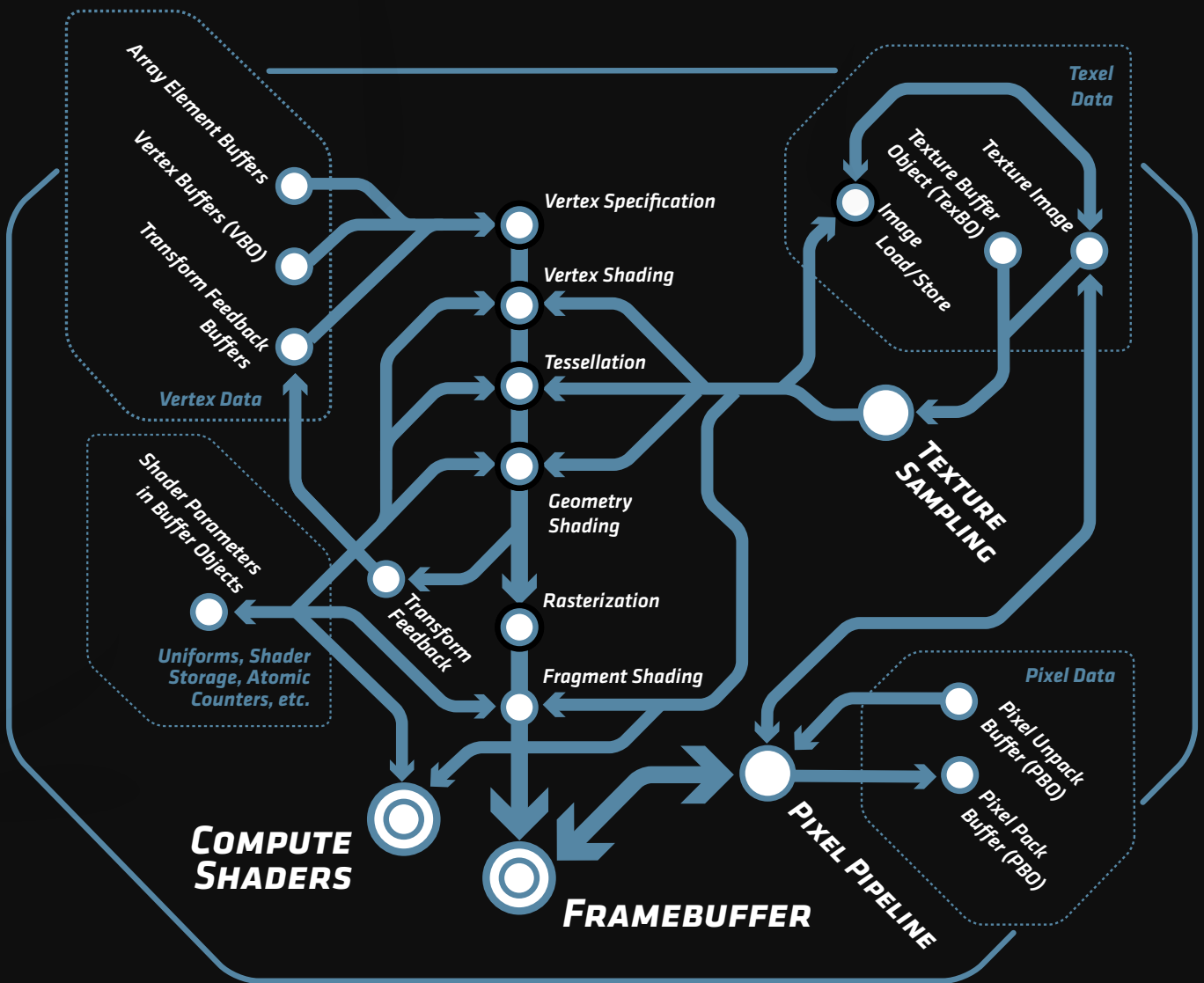


# OpenGL 4.3

CORE SPECIFICATION



The OpenGL<sup>®</sup> Graphics System:  
A Specification  
(Version 4.3 (Core Profile) - February 14, 2013)

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# Contents

<b>1</b>	<b>Introduction</b>	<b>1</b>
1.1	Formatting of the OpenGL Specification . . . . .	1
1.1.1	Formatting of the Compatibility Profile . . . . .	1
1.1.2	Formatting of Optional Features . . . . .	1
1.1.3	Formatting of Changes . . . . .	2
1.2	What is the OpenGL Graphics System? . . . . .	2
1.2.1	Programmer’s View of OpenGL . . . . .	2
1.2.2	Implementor’s View of OpenGL . . . . .	3
1.2.3	Our View . . . . .	3
1.2.4	Fixed-function Hardware and the Compatibility Profile . .	3
1.2.5	The Deprecation Model . . . . .	4
1.3	Related APIs . . . . .	4
1.3.1	OpenGL Shading Language . . . . .	4
1.3.2	OpenGL ES . . . . .	5
1.3.3	OpenGL ES Shading Language . . . . .	5
1.3.4	WebGL . . . . .	5
1.3.5	Window System Bindings . . . . .	6
1.3.6	OpenCL . . . . .	7
<b>2</b>	<b>OpenGL Fundamentals</b>	<b>8</b>
2.1	Execution Model . . . . .	8
2.2	Command Syntax . . . . .	10
2.2.1	Data Conversion For State-Setting Commands . . . . .	12
2.2.2	Data Conversions For State Query Commands . . . . .	14
2.3	Command Execution . . . . .	15
2.3.1	Errors . . . . .	15
2.3.2	Flush and Finish . . . . .	18
2.3.3	Numeric Representation and Computation . . . . .	18
2.3.4	Fixed-Point Data Conversions . . . . .	22

2.4	Context State . . . . .	23
2.4.1	Generic Context State Queries . . . . .	24
2.5	Objects and the Object Model . . . . .	24
2.5.1	Object Management . . . . .	25
2.5.2	Buffer Objects . . . . .	26
2.5.3	Shader Objects . . . . .	26
2.5.4	Program Objects . . . . .	26
2.5.5	Program Pipeline Objects . . . . .	26
2.5.6	Texture Objects . . . . .	27
2.5.7	Sampler Objects . . . . .	27
2.5.8	Renderbuffer Objects . . . . .	27
2.5.9	Framebuffer Objects . . . . .	28
2.5.10	Vertex Array Objects . . . . .	28
2.5.11	Transform Feedback Objects . . . . .	28
2.5.12	Query Objects . . . . .	28
2.5.13	Sync Objects . . . . .	28
2.5.14	Display Lists . . . . .	29
<b>3</b>	<b>Dataflow Model</b>	<b>30</b>
<b>4</b>	<b>Event Model</b>	<b>33</b>
4.1	Sync Objects and Fences . . . . .	33
4.1.1	Waiting for Sync Objects . . . . .	35
4.1.2	Signaling . . . . .	37
4.1.3	Sync Object Queries . . . . .	37
4.2	Query Objects and Asynchronous Queries . . . . .	38
4.2.1	Query Object Queries . . . . .	42
4.3	Time Queries . . . . .	45
<b>5</b>	<b>Shared Objects and Multiple Contexts</b>	<b>47</b>
5.1	Object Deletion Behavior . . . . .	47
5.1.1	Side Effects of Shared Context Destruction . . . . .	47
5.1.2	Automatic Unbinding of Deleted Objects . . . . .	48
5.1.3	Deleted Object and Object Name Lifetimes . . . . .	48
5.2	Sync Objects and Multiple Contexts . . . . .	49
5.3	Propagating Changes to Objects . . . . .	49
5.3.1	Determining Completion of Changes to an object . . . . .	50
5.3.2	Definitions . . . . .	50
5.3.3	Rules . . . . .	51

<b>6</b>	<b>Buffer Objects</b>	<b>53</b>
6.1	Creating and Binding Buffer Objects . . . . .	54
6.1.1	Binding Buffer Objects to Indexed Targets . . . . .	56
6.2	Creating and Modifying Buffer Object Data Stores . . . . .	57
6.2.1	Clearing Buffer Object Data Stores . . . . .	60
6.3	Mapping and Unmapping Buffer Data . . . . .	61
6.3.1	Unmapping Buffers . . . . .	65
6.3.2	Effects of Mapping Buffers on Other GL Commands . . . . .	66
6.4	Effects of Accessing Outside Buffer Bounds . . . . .	66
6.5	Invalidating Buffer Data . . . . .	66
6.6	Copying Between Buffers . . . . .	67
6.7	Buffer Object Queries . . . . .	68
6.7.1	Indexed Buffer Object Limits and Binding Queries . . . . .	69
6.8	Buffer Object State . . . . .	70
<b>7</b>	<b>Programs and Shaders</b>	<b>73</b>
7.1	Shader Objects . . . . .	74
7.2	Shader Binaries . . . . .	77
7.3	Program Objects . . . . .	78
7.3.1	Program Interfaces . . . . .	85
7.4	Program Pipeline Objects . . . . .	103
7.4.1	Shader Interface Matching . . . . .	106
7.4.2	Program Pipeline Object State . . . . .	108
7.5	Program Binaries . . . . .	109
7.6	Uniform Variables . . . . .	111
7.6.1	Loading Uniform Variables In The Default Uniform Block . . . . .	119
7.6.2	Uniform Blocks . . . . .	122
7.6.3	Uniform Buffer Object Bindings . . . . .	125
7.7	Atomic Counter Buffers . . . . .	126
7.7.1	Atomic Counter Buffer Object Storage . . . . .	127
7.7.2	Atomic Counter Buffer Bindings . . . . .	127
7.8	Shader Buffer Variables and Shader Storage Blocks . . . . .	128
7.9	Subroutine Uniform Variables . . . . .	130
7.10	Samplers . . . . .	133
7.11	Images . . . . .	134
7.12	Shader Memory Access . . . . .	135
7.12.1	Shader Memory Access Ordering . . . . .	135
7.12.2	Shader Memory Access Synchronization . . . . .	137
7.13	Shader, Program, and Program Pipeline Queries . . . . .	141
7.14	Required State . . . . .	149

<b>8</b>	<b>Textures and Samplers</b>	<b>152</b>
8.1	Texture Objects	153
8.2	Sampler Objects	156
8.3	Sampler Object Queries	159
8.4	Pixel Rectangles	159
8.4.1	Pixel Storage Modes and Pixel Buffer Objects	160
8.4.2	<del>The Imaging Subset</del>	161
8.4.3	<del>Pixel Transfer Modes</del>	161
8.4.4	Transfer of Pixel Rectangles	161
8.4.5	<del>Pixel Transfer Operations</del>	174
8.5	Texture Image Specification	174
8.5.1	Required Texture Formats	177
8.5.2	Encoding of Special Internal Formats	178
8.5.3	Texture Image Structure	182
8.6	Alternate Texture Image Specification Commands	187
8.6.1	Texture Copying Feedback Loops	195
8.7	Compressed Texture Images	195
8.8	Multisample Textures	202
8.9	Buffer Textures	203
8.10	Texture Parameters	207
8.11	Texture Queries	209
8.12	Depth Component Textures	214
8.13	Cube Map Texture Selection	214
8.13.1	Seamless Cube Map Filtering	215
8.14	Texture Minification	216
8.14.1	Scale Factor and Level of Detail	216
8.14.2	Coordinate Wrapping and Texel Selection	219
8.14.3	Mipmapping	223
8.14.4	Manual Mipmap Generation	225
8.14.5	<del>Automatic Mipmap Generation</del>	226
8.15	Texture Magnification	226
8.16	Combined Depth/Stencil Textures	227
8.17	Texture Completeness	227
8.17.1	Effects of Sampler Objects on Texture Completeness	228
8.17.2	Effects of Completeness on Texture Application	228
8.17.3	Effects of Completeness on Texture Image Specification	229
8.18	Texture Views	229
8.19	Immutable-Format Texture Images	233
8.20	Invalidating Texture Image Data	238
8.21	Texture State and Proxy State	239

8.22	Texture Comparison Modes . . . . .	241
8.22.1	Depth Texture Comparison Mode . . . . .	241
8.23	sRGB Texture Color Conversion . . . . .	242
8.24	Shared Exponent Texture Color Conversion . . . . .	243
8.25	Texture Image Loads and Stores . . . . .	244
<b>9</b>	<b>Framebuffer and Framebuffer Objects</b>	<b>252</b>
9.1	Framebuffer Overview . . . . .	252
9.2	Binding and Managing Framebuffer Objects . . . . .	254
9.2.1	Framebuffer Object Parameters . . . . .	257
9.2.2	Attaching Images to Framebuffer Objects . . . . .	258
9.2.3	Framebuffer Object Queries . . . . .	259
9.2.4	Renderbuffer Objects . . . . .	262
9.2.5	Required Renderbuffer Formats . . . . .	266
9.2.6	Renderbuffer Object Queries . . . . .	266
9.2.7	Attaching Renderbuffer Images to a Framebuffer . . . . .	267
9.2.8	Attaching Texture Images to a Framebuffer . . . . .	268
9.3	Feedback Loops Between Textures and the Framebuffer . . . . .	272
9.3.1	Rendering Feedback Loops . . . . .	273
9.3.2	Texture Copying Feedback Loops . . . . .	274
9.4	Framebuffer Completeness . . . . .	274
9.4.1	Framebuffer Attachment Completeness . . . . .	275
9.4.2	Whole Framebuffer Completeness . . . . .	276
9.4.3	Required Framebuffer Formats . . . . .	279
9.4.4	Effects of Framebuffer Completeness on Framebuffer Operations . . . . .	279
9.4.5	Effects of Framebuffer State on Framebuffer Dependent Values . . . . .	280
9.5	Mapping between Pixel and Element in Attached Image . . . . .	280
9.6	Conversion to Framebuffer-Attachable Image Components . . . . .	281
9.7	Conversion to RGBA Values . . . . .	281
9.8	Layered Framebuffers . . . . .	281
<b>10</b>	<b>Vertex Specification and Drawing Commands</b>	<b>284</b>
10.1	Primitive Types . . . . .	286
10.1.1	Points . . . . .	286
10.1.2	Line Strips . . . . .	286
10.1.3	Line Loops . . . . .	286
10.1.4	Separate Lines . . . . .	286
10.1.5	Polygons . . . . .	287



10.1.6	Triangle Strips . . . . .	287
10.1.7	Triangle Fans . . . . .	288
10.1.8	Separate Triangles . . . . .	288
10.1.9	Quadrilateral (quad) strips . . . . .	288
10.1.10	Separate Quadrilaterals . . . . .	288
10.1.11	Lines with Adjacency . . . . .	288
10.1.12	Line Strips with Adjacency . . . . .	290
10.1.13	Triangles with Adjacency . . . . .	290
10.1.14	Triangle Strips with Adjacency . . . . .	291
10.1.15	Separate Patches . . . . .	292
10.1.16	General Considerations For Polygon Primitives . . . . .	293
10.1.17	Polygon Edges . . . . .	293
10.2	Current Vertex Attribute Values . . . . .	293
10.2.1	Current Generic Attributes . . . . .	293
10.2.2	<del>Current Conventional Attributes</del> . . . . .	295
10.2.3	Vertex Attribute Queries . . . . .	295
10.2.4	Required State . . . . .	296
10.3	Vertex Arrays . . . . .	296
10.3.1	Specifying Arrays for Generic Vertex Attributes . . . . .	296
10.3.2	<del>Specifying Arrays for Fixed-Function Attributes</del> . . . . .	300
10.3.3	Vertex Attribute Divisors . . . . .	300
10.3.4	Transferring Array Elements . . . . .	301
10.3.5	Primitive Restart . . . . .	301
10.3.6	Robust Buffer Access . . . . .	302
10.3.7	Packed Vertex Data Formats . . . . .	303
10.3.8	Vertex Arrays in Buffer Objects . . . . .	303
10.3.9	Array Indices in Buffer Objects . . . . .	304
10.3.10	Indirect Commands in Buffer Objects . . . . .	305
10.4	Vertex Array Objects . . . . .	305
10.5	Drawing Commands Using Vertex Arrays . . . . .	307
10.5.1	<del>Interleaved Arrays</del> . . . . .	317
10.6	Vertex Array and Vertex Array Object Queries . . . . .	317
10.7	Required State . . . . .	318
10.8	<del>Drawing Commands Using <b>Begin</b> and <b>End</b></del> . . . . .	319
10.9	<del>Rectangles</del> . . . . .	319
10.10	Conditional Rendering . . . . .	319

<b>11 Programmable Vertex Processing</b>	<b>321</b>
11.1 Vertex Shaders	321
11.1.1 Vertex Attributes	321
11.1.2 Vertex Shader Variables	326
11.1.3 Shader Execution	330
11.2 Tessellation	340
11.2.1 Tessellation Control Shaders	341
11.2.2 Tessellation Primitive Generation	346
11.2.3 Tessellation Evaluation Shaders	355
11.3 Geometry Shaders	360
11.3.1 Geometry Shader Input Primitives	361
11.3.2 Geometry Shader Output Primitives	362
11.3.3 Geometry Shader Variables	363
11.3.4 Geometry Shader Execution Environment	363
<b>12 Fixed-Function Vertex Processing</b>	<b>370</b>
<b>13 Fixed-Function Vertex Post-Processing</b>	<b>371</b>
13.1 Clamping or Masking	371
13.2 Transform Feedback	372
13.2.1 Transform Feedback Objects	372
13.2.2 Transform Feedback Primitive Capture	374
13.2.3 Transform Feedback Draw Operations	379
13.3 Primitive Queries	380
13.4 Flatshading	381
13.5 Primitive Clipping	382
13.5.1 Clipping Shader Outputs	383
13.5.2 Clip Plane Queries	384
13.6 Coordinate Transformations	384
13.6.1 Controlling the Viewport	385
13.7 Final Color Processing	388
<b>14 Fixed-Function Primitive Assembly and Rasterization</b>	<b>389</b>
14.1 Discarding Primitives Before Rasterization	390
14.2 Invariance	391
14.3 Antialiasing	391
14.3.1 Multisampling	392
14.4 Points	395
14.4.1 Basic Point Rasterization	396
14.4.2 Point Rasterization State	397

14.4.3	Point Multisample Rasterization . . . . .	397
14.5	Line Segments . . . . .	397
14.5.1	Basic Line Segment Rasterization . . . . .	398
14.5.2	Other Line Segment Features . . . . .	400
14.5.3	Line Rasterization State . . . . .	402
14.5.4	Line Multisample Rasterization . . . . .	403
14.6	Polygons . . . . .	403
14.6.1	Basic Polygon Rasterization . . . . .	403
14.6.2	Stippling . . . . .	406
14.6.3	Antialiasing . . . . .	406
14.6.4	Options Controlling Polygon Rasterization . . . . .	406
14.6.5	Depth Offset . . . . .	407
14.6.6	Polygon Multisample Rasterization . . . . .	408
14.6.7	Polygon Rasterization State . . . . .	409
14.7	Current Raster Position . . . . .	409
14.8	Bitmaps . . . . .	409
14.9	Early Per-Fragment Tests . . . . .	409
<b>15</b>	<b>Programmable Fragment Processing</b>	<b>411</b>
15.1	Fragment Shader Variables . . . . .	411
15.2	Shader Execution . . . . .	412
15.2.1	Texture Access . . . . .	413
15.2.2	Shader Inputs . . . . .	414
15.2.3	Shader Outputs . . . . .	417
15.2.4	Early Fragment Tests . . . . .	420
<b>16</b>	<b>Fixed-Function Fragment Processing</b>	<b>421</b>
<b>17</b>	<b>Writing Fragments and Samples to the Framebuffer</b>	<b>422</b>
17.1	Antialiasing Application . . . . .	422
17.2	Multisample Point Fade . . . . .	422
17.3	Per-Fragment Operations . . . . .	423
17.3.1	Pixel Ownership Test . . . . .	423
17.3.2	Scissor Test . . . . .	424
17.3.3	Multisample Fragment Operations . . . . .	426
17.3.4	Alpha Test . . . . .	428
17.3.5	Stencil Test . . . . .	428
17.3.6	Depth Buffer Test . . . . .	429
17.3.7	Occlusion Queries . . . . .	430
17.3.8	Blending . . . . .	431

17.3.9	sRGB Conversion	438
17.3.10	Dithering	438
17.3.11	Logical Operation	439
17.3.12	Additional Multisample Fragment Operations	441
17.4	Whole Framebuffer Operations	442
17.4.1	Selecting Buffers for Writing	442
17.4.2	Fine Control of Buffer Updates	446
17.4.3	Clearing the Buffers	448
17.4.4	Invalidating Framebuffer Contents	451
17.4.5	The Accumulation Buffer	452
<b>18</b>	<b>Reading and Copying Pixels</b>	<b>453</b>
18.1	Drawing Pixels	453
18.2	Reading Pixels	453
18.2.1	Obtaining Pixels from the Framebuffer	454
18.2.2	Conversion of RGBA values	457
18.2.3	Conversion of Depth values	457
18.2.4	Pixel Transfer Operations	458
18.2.5	Conversion to L	458
18.2.6	Final Conversion	458
18.2.7	Placement in Pixel Pack Buffer or Client Memory	459
18.3	Copying Pixels	461
18.3.1	Blitting Pixel Rectangles	461
18.3.2	Copying Between Images	464
18.4	Pixel Draw and Read State	467
<b>19</b>	<b>Compute Shaders</b>	<b>468</b>
19.1	Compute Shader Variables	470
<b>20</b>	<b>Debug Output</b>	<b>471</b>
20.1	Debug Messages	472
20.2	Debug Message Callback	474
20.3	Debug Message Log	475
20.4	Controlling Debug Messages	475
20.5	Externally Generated Messages	477
20.6	Debug Groups	477
20.7	Debug Labels	479
20.8	Asynchronous and Synchronous Debug Output	480
20.9	Debug Output Queries	481

<b>21 Special Functions</b>	<b>484</b>
21.1 Evaluators . . . . .	484
21.2 Selection . . . . .	484
21.3 Feedback . . . . .	484
21.4 Display Lists . . . . .	484
21.5 Hints . . . . .	484
21.6 Saving and Restoring State . . . . .	485
<b>22 Context State Queries</b>	<b>486</b>
22.1 Simple Queries . . . . .	486
22.2 String Queries . . . . .	488
22.3 Internal Format Queries . . . . .	490
<b>23 State Tables</b>	<b>504</b>
<b>A Invariance</b>	<b>579</b>
A.1 Repeatability . . . . .	579
A.2 Multi-pass Algorithms . . . . .	580
A.3 Invariance Rules . . . . .	580
A.4 Tessellation Invariance . . . . .	582
A.5 Atomic Counter Invariance . . . . .	584
A.6 What All This Means . . . . .	585
<b>B Corollaries</b>	<b>586</b>
<b>C Compressed Texture Image Formats</b>	<b>588</b>
C.1 RGTC Compressed Texture Image Formats . . . . .	588
C.1.1 Format COMPRESSED_RED_RGTC1 . . . . .	589
C.1.2 Format COMPRESSED_SIGNED_RED_RGTC1 . . . . .	590
C.1.3 Format COMPRESSED_RG_RGTC2 . . . . .	590
C.1.4 Format COMPRESSED_SIGNED_RG_RGTC2 . . . . .	591
C.2 BPTC Compressed Texture Image Formats . . . . .	591
C.2.1 Formats COMPRESSED_RGBA_BPTC_UNORM and COMPRESSED_SRGB_ALPHA_BPTC_UNORM . . . . .	592
C.2.2 Formats COMPRESSED_RGB_BPTC_SIGNED_FLOAT and COMPRESSED_RGB_BPTC_UNSIGNED_FLOAT . . . . .	598
C.3 ETC Compressed Texture Image Formats . . . . .	600
C.3.1 Format COMPRESSED_RGB8_ETC2 . . . . .	604
C.3.2 Format COMPRESSED_SRGB8_ETC2 . . . . .	611
C.3.3 Format COMPRESSED_RGBA8_ETC2_EAC . . . . .	611

C.3.4	Format COMPRESSED_SRGB8_ALPHA8_ETC2_EAC . . . . .	614
C.3.5	Format COMPRESSED_R11_EAC . . . . .	614
C.3.6	Format COMPRESSED_RG11_EAC . . . . .	617
C.3.7	Format COMPRESSED_SIGNED_R11_EAC . . . . .	618
C.3.8	Format COMPRESSED_SIGNED_RG11_EAC . . . . .	621
C.3.9	Format COMPRESSED_RGB8_PUNCHTHROUGH_ALPHA1_ETC2 . . . . .	621
C.3.10	Format COMPRESSED_SRGB8_PUNCHTHROUGH_ALPHA1_ETC2 . . . . .	628
<b>D</b>	<b>Profiles and the Deprecation Model</b>	<b>629</b>
D.1	Core and Compatibility Profiles . . . . .	630
D.2	Deprecated and Removed Features . . . . .	630
D.2.1	Deprecated But Still Supported Features . . . . .	630
D.2.2	Removed Features . . . . .	631
<b>E</b>	<b>Version 4.2</b>	<b>636</b>
E.1	New Features . . . . .	636
E.2	Deprecation Model . . . . .	637
E.3	Changed Tokens . . . . .	637
E.4	Change Log for Released Specifications . . . . .	638
E.5	Credits and Acknowledgements . . . . .	640
<b>F</b>	<b>Version 4.3</b>	<b>643</b>
F.1	Restructuring . . . . .	643
F.2	New Features . . . . .	644
F.3	Deprecation Model . . . . .	645
F.4	Changed Tokens . . . . .	645
F.5	Change Log for Released Specifications . . . . .	646
F.6	Credits . . . . .	653
F.7	Acknowledgements . . . . .	655
<b>G</b>	<b>OpenGL Registry, Header Files, and ARB Extensions</b>	<b>656</b>
G.1	OpenGL Registry . . . . .	656
G.2	Header Files . . . . .	656
G.3	ARB and Khronos Extensions . . . . .	657
G.3.1	Naming Conventions . . . . .	658
G.3.2	Promoting Extensions to Core Features . . . . .	658
G.3.3	Extension Summaries . . . . .	658

# List of Figures

3.1	Block diagram of the GL pipeline. . . . .	31
8.1	Transfer of pixel rectangles. . . . .	161
8.2	Selecting a subimage from an image . . . . .	166
8.3	A texture image and the coordinates used to access it. . . . .	187
8.4	Example of the components returned for <code>textureGather</code> . . . . .	221
10.1	Vertex processing and primitive assembly. . . . .	284
10.2	Triangle strips, fans, and independent triangles. . . . .	287
10.3	Lines with adjacency. . . . .	288
10.4	Triangles with adjacency. . . . .	290
10.5	Triangle strips with adjacency. . . . .	291
11.1	Domain parameterization for tessellation. . . . .	347
11.2	Inner triangle tessellation. . . . .	350
11.3	Inner quad tessellation. . . . .	353
11.4	Isoline tessellation. . . . .	355
14.1	Rasterization. . . . .	389
14.2	Visualization of Bresenham’s algorithm. . . . .	398
14.3	Rasterization of non-antialiased wide lines. . . . .	401
14.4	The region used in rasterizing an antialiased line segment. . . . .	402
17.1	Per-fragment operations. . . . .	423
18.1	Operation of <b>ReadPixels</b> . . . . .	453

# List of Tables

2.1	GL command suffixes . . . . .	12
2.2	GL data types . . . . .	13
2.3	Summary of GL errors . . . . .	17
4.1	Initial properties of a sync object created with <b>FenceSync</b> . . . . .	34
6.1	Buffer object binding targets. . . . .	55
6.2	Buffer object parameters and their values. . . . .	55
6.3	Buffer object initial state. . . . .	59
6.4	Buffer object state set by <b>MapBufferRange</b> . . . . .	63
6.5	Indexed buffer object limits and binding queries . . . . .	71
7.1	<b>CreateShader</b> <i>type</i> values and the corresponding shader stages. . . . .	75
7.2	<b>GetProgramResourceiv</b> properties and supported interfaces . . . . .	94
7.3	OpenGL Shading Language type tokens . . . . .	98
7.4	Query targets for default uniform block storage, in components. . . . .	112
7.5	Query targets for combined uniform block storage, in components. . . . .	113
7.6	<b>GetProgramResourceiv</b> properties used by <b>GetActiveUniformsiv</b> . . . . .	116
7.7	<b>GetProgramResourceiv</b> properties used by <b>GetActiveUniform-Blockiv</b> . . . . .	117
7.8	<b>GetProgramResourceiv</b> properties used by <b>GetActiveAtomic-CounterBufferiv</b> . . . . .	118
7.9	Interfaces for active subroutines . . . . .	131
7.10	Interfaces for active subroutine uniforms . . . . .	131
8.1	<b>PixelStore</b> parameters. . . . .	160
8.2	Pixel data types. . . . .	163
8.3	Pixel data formats. . . . .	164
8.4	Swap Bytes bit ordering. . . . .	165
8.5	Packed pixel formats. . . . .	168



8.6	UNSIGNED_BYTE formats. Bit numbers are indicated for each component. . . . .	169
8.7	UNSIGNED_SHORT formats . . . . .	170
8.8	UNSIGNED_INT formats . . . . .	171
8.9	FLOAT_UNSIGNED_INT formats . . . . .	172
8.10	Packed pixel field assignments. . . . .	173
8.11	Conversion from RGBA, depth, and stencil pixel components to internal texture components. . . . .	176
8.12	Sized internal color formats. . . . .	181
8.13	Sized internal depth and stencil formats. . . . .	182
8.14	Generic and specific compressed internal formats. . . . .	183
8.15	Internal formats for buffer textures . . . . .	206
8.16	Texture parameters and their values. . . . .	208
8.17	Texture, table, and filter return values. . . . .	213
8.18	Selection of cube map images. . . . .	215
8.19	Texel location wrap mode application. . . . .	220
8.20	Legal texture targets for <b>TextureView</b> . . . . .	230
8.21	Compatible internal formats for <b>TextureView</b> . . . . .	231
8.22	Depth texture comparison functions. . . . .	242
8.23	sRGB texture internal formats. . . . .	243
8.24	Mapping of image load, store, and atomic texel coordinate components to texel numbers. . . . .	246
8.25	Supported image unit formats, with equivalent format layout qualifiers. . . . .	249
8.26	Texel sizes, compatibility classes, and pixel format/type combinations for each image format. . . . .	251
9.1	Correspondence of renderbuffer sized to base internal formats. . . . .	265
9.2	Framebuffer attachment points. . . . .	268
9.3	Layer numbers for cube map texture faces. . . . .	283
10.1	Triangles generated by triangle strips with adjacency. . . . .	292
10.2	Vertex array sizes (values per vertex) and data types for generic vertex attributes . . . . .	297
10.3	Packed component layout for non-BGRA formats. . . . .	303
10.4	Packed component layout for BGRA format. . . . .	303
11.1	Scalar and vector vertex attribute types . . . . .	322
13.1	Transform feedback modes . . . . .	376
13.2	Provoking vertex selection. . . . .	381

15.1 Correspondence of filtered texture components to texture base components. . . . .	414
17.1 RGB and alpha blend equations. . . . .	434
17.2 Blending functions. . . . .	436
17.3 Logical operations . . . . .	440
17.4 Buffer selection for the default framebuffer . . . . .	443
17.5 Buffer selection for a framebuffer object . . . . .	444
17.6 <b>DrawBuffers</b> buffer selection for the default framebuffer . . . . .	444
18.1 <b>PixelStore</b> parameters. . . . .	455
18.2 <b>ReadPixels</b> GL data types and reversed component conversion formulas. . . . .	460
18.3 <b>ReadPixels</b> index masks. . . . .	461
18.4 Compatible internal formats for copying . . . . .	466
20.1 Sources of debug output messages . . . . .	472
20.2 Types of debug output messages . . . . .	473
20.3 Severity levels of messages . . . . .	473
20.4 Object namespace identifiers . . . . .	479
21.1 Hint targets and descriptions . . . . .	485
22.1 Context profile bits . . . . .	489
22.2 Internal format targets . . . . .	491
23.1 State Variable Types . . . . .	505
23.2 Current Values and Associated Data . . . . .	506
23.3 Vertex Array Object State (cont.) . . . . .	507
23.4 Vertex Array Object State (cont.) † The $i$ th attribute defaults to a value of $i$ . . . . .	508
23.5 Vertex Array Data (not in Vertex Array objects) . . . . .	509
23.6 Buffer Object State . . . . .	510
23.7 Transformation state . . . . .	511
23.8 Coloring . . . . .	512
23.9 Rasterization . . . . .	513
23.10 Rasterization (cont.) . . . . .	514
23.11 Multisampling . . . . .	515
23.12 Textures (state per texture unit) . . . . .	516
23.13 Textures (state per texture unit (cont.) . . . . .	517
23.14 Textures (state per texture object) . . . . .	518

23.15	Textures (state per texture object) (cont.) . . . . .	519
23.16	Textures (state per texture image) . . . . .	520
23.17	Textures (state per texture image) (cont.) . . . . .	521
23.18	Textures (state per sampler object) . . . . .	522
23.19	Texture Environment and Generation . . . . .	523
23.20	Pixel Operations . . . . .	524
23.21	Pixel Operations (cont.) . . . . .	525
23.22	Framebuffer Control . . . . .	526
23.23	Framebuffer (state per target binding point) . . . . .	527
23.24	Framebuffer (state per framebuffer object)	
	† This state is queried from the currently bound read framebuffer.	528
23.25	Framebuffer (state per attachment point) . . . . .	529
23.26	Renderbuffer (state per target and binding point) . . . . .	530
23.27	Renderbuffer (state per renderbuffer object) . . . . .	531
23.28	Pixels . . . . .	532
23.29	Pixels (cont.) . . . . .	533
23.30	Shader Object State . . . . .	534
23.31	Program Pipeline Object State . . . . .	535
23.32	Program Object State . . . . .	536
23.33	Program Object State (cont.) . . . . .	537
23.34	Program Object State (cont.) . . . . .	538
23.35	Program Object State (cont.) . . . . .	539
23.36	Program Object State (cont.) . . . . .	540
23.37	Program Object State (cont.) . . . . .	541
23.38	Program Object State (cont.) . . . . .	542
23.39	Program Object State (cont.) . . . . .	543
23.40	Program Interface State . . . . .	544
23.41	Program Object Resource State . . . . .	545
23.42	Program Object Resource State (cont.) . . . . .	546
23.43	Vertex and Geometry Shader State (not part of program objects) . . . . .	547
23.44	Query Object State . . . . .	548
23.45	Image State (state per image unit) . . . . .	549
23.46	Atomic Counter Buffer Binding State . . . . .	550
23.47	Shader Storage Buffer Binding State . . . . .	551
23.48	Transform Feedback State . . . . .	552
23.49	Uniform Buffer Binding State . . . . .	553
23.50	Sync (state per sync object) . . . . .	554
23.51	Hints . . . . .	555
23.52	Compute Dispatch State . . . . .	556
23.53	Implementation Dependent Values . . . . .	557

23.54	Implementation Dependent Values (cont.) . . . . .	558
23.55	Implementation Dependent Values (cont.) . . . . .	559
23.56	Implementation Dependent Version and Extension Support . . . . .	560
23.57	Implementation Dependent Vertex Shader Limits . . . . .	561
23.58	Implementation Dependent Tessellation Shader Limits . . . . .	562
23.59	Implementation Dependent Tessellation Shader Limits (cont.) . . . . .	563
23.60	Implementation Dependent Geometry Shader Limits . . . . .	564
23.61	Implementation Dependent Fragment Shader Limits . . . . .	565
23.62	Implementation Dependent Compute Shader Limits . . . . .	566
23.63	Implementation Dependent Aggregate Shader Limits . . . . .	567
23.64	Implementation Dependent Aggregate Shader Limits (cont.) . . . . .	568
23.65	Implementation Dependent Aggregate Shader Limits (cont.) . . . . .	569
23.66	Implementation Dependent Aggregate Shader Limits (cont.) † The minimum value for each stage is $\text{MAX\_stage\_UNIFORM\_BLOCKS} \times \text{MAX\_UNIFORM\_BLOCK\_SIZE}$ $/ 4 + \text{MAX\_stage\_UNIFORM\_COMPONENTS}$ . . . . .	570
23.67	Debug Output State	571
	† The initial value of <code>DEBUG_OUTPUT</code> is <code>TRUE</code> in a debug context and <code>FALSE</code> in a non-debug context. . . . .	571
23.68	Implementation Dependent Debug Output State . . . . .	572
23.69	Implementation Dependent Values (cont.) . . . . .	573
23.70	Implementation Dependent Values (cont.) . . . . .	574
23.71	Internal Format Dependent Values . . . . .	575
23.72	Implementation Dependent Transform Feedback Limits . . . . .	576
23.73	Framebuffer Dependent Values . . . . .	577
23.74	Miscellaneous . . . . .	578
C.1	Mode-dependent BPTC parameters . . . . .	594
C.2	Partition table for 2 subset . . . . .	595
C.3	Partition table for 3 subset . . . . .	596
C.4	Anchor index values for the second subset of two-subset partitioning . . . . .	597
C.5	Anchor index values for the second subset of three-subset partitioning . . . . .	597
C.6	Anchor index values for the third subset of three-subset partitioning . . . . .	597
C.7	Endpoint and partition parameters for block modes . . . . .	600
C.8	Block formats for block modes . . . . .	601
C.9	Pixel layout for a $8 \times 8$ texture using four <code>COMPRESSED_RGB8_ETC2</code> compressed blocks. . . . .	603
C.10	Pixel layout for an <code>COMPRESSED_RGB8_ETC2</code> compressed block. . . . .	605
C.11	Texel Data format for <code>RGB8_ETC2</code> compressed textures formats . . . . .	606
C.12	Two $2 \times 4$ -pixel subblocks side-by-side. . . . .	607

C.13	Two $4 \times 2$ -pixel subblocks on top of each other. . . . .	607
C.14	Intensity modifier sets for ‘individual’ and ‘differential’ modes: . .	608
C.15	Mapping from pixel index values to modifier values for COMPRESSED_RGB8_ETC2 compressed textures . . . . .	609
C.16	Distance table for ‘T’ and ‘H’ modes. . . . .	610
C.17	Texel Data format for alpha part of COMPRESSED_RGBA8_ETC2_- EAC compressed textures. . . . .	612
C.18	Intensity modifier sets for alpha component. . . . .	613
C.19	Texel Data format for RGB8_PUNCHTHROUGH_ALPHA1_ETC2 compressed textures formats . . . . .	622
C.20	Intensity modifier sets if ‘opaque’ is set and if ‘opaque’ is unset. .	624
C.21	Mapping from pixel index values to modifier values for COMPRESSED_RGB8_PUNCHTHROUGH_ALPHA1_ETC2 compressed textures . . . . .	625
E.1	New token names . . . . .	638
F.1	New token names . . . . .	646

# Chapter 1

## Introduction

This document, referred to as the “OpenGL Specification” or just “Specification” hereafter, describes the OpenGL graphics system: what it is, how it acts, and what is required to implement it. We assume that the reader has at least a rudimentary understanding of computer graphics. This means familiarity with the essentials of computer graphics algorithms and terminology as well as with modern GPUs (Graphic Processing Units).

The canonical version of the Specification is available in the official *OpenGL Registry*, located at URL

<http://www.opengl.org/registry/>

### 1.1 Formatting of the OpenGL Specification

This version of the OpenGL Specification has undergone major restructuring to focus on programmable shading, and to describe important concepts and objects in the context of the entire API before describing details of their use in the graphics pipeline.

#### 1.1.1 ~~Formatting of the Compatibility Profile~~

This subsection is only defined in the compatibility profile.

#### 1.1.2 ~~Formatting of Optional Features~~

This subsection is only defined in the compatibility profile.

### 1.1.3 Formatting of Changes

This version of the OpenGL 4.3 Specification marks changes relative to the first public release of OpenGL 4.3 Specification by typesetting them in color, like this paragraph. Details of these changes are also described in appendix F.5.

## 1.2 What is the OpenGL Graphics System?

OpenGL (for “Open Graphics Library”) is an *API* (Application Programming Interface) to graphics hardware. The API consists of a set of several hundred procedures and functions that allow a programmer to specify the shader programs, objects, and operations involved in producing high-quality graphical images, specifically color images of three-dimensional objects.

Most of OpenGL requires that the graphics hardware contain a framebuffer. Many OpenGL calls control drawing geometric objects such as points, lines, and polygons, but the way that some of this drawing occurs (such as when antialiasing or multisampling is in use) relies on the existence of a framebuffer and its properties. Some commands explicitly manage the framebuffer.

### 1.2.1 Programmer’s View of OpenGL

To the programmer, OpenGL is a set of commands that allow the specification of *shader programs* or *shaders*, data used by shaders, and state controlling aspects of OpenGL outside the scope of shaders. Typically the data represent geometry in two or three dimensions and texture images, while the shaders control the geometric processing, rasterization of geometry and the lighting and shading of *fragments* generated by rasterization, resulting in rendering geometry into the framebuffer.

A typical program that uses OpenGL begins with calls to open a window into the framebuffer into which the program will draw. Then, calls are made to allocate an OpenGL *context* and associate it with the window. Once a context is allocated, OpenGL commands to define shaders, geometry, and textures are made, followed by commands which draw geometry by transferring specified portions of the geometry to the shaders. Drawing commands specify simple geometric objects such as points, line segments, and polygons, which can be further manipulated by shaders. There are also commands which directly control the framebuffer by reading and writing pixels.

### 1.2.2 Implementor's View of OpenGL

To the implementor, OpenGL is a set of commands that control the operation of the GPU. Modern GPUs accelerate almost all OpenGL operations, storing data and framebuffer images in GPU memory and executing shaders in dedicated GPU processors. However, OpenGL may be implemented on less capable GPUs, or even without a GPU, by moving some or all operations into the host CPU.

The implementor's task is to provide a software library on the CPU which implements the OpenGL API, while dividing the work for each OpenGL command between the CPU and the graphics hardware as appropriate for the capabilities of the GPU.

OpenGL contains a considerable amount of information including many types of objects representing programmable shaders and the data they consume and generate, as well as other *context state* controlling non-programmable aspects of OpenGL. Most of these objects and state are available to the programmer, who can set, manipulate, and query their values through OpenGL commands. Some of it, however, is *derived state* visible only by the effect it has on how OpenGL operates. One of the main goals of this Specification is to describe OpenGL objects and context state explicitly, to elucidate how they change in response to OpenGL commands, and to indicate what their effects are.

### 1.2.3 Our View

We view OpenGL as a pipeline having some programmable stages and some state-driven *fixed-function* stages that are invoked by a set of specific drawing operations. This model should engender a specification that satisfies the needs of both programmers and implementors. It does not, however, necessarily provide a model for implementation. An implementation must produce results conforming to those produced by the specified methods, but there may be ways to carry out a particular computation that are more efficient than the one specified.

### 1.2.4 Fixed-function Hardware and the Compatibility Profile

Older generations of graphics hardware were not programmable using shaders, although they were configurable by setting state controlling specific details of their operation. The compatibility profile of OpenGL continues to support the legacy OpenGL commands developed for such fixed-function hardware, although they are typically implemented by writing shaders which reproduce the operation of such hardware. Fixed-function OpenGL commands and operations are described as alternative interfaces following descriptions of the corresponding shader stages.



### 1.2.5 The Deprecation Model

Features marked as *deprecated* in one version of the Specification are expected to be removed in a future version, allowing applications time to transition away from use of deprecated features. The deprecation model is described in more detail, together with a summary of the commands and state deprecated from this version of the API, in appendix [D](#).

## 1.3 Related APIs

Other APIs related to OpenGL are described below. Most of the specifications for these APIs are available on the Khronos Group websites, although some vendor-specific APIs are documented on that vendor's developer website.

### 1.3.1 OpenGL Shading Language

The OpenGL Specification should be read together with a companion document titled *The OpenGL Shading Language*. The latter document (referred to as the OpenGL Shading Language Specification hereafter) defines the syntax and semantics of the programming language used to write shaders (see chapter [7](#)). Descriptions of shaders later in this document may include references to concepts and terms (such as shading language variable types) defined in the OpenGL Shading Language Specification .

OpenGL 4.3 implementations are guaranteed to support version 4.30 of the OpenGL Shading Language. All references to sections of that specification refer to that version. The latest supported version of the shading language may be queried as described in section [22.2](#).

The core profile of OpenGL 4.3 is also guaranteed to support all previous versions of the OpenGL Shading Language back to version 1.40. In some implementations the core profile may also support earlier versions of the Shading Language, and may support compatibility profile versions of the Shading Language for versions 1.40 and earlier. In this case, errors will be generated when using language features such as compatibility profile built-ins not supported by the core profile API. The `#version` strings for all supported versions of the OpenGL Shading Language may be queried as described in section [22.2](#).

The OpenGL Shading Language Specification is available in the OpenGL Registry.

### 1.3.2 OpenGL ES

OpenGL ES is a royalty-free, cross-platform API for full-function 2D and 3D graphics on embedded systems such as mobile phones, game consoles, and vehicles. It consists of well-defined subsets of OpenGL. OpenGL ES version 1.1 implements a subset of the OpenGL 1.5 fixed-function API, OpenGL ES 2.0 implements a subset of the OpenGL 2.0 shader-based API, and OpenGL ES 3.0 implements a subset of OpenGL 3.3. OpenGL ES versions also include some additional functionality taken from later OpenGL versions or specific to OpenGL ES. It is straightforward to port code written for OpenGL ES to corresponding versions of OpenGL.

OpenGL and OpenGL ES are developed in parallel within the Khronos Group, which controls both standards.

OpenGL 4.3 includes functionality initially defined in OpenGL ES 3.0, for increased compatibility between OpenGL and OpenGL ES implementations.

The OpenGL ES Specifications are available in the *Khronos API Registry* at URL

<http://www.khronos.org/registry/>

### 1.3.3 OpenGL ES Shading Language

The Specification should also be read together with companion documents titled *The OpenGL ES Shading Language*. Both versions 1.00 and 3.00 should be read. These documents define versions of the OpenGL Shading Language designed for implementations of OpenGL ES 2.0 and 3.0 respectively, but also supported by OpenGL implementations. References to the OpenGL Shading Language Specification hereafter include both OpenGL and OpenGL ES versions of the Shading Language; references to specific sections are to those sections in version 4.30 of the OpenGL Shading Language Specification .

OpenGL 4.3 implementations are guaranteed to support both versions 1.00 and 3.00 of the OpenGL ES Shading Language.

The `#version` strings for all supported versions of the OpenGL Shading Language may be queried as described in section 22.2.

The OpenGL ES Shading Language Specifications are available in the Khronos API Registry.

### 1.3.4 WebGL

WebGL is a cross-platform, royalty-free web standard for a low-level 3D graphics API based on OpenGL ES 2.0. Developers familiar with OpenGL ES 2.0 will recognize WebGL as a shader-based API using a form of the OpenGL Shading

Language, with constructs that are semantically similar to those of the underlying OpenGL ES 2.0 API. It stays very close to the OpenGL ES 2.0 specification, with some concessions made for what developers expect out of memory-managed languages such as JavaScript.

The WebGL Specification and related documentation are available in the Khronos API Registry.

### 1.3.5 Window System Bindings

OpenGL requires a companion API to create and manage graphics contexts, windows to render into, and other resources beyond the scope of this Specification. There are several such APIs supporting different operating and window systems.

#### 1.3.5.1 GLX - X Window System Bindings

*OpenGL Graphics with the X Window System*, referred to as the GLX Specification hereafter, describes the GLX API for use of OpenGL in the X Window System. It is primarily directed at Linux and Unix systems, but GLX implementations also exist for Microsoft Windows, MacOS X, and some other platforms where X is available. The GLX Specification is available in the OpenGL Registry.

#### 1.3.5.2 WGL - Microsoft Windows Bindings

The WGL API supports use of OpenGL with Microsoft Windows. WGL is documented in Microsoft's MSDN system, although no full specification exists.

#### 1.3.5.3 MacOS X Window System Bindings

Several APIs exist supporting use of OpenGL with Quartz, the MacOS X window system, including CGL, AGL, and NSOpenGLView. These APIs are documented on Apple's developer website.

#### 1.3.5.4 EGL - Mobile and Embedded Device Bindings

The *Khronos Native Platform Graphics Interface* or "EGL Specification" describes the EGL API for use of OpenGL ES on mobile and embedded devices. EGL implementations supporting OpenGL may be available on some desktop platforms as well. The EGL Specification is available in the Khronos API Registry.

### 1.3.6 OpenCL

OpenCL is an open, royalty-free standard for cross-platform, general-purpose parallel programming of processors found in personal computers, servers, and mobile devices, including GPUs. OpenCL defines *interop* methods to share OpenCL memory and image objects with corresponding OpenGL buffer and texture objects, and to coordinate control of and transfer of data between OpenCL and OpenGL. This allows applications to split processing of data between OpenCL and OpenGL; for example, by using OpenCL to implement a physics model and then rendering and interacting with the resulting dynamic geometry using OpenGL.

The OpenCL Specification is available in the Khronos API Registry.

## Chapter 2

# OpenGL Fundamentals

This chapter introduces fundamental concepts including the OpenGL execution model, API syntax, contexts and threads, numeric representation, context state and state queries, and the different types of objects and shaders. It provides a framework for interpreting more specific descriptions of commands and behavior in the remainder of the Specification.

### 2.1 Execution Model

OpenGL (henceforth, “the GL”) is concerned only with processing data in GPU memory, including rendering into a framebuffer and reading values stored in that framebuffer. There is no support for other input or output devices. Programmers must rely on other mechanisms to obtain user input.

The GL draws *primitives* processed by a variety of shader programs and fixed-function processing units controlled by context state. Each primitive is a point, line segment, patch, or polygon. Context state may be changed independently; the setting of one piece of state does not affect the settings of others (although state and shader all interact to determine what eventually ends up in the framebuffer). State is set, primitives drawn, and other GL operations described by sending *commands* in the form of function or procedure calls.

Primitives are defined by a group of one or more *vertices*. A vertex defines a point, an endpoint of a line segment, or a corner of a polygon where two edges meet. Data such as positional coordinates, colors, normals, texture coordinates, etc. are associated with a vertex and each vertex is processed independently, in order, and in the same way. The only exception to this rule is if the group of vertices must be *clipped* so that the indicated primitive fits within a specified region; in this case vertex data may be modified and new vertices created. The type of clipping

depends on which primitive the group of vertices represents.

Commands are always processed in the order in which they are received, although there may be an indeterminate delay before the effects of a command are realized. This means, for example, that one primitive must be drawn completely before any subsequent one can affect the framebuffer. It also means that queries and pixel read operations return state consistent with complete execution of all previously invoked GL commands, except where explicitly specified otherwise. In general, the effects of a GL command on either GL state or the framebuffer must be complete before any subsequent command can have any such effects.

Data binding occurs on call. This means that data passed to a GL command are interpreted when that command is received. Even if the command requires a pointer to data, those data are interpreted when the call is made, and any subsequent changes to the data have no effect on the GL (unless the same pointer is used in a subsequent command).

The GL provides direct control over the fundamental operations of 3D and 2D graphics. This includes specification of parameters of application-defined shader programs performing transformation, lighting, texturing, and shading operations, as well as built-in functionality such as antialiasing and texture filtering. It does not provide a means for describing or modeling complex geometric objects, although shaders can be written to generate such objects. In other words, OpenGL provides mechanisms to describe how complex geometric objects are to be rendered, rather than mechanisms to describe the complex objects themselves.

The model for interpretation of GL commands is client-server. That is, a program (the client) issues commands, and these commands are interpreted and processed by the GL (the server). The server may or may not operate on the same computer or in the same address space as the client. In this sense, the GL is *network transparent*. A server may maintain a number of GL contexts, each of which is an encapsulation of current GL state and objects. A client may choose to be made *current* to any one of these contexts.

Issuing GL commands when a program is not *current* to a context results in undefined behavior.

There are two classes of framebuffers: a window system-provided framebuffer associated with a context when the context is made current, and application-created framebuffers. The window system-provided framebuffer is referred to as the *default framebuffer*. Application-created framebuffers, referred to as *framebuffer objects*, may be created as desired. A context may be associated with two framebuffers, one for each of reading and drawing operations. The default framebuffer and framebuffer objects are distinguished primarily by the interfaces for configuring and managing their state.

The effects of GL commands on the default framebuffer are ultimately con-

trolled by the window system, which allocates framebuffer resources, determines which portions of the default framebuffer the GL may access at any given time, and communicates to the GL how those portions are structured. Therefore, there are no GL commands to initialize a GL context or configure the default framebuffer. Similarly, display of framebuffer contents on a physical display device (including the transformation of individual framebuffer values by such techniques as gamma correction) is not addressed by the GL.

Allocation and configuration of the default framebuffer occurs outside of the GL in conjunction with the window system, using companion APIs described in section 1.3.5.

Allocation and initialization of GL contexts is also done using these companion APIs. GL contexts can be associated with different default framebuffers, and some context state is determined at the time this association is performed.

It is possible to use a GL context *without* a default framebuffer, in which case a framebuffer object must be used to perform all rendering. This is useful for applications needing to perform *offscreen rendering*.

OpenGL is designed to be run on a range of platforms with varying capabilities, memory, and performance. To accommodate this variety, we specify ideal behavior instead of actual behavior for certain GL operations. In cases where deviation from the ideal is allowed, we also specify the rules that an implementation must obey if it is to approximate the ideal behavior usefully. This allowed variation in GL behavior implies that two distinct GL implementations may not agree pixel for pixel when presented with the same input, even when run on identical framebuffer configurations.

Finally, command names, constants, and types are prefixed in the C language binding to OpenGL (by `gl`, `GL_`, and `GL`, respectively), to reduce name clashes with other packages. The prefixes are omitted in this document for clarity.

## 2.2 Command Syntax

The Specification describes OpenGL commands as functions or procedures using ANSI C syntax. Languages such as C++ and JavaScript which allow passing of argument type information permit language bindings with simpler declarations and fewer entry points.

Various groups of GL commands perform the same operation but differ in how arguments are supplied to them. To conveniently accommodate this variation, we adopt a notation for describing commands and their arguments.

GL commands are formed from a *name* which may be followed, depending on the particular command, by a sequence of characters describing a parameter to the

command. If present, a digit indicates the required length (number of values) of the indicated type. Next, a string of characters making up one of the *type descriptors* from table 2.1 indicates the specific size and data type of parameter values. A final **v** character, if present, indicates that the command takes a pointer to an array (a vector) of values rather than a series of individual arguments. Two specific examples are:

```
void Uniform4f( int location, float v0, float v1,
                float v2, float v3 );
```

and

```
void GetFloatv( enum value, float *data );
```

In general, a command declaration has the form

```
rtype Name{ $\epsilon$ 1234}{ $\epsilon$  b s i i64 f d ub us ui ui64}{ $\epsilon$ v}
      ( [args ,] T arg1, . . . , T argN [, args] ) ;
```

*rtype* is the return type of the function. The braces ({} ) enclose a series of type descriptors (see table 2.1), of which one is selected.  $\epsilon$  indicates no type descriptor. The arguments enclosed in brackets (*[args ,]* and *[, args]*) may or may not be present. The *N* arguments *arg1* through *argN* have type *T*, which corresponds to one of the type descriptors indicated in table 2.1 (if there are no letters, then the arguments' type is given explicitly). If the final character is not **v**, then *N* is given by the digit **1**, **2**, **3**, or **4** (if there is no digit, then the number of arguments is fixed). If the final character is **v**, then only *arg1* is present and it is an array of *N* values of the indicated type.

For example,

```
void Uniform{1234}{if}( int location, T value );
```

indicates the eight declarations

```
void Uniform1i( int location, int value );
void Uniform1f( int location, float value );
void Uniform2i( int location, int v0, int v1 );
void Uniform2f( int location, float v0, float v1 );
void Uniform3i( int location, int v0, int v1, int v2 );
void Uniform3f( int location, float v0, float v1,
                float v3 );
```



Type Descriptor	Corresponding GL Type
<b>b</b>	byte
<b>s</b>	short
<b>i</b>	int
<b>i64</b>	int64
<b>f</b>	float
<b>d</b>	double
<b>ub</b>	ubyte
<b>us</b>	ushort
<b>ui</b>	uint
<b>ui64</b>	uint64

Table 2.1: Correspondence of command suffix type descriptors to GL argument types. Refer to table 2.2 for definitions of the GL types.

```
void Uniform4i(int location, int v0, int v1, int v2,
               int v3);
void Uniform4f(int location, float v0, float v1,
               float v2, float v3);
```

Arguments whose type is fixed (i.e. not indicated by a suffix on the command) are of one of the GL data types summarized in table 2.2, or pointers to one of these types. Since many GL operations represent bitfields within these types, transfer blocks of data in these types to graphics hardware which uses the same data types, or otherwise requires these sizes, it is not possible to implement the GL API on an architecture which cannot satisfy the exact bit width requirements in table 2.2.

The types `clampf` and `clampd` are no longer used, replaced by `float` and `double` respectively together with specification language requiring parameter clamping<sup>1</sup>.

### 2.2.1 Data Conversion For State-Setting Commands

Many GL commands specify a value or values to which GL state of a specific type (boolean, enum, integer, or floating-point) is to be set. When multiple versions of such a command exist, using the type descriptor syntax described above, any such version may be used to set the state value. When state values are specified using

<sup>1</sup> These changes are backwards-compatible at the compilation and linking levels, and are being propagated to man pages and header files as well.

GL Type	Bit Width	Description
boolean	1 or more	Boolean
byte	8	Signed two's complement binary integer
ubyte	8	Unsigned binary integer
char	8	Characters making up strings
short	16	Signed two's complement binary integer
ushort	16	Unsigned binary integer
int	32	Signed two's complement binary integer
uint	32	Unsigned binary integer
fixed	32	Signed two's complement 16.16 scaled integer
int64	64	Signed two's complement binary integer
uint64	64	Unsigned binary integer
sizei	32	Non-negative binary integer size
enum	32	Enumerated binary integer value
intptr	<i>ptrbits</i>	Signed twos complement binary integer
sizeiptr	<i>ptrbits</i>	Non-negative binary integer size
sync	<i>ptrbits</i>	Sync object handle (see section 4.1)
bitfield	32	Bit field
half	16	Half-precision floating-point value encoded in an unsigned scalar
float	32	Floating-point value
clampf	32	Floating-point value clamped to [0, 1]
double	64	Floating-point value
clampd	64	Floating-point value clamped to [0, 1]

Table 2.2: GL data types. GL types are not C types. Thus, for example, GL type `int` is referred to as `GLint` outside this document, and is not necessarily equivalent to the C type `int`. An implementation must use exactly the number of bits indicated in the table to represent a GL type.

*ptrbits* is the number of bits required to represent a pointer type; in other words, types `intptr`, `sizeiptr`, and `sync` must be large enough to store any CPU address. `sync` is defined as an anonymous struct pointer in the C language bindings while `intptr` and `sizeiptr` are defined as integer types large enough to hold a pointer.

a different parameter type than the actual type of that state, data conversions are performed as follows:

- When the type of internal state is boolean, zero integer or floating-point values are converted to `FALSE` and non-zero values are converted to `TRUE`.
- When the type of internal state is integer or enum, boolean values of `FALSE` and `TRUE` are converted to 0 and 1, respectively. Floating-point values are rounded to the nearest integer.
- When the type of internal state is floating-point, boolean values of `FALSE` and `TRUE` are converted to 0.0 and 1.0, respectively. Integer values are converted to floating-point, with or without normalization as described for specific commands.

For commands taking arrays of the specified type, these conversions are performed for each element of the passed array.

Each command following these conversion rules refers back to this section. Some commands have additional conversion rules specific to certain state values and data types, which are described following the reference.

Validation of values performed by state-setting commands is performed after conversion, unless specified otherwise for a specific command.

### 2.2.2 Data Conversions For State Query Commands

Query commands (commands whose name begins with **Get**) return a value or values to which GL state has been set. Some of these commands exist in multiple versions returning different data types. When a query command is issued that returns data types different from the actual type of that state, data conversions are performed as follows:

- If a command returning boolean data is called, such as **GetBooleanv**, a floating-point or integer value converts to `FALSE` if and only if it is zero. Otherwise it converts to `TRUE`.
- If a command returning integer data is called, such as **GetIntegerv** or **GetInteger64v**, a boolean value of `TRUE` or `FALSE` is interpreted as 1 or 0, respectively. A floating-point value is rounded to the nearest integer, unless the value is an RGBA color component, a **DepthRange** value, or a depth buffer clear value. In these cases, the query command converts the floating-point value to an integer according to the `INT` entry of table 18.2; a value not in  $[-1, 1]$  converts to an undefined value.

- If a command returning floating-point data is called, such as **GetFloatv** or **GetDoublev**, a boolean value of `TRUE` or `FALSE` is interpreted as 1.0 or 0.0, respectively. An integer value is coerced to floating-point. Single- and double-precision floating-point values are converted as necessary.

If a value is so large in magnitude that it cannot be represented by the returned data type, then the nearest value representable using the requested type is returned.

When querying bitmasks (such as `SAMPLE_MASK_VALUE` or `STENCIL_WRITEMASK`) with **GetIntegerv**, the mask value is treated as a signed integer, so that mask values with the high bit set will not be clamped when returned as signed integers.

Unless otherwise indicated, multi-valued state variables return their multiple values in the same order as they are given as arguments to the commands that set them. For instance, the two **DepthRange** parameters are returned in the order  $n$  followed by  $f$ .

## 2.3 Command Execution

Most of the Specification discusses the behavior of a single context bound to a single *CPU thread*. It is also possible for multiple contexts to share GL objects and for each such context to be bound to a different thread. This section introduces concepts related to GL command execution including error reporting, command queue flushing, and synchronization between command streams. Using these tools can increase performance and utilization of the GPU by separating loosely related tasks into different contexts.

Methods to create, manage, and destroy CPU threads are defined by the host CPU operating system and are not described in the Specification. Binding of GL contexts to CPU threads is controlled through a window system binding layer such as those described in section [1.3.5](#).

### 2.3.1 Errors

The GL detects only a subset of those conditions that could be considered errors. This is because in many cases error checking would adversely impact the performance of an error-free program.

The command

```
enum GetError(void);
```

is used to obtain error information. Each detectable error is assigned a numeric code. When an error is detected, a flag is set and the code is recorded. Further

errors, if they occur, do not affect this recorded code. When **GetError** is called, the code is returned and the flag is cleared, so that a further error will again record its code. If a call to **GetError** returns `NO_ERROR`, then there has been no detectable error since the last call to **GetError** (or since the GL was initialized).

To allow for distributed implementations, there may be several flag-code pairs. In this case, after a call to **GetError** returns a value other than `NO_ERROR` each subsequent call returns the non-zero code of a distinct flag-code pair (in unspecified order), until all non-`NO_ERROR` codes have been returned. When there are no more non-`NO_ERROR` error codes, all flags are reset. This scheme requires some positive number of pairs of a flag bit and an integer. The initial state of all flags is cleared and the initial value of all codes is `NO_ERROR`.

Table 2.3 summarizes GL errors. Currently, when an error flag is set, results of GL operation are undefined only if an `OUT_OF_MEMORY` error has occurred. In other cases, there are no side effects; the command which *generates* the error is ignored so that it has no effect on GL state or framebuffer contents. Except as otherwise noted, if the generating command returns a value, it returns zero. If the generating command modifies values through a pointer argument, no change is made to these values.

These error semantics apply only to GL errors, not to system errors such as memory access errors. This behavior is the current behavior; the action of the GL in the presence of errors is subject to change, and extensions to OpenGL may define behavior currently considered as an error.

Several error generation conditions are implicit in the description of every GL command.

- If a command that requires an enumerated value is passed a symbolic constant that is not one of those specified as allowable for that command, an `INVALID_ENUM` error is generated. This is the case even if the argument is a pointer to a symbolic constant, if the value or values pointed to are not allowable for the given command.
- If a negative number is provided where an argument of type `sizei` or `sizeiptr` is specified, an `INVALID_VALUE` error is generated.
- If memory is exhausted as a side effect of the execution of a command, an `OUT_OF_MEMORY` error may be generated.

The Specification attempts to explicitly describe these implicit error conditions (with the exception of `OUT_OF_MEMORY`) wherever they apply. However, they apply even if not explicitly described, unless a specific command describes different behavior. For example, certain commands use a `sizei` parameter to indicate the

Error	Description	Offending command ignored?
INVALID_ENUM	enum argument out of range	Yes
INVALID_VALUE	Numeric argument out of range	Yes
INVALID_OPERATION	Operation illegal in current state	Yes
INVALID_FRAMEBUFFER_OPERATION	Framebuffer object is not complete	Yes
OUT_OF_MEMORY	Not enough memory left to execute command	Unknown
STACK_OVERFLOW	Command would cause a stack overflow	Yes
STACK_UNDERFLOW	Command would cause a stack underflow	Yes

Table 2.3: Summary of GL errors

length of a string, and also use negative values of the parameter to indicate a null-terminated string. These commands do not generate an `INVALID_VALUE` error, because they explicitly describe different behavior.

Otherwise, errors are generated only for conditions that are explicitly described in the Specification.

When a command could potentially generate several different errors (for example, when is passed separate `enum` and numeric parameters which are both out of range), the GL implementation may choose to generate any of the applicable errors.

When an error is generated, the GL may also generate a debug output message describing its cause (see chapter 20). The message has *source* `DEBUG_SOURCE_API`, *type* `DEBUG_TYPE_ERROR`, and an implementation-dependent ID.

Most commands include a complete summary of errors at the end of their description, including even the implicit errors described above.

Such error summaries are set in a distinct style, like this sentence.

In some cases, however, errors may be generated for a single command for reasons not directly related to that command. One such example is that deferred processing for shader programs may result in link errors detected only when attempting to draw primitives using vertex specification commands. In such cases,

errors generated by a command may be described elsewhere in the specification than the command itself.

### 2.3.2 Flush and Finish

Implementations may buffer multiple commands in a *command queue* before sending them to the GL server for execution. This may happen in places such as the network stack (for network transparent implementations), CPU code executing as part of the GL client or the GL server, or internally to the GPU hardware. Coarse control over command queues is available using the command

```
void Flush(void);
```

which causes all previously issued GL commands to complete in finite time (although such commands may still be executing when **Flush** returns).

The command

```
void Finish(void);
```

forces all previously issued GL commands to complete. **Finish** does not return until all effects from such commands on GL client and server state and the framebuffer are fully realized.

Finer control over command execution can be expressed using fence commands and sync objects, as discussed in section 4.1.

### 2.3.3 Numeric Representation and Computation

The GL must perform a number of floating-point operations during the course of its operation.

Implementations normally perform computations in floating-point, and must meet the range and precision requirements defined under **”Floating-Point Computation”** below.

These requirements only apply to computations performed in GL operations outside of shader execution, such as texture image specification and sampling, and per-fragment operations. Range and precision requirements during shader execution differ and are specified by the OpenGL Shading Language Specification .

In some cases, the representation and/or precision of operations is implicitly limited by the specified format of vertex, texture, or renderbuffer data consumed by the GL. Specific floating-point formats are described later in this section.

#### **Floating-Point Computation**

We do not specify how floating-point numbers are to be represented, or the details of how operations on them are performed.

We require simply that numbers' floating-point parts contain enough bits and that their exponent fields are large enough so that individual results of floating-point operations are accurate to about 1 part in  $10^5$ . The maximum representable magnitude for all floating-point values must be at least  $2^{32}$ .  $x \cdot 0 = 0 \cdot x = 0$  for any non-infinite and non-NaN  $x$ .  $1 \cdot x = x \cdot 1 = x$ .  $x + 0 = 0 + x = x$ .  $0^0 = 1$ . (Occasionally further requirements will be specified.) Most single-precision floating-point formats meet these requirements.

The special values *Inf* and  $-Inf$  encode values with magnitudes too large to be represented; the special value *NaN* encodes "Not A Number" values resulting from undefined arithmetic operations such as  $\frac{0}{0}$ . Implementations are permitted, but not required, to support *Infs* and *NaNs* in their floating-point computations.

Any representable floating-point value is legal as input to a GL command that requires floating-point data. The result of providing a value that is not a floating-point number to such a command is unspecified, but must not lead to GL interruption or termination. In IEEE arithmetic, for example, providing a negative zero or a denormalized number to a GL command yields predictable results, while providing a NaN or an infinity yields unspecified results.

### 16-Bit Floating-Point Numbers

A 16-bit floating-point number has a 1-bit sign ( $S$ ), a 5-bit exponent ( $E$ ), and a 10-bit mantissa ( $M$ ). The value  $V$  of a 16-bit floating-point number is determined by the following:

$$V = \begin{cases} (-1)^S \times 0.0, & E = 0, M = 0 \\ (-1)^S \times 2^{-14} \times \frac{M}{2^{10}}, & E = 0, M \neq 0 \\ (-1)^S \times 2^{E-15} \times \left(1 + \frac{M}{2^{10}}\right), & 0 < E < 31 \\ (-1)^S \times Inf, & E = 31, M = 0 \\ NaN, & E = 31, M \neq 0 \end{cases}$$

If the floating-point number is interpreted as an unsigned 16-bit integer  $N$ , then

$$S = \left\lfloor \frac{N \bmod 65536}{32768} \right\rfloor$$

$$E = \left\lfloor \frac{N \bmod 32768}{1024} \right\rfloor$$

$$M = N \bmod 1024.$$



Any representable 16-bit floating-point value is legal as input to a GL command that accepts 16-bit floating-point data. The result of providing a value that is not a floating-point number (such as *Inf* or *NaN*) to such a command is unspecified, but must not lead to GL interruption or termination. Providing a denormalized number or negative zero to GL must yield predictable results.

### Unsigned 11-Bit Floating-Point Numbers

An unsigned 11-bit floating-point number has no sign bit, a 5-bit exponent ( $E$ ), and a 6-bit mantissa ( $M$ ). The value  $V$  of an unsigned 11-bit floating-point number is determined by the following:

$$V = \begin{cases} 0.0, & E = 0, M = 0 \\ 2^{-14} \times \frac{M}{64}, & E = 0, M \neq 0 \\ 2^{E-15} \times \left(1 + \frac{M}{64}\right), & 0 < E < 31 \\ Inf, & E = 31, M = 0 \\ NaN, & E = 31, M \neq 0 \end{cases}$$

If the floating-point number is interpreted as an unsigned 11-bit integer  $N$ , then

$$E = \left\lfloor \frac{N}{64} \right\rfloor$$

$$M = N \bmod 64.$$

When a floating-point value is converted to an unsigned 11-bit floating-point representation, finite values are rounded to the closest representable finite value. While less accurate, implementations are allowed to always round in the direction of zero. This means negative values are converted to zero. Likewise, finite positive values greater than 65024 (the maximum finite representable unsigned 11-bit floating-point value) are converted to 65024. Additionally: negative infinity is converted to zero; positive infinity is converted to positive infinity; and both positive and negative *NaN* are converted to positive *NaN*.

Any representable unsigned 11-bit floating-point value is legal as input to a GL command that accepts 11-bit floating-point data. The result of providing a value that is not a floating-point number (such as *Inf* or *NaN*) to such a command is unspecified, but must not lead to GL interruption or termination. Providing a denormalized number to GL must yield predictable results.

### Unsigned 10-Bit Floating-Point Numbers

An unsigned 10-bit floating-point number has no sign bit, a 5-bit exponent ( $E$ ), and a 5-bit mantissa ( $M$ ). The value  $V$  of an unsigned 10-bit floating-point number is determined by the following:

$$V = \begin{cases} 0.0, & E = 0, M = 0 \\ 2^{-14} \times \frac{M}{32}, & E = 0, M \neq 0 \\ 2^{E-15} \times \left(1 + \frac{M}{32}\right), & 0 < E < 31 \\ Inf, & E = 31, M = 0 \\ NaN, & E = 31, M \neq 0 \end{cases}$$

If the floating-point number is interpreted as an unsigned 10-bit integer  $N$ , then

$$E = \left\lfloor \frac{N}{32} \right\rfloor$$

$$M = N \bmod 32.$$

When a floating-point value is converted to an unsigned 10-bit floating-point representation, finite values are rounded to the closest representable finite value. While less accurate, implementations are allowed to always round in the direction of zero. This means negative values are converted to zero. Likewise, finite positive values greater than 64512 (the maximum finite representable unsigned 10-bit floating-point value) are converted to 64512. Additionally: negative infinity is converted to zero; positive infinity is converted to positive infinity; and both positive and negative *NaN* are converted to positive *NaN*.

Any representable unsigned 10-bit floating-point value is legal as input to a GL command that accepts 10-bit floating-point data. The result of providing a value that is not a floating-point number (such as *Inf* or *NaN*) to such a command is unspecified, but must not lead to GL interruption or termination. Providing a denormalized number to GL must yield predictable results.

### Fixed-Point Computation

Vertex attributes may be specified using a 32-bit two's-complement signed representation with 16 bits to the right of the binary point (fraction bits).

### General Requirements

Some calculations require division. In such cases (including implied divisions required by vector normalizations), a division by zero produces an unspecified result but must not lead to GL interruption or termination.

### 2.3.4 Fixed-Point Data Conversions

When generic vertex attributes and pixel color or depth components are represented as integers, they are often (but not always) considered to be *normalized*. Normalized integer values are treated specially when being converted to and from floating-point values, and are usually referred to as *normalized fixed-point*. Such values are always either *signed* or *unsigned*.

In the remainder of this section,  $b$  denotes the bit width of the fixed-point integer representation. When the integer is one of the types defined in table 2.2,  $b$  is the required bit width of that type. When the integer is a texture or renderbuffer color or depth component (see section 8.5),  $b$  is the number of bits allocated to that component in the internal format of the texture or renderbuffer. When the integer is a framebuffer color or depth component (see section 9),  $b$  is the number of bits allocated to that component in the framebuffer. For framebuffer and renderbuffer alpha components,  $b$  must be at least 2 if the buffer does not contain an alpha component, or if there is only 1 bit of alpha in the buffer.

The signed and unsigned fixed-point representations are assumed to be  $b$ -bit binary twos-complement integers and binary unsigned integers, respectively.

#### 2.3.4.1 Conversion from Normalized Fixed-Point to Floating-Point

Unsigned normalized fixed-point integers represent numbers in the range  $[0, 1]$ . The conversion from an unsigned normalized fixed-point value  $c$  to the corresponding floating-point value  $f$  is defined as

$$f = \frac{c}{2^b - 1}. \quad (2.1)$$

Signed normalized fixed-point integers represent numbers in the range  $[-1, 1]$ . The conversion from a signed normalized fixed-point value  $c$  to the corresponding floating-point value  $f$  is performed using

$$f = \max \left\{ \frac{c}{2^{b-1} - 1}, -1.0 \right\}. \quad (2.2)$$

Only the range  $[-2^{b-1} + 1, 2^{b-1} - 1]$  is used to represent signed fixed-point values in the range  $[-1, 1]$ . For example, if  $b = 8$ , then the integer value  $-127$  corresponds to  $-1.0$  and the value  $127$  corresponds to  $1.0$ . Note that while zero can be exactly expressed in this representation, one value ( $-128$  in the example) is outside the representable range, and must be clamped before use. This equation is used everywhere that signed normalized fixed-point values are converted to floating-point, including for all signed normalized fixed-point parameters in GL commands, such

as vertex attribute values<sup>2</sup>, as well as for specifying texture or framebuffer values using signed normalized fixed-point.

#### 2.3.4.2 Conversion from Floating-Point to Normalized Fixed-Point

The conversion from a floating-point value  $f$  to the corresponding unsigned normalized fixed-point value  $c$  is defined by first clamping  $f$  to the range  $[0, 1]$ , then computing

$$f' = f \times (2^b - 1). \quad (2.3)$$

$f'$  is then cast to an unsigned binary integer value with exactly  $b$  bits.

The conversion from a floating-point value  $f$  to the corresponding signed normalized fixed-point value  $c$  is performed by clamping  $f$  to the range  $[-1, 1]$ , then computing

$$f' = f \times (2^{b-1} - 1). \quad (2.4)$$

After conversion,  $f'$  is then cast to a signed two's-complement binary integer value with exactly  $b$  bits.

This equation is used everywhere that floating-point values are converted to signed normalized fixed-point, including when querying floating-point state (see section 2.2.2) and returning integers<sup>3</sup>, as well as for specifying signed normalized texture or framebuffer values using floating-point.

## 2.4 Context State

Context state is state that belongs to the GL context as a whole, rather than to instances of the different object types described in section 2.5. Context state controls fixed-function stages of the GPU, such as clipping, primitive rasterization, and framebuffer clears, and also specifies *bindings* of objects to the context specifying which objects are used during command execution.

The Specification describes all visible context state variables and describes how each one can be changed. State variables are grouped somewhat arbitrarily by their

---

<sup>2</sup> This is a behavior change in OpenGL 4.2. In previous versions, a different conversion for signed normalized values was used in which  $-128$  mapped to  $-1.0$ ,  $127$  mapped to  $1.0$ , and  $0.0$  was not exactly representable.

<sup>3</sup> This is a behavior change in OpenGL 4.2. In previous versions, a different conversion for signed normalized values was used in which  $-1.0$  mapped to  $-128$ ,  $1.0$  mapped to  $127$ , and  $0.0$  was not exactly representable.

function. Although we describe operations that the GL performs on the framebuffer, the framebuffer is not a part of GL state.

There are two types of context state. *Server state* resides in the GL server; the majority of GL state falls into this category. *Client state* resides in the GL client. Unless otherwise specified, all state is server state; client state is specifically identified. Each instance of a context includes a complete set of server state; each connection from a client to a server also includes a complete set of client state.

While an implementation of OpenGL may be hardware dependent, the Specification is independent of any specific hardware on which it is implemented. We are concerned with the state of graphics hardware only when it corresponds precisely to GL state.

### 2.4.1 Generic Context State Queries

Context state queries are described in detail in chapter [22](#).

## 2.5 Objects and the Object Model

Many types of *objects* are defined in the remainder of the Specification. Applications may create, modify, query, and destroy many *instances* of each of these object types, limited in most cases only by available graphics memory. Specific instances of different object types are *bound* to a context. The set of bound objects define the shaders which are invoked by GL drawing operations; specify the buffer data, texture image, and framebuffer memory that is accessed by shaders and directly by GL commands; and contain the state used by other operations such as fence synchronization and timer queries.

Each object type corresponds to a distinct set of commands which manage objects of that type. However, there is an object model describing how most types of objects are managed, described below. Exceptions to the object model for specific object types are described later in the Specification together with those object types.

Following the description of the object model, each type of object is briefly described below, together with forward references to full descriptions of that object type in later chapters of the Specification. Objects are described in an order corresponding to the structure of the remainder of the Specification.

## 2.5.1 Object Management

### 2.5.1.1 Name Spaces, Name Generation, and Object Creation

Each object type has a corresponding *name space*. Names of objects are represented by unsigned integers of type `uint`. The name zero is reserved by the GL; for some object types, zero names a *default object* of that type, and in others zero will never correspond to an actual instance of that object type.

Names of most types of objects are created by *generating* unused names using commands starting with **Gen** followed by the object type. For example, the command **GenBuffers** returns one or more previously unused buffer object names.

Generated names are marked by the GL as used, for the purpose of name generation only. Object names marked in this fashion will not be returned by additional calls to generate names of the same type until the names are marked unused again by deleting them (see below).

Generated names do not initially correspond to an instance of an object. Objects with generated names are created by binding a generated name to the context. For example, a buffer object is created by calling the command **BindBuffer** with a name returned by **GenBuffers**, which allocates resources for the buffer object and its state, and associate the name with that object. Sampler objects may also be created by commands in addition to **BindSampler**, as described in section 8.2.

A few types of objects are created by commands which return the name of the new object at the same time they create the object. Examples include **CreateProgram** for program objects and **FenceSync** for fence sync objects.

### 2.5.1.2 Name Deletion and Object Deletion

Objects are deleted by calling deletion commands specific to that object type. For example, the command **DeleteBuffers** is passed an array of buffer object names to delete. After an object is deleted it has no contents, and its name is once again marked unused for the purpose of name generation. If names are deleted that do not correspond to an object, but have been marked for the purpose of name generation, such names are marked as unused again. If unused and unmarked names are deleted they are silently ignored, as is the name zero.

If an object is deleted while it is currently in use by a GL context, its name is immediately marked as unused, and some types of objects are automatically unbound from binding points in the current context, as described in section 5.1.2. However, the actual underlying object is not deleted until it is no longer in use. This situation is discussed in more detail in section 5.1.3.

### 2.5.1.3 Shared Object State

It is possible for groups of contexts to share some server state. Enabling such sharing between contexts is done through window system binding APIs such as those described in section 1.3.5. These APIs are responsible for creation and management of contexts, and not discussed further here. More detailed discussion of the behavior of shared objects is included in chapter 5. Except as defined below for specific object types, all state in a context is specific to that context only.

### 2.5.2 Buffer Objects

The GL uses many types of data supplied by the client. Some of this data must be stored in server memory, and it is desirable to store other types of frequently used client data, such as vertex array and pixel data, in server memory for performance reasons, even if the option to store it in client memory exists.

*Buffer objects* contain a *data store* holding a fixed-sized allocation of server memory, and provide a mechanism to allocate, initialize, read from, and write to such memory.

Buffer objects may be shared. They are described in detail in chapter 6.

### 2.5.3 Shader Objects

The source and/or binary code representing part or all of a shader program that is executed by one of the programmable stages defined by the GL (such as a vertex or fragment shader) is encapsulated in one or more *shader objects*.

Shader objects may be shared. They are described in detail in chapter 7.

### 2.5.4 Program Objects

Shader objects that are to be used by one or more of the programmable stages of the GL are linked together to form a *program object*. The shader programs that are executed by these programmable stages are called *executables*. All information necessary for defining each executable is encapsulated in a program object.

Program objects may be shared. They are described in detail in chapter 7.

### 2.5.5 Program Pipeline Objects

*Program pipeline objects* contain a separate program object binding point for each programmable stage. They allow a primitive to be processed by independent programs in each programmable stage, instead of requiring a single program object for each combination of shader operations. They allow greater flexibility when

combining different shaders in various ways, without requiring a program object for each such combination.

Program pipeline objects are *container objects* including references to program objects, and are not shared. They are described in detail in chapter 7.

### 2.5.6 Texture Objects

*Texture objects* or *textures* include a collection of *texture images* built from arrays of image elements referred to as *texels*. There are many types of texture objects varying by dimensionality and structure; the different texture types are described in detail in the introduction to chapter 8.

Texture objects also include state describing the image parameters of the texture images, and state describing how sampling is performed when a shader accesses a texture.

Shaders may *sample* a texture at a location indicated by specified *texture coordinates*, with details of sampling determined by the sampler state of the texture. The resulting texture samples are typically used to modify a fragment's color, in order to map an image onto a geometric primitive being drawn, but may be used for any purpose in a shader.

Texture objects may be shared. They are described in detail in chapter 8.

### 2.5.7 Sampler Objects

*Sampler objects* contain the subset of texture object state controlling how sampling is performed when a shader accesses a texture. Sampler and texture objects may be bound together so that the sampler object state is used by shaders when sampling the texture, overriding equivalent state in the texture object. Separating texture image data from the method of sampling that data allows reuse of the same sampler state with many different textures without needing to set the sampler state in each texture.

Sampler objects may be shared. They are described in detail in chapter 8.

### 2.5.8 Renderbuffer Objects

*Renderbuffer objects* contain a single image in a format which can be rendered to. Renderbuffer objects are attached to framebuffer objects (see below) when performing *off-screen rendering*.

Renderbuffer objects may be shared. They are described in detail in chapter 9.



### 2.5.9 Framebuffer Objects

*Framebuffer objects* encapsulate the state of a framebuffer, including a collection of color, depth, and stencil buffers. Each such buffer is represented by a renderbuffer object or texture object *attached* to the framebuffer object.

Framebuffer objects are container objects including references to renderbuffer and/or texture objects, and are not shared. They are described in detail in chapter 9.

### 2.5.10 Vertex Array Objects

*Vertex array objects* represent a collection of sets of *vertex attributes*. Each set is stored as an array in a buffer object data store, with each element of the array having a specified format and component count. The attributes of the currently bound vertex array object are used as inputs to the vertex shader when executing drawing commands.

Vertex array objects are container objects including references to buffer objects, and are not shared. They are described in detail in chapter 10.

### 2.5.11 Transform Feedback Objects

*Transform feedback objects* are used to capture attributes of the vertices of transformed primitives passed to the transform feedback stage when *transform feedback mode* is active. They include state required for transform feedback together with references to buffer objects in which attributes are captured.

Transform feedback objects are container objects including references to buffer objects, and are not shared. They are described in detail in section 13.2.1.

### 2.5.12 Query Objects

*Query objects* return information about the processing of a sequence of GL commands, such as the number of primitives processed by drawing commands; the number of primitives written to transform feedback buffers; the number of samples that pass the depth test during fragment processing; and the amount of time required to process commands.

Query objects are not shared. They are described in detail in section 4.2.

### 2.5.13 Sync Objects

A *sync object* acts as a *synchronization primitive* – a representation of events whose completion status can be tested or waited upon. Sync objects may be used for synchronization with operations occurring in the GL state machine or in the graphics

pipeline, and for synchronizing between multiple graphics contexts, among other purposes.

Sync objects may be shared. They are described in detail in section [4.1](#).

#### **2.5.14 ~~Display Lists~~**

[This subsection is only defined in the compatibility profile.](#)

## Chapter 3

# Dataflow Model

Figure 3.1 shows a block diagram of the GL. Some commands specify geometric objects to be drawn while others specify state controlling how objects are handled by the various stages, or specify data contained in textures and buffer objects. Commands are effectively sent through a processing pipeline. Different stages of the pipeline use data contained in different types of buffer objects.

The first stage assembles vertices to form geometric primitives such as points, line segments, and polygons. In the next stage vertices may be transformed, followed by assembly into geometric primitives. Tessellation and geometry shaders may then generate multiple primitives from single input primitives. Optionally, the results of these pipeline stages may be fed back into buffer objects using transform feedback.

The final resulting primitives are clipped to a clip volume in preparation for the next stage, rasterization. The rasterizer produces a series of framebuffer addresses and values using a two-dimensional description of a point, line segment, or polygon. Each *fragment* so produced is fed to the next stage that performs operations on individual fragments before they finally alter the framebuffer. These operations include conditional updates into the framebuffer based on incoming and previously stored depth values (to effect depth buffering), blending of incoming fragment colors with stored colors, as well as masking, stenciling, and other logical operations on fragment values.

Pixels may also be read back from the framebuffer or copied from one portion of the framebuffer to another. These transfers may include some type of decoding or encoding.

Finally, compute shaders which may read from and write to buffer objects may be executed independently of the pipeline shown in figure 3.1.

This ordering is meant only as a tool for describing the GL, not as a strict rule

of how the GL is implemented, and we present it only as a means to organize the various operations of the GL.

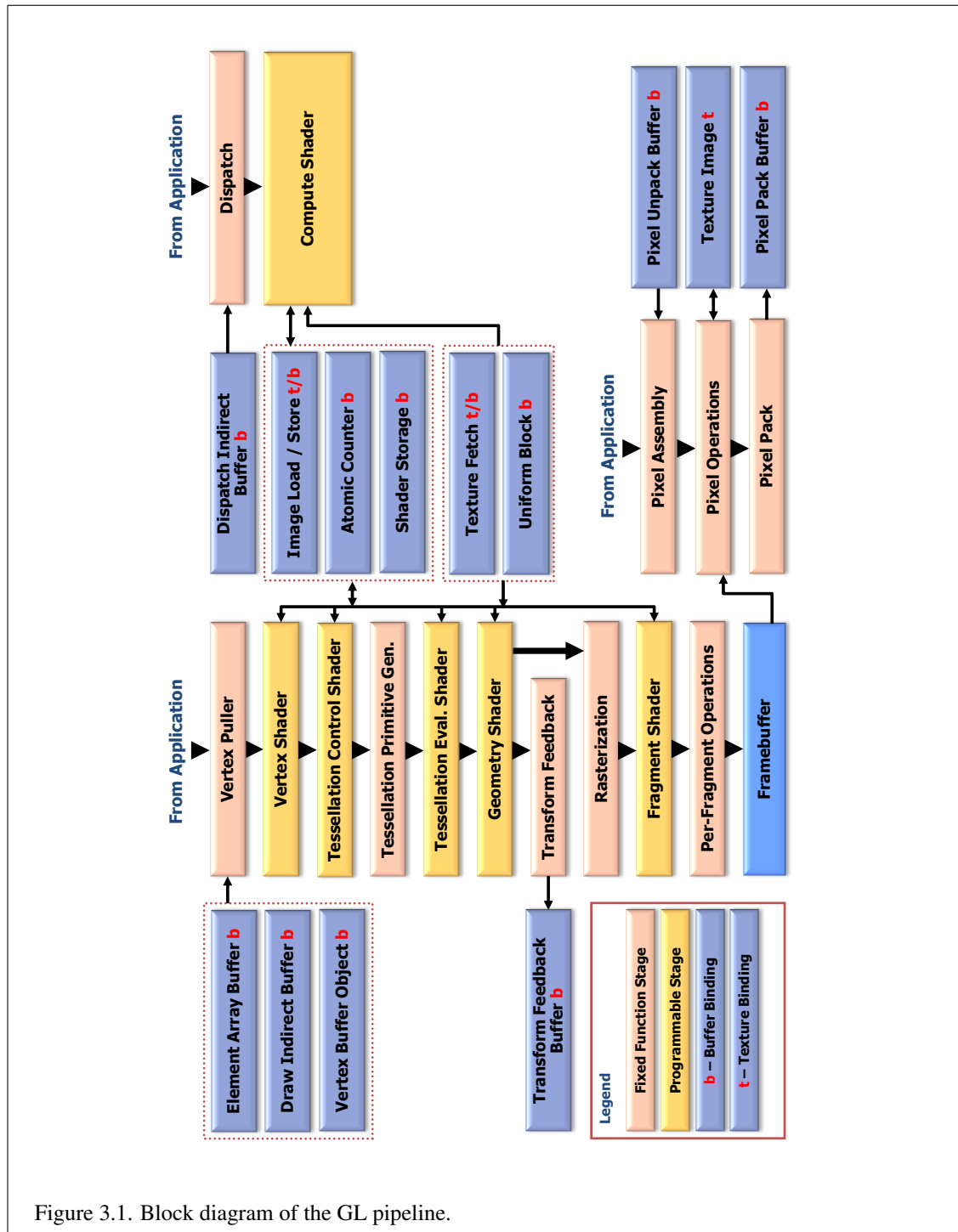


Figure 3.1. Block diagram of the GL pipeline.

## Chapter 4

# Event Model

### 4.1 Sync Objects and Fences

A sync object acts as a *synchronization primitive* – a representation of events whose completion status can be tested or waited upon. Sync objects may be used for synchronization with operations occurring in the GL state machine or in the graphics pipeline, and for synchronizing between multiple graphics contexts, among other purposes.

Sync objects have a status value with two possible states: *signaled* and *unsignaled*. Events are associated with a sync object. When a sync object is created, its status is set to *unsignaled*. When the associated event occurs, the sync object is *signaled* (its status is set to *signaled*). The GL may be asked to wait for a sync object to become *signaled*.

Initially, only one specific type of sync object is defined: the fence sync object, whose associated event is triggered by a fence command placed in the GL command stream. Fence sync objects are used to wait for partial completion of the GL command stream, as a more flexible form of **Finish**.

The command

```
sync FenceSync( enum condition, bitfield flags );
```

creates a new fence sync object, inserts a fence command in the GL command stream and associates it with that sync object, and returns a non-zero name corresponding to the sync object.

When the specified *condition* of the sync object is satisfied by the fence command, the sync object is *signaled* by the GL, causing any **ClientWaitSync** or **WaitSync** commands (see below) blocking on *sync* to *unblock*. No other state is affected by **FenceSync** or by execution of the associated fence command.

Property Name	Property Value
OBJECT_TYPE	SYNC_FENCE
SYNC_CONDITION	<i>condition</i>
SYNC_STATUS	UNSIGNALLED
SYNC_FLAGS	<i>flags</i>

Table 4.1: Initial properties of a sync object created with **FenceSync**.

*condition* must be SYNC\_GPU\_COMMANDS\_COMPLETE. This condition is satisfied by completion of the fence command corresponding to the sync object and all preceding commands in the same command stream. The sync object will not be signaled until all effects from these commands on GL client and server state and the framebuffer are fully realized. Note that completion of the fence command occurs once the state of the corresponding sync object has been changed, but commands waiting on that sync object may not be unblocked until some time after the fence command completes.

*flags* must be zero.

Each sync object contains a number of *properties* which determine the state of the object and the behavior of any commands associated with it. Each property has a *property name* and *property value*. The initial property values for a sync object created by **FenceSync** are shown in table 4.1.

Properties of a sync object may be queried with **GetSynciv** (see section 4.1.3). The SYNC\_STATUS property will be changed to SIGNALLED when *condition* is satisfied.

### Errors

If **FenceSync** fails to create a sync object, zero will be returned and a GL error is generated.

An INVALID\_ENUM error is generated if *condition* is not SYNC\_GPU\_COMMANDS\_COMPLETE.

An INVALID\_VALUE error is generated if *flags* is not zero.

A sync object can be deleted by passing its name to the command

```
void DeleteSync( sync sync );
```

If the fence command corresponding to the specified sync object has completed, or if no **ClientWaitSync** or **WaitSync** commands are blocking on *sync*, the

object is deleted immediately. Otherwise, *sync* is flagged for deletion and will be deleted when it is no longer associated with any fence command and is no longer blocking any **ClientWaitSync** or **WaitSync** command. In either case, after returning from **DeleteSync** the *sync* name is invalid and can no longer be used to refer to the sync object.

**DeleteSync** will silently ignore a *sync* value of zero.

### Errors

An `INVALID_VALUE` error is generated if *sync* is neither zero nor the name of a sync object.

#### 4.1.1 Waiting for Sync Objects

The command

```
enum ClientWaitSync( sync sync, bitfield flags,
    uint64 timeout );
```

causes the GL to block, and will not return until the sync object *sync* is signaled, or until the specified *timeout* period expires. *timeout* is in units of nanoseconds. *timeout* is adjusted to the closest value allowed by the implementation-dependent timeout accuracy, which may be substantially longer than one nanosecond, and may be longer than the requested period.

If *sync* is signaled at the time **ClientWaitSync** is called, then **ClientWaitSync** returns immediately. If *sync* is unsignaled at the time **ClientWaitSync** is called, then **ClientWaitSync** will block and will wait up to *timeout* nanoseconds for *sync* to become signaled. *flags* controls command flushing behavior, and may be `SYNC_FLUSH_COMMANDS_BIT`, as discussed in section 4.1.2.

**ClientWaitSync** returns one of four status values. A return value of `ALREADY_SIGNED` indicates that *sync* was signaled at the time **ClientWaitSync** was called. `ALREADY_SIGNED` will always be returned if *sync* was signaled, even if the value of *timeout* is zero. A return value of `TIMEOUT_EXPIRED` indicates that the specified timeout period expired before *sync* was signaled. A return value of `CONDITION_SATISFIED` indicates that *sync* was signaled before the timeout expired. Finally, if an error occurs, in addition to generating a GL error as specified below, **ClientWaitSync** immediately returns `WAIT_FAILED` without blocking.

If the value of *timeout* is zero, then **ClientWaitSync** does not block, but simply tests the current state of *sync*. `TIMEOUT_EXPIRED` will be returned in this case if *sync* is not signaled, even though no actual wait was performed.



**Errors**

An `INVALID_VALUE` error is generated if *sync* is not the name of a sync object.

An `INVALID_VALUE` error is generated if *flags* contains any bits other than `SYNC_FLUSH_COMMANDS_BIT`.

The command

```
void WaitSync( sync sync, bitfield flags,
                uint64 timeout );
```

is similar to **ClientWaitSync**, but instead of blocking and not returning to the application until *sync* is signaled, **WaitSync** returns immediately, instead causing the GL server to block<sup>1</sup> until *sync* is signaled<sup>2</sup>.

*sync* has the same meaning as for **ClientWaitSync**.

*timeout* must currently be the special value `TIMEOUT_IGNORED`, and is not used. Instead, **WaitSync** will always wait no longer than an implementation-dependent timeout. The duration of this timeout in nanoseconds may be queried by calling **GetInteger64v** with the symbolic constant `MAX_SERVER_WAIT_TIMEOUT`. There is currently no way to determine whether **WaitSync** unblocked because the timeout expired or because the sync object being waited on was signaled.

*flags* must be zero.

If an error occurs, **WaitSync** generates a GL error as specified below, and does not cause the GL server to block.

**Errors**

An `INVALID_VALUE` error is generated if *sync* is not the name of a sync object.

An `INVALID_VALUE` error is generated if *timeout* is not `TIMEOUT_IGNORED` or *flags* is not zero<sup>a</sup>.

<sup>a</sup> *flags* and *timeout* are placeholders for anticipated future extensions of sync object capabilities. They must have these reserved values in order that existing code calling **WaitSync** operate properly in the presence of such extensions.

<sup>1</sup> The GL server may choose to wait either in the CPU executing server-side code, or in the GPU hardware if it supports this operation.

<sup>2</sup> **WaitSync** allows applications to continue to queue commands from the client in anticipation of the sync being signaled, increasing client-server parallelism.

#### 4.1.1.1 Multiple Waiters

It is possible for both the GL client to be blocked on a sync object in a **ClientWaitSync** command, the GL server to be blocked as the result of a previous **WaitSync** command, and for additional **WaitSync** commands to be queued in the GL server, all for a single sync object. When such a sync object is signaled in this situation, the client will be unblocked, the server will be unblocked, and all such queued **WaitSync** commands will continue immediately when they are reached.

See section 5.2 for more information about blocking on a sync object in multiple GL contexts.

#### 4.1.2 Signaling

A fence sync object enters the signaled state only once the corresponding fence command has completed and signaled the sync object.

If the sync object being blocked upon will not be signaled in finite time (for example, by an associated fence command issued previously, but not yet flushed to the graphics pipeline), then **ClientWaitSync** may hang forever. To help prevent this behavior<sup>3</sup>, if the `SYNC_FLUSH_COMMANDS_BIT` bit is set in *flags*, and *sync* is unsignaled when **ClientWaitSync** is called, then the equivalent of **Flush** will be performed before blocking on *sync*.

Additional constraints on the use of sync objects are discussed in chapter 5.

State must be maintained to indicate which sync object names are currently in use. The state required for each sync object in use is an integer for the specific type, an integer for the condition, and a bit indicating whether the object is signaled or unsignaled. The initial values of sync object state are defined as specified by **FenceSync**.

#### 4.1.3 Sync Object Queries

Properties of sync objects may be queried using the command

```
void GetSynciv( sync sync, enum pname, sizei bufSize,
                 sizei *length, int *values );
```

The value or values being queried are returned in the parameters *length* and *values*.

---

<sup>3</sup> The simple flushing behavior defined by `SYNC_FLUSH_COMMANDS_BIT` will not help when waiting for a fence command issued in another context's command stream to complete. Applications which block on a fence sync object must take additional steps to assure that the context from which the corresponding fence command was issued has flushed that command to the graphics pipeline.

On success, **GetSynciv** replaces up to *bufSize* integers in *values* with the corresponding property values of the object being queried. The actual number of integers replaced is returned in *\*length*. If *length* is `NULL`, no length is returned.

If *pname* is `OBJECT_TYPE`, a single value representing the specific type of the sync object is placed in *values*. The only type supported is `SYNC_FENCE`.

If *pname* is `SYNC_STATUS`, a single value representing the status of the sync object (`SIGNALLED` or `UNSIGNALLED`) is placed in *values*.

If *pname* is `SYNC_CONDITION`, a single value representing the condition of the sync object is placed in *values*. The only condition supported is `SYNC_GPU_COMMANDS_COMPLETE`.

If *pname* is `SYNC_FLAGS`, a single value representing the flags with which the sync object was created is placed in *values*. No flags are currently supported.

### Errors

An `INVALID_VALUE` error is generated if *sync* is not the name of a sync object.

An `INVALID_ENUM` error is generated if *pname* is not one of the values described above.

An `INVALID_VALUE` error is generated if *bufSize* is negative.

The command

```
boolean IsSync( sync sync );
```

returns `TRUE` if *sync* is the name of a sync object. If *sync* is not the name of a sync object, or if an error condition occurs, **IsSync** returns `FALSE` (note that zero is not the name of a sync object).

Sync object names immediately become invalid after calling **DeleteSync**, as discussed in sections 4.1 and 5.2, but the underlying sync object will not be deleted until it is no longer associated with any fence command and no longer blocking any **\*WaitSync** command.

## 4.2 Query Objects and Asynchronous Queries

*Asynchronous queries* provide a mechanism to return information about the processing of a sequence of GL commands. Query types supported by the GL include

- Primitive queries with a target of `PRIMITIVES_GENERATED` (see section 13.3) return information on the number of primitives processed by

the GL. There may be at most the value of `MAX_VERTEX_STREAMS` active queries of this type.

- Primitive queries with a target of `TRANSFORM_FEEDBACK_PRIMITIVES_WRITTEN` (see section 13.3) return information on the number of primitives written to one or more buffer objects. There may be at most the value of `MAX_VERTEX_STREAMS` active queries of this type.
- Occlusion queries (see section 17.3.7) count the number of fragments or samples that pass the depth test, or set a boolean to true when any fragments or samples pass the depth test. There may be at most one active query of this type.
- Time elapsed queries (see section 4.3) record the amount of time needed to fully process a sequence of commands. There may be at most one active query of this type.
- Timer queries (see section 4.3) record the current time of the GL. There may be at most one active query of this type.

The results of asynchronous queries are not returned by the GL immediately after the completion of the last command in the set; subsequent commands can be processed while the query results are not complete. When available, the query results are stored in an associated query object. The commands described in section 4.2.1 provide mechanisms to determine when query results are available and return the actual results of the query. The name space for query objects is the unsigned integers, with zero reserved by the GL.

The command

```
void GenQueries(sizei n, uint *ids);
```

returns  $n$  previously unused query object names in *ids*. These names are marked as used, for the purposes of **GenQueries** only, but no object is associated with them until the first time they are used by **BeginQuery**, **BeginQueryIndexed**, or **QueryCounter** (see section 4.3).

### Errors

An `INVALID_VALUE` error is generated if  $n$  is negative.

Query objects are deleted by calling

```
void DeleteQueries(sizei n, const uint *ids);
```

*ids* contains *n* names of query objects to be deleted. After a query object is deleted, its name is again unused. If an active query object is deleted its name immediately becomes unused, but the underlying object is not deleted until it is no longer active (see section 5.1). Unused names in *ids* that have been marked as used for the purposes of **GenQueries** are marked as unused again. Unused names in *ids* are silently ignored, as is the value zero.

### Errors

An `INVALID_VALUE` error is generated if *n* is negative.

Each type of query, other than timer queries of type `TIMESTAMP`, supported by the GL has an active query object name for each of the possible active queries. If an active query object name is non-zero, the GL is currently tracking the corresponding information, and the query results will be written into that query object. If an active query object name is zero, no such information is being tracked.

A query object may be created and made active with the command

```
void BeginQueryIndexed( enum target, uint index,
                        uint id );
```

*target* indicates the type of query to be performed. The valid values of *target* are discussed in more detail in subsequent sections.

*index* is the index of the query and must be between zero and a *target*-specific maximum.

**BeginQueryIndexed** sets the active query object name for *target* and *index* to *id*.

If *id* is an unused query object name, the name is marked as used and associated with a new query object of the type specified by *target*. Otherwise *id* must be the name of an existing query object of that type.

### Errors

An `INVALID_ENUM` error is generated if *target* is not `SAMPLES_PASSED`, `ANY_SAMPLES_PASSED`, or `ANY_SAMPLES_PASSED_CONSERVATIVE` for an occlusion query; `TIME_ELAPSED` for a timer query; `PRIMITIVES_GENERATED` for a primitives generated query; or `TRANSFORM_FEEDBACK_PRIMITIVES_WRITTEN` for a primitives written query.

An `INVALID_VALUE` error is generated if *target* is `SAMPLES_PASSED`, `ANY_SAMPLES_PASSED`, `ANY_SAMPLES_PASSED_CONSERVATIVE`, or `TIME_ELAPSED`, and *index* is not zero.

An `INVALID_VALUE` error is generated if *target* is `PRIMITIVES_GENERATED` or `TRANSFORM_FEEDBACK_PRIMITIVES_WRITTEN`, and *index* is not in the range zero to the value of `MAX_VERTEX_STREAMS` minus one.

An `INVALID_OPERATION` error is generated if *id* is not a name returned from a previous call to **GenQueries**, or if such a name has since been deleted with **DeleteQueries**.

An `INVALID_OPERATION` error is generated if *id* is any of:

- zero
- the name of an existing query object whose type does not match *target*
- an active query object name for any *target* and *index*
- the active query object for conditional rendering (see section 10.10).

An `INVALID_OPERATION` error is generated if the active query object name for *target* and *index* is non-zero.

The command

```
void BeginQuery( enum target, uint id );
```

is equivalent to

```
BeginQueryIndexed (target, 0, id);
```

The command

```
void EndQueryIndexed( enum target, uint index );
```

marks the end of the sequence of commands to be tracked for the active query specified by *target* and *index*. The corresponding active query object is updated to indicate that query results are not available, and the active query object name for *target* and *index* is reset to zero. When the commands issued prior to **EndQueryIndexed** have completed and a final query result is available, the query object active when **EndQuery** was called is updated to contain the query result and to indicate that the query result is available.

*target* and *index* have the same meaning as for **BeginQueryIndexed**.

### Errors

An `INVALID_ENUM` error is generated if *target* is not `SAMPLES_PASSED`, `ANY_SAMPLES_PASSED`, `ANY_SAMPLES_PASSED_CONSERVATIVE`, `TIME_ELAPSED`, `PRIMITIVES_GENERATED`, or `TRANSFORM_FEEDBACK_PRIMITIVES_WRITTEN`.

An `INVALID_VALUE` error is generated if *target* is `SAMPLES_PASSED`, `ANY_SAMPLES_PASSED`, `ANY_SAMPLES_PASSED_CONSERVATIVE`, or `TIME_ELAPSED`, and *index* is not zero.

An `INVALID_VALUE` error is generated if *target* is `PRIMITIVES_GENERATED` or `TRANSFORM_FEEDBACK_PRIMITIVES_WRITTEN`, and *index* is not in the range zero to the value of `MAX_VERTEX_STREAMS` minus one.

An `INVALID_OPERATION` error is generated if the active query object name for *target* and *index* is zero.

The command

```
void EndQuery( enum target );
```

is equivalent to

```
EndQueryIndexed( target, 0 );
```

Query objects contain two pieces of state: a single bit indicating whether a query result is available, and an integer containing the query result value. The number of bits,  $n$ , used to represent the query result is implementation-dependent and may be determined as described in section 4.2.1. In the initial state of a query object, the result is not available (the flag is `FALSE`), and the result value is zero.

If the query result overflows (exceeds the value  $2^n - 1$ ), its value becomes undefined. It is recommended, but not required, that implementations handle this overflow case by saturating at  $2^n - 1$  and incrementing no further.

The necessary state for each possible active query *target* and *index* is an unsigned integer holding the active query object name (zero if no query object is active), and any state necessary to keep the current results of an asynchronous query in progress. Only a single type of occlusion query can be active at one time, so the required state for occlusion queries is shared.

### 4.2.1 Query Object Queries

The command

```
boolean IsQuery( uint id );
```

returns `TRUE` if *id* is the name of a query object. If *id* is zero, or if *id* is a non-zero value that is not the name of a query object, `IsQuery` returns `FALSE`.

Information about an active query object can be queried with the command

```
void GetQueryIndexediv( enum target, uint index,
                        enum pname, int *params );
```

*target* and *index* specify the active query, and have the same meaning as for **BeginQueryIndexed**.

If *pname* is `CURRENT_QUERY`, the name of the currently active query object for *target* and *index*, or zero if no query is active, will be placed in *params*. If *target* is `TIMESTAMP`, zero is always returned.

If *pname* is `QUERY_COUNTER_BITS`, *index* is ignored and the implementation-dependent number of bits used to hold the query result for *target* will be placed in *params*. The number of query counter bits may be zero, in which case the counter contains no useful information.

For primitive queries (`PRIMITIVES_GENERATED` and `TRANSFORM_FEEDBACK_PRIMITIVES_WRITTEN`) if the number of bits is non-zero, the minimum number of bits allowed is 32.

For occlusion queries with *target* `ANY_SAMPLES_PASSED` or `ANY_SAMPLES_PASSED_CONSERVATIVE`, if the number of bits is non-zero, the minimum number of bits is 1. For occlusion queries with *target* `SAMPLES_PASSED`, if the number of bits is non-zero, the minimum number of bits allowed is 32.

For timer queries (*target* `TIME_ELAPSED` and `TIMESTAMP`), if the number of bits is non-zero, the minimum number of bits allowed is 30. This will allow at least 1 second of timing.

### Errors

An `INVALID_ENUM` error is generated if *target* is not `SAMPLES_PASSED`, `ANY_SAMPLES_PASSED`, `ANY_SAMPLES_PASSED_CONSERVATIVE`, `TIMESTAMP`, `TIME_ELAPSED`, `PRIMITIVES_GENERATED`, or `TRANSFORM_FEEDBACK_PRIMITIVES_WRITTEN`.

An `INVALID_VALUE` error is generated if *target* is `SAMPLES_PASSED`, `ANY_SAMPLES_PASSED`, `ANY_SAMPLES_PASSED_CONSERVATIVE`, `TIMESTAMP`, or `TIME_ELAPSED`, and *index* is not zero.

An `INVALID_VALUE` error is generated if *target* is `PRIMITIVES_GENERATED` or `TRANSFORM_FEEDBACK_PRIMITIVES_WRITTEN`, and *index* is not in the range zero to the value of `MAX_VERTEX_STREAMS` minus one.

An `INVALID_ENUM` error is generated if *pname* is not `CURRENT_QUERY` or `QUERY_COUNTER_BITS`.

The command

```
void GetQueryiv( enum target, enum pname, int *params );
```



is equivalent to

```
GetQueryIndexediv (target, 0, pname, params);
```

The state of a query object can be queried with the commands

```
void GetQueryObjectiv(uint id, enum pname,
    int *params);
void GetQueryObjectiiv(uint id, enum pname,
    uint *params);
void GetQueryObjecti64v(uint id, enum pname,
    int64 *params);
void GetQueryObjectui64v(uint id, enum pname,
    uint64 *params);
```

*id* is the name of a query object.

There may be an indeterminate delay before a query object's result value is available. If *pname* is `QUERY_RESULT_AVAILABLE`, `FALSE` is returned if such a delay would be required; otherwise `TRUE` is returned. It must always be true that if any query object returns a result available of `TRUE`, all queries of the same type issued prior to that query must also return `TRUE`.

If *pname* is `QUERY_RESULT`, then the query object's result value is returned as a single integer in *params*. If the value is so large in magnitude that it cannot be represented with the requested type, then the nearest value representable using the requested type is returned. If the number of query counter bits for *target* is zero, then the result is returned as a single integer with the value zero. Querying `QUERY_RESULT` for any given query object forces that query to complete within a finite amount of time.

If multiple queries are issued using the same object name prior to calling **GetQueryObject\***, the result and availability information returned will always be from the last query issued. The results from any queries before the last one will be lost if they are not retrieved before starting a new query on the same *target* and *id*.

### Errors

An `INVALID_OPERATION` error is generated if *id* is not the name of a query object, or if the query object named by *id* is currently active.

An `INVALID_ENUM` error is generated if *pname* is not `QUERY_RESULT` or `QUERY_RESULT_AVAILABLE`.

### 4.3 Time Queries

Query objects may also be used to track the amount of time needed to fully complete a set of GL commands (a *time elapsed query*), or to determine the current time of the GL (a *timer query*).

When **BeginQuery** and **EndQuery** are called with a *target* of `TIME_ELAPSED`, the GL prepares to start and stop the timer used for time elapsed queries. The timer is started or stopped when the effects from all previous commands on the GL client and server state and the framebuffer have been fully realized. The **BeginQuery** and **EndQuery** commands may return before the timer is actually started or stopped. When the time elapsed query timer is finally stopped, the elapsed time (in nanoseconds) is written to the corresponding query object as the query result value, and the query result for that object is marked as available.

A timer query object is created with the command

```
void QueryCounter(uint id, enum target);
```

*target* must be `TIMESTAMP`. If *id* is an unused query object name, the name is marked as used and associated with a new query object of type `TIMESTAMP`. Otherwise *id* must be the name of an existing query object of that type.

When **QueryCounter** is called, the GL records the current time into the corresponding query object. The time is recorded after all previous commands on the GL client and server state and the framebuffer have been fully realized. When the time is recorded, the query result for that object is marked available. **QueryCounter** timer queries can be used within a **BeginQuery** / **EndQuery** block where the *target* is `TIME_ELAPSED` and it does not affect the result of that query object.

The current time of the GL may be queried by calling **GetInteger** or **GetInteger64v** with the symbolic constant `TIMESTAMP`. This will return the GL time after all previous commands have reached the GL server but have not yet necessarily executed. By using a combination of this synchronous get command and the asynchronous timestamp query object target, applications can measure the latency between when commands reach the GL server and when they are realized in the framebuffer.

#### Errors

An `INVALID_ENUM` error is generated if *target* is not `TIMESTAMP`.

An `INVALID_OPERATION` error is generated if *id* is not a name returned from a previous call to **GenQueries**, or if such a name has since been deleted with **DeleteQueries**.

An `INVALID_OPERATION` error is generated if *id* is the name of an exist-

ing query object whose type is not `TIMESTAMP`.

## Chapter 5

# Shared Objects and Multiple Contexts

This chapter describes special considerations for objects shared between multiple OpenGL contexts, including deletion behavior and how changes to shared objects are propagated between contexts.

Objects that may be shared between contexts include buffer objects, program and shader objects, renderbuffer objects, sampler objects, sync objects, and texture objects (except for the texture objects named zero).

Objects which contain references to other objects include framebuffer, program pipeline, query, transform feedback, and vertex array objects. Such objects are called *container objects* and are not shared.

Implementations may allow sharing between contexts implementing different OpenGL versions or different profiles of the same OpenGL version (see appendix D). However, implementation-dependent behavior may result when aspects and/or behaviors of such shared objects do not apply to, and/or are not described by more than one version or profile.

### 5.1 Object Deletion Behavior

#### 5.1.1 Side Effects of Shared Context Destruction

The *share list* is the group of all contexts which share objects. If a shared object is not explicitly deleted, then destruction of any individual context has no effect on that object unless it is the only remaining context in the share list. Once the last context on the share list is destroyed, all shared objects, and all other resources allocated for that context or share list, will be deleted and reclaimed by the imple-

mentation as soon as possible.

### 5.1.2 Automatic Unbinding of Deleted Objects

When a buffer, texture, or renderbuffer object is deleted, it is unbound from any bind points it is bound to in the current context, and detached from any attachments of container objects that are bound to the current context, as described for **DeleteBuffers**, **DeleteTextures**, and **DeleteRenderbuffers**. If the object binding was established with other related state (such as a buffer range in **BindBufferRange** or selected level and layer information in **FramebufferTexture** or **BindImageTexture**), that state is not affected by the automatic unbind. Bind points in other contexts are not affected. Attachments to unbound container objects, such as deletion of a buffer attached to a vertex array object which is not bound to the context, are not affected and continue to act as references on the deleted object, as described in the following section.

### 5.1.3 Deleted Object and Object Name Lifetimes

When a buffer, texture, renderbuffer, query, transform feedback, or sync object is deleted, its name immediately becomes invalid (e.g. is marked unused), but the underlying object will not be deleted until it is no longer *in use*. A buffer, texture, or renderbuffer object is in use while it is attached to any container object or bound to a context bind point in any context. A sync object is in use while there is a corresponding fence command which has not yet completed and signaled the sync object, or while there are any GL clients and/or servers blocked on the sync object as a result of **ClientWaitSync** or **WaitSync** commands. Query and transform feedback objects are in use so long as they are active, as described in sections 4.2 and 13.2.1, respectively.

When a shader object or program object is deleted, it is flagged for deletion, but its name remains valid until the underlying object can be deleted because it is no longer in use. A shader object is in use while it is attached to any program object. A program object is in use while it is attached to any program pipeline object or is a current program in any context.

Caution should be taken when deleting an object attached to a container object (such as a buffer object attached to a vertex array object, or a renderbuffer or texture attached to a framebuffer object), or a shared object bound in multiple contexts. Following its deletion, the object's name may be returned by **Gen\*** commands, even though the underlying object state and data may still be referred to by container objects, or in use by contexts other than the one in which the object was deleted. Such a container or other context may continue using the object, and may

still contain state identifying its name as being currently bound, until such time as the container object is deleted, the attachment point of the container object is changed to refer to another object, or another attempt to bind or attach the name is made in that context. Since the name is marked unused, binding the name will create a new object with the same name, and attaching the name will generate an error. The underlying storage backing a deleted object will not be reclaimed by the GL until all references to the object from container object attachment points or context binding points are removed.

## 5.2 Sync Objects and Multiple Contexts

When multiple GL clients and/or servers are blocked on a single sync object and that sync object is signaled, all such blocks are released. The order in which blocks are released is implementation-dependent.

## 5.3 Propagating Changes to Objects

GL objects contain two types of information, *data* and *state*. Collectively these are referred to below as the *contents* of an object. For the purposes of propagating changes to object contents as described below, data and state are treated consistently.

*Data* is information the GL implementation does not have to inspect, and does not have an operational effect. Currently, data consists of:

- Pixels in the framebuffer.
- The contents of the data stores of buffer objects, renderbuffers, and textures.

*State* determines the configuration of the rendering pipeline, and the GL implementation does have to inspect it.

In hardware-accelerated GL implementations, state typically lives in GPU registers, while data typically lives in GPU memory.

When the contents of an object *T* are changed, such changes are not always immediately visible, and do not always immediately affect GL operations involving that object. Changes may occur via any of the following means:

- State-setting commands, such as **TexParameter**.
- Data-setting commands, such as **TexSubImage\*** or **BufferSubData**.

- Data-setting through rendering to renderbuffers or textures attached to a framebuffer object.
- Data-setting through transform feedback operations followed by an **End-TransformFeedback** command.
- Commands that affect both state and data, such as **TexImage\*** and **BufferData**.
- Changes to mapped buffer data followed by a command such as **Unmap-Buffer** or **FlushMappedBufferRange**.
- Rendering commands that trigger shader invocations, where the shader performs image or buffer variable stores or atomic operations, or built-in atomic counter functions.

When  $T$  is a texture, the contents of  $T$  are construed to include the contents of the data store of  $T$ , even if  $T$ 's data store was modified via a different view of the data store.

### 5.3.1 Determining Completion of Changes to an object

The contents of an object  $T$  are considered to have been changed once a command such as described in section 5.3 has completed. Completion of a command<sup>1</sup> may be determined either by calling **Finish**, or by calling **FenceSync** and executing a **WaitSync** command on the associated sync object. The second method does not require a round trip to the GL server and may be more efficient, particularly when changes to  $T$  in one context must be known to have completed before executing commands dependent on those changes in another context.

### 5.3.2 Definitions

In the remainder of this section, the following terminology is used:

- An object  $T$  is *directly attached* to the current context if it has been bound to one of the context binding points. Examples include but are not limited to bound textures, bound framebuffer, bound vertex arrays, and current programs.

---

<sup>1</sup>The GL already specifies that a single context processes commands in the order they are received. This means that a change to an object in a context at time  $t$  must be completed by the time a command issued in the same context at time  $t + 1$  uses the result of that change.

- *T* is *indirectly attached* to the current context if it is attached to another object *C*, referred to as a *container object*, and *C* is itself directly or indirectly attached. Examples include but are not limited to renderbuffers or textures attached to framebuffers; buffers attached to vertex arrays; and shaders attached to programs.
- An object *T* which is directly attached to the current context may be *re-attached* by re-binding *T* at the same bind point. An object *T* which is indirectly attached to the current context may be re-attached by re-attaching the container object *C* to which *T* is attached.

*Corollary:* re-binding *C* to the current context re-attaches *C* and its hierarchy of contained objects.

### 5.3.3 Rules

The following rules must be obeyed by all GL implementations:

**Rule 1** *If the contents of an object T are changed in the current context while T is directly or indirectly attached, then all operations on T will use the new contents in the current context.*

*Note: The intent of this rule is to address changes in a single context only. The multi-context case is handled by the other rules.*

*Note: “Updates” via rendering or transform feedback are treated consistently with update via GL commands. Once **EndTransformFeedback** has been issued, any subsequent command in the same context that uses the results of the transform feedback operation will see the results. If a feedback loop is setup between rendering and transform feedback (see section 13.2.3), results will be undefined.*

**Rule 2** *While a container object C is bound, any changes made to the contents of C’s attachments in the current context are guaranteed to be seen. To guarantee seeing changes made in another context to objects attached to C, such changes must be completed in that other context (see section 5.3.1) prior to C being bound. Changes made in another context but not determined to have completed as described in section 5.3.1, or after C is bound in the current context, are not guaranteed to be seen.*

**Rule 3** *Changes to the contents of shared objects are not automatically propagated between contexts. If the contents of a shared object T are changed in a context other than the current context, and T is already directly or indirectly attached to the current context, any operations on the current context involving T via those attachments are not guaranteed to use its new contents.*



**Rule 4** *If the contents of an object T are changed in a context other than the current context, T must be attached or re-attached to at least one binding point in the current context, or at least one attachment point of a currently bound container object C, in order to guarantee that the new contents of T are visible in the current context.*

Note: “Attached or re-attached” means either attaching an object to a binding point it wasn’t already attached to, or attaching an object again to a binding point it was already attached.

Example: *If a texture image is bound to multiple texture bind points and the texture is changed in another context, re-binding the texture at any one of the texture bind points is sufficient to cause the changes to be visible at all texture bind points.*

## Chapter 6

# Buffer Objects

Buffer objects contain a data store holding a fixed-sized allocation of server memory. This chapter specifies commands to create, manage, and destroy buffer objects. Specific types of buffer objects and their uses are briefly described together with references to their full specification.

The command

```
void GenBuffers( size_t n, uint *buffers );
```

returns *n* previously unused buffer object names in *buffers*. These names are marked as used, for the purposes of **GenBuffers** only, but they acquire buffer state only when they are first bound with **BindBuffer** (see below), just as if they were unused.

### Errors

An `INVALID_VALUE` error is generated if *n* is negative.

Buffer objects are deleted by calling

```
void DeleteBuffers( size_t n, const uint *buffers );
```

*buffers* contains *n* names of buffer objects to be deleted. After a buffer object is deleted it has no contents, and its name is again unused. If any portion of a buffer object being deleted is mapped in the current context or any context current to another thread, it is as though **UnmapBuffer** (see section 6.3.1) is executed in each such context prior to deleting the data store of the buffer.

Unused names in *buffers* that have been marked as used for the purposes of **GenBuffers** are marked as unused again. Unused names in *buffers* are silently ignored, as is the value zero.

**Errors**

An `INVALID_VALUE` error is generated if  $n$  is negative.

The command

```
boolean IsBuffer( uint buffer );
```

returns `TRUE` if *buffer* is the name of an buffer object. If *buffer* is zero, or if *buffer* is a non-zero value that is not the name of an buffer object, **IsBuffer** returns `FALSE`.

## 6.1 Creating and Binding Buffer Objects

A buffer object is created by binding a name returned by **GenBuffers** to a buffer target. The binding is effected by calling

```
void BindBuffer( enum target, uint buffer );
```

*target* must be one of the targets listed in table 6.1. If the buffer object named *buffer* has not been previously bound, the GL creates a new state vector, initialized with a zero-sized memory buffer and comprising all the state and with the same initial values listed in table 6.2.

Buffer objects created by binding a name returned by **GenBuffers** to any of the valid *targets* are formally equivalent, but the GL may make different choices about storage location and layout based on the initial binding.

**BindBuffer** may also be used to bind an existing buffer object. If the bind is successful no change is made to the state of the newly bound buffer object, and any previous binding to *target* is broken.

While a buffer object is bound, GL operations on the target to which it is bound affect the bound buffer object, and queries of the target to which a buffer object is bound return state from the bound object. Operations on the target also affect any other bindings of that object.

If a buffer object is deleted while it is bound, all bindings to that object in the current context (i.e. in the thread that called **DeleteBuffers**) are reset to zero. Bindings to that buffer in other contexts are not affected, and the deleted buffer may continue to be used at any places it remains bound or attached, as described in section 5.1.

Initially, each buffer object target is bound to zero.

Target name	Purpose	Described in section(s)
ARRAY_BUFFER	Vertex attributes	10.3.8
ATOMIC_COUNTER_BUFFER	Atomic counter storage	7.7
COPY_READ_BUFFER	Buffer copy source	6.6
COPY_WRITE_BUFFER	Buffer copy destination	6.6
DISPATCH_INDIRECT_BUFFER	Indirect compute dispatch commands	19
DRAW_INDIRECT_BUFFER	Indirect command arguments	10.3.10
ELEMENT_ARRAY_BUFFER	Vertex array indices	10.3.9
PIXEL_PACK_BUFFER	Pixel read target	18.2, 22
PIXEL_UNPACK_BUFFER	Texture data source	8.4
SHADER_STORAGE_BUFFER	Read-write storage for shaders	7.8
TEXTURE_BUFFER	Texture data buffer	8.9
TRANSFORM_FEEDBACK_BUFFER	Transform feedback buffer	13.2
UNIFORM_BUFFER	Uniform block storage	7.6.2

Table 6.1: Buffer object binding targets.

Name	Type	Initial Value	Legal Values
BUFFER_SIZE	int64	0	any non-negative integer
BUFFER_USAGE	enum	STATIC_DRAW	STREAM_DRAW, STREAM_READ, STREAM_COPY, STATIC_DRAW, STATIC_READ, STATIC_COPY, DYNAMIC_DRAW, DYNAMIC_READ, DYNAMIC_COPY
BUFFER_ACCESS	enum	READ_WRITE	READ_ONLY, WRITE_ONLY, READ_WRITE
BUFFER_ACCESS_FLAGS	int	0	See section 6.3
BUFFER_MAPPED	boolean	FALSE	TRUE, FALSE
BUFFER_MAP_POINTER	void*	NULL	address
BUFFER_MAP_OFFSET	int64	0	any non-negative integer
BUFFER_MAP_LENGTH	int64	0	any non-negative integer

Table 6.2: Buffer object parameters and their values.

**Errors**

An `INVALID_ENUM` error is generated if *target* is not one of the targets listed in table 6.1.

An `INVALID_OPERATION` error is generated if *buffer* is not zero or a name returned from a previous call to **GenBuffers**, or if such a name has since been deleted with **DeleteBuffers**.

There is no buffer object corresponding to the name zero, so client attempts to modify or query buffer object state for a target bound to zero generate an `INVALID_OPERATION` error.

**6.1.1 Binding Buffer Objects to Indexed Targets**

Buffer objects may be created and bound to *indexed targets* by calling one of the commands

```
void BindBufferRange( enum target, uint index,  
    uint buffer, intptr offset, sizeiptr size );  
void BindBufferBase( enum target, uint index, uint buffer );
```

*target* must be one of `ATOMIC_COUNTER_BUFFER`, `SHADER_STORAGE_BUFFER`, `TRANSFORM_FEEDBACK_BUFFER` or `UNIFORM_BUFFER`. Additional language specific to each target is included in sections referred to for each target in table 6.1.

Each *target* represents an indexed array of buffer object binding points, as well as a single general binding point that can be used by other buffer object manipulation functions, such as **BindBuffer** or **MapBuffer**. Both commands bind the buffer object named by *buffer* to both the general binding point, and to the binding point in the array given by *index*. If the binds are successful no change is made to the state of the bound buffer object, and any previous bindings to the general binding point or to the binding point in the array are broken.

If the buffer object named *buffer* has not been previously bound, the GL creates a new state vector, initialized with a zero-sized memory buffer and comprising all the state and with the same initial values listed in table 6.2.

For **BindBufferRange**, *offset* specifies a starting offset into the buffer object *buffer*, and *size* specifies the amount of data that can be read from or written to the buffer object while used as an indexed target. Both *offset* and *size* are in basic machine units.

**BindBufferBase** binds the entire buffer, even when the size of the buffer is changed after the binding is established. *The starting offset is zero, and the*

amount of data that can be read from or written to the buffer is determined by the size of the bound buffer at the time the binding is used.

Regardless of the *size* specified with **BindBufferRange**, ~~or indirectly with **BindBufferBase**~~, the GL will never read or write beyond the end of a bound buffer. In some cases this constraint may result in visibly different behavior when a buffer overflow would otherwise result, such as described for transform feedback operations in section 13.2.2.

### Errors

An `INVALID_ENUM` error is generated if *target* is not one of the targets listed above.

An `INVALID_VALUE` error is generated if *index* is greater than or equal to the number of *target*-specific indexed binding points, as described in section 6.7.1.

An `INVALID_OPERATION` error is generated if *buffer* is not zero or a name returned from a previous call to **GenBuffers**, or if such a name has since been deleted with **DeleteBuffers**.

An `INVALID_VALUE` error is generated by **BindBufferRange** if *buffer* is non-zero and *size* is less than or equal to zero.

An `INVALID_VALUE` error is generated by **BindBufferRange** if *buffer* is non-zero and *offset* or *size* do not respectively satisfy the constraints described for those parameters for the specified *target*, as described in section 6.7.1.

## 6.2 Creating and Modifying Buffer Object Data Stores

The data store of a buffer object is created and optionally initialized by calling

```
void BufferData(enum target, sizeiptr size, const
                 void *data, enum usage);
```

with *target* set to one of the targets listed in table 6.1, *size* set to the size of the data store in basic machine units, and *data* pointing to the source data in client memory. If *data* is non-NULL, then the source data is copied to the buffer object's data store. If *data* is NULL, then the contents of the buffer object's data store are undefined.

*usage* is specified as one of nine enumerated values, indicating the expected application usage pattern of the data store. In the following descriptions, a buffer's data store is *sourced* when it is read from as a result of GL commands which specify images, or invoke shaders accessing buffer data as a result of drawing commands or compute shader dispatch.

The values are:

`STREAM_DRAW` The data store contents will be specified once by the application, and sourced at most a few times.

`STREAM_READ` The data store contents will be specified once by reading data from the GL, and queried at most a few times by the application.

`STREAM_COPY` The data store contents will be specified once by reading data from the GL, and sourced at most a few times

`STATIC_DRAW` The data store contents will be specified once by the application, and sourced many times.

`STATIC_READ` The data store contents will be specified once by reading data from the GL, and queried many times by the application.

`STATIC_COPY` The data store contents will be specified once by reading data from the GL, and sourced many times.

`DYNAMIC_DRAW` The data store contents will be respecified repeatedly by the application, and sourced many times.

`DYNAMIC_READ` The data store contents will be respecified repeatedly by reading data from the GL, and queried many times by the application.

`DYNAMIC_COPY` The data store contents will be respecified repeatedly by reading data from the GL, and sourced many times.

*usage* is provided as a performance hint only. The specified usage value does not constrain the actual usage pattern of the data store.

**BufferData** deletes any existing data store, and sets the values of the buffer object's state variables as shown in table 6.3.

If any portion of the buffer object is mapped in the current context or any context current to another thread, it is as though **UnmapBuffer** (see section 6.3.1) is executed in each such context prior to deleting the existing data store.

Clients must align data elements consistent with the requirements of the client platform, with an additional base-level requirement that an offset within a buffer to a datum comprising  $N$  basic machine units be a multiple of  $N$ .

### Errors

An `INVALID_OPERATION` error is generated if zero is bound to *target*.

An `INVALID_VALUE` error is generated if *size* is negative.

Name	Value
BUFFER_SIZE	<i>size</i>
BUFFER_USAGE	<i>usage</i>
BUFFER_ACCESS	READ_WRITE
BUFFER_ACCESS_FLAGS	0
BUFFER_MAPPED	FALSE
BUFFER_MAP_POINTER	NULL
BUFFER_MAP_OFFSET	0
BUFFER_MAP_LENGTH	0

Table 6.3: Buffer object initial state.

An `INVALID_ENUM` error is generated if *target* is not one of the targets listed in table 6.1.

An `INVALID_ENUM` error is generated if *usage* is not one of the nine usages described above.

An `OUT_OF_MEMORY` error is generated if the GL is unable to create a data store of the requested size.

To modify some or all of the data contained in a buffer object's data store, the client may use the command

```
void BufferSubData( enum target, intptr offset,
                    sizeiptr size, const void *data );
```

with *target* set to one of the targets listed in table 6.1. *offset* and *size* indicate the range of data in the buffer object that is to be replaced, in terms of basic machine units. *data* specifies a region of client memory *size* basic machine units in length, containing the data that replace the specified buffer range.

### Errors

An `INVALID_OPERATION` error is generated if zero is bound to *target*.

An `INVALID_ENUM` error is generated if *target* is not one of the targets listed in table 6.1.

An `INVALID_VALUE` error is generated if *offset* or *size* is negative, or if  $offset + size$  is greater than the value of `BUFFER_SIZE` for the buffer bound to *target*.

An `INVALID_OPERATION` error is generated if any part of the specified buffer range is mapped with `MapBufferRange` or `MapBuffer` (see sec-



tion 6.3).

### 6.2.1 Clearing Buffer Object Data Stores

To fill all or part of an existing buffer object's data store with constant values, call

```
void ClearBufferSubData( enum target, enum internalformat,
    intptr offset, sizeiptr size, enum format, enum type,
    const void *data );
```

with *target* set to the target to which the destination buffer is bound. *target* must be one of the targets listed in table 6.1. *internalformat* must be set to one of the format tokens listed in table 8.15. *format* and *type* specify the format and type of the source data and are interpreted as described in section 8.4.4.

*offset* is the offset, measured in basic machine units, into the buffer object's data store from which to begin filling, and *size* is the size, also in basic machine units, of the range to fill.

*data* is a pointer to an array of between one and four components containing the data to be used as the source of the constant fill value. The elements of *data* are converted by the GL into the format specified by *internalformat* in the manner described in section 2.2.1, and then used to fill the specified range of the destination buffer. If *data* is NULL, then the pointer is ignored and the sub-range of the buffer is filled with zeros.

#### Errors

An INVALID\_ENUM error is generated if *target* is not one of the targets listed in table 6.1.

An INVALID\_VALUE error is generated if zero is bound to *target*.

An INVALID\_ENUM error is generated if *internalformat* is not one of the format tokens listed in table 8.15.

An INVALID\_VALUE error is generated if *offset* or *size* are not multiples of the number of basic machine units for the internal format specified by *internalformat*. This value may be computed by multiplying the number of components for *internalformat* from table 8.15 by the size of the base type from that table.

An INVALID\_VALUE error is generated if *offset* or *size* is negative, or if  $offset + size$  is greater than the value of BUFFER\_SIZE for the buffer bound to *target*.

An INVALID\_OPERATION error is generated if any part of the specified buffer range is mapped with **MapBufferRange** or **MapBuffer** (see sec-

tion 6.3).

An `INVALID_VALUE` error is generated if *type* is not one of the types in table 8.2.

An `INVALID_VALUE` error is generated if *format* is not one of the formats in table 8.3.

The command

```
void ClearBufferData( enum target, enum internalformat,
                      enum format, enum type, const void *data );
```

is equivalent to calling **ClearBufferSubData** with *target*, *internalformat* and *data* as specified, *offset* zero, and *size* set to the value of `BUFFER_SIZE` for the buffer bound to *target*.

## 6.3 Mapping and Unmapping Buffer Data

All or part of the data store of a buffer object may be mapped into the client's address space by calling

```
void *MapBufferRange( enum target, intptr offset,
                      sizeiptr length, bitfield access );
```

with *target* set to one of the targets listed in table 6.1. *offset* and *length* indicate the range of data in the buffer object that is to be mapped, in terms of basic machine units. *access* is a bitfield containing flags which describe the requested mapping. These flags are described below.

If no error occurs, a pointer to the beginning of the mapped range is returned once all pending operations on that buffer have completed, and may be used to modify and/or query the corresponding range of the buffer, according to the following flag bits set in *access*:

- `MAP_READ_BIT` indicates that the returned pointer may be used to read buffer object data. No GL error is generated if the pointer is used to query a mapping which excludes this flag, but the result is undefined and system errors (possibly including program termination) may occur.
- `MAP_WRITE_BIT` indicates that the returned pointer may be used to modify buffer object data. No GL error is generated if the pointer is used to modify a mapping which excludes this flag, but the result is undefined and system errors (possibly including program termination) may occur.

If no error occurs, the pointer value returned by **MapBufferRange** must reflect an allocation aligned to the value of `MIN_MAP_BUFFER_ALIGNMENT` basic machine units. Subtracting *offset* basic machine units from the returned pointer will always produce a multiple of the value of `MIN_MAP_BUFFER_ALIGNMENT`.

Pointer values returned by **MapBufferRange** may not be passed as parameter values to GL commands. For example, they may not be used to specify array pointers, or to specify or query pixel or texture image data; such actions produce undefined results, although implementations may not check for such behavior for performance reasons.

Mappings to the data stores of buffer objects may have nonstandard performance characteristics. For example, such mappings may be marked as uncacheable regions of memory, and in such cases reading from them may be very slow. To ensure optimal performance, the client should use the mapping in a fashion consistent with the values of `BUFFER_USAGE` and *access*. Using a mapping in a fashion inconsistent with these values is liable to be multiple orders of magnitude slower than using normal memory.

The following optional flag bits in *access* may be used to modify the mapping:

- `MAP_INVALIDATE_RANGE_BIT` indicates that the previous contents of the specified range may be discarded. Data within this range are undefined with the exception of subsequently written data. No GL error is generated if subsequent GL operations access unwritten data, but the result is undefined and system errors (possibly including program termination) may occur. This flag may not be used in combination with `MAP_READ_BIT`.
- `MAP_INVALIDATE_BUFFER_BIT` indicates that the previous contents of the entire buffer may be discarded. Data within the entire buffer are undefined with the exception of subsequently written data. No GL error is generated if subsequent GL operations access unwritten data, but the result is undefined and system errors (possibly including program termination) may occur. This flag may not be used in combination with `MAP_READ_BIT`.
- `MAP_FLUSH_EXPLICIT_BIT` indicates that one or more discrete subranges of the mapping may be modified. When this flag is set, modifications to each subrange must be explicitly flushed by calling **FlushMappedBufferRange**. No GL error is set if a subrange of the mapping is modified and not flushed, but data within the corresponding subrange of the buffer are undefined. This flag may only be used in conjunction with `MAP_WRITE_BIT`. When this option is selected, flushing is strictly limited to regions that are explicitly indicated with calls to **FlushMappedBufferRange** prior to un-

Name	Value
BUFFER_ACCESS	Depends on <i>access</i> <sup>1</sup>
BUFFER_ACCESS_FLAGS	<i>access</i>
BUFFER_MAPPED	TRUE
BUFFER_MAP_POINTER	pointer to the data store
BUFFER_MAP_OFFSET	<i>offset</i>
BUFFER_MAP_LENGTH	<i>length</i>

Table 6.4: Buffer object state set by **MapBufferRange**.

<sup>1</sup> BUFFER\_ACCESS is set to READ\_ONLY, WRITE\_ONLY, or READ\_WRITE if *access* & (MAP\_READ\_BIT|MAP\_WRITE\_BIT) is respectively MAP\_READ\_BIT, MAP\_WRITE\_BIT, or MAP\_READ\_BIT|MAP\_WRITE\_BIT.

map; if this option is not selected **UnmapBuffer** will automatically flush the entire mapped range when called.

- MAP\_UNSYNCHRONIZED\_BIT indicates that the GL should not attempt to synchronize pending operations on the buffer prior to returning from **MapBufferRange**. No GL error is generated if pending operations which source or modify the buffer overlap the mapped region, but the result of such previous and any subsequent operations is undefined.

A successful **MapBufferRange** sets buffer object state values as shown in table 6.4.

### Errors

If an error occurs, **MapBufferRange** returns a NULL pointer.

An INVALID\_VALUE error is generated if *offset* or *length* is negative, if *offset* + *length* is greater than the value of BUFFER\_SIZE, or if *access* has any bits set other than those defined above.

An INVALID\_OPERATION error is generated for any of the following conditions:

- *length* is zero.
- zero is bound to *target*.
- The buffer is already in a mapped state.
- Neither MAP\_READ\_BIT nor MAP\_WRITE\_BIT is set.

- `MAP_READ_BIT` is set and any of `MAP_INVALIDATE_RANGE_BIT`, `MAP_INVALIDATE_BUFFER_BIT`, or `MAP_UNSYNCHRONIZED_BIT` is set.

- `MAP_FLUSH_EXPLICIT_BIT` is set and `MAP_WRITE_BIT` is not set.

An `OUT_OF_MEMORY` error is generated if `MapBufferRange` fails because memory for the mapping could not be obtained.

No error is generated if memory outside the mapped range is modified or queried, but the result is undefined and system errors (possibly including program termination) may occur.

The entire data store of a buffer object can be mapped into the client's address space by calling

```
void *MapBuffer( enum target, enum access );
```

`MapBuffer` is equivalent to

```
MapBufferRange( target, 0, length, flags );
```

where `length` is equal to the value of `BUFFER_SIZE` for the buffer bound to `target` and `flags` is equal to

- `MAP_READ_BIT`, if `access` is `READ_ONLY`
- `MAP_WRITE_BIT`, if `access` is `WRITE_ONLY`
- `MAP_READ_BIT | MAP_WRITE_BIT`, if `access` is `READ_WRITE`.

The pointer value returned by `MapBuffer` must be aligned to the value of `MIN_MAP_BUFFER_ALIGNMENT` basic machine units.

### Errors

An `INVALID_ENUM` error is generated if `access` is not `READ_ONLY`, `WRITE_ONLY`, or `READ_WRITE`.

Other errors are generated as described above for `MapBufferRange`.

If a buffer is mapped with the `MAP_FLUSH_EXPLICIT_BIT` flag, modifications to the mapped range may be indicated by calling

```
void FlushMappedBufferRange( enum target, intptr offset,
                             sizeiptr length );
```

with *target* set to one of the targets listed in table 6.1. *offset* and *length* indicate a modified subrange of the mapping, in basic machine units. The specified subrange to flush is relative to the start of the currently mapped range of buffer. **FlushMappedBufferRange** may be called multiple times to indicate distinct sub-ranges of the mapping which require flushing.

#### Errors

An `INVALID_ENUM` error is generated if *target* is not one of the targets listed in table 6.1.

An `INVALID_OPERATION` error is generated if zero is bound to *target*.

An `INVALID_OPERATION` error is generated if the buffer bound to *target* is not mapped, or is mapped without the `MAP_FLUSH_EXPLICIT_BIT` flag.

An `INVALID_VALUE` error is generated if *offset* or *length* is negative, or if *offset* + *length* exceeds the size of the mapping.

### 6.3.1 Unmapping Buffers

After the client has specified the contents of a mapped buffer range, and before the data in that range are dereferenced by any GL commands, the mapping must be relinquished by calling

```
boolean UnmapBuffer( enum target );
```

with *target* set to one of the targets listed in table 6.1. Unmapping a mapped buffer object invalidates the pointer to its data store and sets the object's `BUFFER_MAPPED`, `BUFFER_MAP_POINTER`, `BUFFER_ACCESS_FLAGS`, `BUFFER_MAP_OFFSET`, and `BUFFER_MAP_LENGTH` state variables to the initial values shown in table 6.3.

**UnmapBuffer** returns `TRUE` unless data values in the buffer's data store have become corrupted during the period that the buffer was mapped. Such corruption can be the result of a screen resolution change or other window system-dependent event that causes system heaps such as those for high-performance graphics memory to be discarded. GL implementations must guarantee that such corruption can occur only during the periods that a buffer's data store is mapped. If such corruption has occurred, **UnmapBuffer** returns `FALSE`, and the contents of the buffer's data store become undefined.

Unmapping that occurs as a side effect of buffer deletion (see section 5.1.2) or reinitialization by **BufferData** is not an error.

Buffer mappings are buffer object state, and are not affected by whether or not a context owning a buffer object is current.

**Errors**

An `INVALID_OPERATION` error is generated if the buffer data store is already in the unmapped state, and `FALSE` is returned.

**6.3.2 Effects of Mapping Buffers on Other GL Commands**

An `INVALID_OPERATION` error is generated by most, but not all GL commands when an attempt is detected by such a command to read data from or write data to a mapped buffer object.

Any command which does not detect these attempts, and performs such an invalid read or write, has undefined results and may result in GL interruption or termination.

**6.4 Effects of Accessing Outside Buffer Bounds**

Most, but not all GL commands operating on buffer objects will detect attempts to read from or write to a location in a bound buffer object at an offset less than zero, or greater than or equal to the buffer's size. When such an attempt is detected, a GL error is generated. Any command which does not detect these attempts, and performs such an invalid read or write, has undefined results, and may result in GL interruption or termination.

Robust buffer access can be enabled by creating a context with robust access enabled through the window system binding APIs. When enabled, any command unable to generate a GL error as described above, such as buffer object accesses from the active program, will not read or modify memory outside of the data store of the buffer object and will not result in GL interruption or termination. Out-of-bounds reads may return values from within the buffer object or zero values. Out-of-bounds writes may modify values within the buffer object or be discarded. Accesses made through resources attached to binding points are only protected within the buffer object from which the binding point is declared. For example, for an out-of-bounds access to a member variable of a uniform block, the access protection is provided within the uniform buffer object, and not for the bound buffer range for this uniform block.

**6.5 Invalidating Buffer Data**

All or part of the data store of a buffer object may be invalidated by calling

```
void InvalidateBufferSubData( uint buffer, intptr offset,
                             sizeiptr length );
```

with *buffer* set to the name of the buffer whose data store is being invalidated. *offset* and *length* specify the range of the data in the buffer object that is to be invalidated. Data in the specified range have undefined values after calling **InvalidateBufferSubData**.

### Errors

An `INVALID_VALUE` error is generated if *buffer* is zero or is not the name of an existing buffer object.

An `INVALID_VALUE` error is generated if *offset* or *length* is negative, or if *offset* + *length* is greater than the value of `BUFFER_SIZE` for *buffer*.

An `INVALID_OPERATION` error is generated if *buffer* is currently mapped by **MapBuffer**, or if the invalidate range intersects the range currently mapped by **MapBufferRange**.

The command

```
void InvalidateBufferData( uint buffer );
```

is equivalent to calling **InvalidateBufferSubData** with *offset* equal to zero and *length* equal to the value of `BUFFER_SIZE` for *buffer*.

## 6.6 Copying Between Buffers

All or part of the data store of a buffer object may be copied to the data store of another buffer object by calling

```
void CopyBufferSubData( enum readtarget, enum writetarget,
                        intptr readoffset, intptr writeoffset, sizeiptr size );
```

with *readtarget* and *writetarget* each set to one of the targets listed in table 6.1. While any of these targets may be used, the `COPY_READ_BUFFER` and `COPY_WRITE_BUFFER` targets are provided specifically for copies, so that they can be done without affecting other buffer binding targets that may be in use.

*writeoffset* and *size* specify the range of data in the buffer object bound to *writetarget* that is to be replaced, in terms of basic machine units. *readoffset* and *size* specify the range of data in the buffer object bound to *readtarget* that is to be copied to the corresponding region of *writetarget*.



**Errors**

An `INVALID_VALUE` error is generated if any of *readoffset*, *writeoffset*, or *size* are negative, if *readoffset* + *size* exceeds the size of the buffer object bound to *readtarget*, or if *writeoffset* + *size* exceeds the size of the buffer object bound to *writetarget*.

An `INVALID_VALUE` error is generated if the same buffer object is bound to both *readtarget* and *writetarget*, and the ranges [*readoffset*, *readoffset* + *size*) and [*writeoffset*, *writeoffset* + *size*) overlap.

An `INVALID_OPERATION` error is generated if zero is bound to *readtarget* or *writetarget*.

An `INVALID_OPERATION` error is generated if the buffer objects bound to either *readtarget* or *writetarget* are mapped.

## 6.7 Buffer Object Queries

The commands

```
void GetBufferParameteriv( enum target, enum pname,
    int *data );
void GetBufferParameteri64v( enum target, enum pname,
    int64 *data );
```

return information about a bound buffer object. *target* must be one of the targets listed in table 6.1, and *pname* must be one of the buffer object parameters in table 6.2, other than `BUFFER_MAP_POINTER`. The value of the specified parameter of the buffer object bound to *target* is returned in *data*.

**Errors**

An `INVALID_ENUM` error is generated if *target* is not one of the targets listed in table 6.1.

An `INVALID_OPERATION` error is generated if zero is bound to *target*.

An `INVALID_ENUM` error is generated if *pname* is not one of [the parameter names](#) the buffer object parameters other than `BUFFER_MAP_POINTER`.

The command

```
void GetBufferSubData( enum target, intptr offset,
    sizeiptr size, void *data );
```

queries the data contents of a buffer object. *target* must be one of the targets listed in table 6.1. *offset* and *size* indicate the range of data in the buffer object that is to be queried, in terms of basic machine units. *data* specifies a region of client memory, *size* basic machine units in length, into which the data is to be retrieved.

### Errors

An `INVALID_ENUM` error is generated if *target* is not one of the targets listed in table 6.1.

An `INVALID_OPERATION` error is generated if zero is bound to *target*.

An `INVALID_VALUE` error is generated if *offset* or *size* is negative, or if *offset* + *size* is greater than the value of `BUFFER_SIZE` for the buffer bound to *target*.

An `INVALID_OPERATION` error is generated if the buffer object bound to *target* is currently mapped.

While part or all of the data store of a buffer object is mapped, the pointer to the mapped range of the data store can be queried by calling

```
void GetBufferPointerv( enum target, enum pname, const
    void **params );
```

with *target* set to one of the targets listed in table 6.1 and *pname* set to `BUFFER_MAP_POINTER`. The single buffer map pointer is returned in *params*. **GetBufferPointerv** returns the `NULL` pointer value if the buffer's data store is not currently mapped, or if the requesting context did not map the buffer object's data store, and the implementation is unable to support mappings on multiple clients.

### Errors

An `INVALID_ENUM` error is generated if *target* is not one of the targets listed in table 6.1.

An `INVALID_ENUM` error is generated if *pname* is not `BUFFER_MAP_POINTER`.

An `INVALID_OPERATION` error is generated if zero is bound to *target*.

## 6.7.1 Indexed Buffer Object Limits and Binding Queries

Several types of buffer bindings support an indexed array of binding points for specific use by the GL, in addition to a single generic binding point for general management of buffers of that type. Each type of binding is described in table 6.5

together with the token names used to refer to each buffer in the array of binding points, the starting offset of the binding for each buffer in the array, any constraints on the corresponding *offset* value passed to **BindBufferRange** (see section 6.1.1), the size of the binding for each buffer in the array, any constraints on the corresponding *size* value passed to **BindBufferRange**, and the size of the array (the number of bind points supported).

To query which buffer objects are bound to an indexed array, call **GetIntegeri\_v** with *target* set to the name of the array binding points. *index* must be in the range zero to the number of bind points supported minus one. The name of the buffer object bound to *index* is returned in *values*. If no buffer object is bound for *index*, zero is returned in *values*.

To query the starting offset or size of the range of a buffer object binding in an indexed array, call **GetInteger64i\_v** with *target* set to respectively the starting offset or binding size name from table 6.5 for that array. *index* must be in the range zero to the number of bind points supported minus one. If the starting offset or size was not specified when the buffer object was bound (e.g. if it was bound with **BindBufferBase**), or if no buffer object is bound to the *target* array at *index*, zero is returned<sup>1</sup>.

### Errors

An `INVALID_VALUE` error is generated by **GetIntegeri\_v** and **GetInteger64i\_v** if *target* is one of the array binding point names, starting offset names, or binding size names from table 6.5 and *index* is greater than or equal to the number of binding points for *target* as described in the same table.

## 6.8 Buffer Object State

The state required to support buffer objects consists of binding names for each of the buffer targets in table 6.1, and for each of the indexed buffer targets in section 6.1.1. The state required for index buffer targets for atomic counters, shader storage, transform feedback, and uniform buffer array bindings is summarized in tables 23.46, 23.47, 23.48, and 23.49 respectively.

Additionally, each vertex array has an associated binding so there is a buffer object binding for each of the vertex attribute arrays. The initial values for all buffer object bindings is zero.

The state of each buffer object consists of a buffer size in basic machine units, a

<sup>1</sup>A zero size is a sentinel value indicating that the actual binding range size is determined by the size of the bound buffer at the time the binding is used.

Atomic counter array bindings (see sec. 7.7.2)	
binding points	ATOMIC_COUNTER_BUFFER_BINDING
starting offset	ATOMIC_COUNTER_BUFFER_START
<i>offset</i> restriction	multiple of 4
binding size	ATOMIC_COUNTER_BUFFER_SIZE
<i>size</i> restriction	none
no. of bind points	value of MAX_ATOMIC_COUNTER_BUFFER_BINDINGS
Shader storage array bindings (see sec. 7.8)	
binding points	SHADER_STORAGE_BUFFER_BINDING
starting offset	SHADER_STORAGE_BUFFER_START
<i>offset</i> restriction	multiple of value of SHADER_STORAGE_BUFFER_OFFSET_ALIGNMENT
binding size	SHADER_STORAGE_BUFFER_SIZE
<i>size</i> restriction	none
no. of bind points	value of MAX_SHADER_STORAGE_BUFFER_BINDINGS
Transform feedback array bindings (see sec. 13.2.2)	
binding points	TRANSFORM_FEEDBACK_BUFFER_BINDING
starting offset	TRANSFORM_FEEDBACK_BUFFER_START
<i>offset</i> restriction	multiple of 4
binding size	TRANSFORM_FEEDBACK_BUFFER_SIZE
<i>size</i> restriction	multiple of 4
no. of bind points	value of MAX_TRANSFORM_FEEDBACK_BUFFERS
Uniform buffer array bindings (see sec. 7.6.3)	
binding points	UNIFORM_BUFFER_BINDING
starting offset	UNIFORM_BUFFER_START
<i>offset</i> restriction	multiple of value of UNIFORM_BUFFER_OFFSET_ALIGNMENT
binding size	UNIFORM_BUFFER_SIZE
<i>size</i> restriction	none
no. of bind points	value of MAX_UNIFORM_BUFFER_BINDINGS

Table 6.5: Indexed buffer object limits and binding queries

usage parameter, an access parameter, a mapped boolean, two integers for the offset and size of the mapped region, a pointer to the mapped buffer (`NULL` if unmapped), and the sized array of basic machine units for the buffer data.

## Chapter 7

# Programs and Shaders

This chapter specifies commands to create, manage, and destroy program and shader objects. Commands and functionality applicable only to specific shader stages (for example, vertex attributes used as inputs by vertex shaders) are described together with those stages in chapters 10 and 15.

A *shader* specifies operations that are meant to occur on data as it moves through different programmable stages of the OpenGL processing pipeline, starting with vertices specified by the application and ending with fragments prior to being written to the framebuffer. The programming language used for shaders is described in the OpenGL Shading Language Specification .

To use a shader, shader source code is first loaded into a *shader object* and then *compiled*. A shader object corresponds to a stage in the rendering pipeline referred to as its *shader stage* or *shader type*.

Alternatively, pre-compiled shader binary code may be directly loaded into a shader object. An implementation must support shader compilation (the boolean value `SHADER_COMPILER` must be `TRUE`). If the integer value of `NUM_SHADER_BINARY_FORMATS` is greater than zero, then shader binary loading is supported.

One or more shader objects are attached to a *program object*. The program object is then *linked*, which generates executable code from all the compiled shader objects attached to the program. Alternatively, pre-compiled program binary code may be directly loaded into a program object (see section 7.5).

When program objects are bound to a shader stage, they become the *current program object* for that stage. When the current program object for a shader stage includes a shader of that type, it is considered the *active program object* for that stage.

The current program object for all stages may be set at once using a single unified program object, or the current program object may be set for each stage

individually using a *separable program object* where different separable program objects may be current for other stages. The set of separable program objects current for all stages are collected in a program pipeline object that must be bound for use. When a linked program object is made active for one of the stages, the corresponding executable code is used to perform processing for that stage.

Shader stages including *vertex shaders*, *tessellation control shaders*, *tessellation evaluation shaders*, *geometry shaders*, *fragment shaders*, and *compute shaders* can be created, compiled, and linked into program objects.

Vertex shaders describe the operations that occur on vertex attributes. Tessellation control and evaluation shaders are used to control the operation of the tessellator, and are described in section 11.2. Geometry shaders affect the processing of primitives assembled from vertices (see section 11.3). Fragment shaders affect the processing of fragments during rasterization (see section 15). A single program object can contain all of these shaders, or any subset thereof.

Compute shaders perform general-purpose computation for dispatched arrays of shader invocations (see section 19), but do not operate on primitives processed by the other shader types.

Shaders can reference several types of variables as they execute. *Uniforms* are per-program variables that are constant during program execution (see section 7.6). *Buffer variables* (see section 7.8) are similar to uniforms, but are stored in buffer object memory which may be written to, and is persistent across multiple shader invocations. *Subroutine uniform variables* (see section 7.9) are similar to uniforms but are context state, rather than program object state. *Samplers* (see section 7.10) are a special form of uniform used for texturing (see chapter 8). *Images* (see section 7.11) are a special form of uniform identifying a level of a texture to be accessed using built-in shader functions as described in section 8.25. *Output variables* hold the results of shader execution that are used later in the pipeline. Each of these variable types is described in more detail below.

## 7.1 Shader Objects

The name space for shader objects is the unsigned integers, with zero reserved for the GL. This name space is shared with program objects. The following sections define commands that operate on shader and program objects.

To create a shader object, use the command

```
uint CreateShader( enum type );
```

The shader object is empty when it is created. The *type* argument specifies the type of shader object to be created and must be one of the values in table 7.1 indicating

<i>type</i>	Shader Stage
VERTEX_SHADER	Vertex shader
TESS_CONTROL_SHADER	Tessellation control shader
TESS_EVALUATION_SHADER	Tessellation evaluation shader
GEOMETRY_SHADER	Geometry shader
FRAGMENT_SHADER	Fragment shader
COMPUTE_SHADER	Compute shader

Table 7.1: **CreateShader** *type* values and the corresponding shader stages.

the corresponding shader stage. A non-zero name that can be used to reference the shader object is returned.

#### Errors

An `INVALID_ENUM` error is generated and zero is returned if *type* is not one of the values in table 7.1,

The command

```
void ShaderSource( uint shader, sizei count, const
                  char *const *string, const int *length );
```

loads source code into the shader object named *shader*. *string* is an array of *count* pointers to optionally null-terminated character strings that make up the source code. The *length* argument is an array with the number of `chars` in each string (the string length). If an element in *length* is negative, its accompanying string is null-terminated. If *length* is `NULL`, all strings in the *string* argument are considered null-terminated. The **ShaderSource** command sets the source code for the *shader* to the text strings in the *string* array. If *shader* previously had source code loaded into it, the existing source code is completely replaced. Any length passed in excludes the null terminator in its count.

The strings that are loaded into a shader object are expected to form the source code for a valid shader as defined in the OpenGL Shading Language Specification

#### Errors

An `INVALID_VALUE` error is generated if *shader* is not the name of either a program or shader object.



An `INVALID_OPERATION` error is generated if *shader* is the name of a program object.

An `INVALID_VALUE` error is generated if *count* is negative.

Once the source code for a shader has been loaded, a shader object can be compiled with the command

```
void CompileShader( uint shader );
```

Each shader object has a boolean status, `COMPILE_STATUS`, that is modified as a result of compilation. This status can be queried with **GetShaderiv** (see section 7.13). This status will be set to `TRUE` if *shader* was compiled without errors and is ready for use, and `FALSE` otherwise. Compilation can fail for a variety of reasons as listed in the OpenGL Shading Language Specification . If **CompileShader** failed, any information about a previous compile is lost. Thus a failed compile does not restore the old state of *shader*.

Changing the source code of a shader object with **ShaderSource** does not change its compile status or the compiled shader code.

Each shader object has an information log, which is a text string that is overwritten as a result of compilation. This information log can be queried with **GetShaderInfoLog** to obtain more information about the compilation attempt (see section 7.13).

### Errors

An `INVALID_VALUE` error is generated if *shader* is not the name of either a program or shader object.

An `INVALID_OPERATION` error is generated if *shader* is the name of a program object.

Resources allocated by the shader compiler may be released with the command

```
void ReleaseShaderCompiler( void );
```

This is a hint from the application, and does not prevent later use of the shader compiler. If shader source is loaded and compiled after **ReleaseShaderCompiler** has been called, **CompileShader** must succeed provided there are no errors in the shader source.

The range and precision for different numeric formats supported by the shader compiler may be determined with the command **GetShaderPrecisionFormat** (see section 7.13).

Shader objects can be deleted with the command

```
void DeleteShader(uint shader);
```

If *shader* is not attached to any program object, it is deleted immediately. Otherwise, *shader* is flagged for deletion and will be deleted when it is no longer attached to any program object. If an object is flagged for deletion, its boolean status bit `DELETE_STATUS` is set to true. The value of `DELETE_STATUS` can be queried with **GetShaderiv** (see section 7.13). **DeleteShader** will silently ignore the value zero.

### Errors

An `INVALID_VALUE` error is generated if *shader* is neither zero nor the name of either a program or shader object.

An `INVALID_OPERATION` error is generated if *shader* is not zero and is the name of a `__` object.

The command

```
boolean IsShader(uint shader);
```

returns `TRUE` if *shader* is the name of a shader object. If *shader* is zero, or a non-zero value that is not the name of a shader object, **IsShader** returns `FALSE`. No error is generated if *shader* is not a valid shader object name.

## 7.2 Shader Binaries

Precompiled shader binaries may be loaded with the command

```
void ShaderBinary(sizei count, const uint *shaders,  
enum binaryformat, const void *binary, sizei length);
```

*shaders* contains a list of *count* shader object handles. Each handle refers to a unique shader type, and may correspond to any of the shader stages in table 7.1. *binary* points to *length* bytes of pre-compiled binary shader code in client memory, and *binaryformat* denotes the format of the pre-compiled code.

The binary image will be decoded according to the extension specification defining the specified *binaryformat*. OpenGL defines no specific binary formats, but does provide a mechanism to obtain token values for such formats provided by extensions. The number of shader binary formats supported can be obtained by querying the value of `NUM_SHADER_BINARY_FORMATS`. The list of specific binary

formats supported can be obtained by querying the value of `SHADER_BINARY_FORMATS`.

Depending on the types of the shader objects in *shaders*, **ShaderBinary** will individually load binary shaders, or load an executable binary that contains an optimized set of shaders stored in the same binary.

#### Errors

An `INVALID_VALUE` error is generated if *count* or *length* is negative.

An `INVALID_ENUM` error is generated if *binaryformat* is not a supported format returned in `SHADER_BINARY_FORMATS`.

An `INVALID_VALUE` error is generated if the data pointed to by *binary* does not match the specified *binaryformat*.

An `INVALID_VALUE` error is generated if any of the handles in *shaders* is not the name of either a program or shader object.

An `INVALID_OPERATION` error is generated if any of the handles in *shader* is the name of a program object.

An `INVALID_OPERATION` error is generated if more than one of the handles in *shaders* refers to the same type of shader object.

Additional errors corresponding to specific binary formats may be generated as specified by the extensions defining those formats.

If **ShaderBinary** fails, the old state of shader objects for which the binary was being loaded will not be restored.

Note that if shader binary interfaces are supported, then a GL implementation may require that an optimized set of shader binaries that were compiled together be specified to **LinkProgram**. Not specifying an optimized pair may cause **LinkProgram** to fail.

## 7.3 Program Objects

A program object is created with the command

```
uint CreateProgram(void);
```

Program objects are empty when they are created. A non-zero name that can be used to reference the program object is returned. If an error occurs, zero will be returned.

To attach a shader object to a program object, use the command

```
void AttachShader(uint program, uint shader);
```

Shader objects may be attached to program objects before source code has been loaded into the shader object, or before the shader object has been compiled. Multiple shader objects of the same type may be attached to a single program object, and a single shader object may be attached to more than one program object.

#### Errors

An `INVALID_VALUE` error is generated if *program* is not the name of either a program or shader object.

An `INVALID_OPERATION` error is generated if *program* is the name of a shader object.

An `INVALID_VALUE` error is generated if *shader* is not the name of either a program or shader object.

An `INVALID_OPERATION` error is generated if *shader* is the name of a program object.

An `INVALID_OPERATION` error is generated if *shader* is already attached to *program*.

To detach a shader object from a program object, use the command

```
void DetachShader( uint program, uint shader );
```

If *shader* has been flagged for deletion and is not attached to any other program object, it is deleted.

#### Errors

An `INVALID_VALUE` error is generated if *program* is not the name of either a program or shader object.

An `INVALID_OPERATION` error is generated if *program* is the name of a shader object.

An `INVALID_VALUE` error is generated if *shader* is not the name of either a program or shader object.

An `INVALID_OPERATION` error is generated if *shader* is the name of a program object.

An `INVALID_OPERATION` error is generated if *shader* is not attached to *program*.

In order to use the shader objects contained in a program object, the program object must be linked. The command

```
void LinkProgram( uint program );
```

will link the program object named *program*. Each program object has a boolean status, `LINK_STATUS`, that is modified as a result of linking. This status can be queried with **GetProgramiv** (see section 7.13). This status will be set to `TRUE` if a valid executable is created, and `FALSE` otherwise.

Linking can fail for a variety of reasons as specified in the OpenGL Shading Language Specification, as well as any of the following reasons:

- One or more of the shader objects attached to *program* are not compiled successfully.
- More active uniform or active sampler variables are used in *program* than allowed (see sections 7.6, 7.10, and 11.3.3).
- The program object contains objects to form a tessellation control shader (see section 11.2.1), and
  - the program is not separable and contains no objects to form a vertex shader;
  - the output patch vertex count is not specified in any compiled tessellation control shader object; or
  - the output patch vertex count is specified differently in multiple tessellation control shader objects.
- The program object contains objects to form a tessellation evaluation shader (see section 11.2.3), and
  - the program is not separable and contains no objects to form a vertex shader;
  - the tessellation primitive mode is not specified in any compiled tessellation evaluation shader object; or
  - the tessellation primitive mode, spacing, vertex order, or point mode is specified differently in multiple tessellation evaluation shader objects.
- The program object contains objects to form a geometry shader (see section 11.3), and
  - the program is not separable and contains no objects to form a vertex shader;

- the input primitive type, output primitive type, or maximum output vertex count is not specified in any compiled geometry shader object; or
  - the input primitive type, output primitive type, or maximum output vertex count is specified differently in multiple geometry shader objects.
- The program object contains objects to form a compute shader (see section 19) and,
    - The program object also contains objects to form any other type of shader.

If **LinkProgram** failed, any information about a previous link of that program object is lost. Thus, a failed link does not restore the old state of *program*.

#### Errors

An `INVALID_VALUE` error is generated if *program* is not the name of either a program or shader object.

An `INVALID_OPERATION` error is generated if *program* is the name of a shader object.

When successfully linked program objects are used for rendering operations, they may access GL state and interface with other stages of the GL pipeline through *active variables* and *active interface blocks*. The GL provides various commands allowing applications to enumerate and query properties of active variables and interface blocks for a specified program. If one of these commands is called with a program for which **LinkProgram** succeeded, the information recorded when the program was linked is returned. If one of these commands is called with a program for which **LinkProgram** failed, no error is generated unless otherwise noted. Implementations may return information on variables and interface blocks that would have been active had the program been linked successfully. In cases where the link failed because the program required too many resources, these commands may help applications determine why limits were exceeded. However, the information returned in this case is implementation-dependent and may be incomplete. If one of these commands is called with a program for which **LinkProgram** had never been called, no error is generated unless otherwise noted, and the program object is considered to have no active variables or interface blocks.

Each program object has an information log that is overwritten as a result of a link operation. This information log can be queried with **GetProgramInfoLog** to obtain more information about the link operation or the validation information (see section 7.13).

If a program has been successfully linked by **LinkProgram** or loaded by **ProgramBinary** (see section 7.5), it can be made part of the current rendering state for all shader stages with the command

```
void UseProgram( uint program );
```

If *program* is non-zero, this command will make *program* the current program object. This will install executable code as part of the current rendering state for each shader stage present when the program was last successfully linked. If **UseProgram** is called with *program* set to zero, then there is no current program object.

The executable code for an individual shader stage is taken from the current program for that stage. If there is a current program object established by **UseProgram**, that program is considered current for all stages. Otherwise, if there is a bound program pipeline object (see section 7.4), the program bound to the appropriate stage of the pipeline object is considered current. If there is no current program object or bound program pipeline object, no program is current for any stage. The current program for a stage is considered *active* if it contains executable code for that stage; otherwise, no program is considered active for that stage. If there is no active program for the vertex or fragment shader stages, the results of vertex and/or fragment processing will be undefined. However, this is not an error. If there is no active program for the tessellation control, tessellation evaluation, or geometry shader stages, those stages are ignored. If there is no active program for the compute shader stage, compute dispatches will generate an error. The active program for the compute shader stage has no effect on the processing of vertices, geometric primitives, and fragments, and the active program for all other shader stages has no effect on compute dispatches.

#### Errors

An `INVALID_VALUE` error is generated if *program* is neither zero nor the name of either a program or shader object.

An `INVALID_OPERATION` error is generated if *program* is not zero and is not the name of a shader object.

An `INVALID_OPERATION` error is generated if *program* has not been linked, or was last linked unsuccessfully. The current rendering state is not modified.

While a program object is in use, applications are free to modify attached shader objects, compile attached shader objects, attach additional shader objects, and detach shader objects. These operations do not affect the link status or executable code of the program object.

If **LinkProgram** or **ProgramBinary** successfully re-links a program object that is active for any shader stage, then the newly generated executable code will be installed as part of the current rendering state for all shader stages where the program is active. Additionally, the newly generated executable code is made part of the state of any program pipeline for all stages where the program is attached.

If a program object that is active for any shader stage is re-linked unsuccessfully, the link status will be set to `FALSE`, but any existing executables and associated state will remain part of the current rendering state until a subsequent call to **UseProgram**, **UseProgramStages**, or **BindProgramPipeline** removes them from use. If such a program is attached to any program pipeline object, the existing executables and associated state will remain part of the program pipeline object until a subsequent call to **UseProgramStages** removes them from use. An unsuccessfully linked program may not be made part of the current rendering state by **UseProgram** or added to program pipeline objects by **UseProgramStages** until it is successfully re-linked. If such a program was attached to a program pipeline at the time of a failed link, its existing executable may still be made part of the current rendering state indirectly by **BindProgramPipeline**.

To set a program object parameter, call

```
void ProgramParameteri( uint program, enum pname,
                        int value );
```

*pname* identifies which parameter to set for *program*. *value* holds the value being set.

If *pname* is `PROGRAM_SEPARABLE`, *value* must be `TRUE` or `FALSE`, and indicates whether *program* can be bound for individual pipeline stages using **UseProgramStages** after it is next linked.

If *pname* is `PROGRAM_BINARY_RETRIEVABLE_HINT`, *value* must be `TRUE` or `FALSE`, and indicates whether a program binary is likely to be retrieved later, as described for **ProgramBinary** in section 7.5.

State set with this command does not take effect until after the next time **LinkProgram** or **ProgramBinary** is called successfully.

#### Errors

An `INVALID_VALUE` error is generated if *program* is not the name of either a program or shader object.

An `INVALID_OPERATION` error is generated if *program* is the name of a shader object.

An `INVALID_ENUM` error is generated if *pname* is not `PROGRAM_SEPARABLE` or `PROGRAM_BINARY_RETRIEVABLE_HINT`.



An `INVALID_VALUE` error is generated if *value* is not `TRUE` or `FALSE`.

Program objects can be deleted with the command

```
void DeleteProgram( uint program );
```

If *program* is not current for any GL context, is not the active program for any program pipeline object, and is not the current program for any stage of any program pipeline object, it is deleted immediately. Otherwise, *program* is flagged for deletion and will be deleted after all of these conditions become true. When a program object is deleted, all shader objects attached to it are detached. **DeleteProgram** will silently ignore the value zero.

### Errors

An `INVALID_VALUE` error is generated if *program* is neither zero nor the name of either a program or shader object.

An `INVALID_OPERATION` error is generated if *program* is not zero and is the name of a .. object.

The command

```
boolean IsProgram( uint program );
```

returns `TRUE` if *program* is the name of a program object. If *program* is zero, or a non-zero value that is not the name of a program object, **IsProgram** returns `FALSE`. No error is generated if *program* is not a valid program object name.

The command

```
uint CreateShaderProgramv( enum type, sizei count,
    const char *const *strings );
```

creates a stand-alone program from an array of null-terminated source code strings for a single shader type. **CreateShaderProgramv** is equivalent to (assuming no errors are generated):

```
const uint shader = CreateShader(type);
if (shader) {
    ShaderSource(shader, count, strings, NULL);
    CompileShader(shader);
    const uint program = CreateProgram();
```

```

if (program) {
    int compiled = FALSE;
    GetShaderiv(shader, COMPILE_STATUS, &compiled);
    ProgramParameteri(program, PROGRAM_SEPARABLE, TRUE);
    if (compiled) {
        AttachShader(program, shader);
        LinkProgram(program);
        DetachShader(program, shader);
    }
    append-shader-info-log-to-program-info-log
}
DeleteShader(shader);
return program;
} else {
    return 0;
}

```

Because no shader is returned by **CreateShaderProgramv** and the shader that is created is deleted in the course of the command sequence, the info log of the shader object is copied to the program so the shader's failed info log for the failed compilation is accessible to the application.

If an error is generated, zero is returned.

### Errors

An `INVALID_ENUM` error is generated and zero is returned if *type* is not one of the values in table 7.1.

An `INVALID_VALUE` error is generated if *count* is negative.

Other errors are generated if the supplied shader code fails to compile and link, as described for the commands in the pseudocode sequence above, but all such errors are generated without any side effects of executing those commands.

### 7.3.1 Program Interfaces

When a program object is made part of the current rendering state, its executable code may communicate with other GL pipeline stages or application code through a variety of *interfaces*. When a program is linked, the GL builds a list of *active resources* for each interface. Examples of active resources include variables, interface blocks, and subroutines used by shader code. Resources referenced in shader

code are considered *active* unless the compiler and linker can conclusively determine that they have no observable effect on the results produced by the executable code of the program. For example, variables might be considered inactive if they are declared but not used in executable code, used only in a clause of an `if` statement that would never be executed, used only in functions that are never called, or used only in computations of temporary variables having no effect on any shader output. In cases where the compiler or linker cannot make a conclusive determination, any resource referenced by shader code will be considered active. The set of active resources for any interface is implementation-dependent because it depends on various analysis and optimizations performed by the compiler and linker.

If a program is linked successfully, the GL will generate lists of active resources based on the executable code produced by the link. If a program is linked unsuccessfully, the link may have failed for a number of reasons, including cases where the program required more resources than supported by the implementation. Implementations are permitted, but not required, to record lists of resources that would have been considered active had the program linked successfully. If an implementation does not record information for any given interface, the corresponding list of active resources is considered empty. If a program has never been linked, all lists of active resources are considered empty.

The GL provides a number of commands to query properties of the interfaces of a program object. Each such command accepts a *programInterface* token, identifying a specific interface. The supported values for *programInterface* are as follows:

- `UNIFORM` corresponds to the set of active uniform variables (see section 7.6) used by *program*.
- `UNIFORM_BLOCK` corresponds to the set of active uniform blocks (see section 7.6) used by *program*.
- `ATOMIC_COUNTER_BUFFER` corresponds to the set of active atomic counter buffer binding points (see section 7.6) used by *program*.
- `PROGRAM_INPUT` corresponds to the set of active input variables used by the first shader stage of *program*. If *program* includes multiple shader stages, input variables from any shader stage other than the first will not be enumerated.
- `PROGRAM_OUTPUT` corresponds to the set of active output variables (see section 11.1.2.1) used by the last shader stage of *program*. If *program* includes multiple shader stages, output variables from any shader stage other than the last will not be enumerated.

- VERTEX\_SUBROUTINE, TESS\_CONTROL\_SUBROUTINE, TESS\_EVALUATION\_SUBROUTINE, GEOMETRY\_SUBROUTINE, FRAGMENT\_SUBROUTINE, and COMPUTE\_SUBROUTINE correspond to the set of active subroutines for the vertex, tessellation control, tessellation evaluation, geometry, fragment, and compute shader stages of *program*, respectively (see section 7.9).
- VERTEX\_SUBROUTINE\_UNIFORM, TESS\_CONTROL\_SUBROUTINE\_UNIFORM, TESS\_EVALUATION\_SUBROUTINE\_UNIFORM, GEOMETRY\_SUBROUTINE\_UNIFORM, FRAGMENT\_SUBROUTINE\_UNIFORM, and COMPUTE\_SUBROUTINE\_UNIFORM correspond to the set of active subroutine uniform variables used by the vertex, tessellation control, tessellation evaluation, geometry, fragment, and compute shader stages of *program*, respectively (see section 7.9).
- TRANSFORM\_FEEDBACK\_VARYING corresponds to the set of output variables in the last non-fragment stage of *program* that would be captured when transform feedback is active (see section 13.2.3).
- BUFFER\_VARIABLE corresponds to the set of active buffer variables used by *program* (see section 7.8).
- SHADER\_STORAGE\_BLOCK corresponds to the set of active shader storage blocks used by *program* (see section 7.8)

When building a list of active variable or interface blocks, resources with aggregate types (such as arrays or structures) may produce multiple entries in the active resource list for the corresponding interface. Additionally, each active variable, interface block, or subroutine in the list is assigned an associated name string that can be used by applications to refer to the resource. For interfaces involving variables, interface blocks, or subroutines, the entries of active resource lists are generated as follows:

- For an active variable declared as a single instance of a basic type, a single entry will be generated, using the variable name from the shader source.
- For an active variable declared as an array of basic types (e.g. not an array of structures or an array of arrays), a single entry will be generated, with its name string formed by concatenating the name of the array and the string "[0]".
- For an active variable declared as a structure, a separate entry will be generated for each active structure member. The name of each entry is formed by

concatenating the name of the structure, the "." character, and the name of the structure member. If a structure member to enumerate is itself a structure or array, these enumeration rules are applied recursively.

- For an active variable declared as an array of an aggregate data type (structures or arrays), a separate entry will be generated for each active array element, unless noted immediately below. The name of each entry is formed by concatenating the name of the array, the "[" character, an integer identifying the element number, and the "]" character. These enumeration rules are applied recursively, treating each enumerated array element as a separate active variable.
- For an active shader storage block member declared as an array, an entry will be generated only for the first array element, regardless of its type. Such block members are referred to as *top-level arrays*. If the block member is an aggregate type, the enumeration rules are applied recursively. During this process, arrays of aggregate data types will enumerate each element separately.
- For an active interface block not declared as an array of block instances, a single entry will be generated, using the block name from the shader source.
- For an active interface block declared as an array of instances, separate entries will be generated for each active instance. The name of the instance is formed by concatenating the block name, the "[" character, an integer identifying the instance number, and the "]" character.
- For an active subroutine, a single entry will be generated, using the subroutine name from the shader source.

When an integer array element or block instance number is part of the name string, it will be specified in decimal form without a "+" or "-" sign or any extra leading zeroes. Additionally, the name string will not include white space anywhere in the string.

The order of the active resource list is implementation-dependent for all interfaces except for `TRANSFORM_FEEDBACK_VARYING`. For `TRANSFORM_FEEDBACK_VARYING`, the active resource list will use the variable order specified in the most recent call to **TransformFeedbackVaryings** before the last call to **LinkProgram**.

For the `ATOMIC_COUNTER_BUFFER` interface, the list of active buffer binding points is built by identifying each unique binding point associated with one or more

active atomic counter uniform variables. Active atomic counter buffers do not have an associated name string.

For the `UNIFORM`, `PROGRAM_INPUT`, `PROGRAM_OUTPUT`, and `TRANSFORM_FEEDBACK_VARYING` interfaces, the active resource list will include all active variables for the interface, including any active built-in variables.

For `PROGRAM_INPUT` and `PROGRAM_OUTPUT` interfaces for shaders that receive or produce patch primitives, the active resource list will include both per-vertex and per-patch inputs and outputs.

For the `TRANSFORM_FEEDBACK_VARYING` interface, the active resource list will include entries for the special varying names `gl_NextBuffer`, `gl_SkipComponents1`, `gl_SkipComponents2`, `gl_SkipComponents3`, and `gl_SkipComponents4` (see section 11.1.2.1). These variables are used to control how varying values are written to transform feedback buffers. When enumerating the properties of such resources, these variables are considered to have a `TYPE` of `NONE` and an `ARRAY_SIZE` of 0 (`gl_NextBuffer`), 1, 2, 3, and 4, respectively.

When a program is linked successfully, active variables in the `UNIFORM`, `PROGRAM_INPUT`, `PROGRAM_OUTPUT`, or any of the subroutine uniform interfaces, are assigned one or more signed integer *locations*. These locations can be used by commands to assign values to uniforms and subroutine uniforms, to identify generic vertex attributes associated with vertex shader inputs, or to identify fragment color output numbers and indices associated with fragment shader outputs. For such variables declared as arrays, separate locations will be assigned to each active array element. Not all active variables are assigned valid locations; the following variables will have an effective location of -1:

- uniforms declared as atomic counters
- members of a uniform block
- built-in inputs, outputs, and uniforms (starting with `gl_`)
- inputs (except for vertex shader inputs) not declared with a `location layout` qualifier
- outputs (except for fragment shader outputs) not declared with a `location layout` qualifier

If a program has not been linked or was last linked unsuccessfully, no locations will be assigned.

The command

```
void GetProgramInterfaceiv( uint program,
    enum programInterface, enum pname, int *params );
```

queries a property of the interface *programInterface* in program *program*, returning its value in *params*. The property to return is specified by *pname*.

If *pname* is `ACTIVE_RESOURCES`, the value returned is the number of resources in the active resource list for *programInterface*. If the list of active resources for *programInterface* is empty, zero is returned.

If *pname* is `MAX_NAME_LENGTH`, the value returned is the length of the longest active name string for an active resource in *programInterface*. This length includes an extra character for the null terminator. If the list of active resources for *programInterface* is empty, zero is returned.

If *pname* is `MAX_NUM_ACTIVE_VARIABLES`, the value returned is the number of active variables belonging to the interface block or atomic counter buffer resource in *programInterface* with the most active variables. If the list of active resources for *programInterface* is empty, zero is returned.

If *pname* is `MAX_NUM_COMPATIBLE_SUBROUTINES`, the value returned is the number of compatible subroutines for the active subroutine uniform in *programInterface* with the most compatible subroutines. If the list of active resources for *programInterface* is empty, zero is returned.

### Errors

An `INVALID_VALUE` error is generated if *program* is not the name of either a program or shader object.

An `INVALID_OPERATION` error is generated if *program* is the name of a shader object.

An `INVALID_ENUM` error is generated if *programInterface* is not one of the interfaces described in the introduction to section 7.3.1.

An `INVALID_ENUM` error is generated if *pname* is not `ACTIVE_RESOURCES`, `MAX_NAME_LENGTH`, `MAX_NUM_ACTIVE_VARIABLES`, or `MAX_NUM_COMPATIBLE_SUBROUTINES`.

An `INVALID_OPERATION` error is generated if *pname* is `MAX_NAME_LENGTH` and *programInterface* is `ATOMIC_COUNTER_BUFFER`, since active atomic counter buffer resources are not assigned name strings.

An `INVALID_OPERATION` error is generated if *pname* is `MAX_NUM_ACTIVE_VARIABLES` and *programInterface* is not `UNIFORM_BLOCK`, `ATOMIC_COUNTER_BUFFER`, or `SHADER_STORAGE_BLOCK`.

An `INVALID_OPERATION` error is generated if *pname* is `MAX_NUM_COMPATIBLE_SUBROUTINES` and *programInterface* is not `VERTEX_SUBROUTINE_UNIFORM`, `TESS_CONTROL_SUBROUTINE_UNIFORM`, `TESS_EVALUATION_SUBROUTINE_UNIFORM`, `GEOMETRY_SUBROUTINE_UNIFORM`, `FRAGMENT_SUBROUTINE_UNIFORM`, or

```
COMPUTE_SUBROUTINE_UNIFORM.
```

Each entry in the active resource list for an interface is assigned a unique unsigned integer index in the range  $0..N - 1$ , where  $N$  is the number of entries in the active resource list. The command

```
uint GetProgramResourceIndex( uint program,
                               enum programInterface, const char *name );
```

returns the unsigned integer index assigned to a resource named *name* in the interface type *programInterface* of program object *program*.

If *name* exactly matches the name string of one of the active resources for *programInterface*, the index of the matched resource is returned. Additionally, if *name* would exactly match the name string of an active resource if "[0]" were appended to *name*, the index of the matched resource is returned. Otherwise, *name* is considered not to be the name of an active resource, and `INVALID_INDEX` is returned. Note that if an interface enumerates a single active resource list entry for an array variable (e.g., "a[0]"), a *name* identifying any array element other than the first (e.g., "a[1]") is not considered to match.

If *programInterface* is `TRANSFORM_FEEDBACK_VARYING`, `INVALID_INDEX` is returned when querying the special *names* `gl_NextBuffer`, `gl_SkipComponents1`, `gl_SkipComponents2`, `gl_SkipComponents3`, and `gl_SkipComponents4`, even if those names were provided to **TransformFeedbackVaryings** (see section 11.1.2.1).

### Errors

An `INVALID_VALUE` error is generated if *program* is not the name of either a program or shader object.

An `INVALID_OPERATION` error is generated if *program* is the name of a shader object.

An `INVALID_ENUM` error is generated if *programInterface* is not one of the interfaces described in the introduction to section 7.3.1.

An `INVALID_ENUM` error is generated if *programInterface* is `ATOMIC_COUNTER_BUFFER`, since active atomic counter buffer resources are not assigned name strings.

The command

```
void GetProgramResourceName( uint program,
                              enum programInterface, uint index, sizei bufSize,
                              sizei *length, char *name );
```



returns the name string assigned to the single active resource with an index of *index* in the interface *programInterface* of program object *program*.

The name string assigned to the active resource identified by *index* is returned as a null-terminated string in *name*. The actual number of characters written into *name*, excluding the null terminator, is returned in *length*. If *length* is `NULL`, no length is returned. The maximum number of characters that may be written into *name*, including the null terminator, is specified by *bufSize*. If the length of the name string (including the null terminator) is greater than *bufSize*, the first *bufSize* – 1 characters of the name string will be written to *name*, followed by a null terminator. If *bufSize* is zero, no error is generated but no characters will be written to *name*. The length of the longest name string for *programInterface*, including a null terminator, can be queried by calling **GetProgramInterfaceiv** with a *pname* of `MAX_NAME_LENGTH`.

### Errors

An `INVALID_VALUE` error is generated if *program* is not the name of either a program or shader object.

An `INVALID_OPERATION` error is generated if *program* is the name of a shader object.

An `INVALID_ENUM` error is generated if *programInterface* is not one of the interfaces described in the introduction to section 7.3.1.

An `INVALID_ENUM` error is generated if *programInterface* is `ATOMIC_COUNTER_BUFFER`, since active atomic counter buffer resources are not assigned name strings.

An `INVALID_VALUE` error is generated if *index* is greater than or equal to the number of entries in the active resource list for *programInterface*.

An `INVALID_VALUE` error is generated if *bufSize* is negative.

The command

```
void GetProgramResourceiv( uint program,
    enum programInterface, uint index, sizei propCount,
    const enum *props, sizei bufSize, sizei *length,
    int *params );
```

returns values for multiple properties of a single active resource with an index of *index* in the interface *programInterface* of program object *program*. Values for *propCount* properties specified by the array *props* are returned.

The values associated with the properties of the active resource are written to consecutive entries in *params*, in increasing order according to position in *props*. If

no error is generated, only the first *bufSize* integer values will be written to *params*; any extra values will not be written. If *length* is not NULL, the actual number of values written to *params* will be written to *length*.

Property	Supported Interfaces
NAME_LENGTH	all but ATOMIC_COUNTER_BUFFER
TYPE	UNIFORM, PROGRAM_INPUT, PROGRAM_OUTPUT, TRANSFORM_FEEDBACK_VARYING, BUFFER_VARIABLE
ARRAY_SIZE	UNIFORM, BUFFER_VARIABLE, PROGRAM_INPUT, PROGRAM_OUTPUT, VERTEX_SUBROUTINE_UNIFORM, TESS_CONTROL_SUBROUTINE_UNIFORM, TESS_EVALUATION_SUBROUTINE_UNIFORM, GEOMETRY_SUBROUTINE_UNIFORM, FRAGMENT_SUBROUTINE_UNIFORM, COMPUTE_SUBROUTINE_UNIFORM, TRANSFORM_FEEDBACK_VARYING
OFFSET, BLOCK_INDEX, ARRAY_STRIDE, MATRIX_STRIDE, IS_ROW_MAJOR	UNIFORM, BUFFER_VARIABLE
ATOMIC_COUNTER_BUFFER_INDEX	UNIFORM
BUFFER_BINDING, BUFFER_DATA_SIZE, NUM_ACTIVE_VARIABLES, ACTIVE_VARIABLES	UNIFORM_BLOCK, ATOMIC_COUNTER_BUFFER_SHADER_STORAGE_BLOCK
REFERENCED_BY_VERTEX_SHADER, REFERENCED_BY_TESS_CONTROL_SHADER, REFERENCED_BY_TESS_EVALUATION_SHADER, REFERENCED_BY_GEOMETRY_SHADER, REFERENCED_BY_FRAGMENT_SHADER, REFERENCED_BY_COMPUTE_SHADER	UNIFORM, UNIFORM_BLOCK, ATOMIC_COUNTER_BUFFER, SHADER_STORAGE_BLOCK, BUFFER_VARIABLE, PROGRAM_INPUT, PROGRAM_OUTPUT
<b>GetProgramResourceiv</b> properties continued on next page	

GetProgramResourceiv properties continued from previous page	
Property	Supported Interfaces
NUM_COMPATIBLE_SUBROUTINES, COMPATIBLE_SUBROUTINES	VERTEX_SUBROUTINE_UNIFORM, TESS_CONTROL_SUBROUTINE_ UNIFORM, TESS_EVALUATION_ SUBROUTINE_UNIFORM, GEOMETRY_ SUBROUTINE_UNIFORM, FRAGMENT_ SUBROUTINE_UNIFORM, COMPUTE_ SUBROUTINE_UNIFORM
TOP_LEVEL_ARRAY_SIZE, TOP_ LEVEL_ARRAY_STRIDE	BUFFER_VARIABLE
LOCATION	UNIFORM, PROGRAM_INPUT, PROGRAM_OUTPUT, VERTEX_ SUBROUTINE_UNIFORM, TESS_ CONTROL_SUBROUTINE_UNIFORM, TESS_EVALUATION_SUBROUTINE_ UNIFORM, GEOMETRY_SUBROUTINE_ UNIFORM, FRAGMENT_SUBROUTINE_ UNIFORM, COMPUTE_SUBROUTINE_ UNIFORM
LOCATION_INDEX	PROGRAM_OUTPUT
IS_PER_PATCH	PROGRAM_INPUT, PROGRAM_OUTPUT

Table 7.2: GetProgramResourceiv properties and supported interfaces

For the property NAME\_LENGTH, a single integer identifying the length of the name string associated with an active variable, interface block, or subroutine is written to *params*. The name length includes a terminating null character.

For the property TYPE, a single integer identifying the type of an active variable is written to *params*. The integer returned is one of the values found in table 7.3.

Type Name Token	Keyword	Attrib	Xfb	Buffer
FLOAT	float	•	•	•
FLOAT_VEC2	vec2	•	•	•
FLOAT_VEC3	vec3	•	•	•
(Continued on next page)				

OpenGL Shading Language Type Tokens (continued)				
Type Name Token	Keyword	Attrib	Xfb	Buffer
FLOAT_VEC4	vec4	•	•	•
DOUBLE	double	•	•	•
DOUBLE_VEC2	dvec2	•	•	•
DOUBLE_VEC3	dvec3	•	•	•
DOUBLE_VEC4	dvec4	•	•	•
INT	int	•	•	•
INT_VEC2	ivec2	•	•	•
INT_VEC3	ivec3	•	•	•
INT_VEC4	ivec4	•	•	•
UNSIGNED_INT	uint	•	•	•
UNSIGNED_INT_VEC2	uvec2	•	•	•
UNSIGNED_INT_VEC3	uvec3	•	•	•
UNSIGNED_INT_VEC4	uvec4	•	•	•
BOOL	bool			•
BOOL_VEC2	bvec2			•
BOOL_VEC3	bvec3			•
BOOL_VEC4	bvec4			•
FLOAT_MAT2	mat2	•	•	•
FLOAT_MAT3	mat3	•	•	•
FLOAT_MAT4	mat4	•	•	•
FLOAT_MAT2x3	mat2x3	•	•	•
FLOAT_MAT2x4	mat2x4	•	•	•
FLOAT_MAT3x2	mat3x2	•	•	•
FLOAT_MAT3x4	mat3x4	•	•	•
FLOAT_MAT4x2	mat4x2	•	•	•
FLOAT_MAT4x3	mat4x3	•	•	•
DOUBLE_MAT2	dmat2	•	•	•
DOUBLE_MAT3	dmat3	•	•	•
DOUBLE_MAT4	dmat4	•	•	•
DOUBLE_MAT2x3	dmat2x3	•	•	•
DOUBLE_MAT2x4	dmat2x4	•	•	•
DOUBLE_MAT3x2	dmat3x2	•	•	•
DOUBLE_MAT3x4	dmat3x4	•	•	•
DOUBLE_MAT4x2	dmat4x2	•	•	•
DOUBLE_MAT4x3	dmat4x3	•	•	•
(Continued on next page)				

OpenGL Shading Language Type Tokens (continued)				
Type Name Token	Keyword	Attrib	Xfb	Buffer
SAMPLER_1D	sampler1D			
SAMPLER_2D	sampler2D			
SAMPLER_3D	sampler3D			
SAMPLER_CUBE	samplerCube			
SAMPLER_1D_SHADOW	sampler1DShadow			
SAMPLER_2D_SHADOW	sampler2DShadow			
SAMPLER_1D_ARRAY	sampler1DArray			
SAMPLER_2D_ARRAY	sampler2DArray			
SAMPLER_CUBE_MAP_ARRAY	samplerCubeArray			
SAMPLER_1D_ARRAY_SHADOW	sampler1DArrayShadow			
SAMPLER_2D_ARRAY_SHADOW	sampler2DArrayShadow			
SAMPLER_2D_MULTISAMPLE	sampler2DMS			
SAMPLER_2D_MULTISAMPLE_- ARRAY	sampler2DMSArray			
SAMPLER_CUBE_SHADOW	samplerCubeShadow			
SAMPLER_CUBE_MAP_ARRAY_- SHADOW	samplerCube- ArrayShadow			
SAMPLER_BUFFER	samplerBuffer			
SAMPLER_2D_RECT	sampler2DRect			
SAMPLER_2D_RECT_SHADOW	sampler2DRectShadow			
INT_SAMPLER_1D	isampler1D			
INT_SAMPLER_2D	isampler2D			
INT_SAMPLER_3D	isampler3D			
INT_SAMPLER_CUBE	isamplerCube			
INT_SAMPLER_1D_ARRAY	isampler1DArray			
INT_SAMPLER_2D_ARRAY	isampler2DArray			
INT_SAMPLER_CUBE_MAP_- ARRAY	isamplerCubeArray			
INT_SAMPLER_2D_- MULTISAMPLE	isampler2DMS			
INT_SAMPLER_2D_- MULTISAMPLE_ARRAY	isampler2DMSArray			
INT_SAMPLER_BUFFER	isamplerBuffer			
INT_SAMPLER_2D_RECT	isampler2DRect			
UNSIGNED_INT_SAMPLER_1D	usampler1D			
(Continued on next page)				

OpenGL Shading Language Type Tokens (continued)				
Type Name Token	Keyword	Attrib	Xfb	Buffer
UNSIGNED_INT_SAMPLER_2D	usampler2D			
UNSIGNED_INT_SAMPLER_3D	usampler3D			
UNSIGNED_INT_SAMPLER_- CUBE	usamplerCube			
UNSIGNED_INT_SAMPLER_- 1D_ARRAY	usampler1DArray			
UNSIGNED_INT_SAMPLER_- 2D_ARRAY	usampler2DArray			
UNSIGNED_INT_SAMPLER_- CUBE_MAP_ARRAY	usamplerCubeArray			
UNSIGNED_INT_SAMPLER_- 2D_MULTISAMPLE	usampler2DMS			
UNSIGNED_INT_SAMPLER_- 2D_MULTISAMPLE_ARRAY	usampler2DMSArray			
UNSIGNED_INT_SAMPLER_- BUFFER	usamplerBuffer			
UNSIGNED_INT_SAMPLER_- 2D_RECT	usampler2DRect			
IMAGE_1D	image1D			
IMAGE_2D	image2D			
IMAGE_3D	image3D			
IMAGE_2D_RECT	image2DRect			
IMAGE_CUBE	imageCube			
IMAGE_BUFFER	imageBuffer			
IMAGE_1D_ARRAY	image1DArray			
IMAGE_2D_ARRAY	image2DArray			
IMAGE_CUBE_MAP_ARRAY	imageCubeArray			
IMAGE_2D_MULTISAMPLE	image2DMS			
IMAGE_2D_MULTISAMPLE_- ARRAY	image2DMSArray			
INT_IMAGE_1D	iimage1D			
INT_IMAGE_2D	iimage2D			
INT_IMAGE_3D	iimage3D			
INT_IMAGE_2D_RECT	iimage2DRect			
INT_IMAGE_CUBE	iimageCube			
(Continued on next page)				

OpenGL Shading Language Type Tokens (continued)				
Type Name Token	Keyword	Attrib	Xfb	Buffer
INT_IMAGE_BUFFER	iimageBuffer			
INT_IMAGE_1D_ARRAY	iimage1DArray			
INT_IMAGE_2D_ARRAY	iimage2DArray			
INT_IMAGE_CUBE_MAP_ARRAY	iimageCubeArray			
INT_IMAGE_2D_MULTISAMPLE	iimage2DMS			
INT_IMAGE_2D_- MULTISAMPLE_ARRAY	iimage2DMSArray			
UNSIGNED_INT_IMAGE_1D	uimage1D			
UNSIGNED_INT_IMAGE_2D	uimage2D			
UNSIGNED_INT_IMAGE_3D	uimage3D			
UNSIGNED_INT_IMAGE_2D_- RECT	uimage2DRect			
UNSIGNED_INT_IMAGE_CUBE	uimageCube			
UNSIGNED_INT_IMAGE_- BUFFER	uimageBuffer			
UNSIGNED_INT_IMAGE_1D_- ARRAY	uimage1DArray			
UNSIGNED_INT_IMAGE_2D_- ARRAY	uimage2DArray			
UNSIGNED_INT_IMAGE_- CUBE_MAP_ARRAY	uimageCubeArray			
UNSIGNED_INT_IMAGE_2D_- MULTISAMPLE	uimage2DMS			
UNSIGNED_INT_IMAGE_2D_- MULTISAMPLE_ARRAY	uimage2DMSArray			
UNSIGNED_INT_ATOMIC_- COUNTER	atomic_uint			

Table 7.3: OpenGL Shading Language type tokens, and corresponding shading language keywords declaring each such type. Types whose “Attrib” column are marked may be declared as vertex attributes (see section 11.1.1). Types whose “Xfb” column are marked may be the types of variable returned by transform feedback (see section 11.1.2.1). Types whose “Buffer” column are marked may be declared as buffer variables (see section 7.8).

For the property `ARRAY_SIZE`, a single integer identifying the number of active array elements of an active variable is written to *params*. The array size returned is in units of the type associated with the property `TYPE`. For active variables not corresponding to an array of basic types, the value zero is written to *params*.

For the property `BLOCK_INDEX`, a single integer identifying the index of the active interface block containing an active variable is written to *params*. If the variable is not the member of an interface block, the value -1 is written to *params*.

For the property `OFFSET`, a single integer identifying the offset of an active variable is written to *params*. For active variables backed by a buffer object, the value written is the offset, in basic machine units, relative to the base of buffer range holding the values of the variable. For active variables not backed by a buffer object, an offset of -1 is written to *params*.

For the property `ARRAY_STRIDE`, a single integer identifying the stride between array elements in an active variable is written to *params*. For active variables declared as an array of basic types, the value written is the difference, in basic machine units, between the offsets of consecutive elements in an array. For active variables not declared as an array of basic types, zero is written to *params*. For active variables not backed by a buffer object, -1 is written to *params*, regardless of the variable type.

For the property `MATRIX_STRIDE`, a single integer identifying the stride between columns of a column-major matrix or rows of a row-major matrix is written to *params*. For active variables declared a single matrix or array of matrices, the value written is the difference, in basic machine units, between the offsets of consecutive columns or rows in each matrix. For active variables not declared as a matrix or array of matrices, zero is written to *params*. For active variables not backed by a buffer object, -1 is written to *params*, regardless of the variable type.

For the property `IS_ROW_MAJOR`, a single integer identifying whether an active variable is a row-major matrix is written to *params*. For active variables backed by a buffer object, declared as a single matrix or array of matrices, and stored in row-major order, one is written to *params*. For all other active variables, zero is written to *params*.

For the property `ATOMIC_COUNTER_BUFFER_INDEX`, a single integer identifying the index of the active atomic counter buffer containing an active variable is written to *params*. If the variable is not an atomic counter uniform, the value -1 is written to *params*.

For the property `BUFFER_BINDING`, the index of the buffer binding point associated with the active uniform block, shader storage block, or atomic counter buffer is written to *params*.

For the property `BUFFER_DATA_SIZE`, the implementation-dependent minimum total buffer object size is written to *params*. This value is the size, in basic



machine units, required to hold all active variables associated with an active uniform block, shader storage block, or atomic counter buffer. If the final member of an active shader storage block is an array with no declared size, the minimum buffer size is computed assuming the array was declared as an array with one element.

For the property `NUM_ACTIVE_VARIABLES`, the number of active variables associated with an active uniform block, shader storage block, or atomic counter buffer is written to *params*.

For the property `ACTIVE_VARIABLES`, an array of active variable indices associated with an active uniform block, shader storage block, or atomic counter buffer is written to *params*. The number of values written to *params* for an active resource is given by the value of the property `NUM_ACTIVE_VARIABLES` for the resource.

For the properties `REFERENCED_BY_VERTEX_SHADER`, `REFERENCED_BY_TESS_CONTROL_SHADER`, `REFERENCED_BY_TESS_EVALUATION_SHADER`, `REFERENCED_BY_GEOMETRY_SHADER`, `REFERENCED_BY_FRAGMENT_SHADER`, and `REFERENCED_BY_COMPUTE_SHADER`, a single integer is written to *params*, identifying whether the active resource is referenced by the vertex, tessellation control, tessellation evaluation, geometry, fragment, or compute shaders, respectively, in the program object. The value 1 is written to *params* if an active variable is referenced by the corresponding shader, or if an active uniform block, shader storage block, or atomic counter buffer contains at least one variable referenced by the corresponding shader. Otherwise, the value zero is written to *params*.

For the property `TOP_LEVEL_ARRAY_SIZE`, a single integer identifying the number of active array elements of the top-level shader storage block member containing the active variable is written to *params*. If the top-level block member is not declared as an array, the value 1 is written to *params*. If the top-level block member is an array with no declared size, the value zero is written to *params*.

For the property `TOP_LEVEL_ARRAY_STRIDE`, a single integer identifying the stride between array elements of the top-level shader storage block member containing the active variable is written to *params*. For top-level block members declared as arrays, the value written is the difference, in basic machine units, between the offsets of the active variable for consecutive elements in the top-level array. For top-level block members not declared as an array, zero is written to *params*.

For the property `LOCATION`, a single integer identifying the assigned location for an active uniform, input, output, or subroutine uniform variable is written to *params*. For input, output, or uniform variables with locations specified by a `layout` qualifier, the specified location is used. For vertex shader input, fragment shader output, or uniform variables without a `layout` qualifier, the location assigned when a program is linked is written to *params*. For all other input and output variables, the value -1 is written to *params*. For atomic counter uniforms and uniforms in uniform blocks, the value -1 is written to *params*.

For the property `LOCATION_INDEX`, a single integer identifying the fragment color index of an active fragment shader output variable is written to *params*. If the active variable is not an output for a fragment shader, the value -1 will be written to *params*.

For the property `IS_PER_PATCH`, a single integer identifying whether the input or output is a per-patch attribute is written to *params*. If the active variable is a per-patch attribute (declared with the `patch` qualifier), the value 1 is written to *params*; otherwise, the value zero is written to *params*.

### Errors

An `INVALID_VALUE` error is generated if *program* is not the name of either a program or shader object.

An `INVALID_OPERATION` error is generated if *program* is the name of a shader object.

An `INVALID_ENUM` error is generated if *programInterface* is not one of the interfaces described in the introduction to section 7.3.1.

An `INVALID_VALUE` error is generated if *propCount* is less than or equal to zero, or if *bufSize* is negative.

An `INVALID_ENUM` error is generated if any value in *props* is not one of the properties described above.

An `INVALID_OPERATION` error is generated if any value in *props* is not allowed for *programInterface*. The set of allowed *programInterface* values for each property can be found in table 7.2.

The commands

```
int GetProgramResourceLocation( uint program,
    enum programInterface, const char *name );
int GetProgramResourceLocationIndex( uint program,
    enum programInterface, const char *name );
```

returns the location or the fragment color index, respectively, assigned to the variable named *name* in interface *programInterface* of program object *program*. For **GetProgramResourceLocation**, *programInterface* must be one of `UNIFORM`, `PROGRAM_INPUT`, `PROGRAM_OUTPUT`, `VERTEX_SUBROUTINE_UNIFORM`, `TESS_CONTROL_SUBROUTINE_UNIFORM`, `TESS_EVALUATION_SUBROUTINE_UNIFORM`, `GEOMETRY_SUBROUTINE_UNIFORM`, `FRAGMENT_SUBROUTINE_UNIFORM`, or `COMPUTE_SUBROUTINE_UNIFORM`. For **GetProgramResourceLocationIndex**, *programInterface* must be `PROGRAM_OUTPUT`. The value -1 will be

returned by either command if an error occurs, if *name* does not identify an active variable on *programInterface*, or if *name* identifies an active variable that does not have a valid location assigned, as described above. The locations returned by these commands are the same locations returned when querying the `LOCATION` and `LOCATION_INDEX` resource properties.

A string provided to **GetProgramResourceLocation** or **GetProgramResourceLocationIndex** is considered to match an active variable if

- the string exactly matches the name of the active variable;
- if the string identifies the base name of an active array, where the string would exactly match the name of the variable if the suffix "[0]" were appended to the string; or
- if the string identifies an active element of the array, where the string ends with the concatenation of the "[" character, an integer (with no "+" sign, extra leading zeroes, or whitespace) identifying an array element, and the "]" character, the integer is less than the number of active elements of the array variable, and where the string would exactly match the enumerated name of the array if the decimal integer were replaced with zero.

Any other string is considered not to identify an active variable. If the string specifies an element of an array variable, **GetProgramResourceLocation** and **GetProgramResourceLocationIndex** return the location or fragment color index assigned to that element. If it specifies the base name of an array, it identifies the resources associated with the first element of the array.

### Errors

An `INVALID_VALUE` error is generated if *program* is not the name of either a program or shader object.

An `INVALID_OPERATION` error is generated if *program* is the name of a shader object.

An `INVALID_OPERATION` error is generated if *program* has not been linked or was last linked unsuccessfully.

An `INVALID_ENUM` error is generated if *programInterface* is not one of the interfaces named above.

## 7.4 Program Pipeline Objects

Instead of packaging all shader stages into a single program object, shader types might be contained in multiple program objects each consisting of part of the complete pipeline. A program object may even contain only a single shader stage. This facilitates greater flexibility when combining different shaders in various ways without requiring a program object for each combination.

A program pipeline object contains bindings for each shader type associating that shader type with a program object.

The command

```
void GenProgramPipelines( sizei n, uint *pipelines );
```

returns *n* previously unused program pipeline object names in *pipelines*. These names are marked as used, for the purposes of **GenProgramPipelines** only, but they acquire state only when they are first bound.

### Errors

An `INVALID_VALUE` error is generated if *n* is negative.

Program pipeline objects are deleted by calling

```
void DeleteProgramPipelines( sizei n, const  
    uint *pipelines );
```

*pipelines* contains *n* names of program pipeline objects to be deleted. Once a program pipeline object is deleted, it has no contents and its name becomes unused. If an object that is currently bound is deleted, the binding for that object reverts to zero and no program pipeline object becomes current. Unused names in *pipelines* that have been marked as used for the purposes of **GenProgramPipelines** are marked as unused again. Unused names in *pipelines* are silently ignored, as is the value zero.

### Errors

An `INVALID_VALUE` error is generated if *n* is negative.

The command

```
boolean IsProgramPipeline( uint pipeline );
```

returns `TRUE` if *pipeline* is the name of a program pipeline object. If *pipeline* is zero, or a non-zero value that is not the name of a program pipeline object, **IsProgramPipeline** returns `FALSE`. No error is generated if *pipeline* is not a valid program pipeline object name.

A program pipeline object is created by binding a name returned by **GenProgramPipelines** with the command

```
void BindProgramPipeline( uint pipeline );
```

*pipeline* is the program pipeline object name. The resulting program pipeline object is a new state vector, comprising all the state and with the same initial values listed in table 23.31.

**BindProgramPipeline** may also be used to bind an existing program pipeline object. If the bind is successful, no change is made to the state of the bound program pipeline object, and any previous binding is broken. If **BindProgramPipeline** is called with *pipeline* set to zero, then there is no current program pipeline object.

If no current program object has been established by **UseProgram**, the program objects used for each shader stage and for uniform updates are taken from the bound program pipeline object, if any. If there is a current program object established by **UseProgram**, the bound program pipeline object has no effect on rendering or uniform updates. When a bound program pipeline object is used for rendering, individual shader executables are taken from its program objects as described in the discussion of **UseProgram** in section 7.3).

#### Errors

An `INVALID_OPERATION` error is generated if *pipeline* is not zero or a name returned from a previous call to **GenProgramPipelines**, or if such a name has since been deleted with **DeleteProgramPipelines**.

The executables in a program object associated with one or more shader stages can be made part of the program pipeline state for those shader stages with the command:

```
void UseProgramStages( uint pipeline, bitfield stages,
                        uint program );
```

where *pipeline* is the program pipeline object to be updated, *stages* is the bitwise OR of accepted constants representing shader stages, and *program* is the program object from which the executables are taken. The bits set in *stages* indicate the

program stages for which the program object named by *program* becomes current. These stages may include compute, vertex, tessellation control, tessellation evaluation, geometry, or fragment, indicated respectively by `COMPUTE_SHADER_BIT`, `VERTEX_SHADER_BIT`, `TESS_CONTROL_SHADER_BIT`, `TESS_EVALUATION_SHADER_BIT`, `GEOMETRY_SHADER_BIT`, or `FRAGMENT_SHADER_BIT`. The constant `ALL_SHADER_BITS` indicates *program* is to be made current for all shader stages.

If *program* refers to a program object with a valid shader attached for an indicated shader stage, this call installs the executable code for that stage in the indicated program pipeline object state. If **UseProgramStages** is called with *program* set to zero or with a program object that contains no executable code for any stage in *stages*, it is as if the pipeline object has no programmable stage configured for that stage.

If *pipeline* is a name that has been generated (without subsequent deletion) by **GenProgramPipelines**, but refers to a program pipeline object that has not been previously bound, the GL first creates a new state vector in the same manner as when **BindProgramPipeline** creates a new program pipeline object.

#### Errors

An `INVALID_VALUE` error is generated if *stages* is not the special value `ALL_SHADER_BITS`, and has any bits set other than `TESS_CONTROL_SHADER_BIT`, `TESS_EVALUATION_SHADER_BIT`, `VERTEX_SHADER_BIT`, `GEOMETRY_SHADER_BIT`, and `FRAGMENT_SHADER_BIT`.

An `INVALID_VALUE` error is generated if *program* is not the name of either a program or shader object.

An `INVALID_OPERATION` error is generated if *program* is the name of a shader object.

An `INVALID_OPERATION` error is generated if the program object named by *program* was linked without the `PROGRAM_SEPARABLE` parameter set, has not been linked, or was last linked unsuccessfully. The corresponding shader stages in *pipeline* are not modified.

An `INVALID_OPERATION` error is generated if *pipeline* is not a name returned from a previous call to **GenProgramPipelines** or if such a name has since been deleted by **DeleteProgramPipelines**.

The command

```
void ActiveShaderProgram(uint pipeline, uint program);
```

sets the linked program named by *program* to be the active program (see sec-

tion 7.6.1) used for uniform updates for the program pipeline object *pipeline*.

If *pipeline* is a name that has been generated (without subsequent deletion) by **GenProgramPipelines**, but refers to a program pipeline object that has not been previously bound, the GL first creates a new state vector in the same manner as when **BindProgramPipeline** creates a new program pipeline object.

### Errors

An `INVALID_OPERATION` error is generated if *pipeline* is not a name returned from a previous call to **GenProgramPipelines** or if such a name has since been deleted by **DeleteProgramPipelines**.

An `INVALID_VALUE` error is generated if *program* is not the name of either a program or shader object.

An `INVALID_OPERATION` error is generated if *program* is the name of a shader object.

An `INVALID_OPERATION` error is generated if *program* has not been linked, or was last linked unsuccessfully. The active program is not modified.

### 7.4.1 Shader Interface Matching

When multiple shader stages are active, the outputs of one stage form an interface with the inputs of the next stage. At each such interface, shader inputs are matched up against outputs from the previous stage:

- An output block is considered to match an input block in the subsequent shader if the two blocks have the same block name, and the members of the block match exactly in name, type, qualification, and declaration order.
- An output variable is considered to match an input variable in the subsequent shader if:
  - the two variables match in name, type, and qualification; or
  - the two variables are declared with the same location `layout` qualifier and match in type and qualification.

Variables or block members declared as structures are considered to match in type if and only if structure members match in name, type, qualification, and declaration order. Variables or block members declared as arrays are considered to match in type only if both declarations specify the same element type and array size. The rules for determining if variables or block members match in qualification are found in the OpenGL Shading Language Specification .

Tessellation control shader per-vertex output variables and blocks and tessellation control, tessellation evaluation, and geometry shader per-vertex input variables and blocks are required to be declared as arrays, with each element representing input or output values for a single vertex of a multi-vertex primitive. For the purposes of interface matching, such variables and blocks are treated as though they were not declared as arrays.

For program objects containing multiple shaders, **LinkProgram** will check for mismatches on interfaces between shader stages in the program being linked and generate a link error if a mismatch is detected. A link error is generated if any statically referenced input variable or block does not have a matching output. If either shader redeclares the built-in array `gl_ClipDistance[]`, the array must have the same size in both shaders.

With separable program objects, interfaces between shader stages may involve the outputs from one program object and the inputs from a second program object. For such interfaces, it is not possible to detect mismatches at link time, because the programs are linked separately. When each such program is linked, all inputs or outputs interfacing with another program stage are treated as active. The linker will generate an executable that assumes the presence of a compatible program on the other side of the interface. If a mismatch between programs occurs, no GL error is generated, but some or all of the inputs on the interface will be undefined.

At an interface between program objects, the set of inputs and outputs are considered to match exactly if and only if:

- Every declared input block or variable must have a matching output, as described above.
- There are no output blocks or user-defined output variables declared without a matching input block or variable declaration.

When the set of inputs and outputs on an interface between programs matches exactly, all inputs are well-defined except when the corresponding outputs were not written in the previous shader. However, any mismatch between inputs and outputs results in all inputs being undefined except for cases noted below. Even if an input has a corresponding output that matches exactly, mismatches on other inputs or outputs may adversely affect the executable code generated to read or write the matching variable.

The inputs and outputs on an interface between programs need not match exactly when input and output location qualifiers (sections 4.4.1 (“Input Layout Qualifiers”) and 4.4.2 (“Output Layout Qualifiers”) of the OpenGL Shading Language Specification ) are used. When using location qualifiers, any input with an input location qualifier will be well-defined as long as the other program writes to a



matching output, as described above. The names of variables need not match when matching by location.

Additionally, scalar and vector inputs with location `layout` qualifiers will be well-defined if there is a corresponding output satisfying all of the following conditions:

- the input and output match exactly in qualification, including in the location `layout` qualifier;
- the output is a vector with the same basic component type and has more components than the input; and
- the common component type of the input and output is `int`, `uint`, or `float` (scalars, vectors, and matrices with `double` component type are excluded).

In this case, the components of the input will be taken from the first components of the matching output, and the extra components of the output will be ignored.

To use any built-in input or output in the `gl_PerVertex` block in separable program objects, shader code must redeclare that block prior to use. A separable program will fail to link if:

- it contains multiple shaders of a single type with different redeclarations of this built-in block; or
- any shader uses a built-in block member not found in the redeclaration of that block.

There is one exception to this rule described below.

As described above, an exact interface match requires matching built-in input and output blocks. At an interface between two non-fragment shader stages, the `gl_PerVertex` input and output blocks are considered to match if and only if the block members match exactly in name, type, qualification, and declaration order. At an interface involving the fragment shader stage, the presence or absence of any built-in output does not affect interface matching.

Built-in inputs or outputs not found in blocks do not affect interface matching. Any such built-in inputs are well-defined unless they are derived from built-in outputs not written by the previous shader stage.

### 7.4.2 Program Pipeline Object State

The state required to support program pipeline objects consists of a single binding name of the current program pipeline object. This binding is initially zero indicating no program pipeline object is bound.

The state of each program pipeline object consists of:

- Unsigned integers are required to hold the names of the active program and each of the current vertex, tessellation control, tessellation evaluation, geometry, fragment, and compute stage programs. Each integer is initially zero.
- A boolean holding the status of the last validation attempt, initially false.
- An array of type `char` containing the information log (see section 7.13), initially empty.
- An integer holding the length of the information log.

## 7.5 Program Binaries

The command

```
void GetProgramBinary( uint program, sizei bufSize,
                      sizei *length, enum *binaryFormat, void *binary );
```

returns a binary representation of the program object's compiled and linked executable source, henceforth referred to as its program binary. The maximum number of bytes that may be written into *binary* is specified by *bufSize*. The actual number of bytes written into *binary* is returned in *length* and its format is returned in *binaryFormat*. If *length* is `NULL`, then no length is returned.

The number of bytes in the program binary can be queried by calling **GetProgramiv** with *pname* `PROGRAM_BINARY_LENGTH`.

### Errors

An `INVALID_VALUE` error is generated if *program* is not the name of either a program or shader object.

An `INVALID_OPERATION` error is generated if *program* is the name of a shader object.

An `INVALID_OPERATION` error is generated if *program* has not been linked, or was last linked unsuccessfully. In this case its program binary length is zero.

An `INVALID_VALUE` error is generated if *bufSize* is negative.

An `INVALID_OPERATION` error is generated if *bufSize* is less than the number of bytes in the program binary.

The command

```
void ProgramBinary(uint program, enum binaryFormat,  
    const void *binary, size_t length);
```

loads a program object with a program binary previously returned from **GetProgramBinary**. This is useful to avoid online compilation, while still using OpenGL Shading Language source shaders as a portable initial format. *binaryFormat* and *binary* must be those returned by a previous call to **GetProgramBinary**, and *length* must be the length of the program binary as returned by **GetProgramBinary** or **GetProgramiv** with *pname* `PROGRAM_BINARY_LENGTH`. Loading the program binary will fail, setting the `LINK_STATUS` of *program* to `FALSE`, if these conditions are not met.

Loading a program binary may also fail if the implementation determines that there has been a change in hardware or software configuration from when the program binary was produced such as having been compiled with an incompatible or outdated version of the compiler. In this case the application should fall back to providing the original OpenGL Shading Language source shaders, and perhaps again retrieve the program binary for future use.

A program object's program binary is replaced by calls to **LinkProgram** or **ProgramBinary**. Where linking success or failure is concerned, **ProgramBinary** can be considered to perform an implicit linking operation. **LinkProgram** and **ProgramBinary** both set the program object's `LINK_STATUS` to `TRUE` or `FALSE`, as queried with **GetProgramiv**, to reflect success or failure and update the information log, queried with **GetProgramInfoLog**, to provide details about warnings or errors.

A successful call to **ProgramBinary** will reset all uniform variables in the default uniform block, all uniform block buffer bindings, and all shader storage block buffer bindings to their initial values. The initial value is either the value of the variable's initializer as specified in the original shader source, or zero if no initializer was present.

Additionally, all vertex shader input and fragment shader output assignments that were in effect when the program was linked before saving are restored when **ProgramBinary** is called successfully.

If **ProgramBinary** fails to load a binary, no error is generated, but any information about a previous link or load of that program object is lost. Thus, a failed load does not restore the old state of *program*. The failure does not alter other program state not affected by linking such as the attached shaders, and the vertex attribute and fragment data location bindings as set by **BindAttribLocation** and **BindFragDataLocation**.

OpenGL defines no specific binary formats, but does provide a mechanism to obtain token values for such formats provided by extensions. The number of program binary formats supported can be obtained by querying the value of `NUM_PROGRAM_BINARY_FORMATS`. The list of specific binary formats supported can be obtained by querying the value of `PROGRAM_BINARY_FORMATS`. The *binaryFormat* returned by **GetProgramBinary** must be present in this list.

Any program binary retrieved using **GetProgramBinary** and submitted using **ProgramBinary** under the same configuration must be successful. Any programs loaded successfully by **ProgramBinary** must be run properly with any legal GL state vector.

If an implementation needs to recompile or otherwise modify program executables based on GL state outside the program, **GetProgramBinary** is required to save enough information to allow such recompilation.

To indicate that a program binary is likely to be retrieved, **ProgramParameteri** should be called with *pname* `PROGRAM_BINARY_RETRIEVABLE_HINT` and *value* `TRUE`. This setting will not be in effect until the next time **LinkProgram** or **ProgramBinary** has been called successfully. Additionally, the application may defer **GetProgramBinary** calls until after using the program with all non-program state vectors that it is likely to encounter. Such deferral may allow implementations to save additional information in the program binary that would minimize recompilation in future uses of the program binary.

### Errors

An `INVALID_VALUE` error is generated if *program* is not the name of either a program or shader object.

An `INVALID_OPERATION` error is generated if *program* is the name of a shader object.

An `INVALID_ENUM` error is generated if *binaryFormat* is not a binary format present in the list of specific binary formats supported.

An `INVALID_VALUE` error is generated if *length* is negative.

## 7.6 Uniform Variables

Shaders can declare named *uniform variables*, as described in the OpenGL Shading Language Specification . A uniform is considered an *active uniform* if the compiler and linker determine that the uniform will actually be accessed when the executable code is executed. In cases where the compiler and linker cannot make a conclusive determination, the uniform will be considered active.

Shader Stage	<i>pname</i> for querying default uniform block storage, in components
Vertex (see section 11.1.2)	MAX_VERTEX_UNIFORM_COMPONENTS
Tessellation control (see section 11.2.1.1)	MAX_TESS_CONTROL_UNIFORM_COMPONENTS
Tessellation evaluation (see section 11.2.3.1)	MAX_TESS_EVALUATION_UNIFORM_COMPONENTS
Geometry (see section 11.3.3)	MAX_GEOMETRY_UNIFORM_COMPONENTS
Fragment (see section 15.1)	MAX_FRAGMENT_UNIFORM_COMPONENTS
Compute (see section 19.1)	MAX_COMPUTE_UNIFORM_COMPONENTS

Table 7.4: Query targets for default uniform block storage, in components.

Sets of uniforms, except for atomic counters, images, samplers, and subroutine uniforms, can be grouped into *uniform blocks*.

*Named uniform blocks*, as described in the OpenGL Shading Language Specification, store uniform values in the data store of a buffer object corresponding to the uniform block. Such blocks are assigned a *uniform block index*.

Uniforms that are declared outside of a named uniform block are part of the *default uniform block*. The default uniform block has no name or uniform block index. Uniforms in the default uniform block, except for subroutine uniforms, are program object-specific state. They retain their values once loaded, and their values are restored whenever a program object is used, as long as the program object has not been re-linked.

Like uniforms, uniform blocks can be active or inactive. Active uniform blocks are those that contain active uniforms after a program has been compiled and linked.

The implementation-dependent amount of storage available for uniform variables, except for subroutine uniforms and atomic counters, in the default uniform block accessed by a shader for a particular shader stage can be queried by calling **GetIntegerv** with *pname* as specified in table 7.4 for that stage.

The implementation-dependent constants `MAX_VERTEX_UNIFORM_VECTORS` and `MAX_FRAGMENT_UNIFORM_VECTORS` have values respectively equal to the values of `MAX_VERTEX_UNIFORM_COMPONENTS` and `MAX_FRAGMENT_UNIFORM_COMPONENTS` divided by four.

The total amount of combined storage available for uniform variables in all uniform blocks accessed by a shader for a particular shader stage can be queried by calling **GetIntegerv** with *pname* as specified in table 7.5 for that stage.

These values represent the numbers of individual floating-point, integer, or boolean values that can be held in uniform variable storage for a shader. For uni-

Shader Stage	<i>pname</i> for querying combined uniform block storage, in components
Vertex	MAX_COMBINED_VERTEX_UNIFORM_COMPONENTS
Tessellation control	MAX_COMBINED_TESS_CONTROL_UNIFORM_COMPONENTS
Tessellation evaluation	MAX_COMBINED_TESS_EVALUATION_UNIFORM_COMPONENTS
Geometry	MAX_COMBINED_GEOMETRY_UNIFORM_COMPONENTS
Fragment	MAX_COMBINED_FRAGMENT_UNIFORM_COMPONENTS
Compute	MAX_COMBINED_COMPUTE_UNIFORM_COMPONENTS

Table 7.5: Query targets for combined uniform block storage, in components.

forms with boolean, integer, or floating-point components,

- A scalar uniform will consume no more than 1 component
- A vector uniform will consume no more than  $n$  components, where  $n$  is the vector component count
- A matrix uniform will consume no more than  $4 \times \min(r, c)$  components, where  $r$  and  $c$  are the number of rows and columns in the matrix.

Scalar, vector, and matrix uniforms with double-precision components will consume no more than twice the number of components of equivalent uniforms with floating-point components.

A link error is generated if an attempt is made to utilize more than the space available for uniform variables in a shader stage.

When a program is successfully linked, all active uniforms, except for atomic counters, belonging to the program object's default uniform block are initialized as defined by the version of the OpenGL Shading Language used to compile the program. A successful link will also generate a location for each active uniform in the default uniform block which doesn't already have an explicit location defined in the shader. The generated locations will never take the location of a uniform with an explicit location defined in the shader, even if that uniform is determined to be inactive. The values of active uniforms in the default uniform block can be changed using this location and the appropriate **Uniform\*** or **ProgramUniform\*** command (see section 7.6.1). These generated locations are invalidated and new ones assigned after each successful re-link. The explicitly defined locations and the generated locations must be in the range of zero to the value of `MAX_UNIFORM_`  
`LOCATIONS` minus one.

Similarly, when a program is successfully linked, all active atomic counters are assigned bindings, offsets (and strides for arrays of atomic counters) according to layout rules described in section 7.6.2.2. Atomic counter uniform buffer objects provide the storage for atomic counters, so the values of atomic counters may be changed by modifying the contents of the buffer object using the commands in sections 6.2, 6.2.1, 6.3, 6.5, and 6.6. Atomic counters are not assigned a location and may not be modified using the **Uniform\*** commands. The bindings, offsets, and strides belonging to atomic counters of a program object are invalidated and new ones assigned after each successful re-link.

Similarly, when a program is successfully linked, all active uniforms belonging to the program's named uniform blocks are assigned offsets (and strides for array and matrix type uniforms) within the uniform block according to layout rules described below. Uniform buffer objects provide the storage for named uniform blocks, so the values of active uniforms in named uniform blocks may be changed by modifying the contents of the buffer object. Uniforms in a named uniform block are not assigned a location and may not be modified using the **Uniform\*** commands. The offsets and strides of all active uniforms belonging to named uniform blocks of a program object are invalidated and new ones assigned after each successful re-link.

To determine the set of active uniform variables used by a program, applications can query the properties and active resources of the UNIFORM interface of a program.

Additionally, several dedicated commands are provided to query properties of active uniforms. The command

```
int GetUniformLocation( uint program, const
    char *name );
```

is equivalent to

```
GetProgramResourceLocation (program, UNIFORM, name);
```

The command

```
void GetActiveUniformName( uint program,
    uint uniformIndex, sizei bufSize, sizei *length,
    char *uniformName );
```

is equivalent to

```
GetProgramResourceName (program, UNIFORM, uniformIndex,
    bufSize, length, uniformName);
```

The command

```
void GetUniformIndices(uint program,
    sizei uniformCount, const char **uniformNames,
    uint *uniformIndices );
```

is equivalent to

```
for (int i = 0; i < uniformCount; i++) {
    uniformIndices[i] = GetProgramResourceIndex (program,
        UNIFORM, uniformNames[i]);
}
```

The command

```
void GetActiveUniform(uint program, uint index,
    sizei bufSize, sizei *length, int *size, enum *type,
    char *name );
```

is equivalent to

```
const enum props[] = { ARRAY_SIZE, TYPE };
GetProgramResourceName (program, UNIFORM, index,
    bufSize, length, name);
GetProgramResourceiv (program, UNIFORM, index,
    1, &props[0], 1, NULL, size);
GetProgramResourceiv (program, UNIFORM, index,
    1, &props[1], 1, NULL, (int *)type);
```

The command

```
void GetActiveUniformsiv(uint program,
    sizei uniformCount, const uint *uniformIndices,
    enum pname, int *params );
```

is equivalent to

```
GLenum prop;
for (int i = 0; i < uniformCount; i++) {
    GetProgramResourceiv (program, UNIFORM, uniformIndices[i],
        1, &prop, 1, NULL, &params[i]);
}
```



<i>pname</i>	<i>prop</i>
UNIFORM_TYPE	TYPE
UNIFORM_SIZE	ARRAY_SIZE
UNIFORM_NAME_LENGTH	NAME_LENGTH
UNIFORM_BLOCK_INDEX	BLOCK_INDEX
UNIFORM_OFFSET	OFFSET
UNIFORM_ARRAY_STRIDE	ARRAY_STRIDE
UNIFORM_MATRIX_STRIDE	MATRIX_STRIDE
UNIFORM_IS_ROW_MAJOR	IS_ROW_MAJOR
UNIFORM_ATOMIC_COUNTER_BUFFER_INDEX	ATOMIC_COUNTER_BUFFER_INDEX

Table 7.6: **GetProgramResourceiv** properties used by **GetActiveUniformsiv**.

where the value of *prop* is taken from table 7.6, based on the value of *pname*.

To determine the set of active uniform blocks used by a program, applications can query the properties and active resources of the `UNIFORM_BLOCK` interface.

Additionally, several commands are provided to query properties of active uniform blocks. The command

```
uint GetUniformBlockIndex(uint program, const
    char *uniformBlockName );
```

is equivalent to

```
GetProgramResourceIndex (program, UNIFORM_BLOCK, uniformBlockName );
```

The command

```
void GetActiveUniformBlockName(uint program,
    uint uniformBlockIndex, sizei bufSize, sizei length,
    char *uniformBlockName );
```

is equivalent to

```
GetProgramResourceName (program, UNIFORM_BLOCK,
    uniformBlockIndex, bufSize, length, uniformBlockName );
```

The command

```
void GetActiveUniformBlockiv(uint program,
    uint uniformBlockIndex, enum pname, int *params );
```

<i>pname</i>	<i>prop</i>
UNIFORM_BLOCK_BINDING	BUFFER_BINDING
UNIFORM_BLOCK_DATA_SIZE	BUFFER_DATA_SIZE
UNIFORM_BLOCK_NAME_LENGTH	NAME_LENGTH
UNIFORM_BLOCK_ACTIVE_UNIFORMS	NUM_ACTIVE_VARIABLES
UNIFORM_BLOCK_ACTIVE_UNIFORM_INDICES	ACTIVE_VARIABLES
UNIFORM_BLOCK_REFERENCED_BY_VERTEX_SHADER	REFERENCED_BY_VERTEX_SHADER
UNIFORM_BLOCK_REFERENCED_BY_TESS_CONTROL_SHADER	REFERENCED_BY_TESS_CONTROL_SHADER
UNIFORM_BLOCK_REFERENCED_BY_TESS_EVALUATION_SHADER	REFERENCED_BY_TESS_EVALUATION_SHADER
UNIFORM_BLOCK_REFERENCED_BY_GEOMETRY_SHADER	REFERENCED_BY_GEOMETRY_SHADER
UNIFORM_BLOCK_REFERENCED_BY_FRAGMENT_SHADER	REFERENCED_BY_FRAGMENT_SHADER
UNIFORM_BLOCK_REFERENCED_BY_COMPUTE_SHADER	REFERENCED_BY_COMPUTE_SHADER

Table 7.7: **GetProgramResourceiv** properties used by **GetActiveUniformBlockiv**.

is equivalent to

```
GLenum prop;
GetProgramResourceiv(program, UNIFORM_BLOCK,
    uniformBlockIndex, 1, &prop, maxSize, NULL, params);
```

where the value of *prop* is taken from table 7.7, based on the value of *pname*, and *maxSize* is taken to specify a sufficiently large buffer to receive all values that would be written to *params*.

To determine the set of active atomic counter buffer binding points used by a program, applications can query the properties and active resources of the `ATOMIC_COUNTER_BUFFER` interface of a program.

Additionally, the command

```
void GetActiveAtomicCounterBufferiv(uint program,
    uint bufferIndex, enum pname, int *params);
```

<i>pname</i>	<i>prop</i>
ATOMIC_COUNTER_BUFFER_BINDING	BUFFER_BINDING
ATOMIC_COUNTER_BUFFER_DATA_SIZE	BUFFER_DATA_SIZE
ATOMIC_COUNTER_BUFFER_ACTIVE_ATOMIC_COUNTERS	NUM_ACTIVE_VARIABLES
ATOMIC_COUNTER_BUFFER_ACTIVE_ATOMIC_COUNTER_INDICES	ACTIVE_VARIABLES
ATOMIC_COUNTER_BUFFER_REFERENCED_BY_VERTEX_SHADER	REFERENCED_BY_VERTEX_SHADER
ATOMIC_COUNTER_BUFFER_REFERENCED_BY_TESS_CONTROL_SHADER	REFERENCED_BY_TESS_CONTROL_SHADER
ATOMIC_COUNTER_BUFFER_REFERENCED_BY_TESS_EVALUATION_SHADER	REFERENCED_BY_TESS_EVALUATION_SHADER
ATOMIC_COUNTER_BUFFER_REFERENCED_BY_GEOMETRY_SHADER	REFERENCED_BY_GEOMETRY_SHADER
ATOMIC_COUNTER_BUFFER_REFERENCED_BY_FRAGMENT_SHADER	REFERENCED_BY_FRAGMENT_SHADER
ATOMIC_COUNTER_BUFFER_REFERENCED_BY_COMPUTE_SHADER	REFERENCED_BY_COMPUTE_SHADER

Table 7.8: **GetProgramResourceiv** properties used by **GetActiveAtomicCounterBufferiv**.

can be used to determine properties of active atomic counter buffer bindings used by *program* and is equivalent to

```
GLenum prop;
GetProgramResourceiv (program, ATOMIC_COUNTER_BUFFER,
    bufferIndex, 1, &prop, maxSize, NULL, params);
```

where the value of *prop* is taken from table 7.8, based on the value of *pname*, and *maxSize* is taken to specify a sufficiently large buffer to receive all values that would be written to *params*.

### 7.6.1 Loading Uniform Variables In The Default Uniform Block

To load values into the uniform variables except for subroutine uniforms and atomic counters, of the default uniform block of the active program object, use the commands

```
void Uniform{1234}{ifd ui}( int location, T value );
void Uniform{1234}{ifd ui}v( int location, sizei count,
    const T *value );
void UniformMatrix{234}{fd}v( int location, sizei count,
    boolean transpose, const float *value );
void UniformMatrix{2x3,3x2,2x4,4x2,3x4,4x3}{fd}v(
    int location, sizei count, boolean transpose, const
    float *value );
```

If a non-zero program object is bound by **UseProgram**, it is the active program object whose uniforms are updated by these commands. If no program object is bound using **UseProgram**, the active program object of the current program pipeline object set by **ActiveShaderProgram** is the active program object. If the current program pipeline object has no active program or there is no current program pipeline object, then there is no active program.

The given values are loaded into the default uniform block uniform variable location identified by *location* and associated with a uniform variable.

The **Uniform\*f{v}** commands will load *count* sets of one to four floating-point values into a uniform defined as a float, a floating-point vector, or an array of either of these types.

The **Uniform\*d{v}** commands will load *count* sets of one to four double-precision floating-point values into a uniform defined as a double, a double vector, or an array of either of these types.

The **Uniform\*i{v}** commands will load *count* sets of one to four integer values into a uniform defined as a sampler, an image, an integer, an integer vector, or an array of any of these types. Only the **Uniform1i{v}** commands can be used to load sampler and image values (see below).

The **Uniform\*ui{v}** commands will load *count* sets of one to four unsigned integer values into a uniform defined as a unsigned integer, an unsigned integer vector, or an array of either of these types.

The **UniformMatrix{234}fv** and **UniformMatrix{234}dv** commands will load *count*  $2 \times 2$ ,  $3 \times 3$ , or  $4 \times 4$  matrices (corresponding to **2**, **3**, or **4** in the command name) of single- or double-precision floating-point values, respectively, into a uniform defined as a matrix or an array of matrices. If *transpose* is **FALSE**, the matrix is specified in column major order, otherwise in row major order.

The **UniformMatrix**{*2x3,3x2,2x4,4x2,3x4,4x3*}**fv** and **UniformMatrix**{*2x3,3x2,2x4,4x2,3x4,4x3*}**dv** commands will load *count*  $2 \times 3$ ,  $3 \times 2$ ,  $2 \times 4$ ,  $4 \times 2$ ,  $3 \times 4$ , or  $4 \times 3$  matrices (corresponding to the numbers in the command name) of single- or double-precision floating-point values, respectively, into a uniform defined as a matrix or an array of matrices. The first number in the command name is the number of columns; the second is the number of rows. For example, **UniformMatrix2x4fv** is used to load a single-precision matrix consisting of two columns and four rows. If *transpose* is **FALSE**, the matrix is specified in column major order, otherwise in row major order.

When loading values for a uniform declared as a boolean, a boolean vector, or an array of either of these types, any of the **Uniform\*i{v}**, **Uniform\*ui{v}**, and **Uniform\*f{v}** commands can be used. Type conversion is done by the GL. Boolean values are set to **FALSE** if the corresponding input value is 0 or 0.0f, and set to **TRUE** otherwise. The **Uniform\*** command used must match the size of the uniform, as declared in the shader. For example, to load a uniform declared as a **bvec2**, any of the **Uniform2{if ui}\*** commands may be used.

For all other uniform types loadable with **Uniform\*** commands, the command used must match the size and type of the uniform, as declared in the shader, and no type conversions are done. For example, to load a uniform declared as a **vec4**, **Uniform4f{v}** must be used, and to load a uniform declared as a **dmat3**, **UniformMatrix3dv** must be used.

When loading *N* elements starting at an arbitrary position *k* in a uniform declared as an array, elements *k* through *k* + *N* - 1 in the array will be replaced with the new values. Values for any array element that exceeds the highest array element index used, as reported by **GetActiveUniform**, will be ignored by the GL.

If the value of *location* is -1, the **Uniform\*** commands will silently ignore the data passed in, and the current uniform values will not be changed.

### Errors

An **INVALID\_VALUE** error is generated if *count* is negative.

An **INVALID\_OPERATION** error is generated if any of the following conditions occur:

- the size indicated in the name of the **Uniform\*** command used does not match the size of the uniform declared in the shader,
- the component type and count indicated in the name of the **Uniform\*** command used does not match the type of the uniform declared in the shader, where a **boolean** uniform component type is considered to match any of the **Uniform\*i{v}**, **Uniform\*ui{v}**, or **Uniform\*f{v}**

**commands.**

- *count* is greater than one, and the uniform declared in the shader is not an array variable,
- no variable with a location of *location* exists in the program object currently in use and *location* is not -1, or
- there is no active program object in use.

To load values into the uniform variables of the default uniform block of a program which may not necessarily be bound, use the commands

```
void ProgramUniform{1234}{ifd}( uint program,
    int location, T value );
void ProgramUniform{1234}{ifd}v( uint program,
    int location, size_t count, const T *value );
void ProgramUniform{1234}ui( uint program, int location,
    T value );
void ProgramUniform{1234}uiv( uint program,
    int location, size_t count, const T *value );
void ProgramUniformMatrix{234}{fd}v( uint program,
    int location, size_t count, boolean transpose, const
    T *value );
void ProgramUniformMatrix{2x3,3x2,2x4,4x2,3x4,4x3}{fd}v(
    uint program, int location, size_t count,
    boolean transpose, const T *value );
```

These commands operate identically to the corresponding commands above without **Program** in the command name except, rather than updating the currently active program object, these **Program** commands update the program object named by the initial *program* parameter. The remaining parameters following the initial *program* parameter match the parameters for the corresponding non-**Program** uniform command.

**Errors**

An `INVALID_VALUE` error is generated if *program* is not the name of either a program or shader object.

An `INVALID_OPERATION` error is generated if *program* is the name of a shader object.

An `INVALID_OPERATION` error is generated if *program* has not been

linked, or was last linked unsuccessfully.

In addition, all errors described for the corresponding **Uniform\*** commands apply.

## 7.6.2 Uniform Blocks

The values of uniforms arranged in named uniform blocks are extracted from buffer object storage. The mechanisms for placing individual uniforms in a buffer object and connecting a uniform block to an individual buffer object are described below.

There is a set of implementation-dependent maximums for the number of active uniform blocks used by each shader stage. If the number of uniform blocks used by any shader stage in the program exceeds its corresponding limit, the program will fail to link. The limits for vertex, tessellation control, tessellation evaluation, geometry, fragment, and compute shaders can be obtained by calling **GetIntegerv** with *pname* values of `MAX_VERTEX_UNIFORM_BLOCKS`, `MAX_TESS_CONTROL_UNIFORM_BLOCKS`, `MAX_TESS_EVALUATION_UNIFORM_BLOCKS`, `MAX_GEOMETRY_UNIFORM_BLOCKS`, `MAX_FRAGMENT_UNIFORM_BLOCKS`, and `MAX_COMPUTE_UNIFORM_BLOCKS`, respectively.

Additionally, there is an implementation-dependent limit on the sum of the number of active uniform blocks used by each shader stage of a program. If a uniform block is used by multiple shader stages, each such use counts separately against this combined limit. The combined uniform block use limit can be obtained by calling **GetIntegerv** with a *pname* of `MAX_COMBINED_UNIFORM_BLOCKS`.

When a named uniform block is declared by multiple shaders in a program, it must be declared identically in each shader. The uniforms within the block must be declared with the same names, types and `layout` qualifiers, and in the same order. If a program contains multiple shaders with different declarations for the same named uniform block, the program will fail to link.

### 7.6.2.1 Uniform Buffer Object Storage

When stored in buffer objects associated with uniform blocks, uniforms are represented in memory as follows:

- Members of type `bool`, `int`, `uint`, `float`, and `double` are respectively extracted from a buffer object by reading a single `uint`, `int`, `uint`, `float`, or `double` value at the specified offset.
- Vectors with  $N$  elements with basic data types of `bool`, `int`, `uint`, `float`, or `double` are extracted as  $N$  values in consecutive memory locations beginning at the specified offset, with components stored in order with the first

(X) component at the lowest offset. The GL data type used for component extraction is derived according to the rules for scalar members above.

- Column-major matrices with  $C$  columns and  $R$  rows (using the types `dmatC×R` and `matC×R` for double-precision and floating-point components respectively, or simply `dmatC` and `matC` respectively if  $C = R$ ) are treated as an array of  $C$  floating-point column vectors, each consisting of  $R$  double-precision or floating-point components. The column vectors will be stored in order, with column zero at the lowest offset. The difference in offsets between consecutive columns of the matrix will be referred to as the column stride, and is constant across the matrix. The column stride is an implementation-dependent function of the matrix type, and may be determined after a program is linked by querying the `MATRIX_STRIDE` interface using `GetProgramResourceiv` (see section 7.3.1).
- Row-major matrices with  $C$  columns and  $R$  rows (using the types `dmatC×R` and `matC×R` for double-precision and floating-point components respectively, or simply `dmatC` and `matC` respectively if  $C = R$ ) are treated as an array of  $R$  floating-point row vectors, each consisting of  $C$  double-precision or floating-point components. The row vectors will be stored in order, with row zero at the lowest offset. The difference in offsets between consecutive rows of the matrix will be referred to as the row stride, and is constant across the matrix. The row stride is an implementation-dependent function of the matrix type, and may be determined after a program is linked by querying the `MATRIX_STRIDE` interface using `GetProgramResourceiv` (see section 7.3.1).
- Arrays of scalars, vectors, and matrices are stored in memory by element order, with array member zero at the lowest offset. The difference in offsets between each pair of elements in the array in basic machine units is referred to as the array stride, and is constant across the entire array. The array stride, `UNIFORM_ARRAY_STRIDE`, is an implementation-dependent value and may be queried after a program is linked.

### 7.6.2.2 Standard Uniform Block Layout

By default, uniforms contained within a uniform block are extracted from buffer storage in an implementation-dependent manner. Applications may query the offsets assigned to uniforms inside uniform blocks with query functions provided by the GL.



The `layout` qualifier provides shaders with control of the layout of uniforms within a uniform block. When the `std140` layout is specified, the offset of each uniform in a uniform block can be derived from the definition of the uniform block by applying the set of rules described below.

When using the `std140` storage layout, structures will be laid out in buffer storage with its members stored in monotonically increasing order based on their location in the declaration. A structure and each structure member have a base offset and a base alignment, from which an aligned offset is computed by rounding the base offset up to a multiple of the base alignment. The base offset of the first member of a structure is taken from the aligned offset of the structure itself. The base offset of all other structure members is derived by taking the offset of the last basic machine unit consumed by the previous member and adding one. Each structure member is stored in memory at its aligned offset. The members of a top-level uniform block are laid out in buffer storage by treating the uniform block as a structure with a base offset of zero.

1. If the member is a scalar consuming  $N$  basic machine units, the base alignment is  $N$ .
2. If the member is a two- or four-component vector with components consuming  $N$  basic machine units, the base alignment is  $2N$  or  $4N$ , respectively.
3. If the member is a three-component vector with components consuming  $N$  basic machine units, the base alignment is  $4N$ .
4. If the member is an array of scalars or vectors, the base alignment and array stride are set to match the base alignment of a single array element, according to rules (1), (2), and (3), and rounded up to the base alignment of a `vec4`. The array may have padding at the end; the base offset of the member following the array is rounded up to the next multiple of the base alignment.
5. If the member is a column-major matrix with  $C$  columns and  $R$  rows, the matrix is stored identically to an array of  $C$  column vectors with  $R$  components each, according to rule (4).
6. If the member is an array of  $S$  column-major matrices with  $C$  columns and  $R$  rows, the matrix is stored identically to a row of  $S \times C$  column vectors with  $R$  components each, according to rule (4).
7. If the member is a row-major matrix with  $C$  columns and  $R$  rows, the matrix is stored identically to an array of  $R$  row vectors with  $C$  components each, according to rule (4).

8. If the member is an array of  $S$  row-major matrices with  $C$  columns and  $R$  rows, the matrix is stored identically to a row of  $S \times R$  row vectors with  $C$  components each, according to rule (4).
9. If the member is a structure, the base alignment of the structure is  $N$ , where  $N$  is the largest base alignment value of any of its members, and rounded up to the base alignment of a `vec4`. The individual members of this sub-structure are then assigned offsets by applying this set of rules recursively, where the base offset of the first member of the sub-structure is equal to the aligned offset of the structure. The structure may have padding at the end; the base offset of the member following the sub-structure is rounded up to the next multiple of the base alignment of the structure.
10. If the member is an array of  $S$  structures, the  $S$  elements of the array are laid out in order, according to rule (9).

Shader storage blocks (see section 7.8) also support the `std140` layout qualifier, as well as a `std430` qualifier not supported for uniform blocks. When using the `std430` storage layout, shader storage blocks will be laid out in buffer storage identically to uniform and shader storage blocks using the `std140` layout, except that the base alignment and stride of arrays of scalars and vectors in rule 4 and of structures in rule 9 are not rounded up a multiple of the base alignment of a `vec4`.

### 7.6.3 Uniform Buffer Object Bindings

The value an active uniform inside a named uniform block is extracted from the data store of a buffer object bound to one of an array of uniform buffer binding points. The number of binding points can be queried using `GetIntegerv` with the constant `MAX_UNIFORM_BUFFER_BINDINGS`.

Regions of buffer objects are bound as storage for uniform blocks by calling one of the commands `BindBufferRange` or `BindBufferBase` (see section 6.1.1) with *target* set to `UNIFORM_BUFFER`.

Each of a program's active uniform blocks has a corresponding uniform buffer object binding point. The binding is established when a program is linked or re-linked, and the initial value of the binding is specified by a `layout` qualifier (if present), or zero otherwise. The binding point can be assigned by calling:

```
void UniformBlockBinding( uint program,  
                          uint uniformBlockIndex, uint uniformBlockBinding );
```

*program* is a name of a program object for which the command `LinkProgram` has been issued in the past.

If successful, **UniformBlockBinding** specifies that *program* will use the data store of the buffer object bound to the binding point *uniformBlockBinding* to extract the values of the uniforms in the uniform block identified by *uniformBlockIndex*.

When executing shaders that access uniform blocks, the binding point corresponding to each active uniform block must be populated with a buffer object with a size no smaller than the minimum required size of the uniform block (the value of `UNIFORM_BLOCK_DATA_SIZE`). For binding points populated by **BindBufferRange**, the size in question is the value of the *size* parameter. If any active uniform block is not backed by a sufficiently large buffer object, the results of shader execution may be undefined or modified, as described in section 6.4. Shaders may be executed to process the primitives and vertices specified by any command that transfers vertices to the GL.

### Errors

An `INVALID_VALUE` error is generated if *program* is not the name of either a program or shader object.

An `INVALID_OPERATION` error is generated if *program* is the name of a shader object.

An `INVALID_VALUE` error is generated if *uniformBlockIndex* is not an active uniform block index of *program*, or if *uniformBlockBinding* is greater than or equal to the value of `MAX_UNIFORM_BUFFER_BINDINGS`.

## 7.7 Atomic Counter Buffers

The values of atomic counters are backed by buffer object storage. The mechanisms for accessing individual atomic counters in a buffer object and connecting to an atomic counter are described in this section.

There is a set of implementation-dependent maximums for the number of active atomic counter buffers referenced by each shader. If the number of atomic counter buffer bindings referenced by any shader in the program exceeds the corresponding limit, the program will fail to link. The limits for vertex, tessellation control, tessellation evaluation, geometry, fragment, and compute shaders can be obtained by calling **GetIntegerv** with *pname* values of `MAX_VERTEX_ATOMIC_COUNTER_BUFFERS`, `MAX_TESS_CONTROL_ATOMIC_COUNTER_BUFFERS`, `MAX_TESS_EVALUATION_ATOMIC_COUNTER_BUFFERS`, `MAX_GEOMETRY_ATOMIC_COUNTER_BUFFERS`, `MAX_FRAGMENT_ATOMIC_COUNTER_BUFFERS`, and `MAX_COMPUTE_ATOMIC_COUNTER_BUFFERS`, respectively.

Additionally, there is an implementation-dependent limit on the sum of the

number of active atomic counter buffers used by each shader stage of a program. If an atomic counter buffer is used by multiple shader stages, each such use counts separately against this combined limit. The combined atomic counter buffer use limit can be obtained by calling **GetIntegerv** with a *pname* of `MAX_ATOMIC_COUNTER_BUFFERS`.

### 7.7.1 Atomic Counter Buffer Object Storage

Atomic counters stored in buffer objects are represented in memory as follows:

- Members of type `atomic_uint` are extracted from a buffer object by reading a single `uint`-typed value at the specified offset.
- Arrays of type `atomic_uint` are stored in memory by element order, with array element member zero at the lowest offset. The difference in offsets between each pair of elements in the array in basic machine units is referred to as the array stride, and is constant across the entire array. The array stride, `UNIFORM_ARRAY_STRIDE`, is an implementation-dependent value and may be queried after a program is linked.

### 7.7.2 Atomic Counter Buffer Bindings

The value of an active atomic counter is extracted from or written to the data store of a buffer object bound to one of an array of atomic counter buffer binding points. The number of binding points can be queried by calling **GetIntegerv** with a *pname* of `MAX_ATOMIC_COUNTER_BUFFER_BINDINGS`.

Regions of buffer objects are bound as storage for atomic counters by calling one of the commands **BindBufferRange** or **BindBufferBase** (see section 6.1.1) with *target* set to `ATOMIC_COUNTER_BUFFER`.

Each of a program's active atomic counter buffer bindings has a corresponding atomic counter buffer binding point. This binding point is established with the `layout` qualifier in the shader text, either explicitly or implicitly, as described in the OpenGL Shading Language Specification .

When executing shaders that access atomic counters, each active atomic counter buffer must be populated with a buffer object with a size no smaller than the minimum required size for that buffer (the value of `ATOMIC_COUNTER_BUFFER_DATA_SIZE`). For binding points populated by **BindBufferRange**, the size in question is the value of the *size* parameter. If any active atomic counter buffer is not backed by a sufficiently large buffer object, the results of shader execution may be undefined or modified, as described in section 6.4.

## 7.8 Shader Buffer Variables and Shader Storage Blocks

Shaders can declare named *buffer variables*, as described in the OpenGL Shading Language Specification . Sets of buffer variables are grouped into interface blocks called *shader storage blocks*. The values of each buffer variable in a shader storage block are read from or written to the data store of a buffer object bound to the binding point associated with the block. The values of active buffer variables may be changed by executing shaders that assign values to them or perform atomic memory operations on them, by modifying the contents of the bound buffer object's data store with the commands in sections 6.2, 6.2.1, 6.3, 6.5, and 6.6. by binding a new buffer object to the binding point associated with the block, or by changing the binding point associated with the block.

Buffer variables in shader storage blocks are represented in memory in the same way as uniforms stored in uniform blocks, as described in section 7.6.2.1. When a program is linked successfully, each active buffer variable is assigned an offset relative to the base of the buffer object binding associated with its shader storage block. For buffer variables declared as arrays and matrices, strides between array elements or matrix columns or rows will also be assigned. Offsets and strides of buffer variables will be assigned in an implementation-dependent manner unless the shader storage block is declared using the `std140` or `std430` storage layout qualifiers. For `std140` and `std430` shader storage blocks, offsets will be assigned using the method described in section 7.6.2.2. If a program is re-linked, existing buffer variable offsets and strides are invalidated, and a new set of active variables, offsets, and strides will be generated.

The total amount of buffer object storage that can be accessed in any shader storage block is subject to an implementation-dependent limit. The maximum amount of available space, in basic machine units, can be queried by calling **GetIntegerv** with the constant `MAX_SHADER_STORAGE_BLOCK_SIZE`. If the amount of storage required for any shader storage block exceeds this limit, a program will fail to link.

If the number of active shader storage blocks referenced by the shaders in a program exceeds implementation-dependent limits, the program will fail to link. The limits for vertex, tessellation control, tessellation evaluation, geometry, fragment, and compute shaders can be obtained by calling **GetIntegerv** with pname values of `MAX_VERTEX_SHADER_STORAGE_BLOCKS`, `MAX_TESS_CONTROL_SHADER_STORAGE_BLOCKS`, `MAX_TESS_EVALUATION_SHADER_STORAGE_BLOCKS`, `MAX_GEOMETRY_SHADER_STORAGE_BLOCKS`, `MAX_FRAGMENT_SHADER_STORAGE_BLOCKS`, and `MAX_COMPUTE_SHADER_STORAGE_BLOCKS`, respectively. Additionally, a program will fail to link if the sum of the number of active shader storage blocks referenced by

each shader stage in a program exceeds the value of the implementation-dependent limit `MAX_COMBINED_SHADER_STORAGE_BLOCKS`. If a shader storage block in a program is referenced by multiple shaders, each such reference counts separately against this combined limit.

When a named shader storage block is declared by multiple shaders in a program, it must be declared identically in each shader. The buffer variables within the block must be declared with the same names, types, qualification, and declaration order. If a program contains multiple shaders with different declarations for the same named shader storage block, the program will fail to link.

Regions of buffer objects are bound as storage for shader storage blocks by calling one of the commands **BindBufferRange** or **BindBufferBase** (see section 6.1.1) with target set to `SHADER_STORAGE_BUFFER`.

Each of a program's active shader storage blocks has a corresponding shader storage buffer object binding point. When a program object is linked, the shader storage buffer object binding point assigned to each of its active shader storage blocks is reset to the value specified by the corresponding `bindingLayout` qualifier, if present, or zero otherwise. After a program is linked, the command

```
void ShaderStorageBlockBinding( uint program,
                               uint storageBlockIndex, uint storageBlockBinding );
```

changes the active shader storage block with an assigned index of *storageBlockIndex* in program object *program*. **ShaderStorageBlockBinding** specifies that *program* will use the data store of the buffer object bound to the binding point *storageBlockBinding* to read and write the values of the buffer variables in the shader storage block identified by *storageBlockIndex*.

### Errors

An `INVALID_VALUE` error is generated if *program* is not the name of either a program or shader object.

An `INVALID_OPERATION` error is generated if *program* is the name of a shader object.

An `INVALID_VALUE` error is generated if *storageBlockIndex* is not an active shader storage block index in *program*, or if *storageBlockBinding* is greater than or equal to the value of `MAX_SHADER_STORAGE_BUFFER_BINDINGS`.

When executing shaders that access shader storage blocks, the binding point corresponding to each active shader storage block must be populated with a buffer object with a size no smaller than the minimum required size of the shader storage

block (the value of `BUFFER_SIZE` for the appropriate `SHADER_STORAGE_BLOCK` resource). For binding points populated by **BindBufferRange**, the size in question is the value of the *size* parameter or the size of the buffer minus the value of the *offset* parameter, whichever is smaller. If any active shader storage block is not backed by a sufficiently large buffer object, the results of shader execution may be undefined or modified, as described in section 6.4.

## 7.9 Subroutine Uniform Variables

Subroutine uniform variables are similar to uniform variables, except they are context state rather than program state, and apply only to a single program stage. Having subroutine uniforms be context state allows them to have different values if the program is used in multiple contexts simultaneously. There is a set of subroutine uniforms for each shader stage.

A subroutine uniform may have an explicit location specified in the shader. At link time, all active subroutine uniforms without an explicit location will be assigned a unique location. The value of `ACTIVE_SUBROUTINE_UNIFORM_LOCATIONS` for a program object is the largest assigned or generated location plus one. An assigned location will never take the location of an explicitly assigned location, even if that subroutine uniform is inactive. Between the location zero and the value of `ACTIVE_SUBROUTINE_UNIFORM_LOCATIONS` minus one there may be unused locations, either because they were not assigned a subroutine uniform or because the subroutine uniform was determined to be inactive by the linker. These locations will be ignored when assigning the subroutine index as described below.

There is an implementation-dependent limit on the number of active subroutine uniform locations in each shader stage; a program will fail to link if the number of subroutine uniform locations required is greater than the value of `MAX_SUBROUTINE_UNIFORM_LOCATIONS` or if an explicit subroutine uniform location is outside this limit. For active subroutine uniforms declared as arrays, the declared array elements are assigned consecutive locations.

Each function in a shader associated with a subroutine type is considered an active subroutine, unless the compiler conclusively determines that the function could never be assigned to an active subroutine uniform. The subroutine functions can be assigned an explicit index in the shader between zero and the value of `MAX_SUBROUTINES` minus one. At link time, all active subroutines without an explicit index will be assigned an index between zero and the value of `ACTIVE_SUBROUTINES` minus one. An assigned index will never take the same index of an explicitly assigned index in the shader, even if that subroutine is inactive. Between index zero and the value of `ACTIVE_SUBROUTINES` minus one there may

Interface	Shader Type
VERTEX_SUBROUTINE	VERTEX_SHADER
TESS_CONTROL_SUBROUTINE	TESS_CONTROL_SHADER
TESS_EVALUATION_SUBROUTINE	TESS_EVALUATION_SHADER
GEOMETRY_SUBROUTINE	GEOMETRY_SHADER
FRAGMENT_SUBROUTINE	FRAGMENT_SHADER
COMPUTE_SUBROUTINE	COMPUTE_SHADER

Table 7.9: Interfaces for active subroutines for a particular shader type in a program.

Interface	Shader Type
VERTEX_SUBROUTINE_UNIFORM	VERTEX_SHADER
TESS_CONTROL_SUBROUTINE_UNIFORM	TESS_CONTROL_SHADER
TESS_EVALUATION_SUBROUTINE_UNIFORM	TESS_EVALUATION_SHADER
GEOMETRY_SUBROUTINE_UNIFORM	GEOMETRY_SHADER
FRAGMENT_SUBROUTINE_UNIFORM	FRAGMENT_SHADER
COMPUTE_SUBROUTINE_UNIFORM	COMPUTE_SHADER

Table 7.10: Interfaces for active subroutine uniforms for a particular shader type in a program.

be unused indices either because they weren't assigned an index by the linker or because the subroutine was determined to be inactive by the linker. If there are no explicitly defined subroutine indices in the shader the implementation must assign indices between zero and the value of `ACTIVE_SUBROUTINES` minus one with no index unused. It is recommended, but not required, that the application assigns a range of tightly packed indices starting from zero to avoid indices between zero and the value of `ACTIVE_SUBROUTINES` minus one being unused.

To determine the set of active subroutines and subroutines used by a particular shader stage of a program, applications can query the properties and active resources of the interfaces for the shader type, as listed in tables 7.9 and 7.10.

Additionally, dedicated commands are provided to determine properties of active subroutines and active subroutine uniforms. The commands

```
uint GetSubroutineIndex( uint program, enum shadertype,
    const char *name );
void GetActiveSubroutineName( uint program,
```



```
enum shadertype, uint index, sizei bufsize,
sizei *length, char *name);
```

are equivalent to

```
GetProgramResourceIndex (program, programInterface, name);
```

and

```
GetProgramResourceName (program, programInterface,
index, bufsize, length, name);
```

respectively, where *programInterface* is taken from table 7.9 according to the value of *shadertype*.

The commands

```
int GetSubroutineUniformLocation( uint program,
enum shadertype, const char *name );
void GetActiveSubroutineUniformName( uint program,
enum shadertype, uint index, sizei bufsize,
sizei *length, char *name );
void GetActiveSubroutineUniformiv( uint program,
enum shadertype, uint index, enum pname, int *values );
```

are equivalent to

```
GetProgramResourceLocation (program, programInterface, name);
```

```
GetProgramResourceName (program, programInterface,
index, bufsize, length, name);
```

and

```
GetProgramResourceiv (program, programInterface,
index, 1, &pname, maxSize, NULL, values);
```

respectively, where *programInterface* is taken from table 7.10 according to the value of *shadertype*. For **GetActiveSubroutineUniformiv**, *pname* must be one of NUM\_COMPATIBLE\_SUBROUTINES or COMPATIBLE\_SUBROUTINES, and *maxSize* is taken to specify a sufficiently large buffer to receive all values that would be written to *params*.

The command

```
void UniformSubroutinesuiv( enum shadertype, sizei count,
    const uint *indices );
```

will load all active subroutine uniforms for shader stage *shadertype* with subroutine indices from *indices*, storing *indices*[*i*] into the uniform at location *i*. The indices for any locations between zero and the value of `ACTIVE_SUBROUTINE_UNIFORM_LOCATIONS` minus one which are not used will be ignored.

### Errors

An `INVALID_ENUM` error is generated if *shadertype* is not one of the values in table 7.1,

An `INVALID_VALUE` error is generated if *count* is negative, is not equal to the value of `ACTIVE_SUBROUTINE_UNIFORM_LOCATIONS` for the program currently in use at shader stage *shadertype*, or if the uniform at location *i* is used and the value in *indices*[*i*] is greater than or equal to the value of `ACTIVE_SUBROUTINES` for the shader stage.

An `INVALID_VALUE` error is generated if the value of *indices*[*i*] for a used uniform location specifies an unused subroutine index.

An `INVALID_OPERATION` error is generated if, for any subroutine index being loaded to a particular uniform location, the function corresponding to the subroutine index was not associated (as defined in section 6.1.2 of the OpenGL Shading Language Specification ) with the type of the subroutine variable at that location.

An `INVALID_OPERATION` error is generated if no program is active.

Each subroutine uniform must have at least one subroutine to assign to the uniform. A program will fail to link if any stage has one or more subroutine uniforms that has no subroutine associated with the subroutine type of the uniform.

When the active program for a shader stage is re-linked or changed by a call to `UseProgram`, `BindProgramPipeline`, or `UseProgramStages`, subroutine uniforms for that stage are reset to arbitrarily chosen default functions with compatible subroutine types.

## 7.10 Samplers

*Samplers* are special uniforms used in the OpenGL Shading Language to identify the texture object used for each texture lookup. The value of a sampler indicates the texture image unit being accessed. Setting a sampler's value to *i* selects texture

image unit number  $i$ . The values of  $i$  ranges from zero to the implementation-dependent maximum supported number of texture image units **minus one**.

The type of the sampler identifies the target on the texture image unit, as shown in table 7.3 for `sampler*` types. The texture object bound to that texture image unit's target is then used for the texture lookup. For example, a variable of type `sampler2D` selects target `TEXTURE_2D` on its texture image unit. Binding of texture objects to targets is done as usual with **BindTexture**. Selecting the texture image unit to bind to is done as usual with **ActiveTexture**.

The location of a sampler is is queried with **GetUniformLocation**, just like any uniform variable. Sampler values must be set by calling **Uniform1i{v}**.

### Errors

An `INVALID_VALUE` error is generated if **Uniform1i{v}** is used to set a sampler to a value less than zero or greater than or equal to the value of `MAX_COMBINED_TEXTURE_IMAGE_UNITS`.

An `INVALID_OPERATION` error is generated if a sampler is loaded with any of the other **Uniform\*** commands.

It is not allowed to have variables of different sampler types pointing to the same texture image unit within a program object. This situation can only be detected at the next rendering command issued, and an `INVALID_OPERATION` error will then be generated.

Active samplers are samplers actually being used in a program object. The **LinkProgram** command determines if a sampler is active or not. The **LinkProgram** command will attempt to determine if the active samplers in the shader(s) contained in the program object exceed the maximum allowable limits. If it determines that the count of active samplers exceeds the allowable limits, then the link fails (these limits can be different for different types of shaders). Each active sampler variable counts against the limit, even if multiple samplers refer to the same texture image unit.

## 7.11 Images

*Images* are special uniforms used in the OpenGL Shading Language to identify a level of a texture to be read or written using built-in image load, store, and atomic functions in the manner described in section 8.25. The value of an image uniform is an integer specifying the image unit accessed. Image units are numbered beginning at zero, and there is an implementation-dependent number of available image units

(the value of `MAX_IMAGE_UNITS`).

Note that image units used for image variables are independent of the texture image units used for sampler variables; the number of units provided by the implementation may differ. Textures are bound independently and separately to image and texture image units.

The type of an image variable must match the texture target of the image currently bound to the image unit, otherwise the result of a load, store, or atomic operation is undefined (see section 4.1.7.2 of the OpenGL Shading Language Specification for more details).

The location of an image variable needs to be queried with **GetUniformLocation**, just like any uniform variable. Image values must be set by calling **Uniform1i{v}**.

Unlike samplers, there is no limit on the number of active image variables that may be used by a program or by any particular shader. However, given that there is an implementation-dependent limit on the number of unique image units, the actual number of images that may be used by all shaders in a program is limited.

### Errors

An `INVALID_VALUE` error is generated if **Uniform1i{v}** is used to set an image uniform to a value less than zero or greater than or equal to the value of `MAX_IMAGE_UNITS`.

An `INVALID_OPERATION` error is generated if an image variable is loaded with any of the other **Uniform\*** commands.

## 7.12 Shader Memory Access

As described in the OpenGL Shading Language Specification, shaders may perform random-access reads and writes to buffer object memory by reading from, assigning to, or performing atomic memory operation on shader buffer variables, or to texture or buffer object memory by using built-in image load, store, and atomic functions operating on shader image variables. The ability to perform such random-access reads and writes in systems that may be highly pipelined results in ordering and synchronization issues discussed in the sections below.

### 7.12.1 Shader Memory Access Ordering

The order in which texture or buffer object memory is read or written by shaders is largely undefined. For some shader types (vertex, tessellation evaluation, and in

some cases, fragment), even the number of shader invocations that might perform loads and stores is undefined. In particular, the following rules apply:

- While a vertex or tessellation evaluation shader will be executed at least once for each unique vertex specified by the application (vertex shaders) or generated by the tessellation primitive generator (tessellation evaluation shaders), it may be executed more than once for implementation-dependent reasons. Additionally, if the same vertex is specified multiple times in a collection of primitives (e.g., repeating an index in **DrawElements**), the vertex shader might be run only once.
- For each fragment generated by the GL, the number of fragment shader invocations depends on a number of factors. If the fragment fails the pixel ownership test (see section 17.3.1), the fragment shader may not be executed. Otherwise, if the framebuffer has no multisample buffer (the value of `SAMPLE_BUFFERS` is zero), the fragment shader will be invoked exactly once. If the fragment shader specifies per-sample shading, the fragment shader will be run once per covered sample. Otherwise, the number of fragment shader invocations is undefined, but must be in the range  $[1, N]$ , where  $N$  is the number of samples covered by the fragment.
- If a fragment shader is invoked to process fragments or samples not covered by a primitive being rasterized to facilitate the approximation of derivatives for texture lookups, stores and atomics have no effect.
- The relative order of invocations of the same shader type are undefined. A store issued by a shader when working on primitive B might complete prior to a store for primitive A, even if primitive A is specified prior to primitive B. This applies even to fragment shaders; while fragment shader outputs are written to the framebuffer in primitive order, stores executed by fragment shader invocations are not.
- The relative order of invocations of different shader types is largely undefined. However, when executing a shader whose inputs are generated from a previous programmable stage, the shader invocations from the previous stage are guaranteed to have executed far enough to generate final values for all next-stage inputs. That implies shader completion for all stages except geometry; geometry shaders are guaranteed only to have executed far enough to emit all needed vertices.

The above limitations on shader invocation order also make some forms of synchronization between shader invocations within a single set of primitives unimplementable. For example, having one invocation poll memory written by another

invocation assumes that the other invocation has been launched and can complete its writes. The only case where such a guarantee is made is when the inputs of one shader invocation are generated from the outputs of a shader invocation in a previous stage.

Stores issued to different memory locations within a single shader invocation may not be visible to other invocations in the order they were performed. The built-in function `memoryBarrier()` may be used to provide stronger ordering of reads and writes performed by a single invocation. Calling `memoryBarrier()` guarantees that any memory transactions issued by the shader invocation prior to the call complete prior to the memory transactions issued after the call. Memory barriers may be needed for algorithms that require multiple invocations to access the same memory and require the operations need to be performed in a partially-defined relative order. For example, if one shader invocation does a series of writes, followed by a `memoryBarrier()` call, followed by another write, then another invocation that sees the results of the final write will also see the previous writes. Without the memory barrier, the final write may be visible before the previous writes.

The built-in atomic memory transaction functions may be used to read and write a given memory address atomically. While built-in atomic functions issued by multiple shader invocations are executed in undefined order relative to each other, these functions perform both a read and a write of a memory address and guarantee that no other memory transaction will write to the underlying memory between the read and write. Atomics allow shaders to use shared global addresses for mutual exclusion or as counters, among other uses.

### 7.12.2 Shader Memory Access Synchronization

Data written to textures or buffer objects by a shader invocation may eventually be read by other shader invocations, sourced by other fixed pipeline stages, or read back by the application. When applications write to buffer objects or textures using API commands such as **TexSubImage\*** or **BufferSubData**, the GL implementation knows when and where writes occur and can perform implicit synchronization to ensure that operations requested before the update see the original data and that subsequent operations see the modified data. Without logic to track the target address of each shader instruction performing a store, automatic synchronization of stores performed by a shader invocation would require the GL implementation to make worst-case assumptions at significant performance cost. To permit cases where textures or buffers may be read or written in different pipeline stages without the overhead of automatic synchronization, buffer object and texture stores performed by shaders are not automatically synchronized with other GL operations

using the same memory.

Explicit synchronization is required to ensure that the effects of buffer and texture data stores performed by shaders will be visible to subsequent operations using the same objects and will not overwrite data still to be read by previously requested operations. Without manual synchronization, shader stores for a “new” primitive may complete before processing of an “old” primitive completes. Additionally, stores for an “old” primitive might not be completed before processing of a “new” primitive starts. The command

```
void MemoryBarrier(bitfield barriers);
```

defines a barrier ordering the memory transactions issued prior to the command relative to those issued after the barrier. For the purposes of this ordering, memory transactions performed by shaders are considered to be issued by the rendering command that triggered the execution of the shader. *barriers* is a bitfield indicating the set of operations that are synchronized with shader stores; the bits used in *barriers* are as follows:

- `VERTEX_ATTRIB_ARRAY_BARRIER_BIT`: If set, vertex data sourced from buffer objects after the barrier will reflect data written by shaders prior to the barrier. The set of buffer objects affected by this bit is derived from the buffer object bindings used for arrays of generic vertex attributes (`VERTEX_ATTRIB_ARRAY_BUFFER` bindings).
- `ELEMENT_ARRAY_BARRIER_BIT`: If set, vertex array indices sourced from buffer objects after the barrier will reflect data written by shaders prior to the barrier. The buffer objects affected by this bit are derived from the `ELEMENT_ARRAY_BUFFER` binding.
- `UNIFORM_BARRIER_BIT`: Shader uniforms sourced from buffer objects after the barrier will reflect data written by shaders prior to the barrier.
- `TEXTURE_FETCH_BARRIER_BIT`: Texture fetches from shaders, including fetches from buffer object memory via buffer textures, after the barrier will reflect data written by shaders prior to the barrier.
- `SHADER_IMAGE_ACCESS_BARRIER_BIT`: Memory accesses using shader built-in image load, store, and atomic functions issued after the barrier will reflect data written by shaders prior to the barrier. Additionally, image stores and atomics issued after the barrier will not execute until all memory accesses (e.g., loads, stores, texture fetches, vertex fetches) initiated prior to the barrier complete.

- `COMMAND_BARRIER_BIT`: Command data sourced from buffer objects by **Draw\*Indirect** and **DispatchComputeIndirect** commands after the barrier will reflect data written by shaders prior to the barrier. The buffer objects affected by this bit are derived from the `DRAW_INDIRECT_BUFFER` and `DISPATCH_INDIRECT_BUFFER` bindings.
- `PIXEL_BUFFER_BARRIER_BIT`: Reads/writes of buffer objects via the `PIXEL_PACK_BUFFER` and `PIXEL_UNPACK_BUFFER` bindings (**ReadPixels**, **TexSubImage**, etc.) after the barrier will reflect data written by shaders prior to the barrier. Additionally, buffer object writes issued after the barrier will wait on the completion of all shader writes initiated prior to the barrier.
- `TEXTURE_UPDATE_BARRIER_BIT`: Writes to a texture via **Tex(Sub)Image\***, **CopyTex\***, or **CompressedTex\***, and reads via **GetTexImage** after the barrier will reflect data written by shaders prior to the barrier. Additionally, texture writes from these commands issued after the barrier will not execute until all shader writes initiated prior to the barrier complete.
- `BUFFER_UPDATE_BARRIER_BIT`: Reads and writes to buffer object memory after the barrier using the commands in sections 6.2, 6.2.1, 6.3, 6.6, and 6.5. will reflect data written by shaders prior to the barrier. Additionally, writes via these commands issued after the barrier will wait on the completion of any shader writes to the same memory initiated prior to the barrier.
- `FRAMEBUFFER_BARRIER_BIT`: Reads and writes via framebuffer object attachments after the barrier will reflect data written by shaders prior to the barrier. Additionally, framebuffer writes issued after the barrier will wait on the completion of all shader writes issued prior to the barrier.
- `TRANSFORM_FEEDBACK_BARRIER_BIT`: Writes via transform feedback bindings after the barrier will reflect data written by shaders prior to the barrier. Additionally, transform feedback writes issued after the barrier will wait on the completion of all shader writes issued prior to the barrier.
- `ATOMIC_COUNTER_BARRIER_BIT`: Accesses to atomic counters after the barrier will reflect writes prior to the barrier.
- `SHADER_STORAGE_BARRIER_BIT`: Memory accesses using shader buffer variables issued after the barrier will reflect data written by shaders prior to the barrier. Additionally, assignments to and atomic operations performed on shader buffer variables after the barrier will not execute until all memory



accesses (e.g., loads, stores, texture fetches, vertex fetches) initiated prior to the barrier complete.

If *barriers* is `ALL_BARRIER_BITS`, shader memory accesses will be synchronized relative to all the operations described above.

Implementations may cache buffer object and texture image memory that could be written by shaders in multiple caches; for example, there may be separate caches for texture, vertex fetching, and one or more caches for shader memory accesses. Implementations are not required to keep these caches coherent with shader memory writes. Stores issued by one invocation may not be immediately observable by other pipeline stages or other shader invocations because the value stored may remain in a cache local to the processor executing the store, or because data overwritten by the store is still in a cache elsewhere in the system. When **MemoryBarrier** is called, the GL flushes and/or invalidates any caches relevant to the operations specified by the *barriers* parameter to ensure consistent ordering of operations across the barrier.

To allow for independent shader invocations to communicate by reads and writes to a common memory address, image variables in the OpenGL Shading Language may be declared as `coherent`. Buffer object or texture image memory accessed through such variables may be cached only if caches are automatically updated due to stores issued by any other shader invocation. If the same address is accessed using both coherent and non-coherent variables, the accesses using variables declared as `coherent` will observe the results stored using coherent variables in other invocations. Using variables declared as `coherent` guarantees only that the results of stores will be immediately visible to shader invocations using similarly-declared variables; calling **MemoryBarrier** is required to ensure that the stores are visible to other operations.

The following guidelines may be helpful in choosing when to use coherent memory accesses and when to use barriers.

- Data that are read-only or constant may be accessed without using coherent variables or calling **MemoryBarrier**. Updates to the read-only data via commands such as **BufferSubData** will invalidate shader caches implicitly as required.
- Data that are shared between shader invocations at a fine granularity (e.g., written by one invocation, consumed by another invocation) should use coherent variables to read and write the shared data.
- Data written by one shader invocation and consumed by other shader invocations launched as a result of its execution (*dependent invocations*)

should use coherent variables in the producing shader invocation and call `memoryBarrier()` after the last write. The consuming shader invocation should also use coherent variables.

- Data written to image variables in one rendering pass and read by the shader in a later pass need not use coherent variables or `memoryBarrier()`. Calling **MemoryBarrier** with the `SHADER_IMAGE_ACCESS_BARRIER_BIT` set in *barriers* between passes is necessary.
- Data written by the shader in one rendering pass and read by another mechanism (e.g., vertex or index buffer pulling) in a later pass need not use coherent variables or `memoryBarrier()`. Calling **MemoryBarrier** with the appropriate bits set in *barriers* between passes is necessary.

## 7.13 Shader, Program, and Program Pipeline Queries

The command

```
void GetShaderiv(uint shader, enum pname, int *params);
```

returns properties of the shader object named *shader* in *params*. The parameter value to return is specified by *pname*.

If *pname* is `SHADER_TYPE`, one of the values from table 7.1 corresponding to the type of *shader* is returned.

If *pname* is `DELETE_STATUS`, `TRUE` is returned if the shader has been flagged for deletion and `FALSE` is returned otherwise.

If *pname* is `COMPILE_STATUS`, `TRUE` is returned if the shader was last compiled successfully, and `FALSE` is returned otherwise.

If *pname* is `INFO_LOG_LENGTH`, the length of the info log, including a null terminator, is returned. If there is no info log, zero is returned.

If *pname* is `SHADER_SOURCE_LENGTH`, the length of the concatenation of the source strings making up the shader source, including a null terminator, is returned. If no source has been defined, zero is returned.

### Errors

An `INVALID_VALUE` error is generated if *shader* is not the name of either a program or shader object.

An `INVALID_OPERATION` error is generated if *shader* is the name of a program object.

An `INVALID_ENUM` error is generated if *pname* is not `SHADER_TYPE`,

```
DELETE_STATUS, COMPILE_STATUS, INFO_LOG_LENGTH, or SHADER_  
SOURCE_LENGTH.
```

The command

```
void GetProgramiv( uint program, enum pname,  
int *params );
```

returns properties of the program object named *program* in *params*. The parameter value to return is specified by *pname*.

If *pname* is `DELETE_STATUS`, `TRUE` is returned if the program has been flagged for deletion, and `FALSE` is returned otherwise.

If *pname* is `LINK_STATUS`, `TRUE` is returned if the program was last compiled successfully, and `FALSE` is returned otherwise.

If *pname* is `VALIDATE_STATUS`, `TRUE` is returned if the last call to **ValidateProgram** (see section 11.1.3.11) with *program* was successful, and `FALSE` is returned otherwise.

If *pname* is `INFO_LOG_LENGTH`, the length of the info log, including a null terminator, is returned. If there is no info log, zero is returned.

If *pname* is `ATTACHED_SHADERS`, the number of objects attached is returned.

If *pname* is `ACTIVE_ATTRIBUTES`, the number of active attributes (see section 7.3.1) in *program* is returned. If no active attributes exist, zero is returned.

If *pname* is `ACTIVE_ATTRIBUTE_MAX_LENGTH`, the length of the longest active attribute name, including a null terminator, is returned. If no active attributes exist, zero is returned.

If *pname* is `ACTIVE_UNIFORMS`, the number of active uniforms is returned. If no active uniforms exist, zero is returned.

If *pname* is `ACTIVE_UNIFORM_MAX_LENGTH`, the length of the longest active uniform name, including a null terminator, is returned. If no active uniforms exist, zero is returned.

If *pname* is `TRANSFORM_FEEDBACK_BUFFER_MODE`, the buffer mode used when transform feedback (see section 11.1.2.1) is active is returned. It can be one of `SEPARATE_ATTRIBS` or `INTERLEAVED_ATTRIBS`.

If *pname* is `TRANSFORM_FEEDBACK_VARYINGS`, the number of output variables to capture in transform feedback mode for the program is returned.

If *pname* is `TRANSFORM_FEEDBACK_VARYING_MAX_LENGTH`, the length of the longest output variable name specified to be used for transform feedback, including a null terminator, is returned. If no outputs are used for transform feedback, zero is returned.

If *pname* is `ACTIVE_UNIFORM_BLOCKS`, the number of uniform blocks for *program* containing active uniforms is returned.

If *pname* is `ACTIVE_UNIFORM_BLOCK_MAX_NAME_LENGTH`, the length of the longest active uniform block name, including the null terminator, is returned.

If *pname* is `GEOMETRY_VERTICES_OUT`, the maximum number of vertices the geometry shader (see section 11.3) will output is returned.

If *pname* is `GEOMETRY_INPUT_TYPE`, the geometry shader input type, which must be one of `POINTS`, `LINES`, `LINES_ADJACENCY`, `TRIANGLES` or `TRIANGLES_ADJACENCY`, is returned.

If *pname* is `GEOMETRY_OUTPUT_TYPE`, the geometry shader output type, which must be one of `POINTS`, `LINE_STRIP` or `TRIANGLE_STRIP`, is returned.

If *pname* is `GEOMETRY_SHADER_INVOCATIONS`, the number of geometry shader invocations per primitive will be returned.

If *pname* is `TESS_CONTROL_OUTPUT_VERTICES`, the number of vertices in the tessellation control shader (see section 11.2.1) output patch is returned.

If *pname* is `TESS_GEN_MODE`, `QUADS`, `TRIANGLES`, or `ISOLINES` is returned, depending on the primitive mode declaration in the tessellation evaluation shader (see section 11.2.3). If *pname* is `TESS_GEN_SPACING`, `EQUAL`, `FRACTIONAL_EVEN`, or `FRACTIONAL_ODD` is returned, depending on the spacing declaration in the tessellation evaluation shader. If *pname* is `TESS_GEN_VERTEX_ORDER`, `CCW` or `CW` is returned, depending on the vertex order declaration in the tessellation evaluation shader. If *pname* is `TESS_GEN_POINT_MODE`, `TRUE` is returned if point mode is enabled in a tessellation evaluation shader declaration; `FALSE` is returned otherwise.

If *pname* is `COMPUTE_WORK_GROUP_SIZE`, an array of three integers containing the local work group size of the compute program (see chapter 19), as specified by its input layout qualifier(s), is returned

If *pname* is `PROGRAM_SEPARABLE`, `TRUE` is returned if the program has been flagged for use as a separable program object that can be bound to individual shader stages with **UseProgramStages**.

If *pname* is `PROGRAM_BINARY_RETRIEVABLE_HINT`, the current value of whether the binary retrieval hint is enabled for *program* is returned.

If *pname* is `ACTIVE_ATOMIC_COUNTER_BUFFERS`, the number of active atomic counter buffers used by *program* is returned.

### Errors

An `INVALID_VALUE` error is generated if *program* is not the name of either a program or shader object.

An `INVALID_OPERATION` error is generated if *program* is the name of a shader object.

An `INVALID_ENUM` error is generated if *pname* is not one of the values

listed above.

An `INVALID_OPERATION` error is generated if `GEOMETRY_VERTICES_OUT`, `GEOMETRY_INPUT_TYPE`, `GEOMETRY_OUTPUT_TYPE`, or `GEOMETRY_SHADER_INVOCATIONS` are queried for a program which has not been linked successfully, or which does not contain objects to form a geometry shader.

An `INVALID_OPERATION` error is generated if `TESS_CONTROL_OUTPUT_VERTICES` is queried for a program which has not been linked successfully, or which does not contain objects to form a tessellation control shader.

An `INVALID_OPERATION` error is generated if `TESS_GEN_MODE`, `TESS_GEN_SPACING`, `TESS_GEN_VERTEX_ORDER`, or `TESS_GEN_POINT_MODE` are queried for a program which has not been linked successfully, or which does not contain objects to form a tessellation evaluation shader.

An `INVALID_OPERATION` error is generated if `COMPUTE_WORK_GROUP_SIZE` is queried for a program which has not been linked successfully, or which does not contain objects to form a compute shader.

The command

```
void GetProgramPipelineiv(uint pipeline, enum pname,
    int *params);
```

returns properties of the program pipeline object named *pipeline* in *params*. The parameter value to return is specified by *pname*.

If *pipeline* is a name that has been generated (without subsequent deletion) by **GenProgramPipelines**, but refers to a program pipeline object that has not been previously bound, the GL first creates a new state vector in the same manner as when **BindProgramPipeline** creates a new program pipeline object.

If *pname* is `ACTIVE_PROGRAM`, the name of the active program object (used for uniform updates) of *pipeline* is returned.

If *pname* is one of the shader stage *type* arguments in table 7.1, the name of the program object current for the corresponding shader stage of *pipeline* returned.

If *pname* is `VALIDATE_STATUS`, the validation status of *pipeline*, as determined by **ValidateProgramPipeline** (see section 11.1.3.11) is returned.

If *pname* is `INFO_LOG_LENGTH`, the length of the info log for *pipeline*, including a null terminator, is returned. If there is no info log, zero is returned.

### Errors

An `INVALID_OPERATION` error is generated if *pipeline* is not a name returned from a previous call to **GenProgramPipelines** or if such a name has

since been deleted by **DeleteProgramPipelines**.

An `INVALID_ENUM` error is generated if *pname* is not `ACTIVE_PROGRAM`, `INFO_LOG_LENGTH`, `VALIDATE_STATUS`, or one of the *type* arguments in table 7.1.

The command

```
void GetAttachedShaders( uint program, sizei maxCount,
                          sizei *count, uint *shaders );
```

returns the names of shader objects attached to *program* in *shaders*. The actual number of shader names written into *shaders* is returned in *count*. If no shaders are attached, *count* is set to zero. If *count* is `NULL` then it is ignored. The maximum number of shader names that may be written into *shaders* is specified by *maxCount*. The number of objects attached to *program* is given by can be queried by calling **GetProgramiv** with `ATTACHED_SHADERS`.

### Errors

An `INVALID_VALUE` error is generated if *program* is not the name of either a program or shader object.

An `INVALID_OPERATION` error is generated if *program* is the name of a shader object.

An `INVALID_VALUE` error is generated if *maxCount* is negative.

A string that contains information about the last compilation attempt on a shader object, last link or validation attempt on a program object, or last validation attempt on a program pipeline object, called the *info log*, can be obtained with the commands

```
void GetShaderInfoLog( uint shader, sizei bufSize,
                       sizei *length, char *infoLog );
void GetProgramInfoLog( uint program, sizei bufSize,
                        sizei *length, char *infoLog );
void GetProgramPipelineInfoLog( uint pipeline,
                                 sizei bufSize, sizei *length, char *infoLog );
```

These commands return an info log string for the corresponding type of object in *infoLog*. This string will be null-terminated. The actual number of characters written into *infoLog*, excluding the null terminator, is returned in *length*. If *length* is `NULL`, then no length is returned. The maximum number of characters that may

be written into *infoLog*, including the null terminator, is specified by *bufSize*. The number of characters in the info log for a shader object, program object, or program pipeline object can be queried respectively with **GetShaderiv**, **GetProgramiv**, or **GetProgramPipelineiv** with *pname* `INFO_LOG_LENGTH`.

If *shader* is a shader object, **GetShaderInfoLog** will return either an empty string or information about the last compilation attempt for that object. If *program* is a program object, **GetProgramInfoLog** will return either an empty string or information about the last link attempt or last validation attempt (see section 11.1.3.11) for that object. If *pipeline* is a program pipeline object, **GetProgramPipelineInfoLog** will return either an empty string or information about the last validation attempt for that object.

The info log is typically only useful during application development and an application should not expect different GL implementations to produce identical info logs.

#### Errors

An `INVALID_VALUE` error is generated if *program* is not the name of either a program or shader object.

An `INVALID_OPERATION` error is generated if *program* is the name of a shader object. An `INVALID_VALUE` error is generated if *shader* is not the name of either a program or shader object.

An `INVALID_OPERATION` error is generated if *shader* is the name of a program object.

An `INVALID_VALUE` error is generated if *pipeline* is not the name of an existing program pipeline object.

An `INVALID_VALUE` error is generated if *bufSize* is negative.

The command

```
void GetShaderSource( uint shader, sizei bufSize,
                     sizei *length, char *source );
```

returns in *source* the string making up the source code for the shader object *shader*. The string *source* will be null-terminated. The actual number of characters written into *source*, excluding the null terminator, is returned in *length*. If *length* is `NULL`, no length is returned. The maximum number of characters that may be written into *source*, including the null terminator, is specified by *bufSize*. The string *source* is a concatenation of the strings passed to the GL using **ShaderSource**. The length of this concatenation is given by `SHADER_SOURCE_LENGTH`, which can be queried with **GetShaderiv**.

**Errors**

An `INVALID_VALUE` error is generated if *shader* is not the name of either a program or shader object.

An `INVALID_OPERATION` error is generated if *shader* is the name of a program object.

An `INVALID_VALUE` error is generated if *bufSize* is negative.

The command

```
void GetShaderPrecisionFormat( enum shadertype,
                               enum precisiontype, int *range, int *precision );
```

returns the range and precision for different numeric formats supported by the shader compiler. *shadertype* must be `VERTEX_SHADER` or `FRAGMENT_SHADER`. *precisiontype* must be one of `LOW_FLOAT`, `MEDIUM_FLOAT`, `HIGH_FLOAT`, `LOW_INT`, `MEDIUM_INT` or `HIGH_INT`. *range* points to an array of two integers in which encodings of the format's numeric range are returned. If *min* and *max* are the smallest and largest values representable in the format, then the values returned are defined to be

$$range[0] = \lfloor \log_2(|min|) \rfloor$$

$$range[1] = \lfloor \log_2(|max|) \rfloor$$

*precision* points to an integer in which the  $\log_2$  value of the number of bits of precision of the format is returned. If the smallest representable value greater than 1 is  $1 + \epsilon$ , then *\*precision* will contain  $\lfloor -\log_2(\epsilon) \rfloor$ , and every value in the range

$$[-2^{range[0]}, 2^{range[1]}]$$

can be represented to at least one part in  $2^{*precision}$ . For example, an IEEE single-precision floating-point format would return  $range[0] = 127$ ,  $range[1] = 127$ , and  $*precision = 23$ , while a 32-bit two's-complement integer format would return  $range[0] = 31$ ,  $range[1] = 30$ , and  $*precision = 0$ .

The minimum required precision and range for formats corresponding to the different values of *precisiontype* are described in section 4.7("Precision and Precision Qualifiers") of the OpenGL Shading Language Specification .

**Errors**



An `INVALID_ENUM` error is generated if *shadertype* is not `VERTEX_SHADER` or `FRAGMENT_SHADER`.

The commands

```
void GetUniformfv( uint program, int location,
                   float *params );
void GetUniformdv( uint program, int location,
                   double *params );
void GetUniformiv( uint program, int location,
                   int *params );
void GetUniformuiv( uint program, int location,
                    uint *params );
```

return the value or values of the uniform at location *location* of the default uniform block for program object *program* in the array *params*. The type of the uniform at *location* determines the number of values returned.

In order to query the values of an array of uniforms, a **GetUniform\*** command needs to be issued for each array element. If the uniform queried is a matrix, the values of the matrix are returned in column major order.

### Errors

An `INVALID_VALUE` error is generated if *program* is not the name of either a program or shader object.

An `INVALID_OPERATION` error is generated if *program* is the name of a shader object.

An `INVALID_OPERATION` error is generated if *program* has not been linked successfully, or if *location* is not a valid location for *program*.

The command

```
void GetUniformSubroutineuiv( enum shadertype,
                               int location, uint *params );
```

returns the value of the subroutine uniform at location *location* for shader stage *shadertype* of the current program. If *location* represents an unused location, the value `INVALID_INDEX` is returned and no error is generated.

**Errors**

An `INVALID_ENUM` error is generated if *shadertype* is not one of the values in table 7.1,

An `INVALID_VALUE` error is generated if *location* is greater than or equal to the value of `ACTIVE_SUBROUTINE_UNIFORM_LOCATIONS` for the shader currently in use at shader stage *shadertype*.

An `INVALID_OPERATION` error is generated if no program is active.

The command

```
void GetProgramStageiv( uint program, enum shadertype,
                        enum pname, int *values );
```

returns properties of the program object *program* specific to the programmable stage corresponding to *shadertype* in *values*. The parameter value to return is specified by *pname*. If *pname* is `ACTIVE_SUBROUTINE_UNIFORMS`, the number of active subroutine variables in the stage is returned. If *pname* is `ACTIVE_SUBROUTINE_UNIFORM_LOCATIONS`, the number of active subroutine variable locations in the stage is returned. If *pname* is `ACTIVE_SUBROUTINES`, the number of active subroutines in the stage is returned. If *pname* is `ACTIVE_SUBROUTINE_UNIFORM_MAX_LENGTH` or `ACTIVE_SUBROUTINE_MAX_LENGTH`, the length of the longest subroutine uniform or subroutine name, respectively, for the stage is returned. The returned name length includes space for a null terminator. If there is no shader of type *shadertype* in *program*, the values returned will be consistent with a shader with no subroutines or subroutine uniforms.

**Errors**

An `INVALID_VALUE` error is generated if *program* is not the name of either a program or shader object.

An `INVALID_OPERATION` error is generated if *program* is the name of a shader object.

An `INVALID_ENUM` error is generated if *shadertype* is not one of the values in table 7.1.

## 7.14 Required State

The GL maintains state to indicate which shader and program object names are in use. Initially, no shader or program objects exist, and no names are in use.

The state required per shader object consists of:

- An unsigned integer specifying the shader object name.
- An integer holding the value of `SHADER_TYPE`.
- A boolean holding the delete status, initially `FALSE`.
- A boolean holding the status of the last compile, initially `FALSE`.
- An array of type `char` containing the information log, initially empty.
- An integer holding the length of the information log.
- An array of type `char` containing the concatenated shader string, initially empty.
- An integer holding the length of the concatenated shader string.

The state required per program object consists of:

- An unsigned integer indicating the program object name.
- A boolean holding the delete status, initially `FALSE`.
- A boolean holding the status of the last link attempt, initially `FALSE`.
- A boolean holding the status of the last validation attempt, initially `FALSE`.
- An integer holding the number of attached shader objects.
- A list of unsigned integers to keep track of the names of the shader objects attached.
- An array of type `char` containing the information log, initially empty.
- An integer holding the length of the information log.
- An integer holding the number of active uniforms.
- For each active uniform, three integers, holding its location, size, and type, and an array of type `char` holding its name.
- An array holding the values of each active uniform.
- An integer holding the number of active attributes.
- For each active attribute, three integers holding its location, size, and type, and an array of type `char` holding its name.

- A boolean holding the hint to the retrievability of the program binary, initially `FALSE`.

Additional state required to support vertex shaders consists of:

- A bit indicating whether or not program point size mode (section 14.4.1) is enabled, initially disabled.

Additional state required to support transform feedback consists of:

- An integer holding the transform feedback mode, initially `INTERLEAVED_ATTRIBUTES`.
- An integer holding the number of outputs to be captured, initially zero.
- An integer holding the length of the longest output name being captured, initially zero.
- For each output being captured, two integers holding its size and type, and an array of type `char` holding its name.

Additionally, one unsigned integer is required to hold the name of the current program object, if any.

This list of program object state is not complete. Tables 23.32-23.42 describe additional program object state specific to program binaries, geometry shaders, tessellation control and evaluation shaders, shader subroutines, and uniform blocks.

Table 23.43 describes state related to vertex and geometry shaders that is not program object state.

## Chapter 8

# Textures and Samplers

Texturing maps a portion of one or more specified images onto a fragment or vertex. This mapping is accomplished in shaders by *sampling* the color of an image at the location indicated by specified  $(s, t, r)$  *texture coordinates*. Texture lookups are typically used to modify a fragment's RGBA color but may be used for any purpose in a shader.

This chapter first describes how pixel rectangles, texture images, and texture and sampler object parameters are specified and queried, in sections 8.1-8.11. The remainder of the chapter in sections 8.12-8.25 describe how texture sampling is performed in shaders.

The internal data type of a texture may be signed or unsigned normalized fixed-point, signed or unsigned integer, or floating-point, depending on the internal format of the texture. The correspondence between the internal format and the internal data type is given in tables 8.12-8.13. Fixed-point and floating-point textures return a floating-point value and integer textures return signed or unsigned integer values. The fragment shader is responsible for interpreting the result of a texture lookup as the correct data type, otherwise the result is undefined.

Each of the supported types of texture is a collection of images built from one-, two-, or three-dimensional arrays of image elements referred to as *texels*. One-, two-, and three-dimensional textures consist respectively of one-, two-, or three-dimensional texel arrays. One- and two-dimensional array textures are arrays of one- or two-dimensional images, consisting of one or more *layers*. Two-dimensional multisample and two-dimensional multisample array textures are special two-dimensional and two-dimensional array textures, respectively, containing multiple samples in each texel. Cube maps are special two-dimensional array textures with six layers that represent the faces of a cube. When accessing a cube map, the texture coordinates are projected onto one of the six faces of the cube. A cube

map array is a collection of cube map layers stored as a two-dimensional array texture. When accessing a cube map array, the texture coordinate  $s$ ,  $t$ , and  $r$  are applied similarly as cube maps while the last texture coordinate  $q$  is used as the index of one of the cube map slices. Rectangle textures are special two-dimensional textures consisting of only a single image and accessed using unnormalized coordinates. Buffer textures are special one-dimensional textures whose texel arrays are stored in separate buffer objects.

Implementations must support texturing using multiple images.

The following subsections (up to and including section 8.14) specify the GL operation with a single texture. Multiple texture images may be sampled and combined by shaders as described in section 11.1.3.5.

The coordinates used for texturing in a fragment shader are defined by the OpenGL Shading Language Specification .

The command

```
void ActiveTexture( enum texture );
```

specifies the *active texture unit selector*. The selector may be queried by calling **GetIntegerv** with *pname* set to `ACTIVE_TEXTURE`.

Each texture image unit consists of all the texture state defined in chapter 8.

The active texture unit selector selects the texture image unit accessed by commands involving texture image processing. Such commands include **TexParameter**, **TexImage**, **BindTexture**, and queries of all such state.

### Errors

An `INVALID_ENUM` error is generated if an invalid *texture* is specified. *texture* is a symbolic constant of the form `TEXTUREi`, indicating that texture unit  $i$  is to be modified. The constants obey `TEXTUREi = TEXTURE0 +  $i$`  where  $i$  is in the range 0 to  $k - 1$ , and  $k$  is the value of `MAX_COMBINED_TEXTURE_IMAGE_UNITS`.

The state required for the active texture image unit selector is a single integer. The initial value is `TEXTURE0`.

## 8.1 Texture Objects

Textures in GL are represented by named objects. The name space for texture objects is the unsigned integers, with zero reserved by the GL to represent the default texture object. The default texture object is bound to each of the

TEXTURE\_1D, TEXTURE\_2D, TEXTURE\_3D, TEXTURE\_1D\_ARRAY, TEXTURE\_2D\_ARRAY, TEXTURE\_RECTANGLE, TEXTURE\_BUFFER, TEXTURE\_CUBE\_MAP, TEXTURE\_CUBE\_MAP\_ARRAY, TEXTURE\_2D\_MULTISAMPLE, and TEXTURE\_2D\_MULTISAMPLE\_ARRAY targets during context initialization.

A new texture object is created by binding an unused name to one of these texture targets. The command

```
void GenTextures( sizei n, uint *textures );;
```

returns *n* previously unused texture names in *textures*. These names are marked as used, for the purposes of **GenTextures** only, but they acquire texture state and a dimensionality only when they are first bound, just as if they were unused.

#### Errors

An `INVALID_VALUE` error is generated if *n* is negative.

The binding is effected by calling

```
void BindTexture( enum target, uint texture );
```

with *target* set to the desired texture target and *texture* set to the unused name. The resulting texture object is a new state vector, comprising all the state and with the same initial values listed in section 8.21 The new texture object bound to *target* is, and remains a texture of the dimensionality and type specified by *target* until it is deleted.

**BindTexture** may also be used to bind an existing texture object to any of these targets. If the bind is successful no change is made to the state of the bound texture object, and any previous binding to *target* is broken.

While a texture object is bound, GL operations on the target to which it is bound affect the bound object, and queries of the target to which it is bound return state from the bound object. If texture mapping of the dimensionality of the target to which a texture object is bound is enabled, the state of the bound texture object directs the texturing operation.

#### Errors

An `INVALID_ENUM` error is generated if *target* is not one of the texture targets described in the introduction to section 8.1.

An `INVALID_OPERATION` error is generated if an attempt is made to bind a texture object of different dimensionality than the specified *target*.

An `INVALID_OPERATION` error is generated if *texture* is not zero or a

name returned from a previous call to **GenTextures**, or if such a name has since been deleted.

Texture objects are deleted by calling

```
void DeleteTextures(size_t n, const uint *textures);
```

*textures* contains *n* names of texture objects to be deleted. After a texture object is deleted, it has no contents or dimensionality, and its name is again unused. If a texture that is currently bound to any of the target bindings of **BindTexture** is deleted, it is as though **BindTexture** had been executed with the same target and texture zero. Additionally, special care must be taken when deleting a texture if any of the images of the texture are attached to a framebuffer object. See section 9.2.8 for details.

Unused names in *textures* that have been marked as used for the purposes of **GenTextures** are marked as unused again. Unused names in *textures* are silently ignored, as is the name zero.

### Errors

An `INVALID_VALUE` error is generated if *n* is negative.

The command

```
boolean IsTexture(uint texture);
```

returns `TRUE` if *texture* is the name of a texture object. If *texture* is zero, or is a non-zero value that is not the name of a texture object, or if an error condition occurs, **IsTexture** returns `FALSE`.

The texture object name space, including the initial one-, two-, and three-dimensional, one- and two-dimensional array, rectangle, buffer, cube map, cube map array, two-dimensional multisample, and two-dimensional multisample array texture objects, is shared among all texture units. A texture object may be bound to more than one texture unit simultaneously. After a texture object is bound, any GL operations on that target object affect any other texture units to which the same texture object is bound.

Texture binding is affected by the setting of the state `ACTIVE_TEXTURE`. If a texture object is deleted, it as if all texture units which are bound to that texture object are rebound to texture object zero.



## 8.2 Sampler Objects

The state necessary for texturing can be divided into two categories as described in section 8.21. A GL texture object includes both categories. The first category represents dimensionality and other image parameters, and the second category represents sampling state. Additionally, a sampler object may be created to encapsulate only the second category - the sampling state - of a texture object.

A new sampler object is created by binding an unused name to a texture unit. The command

```
void GenSamplers( sizei count, uint *samplers );
```

returns *count* previously unused sampler object names in *samplers*. The name zero is reserved by the GL to represent no sampler being bound to a sampler unit. The names are marked as used, for the purposes of **GenSamplers** only, but they acquire state only when they are first used as a parameter to **BindSampler**, **SamplerParameter\***, **GetSamplerParameter\***, or **IsSampler**. When a sampler object is first used in one of these functions, the resulting sampler object is initialized with a new state vector, comprising all the state and with the same initial values listed in table 23.18.

### Errors

An `INVALID_VALUE` error is generated if *count* is negative.

When a sampler object is bound to a texture unit, its state supersedes that of the texture object bound to that texture unit. If the sampler name zero is bound to a texture unit, the currently bound texture's sampler state becomes active. A single sampler object may be bound to multiple texture units simultaneously.

A sampler object binding is effected with the command

```
void BindSampler( uint unit, uint sampler );
```

with *unit* set to the zero-based index of the texture unit to which to bind the sampler and *sampler* set to the name of a sampler object returned from a previous call to **GenSamplers**.

If the bind is successful no change is made to the state of the bound sampler object, and any previous binding to *unit* is broken.

If state is present in a sampler object bound to a texture unit that would have been rejected by a call to **TexParameter\*** for the texture bound to that unit, the behavior of the implementation is as if the texture were incomplete. For example, if

TEXTURE\_WRAP\_S or TEXTURE\_WRAP\_T is set to REPEAT or MIRRORED\_REPEAT on the sampler object bound to a texture unit and the texture bound to that unit is a rectangle texture, the texture will be considered incomplete.

Sampler object state which does not affect sampling for the type of texture bound to a texture unit, such as TEXTURE\_WRAP\_R for a rectangle texture, does not affect completeness.

The currently bound sampler may be queried by calling **GetIntegerv** with *pname* set to SAMPLER\_BINDING. When a sampler object is unbound from the texture unit (by binding another sampler object, or the sampler object named zero, to that texture unit) the modified state is again replaced with the sampler state associated with the texture object bound to that texture unit.

### Errors

An INVALID\_VALUE error is generated if *unit* is greater than or equal to the value of MAX\_COMBINED\_TEXTURE\_IMAGE\_UNITS.

An INVALID\_OPERATION error is generated if *sampler* is not zero or a name returned from a previous call to **GenSamplers**, or if such a name has since been deleted with **DeleteSamplers**.

The parameters represented by a sampler object are a subset of those described in section 8.10. Each parameter of a sampler object is set by calling

```
void SamplerParameter{if}( uint sampler, enum pname,
    T param );
void SamplerParameter{if}v( uint sampler, enum pname,
    const T *param );
void SamplerParameterI{i ui}v( uint sampler, enum pname,
    const T *params );
```

*sampler* is the name of a sampler object previously reserved by a call to **GenSamplers**. *pname* is the name of a parameter to modify and *param* is the new value of that parameter. *pname* must be one of the sampler state names in table 23.18.

Texture state listed in tables 23.16- 23.17 but not listed here and in the sampler state in table 23.18 is not part of the sampler state, and remains in the texture object.

Data conversions are performed as specified in section 2.2.1, except that if the values for TEXTURE\_BORDER\_COLOR are specified with a call to **SamplerParameterIiv** or **SamplerParameterIuiv**, the values are unmodified and stored with an internal data type of integer. If specified with **SamplerParameteriv**, they are converted to floating-point using equation 2.1. Otherwise, border color values are unmodified and stored as floating-point.

Modifying a parameter of a sampler object affects all texture units to which that sampler object is bound. Calling **TexParameter** has no effect on the sampler object bound to the active texture unit. It will modify the parameters of the texture object bound to that unit.

### Errors

An `INVALID_OPERATION` error is generated if *sampler* is not the name of a sampler object previously returned from a call to **GenSamplers**.

An `INVALID_ENUM` error is generated if *pname* is not one of the sampler state names in table 23.18.

If the value of *param* is not an acceptable value for the parameter specified in *pname*, an error is generated as specified in the description of **TexParameter\***.

Sampler objects are deleted by calling

```
void DeleteSamplers(sizei count, const uint *samplers);
```

*samplers* contains *count* names of sampler objects to be deleted. After a sampler object is deleted, its name is again unused. If a sampler object that is currently bound to a sampler unit is deleted, it is as though **BindSampler** is called with *unit* set to the unit the sampler is bound to and *sampler* zero. Unused names in *samplers* that have been marked as used for the purposes of **GenSamplers** are marked as unused again. Unused names in *samplers* are silently ignored, as is the reserved name zero.

### Errors

An `INVALID_VALUE` error is generated if *count* is negative.

The command

```
boolean IsSampler(uint sampler);
```

may be called to determine whether *sampler* is the name of a sampler object. **IsSampler** will return `TRUE` if *sampler* is the name of a sampler object previously returned from a call to **GenSamplers** and `FALSE` otherwise. Zero is not the name of a sampler object.

### 8.3 Sampler Object Queries

The current values of the parameters of a sampler object may be queried by calling

```
void GetSamplerParameter{if}v( uint sampler,
    enum pname, T *params );
void GetSamplerParameterI{i ui}v( uint sampler,
    enum pname, T *params );
```

*sampler* is the name of the sampler object from which to retrieve parameters. *pname* is the name of the parameter to be queried, and must be one of the sampler state names in table 23.18. *params* is the address of an array into which the current value of the parameter will be placed.

Querying `TEXTURE_BORDER_COLOR` with **GetSamplerParameterIiv** or **GetSamplerParameterIuiv** returns the border color values as signed integers or unsigned integers, respectively; otherwise the values are returned as described in section 2.2.2. If the border color is queried with a type that does not match the original type with which it was specified, the result is undefined.

#### Errors

An `INVALID_OPERATION` error is generated if *sampler* is not the name of a sampler object previously returned from a call to **GenSamplers**.

An `INVALID_ENUM` error is generated if *pname* is not one of the sampler state names in table 23.18.

### 8.4 Pixel Rectangles

Rectangles of color, depth, and certain other values may be specified to the GL using **TexImage\*D** (see section 8.5). Some of the parameters and operations governing the operation of these commands are shared by **ReadPixels** (used to obtain pixel values from the framebuffer); the discussion of **ReadPixels**, however, is deferred until chapter 9 after the framebuffer has been discussed in detail. Nevertheless, we note in this section when parameters and state pertaining to these commands also pertain to **ReadPixels**.

A number of parameters control the encoding of pixels in buffer object or client memory (for reading and writing) and how pixels are processed before being placed in or after being read from the framebuffer (for reading, writing, and copying). These parameters are set with **PixelStore**.

Parameter Name	Type	Initial Value	Valid Range
UNPACK_SWAP_BYTES	boolean	FALSE	TRUE/FALSE
UNPACK_LSB_FIRST	boolean	FALSE	TRUE/FALSE
UNPACK_ROW_LENGTH	integer	0	[0, ∞)
UNPACK_SKIP_ROWS	integer	0	[0, ∞)
UNPACK_SKIP_PIXELS	integer	0	[0, ∞)
UNPACK_ALIGNMENT	integer	4	1,2,4,8
UNPACK_IMAGE_HEIGHT	integer	0	[0, ∞)
UNPACK_SKIP_IMAGES	integer	0	[0, ∞)
UNPACK_COMPRESSED_BLOCK_WIDTH	integer	0	[0, ∞)
UNPACK_COMPRESSED_BLOCK_HEIGHT	integer	0	[0, ∞)
UNPACK_COMPRESSED_BLOCK_DEPTH	integer	0	[0, ∞)
UNPACK_COMPRESSED_BLOCK_SIZE	integer	0	[0, ∞)

Table 8.1: **PixelStore** parameters pertaining to one or more of **TexImage\*D**, **TexSubImage\*D**, **CompressedTexImage\*D** and **CompressedTexSubImage\*D**.

#### 8.4.1 Pixel Storage Modes and Pixel Buffer Objects

Pixel storage modes affect the operation of **TexImage\*D**, **TexSubImage\*D**, **CompressedTexImage\*D**, **CompressedTexSubImage\*D**, and **ReadPixels** when one of these commands is issued. Pixel storage modes are set with

```
void PixelStore{if}( enum pname, T param );
```

*pname* is a symbolic constant indicating a parameter to be set, and *param* is the value to set it to. Table 8.1 summarizes the pixel storage parameters, their types, their initial values, and their allowable ranges.

#### Errors

An `INVALID_ENUM` error is generated if *pname* is not one of the parameter names in table 8.1.

An `INVALID_VALUE` error is generated if *param* is outside the given range for *pname* in table 8.1.

Data conversions are performed as specified in section 2.2.1.

In addition to storing pixel data in client memory, pixel data may also be stored in buffer objects (described in section 6). The current pixel unpack and

pack buffer objects are designated by the `PIXEL_UNPACK_BUFFER` and `PIXEL_UNPACK_BUFFER` targets respectively.

Initially, zero is bound for the `PIXEL_UNPACK_BUFFER`, indicating that image specification commands such as **TexImage\**D*** source their pixels from client memory pointer parameters. However, if a non-zero buffer object is bound as the current pixel unpack buffer, then the pointer parameter is treated as an offset into the designated buffer object.

#### 8.4.2 The Imaging Subset

This subsection is only defined in the compatibility profile.

#### 8.4.3 Pixel Transfer Modes

This subsection is only defined in the compatibility profile.

#### 8.4.4 Transfer of Pixel Rectangles

The process of transferring pixels encoded in buffer object or client memory is diagrammed in figure 8.1. We describe the stages of this process in the order in which they occur.

Commands accepting or returning pixel rectangles take the following arguments (as well as additional arguments specific to their function):

*format* is a symbolic constant indicating what the values in memory represent.

*width* and *height* are the width and height, respectively, of the pixel rectangle to be transferred.

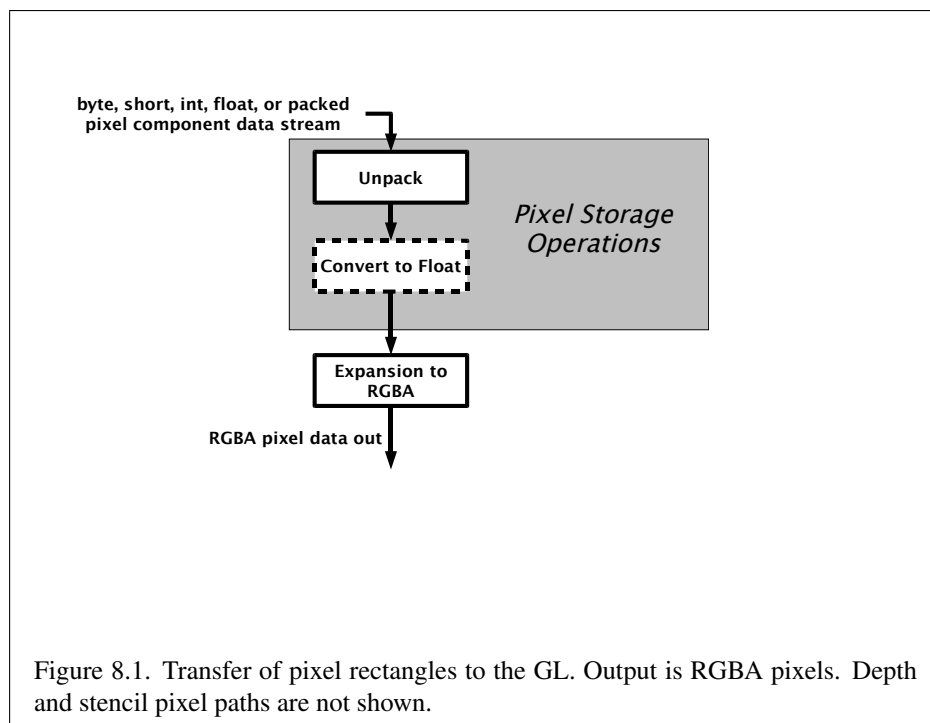
*data* refers to the data to be drawn. These data are represented with one of several GL data types, specified by *type*. The correspondence between the *type* token values and the GL data types they indicate is given in table 8.2.

Not all combinations of *format* and *type* are valid.

An `INVALID_ENUM` error is generated if *format* is `DEPTH_STENCIL` and *type* is not `UNSIGNED_INT_24_8` or `FLOAT_32_UNSIGNED_INT_24_8_REV`.

An `INVALID_ENUM` error is generated if *format* is one of the `INTEGER` component formats defined in table 8.3 and *type* is one of the floating-point types defined in table 8.2.

Some additional constraints on the combinations of *format* and *type* values that are accepted are discussed below. Additional restrictions may be imposed by specific commands.



<i>type</i> Parameter Token Name	Corresponding GL Data Type	Special Interpretation	Floating Point
UNSIGNED_BYTE	ubyte	No	No
BYTE	byte	No	No
UNSIGNED_SHORT	ushort	No	No
SHORT	short	No	No
UNSIGNED_INT	uint	No	No
INT	int	No	No
HALF_FLOAT	half	No	Yes
FLOAT	float	No	Yes
UNSIGNED_BYTE_3_3_2	ubyte	Yes	No
UNSIGNED_BYTE_2_3_3_REV	ubyte	Yes	No
UNSIGNED_SHORT_5_6_5	ushort	Yes	No
UNSIGNED_SHORT_5_6_5_REV	ushort	Yes	No
UNSIGNED_SHORT_4_4_4_4	ushort	Yes	No
UNSIGNED_SHORT_4_4_4_4_REV	ushort	Yes	No
UNSIGNED_SHORT_5_5_5_1	ushort	Yes	No
UNSIGNED_SHORT_1_5_5_5_REV	ushort	Yes	No
UNSIGNED_INT_8_8_8_8	uint	Yes	No
UNSIGNED_INT_8_8_8_8_REV	uint	Yes	No
UNSIGNED_INT_10_10_10_2	uint	Yes	No
UNSIGNED_INT_2_10_10_10_REV	uint	Yes	No
UNSIGNED_INT_24_8	uint	Yes	No
UNSIGNED_INT_10F_11F_11F_REV	uint	Yes	Yes
UNSIGNED_INT_5_9_9_9_REV	uint	Yes	Yes
FLOAT_32_UNSIGNED_INT_24_8_REV	n/a	Yes	No

Table 8.2: Pixel data *type* parameter values and the corresponding GL data types. Refer to table 2.2 for definitions of GL data types. Special interpretations are described near the end of section 8.2. Floating-point types are incompatible with INTEGER formats as described above.



Format Name	Element Meaning and Order	Target Buffer
STENCIL_INDEX	Stencil Index	Stencil
DEPTH_COMPONENT	Depth	Depth
DEPTH_STENCIL	Depth and Stencil Index	Depth and Stencil
RED	R	Color
GREEN	G	Color
BLUE	B	Color
RG	R, G	Color
RGB	R, G, B	Color
RGBA	R, G, B, A	Color
BGR	B, G, R	Color
BGRA	B, G, R, A	Color
RED_INTEGER	iR	Color
GREEN_INTEGER	iG	Color
BLUE_INTEGER	iB	Color
RG_INTEGER	iR, iG	Color
RGB_INTEGER	iR, iG, iB	Color
RGBA_INTEGER	iR, iG, iB, iA	Color
BGR_INTEGER	iB, iG, iR	Color
BGRA_INTEGER	iB, iG, iR, iA	Color

Table 8.3: Pixel data formats. The second column gives a description of and the number and order of elements in a group. Unless specified as an index, formats yield components. Components are floating-point unless prefixed with the letter 'i', which indicates they are integer.

#### 8.4.4.1 Unpacking

Data are taken from the currently bound pixel unpack buffer or client memory as a sequence of signed or unsigned bytes (GL data types `byte` and `ubyte`), signed or unsigned short integers (GL data types `short` and `ushort`), signed or unsigned integers (GL data types `int` and `uint`), or floating-point values (GL data types `half` and `float`). These elements are grouped into sets of one, two, three, or four values, depending on the *format*, to form a group. Table 8.3 summarizes the format of groups obtained from memory; it also indicates those formats that yield indices and those that yield floating-point or integer components.

If a pixel unpack buffer is bound (as indicated by a non-zero value of `PIXEL_UNPACK_BUFFER_BINDING`), *data* is an offset into the pixel unpack buffer and

Element Size	Default Bit Ordering	Modified Bit Ordering
8 bit	[7..0]	[7..0]
16 bit	[15..0]	[7..0][15..8]
32 bit	[31..0]	[7..0][15..8][23..16][31..24]

Table 8.4: Bit ordering modification of elements when `UNPACK_SWAP_BYTES` is enabled. These reorderings are defined only when GL data type `ubyte` has 8 bits, and then only for GL data types with 8, 16, or 32 bits. Bit 0 is the least significant.

the pixels are unpacked from the buffer relative to this offset; otherwise, *data* is a pointer to client memory and the pixels are unpacked from client memory relative to the pointer.

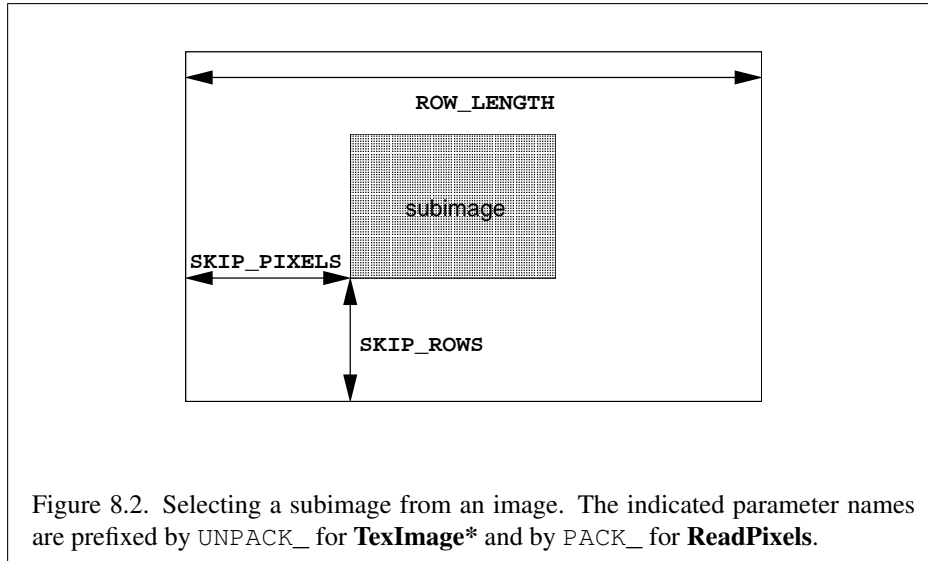
### Errors

An `INVALID_OPERATION` error is generated if a pixel unpack buffer object is bound and unpacking the pixel data according to the process described below would access memory beyond the size of the pixel unpack buffer's memory size.

An `INVALID_OPERATION` error is generated if a pixel unpack buffer object is bound and *data* is not evenly divisible by the number of basic machine units needed to store in memory the corresponding GL data type from table 8.2 for the *type* parameter (or not evenly divisible by 4 for *type* `FLOAT_32_UNUNSIGNED_INT_24_8_REV`, which does not have a corresponding GL data type).

By default the values of each GL data type are interpreted as they would be specified in the language of the client's GL binding. If `UNPACK_SWAP_BYTES` is enabled, however, then the values are interpreted with the bit orderings modified as per table 8.4. The modified bit orderings are defined only if the GL data type `ubyte` has eight bits, and then for each specific GL data type only if that type is represented with 8, 16, or 32 bits.

The groups in memory are treated as being arranged in a rectangle. This rectangle consists of a series of *rows*, with the first element of the first group of the first row pointed to by *data*. If the value of `UNPACK_ROW_LENGTH` is not positive, then the number of groups in a row is *width*; otherwise the number of groups is `UNPACK_ROW_LENGTH`. If *p* indicates the location in memory of the first element



of the first row, then the first element of the  $N$ th row is indicated by

$$p + Nk \quad (8.1)$$

where  $N$  is the row number (counting from zero) and  $k$  is defined as

$$k = \begin{cases} nl & s \geq a, \\ \frac{a}{s} \lceil \frac{snl}{a} \rceil & s < a \end{cases} \quad (8.2)$$

where  $n$  is the number of elements in a group,  $l$  is the number of groups in the row,  $a$  is the value of UNPACK\_ALIGNMENT, and  $s$  is the size, in units of GL ubytes, of an element. If the number of bits per element is not 1, 2, 4, or 8 times the number of bits in a GL ubyte, then  $k = nl$  for all values of  $a$ .

There is a mechanism for selecting a sub-rectangle of groups from a larger containing rectangle. This mechanism relies on three integer parameters: UNPACK\_ROW\_LENGTH, UNPACK\_SKIP\_ROWS, and UNPACK\_SKIP\_PIXELS. Before obtaining the first group from memory, the *data* pointer is advanced by  $(\text{UNPACK\_SKIP\_PIXELS})n + (\text{UNPACK\_SKIP\_ROWS})k$  elements. Then *width* groups are obtained from contiguous elements in memory (without advancing the pointer), after which the pointer is advanced by  $k$  elements. *height* sets of *width* groups of values are obtained this way. See figure 8.2.

### Special Interpretations

A *type* matching one of the types in table 8.5 is a special case in which all the components of each group are packed into a single unsigned byte, unsigned short, or unsigned int, depending on the type. If *type* is `FLOAT_32_UNSIGNED_INT_24_8_REV`, the components of each group are contained within two 32-bit words; the first word contains the float component, and the second word contains a packed 24-bit unused field, followed by an 8-bit component. The number of components per packed pixel is fixed by the type, and must match the number of components per group indicated by the *format* parameter, as listed in table 8.5.

An `INVALID_OPERATION` error is generated by any command processing pixel rectangles if a mismatch occurs.

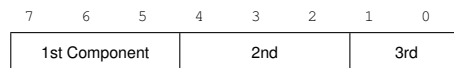
Bitfield locations of the first, second, third, and fourth components of each packed pixel type are illustrated in tables 8.6- 8.9. Each bitfield is interpreted as an unsigned integer value.

Components are normally packed with the first component in the most significant bits of the bitfield, and successive component occupying progressively less significant locations. Types whose token names end with `_REV` reverse the component packing order from least to most significant locations. In all cases, the most significant bit of each component is packed in the most significant bit location of its location in the bitfield.

<i>type</i> Parameter Token Name	GL Data Type	Number of Components	Matching Pixel Formats
UNSIGNED_BYTE_3_3_2	ubyte	3	RGB, RGB_INTEGER
UNSIGNED_BYTE_2_3_3_REV	ubyte	3	RGB, RGB_INTEGER
UNSIGNED_SHORT_5_6_5	ushort	3	RGB, RGB_INTEGER
UNSIGNED_SHORT_5_6_5_REV	ushort	3	RGB, RGB_INTEGER
UNSIGNED_SHORT_4_4_4_4	ushort	4	RGBA, BGRA, RGBA_ INTEGER, BGRA_ INTEGER
UNSIGNED_SHORT_4_4_4_4_REV	ushort	4	RGBA, BGRA, RGBA_ INTEGER, BGRA_ INTEGER
UNSIGNED_SHORT_5_5_5_1	ushort	4	RGBA, BGRA, RGBA_ INTEGER, BGRA_ INTEGER
UNSIGNED_SHORT_1_5_5_5_REV	ushort	4	RGBA, BGRA, RGBA_ INTEGER, BGRA_ INTEGER
UNSIGNED_INT_8_8_8_8	uint	4	RGBA, BGRA, RGBA_ INTEGER, BGRA_ INTEGER
UNSIGNED_INT_8_8_8_8_REV	uint	4	RGBA, BGRA, RGBA_ INTEGER, BGRA_ INTEGER
UNSIGNED_INT_10_10_10_2	uint	4	RGBA, BGRA, RGBA_ INTEGER, BGRA_ INTEGER
UNSIGNED_INT_2_10_10_10_REV	uint	4	RGBA, BGRA, RGBA_ INTEGER, BGRA_ INTEGER
UNSIGNED_INT_24_8	uint	2	DEPTH_STENCIL
UNSIGNED_INT_10F_11F_11F_REV	uint	3	RGB
UNSIGNED_INT_5_9_9_9_REV	uint	4	RGB
FLOAT_32_UNSIGNED_INT_24_8_REV	n/a	2	DEPTH_STENCIL

Table 8.5: Packed pixel formats.

UNSIGNED\_BYTE\_3\_3\_2:



UNSIGNED\_BYTE\_2\_3\_3\_REV:

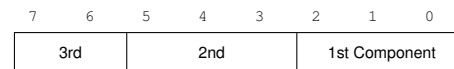
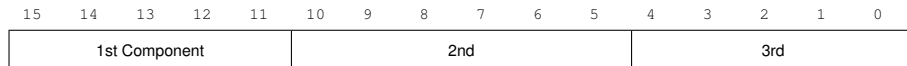
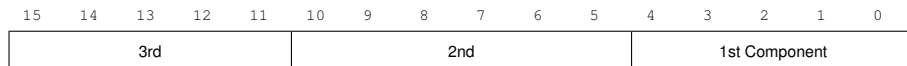


Table 8.6: UNSIGNED\_BYTE formats. Bit numbers are indicated for each component.

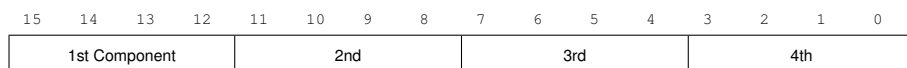
UNSIGNED\_SHORT\_5\_6\_5:



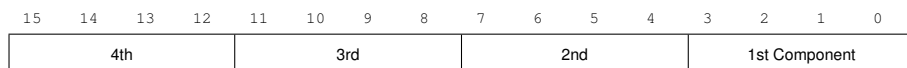
UNSIGNED\_SHORT\_5\_6\_5\_REV:



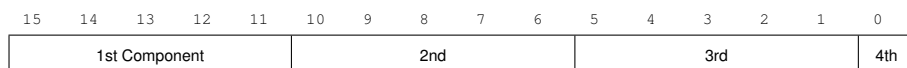
UNSIGNED\_SHORT\_4\_4\_4\_4:



UNSIGNED\_SHORT\_4\_4\_4\_4\_REV:



UNSIGNED\_SHORT\_5\_5\_5\_1:



UNSIGNED\_SHORT\_1\_5\_5\_5\_REV:

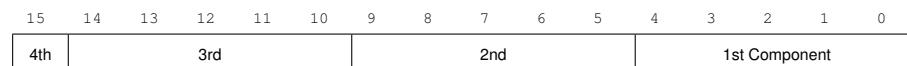


Table 8.7: UNSIGNED\_SHORT formats

UNSIGNED\_INT\_8\_8\_8\_8:

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
1st Component								2nd								3rd								4th							

UNSIGNED\_INT\_8\_8\_8\_8\_REV:

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
4th								3rd								2nd								1st Component							

UNSIGNED\_INT\_10\_10\_10\_2:

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
1st Component										2nd										3rd						4th					

UNSIGNED\_INT\_2\_10\_10\_10\_REV:

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
4th				3rd										2nd						1st Component											

UNSIGNED\_INT\_24\_8:

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
1st Component																								2nd							

UNSIGNED\_INT\_10F\_11F\_11F\_REV:

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
3rd										2nd										1st Component											

UNSIGNED\_INT\_5\_9\_9\_9\_REV:

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
4th				3rd								2nd								1st Component											

Table 8.8: UNSIGNED\_INT formats



FLOAT\_32\_UNSIGNED\_INT\_24\_8\_REV:

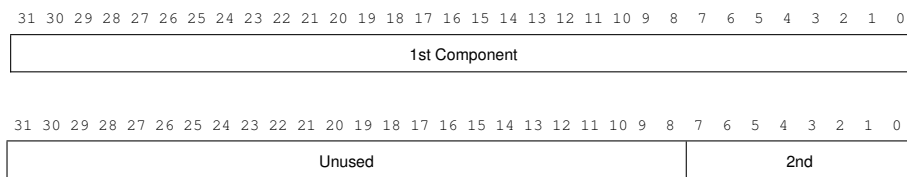


Table 8.9: FLOAT\_UNSIGNED\_INT formats

Format	First Component	Second Component	Third Component	Fourth Component
RGB	red	green	blue	
RGBA	red	green	blue	alpha
BGRA	blue	green	red	alpha
DEPTH_STENCIL	depth	stencil		

Table 8.10: Packed pixel field assignments.

The assignment of component to fields in the packed pixel is as described in table 8.10.

Byte swapping, if enabled, is performed before the components are extracted from each pixel. The above discussions of row length and image extraction are valid for packed pixels, if “group” is substituted for “component” and the number of components per group is understood to be one.

A *type* of `UNSIGNED_INT_10F_11F_11F_REV` and *format* of `RGB` is a special case in which the data are a series of `GL uint` values. Each `uint` value specifies 3 packed components as shown in table 8.8. The 1st, 2nd, and 3rd components are called  $f_{red}$  (11 bits),  $f_{green}$  (11 bits), and  $f_{blue}$  (10 bits) respectively.

$f_{red}$  and  $f_{green}$  are treated as unsigned 11-bit floating-point values and converted to floating-point red and green components respectively as described in section 2.3.3.  $f_{blue}$  is treated as an unsigned 10-bit floating-point value and converted to a floating-point blue component as described in section 2.3.3.

A *type* of `UNSIGNED_INT_5_9_9_9_REV` and *format* of `RGB` is a special case in which the data are a series of `GL uint` values. Each `uint` value specifies 4 packed components as shown in table 8.8. The 1st, 2nd, 3rd, and 4th components are called  $p_{red}$ ,  $p_{green}$ ,  $p_{blue}$ , and  $p_{exp}$  respectively and are treated as unsigned integers. These are then used to compute floating-point `RGB` components (ignoring the “Conversion to floating-point” section below in this case) as follows:

$$\begin{aligned} red &= p_{red}2^{p_{exp}-B-N} \\ green &= p_{green}2^{p_{exp}-B-N} \\ blue &= p_{blue}2^{p_{exp}-B-N} \end{aligned}$$

where  $B = 15$  (the exponent bias) and  $N = 9$  (the number of mantissa bits).

#### 8.4.4.2 Conversion to floating-point

This step applies only to groups of floating-point components. It is not performed on indices or integer components. For groups containing both components and indices, such as `DEPTH_STENCIL`, the indices are not converted.

Each element in a group is converted to a floating-point value. For unsigned or signed integer elements, equations 2.1 or 2.2, respectively, are used.

#### 8.4.4.3 Final Expansion to RGBA

This step is performed only for non-depth component groups. Each group is converted to a group of 4 elements as follows: if a group does not contain an A element, then A is added and set to 1 for integer components or 1.0 for floating-point components. If any of R, G, or B is missing from the group, each missing element is added and assigned a value of 0 for integer components or 0.0 for floating-point components.

#### 8.4.5 Pixel Transfer Operations

[This subsection is only defined in the compatibility profile.](#)

### 8.5 Texture Image Specification

The command

```
void TexImage3D( enum target, int level, int internalformat,  
                sizei width, sizei height, sizei depth, int border,  
                enum format, enum type, const void *data );
```

is used to specify a three-dimensional texture image. *target* must be one of `TEXTURE_3D` for a three-dimensional texture, `TEXTURE_2D_ARRAY` for a two-dimensional array texture, or `TEXTURE_CUBE_MAP_ARRAY` for a cube map array texture. Additionally, *target* may be either `PROXY_TEXTURE_3D` for a three-dimensional proxy texture, `PROXY_TEXTURE_2D_ARRAY` for a two-dimensional proxy array texture, or `PROXY_TEXTURE_CUBE_MAP_ARRAY` for a cube map array texture, as discussed in section 8.21. *format*, *type*, and *data* specify the format of the image data, the type of those data, and a reference to the image data in the currently bound pixel unpack buffer or client memory, as described in section 8.4.4. The *format* `STENCIL_INDEX` is not allowed.

The groups in memory are treated as being arranged in a sequence of adjacent rectangles. Each rectangle is a two-dimensional image, whose size and organization are specified by the *width* and *height* parameters to **TexImage3D**. The values of `UNPACK_ROW_LENGTH` and `UNPACK_ALIGNMENT` control the row-to-row spacing in these images as described in section 8.4.4. If the value of the integer parameter `UNPACK_IMAGE_HEIGHT` is not positive, then the number of rows in each two-dimensional image is *height*; otherwise the number of rows is `UNPACK_IMAGE_HEIGHT`. Each two-dimensional image comprises an integral number of rows, and is exactly adjacent to its neighbor images.

The mechanism for selecting a sub-volume of a three-dimensional image relies on the integer parameter `UNPACK_SKIP_IMAGES`. If `UNPACK_SKIP_IMAGES` is positive, the pointer is advanced by `UNPACK_SKIP_IMAGES` times the number of elements in one two-dimensional image before obtaining the first group from memory. Then *depth* two-dimensional images are processed, each having a subimage extracted as described in section 8.4.4.

The selected groups are transferred to the GL as described in section 8.4.4 and then clamped to the representable range of the internal format. If the *internalformat* of the texture is signed or unsigned integer, components are clamped to  $[-2^{n-1}, 2^{n-1} - 1]$  or  $[0, 2^n - 1]$ , respectively, where  $n$  is the number of bits per component. For color component groups, if the *internalformat* of the texture is signed or unsigned normalized fixed-point, components are clamped to  $[-1, 1]$  or  $[0, 1]$ , respectively. For depth component groups, the depth value is clamped to  $[0, 1]$ . Otherwise, values are not modified. Stencil index values are masked by  $2^n - 1$ , where  $n$  is the number of stencil bits in the internal format resolution (see below). If the base internal format is `DEPTH_STENCIL` and *format* is not `DEPTH_STENCIL`, then the values of the stencil index texture components are undefined.

Components are then selected from the resulting R, G, B, A, depth, or stencil values to obtain a texture with the *base internal format* specified by (or derived from) *internalformat*. Table 8.11 summarizes the mapping of R, G, B, A, depth, or stencil values to texture components, as a function of the base internal format of the texture image. *internalformat* may be specified as one of the internal format symbolic constants listed in table 8.11, as one of the *sized internal format* symbolic constants listed in tables 8.12- 8.13, as one of the generic compressed internal format symbolic constants listed in table 8.14, or as one of the specific compressed internal format symbolic constants (if listed in table 8.14).

An `INVALID_VALUE` error is generated if *internalformat* is not one of the above values.

Textures with a base internal format of `DEPTH_COMPONENT` or `DEPTH_STENCIL` are supported by texture image specification commands only if *target* is `TEXTURE_1D`, `TEXTURE_2D`, `TEXTURE_1D_ARRAY`, `TEXTURE_2D_`

Base Internal Format	RGBA, Depth, and Stencil Values	Internal Components
DEPTH_COMPONENT	Depth	$D$
DEPTH_STENCIL	Depth,Stencil	$D,S$
RED	R	$R$
RG	R,G	$R,G$
RGB	R,G,B	$R,G,B$
RGBA	R,G,B,A	$R,G,B,A$

Table 8.11: Conversion from RGBA, depth, and stencil pixel components to internal texture components. Texture components  $R$ ,  $G$ ,  $B$ , and  $A$  are converted back to RGBA colors during filtering as shown in table 15.1.

ARRAY, TEXTURE\_RECTANGLE, TEXTURE\_CUBE\_MAP, TEXTURE\_CUBE\_MAP\_ARRAY, PROXY\_TEXTURE\_1D, PROXY\_TEXTURE\_2D, PROXY\_TEXTURE\_1D\_ARRAY, PROXY\_TEXTURE\_2D\_ARRAY, PROXY\_TEXTURE\_RECTANGLE, PROXY\_TEXTURE\_CUBE\_MAP, or PROXY\_TEXTURE\_CUBE\_MAP\_ARRAY.

An INVALID\_OPERATION error is generated if these formats are used in conjunction with any other *target*.

Textures with a base internal format of DEPTH\_COMPONENT or DEPTH\_STENCIL require either depth component data or depth/stencil component data. Textures with other base internal formats require RGBA component data.

An INVALID\_OPERATION error is generated if one of the base internal format and *format* is DEPTH\_COMPONENT or DEPTH\_STENCIL, and the other is neither of these values.

Textures with integer internal formats (see table 8.12) require integer data.

An INVALID\_OPERATION error is generated if the internal format is integer and *format* is not one of the integer formats listed in table 8.3, or if the internal format is not integer and *format* is an integer format.

In addition to the specific compressed internal formats listed in table 8.14, the GL provides a mechanism to query token values for specific compressed internal formats, suitable for general-purpose<sup>1</sup> usage. Formats with restrictions that need to be specifically understood prior to use will not be returned by this query. The number of specific compressed internal formats is obtained by querying the value of NUM\_COMPRESSED\_TEXTURE\_FORMATS. The set of specific compressed internal formats is obtained by querying COMPRESSED\_TEXTURE\_FORMATS with **GetIntegerv**, returning an array containing that number of values.

<sup>1</sup> These queries have been deprecated in OpenGL 4.2, because the vagueness of the term “general-purpose” makes it possible for implementations to choose to return **no** formats from the query.

Generic compressed internal formats are never used directly as the internal formats of texture images. If *internalformat* is one of the six generic compressed internal formats, its value is replaced by the symbolic constant for a specific compressed internal format of the GL's choosing with the same base internal format. If no specific compressed format is available, *internalformat* is instead replaced by the corresponding base internal format. If *internalformat* is given as or mapped to a specific compressed internal format, but the GL can not support images compressed in the chosen internal format for any reason (e.g., the compression format might not support 3D textures), *internalformat* is replaced by the corresponding base internal format and the texture image will not be compressed by the GL.

The *internal component resolution* is the number of bits allocated to each value in a texture image. If *internalformat* is specified as a base internal format, the GL stores the resulting texture with internal component resolutions of its own choosing. If a sized internal format is specified, the mapping of the R, G, B, A, depth, and stencil values to texture components is equivalent to the mapping of the corresponding base internal format's components, as specified in table 8.11; the type (unsigned int, float, etc.) is assigned the same type specified by *internalformat*; and the memory allocation per texture component is assigned by the GL to match the allocations listed in tables 8.12- 8.13 as closely as possible. (The definition of closely is left up to the implementation. However, a non-zero number of bits must be allocated for each component whose *desired* allocation in tables 8.12- 8.13 is non-zero, and zero bits must be allocated for all other components).

### 8.5.1 Required Texture Formats

Implementations are required to support at least one allocation of internal component resolution for each type (unsigned int, float, etc.) for each base internal format.

In addition, implementations are required to support the following sized and compressed internal formats. Requesting one of these sized internal formats for any texture type will allocate at least the internal component sizes, and exactly the component types shown for that format in tables 8.12- 8.13:

- Texture and renderbuffer color formats (see section 9.2.5).
  - RGBA32F, RGBA32I, RGBA32UI, RGBA16, RGBA16F, RGBA16I, RGBA16UI, RGBA8, RGBA8I, RGBA8UI, SRGB8\_ALPHA8, RGB10\_A2, RGB10\_A2UI, RGB5\_A1, and RGBA4.
  - R11F\_G11F\_B10F and RGB565.

- RG32F, RG32I, RG32UI, RG16, RG16F, RG16I, RG16UI, RG8, RG8I, and RG8UI.
- R32F, R32I, R32UI, R16F, R16I, R16UI, R16, R8, R8I, and R8UI.
- Texture-only color formats:
  - RGBA16\_SNORM and RGBA8\_SNORM.
  - RGB32F, RGB32I, and RGB32UI.
  - RGB16\_SNORM, RGB16F, RGB16I, RGB16UI, and RGB16.
  - RGB8\_SNORM, RGB8, RGB8I, RGB8UI, and SRGB8.
  - RGB9\_E5.
  - RG16\_SNORM and RG8\_SNORM.
  - R16\_SNORM and R8\_SNORM.
  - All of the specific compressed texture formats described in table 8.14 and appendix C.
- Depth formats: DEPTH\_COMPONENT32F, DEPTH\_COMPONENT24, and DEPTH\_COMPONENT16.
- Combined depth+stencil formats: DEPTH32F\_STENCIL8 and DEPTH24\_STENCIL8.

### 8.5.2 Encoding of Special Internal Formats

If *internalformat* is R11F\_G11F\_B10F, the red, green, and blue bits are converted to unsigned 11-bit, unsigned 11-bit, and unsigned 10-bit floating-point values as described in sections 2.3.3 and 2.3.3.

If *internalformat* is RGB9\_E5, the red, green, and blue bits are converted to a shared exponent format according to the following procedure:

Components *red*, *green*, and *blue* are first clamped (in the process, mapping *NaN* to zero) as follows:

$$\begin{aligned} red_c &= \max(0, \min(\text{sharedexp}_{max}, red)) \\ green_c &= \max(0, \min(\text{sharedexp}_{max}, green)) \\ blue_c &= \max(0, \min(\text{sharedexp}_{max}, blue)) \end{aligned}$$

where

$$\text{sharedexp}_{max} = \frac{(2^N - 1)}{2^N} 2^{E_{max} - B}.$$

$N$  is the number of mantissa bits per component (9),  $B$  is the exponent bias (15), and  $E_{max}$  is the maximum allowed biased exponent value (31).

The largest clamped component,  $max_c$ , is determined:

$$max_c = \max(red_c, green_c, blue_c)$$

A preliminary shared exponent  $exp_p$  is computed:

$$exp_p = \max(-B - 1, \lfloor \log_2(max_c) \rfloor) + 1 + B$$

A refined shared exponent  $exp_s$  is computed:

$$max_s = \left\lfloor \frac{max_c}{2^{exp_p - B - N}} + 0.5 \right\rfloor$$

$$exp_s = \begin{cases} exp_p, & 0 \leq max_s < 2^N \\ exp_p + 1, & max_s = 2^N \end{cases}$$

Finally, three integer values in the range 0 to  $2^N - 1$  are computed:

$$red_s = \left\lfloor \frac{red_c}{2^{exp_s - B - N}} + 0.5 \right\rfloor$$

$$green_s = \left\lfloor \frac{green_c}{2^{exp_s - B - N}} + 0.5 \right\rfloor$$

$$blue_s = \left\lfloor \frac{blue_c}{2^{exp_s - B - N}} + 0.5 \right\rfloor$$

The resulting  $red_s$ ,  $green_s$ ,  $blue_s$ , and  $exp_s$  are stored in the red, green, blue, and shared bits respectively of the texture image.

An implementation accepting pixel data of *type* UNSIGNED\_INT\_5\_9\_9\_9\_REV with *format* RGB is allowed to store the components “as is”.

Sized Internal Format	Base Internal Format	R bits	G bits	B bits	A bits	Shared bits	Color-renderable
R8	RED	8					✓
R8_SNORM	RED	s8					✓
R16	RED	16					✓
R16_SNORM	RED	s16					✓
Sized internal color formats continued on next page							



Sized internal color formats continued from previous page							
Sized Internal Format	Base Internal Format	<i>R</i> bits	<i>G</i> bits	<i>B</i> bits	<i>A</i> bits	Shared bits	Color-renderable
RG8	RG	8	8				✓
RG8_SNORM	RG	s8	s8				✓
RG16	RG	16	16				✓
RG16_SNORM	RG	s16	s16				✓
R3_G3_B2	RGB	3	3	2			✓
RGB4	RGB	4	4	4			✓
RGB5	RGB	5	5	5			✓
RGB565	RGB	5	6	5			✓
RGB8	RGB	8	8	8			✓
RGB8_SNORM	RGB	s8	s8	s8			✓
RGB10	RGB	10	10	10			✓
RGB12	RGB	12	12	12			✓
RGB16	RGB	16	16	16			✓
RGB16_SNORM	RGB	s16	s16	s16			✓
RGBA2	RGBA	2	2	2	2		✓
RGBA4	RGBA	4	4	4	4		✓
RGB5_A1	RGBA	5	5	5	1		✓
RGBA8	RGBA	8	8	8	8		✓
RGBA8_SNORM	RGBA	s8	s8	s8	s8		✓
RGB10_A2	RGBA	10	10	10	2		✓
RGB10_A2UI	RGBA	ui10	ui10	ui10	ui2		✓
RGBA12	RGBA	12	12	12	12		✓
RGBA16	RGBA	16	16	16	16		✓
RGBA16_SNORM	RGBA	s16	s16	s16	s16		✓
SRGB8	RGB	8	8	8			✓
SRGB8_ALPHA8	RGBA	8	8	8	8		✓
R16F	RED	f16					✓
RG16F	RG	f16	f16				✓
RGB16F	RGB	f16	f16	f16			✓
RGBA16F	RGBA	f16	f16	f16	f16		✓
R32F	RED	f32					✓
RG32F	RG	f32	f32				✓
RGB32F	RGB	f32	f32	f32			✓

Sized internal color formats continued on next page

Sized internal color formats continued from previous page							
Sized Internal Format	Base Internal Format	<i>R</i> bits	<i>G</i> bits	<i>B</i> bits	<i>A</i> bits	Shared bits	Color-renderable
RGBA32F	RGBA	f32	f32	f32	f32		✓
R11F_G11F_B10F	RGB	f11	f11	f10			✓
RGB9_E5	RGB	9	9	9		5	
R8I	RED	i8					✓
R8UI	RED	ui8					✓
R16I	RED	i16					✓
R16UI	RED	ui16					✓
R32I	RED	i32					✓
R32UI	RED	ui32					✓
RG8I	RG	i8	i8				✓
RG8UI	RG	ui8	ui8				✓
RG16I	RG	i16	i16				✓
RG16UI	RG	ui16	ui16				✓
RG32I	RG	i32	i32				✓
RG32UI	RG	ui32	ui32				✓
RGB8I	RGB	i8	i8	i8			✓
RGB8UI	RGB	ui8	ui8	ui8			✓
RGB16I	RGB	i16	i16	i16			✓
RGB16UI	RGB	ui16	ui16	ui16			✓
RGB32I	RGB	i32	i32	i32			✓
RGB32UI	RGB	ui32	ui32	ui32			✓
RGBA8I	RGBA	i8	i8	i8	i8		✓
RGBA8UI	RGBA	ui8	ui8	ui8	ui8		✓
RGBA16I	RGBA	i16	i16	i16	i16		✓
RGBA16UI	RGBA	ui16	ui16	ui16	ui16		✓
RGBA32I	RGBA	i32	i32	i32	i32		✓
RGBA32UI	RGBA	ui32	ui32	ui32	ui32		✓

Table 8.12: Correspondence of sized internal color formats to base internal formats, internal data type, and *desired* component resolutions for each sized internal format. The component resolution prefix indicates the internal data type: *f* is floating-point, *i* is signed integer, *ui* is unsigned integer, *s* is signed normalized fixed-point, and no prefix is unsigned normalized fixed-point. The color-renderable column is used in determining framebuffer completeness, as described in section 9.4.

Sized Internal Format	Base Internal Format	$D$ bits	$S$ bits
DEPTH_COMPONENT16	DEPTH_COMPONENT	16	
DEPTH_COMPONENT24	DEPTH_COMPONENT	24	
DEPTH_COMPONENT32	DEPTH_COMPONENT	32	
DEPTH_COMPONENT32F	DEPTH_COMPONENT	f32	
DEPTH24_STENCIL8	DEPTH_STENCIL	24	8
DEPTH32F_STENCIL8	DEPTH_STENCIL	f32	8

Table 8.13: Correspondence of sized internal depth and stencil formats to base internal formats, internal data type, and *desired* component resolutions for each sized internal format. The component resolution prefix indicates the internal data type: *f* is floating-point, *i* is signed integer, *ui* is unsigned integer, and no prefix is fixed-point.

If a compressed internal format is specified, the mapping of the R, G, B, and A values to texture components is equivalent to the mapping of the corresponding base internal format's components, as specified in table 8.11. The specified image is compressed using a (possibly lossy) compression algorithm chosen by the GL.

A GL implementation may vary its allocation of internal component resolution or compressed internal format based on any **TexImage3D**, **TexImage2D** (see below), or **TexImage1D** (see below) parameter (except *target*), but the allocation and chosen compressed image format must not be a function of any other state and cannot be changed once they are established. In addition, the choice of a compressed image format may not be affected by the *data* parameter. Allocations must be invariant; the same allocation and compressed image format must be chosen each time a texture image is specified with the same parameter values. These allocation rules also apply to proxy textures, which are described in section 8.21.

### 8.5.3 Texture Image Structure

The image itself (referred to by *data*) is a sequence of groups of values. The first group is the lower left back corner of the texture image. Subsequent groups fill out rows of width *width* from left to right; *height* rows are stacked from bottom to top forming a single two-dimensional image slice; and *depth* slices are stacked from back to front. When the final R, G, B, and A components have been computed for a group, they are assigned to components of a *texel* as described by table 8.11.

Compressed Internal Format	Base Internal Format	Type
COMPRESSED_RED	RED	Generic
COMPRESSED_RG	RG	Generic
COMPRESSED_RGB	RGB	Generic
COMPRESSED_RGBA	RGBA	Generic
COMPRESSED_SRGB	RGB	Generic
COMPRESSED_SRGB_ALPHA	RGBA	Generic
COMPRESSED_RED_RGTC1	RED	Specific
COMPRESSED_SIGNED_RED_RGTC1	RED	Specific
COMPRESSED_RG_RGTC2	RG	Specific
COMPRESSED_SIGNED_RG_RGTC2	RG	Specific
COMPRESSED_RGBA_BPTC_UNORM	RGBA	Specific
COMPRESSED_SRGB_ALPHA_BPTC_UNORM	RGBA	Specific
COMPRESSED_RGB_BPTC_SIGNED_FLOAT	RGB	Specific
COMPRESSED_RGB_BPTC_UNSIGNED_FLOAT	RGB	Specific
COMPRESSED_RGB8_ETC2	RGB	Specific
COMPRESSED_SRGB8_ETC2	RGB	Specific
COMPRESSED_RGB8_PUNCHTHROUGH_ALPHA1_ETC2	RGB	Specific
COMPRESSED_SRGB8_PUNCHTHROUGH_ALPHA1_ETC2	RGB	Specific
COMPRESSED_RGBA8_ETC2_EAC	RGBA	Specific
COMPRESSED_SRGB8_ALPHA8_ETC2_EAC	RGBA	Specific
COMPRESSED_R11_EAC	RED	Specific
COMPRESSED_SIGNED_R11_EAC	RED	Specific
COMPRESSED_RG11_EAC	RG	Specific
COMPRESSED_SIGNED_RG11_EAC	RG	Specific

Table 8.14: Generic and specific compressed internal formats. The Specific formats are described in appendix C.

Counting from zero, each resulting  $N$ th texel is assigned internal integer coordinates  $(i, j, k)$ , where

$$\begin{aligned} i &= (N \bmod \textit{width}) - w_b \\ j &= \left( \left\lfloor \frac{N}{\textit{width}} \right\rfloor \bmod \textit{height} \right) - h_b \\ k &= \left( \left\lfloor \frac{N}{\textit{width} \times \textit{height}} \right\rfloor \bmod \textit{depth} \right) - d_b \end{aligned}$$

and  $w_b$ ,  $h_b$ , and  $d_b$  are the specified border width, height, and depth.  $w_b$  and  $h_b$  are the specified *border* value;  $d_b$  is the specified *border* value if *target* is `TEXTURE_3D`, or zero if *target* is `TEXTURE_2D_ARRAY` or `TEXTURE_CUBE_MAP_ARRAY`. Thus the last two-dimensional image slice of the three-dimensional image is indexed with the highest value of  $k$ .

When *target* is `TEXTURE_CUBE_MAP_ARRAY`, specifying a cube map array texture,  $k$  refers to a *layer-face*. The layer is given by

$$\textit{layer} = \left\lfloor \frac{k}{6} \right\rfloor,$$

and the face is given by

$$\textit{face} = k \bmod 6.$$

The face number corresponds to the cube map faces as shown in table 9.3.

If the internal data type of the image array is signed or unsigned normalized fixed-point, each color component is converted using equation 2.4 or 2.3, respectively. If the internal type is floating-point or integer, components are clamped to the representable range of the corresponding internal component, but are not converted.

The *level* argument to **TexImage3D** is an integer *level-of-detail* number. Levels of detail are discussed below, under **Mipmapping**. The main texture image has a level of detail number of zero.

An `INVALID_VALUE` error is generated if a negative level-of-detail is specified,

The *border* argument to **TexImage3D** is a border width. The significance of borders is described below. The border width affects the dimensions of the texture image: let

$$\begin{aligned} w_s &= w_t + 2w_b \\ h_s &= h_t + 2h_b \\ d_s &= d_t + 2d_b \end{aligned} \tag{8.3}$$

where  $w_s$ ,  $h_s$ , and  $d_s$  are the specified image *width*, *height*, and *depth*, and  $w_t$ ,  $h_t$ , and  $d_t$  are the dimensions of the texture image internal to the border.

An `INVALID_VALUE` error is generated if  $w_t$ ,  $h_t$ , or  $d_t$  are negative.

The maximum border width  $b_t$  is 0.

An `INVALID_VALUE` error is generated if *border* is negative or greater than  $b_t$ .

The maximum allowable width, height, or depth of a texel array for a three-dimensional texture is an implementation-dependent function of the level-of-detail and internal format of the resulting image array. It must be at least  $2^{k-lod} + 2b_t$  for image arrays of level-of-detail 0 through  $k$ , where  $k$  is the log base 2 of `MAX_3D_TEXTURE_SIZE`,  $lod$  is the level-of-detail of the image array, and  $b_t$  is the maximum border width. It may be zero for image arrays of any level-of-detail greater than  $k$ .

An `INVALID_VALUE` error is generated if *width*, *height*, or *depth* exceed the corresponding maximum size.

As described in section 8.17, these implementation-dependent limits may be configured to reject textures at level 1 or greater unless a mipmap complete set of image arrays consistent with the specified sizes can be supported.

An `INVALID_VALUE` error is generated if *target* is `TEXTURE_CUBE_MAP_ARRAY` or `PROXY_TEXTURE_CUBE_MAP_ARRAY`, and *width* and *height* are not equal.

An `INVALID_VALUE` error is generated if *depth* is not a multiple of six, indicating  $6N$  layer-faces in the cube map array.

An `INVALID_OPERATION` error is generated if a pixel unpack buffer object is bound and storing texture data would access memory beyond the end of the pixel unpack buffer.

In a similar fashion, the maximum allowable width of a texel array for a one- or two-dimensional, one- or two-dimensional array, two-dimensional multisample, or two-dimensional multisample array texture, and the maximum allowable height of a two-dimensional, two-dimensional array, two-dimensional multisample, or two-dimensional multisample array texture, must be at least  $2^{k-lod} + 2b_t$  for image arrays of level 0 through  $k$ , where  $k$  is the log base 2 of `MAX_TEXTURE_SIZE`.

The maximum allowable width and height of a cube map or cube map array texture must be the same, and must be at least  $2^{k-lod} + 2b_t$  for image arrays level 0 through  $k$ , where  $k$  is the log base 2 of the value of `MAX_CUBE_MAP_TEXTURE_SIZE`. The maximum number of layers for one- and two-dimensional array textures (height or depth, respectively), and the maximum number of layer-faces for cube map array textures (depth), must be at least the value of `MAX_ARRAY_TEXTURE_LAYERS` for all levels.

The maximum allowable width and height of a rectangle texture image must each be at least the value of the implementation-dependent constant `MAX_`

RECTANGLE\_TEXTURE\_SIZE.

The command

```
void TexImage2D( enum target, int level, int internalformat,
                 sizei width, sizei height, int border, enum format,
                 enum type, const void *data );
```

is used to specify a two-dimensional texture image. *target* must be one of TEXTURE\_2D for a two-dimensional texture, TEXTURE\_1D\_ARRAY for a one-dimensional array texture, TEXTURE\_RECTANGLE for a rectangle texture, or one of the cube map face targets from table 8.18 for a cube map texture. Additionally, *target* may be either PROXY\_TEXTURE\_2D for a two-dimensional proxy texture, PROXY\_TEXTURE\_1D\_ARRAY for a one-dimensional proxy array texture, PROXY\_TEXTURE\_RECTANGLE for a rectangle proxy texture, or PROXY\_TEXTURE\_CUBE\_MAP for a cube map proxy texture in the special case discussed in section 8.21. The other parameters match the corresponding parameters of **TexImage3D**.

For the purposes of decoding the texture image, **TexImage2D** is equivalent to calling **TexImage3D** with corresponding arguments and *depth* of 1, except that UNPACK\_SKIP\_IMAGES is ignored.

A two-dimensional or rectangle texture consists of a single two-dimensional texture image. A cube map texture is a set of six two-dimensional texture images. The six cube map texture face targets from table 8.18 form a single cube map texture. These targets each update the corresponding cube map face two-dimensional texture image. Note that the cube map face targets are used when specifying, updating, or querying one of a cube map's six two-dimensional images, but when binding to a cube map texture object (that is when the cube map is accessed as a whole as opposed to a particular two-dimensional image), the TEXTURE\_CUBE\_MAP target is specified.

### Errors

An INVALID\_ENUM error is generated if *target* is not one of the valid targets listed above.

An INVALID\_VALUE error is generated if *target* is one of the cube map face targets from table 8.18, and *width* and *height* are not equal.

An INVALID\_VALUE error is generated if *target* is TEXTURE\_RECTANGLE and *level* is non-zero.

An INVALID\_VALUE error is generated if *border* is non-zero.

Finally, the command

```
void TexImage1D( enum target, int level,
                 int internalformat, size_t width, int border,
                 enum format, enum type, const void *data );
```

is used to specify a one-dimensional texture image. *target* must be either `TEXTURE_1D`, or `PROXY_TEXTURE_1D` in the special case discussed in section 8.21.

For the purposes of decoding the texture image, **TexImage1D** is equivalent to calling **TexImage2D** with corresponding arguments and *height* of 1.

The image indicated to the GL by the image pointer is decoded and copied into the GL's internal memory.

We shall refer to the decoded image as the *texel array*. A three-dimensional texel array has width, height, and depth  $w_s$ ,  $h_s$ , and  $d_s$  as defined in equation 8.3. A two-dimensional or rectangle texel array has depth  $d_s = 1$ , with height  $h_s$  and width  $w_s$  as above. A one-dimensional texel array has depth  $d_s = 1$ , height  $h_s = 1$ , and width  $w_s$  as above.

An element  $(i, j, k)$  of the texel array is called a *texel* (for a two-dimensional texture or one-dimensional array texture,  $k$  is irrelevant; for a one-dimensional texture,  $j$  and  $k$  are both irrelevant). The *texture value* used in texturing a fragment is determined by sampling the texture in a shader, but may not correspond to any actual texel. See figure 8.3. If *target* is `TEXTURE_CUBE_MAP_ARRAY`, the texture value is determined by  $(s, t, r, q)$  coordinates where  $s$ ,  $t$ , and  $r$  are defined to be the same as for `TEXTURE_CUBE_MAP` and  $q$  is defined as the index of a specific cube map in the cube map array.

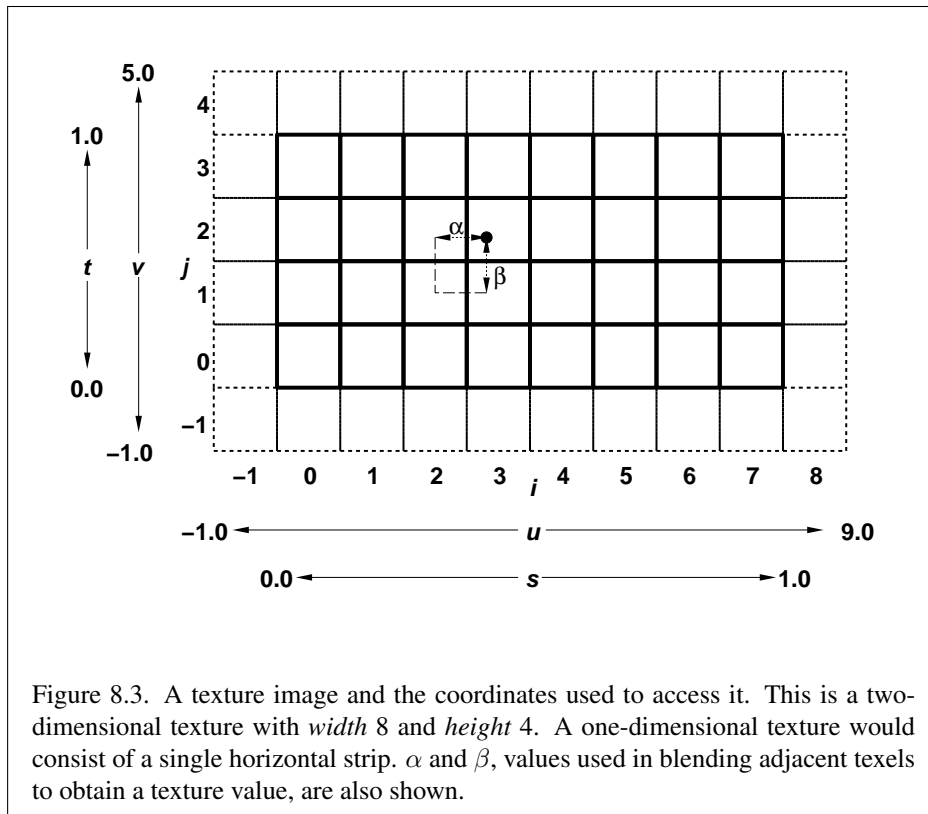
If the *data* argument of **TexImage1D**, **TexImage2D**, or **TexImage3D** is `NULL`, and the pixel unpack buffer object is zero, a one-, two-, or three-dimensional texel array is created with the specified *target*, *level*, *internalformat*, *border*, *width*, *height*, and *depth*, but with unspecified image contents. In this case no pixel values are accessed in client memory, and no pixel processing is performed. Errors are generated, however, exactly as though the *data* pointer were valid. Otherwise if the pixel unpack buffer object is non-zero, the *data* argument is treated normally to refer to the beginning of the pixel unpack buffer object's data.

## 8.6 Alternate Texture Image Specification Commands

Two-dimensional and one-dimensional texture images may also be specified using image data taken directly from the framebuffer, and rectangular subregions of existing texture images may be respecified.

The command





```
void CopyTexImage2D(enum target, int level,
                    enum internalformat, int x, int y, sizei width,
                    sizei height, int border);
```

defines a two-dimensional texel array in exactly the manner of **TexImage2D**, except that the image data are taken from the framebuffer rather than from client memory. *target* must be one of `TEXTURE_2D`, `TEXTURE_1D_ARRAY`, `TEXTURE_RECTANGLE`, or one of the cube map face targets from table 8.18. *x*, *y*, *width*, and *height* correspond precisely to the corresponding arguments to **ReadPixels** (refer to section 18.2); they specify the image's *width* and *height*, and the lower left (*x*, *y*) coordinates of the framebuffer region to be copied. The image is taken from the framebuffer exactly as if these arguments were passed to **CopyPixels** (see section 18.3) with argument *type* set to `COLOR`, `DEPTH`, or `DEPTH_STENCIL`, depending on *internalformat*, stopping after conversion of depth values. RGBA data is taken from the current color buffer, while depth component and stencil index data are taken from the depth and stencil buffers, respectively.

Subsequent processing is identical to that described for **TexImage2D**, beginning with clamping of the R, G, B, A, or depth values, and masking of the stencil index values from the resulting pixel groups. Parameters *level*, *internalformat*, and *border* are specified using the same values, with the same meanings, as the corresponding arguments of **TexImage2D**.

The constraints on *width*, *height*, and *border* are exactly those for the corresponding arguments of **TexImage2D**.

### Errors

An `INVALID_ENUM` error is generated if *target* is not `TEXTURE_2D`, `TEXTURE_1D_ARRAY`, `TEXTURE_RECTANGLE`, or one of the cube map face targets from table 8.18.

An `INVALID_ENUM` error is generated if an invalid value is specified for *internalformat*.

An `INVALID_VALUE` error is generated if the *target* parameter to **CopyTexImage2D** is one of the six cube map two-dimensional image targets, and the *width* and *height* parameters are not equal.

An `INVALID_OPERATION` error is generated under any of the following conditions:

- if depth component data is required and no depth buffer is present
- if stencil index data is required and no stencil buffer is present
- if integer RGBA data is required and the format of the current color

buffer is not integer

- if floating- or fixed-point RGBA data is required and the format of the current color buffer is integer
- if the value of `FRAMEBUFFER_ATTACHMENT_COLOR_ENCODING` for the framebuffer attachment corresponding to the read buffer is `LINEAR` (see section 9.2.3) and *internalformat* is one of the sRGB formats in table 8.23
- if the value of `FRAMEBUFFER_ATTACHMENT_COLOR_ENCODING` for the framebuffer attachment corresponding to the read buffer is `SRGB` and *internalformat* is not one of the sRGB formats. in table 8.23.

An `INVALID_VALUE` error is generated if *width* or *height* is negative.

An `INVALID_FRAMEBUFFER_OPERATION` error is generated if the object bound to `READ_FRAMEBUFFER_BINDING` (see section 9) is not framebuffer complete (as defined in section 9.4.2).

An `INVALID_OPERATION` error is generated if the object bound to `READ_FRAMEBUFFER_BINDING` is framebuffer complete and the value of `SAMPLE_BUFFERS` is greater than zero.

The command

```
void CopyTexImage1D(enum target, int level,
                    enum internalformat, int x, int y, sizei width,
                    int border);
```

defines a one-dimensional texel array in exactly the manner of `TexImage1D`, except that the image data are taken from the framebuffer, rather than from client memory. Currently, *target* must be `TEXTURE_1D`. For the purposes of decoding the texture image, `CopyTexImage1D` is equivalent to calling `CopyTexImage2D` with corresponding arguments and *height* of 1, except that the *height* of the image is always 1, regardless of the value of *border*. *level*, *internalformat*, and *border* are specified using the same values, with the same meanings, as the corresponding arguments of `TexImage1D`. The constraints on *width* and *border* are exactly those of the corresponding arguments of `TexImage1D`.

## Errors

Six additional commands,

```
void TexSubImage3D(enum target, int level, int xoffset,
                   int yoffset, int zoffset, sizei width, sizei height,
```

```

    sizei depth, enum format, enum type, const
    void *data );
void TexSubImage2D( enum target, int level, int xoffset,
    int yoffset, sizei width, sizei height, enum format,
    enum type, const void *data );
void TexSubImage1D( enum target, int level, int xoffset,
    sizei width, enum format, enum type, const
    void *data );
void CopyTexSubImage3D( enum target, int level,
    int xoffset, int yoffset, int zoffset, int x, int y,
    sizei width, sizei height );
void CopyTexSubImage2D( enum target, int level,
    int xoffset, int yoffset, int x, int y, sizei width,
    sizei height );
void CopyTexSubImage1D( enum target, int level,
    int xoffset, int x, int y, sizei width );

```

respecify only a rectangular subregion of an existing texel array. No change is made to the *internalformat*, *width*, *height*, *depth*, or *border* parameters of the specified texel array, nor is any change made to texel values outside the specified subregion.

The *target* arguments of **TexSubImage1D** and **CopyTexSubImage1D** must be `TEXTURE_1D`, the *target* arguments of **TexSubImage2D** and **CopyTexSubImage2D** must be one of `TEXTURE_2D`, `TEXTURE_1D_ARRAY`, `TEXTURE_RECTANGLE`, or one of the cube map face targets from table 8.18, and the *target* arguments of **TexSubImage3D** and **CopyTexSubImage3D** must be `TEXTURE_3D`, `TEXTURE_2D_ARRAY`, or `TEXTURE_CUBE_MAP_ARRAY`.

The *level* parameter of each command specifies the level of the texel array that is modified.

#### Errors

An `INVALID_VALUE` error is generated if *level* is negative or greater than the base 2 logarithm of the maximum texture width, height, or depth.

An `INVALID_VALUE` error is generated if *target* is `TEXTURE_RECTANGLE` and *level* is not zero.

**TexSubImage3D** arguments *width*, *height*, *depth*, *format*, and *type*, ~~and *data*~~ match the corresponding arguments to **TexImage3D**, meaning that they **accept** the same values, and have the same meanings. Likewise, **TexSubImage2D** arguments *width*, *height*, *format*, and *type*, ~~and *data*~~ match the corresponding arguments to **TexImage2D**, and **TexSubImage1D** arguments *width*, *format*, and *type*, ~~and *data*~~

match the corresponding arguments to **TexImage1D**. The *data* argument of **TexSubImage3D**, **TexSubImage2D**, and **TexSubImage1D** matches the corresponding argument of **TexImage3D**, **TexImage2D**, and **TexImage1D**, respectively, except that a **NULL** pointer does not represent unspecified image contents.

**CopyTexSubImage3D** and **CopyTexSubImage2D** arguments *x*, *y*, *width*, and *height* match the corresponding arguments to **CopyTexImage2D**<sup>2</sup>. **CopyTexSubImage1D** arguments *x*, *y*, and *width* match the corresponding arguments to **CopyTexImage1D**. Each of the **TexSubImage** commands interprets and processes pixel groups in exactly the manner of its **TexImage** counterpart, except that the assignment of R, G, B, A, depth, and stencil index pixel group values to the texture components is controlled by the *internalformat* of the texel array, not by an argument to the command. The same constraints and errors apply to the **TexSubImage** commands' argument *format* and the *internalformat* of the texel array being re-specified as apply to the *format* and *internalformat* arguments of its **TexImage** counterparts.

Arguments *xoffset*, *yoffset*, and *zoffset* of **TexSubImage3D** and **CopyTexSubImage3D** specify the lower left texel coordinates of a *width*-wide by *height*-high by *depth*-deep rectangular subregion of the texel array. For cube map array textures, *zoffset* is the first layer-face to update, and *depth* is the number of layer-faces to update. The *depth* argument associated with **CopyTexSubImage3D** is always 1, because framebuffer memory is two-dimensional - only a portion of a single (*s*, *t*) slice of a three-dimensional texture is replaced by **CopyTexSubImage3D**.

Negative values of *xoffset*, *yoffset*, and *zoffset* correspond to the coordinates of border texels, addressed as in figure 8.3. Taking  $w_s$ ,  $h_s$ ,  $d_s$ ,  $w_b$ ,  $h_b$ , and  $d_b$  to be the specified width, height, depth, and border width, border height, and border depth of the texel array, and taking *x*, *y*, *z*, *w*, *h*, and *d* to be the *xoffset*, *yoffset*, *zoffset*, *width*, *height*, and *depth* argument values, any of the following relationships generates an **INVALID\_VALUE** error:

$$\begin{aligned}x &< -w_b \\x + w &> w_s - w_b \\y &< -h_b \\y + h &> h_s - h_b \\z &< -d_b\end{aligned}$$

<sup>2</sup> Because the framebuffer is inherently two-dimensional, there is no **CopyTexImage3D** command.

$$z + d > d_s - d_b$$

Counting from zero, the  $n$ th pixel group is assigned to the texel with internal integer coordinates  $[i, j, k]$ , where

$$\begin{aligned} i &= x + (n \bmod w) \\ j &= y + (\lfloor \frac{n}{w} \rfloor \bmod h) \\ k &= z + (\lfloor \frac{n}{width * height} \rfloor \bmod d) \end{aligned}$$

Arguments *xoffset* and *yoffset* of **TexSubImage2D** and **CopyTexSubImage2D** specify the lower left texel coordinates of a *width*-wide by *height*-high rectangular subregion of the texel array. Negative values of *xoffset* and *yoffset* correspond to the coordinates of border texels, addressed as in figure 8.3. Taking  $w_s$ ,  $h_s$ , and  $b_s$  to be the specified width, height, and border width of the texel array, and taking  $x$ ,  $y$ ,  $w$ , and  $h$  to be the *xoffset*, *yoffset*, *width*, and *height* argument values, any of the following relationships generates an `INVALID_VALUE` error:

$$\begin{aligned} x &< -b_s \\ x + w &> w_s - b_s \\ y &< -b_s \\ y + h &> h_s - b_s \end{aligned}$$

Counting from zero, the  $n$ th pixel group is assigned to the texel with internal integer coordinates  $[i, j]$ , where

$$\begin{aligned} i &= x + (n \bmod w) \\ j &= y + (\lfloor \frac{n}{w} \rfloor \bmod h) \end{aligned}$$

The *xoffset* argument of **TexSubImage1D** and **CopyTexSubImage1D** specifies the left texel coordinate of a *width*-wide subregion of the texel array. Negative values of *xoffset* correspond to the coordinates of border texels. Taking  $w_s$  and  $b_s$  to be the specified width and border width of the texel array, and  $x$  and  $w$  to be the *xoffset* and *width* argument values, either of the following relationships generates an `INVALID_VALUE` error:

$$\begin{aligned} x &< -b_s \\ x + w &> w_s - b_s \end{aligned}$$

Counting from zero, the  $n$ th pixel group is assigned to the texel with internal integer coordinates  $[i]$ , where

$$i = x + (n \bmod w)$$

Texture images with compressed internal formats may be stored in such a way that it is not possible to modify an image with subimage commands without having to decompress and recompress the texture image. Even if the image were modified in this manner, it may not be possible to preserve the contents of some of the texels outside the region being modified. To avoid these complications, the GL does not support arbitrary modifications to texture images with compressed internal formats. Calling **TexSubImage3D**, **CopyTexSubImage3D**, **TexSubImage2D**, **CopyTexSubImage2D**, **TexSubImage1D**, or **CopyTexSubImage1D** will generate an `INVALID_OPERATION` error if  $xoffset$ ,  $yoffset$ , or  $zoffset$  is not equal to  $-b_s$  (border width). In addition, the contents of any texel outside the region modified by such a call are undefined. These restrictions may be relaxed for specific compressed internal formats whose images are easily modified.

If the internal format of the texture image being modified is one of the specific compressed formats described in table 8.14, the texture is stored using the corresponding compressed texture image encoding (see appendix C). Since such images are easily edited along  $4 \times 4$  texel boundaries, the limitations on subimage location and size are relaxed for **TexSubImage2D**, **TexSubImage3D**, **CopyTexSubImage2D**, and **CopyTexSubImage3D**. These commands will generate an `INVALID_OPERATION` error if one of the following conditions occurs:

- $width$  is not a multiple of four,  $width + xoffset$  is not equal to the value of `TEXTURE_WIDTH`, and either  $xoffset$  or  $yoffset$  is non-zero.
- $height$  is not a multiple of four,  $height + yoffset$  is not equal to the value of `TEXTURE_HEIGHT`, and either  $xoffset$  or  $yoffset$  is non-zero.
- $xoffset$  or  $yoffset$  is not a multiple of four.

The contents of any  $4 \times 4$  block of texels of such a compressed texture image that does not intersect the area being modified are preserved during valid **TexSubImage\*** and **CopyTexSubImage\*** calls.

### Errors

An `INVALID_FRAMEBUFFER_OPERATION` error is generated by **CopyTexSubImage3D**, **CopyTexImage2D**, **CopyTexSubImage2D**, **CopyTexImage1D**, or **CopyTexSubImage1D** if the object bound to `READ_`

FRAMEBUFFER\_BINDING is not framebuffer complete (see section 9.4.2)

An INVALID\_OPERATION error is generated by **CopyTexSubImage3D**, **CopyTexImage2D**, **CopyTexSubImage2D**, **CopyTexImage1D**, or **CopyTexSubImage1D** if

- the value of READ\_BUFFER is NONE.
- the value of READ\_FRAMEBUFFER\_BINDING is non-zero, and
  - the read buffer selects an attachment that has no image attached, or
  - the value of SAMPLE\_BUFFERS for the read framebuffer is greater than zero.

### 8.6.1 Texture Copying Feedback Loops

Calling **CopyTexSubImage3D**, **CopyTexImage2D**, **CopyTexSubImage2D**, **CopyTexImage1D**, or **CopyTexSubImage1D** will result in undefined behavior if the destination texture image level is also bound to to the selected read buffer (see section 18.2) of the read framebuffer. This situation is discussed in more detail in the description of feedback loops in section 9.3.2.

## 8.7 Compressed Texture Images

Texture images may also be specified or modified using image data already stored in a known compressed image format, including the formats defined in appendix C as well as any additional formats defined by extensions.

The commands

```
void CompressedTexImage1D( enum target, int level,
    enum internalformat, sizei width, int border,
    sizei imageSize, const void *data );
void CompressedTexImage2D( enum target, int level,
    enum internalformat, sizei width, sizei height,
    int border, sizei imageSize, const void *data );
void CompressedTexImage3D( enum target, int level,
    enum internalformat, sizei width, sizei height,
    sizei depth, int border, sizei imageSize, const
    void *data );
```

define one-, two-, and three-dimensional texture images, respectively, with incoming data stored in a specific compressed image format. The *target*, *level*, *inter-*



*nformat*, *width*, *height*, *depth*, and *border* parameters have the same meaning as in **TexImage1D**, **TexImage2D**, and **TexImage3D**, except that compressed rectangle texture formats are not supported. *data* refers to compressed image data stored in the specific compressed image format corresponding to *internalformat*. If a pixel unpack buffer is bound (as indicated by a non-zero value of `PIXEL_UNPACK_BUFFER_BINDING`), *data* is an offset into the pixel unpack buffer and the compressed data is read from the buffer relative to this offset; otherwise, *data* is a pointer to client memory and the compressed data is read from client memory relative to the pointer.

The compressed image will be decoded according to the specification defining the *internalformat* token. Compressed texture images are treated as an array of *imageSize* `ubytes` relative to *data*.

If the compressed image is not encoded according to the defined image format, the results of the call are undefined.

If the compressed data are arranged into fixed-size blocks of texels, the pixel storage modes can be used to select a sub-rectangle from a larger containing rectangle. These pixel storage modes operate in the same way as they do for **TexImage\*D** and as described in section 8.4.4. In the remainder of this section, denote by  $b_s$ ,  $b_w$ ,  $b_h$ , and  $b_d$  the values of pixel storage modes `UNPACK_COMPRESSED_BLOCK_SIZE`, `UNPACK_COMPRESSED_BLOCK_WIDTH`, `UNPACK_COMPRESSED_BLOCK_HEIGHT`, and `UNPACK_COMPRESSED_BLOCK_DEPTH` respectively.  $b_s$  is the compressed block size in bytes;  $b_w$ ,  $b_h$ , and  $b_d$  are the compressed block width, height, and depth in pixels.

By default the pixel storage modes `UNPACK_ROW_LENGTH`, `UNPACK_SKIP_ROWS`, `UNPACK_SKIP_PIXELS`, `UNPACK_IMAGE_HEIGHT` and `UNPACK_SKIP_IMAGES` are ignored for compressed images. To enable `UNPACK_SKIP_PIXELS` and `UNPACK_ROW_LENGTH`,  $b_s$  and  $b_w$  must both be non-zero. To also enable `UNPACK_SKIP_ROWS` and `UNPACK_IMAGE_HEIGHT`,  $b_h$  must be non-zero. And to also enable `UNPACK_SKIP_IMAGES`,  $b_d$  must be non-zero. All parameters must be consistent with the compressed format to produce the desired results.

### Errors

An `INVALID_ENUM` error is generated if the *target* parameter to any of the **CompressedTexImage*n*D** commands is `TEXTURE_RECTANGLE` or `PROXY_TEXTURE_RECTANGLE`.

An `INVALID_ENUM` error is generated if *internalformat* is not a supported specific compressed internal format from table 8.14. In particular, this error will be generated for any of the generic compressed internal formats.

An `INVALID_VALUE` error is generated if *width*, *height*, *depth*, or *image-*

*Size* is negative.

An `INVALID_OPERATION` error is generated if a pixel unpack buffer object is bound and  $data + imageSize$  is greater than the size of the pixel buffer.

An `INVALID_VALUE` error is generated if the *imageSize* parameter is not consistent with the format, dimensions, and contents of the compressed image.

An `INVALID_OPERATION` error is generated if any of the following conditions are violated when selecting a sub-rectangle from a compressed image:

- the value of `UNPACK_SKIP_PIXELS` must be a multiple of  $b_w$ ;
- the value of `UNPACK_SKIP_ROWS` must be a multiple of  $b_h$  for **CompressedTexImage2D** and **CompressedTexImage3D**;
- the value of `UNPACK_SKIP_IMAGES` must be a multiple of  $b_d$  for **CompressedTexImage3D**.

An `INVALID_VALUE` error is generated if *imageSize* does not match the following requirements when pixel storage modes are active.

For **CompressedTexImage1D** the *imageSize* parameter must be equal to

$$b_s \times \left\lceil \frac{width}{b_w} \right\rceil$$

For **CompressedTexImage2D** the *imageSize* parameter must be equal to

$$b_s \times \left\lceil \frac{width}{b_w} \right\rceil \times \left\lceil \frac{height}{b_h} \right\rceil$$

For **CompressedTexImage3D** the *imageSize* parameter must be equal to

$$b_s \times \left\lceil \frac{width}{b_w} \right\rceil \times \left\lceil \frac{height}{b_h} \right\rceil \times \left\lceil \frac{depth}{b_d} \right\rceil$$

Based on the definition of unpacking from section 8.4.4 for uncompressed images, unpacking compressed images can be defined where:

- $n$ , the number of elements in a group, is 1
- $s$ , the size of an element, is  $b_s$
- $l$ , the number of groups in a row, is

$$l = \begin{cases} \left\lceil \frac{row\_length}{b_w} \right\rceil, & row\_length > 0 \\ \left\lceil \frac{length}{b_w} \right\rceil, & otherwise \end{cases}$$

where *row\_length* is the value of `UNPACK_ROW_LENGTH`.

- $a$ , the value of `UNPACK_ALIGNMENT`, is ignored and
- $k = n \times l$  as is defined for uncompressed images.

Before obtaining the first compressed image block from memory, the *data* pointer is advanced by

$$\frac{\text{UNPACK_SKIP_PIXELS}}{b_w} \times n + \frac{\text{UNPACK_SKIP_ROWS}}{b_h} \times k$$

elements. Then  $\left\lceil \frac{\text{width}}{b_w} \right\rceil$  blocks are obtained from contiguous blocks in memory (without advancing the pointer), after which the pointer is advanced by  $k$  elements.  $\left\lceil \frac{\text{height}}{b_h} \right\rceil$  sets of  $\left\lceil \frac{\text{width}}{b_w} \right\rceil$  blocks are obtained this way. For three-dimensional compressed images the pointer is advanced by  $\frac{\text{UNPACK_SKIP_IMAGES}}{b_d}$  times the number of elements in one two-dimensional image before obtaining the first group from memory. Then after *height* rows are obtained the pointer skips over the remaining  $\left\lceil \frac{\text{UNPACK_IMAGE_HEIGHT}}{b_h} \right\rceil$  rows, if `UNPACK_IMAGE_HEIGHT` is positive, before starting the next two-dimensional image.

An `INVALID_OPERATION` error is generated if any format-specific restrictions imposed by specific compressed internal formats are violated by the compressed image specification calls or parameters. For example, a format might be supported only for 2D textures, or might not allow non-zero *border* values. Any such restrictions will be documented in the extension specification defining the compressed internal format.

Any restrictions imposed by specific compressed internal formats will be invariant, meaning that if the GL accepts and stores a texture image in compressed form, providing the same image to **CompressedTexImage1D**, **CompressedTexImage2D**, or **CompressedTexImage3D** will not generate an `INVALID_OPERATION` error if the following restrictions are satisfied:

- *data* points to a compressed texture image returned by **GetCompressedTexImage** (section 8.11).
- *target*, *level*, and *internalformat* match the *target*, *level* and *format* parameters provided to the **GetCompressedTexImage** call returning *data*.
- *width*, *height*, *depth*, *internalformat*, and *imageSize* match the values of `TEXTURE_WIDTH`, `TEXTURE_HEIGHT`, `TEXTURE_DEPTH`, `TEXTURE_INTERNAL_FORMAT`, and `TEXTURE_COMPRESSED_IMAGE_SIZE` for image level *level* in effect at the time of the **GetCompressedTexImage** call returning *data*.

This guarantee applies not just to images returned by **GetCompressedTexImage**, but also to any other properly encoded compressed texture image of the same size and format.

If *internalformat* is one of the specific compressed formats described in table 8.14, the compressed image data is stored using the corresponding texture image encoding (see appendix C). The corresponding compression algorithms support only two-dimensional images without borders, though 3D images can be compressed as multiple slices of compressed 2D BPTC images.

### Errors

An `INVALID_ENUM` error is generated by **CompressedTexImage1D** if *internalformat* is one of the specific compressed formats.

An `INVALID_OPERATION` error is generated by **CompressedTexImage2D** if *internalformat* is one of the EAC, ETC2, or RGTC formats and either *border* is non-zero, or *target* is `TEXTURE_RECTANGLE`.

An `INVALID_OPERATION` error is generated by **CompressedTexImage3D** if *internalformat* is one of the EAC, ETC2, or RGTC formats and either *border* is non-zero, or *target* is not `TEXTURE_2D_ARRAY`.

An `INVALID_OPERATION` error is generated by **CompressedTexImage2D** and **CompressedTexImage3D** if *internalformat* is one of the BPTC formats and *border* is non-zero.

If the *data* argument of **CompressedTexImage1D**, **CompressedTexImage2D**, or **CompressedTexImage3D** is `NULL`, and the pixel unpack buffer object is zero, a texel array with unspecified image contents is created, just as when a `NULL` pointer is passed to **TexImage1D**, **TexImage2D**, or **TexImage3D**.

The commands

```
void CompressedTexSubImage1D(enum target, int level,
    int xoffset, sizei width, enum format, sizei imageSize,
    const void *data);
void CompressedTexSubImage2D(enum target, int level,
    int xoffset, int yoffset, sizei width, sizei height,
    enum format, sizei imageSize, const void *data);
void CompressedTexSubImage3D(enum target, int level,
    int xoffset, int yoffset, int zoffset, sizei width,
    sizei height, sizei depth, enum format,
    sizei imageSize, const void *data);
```

respecify only a rectangular region of an existing texel array, with incoming data

stored in a specific compressed image format. The *target*, *level*, *xoffset*, *yoffset*, *zoffset*, *width*, *height*, and *depth* parameters have the same meaning as in **TexSubImage1D**, **TexSubImage2D**, and **TexSubImage3D**. *data* points to compressed image data stored in the compressed image format corresponding to *format*.

The image pointed to by *data* and the *imageSize* parameter are interpreted as though they were provided to **CompressedTexImage1D**, **CompressedTexImage2D**, and **CompressedTexImage3D**.

Any restrictions imposed by specific compressed internal formats will be invariant, meaning that if the GL accepts and stores a texture image in compressed form, providing the same image to **CompressedTexSubImage1D**, **CompressedTexSubImage2D**, **CompressedTexSubImage3D** will not generate an `INVALID_OPERATION` error if the following restrictions are satisfied:

- *data* points to a compressed texture image returned by **GetCompressedTexImage** (section 8.11).
- *target*, *level*, and *format* match the *target*, *level* and *format* parameters provided to the **GetCompressedTexImage** call returning *data*.
- *width*, *height*, *depth*, *format*, and *imageSize* match the values of `TEXTURE_WIDTH`, `TEXTURE_HEIGHT`, `TEXTURE_DEPTH`, `TEXTURE_INTERNAL_FORMAT`, and `TEXTURE_COMPRESSED_IMAGE_SIZE` for image level *level* in effect at the time of the **GetCompressedTexImage** call returning *data*.
- *width*, *height*, *depth*, and *format* match the values of `TEXTURE_WIDTH`, `TEXTURE_HEIGHT`, `TEXTURE_DEPTH`, and `TEXTURE_INTERNAL_FORMAT` currently in effect for image level *level*.
- *xoffset*, *yoffset*, and *zoffset* are all zero.

This guarantee applies not just to images returned by **GetCompressedTexImage**, but also to any other properly encoded compressed texture image of the same size.

If the internal format of the image being modified is one of the specific compressed formats described in table 8.14, the texture is stored using the corresponding texture image encoding (see appendix C).

Since these specific compressed formats are easily edited along  $4 \times 4$  texel boundaries, the limitations on subimage location and size are relaxed for **CompressedTexSubImage2D** and **CompressedTexSubImage3D**.

The contents of any  $4 \times 4$  block of texels of a compressed texture image in these specific compressed formats that does not intersect the area being modified are preserved during **CompressedTexSubImage\*** calls.

**Errors**

An `INVALID_ENUM` error is generated if *target* is `TEXTURE_RECTANGLE` or `PROXY_TEXTURE_RECTANGLE`,

An `INVALID_ENUM` error is generated if *format* is one of the generic compressed internal formats.

An `INVALID_OPERATION` error is generated if *format* does not match the internal format of the texture image being modified, since these commands do not provide for image format conversion.

An `INVALID_VALUE` error is generated if *width*, *height*, *depth*, or *imageSize* is negative.

An `INVALID_VALUE` error is generated if *imageSize* is not consistent with the format, dimensions, and contents of the compressed image (too little or too much data),

An `INVALID_OPERATION` error is generated if any format-specific restrictions are violated, as with **CompressedTexImage** calls. Any such restrictions will be documented in the specification defining the compressed internal format.

An `INVALID_OPERATION` error is generated if *xoffset*, *yoffset*, or *zoffset* are not equal to zero, or if *width*, *height*, and *depth* do not match the corresponding dimensions of the texture level. The contents of any texel outside the region modified by the call are undefined. These restrictions may be relaxed for specific compressed internal formats whose images are easily modified.

An `INVALID_ENUM` error is generated by **CompressedTexSubImage1D** if the internal format of the texture bound to *target* is one of the specific compressed formats.

An `INVALID_OPERATION` error is generated by **CompressedTexSubImage2D** if the internal format of the texture bound to *target* is one of the EAC, ETC2, or RGTC formats and *border* is non-zero.

An `INVALID_OPERATION` error is generated by **CompressedTexSubImage3D** if the internal format of the texture bound to *target* is one of the EAC, ETC2, or RGTC formats and either *border* is non-zero, or *target* is not `TEXTURE_2D_ARRAY`.

An `INVALID_OPERATION` error is generated by **CompressedTexSubImage2D** and **CompressedTexSubImage3D** if the internal format of the texture bound to *target* is one of the BPTC formats and *border* is non-zero.

An `INVALID_OPERATION` error is generated by **CompressedTexSubImage2D** and **CompressedTexSubImage3D** if any of the following conditions occurs:

- *width* is not a multiple of four, and *width + xoffset* is not equal to the value of `TEXTURE_WIDTH`.
- *height* is not a multiple of four, and *height + yoffset* is not equal to the value of `TEXTURE_HEIGHT`.
- *xoffset* or *yoffset* is not a multiple of four.

## 8.8 Multisample Textures

In addition to the texture types described in previous sections, two additional types of textures are supported. A multisample texture is similar to a two-dimensional or two-dimensional array texture, except it contains multiple samples per texel. Multisample textures do not have multiple image levels.

The commands

```
void TexImage2DMultisample( enum target, sizei samples,
    int internalformat, sizei width, sizei height,
    boolean fixedsamplelocations );
void TexImage3DMultisample( enum target, sizei samples,
    int internalformat, sizei width, sizei height,
    sizei depth, boolean fixedsamplelocations );
```

establish the data storage, format, dimensions, and number of samples of a multisample texture's image. For **TexImage2DMultisample**, *target* must be `TEXTURE_2D_MULTISAMPLE` or `PROXY_TEXTURE_2D_MULTISAMPLE` and for **TexImage3DMultisample** *target* must be `TEXTURE_2D_MULTISAMPLE_ARRAY` or `PROXY_TEXTURE_2D_MULTISAMPLE_ARRAY`. *width* and *height* are the dimensions in texels of the texture.

*samples* represents a request for a desired minimum number of samples. Since different implementations may support different sample counts for multisampled textures, the actual number of samples allocated for the texture image is implementation-dependent. However, the resulting value for `TEXTURE_SAMPLES` is guaranteed to be greater than or equal to *samples* and no more than the next larger sample count supported by the implementation.

*internalformat* must be color-renderable, depth-renderable, or stencil-renderable (as defined in section 9.4).

If *fixedsamplelocations* is `TRUE`, the image will use identical sample locations and the same number of samples for all texels in the image, and the sample locations will not depend on the *internalformat* or size of the image.

Upon success, **TexImage\*Multisample** deletes any existing image for *target* and the contents of texels are undefined. `TEXTURE_WIDTH`, `TEXTURE_HEIGHT`, `TEXTURE_SAMPLES`, `TEXTURE_INTERNAL_FORMAT` and `TEXTURE_FIXED_SAMPLE_LOCATIONS` are set to *width*, *height*, the actual number of samples allocated, *internalformat*, and *fixedsamplelocations* respectively.

When a multisample texture is accessed in a shader, the access takes one vector of integers describing which texel to fetch and an integer corresponding to the sample numbers described in section 14.3.1 describing which sample within the texel to fetch. No standard sampling instructions are allowed on the multisample texture targets. Fetching a sample number less than zero, or greater than or equal to the number of samples in the texture, produces undefined results.

### Errors

An `INVALID_VALUE` error is generated if *width*, *height*, or *depth* is negative.

An `INVALID_VALUE` error is generated if either *width* or *height* is greater than the value of `MAX_TEXTURE_SIZE`, or if *samples* is zero.

An `INVALID_OPERATION` error is generated if *samples* is greater than the maximum number of samples supported for this *target* and *internalformat*. The maximum number of samples supported can be determined by calling **GetInternalformativ** with a *pname* of `SAMPLES` (see section 22.3).

An `OUT_OF_MEMORY` error is generated if the GL is unable to create a texture image of the requested size.

## 8.9 Buffer Textures

In addition to one-, two-, and three-dimensional, one- and two-dimensional array, and cube map textures described in previous sections, one additional type of texture is supported. A buffer texture is similar to a one-dimensional texture. However, unlike other texture types, the texel array is not stored as part of the texture. Instead, a buffer object is attached to a buffer texture and the texel array is taken from that buffer object's data store. When the contents of a buffer object's data store are modified, those changes are reflected in the contents of any buffer texture to which the buffer object is attached. Buffer textures do not have multiple image levels; only a single data store is available.

The command

```
void TexBufferRange( enum target, enum internalformat,
                    uint buffer, intptr offset, sizeiptr size );
```



attaches the range of the storage for the buffer object named *buffer* for *size* basic machine units, starting at *offset* (also in basic machine units) to the active buffer texture, and specifies an internal format for the texel array found in the range of the attached buffer object. If *buffer* is zero, then any buffer object attached to the buffer texture is detached, the values *offset* and *size* are ignored and the state for *offset* and *size* for the buffer texture are reset to zero. *target* must be `TEXTURE_BUFFER`. *internalformat* specifies the storage format and must be one of the sized internal formats found in table 8.15.

### Errors

An `INVALID_ENUM` error is generated if *target* is not `TEXTURE_BUFFER`.

An `INVALID_ENUM` error is generated if *internalformat* is not one of the sized internal formats in table 8.15.

An `INVALID_OPERATION` error is generated if *buffer* is non-zero, but is not the name of a buffer object.

An `INVALID_VALUE` error is generated if *offset* is negative, if *size* is less than or equal to zero, or if *offset* + *size* is greater than the value of `BUFFER_SIZE` for the buffer bound to *target*.

An `INVALID_VALUE` error is generated if *offset* is not an integer multiple of the value of `TEXTURE_BUFFER_OFFSET_ALIGNMENT`.

The command

```
void TexBuffer( enum target, enum internalformat,
                uint buffer );
```

is equivalent to

```
TexBufferRange( target, internalformat, buffer, 0, size );
```

with *size* set to the value of `BUFFER_SIZE` for *buffer*.

When a range of the storage of a buffer object is attached to a buffer texture, the range of the buffer's data store is taken as the texture's texel array. The number of texels in the buffer texture's texel array is given by

$$\left\lfloor \frac{size}{components \times sizeof(base\_type)} \right\rfloor.$$

where *components* and *base.type* are the element count and base type for elements, as specified in table 8.15.

The number of texels in the texel array is then clamped to value of the implementation-dependent limit `MAX_TEXTURE_BUFFER_SIZE`. When a buffer texture is accessed in a shader, the results of a texel fetch are undefined if the specified texel coordinate is negative, or greater than or equal to the clamped number of texels in the texel array.

When a buffer texture is accessed in a shader, an integer is provided to indicate the texel coordinate being accessed. If no buffer object is bound to the buffer texture, the results of the texel access are undefined. Otherwise, the attached buffer object's data store is interpreted as an array of elements of the GL data type corresponding to *internalformat*. Each texel consists of one to four elements that are mapped to texture components (R, G, B, and A). Element  $m$  of the texel numbered  $n$  is taken from element  $n \times \text{components} + m$  of the attached buffer object's data store. Elements and texels are both numbered starting with zero. For texture formats with signed or unsigned normalized fixed-point components, the extracted values are converted to floating-point using equations 2.2 or 2.1, respectively. The components of the texture are then converted to a  $(R, G, B, A)$  vector according to table 8.15, and returned to the shader as a four-component result vector with components of the appropriate data type for the texture's internal format. The base data type, component count, normalized component information, and mapping of data store elements to texture components is specified in table 8.15.

Sized Internal Format	Base Type	Components	Norm	Component			
				0	1	2	3
R8	ubyte	1	Yes	R	0	0	1
R16	ushort	1	Yes	R	0	0	1
R16F	half	1	No	R	0	0	1
R32F	float	1	No	R	0	0	1
R8I	byte	1	No	R	0	0	1
R16I	short	1	No	R	0	0	1
R32I	int	1	No	R	0	0	1
R8UI	ubyte	1	No	R	0	0	1
R16UI	ushort	1	No	R	0	0	1
R32UI	uint	1	No	R	0	0	1
RG8	ubyte	2	Yes	R	G	0	1
RG16	ushort	2	Yes	R	G	0	1
RG16F	half	2	No	R	G	0	1
RG32F	float	2	No	R	G	0	1
(Continued on next page)							

Internal formats for buffer textures (continued)							
Sized Internal Format	Base Type	Components	Norm	Component			
				0	1	2	3
RG8I	byte	2	No	R	G	0	1
RG16I	short	2	No	R	G	0	1
RG32I	int	2	No	R	G	0	1
RG8UI	ubyte	2	No	R	G	0	1
RG16UI	ushort	2	No	R	G	0	1
RG32UI	uint	2	No	R	G	0	1
RGB32F	float	3	No	R	G	B	1
RGB32I	int	3	No	R	G	B	1
RGB32UI	uint	3	No	R	G	B	1
RGBA8	ubyte	4	Yes	R	G	B	A
RGBA16	ushort	4	Yes	R	G	B	A
RGBA16F	half	4	No	R	G	B	A
RGBA32F	float	4	No	R	G	B	A
RGBA8I	byte	4	No	R	G	B	A
RGBA16I	short	4	No	R	G	B	A
RGBA32I	int	4	No	R	G	B	A
RGBA8UI	ubyte	4	No	R	G	B	A
RGBA16UI	ushort	4	No	R	G	B	A
RGBA32UI	uint	4	No	R	G	B	A

Table 8.15: Internal formats for buffer textures. For each format, the data type of each element is indicated in the “Base Type” column and the element count is in the “Components” column. The “Norm” column indicates whether components should be treated as normalized floating-point values. The “Component 0, 1, 2, and 3” columns indicate the mapping of each element of a texel to texture components.

In addition to attaching buffer objects to textures, buffer objects can be bound to the buffer object target named `TEXTURE_BUFFER`, in order to specify, modify, or read the buffer object’s data store. The buffer object bound to `TEXTURE_BUFFER` has no effect on rendering. A buffer object is bound to `TEXTURE_BUFFER` by calling **BindBuffer** with *target* set to `TEXTURE_BUFFER`, as described in section 6.

## 8.10 Texture Parameters

Texture parameters control how the texel array is treated when specified or changed, and when applied to a fragment. Each parameter is set by calling

```
void TexParameter{if}( enum target, enum pname, T param );
void TexParameter{if}v( enum target, enum pname, const
    T *params );
void TexParameterI{i ui}v( enum target, enum pname, const
    T *params );
```

*target* is the texture target, and must be one of TEXTURE\_1D, TEXTURE\_2D, TEXTURE\_3D, TEXTURE\_1D\_ARRAY, TEXTURE\_2D\_ARRAY, TEXTURE\_RECTANGLE, TEXTURE\_CUBE\_MAP, TEXTURE\_CUBE\_MAP\_ARRAY, TEXTURE\_2D\_MULTISAMPLE, or TEXTURE\_2D\_MULTISAMPLE\_ARRAY. *pname* is a symbolic constant indicating the parameter to be set; the possible constants and corresponding parameters are summarized in table 8.16. In the first form of the command, *param* is a value to which to set a single-valued parameter; in the remaining forms, *params* is an array of parameters whose type depends on the parameter being set.

Data conversions are performed as specified in section 2.2.1.

In addition, if the values for TEXTURE\_BORDER\_COLOR are specified with **TexParameterIiv** or **TexParameterIuiv**, the values are unmodified and stored with an internal data type of integer. If specified with **TexParameteriv**, they are converted to floating-point using equation 2.2. Otherwise the values are unmodified and stored as floating-point.

If *pname* is TEXTURE\_SWIZZLE\_RGBA, *params* is an array of four enums which respectively set the TEXTURE\_SWIZZLE\_R, TEXTURE\_SWIZZLE\_G, TEXTURE\_SWIZZLE\_B, and TEXTURE\_SWIZZLE\_A parameters simultaneously.

Name	Type	Legal Values
DEPTH_STENCIL_TEXTURE_MODE	enum	DEPTH_COMPONENT, STENCIL_INDEX
TEXTURE_BASE_LEVEL	int	any non-negative integer
TEXTURE_BORDER_COLOR	4 floats, ints, or uints	any 4 values
TEXTURE_COMPARE_MODE	enum	NONE, COMPARE_REF_TO_TEXTURE

Texture parameters continued on next page

Texture parameters continued from previous page		
Name	Type	Legal Values
TEXTURE_COMPARE_FUNC	enum	LEQUAL, GEQUAL, LESS, GREATER, EQUAL, NOTEQUAL, ALWAYS, NEVER
TEXTURE_LOD_BIAS	float	any value
TEXTURE_MAG_FILTER	enum	NEAREST, LINEAR
TEXTURE_MAX_LEVEL	int	any non-negative integer
TEXTURE_MAX_LOD	float	any value
TEXTURE_MIN_FILTER	enum	NEAREST, LINEAR, NEAREST_MIPMAP_NEAREST, NEAREST_MIPMAP_LINEAR, LINEAR_MIPMAP_NEAREST, LINEAR_MIPMAP_LINEAR,
TEXTURE_MIN_LOD	float	any value
TEXTURE_SWIZZLE_R	enum	RED, GREEN, BLUE, ALPHA, ZERO, ONE
TEXTURE_SWIZZLE_G	enum	RED, GREEN, BLUE, ALPHA, ZERO, ONE
TEXTURE_SWIZZLE_B	enum	RED, GREEN, BLUE, ALPHA, ZERO, ONE
TEXTURE_SWIZZLE_A	enum	RED, GREEN, BLUE, ALPHA, ZERO, ONE
TEXTURE_SWIZZLE_RGBA	4 enums	RED, GREEN, BLUE, ALPHA, ZERO, ONE
TEXTURE_WRAP_S	enum	CLAMP_TO_EDGE, REPEAT, CLAMP_TO_BORDER, MIRRORED_REPEAT
TEXTURE_WRAP_T	enum	CLAMP_TO_EDGE, REPEAT, CLAMP_TO_BORDER, MIRRORED_REPEAT
TEXTURE_WRAP_R	enum	CLAMP_TO_EDGE, REPEAT, CLAMP_TO_BORDER, MIRRORED_REPEAT

Table 8.16: Texture parameters and their values.

In the remainder of chapter 8, denote by  $lod_{min}$ ,  $lod_{max}$ ,  $level_{base}$ , and  $level_{max}$  the values of the texture parameters `TEXTURE_MIN_LOD`, `TEXTURE_MAX_LOD`, `TEXTURE_BASE_LEVEL`, and `TEXTURE_MAX_LEVEL` respectively. However, if `TEXTURE_IMMUTABLE_FORMAT` is `TRUE`, then  $level_{base}$  is clamped to the range  $[0, level_{immut} - 1]$  and  $level_{max}$  is then clamped to the range  $[level_{base}, level_{immut} - 1]$ , where  $level_{immut}$  is the parameter passed to **TexStorage\*** for the texture object (the value of `TEXTURE_IMMUTABLE_LEVELS`; see section 8.19). If the texture was created with **TextureView**, then the `TEXTURE_BASE_LEVEL` and `TEXTURE_MAX_LEVEL` parameters are interpreted relative to the view and not relative to the original data store.

Texture parameters for a cube map texture apply to the cube map as a whole; the six distinct two-dimensional texture images use the texture parameters of the cube map itself.

### Errors

An `INVALID_ENUM` error is generated if the type of the parameter specified by *pname* is `enum`, and the value(s) specified by *param* or *params* are not among the legal values shown in table 8.16.

An `INVALID_ENUM` error is generated if **TexParameter{if}** is called for a non-scalar parameter (`TEXTURE_BORDER_COLOR` or `TEXTURE_SWIZZLE_RGBA`. ~~or if **TexParameter\*v** is called for a scalar parameter (all other parameters in table 8.16).~~

An `INVALID_ENUM` error is generated if *target* is either `TEXTURE_2D_MULTISAMPLE` or `TEXTURE_2D_MULTISAMPLE_ARRAY`, and *pname* is any sampler state from table 23.18.

An `INVALID_OPERATION` error is generated if *target* is either `TEXTURE_2D_MULTISAMPLE` or `TEXTURE_2D_MULTISAMPLE_ARRAY`, and *pname* `TEXTURE_BASE_LEVEL` is set to a value other than zero.

## 8.11 Texture Queries

### 8.11.0.1 Active Texture

Queries of most texture state variables are qualified by the value of `ACTIVE_TEXTURE` to determine which server texture state vector is queried.

Table 23.12 indicates those state variables which are qualified by `ACTIVE_TEXTURE` during state queries.

The commands

```
void GetTexParameter{if}v( enum target, enum value,
    T data );
void GetTexParameterI{i ui}v( enum target, enum value,
    T data );
```

place information about texture parameter *value* for the specified *target* into *data*. *value* must be `IMAGE_FORMAT_COMPATIBILITY_TYPE`, `TEXTURE_IMMUTABLE_FORMAT`, `TEXTURE_IMMUTABLE_LEVELS`, `TEXTURE_VIEW_MIN_LEVEL`, `TEXTURE_VIEW_NUM_LEVELS`, `TEXTURE_VIEW_MIN_LAYER`, `TEXTURE_VIEW_NUM_LAYERS`, or one of the symbolic values in table 8.16.

*target* may be one of `TEXTURE_1D`, `TEXTURE_2D`, `TEXTURE_3D`, `TEXTURE_1D_ARRAY`, `TEXTURE_2D_ARRAY`, `TEXTURE_RECTANGLE`, `TEXTURE_CUBE_MAP`, `TEXTURE_CUBE_MAP_ARRAY`, `TEXTURE_2D_MULTISAMPLE`, or `TEXTURE_2D_MULTISAMPLE_ARRAY`, indicating the currently bound one-, two-, three-dimensional, one- or two-dimensional array, rectangle, cube map, cube map array, two-dimensional multisample, or two-dimensional multisample array texture object.

Querying *value* `TEXTURE_BORDER_COLOR` with **GetTexParameterIv** or **GetTexParameterIuiv** returns the border color values as signed integers or unsigned integers, respectively; otherwise the values are returned as described in section 2.2.2. If the border color is queried with a type that does not match the original type with which it was specified, the result is undefined.

```
void GetTexLevelParameter{if}v( enum target, int lod,
    enum value, T data );
```

places information about texture image parameter *value* for level-of-detail *lod* of the specified *target* into *data*. *value* must be one of the symbolic values in tables 23.16- 23.17.

*target* may be one of `TEXTURE_1D`, `TEXTURE_2D`, `TEXTURE_3D`, `TEXTURE_1D_ARRAY`, `TEXTURE_2D_ARRAY`, `TEXTURE_CUBE_MAP_ARRAY`, `TEXTURE_RECTANGLE`, one of the cube map face targets from table 8.18, `TEXTURE_2D_MULTISAMPLE`, `TEXTURE_2D_MULTISAMPLE_ARRAY`, `PROXY_TEXTURE_1D`, `PROXY_TEXTURE_2D`, `PROXY_TEXTURE_3D`, `PROXY_TEXTURE_1D_ARRAY`, `PROXY_TEXTURE_2D_ARRAY`, `PROXY_TEXTURE_CUBE_MAP_ARRAY`, `PROXY_TEXTURE_RECTANGLE`, `PROXY_TEXTURE_CUBE_MAP`, `PROXY_TEXTURE_2D_MULTISAMPLE`, or `PROXY_TEXTURE_2D_MULTISAMPLE_ARRAY`, indicating the one-, two-, or three-dimensional texture, one-or two-dimensional array texture, cube map array texture, rectangle texture, one of the six distinct 2D images making up the cube map texture object, two-dimensional multisample

texture, two-dimensional multisample array texture; or the one-, two-, three-dimensional, one-or two-dimensional array, cube map array, rectangle, cube map, two-dimensional multisample, or two-dimensional multisample array proxy state vector.

*target* may also be `TEXTURE_BUFFER`, indicating the texture buffer. In the case *lod* must be zero or an `INVALID_VALUE` error is generated.

Note that `TEXTURE_CUBE_MAP` is not a valid *target* parameter for **GetTexLevelParameter**, because it does not specify a particular cube map face.

*lod* determines which level-of-detail's state is returned. If *lod* is negative or larger than the maximum allowable level-of-detail, then an `INVALID_VALUE` error is generated.

For texture images with uncompressed internal formats, queries of *value* `TEXTURE_RED_TYPE`, `TEXTURE_GREEN_TYPE`, `TEXTURE_BLUE_TYPE`, `TEXTURE_ALPHA_TYPE`, and `TEXTURE_DEPTH_TYPE` return the data type used to store the component. Types `NONE`, `SIGNED_NORMALIZED`, `UNSIGNED_NORMALIZED`, `FLOAT`, `INT`, and `UNSIGNED_INT` respectively indicate missing, signed normalized fixed-point, unsigned normalized fixed-point, floating-point, signed unnormalized integer, and unsigned unnormalized integer components. Queries of *value* `TEXTURE_RED_SIZE`, `TEXTURE_GREEN_SIZE`, `TEXTURE_BLUE_SIZE`, `TEXTURE_ALPHA_SIZE`, `TEXTURE_DEPTH_SIZE`, `TEXTURE_STENCIL_SIZE`, and `TEXTURE_SHARED_SIZE` return the actual resolutions of the stored image array components, not the resolutions specified when the image array was defined.

For texture images with compressed internal formats, the types returned specify how components are interpreted after decompression, while the resolutions returned specify the component resolution of an uncompressed internal format that produces an image of roughly the same quality as the compressed image in question. Since the quality of the implementation's compression algorithm is likely data-dependent, the returned component sizes should be treated only as rough approximations.

Querying *value* `TEXTURE_COMPRESSED_IMAGE_SIZE` returns the size (in `bytes`) of the compressed texture image that would be returned by **GetCompressedTexImage** (section 8.11). An `INVALID_OPERATION` error is generated if *value* is `TEXTURE_COMPRESSED_IMAGE_SIZE` and *target* is a proxy target, or *target* has an uncompressed internal format.

Queries of *value* `TEXTURE_INTERNAL_FORMAT`, `TEXTURE_WIDTH`, `TEXTURE_HEIGHT`, and `TEXTURE_DEPTH` return the internal format, width, height, and depth, respectively, as specified when the image array was created.

The command



```
void GetTexImage( enum tex, int lod, enum format,  
                  enum type, void *img );
```

is used to obtain texture images. It is somewhat different from the other **Get\*** commands; *tex* is a symbolic value indicating which texture (or texture face in the case of a cube map texture target name) is to be obtained. `TEXTURE_1D`, `TEXTURE_2D`, `TEXTURE_3D`, `TEXTURE_1D_ARRAY`, `TEXTURE_2D_ARRAY`, `TEXTURE_CUBE_MAP_ARRAY`, and `TEXTURE_RECTANGLE` indicate a one-, two-, or three-dimensional, one- or two-dimensional array, cube map array, or rectangle texture respectively. If *tex* is one of the targets from table 8.18, it indicates the corresponding face of a cube map texture. *lod* is a level-of-detail number, *format* is a pixel format from table 8.3, *type* is a pixel type from table 8.2.

**GetTexImage** obtains component groups from a texture image with the indicated level-of-detail. If *format* is a color format then the components are assigned among R, G, B, and A according to table 8.17, starting with the first group in the first row, and continuing by obtaining groups in order from each row and proceeding from the first row to the last, and from the first image to the last for three-dimensional textures. One- and two-dimensional array and cube map array textures are treated as two-, three-, and three-dimensional images, respectively, where the layers are treated as rows or images. If *format* is `DEPTH_COMPONENT`, then each depth component is assigned with the same ordering of rows and images. If *format* is `DEPTH_STENCIL`, then each depth component and each stencil index is assigned with the same ordering of rows and images.

These groups are then packed and placed in client or pixel buffer object memory. If a pixel pack buffer is bound (as indicated by a non-zero value of `PIXEL_PACK_BUFFER_BINDING`), *img* is an offset into the pixel pack buffer; otherwise, *img* is a pointer to client memory. Pixel storage modes that are applicable to **ReadPixels** are applied.

For three-dimensional, two-dimensional array, and cube map array textures, pixel storage operations are applied as if the image were two-dimensional, except that the additional pixel storage state values `PACK_IMAGE_HEIGHT` and `PACK_SKIP_IMAGES` are applied. The correspondence of texels to memory locations is as defined for **TexImage3D** in section 8.5.

The row length, number of rows, image depth, and number of images are determined by the size of the texture image (including any borders).

### Errors

An `INVALID_VALUE` error is generated if *lod* is negative or larger than the maximum allowable level.

Base Internal Format	R	G	B	A
RED	$R_i$	0	0	1
RG	$R_i$	$G_i$	0	1
RGB	$R_i$	$G_i$	$B_i$	1
RGBA	$R_i$	$G_i$	$B_i$	$A_i$

Table 8.17: Texture, table, and filter return values.  $R_i$ ,  $G_i$ ,  $B_i$ , and  $A_i$  are components of the internal format that are assigned to pixel values R, G, B, and A. If a requested pixel value is not present in the internal format, the specified constant value is used.

An `INVALID_ENUM` error is generated if *format* is `STENCIL_INDEX`.

An `INVALID_VALUE` error is generated if *lod* is non-zero and *tex* is `TEXTURE_RECTANGLE`.

An `INVALID_OPERATION` error is generated if any of the following mismatches between *format* and the internal format of the texture image exist:

- *format* is a color format (one of the formats in table 8.3 whose target is the color buffer) and the base internal format of the texture image is not a color format.
- *format* is `DEPTH_COMPONENT` and the base internal format is not `DEPTH_COMPONENT` or `DEPTH_STENCIL`.
- *format* is `DEPTH_STENCIL` and the base internal format is not `DEPTH_STENCIL`.
- *format* is one of the integer formats in table 8.3 and the internal format of the texture image is not integer, or *format* is not one of the integer formats in table 8.3 and the internal format is integer.

An `INVALID_OPERATION` error is generated if a pixel pack buffer object is bound and packing the texture image into the buffer's memory would exceed the size of the buffer.

An `INVALID_OPERATION` error is generated if a pixel pack buffer object is bound and *img* is not evenly divisible by the number of basic machine units needed to store in memory the GL data type corresponding to *type* (see table 8.2).

The command

```
void GetCompressedTexImage(enum target, int lod,
```

```
void *img );
```

is used to obtain texture images stored in compressed form. The parameters *target*, *lod*, and *img* are interpreted in the same manner as in **GetTexImage**. When called, **GetCompressedTexImage** writes *n* bytes of compressed image data to the pixel pack buffer or client memory pointed to by *img*, where *n* is the value of `TEXTURE_COMPRESSED_IMAGE_SIZE` for the texture. The compressed image data is formatted according to the definition of the texture's internal format.

By default the pixel storage modes `PACK_ROW_LENGTH`, `PACK_SKIP_ROWS`, `PACK_SKIP_PIXELS`, `PACK_IMAGE_HEIGHT` and `PACK_SKIP_IMAGES` are ignored for compressed images. To enable `PACK_SKIP_PIXELS` and `PACK_ROW_LENGTH`, the values of `PACK_COMPRESSED_BLOCK_SIZE` and `PACK_COMPRESSED_BLOCK_WIDTH` must both be non-zero. To also enable `PACK_SKIP_ROWS` and `PACK_IMAGE_HEIGHT`, the value of `PACK_COMPRESSED_BLOCK_HEIGHT` must be non-zero. And to also enable `PACK_SKIP_IMAGES`, the value of `PACK_COMPRESSED_BLOCK_DEPTH` must be non-zero. All parameters must be consistent with the compressed format to produce the desired results. When the pixel storage modes are active, the correspondence of texels to memory locations is as defined for **CompressedTexImage3D** in section 8.7.

### Errors

An `INVALID_VALUE` error is generated if *lod* is negative, or greater than the maximum allowable level.

An `INVALID_OPERATION` error is generated if the texture image is stored with an uncompressed internal format.

An `INVALID_OPERATION` error is generated if a pixel pack buffer object is bound and  $img + n$  is greater than the size of the buffer.

## 8.12 Depth Component Textures

Depth textures and the depth components of depth/stencil textures can be treated as `RED` textures during texture filtering and application (see section 8.22). The initial state for depth and depth/stencil textures treats them as `RED` textures.

## 8.13 Cube Map Texture Selection

When cube map texturing is enabled, the  $(s \ t \ r)$  texture coordinates are treated as a direction vector  $(r_x \ r_y \ r_z)$  emanating from the center of a cube. The *q*

Major Axis Direction	Target	$s_c$	$t_c$	$m_a$
$+r_x$	TEXTURE_CUBE_MAP_POSITIVE_X	$-r_z$	$-r_y$	$r_x$
$-r_x$	TEXTURE_CUBE_MAP_NEGATIVE_X	$r_z$	$-r_y$	$r_x$
$+r_y$	TEXTURE_CUBE_MAP_POSITIVE_Y	$r_x$	$r_z$	$r_y$
$-r_y$	TEXTURE_CUBE_MAP_NEGATIVE_Y	$r_x$	$-r_z$	$r_y$
$+r_z$	TEXTURE_CUBE_MAP_POSITIVE_Z	$r_x$	$-r_y$	$r_z$
$-r_z$	TEXTURE_CUBE_MAP_NEGATIVE_Z	$-r_x$	$-r_y$	$r_z$

Table 8.18: Selection of cube map images based on major axis direction of texture coordinates.

coordinate is ignored. At texture application time, the interpolated per-fragment direction vector selects one of the cube map face’s two-dimensional images based on the largest magnitude coordinate direction (the major axis direction). If two or more coordinates have the identical magnitude, the implementation may define the rule to disambiguate this situation. The rule must be deterministic and depend only on  $(r_x \ r_y \ r_z)$ . The target column in table 8.18 explains how the major axis direction maps to the two-dimensional image of a particular cube map target.

Using the  $s_c$ ,  $t_c$ , and  $m_a$  determined by the major axis direction as specified in table 8.18, an updated  $(s \ t)$  is calculated as follows:

$$s = \frac{1}{2} \left( \frac{s_c}{|m_a|} + 1 \right)$$

$$t = \frac{1}{2} \left( \frac{t_c}{|m_a|} + 1 \right)$$

### 8.13.1 Seamless Cube Map Filtering

Seamless cube map filtering is enabled or disabled by calling **Enable** or **Disable**, respectively, with the symbolic constant `TEXTURE_CUBE_MAP_SEAMLESS`.

When seamless cube map filtering is disabled, the new  $(s \ t)$  is used to find a texture value in the determined face’s two-dimensional image using the rules given in sections 8.14 through 8.15.

When seamless cube map filtering is enabled, the rules for texel selection in sections 8.14 through 8.15 are modified so that texture wrap modes are ignored. Instead,

- If `NEAREST` filtering is done within a miplevel, always apply wrap mode `CLAMP_TO_EDGE`.

- If `LINEAR` filtering is done within a mipmap level, always apply wrap mode `CLAMP_TO_BORDER`. Then,
  - If a texture sample location would lie in the texture border in either  $u$  or  $v$ , instead select the corresponding texel from the appropriate neighboring face.
  - If a texture sample location would lie in the texture border in *both*  $u$  and  $v$  (in one of the corners of the cube), there is no unique neighboring face from which to extract one texel. The recommended method to generate this texel is to average the values of the three available samples. However, implementations are free to construct this fourth texel in another way, so long as, when the three available samples have the same value, this texel also has that value.

The required state is one bit indicating whether seamless cube map filtering is enabled or disabled. Initially, it is disabled.

## 8.14 Texture Minification

Applying a texture to a primitive implies a mapping from texture image space to framebuffer image space. In general, this mapping involves a reconstruction of the sampled texture image, followed by a homogeneous warping implied by the mapping to framebuffer space, then a filtering, followed finally by a resampling of the filtered, warped, reconstructed image before applying it to a fragment. In the GL this mapping is approximated by one of two simple filtering schemes. One of these schemes is selected based on whether the mapping from texture space to framebuffer space is deemed to *magnify* or *minify* the texture image.

### 8.14.1 Scale Factor and Level of Detail

The choice is governed by a scale factor  $\rho(x, y)$  and the *level-of-detail* parameter  $\lambda(x, y)$ , defined as

$$\lambda_{base}(x, y) = \log_2[\rho(x, y)] \quad (8.4)$$

$$\lambda'(x, y) = \lambda_{base}(x, y) + \text{clamp}(\text{bias}_{texobj} + \text{bias}_{shader}) \quad (8.5)$$

$$\lambda = \begin{cases} lod_{max}, & \lambda' > lod_{max} \\ \lambda', & lod_{min} \leq \lambda' \leq lod_{max} \\ lod_{min}, & \lambda' < lod_{min} \\ undefined, & lod_{min} > lod_{max} \end{cases} \quad (8.6)$$

$bias_{texobj}$  is the value of `TEXTURE_LOD_BIAS` for the bound texture object (as described in section 8.10).  $bias_{shader}$  is the value of the optional bias parameter in the texture lookup functions available to fragment shaders. If the texture access is performed in a fragment shader without a provided bias, or outside a fragment shader, then  $bias_{shader}$  is zero. The sum of these values is clamped to the range  $[-bias_{max}, bias_{max}]$  where  $bias_{max}$  is the value of the implementation defined constant `MAX_TEXTURE_LOD_BIAS`.

If  $\lambda(x, y)$  is less than or equal to the constant  $c$  (see section 8.15) the texture is said to be magnified; if it is greater, the texture is minified. Sampling of minified textures is described in the remainder of this section, while sampling of magnified textures is described in section 8.15.

The initial values of  $lod_{min}$  and  $lod_{max}$  are chosen so as to never clamp the normal range of  $\lambda$ . They may be respecified for a specific texture by calling **TexParameter\*** with *pname* set to `TEXTURE_MIN_LOD` or `TEXTURE_MAX_LOD` respectively.

Let  $s(x, y)$  be the function that associates an  $s$  texture coordinate with each set of window coordinates  $(x, y)$  that lie within a primitive; define  $t(x, y)$  and  $r(x, y)$  analogously. Let

$$\begin{aligned} u(x, y) &= \begin{cases} s(x, y) + \delta_u, & \text{rectangle texture} \\ w_t \times s(x, y) + \delta_u, & \text{otherwise} \end{cases} \\ v(x, y) &= \begin{cases} t(x, y) + \delta_v, & \text{rectangle texture} \\ h_t \times t(x, y) + \delta_v, & \text{otherwise} \end{cases} \\ w(x, y) &= d_t \times r(x, y) + \delta_w \end{aligned} \quad (8.7)$$

where  $w_t$ ,  $h_t$ , and  $d_t$  are as defined by equation 8.3 with  $w_s$ ,  $h_s$ , and  $d_s$  equal to the width, height, and depth of the image array whose level is  $level_{base}$ . For a one-dimensional or one-dimensional array texture, define  $v(x, y) = 0$  and  $w(x, y) = 0$ ; for a two-dimensional, two-dimensional array, rectangle, cube map, or cube map array texture, define  $w(x, y) = 0$ .

$(\delta_u, \delta_v, \delta_w)$  are the texel offsets specified in the OpenGL Shading Language texture lookup functions that support offsets. If the texture function used does not support offsets, all three shader offsets are taken to be zero.

If the value of any non-ignored component of the offset vector operand is outside implementation-dependent limits, the results of the texture lookup are undefined. For all instructions except `textureGather`, the limits are the values of `MIN_PROGRAM_TEXEL_OFFSET` and `MAX_PROGRAM_TEXEL_OFFSET`. For the `textureGather` instruction, the limits are the values of `MIN_PROGRAM_TEXTURE_GATHER_OFFSET` and `MAX_PROGRAM_TEXTURE_GATHER_OFFSET`.

For a polygon or point,  $\rho$  is given at a fragment with window coordinates  $(x, y)$  by

$$\rho = \max \left\{ \sqrt{\left(\frac{\partial u}{\partial x}\right)^2 + \left(\frac{\partial v}{\partial x}\right)^2 + \left(\frac{\partial w}{\partial x}\right)^2}, \sqrt{\left(\frac{\partial u}{\partial y}\right)^2 + \left(\frac{\partial v}{\partial y}\right)^2 + \left(\frac{\partial w}{\partial y}\right)^2} \right\} \quad (8.8)$$

where  $\partial u/\partial x$  indicates the derivative of  $u$  with respect to window  $x$ , and similarly for the other derivatives.

For a line, the formula is

$$\rho = \sqrt{\left(\frac{\partial u}{\partial x}\Delta x + \frac{\partial u}{\partial y}\Delta y\right)^2 + \left(\frac{\partial v}{\partial x}\Delta x + \frac{\partial v}{\partial y}\Delta y\right)^2 + \left(\frac{\partial w}{\partial x}\Delta x + \frac{\partial w}{\partial y}\Delta y\right)^2} / l, \quad (8.9)$$

where  $\Delta x = x_2 - x_1$  and  $\Delta y = y_2 - y_1$  with  $(x_1, y_1)$  and  $(x_2, y_2)$  being the segment's window coordinate endpoints and  $l = \sqrt{\Delta x^2 + \Delta y^2}$ .

While it is generally agreed that equations 8.8 and 8.9 give the best results when texturing, they are often impractical to implement. Therefore, an implementation may approximate the ideal  $\rho$  with a function  $f(x, y)$  subject to these conditions:

1.  $f(x, y)$  is continuous and monotonically increasing in each of  $|\partial u/\partial x|$ ,  $|\partial u/\partial y|$ ,  $|\partial v/\partial x|$ ,  $|\partial v/\partial y|$ ,  $|\partial w/\partial x|$ , and  $|\partial w/\partial y|$
2. Let

$$m_u = \max \left\{ \left| \frac{\partial u}{\partial x} \right|, \left| \frac{\partial u}{\partial y} \right| \right\}$$

$$m_v = \max \left\{ \left| \frac{\partial v}{\partial x} \right|, \left| \frac{\partial v}{\partial y} \right| \right\}$$

$$m_w = \max \left\{ \left| \frac{\partial w}{\partial x} \right|, \left| \frac{\partial w}{\partial y} \right| \right\}.$$

Then  $\max\{m_u, m_v, m_w\} \leq f(x, y) \leq m_u + m_v + m_w$ .

### 8.14.2 Coordinate Wrapping and Texel Selection

After generating  $u(x, y)$ ,  $v(x, y)$ , and  $w(x, y)$ , they may be clamped and wrapped before sampling the texture, depending on the corresponding texture wrap modes.

Let  $u'(x, y) = u(x, y)$ ,  $v'(x, y) = v(x, y)$ , and  $w'(x, y) = w(x, y)$ .

The value assigned to `TEXTURE_MIN_FILTER` is used to determine how the texture value for a fragment is selected.

When the value of `TEXTURE_MIN_FILTER` is `NEAREST`, the texel in the image array of level  $level_{base}$  that is nearest (in Manhattan distance) to  $(u', v', w')$  is obtained. Let  $(i, j, k)$  be integers such that

$$\begin{aligned} i &= \text{wrap}(\lfloor u'(x, y) \rfloor) \\ j &= \text{wrap}(\lfloor v'(x, y) \rfloor) \\ k &= \text{wrap}(\lfloor w'(x, y) \rfloor) \end{aligned}$$

and the value returned by  $\text{wrap}()$  is defined in table 8.19. For a three-dimensional texture, the texel at location  $(i, j, k)$  becomes the texture value. For two-dimensional, two-dimensional array, rectangle, or cube map textures,  $k$  is irrelevant, and the texel at location  $(i, j)$  becomes the texture value. For one-dimensional texture or one-dimensional array textures,  $j$  and  $k$  are irrelevant, and the texel at location  $i$  becomes the texture value.

For one- and two-dimensional array textures, the texel is obtained from image layer  $l$ , where

$$l = \begin{cases} \text{clamp}(\lfloor t + 0.5 \rfloor, 0, h_t - 1), & \text{for one-dimensional array textures} \\ \text{clamp}(\lfloor r + 0.5 \rfloor, 0, d_t - 1), & \text{for two-dimensional array textures} \end{cases}$$

If the selected  $(i, j, k)$ ,  $(i, j)$ , or  $i$  location refers to a border texel that satisfies any of the conditions

$$\begin{aligned} i < -b_s & & i \geq w_t + b_s \\ j < -b_s & & j \geq h_t + b_s \\ k < -b_s & & k \geq d_t + b_s \end{aligned}$$

then the border values defined by `TEXTURE_BORDER_COLOR` are used in place of the non-existent texel. If the texture contains color components, the values of `TEXTURE_BORDER_COLOR` are interpreted as an RGBA color to match the texture's internal format in a manner consistent with table 8.11. The internal data type of the



Wrap mode	Result of $wrap(coord)$
CLAMP_TO_EDGE	$clamp(coord, 0, size - 1)$
CLAMP_TO_BORDER	$clamp(coord, -1, size)$
REPEAT	$fmod(coord, size)$
MIRRORED_REPEAT	$(size - 1) - mirror(fmod(coord, 2 \times size) - size)$

Table 8.19: Texel location wrap mode application.  $fmod(a, b)$  returns  $a - b \times \lfloor \frac{a}{b} \rfloor$ .  $mirror(a)$  returns  $a$  if  $a \geq 0$ , and  $-(1 + a)$  otherwise. The values of  $mode$  and  $size$  are `TEXTURE_WRAP_S` and  $w_t$ , `TEXTURE_WRAP_T` and  $h_t$ , and `TEXTURE_WRAP_R` and  $d_t$  when wrapping  $i$ ,  $j$ , or  $k$  coordinates, respectively.

border values must be consistent with the type returned by the texture as described in chapter 8, or the result is undefined. Border values are clamped before they are used, according to the format in which texture components are stored. For signed and unsigned normalized fixed-point formats, border values are clamped to  $[-1, 1]$  and  $[0, 1]$ , respectively. For floating-point and integer formats, border values are clamped to the representable range of the format. If the texture contains depth components, the first component of `TEXTURE_BORDER_COLOR` is interpreted as a depth value.

When the value of `TEXTURE_MIN_FILTER` is `LINEAR`, a  $2 \times 2 \times 2$  cube of texels in the image array of level  $level_{base}$  is selected. Let

$$\begin{aligned}
 i_0 &= wrap(\lfloor u' - 0.5 \rfloor) \\
 j_0 &= wrap(\lfloor v' - 0.5 \rfloor) \\
 k_0 &= wrap(\lfloor w' - 0.5 \rfloor) \\
 i_1 &= wrap(\lfloor u' - 0.5 \rfloor + 1) \\
 j_1 &= wrap(\lfloor v' - 0.5 \rfloor + 1) \\
 k_1 &= wrap(\lfloor w' - 0.5 \rfloor + 1) \\
 \alpha &= frac(u' - 0.5) \\
 \beta &= frac(v' - 0.5) \\
 \gamma &= frac(w' - 0.5)
 \end{aligned}$$

where  $frac(x)$  denotes the fractional part of  $x$ .

For a three-dimensional texture, the texture value  $\tau$  is found as

$$\begin{aligned} \tau = & (1 - \alpha)(1 - \beta)(1 - \gamma)\tau_{i_0j_0k_0} + \alpha(1 - \beta)(1 - \gamma)\tau_{i_1j_0k_0} \\ & + (1 - \alpha)\beta(1 - \gamma)\tau_{i_0j_1k_0} + \alpha\beta(1 - \gamma)\tau_{i_1j_1k_0} \\ & + (1 - \alpha)(1 - \beta)\gamma\tau_{i_0j_0k_1} + \alpha(1 - \beta)\gamma\tau_{i_1j_0k_1} \\ & + (1 - \alpha)\beta\gamma\tau_{i_0j_1k_1} + \alpha\beta\gamma\tau_{i_1j_1k_1} \end{aligned} \quad (8.10)$$

where  $\tau_{ijk}$  is the texel at location  $(i, j, k)$  in the three-dimensional texture image.

For a two-dimensional, two-dimensional array, rectangle, or cube map texture,

$$\begin{aligned} \tau = & (1 - \alpha)(1 - \beta)\tau_{i_0j_0} + \alpha(1 - \beta)\tau_{i_1j_0} \\ & + (1 - \alpha)\beta\tau_{i_0j_1} + \alpha\beta\tau_{i_1j_1} \end{aligned}$$

where  $\tau_{ij}$  is the texel at location  $(i, j)$  in the two-dimensional texture image. For two-dimensional array textures, all texels are obtained from layer  $l$ , where

$$l = \text{clamp}(\lfloor r + 0.5 \rfloor, 0, d_t - 1).$$

The `textureGather` and `textureGatherOffset` built-in shader functions return a vector derived from sampling a  $2 \times 2$  block of texels in the image array of level `levelbase`. The rules for the `LINEAR` minification filter are applied to identify the four selected texels. Each texel is then converted to a texture source color  $(R_s, G_s, B_s, A_s)$  according to table 15.1 and then swizzled as described in section 15.2.1. A four-component vector is then assembled by taking the  $R_s$  component from the swizzled texture source colors of the four texels, in the order  $\tau_{i_0j_1}$ ,  $\tau_{i_1j_1}$ ,  $\tau_{i_1j_0}$ , and  $\tau_{i_0j_0}$  (see figure 8.4). Incomplete textures (see section 8.17) are considered to return a texture source color of  $(0, 0, 0, 1)$  for all four source texels.

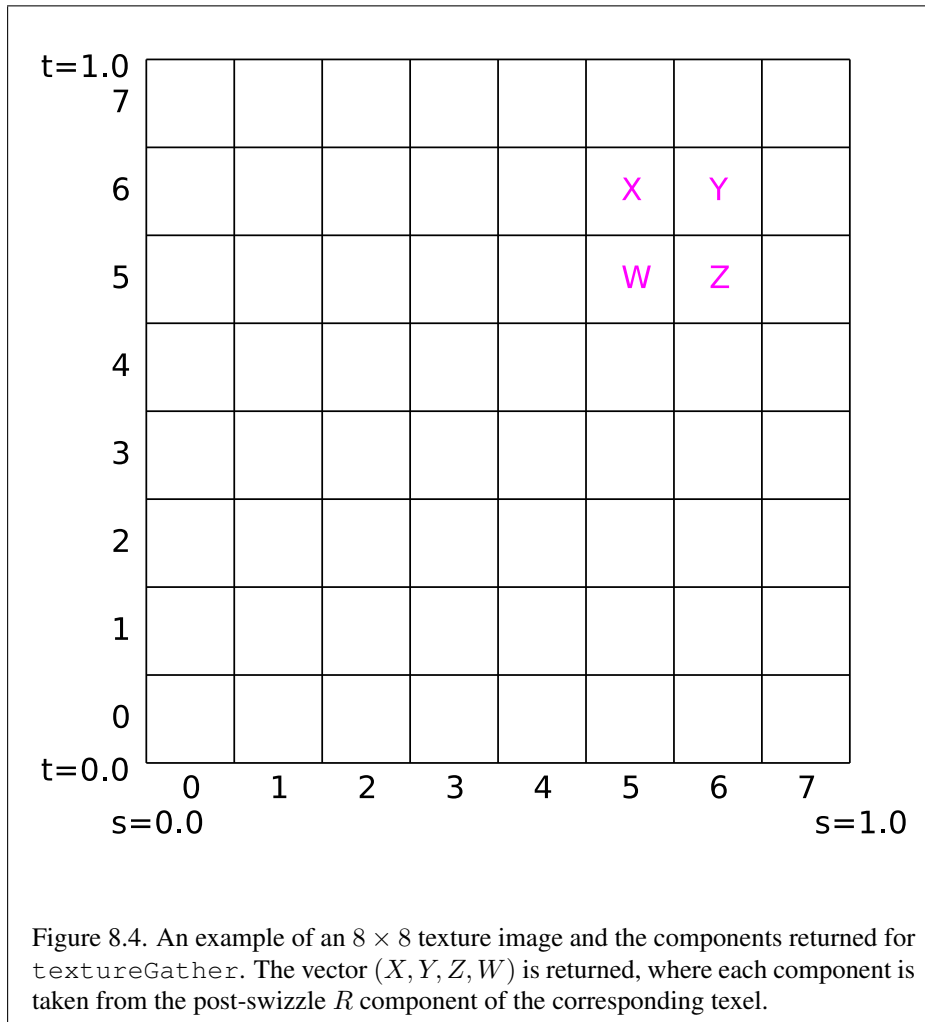
And for a one-dimensional or one-dimensional array texture,

$$\tau = (1 - \alpha)\tau_{i_0} + \alpha\tau_{i_1}$$

where  $\tau_i$  is the texel at location  $i$  in the one-dimensional texture. For one-dimensional array textures, both texels are obtained from layer  $l$ , where

$$l = \text{clamp}(\lfloor t + 0.5 \rfloor, 0, h_t - 1).$$

For any texel in the equation above that refers to a border texel outside the defined range of the image, the texel value is taken from the texture border color as with `NEAREST` filtering.



### 8.14.2.1 Rendering Feedback Loops

If all of the following conditions are satisfied, then the value of the selected  $\tau_{ijk}$ ,  $\tau_{ij}$ , or  $\tau_i$  in the above equations is undefined instead of referring to the value of the texel at location  $(i, j, k)$ ,  $(i, j)$ , or  $(i)$  respectively. This situation is discussed in more detail in the description of feedback loops in section 9.3.1.

- The current `DRAW_FRAMEBUFFER_BINDING` names a framebuffer object  $F$ .
- The texture is attached to one of the attachment points,  $A$ , of framebuffer object  $F$ .
- The value of `TEXTURE_MIN_FILTER` is `NEAREST` or `LINEAR`, and the value of `FRAMEBUFFER_ATTACHMENT_TEXTURE_LEVEL` for attachment point  $A$  is equal to  $level_{base}$

-or-

The value of `TEXTURE_MIN_FILTER` is `NEAREST_MIPMAP_NEAREST`, `NEAREST_MIPMAP_LINEAR`, `LINEAR_MIPMAP_NEAREST`, or `LINEAR_MIPMAP_LINEAR`, and the value of `FRAMEBUFFER_ATTACHMENT_TEXTURE_LEVEL` for attachment point  $A$  is within the inclusive range from  $level_{base}$  to  $q$ .

### 8.14.3 Mipmapping

`TEXTURE_MIN_FILTER` values `NEAREST_MIPMAP_NEAREST`, `NEAREST_MIPMAP_LINEAR`, `LINEAR_MIPMAP_NEAREST`, and `LINEAR_MIPMAP_LINEAR` each require the use of a *mipmap*. Rectangle textures do not support mipmapping (it is an error to specify a minification filter that requires mipmapping). A mipmap is an ordered set of arrays representing the same image; each array has a resolution lower than the previous one. If the image array of level  $level_{base}$  has dimensions  $w_t \times h_t \times d_t$ , then there are  $\lfloor \log_2(maxsize) \rfloor + 1$  levels in the mipmap. where

$$maxsize = \begin{cases} w_t, & \text{for 1D and 1D array textures} \\ \max(w_t, h_t), & \text{for 2D, 2D array, cube map, and cube map array textures} \\ \max(w_t, h_t, d_t), & \text{for 3D textures} \end{cases}$$

Numbering the levels such that level  $level_{base}$  is the 0th level, the  $i$ th array has dimensions

$$\max(1, \lfloor \frac{w_t}{w_d} \rfloor) \times \max(1, \lfloor \frac{h_t}{h_d} \rfloor) \times \max(1, \lfloor \frac{d_t}{d_d} \rfloor)$$

where

$$\begin{aligned} w_d &= 2^i \\ h_d &= \begin{cases} 1, & \text{for 1D and 1D array textures} \\ 2^i, & \text{otherwise} \end{cases} \\ d_d &= \begin{cases} 2^i, & \text{for 3D textures} \\ 1, & \text{otherwise} \end{cases} \end{aligned}$$

until the last array is reached with dimension  $1 \times 1 \times 1$ .

Each array in a mipmap is defined using **TexImage3D**, **TexImage2D**, **CopyTexImage2D**, **TexImage1D**, or **CopyTexImage1D** or by functions that are defined in terms of these functions. The array being set is indicated with the level-of-detail argument *level*. Level-of-detail numbers proceed from  $level_{base}$  for the original texel array through the maximum level  $p$ , with each unit increase indicating an array of half the dimensions of the previous one (rounded down to the next integer if fractional) as already described. For immutable-format textures,  $p$  is one less than the *levels* parameter passed to **TexStorage\***; otherwise  $p = \lfloor \log_2(maxsize) \rfloor + level_{base}$ . All arrays from  $level_{base}$  through  $q = \min\{p, level_{max}\}$  must be defined, as discussed in section 8.17.

The values of  $level_{base}$  and  $level_{max}$  may be respecified for a specific texture by calling **TexParameter\*** with *pname* set to `TEXTURE_BASE_LEVEL` or `TEXTURE_MAX_LEVEL` respectively.

An `INVALID_VALUE` error is generated by **TexParameter\*** if either value is negative.

The mipmap is used in conjunction with the level of detail to approximate the application of an appropriately filtered texture to a fragment. Let  $c$  be the value of  $\lambda$  at which the transition from minification to magnification occurs (since this discussion pertains to minification, we are concerned only with values of  $\lambda$  where  $\lambda > c$ ).

For mipmap filters `NEAREST_MIPMAP_NEAREST` and `LINEAR_MIPMAP_NEAREST`, the  $d$ th mipmap array is selected, where

$$d = \begin{cases} level_{base}, & \lambda \leq \frac{1}{2} \\ \lceil level_{base} + \lambda + \frac{1}{2} \rceil - 1, & \lambda > \frac{1}{2}, level_{base} + \lambda \leq q + \frac{1}{2} \\ q, & \lambda > \frac{1}{2}, level_{base} + \lambda > q + \frac{1}{2} \end{cases} \quad (8.11)$$

The rules for NEAREST or LINEAR filtering are then applied to the selected array. Specifically, the coordinate  $(u, v, w)$  is computed as in equation 8.7, with  $w_s, h_s,$  and  $d_s$  equal to the width, height, and depth of the image array whose level is  $d$ .

For mipmap filters NEAREST\_MIPMAP\_LINEAR and LINEAR\_MIPMAP\_LINEAR, the level  $d_1$  and  $d_2$  mipmap arrays are selected, where

$$d_1 = \begin{cases} q, & level_{base} + \lambda \geq q \\ \lfloor level_{base} + \lambda \rfloor, & \text{otherwise} \end{cases} \quad (8.12)$$

$$d_2 = \begin{cases} q, & level_{base} + \lambda \geq q \\ d_1 + 1, & \text{otherwise} \end{cases} \quad (8.13)$$

The rules for NEAREST or LINEAR filtering are then applied to each of the selected arrays, yielding two corresponding texture values  $\tau_1$  and  $\tau_2$ . Specifically, for level  $d_1$ , the coordinate  $(u, v, w)$  is computed as in equation 8.7, with  $w_s, h_s,$  and  $d_s$  equal to the width, height, and depth of the image array whose level is  $d_1$ . For level  $d_2$  the coordinate  $(u', v', w')$  is computed as in equation 8.7, with  $w_s, h_s,$  and  $d_s$  equal to the width, height, and depth of the image array whose level is  $d_2$ .

The final texture value is then found as

$$\tau = [1 - \text{frac}(\lambda)]\tau_1 + \text{frac}(\lambda)\tau_2.$$

#### 8.14.4 Manual Mipmap Generation

Mipmaps can be generated manually with the command

```
void GenerateMipmap( enum target );
```

where *target* is one of TEXTURE\_1D, TEXTURE\_2D, TEXTURE\_3D, TEXTURE\_1D\_ARRAY, TEXTURE\_2D\_ARRAY, TEXTURE\_CUBE\_MAP, or TEXTURE\_CUBE\_MAP\_ARRAY.

Mipmap generation affects the texture image attached to *target*.

If *target* is TEXTURE\_CUBE\_MAP or TEXTURE\_CUBE\_MAP\_ARRAY, the texture bound to *target* must be cube complete or cube array complete respectively, as defined in section 8.17.

Mipmap generation replaces texel array levels  $level_{base} + 1$  through  $q$  with arrays derived from the  $level_{base}$  array, regardless of their previous contents. All other mipmap arrays, including the  $level_{base}$  array, are left unchanged by this computation.

The internal formats of the derived mipmap arrays all match those of the  $level_{base}$  array, and the dimensions of the derived arrays follow the requirements described in section 8.17.

The contents of the derived arrays are computed by repeated, filtered reduction of the  $level_{base}$  array. For one- and two-dimensional array and cube map array textures, each layer is filtered independently. No particular filter algorithm is required, though a box filter is recommended as the default filter.

#### Errors

An `INVALID_ENUM` error is generated if *target* is not `TEXTURE_1D`, `TEXTURE_2D`, `TEXTURE_3D`, `TEXTURE_1D_ARRAY`, `TEXTURE_2D_ARRAY`, `TEXTURE_CUBE_MAP`, or `TEXTURE_CUBE_MAP_ARRAY`.

An `INVALID_OPERATION` error is generated if *target* is `TEXTURE_CUBE_MAP` or `TEXTURE_CUBE_MAP_ARRAY`, and the texture bound to *target* is not cube complete or cube array complete respectively.

#### 8.14.5 Automatic Mipmap Generation

This subsection is only defined in the compatibility profile.

### 8.15 Texture Magnification

When  $\lambda$  indicates magnification, the value assigned to `TEXTURE_MAG_FILTER` determines how the texture value is obtained. There are two possible values for `TEXTURE_MAG_FILTER`: `NEAREST` and `LINEAR`. `NEAREST` behaves exactly as `NEAREST` for `TEXTURE_MIN_FILTER` and `LINEAR` behaves exactly as `LINEAR` for `TEXTURE_MIN_FILTER` as described in section 8.14, including the texture coordinate wrap modes specified in table 8.19. The level-of-detail  $level_{base}$  texel array is always used for magnification.

Implementations may either unconditionally assume  $c = 0$  for the minification vs. magnification switch-over point, or may choose to make  $c$  depend on the combination of minification and magnification modes as follows: if the magnification filter is given by `LINEAR` and the minification filter is given by `NEAREST_MIPMAP_NEAREST` or `NEAREST_MIPMAP_LINEAR`, then  $c = 0.5$ . This is done to ensure that a minified texture does not appear *sharper* than a magnified texture. Otherwise  $c = 0$ .

## 8.16 Combined Depth/Stencil Textures

If the texture image has a base internal format of `DEPTH_STENCIL`, then the stencil index texture component is ignored by default. The texture value  $\tau$  does not include a stencil index component, but includes only the depth component.

In order to access the stencil index texture component the `DEPTH_STENCIL_TEXTURE_MODE` texture parameter should be set to `STENCIL_INDEX`. When this mode is set the depth component is ignored and the texture value includes only the stencil index component. The stencil index value is treated as an unsigned integer texture and returns an unsigned integer value when sampled. When sampling the stencil index only `NEAREST` filtering is supported. The `DEPTH_STENCIL_TEXTURE_MODE` is ignored for non depth/stencil textures.

## 8.17 Texture Completeness

A texture is said to be *complete* if all the image arrays and texture parameters required to utilize the texture for texture application are consistently defined. The definition of completeness varies depending on texture dimensionality and type.

For one-, two-, and three-dimensional and one-and two-dimensional array textures, a texture is *mipmap complete* if all of the following conditions hold true:

- The set of mipmap arrays  $level_{base}$  through  $q$  (where  $q$  is defined in section 8.14.3) were each specified with the same internal format.
- The dimensions of the arrays follow the sequence described in the **Mipmapping** discussion of section 8.14.
- $level_{base} \leq level_{max}$

Array levels  $k$  where  $k < level_{base}$  or  $k > q$  are insignificant to the definition of completeness.

A cube map texture is mipmap complete if each of the six texture images, considered individually, is mipmap complete. Additionally, a cube map texture is *cube complete* if the following conditions all hold true:

- The  $level_{base}$  arrays of each of the six texture images making up the cube map have identical, positive, and square dimensions.
- The  $level_{base}$  arrays were each specified with the same internal format.



A cube map array texture is *cube array complete* if it is complete when treated as a two-dimensional array and cube complete for every cube map slice within the array texture.

Using the preceding definitions, a texture is complete unless any of the following conditions hold true:

- Any dimension of the  $level_{base}$  array is not positive. For a rectangle or multisample texture,  $level_{base}$  is always zero.
- The texture is a cube map texture, and is not cube complete.
- The texture is a cube map array texture, and is not cube array complete.
- The minification filter requires a mipmap (is neither NEAREST nor LINEAR), and the texture is not mipmap complete.
- The internal format of the texture arrays is integer (see table 8.12), and either the magnification filter is not NEAREST, or the minification filter is neither NEAREST nor NEAREST\_MIPMAP\_NEAREST.
- The internal format of the texture is DEPTH\_STENCIL, the DEPTH\_STENCIL\_TEXTURE\_MODE for the texture is STENCIL\_INDEX and either the magnification filter or the minification filter is not NEAREST.

### 8.17.1 Effects of Sampler Objects on Texture Completeness

If a sampler object and a texture object are simultaneously bound to the same texture unit, then the sampling state for that unit is taken from the sampler object (see section 8.2). This can have an effect on the effective completeness of the texture. In particular, if the texture is not mipmap complete and the sampler object specifies a TEXTURE\_MIN\_FILTER requiring mipmaps, the texture will be considered incomplete for the purposes of that texture unit. However, if the sampler object does not require mipmaps, the texture object will be considered complete. This means that a texture can be considered both complete and incomplete simultaneously if it is bound to two or more texture units along with sampler objects with different states.

### 8.17.2 Effects of Completeness on Texture Application

Texture lookup and texture fetch operations performed in shaders are affected by completeness of the texture being sampled as described in sections 11.1.3.5 and 15.2.1.

### 8.17.3 Effects of Completeness on Texture Image Specification

The implementation-dependent maximum sizes for texture image arrays depend on the texture level. In particular, an implementation may allow a texture image array of level 1 or greater to be created only if a mipmap complete set of image arrays consistent with the requested array can be supported where the values of `TEXTURE_BASE_LEVEL` and `TEXTURE_MAX_LEVEL` are 0 and 1000 respectively. As a result, implementations may permit a texture image array at level zero that will never be mipmap complete and can only be used with non-mipmapped minification filters.

## 8.18 Texture Views

A texture can be created which references the data store of another texture and interprets the data with a different format, and/or selects a subset of the levels and/or layers of the other texture. The data store for such a texture is shared with the data store of the original texture. Updating the shared data store using the original texture affects texture values read using the new texture, and vice versa. A texture data store remains in existence until all textures that reference it are deleted.

The command

```
void TextureView( uint texture, enum target,  
                  uint origtexture, enum internalformat, uint minlevel,  
                  uint numlevels, uint minlayer, uint numlayers );
```

initializes the texture named *texture* to the target specified by *target*. *texture*'s data store is inherited from the texture named *origtexture*, but elements of the data store are interpreted according to the internal format specified by *internalformat*. Additionally, if *origtexture* is an array or has multiple mipmap levels, the parameters *minlayer*, *numlayers*, *minlevel*, and *numlevels* control which of those slices and levels are considered part of the texture.

The *minlevel* and *minlayer* parameters are relative to the view of *origtexture*. If *numlayers* or *numlevels* extend beyond *origtexture*, they are clamped to the maximum extent of the original texture.

If the command is successful, the texture parameters in *texture* are updated as follows:

- `TEXTURE_IMMUTABLE_FORMAT` is set to `TRUE`.
- `TEXTURE_IMMUTABLE_LEVELS` is set to the value of `TEXTURE_IMMUTABLE_LEVELS` for *origtexture*.

Original target	Valid new targets
TEXTURE_1D	TEXTURE_1D, TEXTURE_1D_ARRAY
TEXTURE_2D	TEXTURE_2D, TEXTURE_2D_ARRAY
TEXTURE_3D	TEXTURE_3D
TEXTURE_CUBE_MAP	TEXTURE_CUBE_MAP, TEXTURE_2D, TEXTURE_2D_ARRAY, TEXTURE_CUBE_ MAP_ARRAY
TEXTURE_RECTANGLE	TEXTURE_RECTANGLE
TEXTURE_BUFFER	<i>none</i>
TEXTURE_1D_ARRAY	TEXTURE_1D_ARRAY, TEXTURE_1D
TEXTURE_2D_ARRAY	TEXTURE_2D_ARRAY, TEXTURE_2D, TEXTURE_CUBE_MAP, TEXTURE_CUBE_ MAP_ARRAY
TEXTURE_CUBE_MAP_ARRAY	TEXTURE_CUBE_MAP_ARRAY, TEXTURE_2D_ ARRAY, TEXTURE_2D, TEXTURE_CUBE_MAP
TEXTURE_2D_MULTISAMPLE	TEXTURE_2D_MULTISAMPLE, TEXTURE_2D_ MULTISAMPLE_ARRAY
TEXTURE_2D_MULTISAMPLE_ARRAY	TEXTURE_2D_MULTISAMPLE, TEXTURE_2D_ MULTISAMPLE_ARRAY

Table 8.20: Legal texture targets for **TextureView**.

- TEXTURE\_VIEW\_MIN\_LEVEL is set to *minlevel* plus the value of TEXTURE\_VIEW\_MIN\_LEVEL for *origtexture*.
- TEXTURE\_VIEW\_MIN\_LAYER is set to *minlayer* plus the value of TEXTURE\_VIEW\_MIN\_LAYER for *origtexture*.
- TEXTURE\_VIEW\_NUM\_LEVELS is set to the lesser of *numlevels* and the value of TEXTURE\_VIEW\_NUM\_LEVELS for *origtexture* minus *minlevels*.
- TEXTURE\_VIEW\_NUM\_LAYERS is set to the lesser of *numlayers* and the value of TEXTURE\_VIEW\_NUM\_LAYERS for *origtexture* minus *minlayer*.

The new texture's target must be *compatible* with the target of *origtexture*, as defined by table 8.20.

Numerous constraints on *numlayers* and the texture dimensions depend on *target* and the target of *origtexture*. These constraints are summarized below in the errors section.

Class	Internal formats
128-bit	RGBA32F, RGBA32UI, RGBA32I
96-bit	RGB32F, RGB32UI, RGB32I
64-bit	RGBA16F, RG32F, RGBA16UI, RG32UI, RGBA16I, RG32I, RGBA16, RGBA16_SNORM
48-bit	RGB16, RGB16_SNORM, RGB16F, RGB16UI, RGB16I
32-bit	RG16F, R11F_G11F_B10F, R32F, RGB10_A2UI, RGBA8UI, RG16UI, R32UI, RGBA8I, RG16I, R32I, RGB10_A2, RGBA8, RG16, RGBA8_SNORM, RG16_SNORM, SRGB8_ALPHA8, RGB9_E5
24-bit	RGB8, RGB8_SNORM, SRGB8, RGB8UI, RGB8I
16-bit	R16F, RG8UI, R16UI, RG8I, R16I, RG8, R16, RG8_SNORM, R16_SNORM
8-bit	R8UI, R8I, R8, R8_SNORM
RGTC1_RED	COMPRESSED_RED_RGTC1, COMPRESSED_SIGNED_RED_RGTC1
RGTC2_RG	COMPRESSED_RG_RGTC2, COMPRESSED_SIGNED_RG_RGTC2
BPTC_UNORM	COMPRESSED_RGBA_BPTC_UNORM, COMPRESSED_SRGB_ALPHA_BPTC_UNORM
BPTC_FLOAT	COMPRESSED_RGB_BPTC_SIGNED_FLOAT, COMPRESSED_RGBA_BPTC_UNSIGNED_FLOAT

Table 8.21: Compatible internal formats for **TextureView**. Formats in the same row may be cast to each other.

When *origtexture*'s target is `TEXTURE_CUBE_MAP`, the layer parameters are interpreted in the same order as if it were a `TEXTURE_CUBE_MAP_ARRAY` with 6 layer-faces.

The two textures' internal formats must be compatible according to table 8.21 if the internal format exists in that table. The internal formats must be identical if not in that table.

If the internal format does not exactly match the internal format of the original texture, the contents of the memory are reinterpreted in the same manner as for image bindings described in section 8.25.

Texture commands that take a *level* or *layer* parameter, such as **TexSubImage2D**, interpret that parameter to be relative to the view of the texture. i.e. the mipmap level of the data store that would be updated via **TexSubImage2D** would be the sum of *level* and the value of `TEXTURE_VIEW_MIN_LEVEL`.

**Errors**

An `INVALID_VALUE` error is generated if *texture* is zero.

An `INVALID_OPERATION` error is generated if *texture* is not a valid name returned by **GenTextures**, or if *texture* has already been bound and given a target.

An `INVALID_VALUE` error is generated if *origtexture* is not the name of a texture.

An `INVALID_OPERATION` error is generated if the value of `TEXTURE_IMMUTABLE_FORMAT` for *origtexture* is not `TRUE`.

An `INVALID_OPERATION` error is generated if *target* is not compatible with the target of *origtexture*, as defined by table 8.20.

An `INVALID_OPERATION` error is generated if the internal format of *origtexture* exists in table 8.21 and is not compatible with *internalformat*, as described in that table.

An `INVALID_OPERATION` error is generated if the internal format of *origtexture* does not exist in table 8.21, and is not identical to *internalformat*.

An `INVALID_VALUE` error is generated if *minlevel* or *minlayer* are larger than the greatest level or layer, respectively, of *origtexture*.

An `INVALID_VALUE` error is generated if *target* is `TEXTURE_CUBE_MAP` and the clamped *numlayers* is not 6.

An `INVALID_VALUE` error is generated if *target* is `TEXTURE_CUBE_MAP_ARRAY` and the clamped *numlayers* is not a multiple of 6. In this case *numlayers* counts layer-faces rather than layers.

An `INVALID_VALUE` error is generated if *target* is `TEXTURE_1D`, `TEXTURE_2D`, `TEXTURE_3D`, `TEXTURE_RECTANGLE`, or `TEXTURE_2D_MULTISAMPLE` and *numlayers* does not equal 1.

An `INVALID_OPERATION` error is generated if *target* is `TEXTURE_CUBE_MAP` or `TEXTURE_CUBE_MAP_ARRAY`, and the width and height of *origtexture*'s levels are not equal.

An `INVALID_OPERATION` error is generated if any dimension of *origtexture* is larger than the maximum supported corresponding dimension of the new target. For example, if *origtexture* has a `TEXTURE_2D_ARRAY` target and *target* is `TEXTURE_CUBE_MAP`, its width must be no greater than the value of `MAX_CUBE_MAP_TEXTURE_SIZE`.

## 8.19 Immutable-Format Texture Images

An alternative set of commands is provided for specifying the properties of all levels of a texture at once. Once a texture is specified with such a command, the format and dimensions of all levels becomes immutable, unless it is a proxy texture (since otherwise it would no longer be possible to use the proxy). The contents of the images and the parameters can still be modified. Such a texture is referred to as an *immutable-format* texture. The immutability status of a texture can be determined by calling **GetTexParameter** with *pname* `TEXTURE_IMMUTABLE_FORMAT`.

Each of the commands below is described by pseudocode which indicates the effect on the dimensions and format of the texture. For each command the following apply in addition to the pseudocode:

- If executing the pseudocode would result in any other error, the error is generated and the command will have no effect.
- Any existing levels that are not replaced are reset to their initial state.
- The pixel unpack buffer should be considered to be zero; i.e., the image contents are unspecified.
- Since no pixel data are provided, the *format* and *type* values used in the pseudocode are irrelevant; they can be considered to be any values that are legal to use with *internalformat*.
- If the command is successful, `TEXTURE_IMMUTABLE_FORMAT` becomes `TRUE`. `TEXTURE_IMMUTABLE_LEVELS` and `TEXTURE_VIEW_NUM_LEVELS` become *levels*. If the texture target is `TEXTURE_1D_ARRAY` then `TEXTURE_VIEW_NUM_LAYERS` becomes *height*. If the texture target is `TEXTURE_2D_ARRAY`, `TEXTURE_CUBE_MAP_ARRAY`, or `TEXTURE_2D_MULTISAMPLE_ARRAY` then `TEXTURE_VIEW_NUM_LAYERS` becomes *depth*. If the texture target is `TEXTURE_CUBE_MAP`, then `TEXTURE_VIEW_NUM_LAYERS` becomes 6. For any other texture target, `TEXTURE_VIEW_NUM_LAYERS` becomes 1.

For each command, the following errors are generated in addition to the errors described specific to that command:

### Errors

An `INVALID_OPERATION` error is generated if zero is bound to *target*.  
If executing the pseudo-code would result in a `OUT_OF_MEMORY` error, the

error is generated and the results of executing the command are undefined.

An `INVALID_VALUE` error is generated if *width*, *height*, *depth* or *levels* are less than 1.

An `INVALID_ENUM` error is generated if *internalformat* is one of the un-sized base internal formats listed in table 8.11.

The command

```
void TexStorage1D( enum target, sizei levels,
                  enum internalformat, sizei width );
```

specifies all the levels of a one-dimensional texture (or proxy) at the same time. It is described by the pseudocode below:

```
for (i = 0; i < levels; i++) {
    TexImage1D(target, i, internalformat, width, 0,
              format, type, NULL);
    width = max(1, [ $\frac{width}{2}$ ]);
}
```

### Errors

An `INVALID_ENUM` error is generated if *target* is not `TEXTURE_1D` or `PROXY_TEXTURE_1D`.

An `INVALID_OPERATION` error is generated if *levels* is greater than  $\lceil \log_2(\textit{width}) \rceil + 1$ .

An `INVALID_VALUE` error is generated if *width* is negative.

The command

```
void TexStorage2D( enum target, sizei levels,
                  enum internalformat, sizei width, sizei height );
```

specifies all the levels of a two-dimensional, cube-map, one-dimension array or rectangle texture (or proxy) at the same time. The pseudocode depends on *target*:

*targets* `TEXTURE_2D`, `PROXY_TEXTURE_2D`, `TEXTURE_RECTANGLE`, `PROXY_TEXTURE_RECTANGLE`, or `PROXY_TEXTURE_CUBE_MAP`:

```
for (i = 0; i < levels; i++) {
    TexImage2D(target, i, internalformat, width, height, 0,
```

```

        format, type, NULL);
    width = max(1,  $\lfloor \frac{\textit{width}}{2} \rfloor$ );
    height = max(1,  $\lfloor \frac{\textit{height}}{2} \rfloor$ );
}

```

*target* TEXTURE\_CUBE\_MAP:

```

for (i = 0; i < levels; i++) {
    for face in (+X, -X, +Y, -Y, +Z, -Z) {
        TexImage2D(face, i, internalformat, width, height, 0,
            format, type, NULL);
    }
    width = max(1,  $\lfloor \frac{\textit{width}}{2} \rfloor$ );
    height = max(1,  $\lfloor \frac{\textit{height}}{2} \rfloor$ );
}

```

*targets* TEXTURE\_1D\_ARRAY or PROXY\_TEXTURE\_1D\_ARRAY:

```

for (i = 0; i < levels; i++) {
    TexImage2D(target, i, internalformat, width, height, 0,
        format, type, NULL);
    width = max(1,  $\lfloor \frac{\textit{width}}{2} \rfloor$ );
}

```

### Errors

An INVALID\_ENUM error is generated if *target* is not one of those listed above,

An INVALID\_OPERATION error is generated if any of the following conditions hold:

- *target* is TEXTURE\_1D\_ARRAY or PROXY\_TEXTURE\_1D\_ARRAY, and *levels* is greater than  $\lfloor \log_2(\textit{width}) \rfloor + 1$
- *target* is not TEXTURE\_1D\_ARRAY or PROXY\_TEXTURE\_1D\_ARRAY, and *levels* is greater than  $\lfloor \log_2(\max(\textit{width}, \textit{height})) \rfloor + 1$

An INVALID\_VALUE error is generated if *width* or *height* is negative.

The command

```

void TexStorage3D(enum target, sizei levels,
    enum internalformat, sizei width, sizei height,
    sizei depth);

```



specifies all the levels of a three-dimensional, two-dimensional array texture, or cube-map array texture (or proxy). The pseudocode depends on the *target*:

*targets* TEXTURE\_3D or PROXY\_TEXTURE\_3D:

```
for (i = 0; i < levels; i++) {
    TexImage3D(target, i, internalformat, width, height, depth, 0,
              format, type, NULL);
    width = max(1, ⌊ $\frac{width}{2}$ ⌋);
    height = max(1, ⌊ $\frac{height}{2}$ ⌋);
    depth = max(1, ⌊ $\frac{depth}{2}$ ⌋);
}
```

*targets* TEXTURE\_2D\_ARRAY, PROXY\_TEXTURE\_2D\_ARRAY, TEXTURE\_CUBE\_MAP\_ARRAY or PROXY\_TEXTURE\_CUBE\_MAP\_ARRAY:

```
for (i = 0; i < levels; i++) {
    TexImage3D(target, i, internalformat, width, height, depth, 0,
              format, type, NULL);
    width = max(1, ⌊ $\frac{width}{2}$ ⌋);
    height = max(1, ⌊ $\frac{height}{2}$ ⌋);
}
```

### Errors

An INVALID\_ENUM error is generated if *target* is not one of those listed above,

An INVALID\_OPERATION error is generated if any of the following conditions hold:

- *target* is TEXTURE\_3D or PROXY\_TEXTURE\_3D and *levels* is greater than  $\lfloor \log_2(\max(\text{width}, \text{height}, \text{depth})) \rfloor + 1$
- *target* is TEXTURE\_2D\_ARRAY, PROXY\_TEXTURE\_2D\_ARRAY, TEXTURE\_CUBE\_MAP\_ARRAY or PROXY\_TEXTURE\_CUBE\_MAP\_ARRAY and *levels* is greater than  $\lfloor \log_2(\max(\text{width}, \text{height})) \rfloor + 1$

An INVALID\_VALUE error is generated if *width*, *height*, or *depth* is negative.

The command

```
void TexStorage2DMultisample( enum target, sizei samples,
                             enum internalformat, sizei width, sizei height,
                             boolean fixedsamplelocations );
```

specifies a two-dimensional multisample texture (or proxy). *target* must be `TEXTURE_2D_MULTISAMPLE` or `PROXY_TEXTURE_2D_MULTISAMPLE`. The pseudo-code is equivalent to calling **TexImage2DMultisample** with the equivalently named parameters set to the same values.

#### Errors

An `INVALID_ENUM` error is generated if *target* is not `TEXTURE_2D_MULTISAMPLE` or `PROXY_TEXTURE_2D_MULTISAMPLE`.

An `INVALID_VALUE` error is generated if *width* or *height* is negative.

The command

```
void TexStorage3DMultisample( enum target, sizei samples,
                             enum internalformat, sizei width, sizei height,
                             sizei depth, boolean fixedsamplelocations );
```

specifies a two-dimensional multisample array texture (or proxy). *target* must be `TEXTURE_2D_MULTISAMPLE_ARRAY` or `PROXY_TEXTURE_2D_MULTISAMPLE_ARRAY`. The pseudo-code is equivalent to calling **TexImage3DMultisample** with the equivalently named parameters set to the same values.

#### Errors

An `INVALID_ENUM` error is generated if *target* is not `TEXTURE_2D_MULTISAMPLE_ARRAY` or `PROXY_TEXTURE_2D_MULTISAMPLE_ARRAY`.

An `INVALID_VALUE` error is generated if *width*, *height*, or *depth* is negative.

After a successful call to any **TexStorage\*** command with a non-proxy target, the value of `TEXTURE_IMMUTABLE_FORMAT` for this texture object is set to `TRUE`, and no further changes to the dimensions or format of the texture object may be made. Other commands may only alter the texel values and texture parameters. An `INVALID_OPERATION` error is generated by any of the following commands with the same texture, even if it does not affect the dimensions or format:

- **TexImage\***

- **CompressedTexImage\***
- **CopyTexImage\***
- **TexStorage\***

## 8.20 Invalidating Texture Image Data

All or part of a texture image may be invalidated, effectively leaving those texels undefined, by calling

```
void InvalidateTexSubImage(uint texture, int level,
    int xoffset, int yoffset, int zoffset, sizei width,
    sizei height, sizei depth);
```

with *texture* and *level* indicating which texture image is being invalidated. After this command, data in that subregion have undefined values. *xoffset*, *yoffset*, *zoffset*, *width*, *height*, and *depth* are interpreted as they are in **TexSubImage3D**. For texture targets that don't have certain dimensions, this command treats those dimensions as having a size of 1. For example, to invalidate a portion of a two-dimensional texture, the application would use *zoffset* equal to zero and *depth* equal to one. Cube map textures are treated as an array of six slices in the z-dimension, where a value of *zoffset* is interpreted as specifying the cube map face for the corresponding *layer* in table 9.3.

### Errors

An `INVALID_VALUE` error is generated if *level* is negative or greater than the base 2 logarithm of the maximum texture width, height, or depth. The arguments *xoffset*, *yoffset*, *zoffset*, *width*, *height*, and *depth* generate the same errors as in the **TexSubImage** commands. That is, the specified subregion must be between  $-b$  and  $dim + b$ , where *dim* is the size of the dimension of the texture image, and *b* is the border width of that texture image, otherwise an `INVALID_VALUE` error is generated. The border is not applied to dimensions that don't exist in a given texture target).

An `INVALID_VALUE` error is generated if *texture* is zero or is not the name of a texture; it is not possible to invalidate a portion of a default texture.

An `INVALID_VALUE` error is generated if the target of *texture* is `TEXTURE_RECTANGLE`, `TEXTURE_BUFFER`, `TEXTURE_2D_MULTISAMPLE`, or `TEXTURE_2D_MULTISAMPLE_ARRAY`, and *level* is not zero.

An `INVALID_VALUE` error is generated if *width*, *height*, or *depth* is nega-

tive.

The command

```
void InvalidateTexImage(uint texture, int level);
```

is equivalent to calling **InvalidateTexSubImage** with *xoffset*, *yoffset*, and *zoffset* equal to  $-b$  and *width*, *height*, and *depth* equal to the dimensions of the texture image plus  $2 \times b$  (or zero and one for dimensions the texture doesn't have).

## 8.21 Texture State and Proxy State

The state necessary for texture can be divided into two categories. First, there are the multiple sets of texel arrays (a single array for the rectangle texture target; one set of mipmap arrays each for the one-, two-, and three-dimensional and one- and two-dimensional array texture targets; and six sets of mipmap arrays for the cube map texture targets) and their number. Each array has associated with it a width, height (two- and three-dimensional, rectangle, one-dimensional array, cube map, and cube map array only), and depth (three-dimensional, two-dimensional array, and cube map array only), an integer describing the internal format of the image, integer values describing the resolutions of each of the red, green, blue, alpha, depth, and stencil components of the image, integer values describing the type (unsigned normalized, integer, floating-point, etc.) of each of the components, a boolean describing whether the image is compressed or not, an integer size of a compressed image, and an integer containing the name of a buffer object bound as the data store of the image.

Each initial texel array is null (zero width, height, and depth, internal format RGBA, component sizes set to zero and component types set to NONE, the compressed flag set to FALSE, a zero compressed size, and the bound buffer object name is zero. Multisample textures contain an integer identifying the number of samples in each texel, and a boolean indicating whether identical sample locations and the same number of samples will be used for all texels in the image. The buffer texture target has associated two pointer sized integers containing the offset and range of the buffer object's data store and an integer containing the name of the buffer object that provided the data store for the texture, initially zero.

Next, there are the four sets of texture properties, corresponding to the one-, two-, three-dimensional, and cube map texture targets. Each set consists of the selected minification and magnification filters, the wrap modes for *s*, *t* (two- and three-dimensional and cube map only), and *r* (three-dimensional only), the TEXTURE\_BORDER\_COLOR, two floating-point numbers describing the minimum

and maximum level of detail, two integers describing the base and maximum mipmap array, a boolean flag indicating whether the format and dimensions of the texture are immutable, three integers describing the depth texture mode, compare mode, and compare function, and four integers describing the red, green, blue, and alpha swizzle modes (see section 15.2.1).

In the initial state, the value assigned to `TEXTURE_MIN_FILTER` is `NEAREST_MIPMAP_LINEAR` (except for rectangle textures, where the initial value is `LINEAR`), and the value for `TEXTURE_MAG_FILTER` is `LINEAR`. `s`, `t`, and `r` wrap modes are all set to `REPEAT` (except for rectangle textures, where the initial value is `CLAMP_TO_EDGE`). The values of `TEXTURE_MIN_LOD` and `TEXTURE_MAX_LOD` are -1000 and 1000 respectively. The values of `TEXTURE_BASE_LEVEL` and `TEXTURE_MAX_LEVEL` are 0 and 1000 respectively. The value of `TEXTURE_BORDER_COLOR` is (0,0,0,0). The value of `TEXTURE_IMMUTABLE_FORMAT` is `FALSE`. The values of `TEXTURE_COMPARE_MODE`, and `TEXTURE_COMPARE_FUNC` are `NONE`, and `LEQUAL` respectively. The values of `TEXTURE_SWIZZLE_R`, `TEXTURE_SWIZZLE_G`, `TEXTURE_SWIZZLE_B`, and `TEXTURE_SWIZZLE_A` are `RED`, `GREEN`, `BLUE`, and `ALPHA`, respectively. The values of `TEXTURE_IMMUTABLE_LEVELS`, `TEXTURE_VIEW_MIN_LEVEL`, `TEXTURE_VIEW_NUM_LEVELS`, `TEXTURE_VIEW_MIN_LAYER`, `TEXTURE_VIEW_NUM_LAYERS` are each zero.

In addition to image arrays for the non-proxy texture targets described above, partially instantiated image arrays are maintained for one-, two-, and three-dimensional, rectangle, one- and two-dimensional array, and cube map array textures. Additionally, a single proxy image array is maintained for the cube map texture. Each proxy image array includes width, height, depth, and internal format state values, as well as state for the red, green, blue, alpha, depth, and stencil component resolutions and types. Proxy arrays do not include image data nor texture parameters. When **TexImage3D** is executed with *target* specified as `PROXY_TEXTURE_3D`, the three-dimensional proxy state values of the specified level-of-detail are recomputed and updated. If the image array would not be supported by **TexImage3D** called with *target* set to `TEXTURE_3D`, no error is generated, but the proxy width, height, depth, and component resolutions are set to zero, and the component types are set to `NONE`. If the image array would be supported by such a call to **TexImage3D**, the proxy state values are set exactly as though the actual image array were being specified. No pixel data are transferred or processed in either case.

Proxy arrays for one- and two-dimensional textures, one- and two-dimensional array textures, and cube map array textures are operated on in the same way when **TexImage1D** is executed with *target* specified as `PROXY_TEXTURE_1D`, **TexImage2D** is executed with *target* specified as `PROXY_TEXTURE_2D`, `PROXY_`

TEXTURE\_1D\_ARRAY, or PROXY\_TEXTURE\_RECTANGLE, or **TexImage3D** is executed with *target* specified as PROXY\_TEXTURE\_2D\_ARRAY or PROXY\_TEXTURE\_CUBE\_MAP\_ARRAY.

Proxy arrays for two-dimensional multisample and two-dimensional multisample array textures are operated on in the same way when **TexImage2DMultisample** is called with *target* specified as PROXY\_TEXTURE\_2D\_MULTISAMPLE, or **TexImage3DMultisample** is called with *target* specified as PROXY\_TEXTURE\_2D\_MULTISAMPLE\_ARRAY.

The cube map proxy arrays are operated on in the same manner when **TexImage2D** is executed with the *target* field specified as PROXY\_TEXTURE\_CUBE\_MAP, with the addition that determining that a given cube map texture is supported with PROXY\_TEXTURE\_CUBE\_MAP indicates that all six of the cube map 2D images are supported. Likewise, if the specified PROXY\_TEXTURE\_CUBE\_MAP is not supported, none of the six cube map two-dimensional images are supported.

There is no image or non-level-related state associated with proxy textures. Therefore they may not be used as textures, and calling **BindTexture**, **GetTexImage**, **GetTexParameteriv**, or **GetTexParameterfv** with a proxy texture *target* generates an INVALID\_ENUM error.

## 8.22 Texture Comparison Modes

Texture values can also be computed according to a specified comparison function. Texture parameter TEXTURE\_COMPARE\_MODE specifies the comparison operands, and parameter TEXTURE\_COMPARE\_FUNC specifies the comparison function.

### 8.22.1 Depth Texture Comparison Mode

If the currently bound texture's base internal format is DEPTH\_COMPONENT or DEPTH\_STENCIL, then TEXTURE\_COMPARE\_MODE and TEXTURE\_COMPARE\_FUNC control the output of the texture unit as described below. Otherwise, the texture unit operates in the normal manner and texture comparison is bypassed.

Let  $D_t$  be the depth texture value of a depth/stencil texture. Let  $S_t$  be the stencil index component. If there is no stencil component, the value of  $S_t$  is undefined. Let  $D_{ref}$  be the reference value, provided by the shader's texture lookup function.

If the texture's internal format indicates a fixed-point depth texture, then  $D_t$  and  $D_{ref}$  are clamped to the range  $[0, 1]$ ; otherwise no clamping is performed.

Then the effective texture value is computed as follows:

- If the base internal format is DEPTH\_STENCIL and the value of DEPTH\_STENCIL\_TEXTURE\_MODE is STENCIL\_INDEX, then  $r = S_t$

- Otherwise, if the value of `TEXTURE_COMPARE_MODE` is `NONE`, then  $r = D_t$
- Otherwise, if the value of `TEXTURE_COMPARE_MODE` is `COMPARE_REF_TO_TEXTURE`, then  $r$  depends on the texture comparison function as shown in table 8.22

Texture Comparison Function	Computed result $r$
LEQUAL	$r = \begin{cases} 1.0, & D_{ref} \leq D_t \\ 0.0, & D_{ref} > D_t \end{cases}$
GEQUAL	$r = \begin{cases} 1.0, & D_{ref} \geq D_t \\ 0.0, & D_{ref} < D_t \end{cases}$
LESS	$r = \begin{cases} 1.0, & D_{ref} < D_t \\ 0.0, & D_{ref} \geq D_t \end{cases}$
GREATER	$r = \begin{cases} 1.0, & D_{ref} > D_t \\ 0.0, & D_{ref} \leq D_t \end{cases}$
EQUAL	$r = \begin{cases} 1.0, & D_{ref} = D_t \\ 0.0, & D_{ref} \neq D_t \end{cases}$
NOTEQUAL	$r = \begin{cases} 1.0, & D_{ref} \neq D_t \\ 0.0, & D_{ref} = D_t \end{cases}$
ALWAYS	$r = 1.0$
NEVER	$r = 0.0$

Table 8.22: Depth texture comparison functions.

The resulting  $r$  is assigned to  $R_t$ .

If the value of `TEXTURE_MAG_FILTER` is not `NEAREST`, or the value of `TEXTURE_MIN_FILTER` is not `NEAREST` or `NEAREST_MIPMAP_NEAREST`, then  $r$  may be computed by comparing more than one depth texture value to the texture reference value. The details of this are implementation-dependent, but  $r$  should be a value in the range  $[0, 1]$  which is proportional to the number of comparison passes or failures.

## 8.23 sRGB Texture Color Conversion

If the currently bound texture's internal format is one of the sRGB formats in table 8.23, the red, green, and blue components are converted from an sRGB color

Internal Format
SRGB
SRGB8
SRGB_ALPHA
SRGB8_ALPHA8
COMPRESSED_SRGB
COMPRESSED_SRGB8_ETC2
COMPRESSED_SRGB_ALPHA
COMPRESSED_SRGB8_ALPHA8_ETC2_EAC
COMPRESSED_SRGB8_PUNCHTHROUGH_ALPHA1_ETC2
COMPRESSED_SRGB_ALPHA_BPTC_UNORM

Table 8.23: sRGB texture internal formats.

space to a linear color space as part of filtering described in sections 8.14 and 8.15. Any alpha component is left unchanged. Ideally, implementations should perform this color conversion on each sample prior to filtering but implementations are allowed to perform this conversion after filtering (though this post-filtering approach is inferior to converting from sRGB prior to filtering).

The conversion from an sRGB encoded component,  $c_s$ , to a linear component,  $c_l$ , is as follows.

$$c_l = \begin{cases} \frac{c_s}{12.92}, & c_s \leq 0.04045 \\ \left(\frac{c_s + 0.055}{1.055}\right)^{2.4}, & c_s > 0.04045 \end{cases} \quad (8.14)$$

Assume  $c_s$  is the sRGB component in the range  $[0, 1]$ .

## 8.24 Shared Exponent Texture Color Conversion

If the currently bound texture's internal format is `RGB9_E5`, the red, green, blue, and shared bits are converted to color components (prior to filtering) using shared exponent decoding. The component  $red_s$ ,  $green_s$ ,  $blue_s$ , and  $exp_s$  values (see section 8.5.2) are treated as unsigned integers and are converted to floating-point  $red$ ,  $green$ , and  $blue$  as follows:



$$\begin{aligned}
 red &= red_s 2^{exp_s - B - N} \\
 green &= green_s 2^{exp_s - B - N} \\
 blue &= blue_s 2^{exp_s - B - N}
 \end{aligned}$$

## 8.25 Texture Image Loads and Stores

The contents of a texture may be made available for shaders to read and write by binding the texture to one of a collection of image units. The GL implementation provides an array of image units numbered beginning with zero, with the total number of image units provided given by the implementation-dependent value of `MAX_IMAGE_UNITS`. Unlike texture image units, image units do not have a separate attachment for each texture target texture; each image unit may have only one texture bound at a time.

A texture may be bound to an image unit for use by image loads and stores with the command

```
void BindImageTexture(uint unit, uint texture, int level,
    boolean layered, int layer, enum access, enum format);
```

where *unit* identifies the image unit, *texture* is the name of the texture, and *level* selects a single level of the texture. If *texture* is zero, any texture currently bound to image unit *unit* is unbound.

### Errors

An `INVALID_VALUE` error is generated if *unit* is greater than or equal to the value of `MAX_IMAGE_UNITS`, if *level* or *layer* is negative, or if *texture* is not the name of an existing texture object.

If the texture identified by *texture* is a one-dimensional array, two-dimensional array, three-dimensional, cube map, cube map array, or two-dimensional multi-sample array texture, it is possible to bind either the entire texture level or a single layer or face of the texture level. If *layered* is `TRUE`, the entire level is bound. If *layered* is `FALSE`, only the single layer identified by *layer* will be bound. When *layered* is `FALSE`, the single bound layer is treated as a different texture target for image accesses:

- one-dimensional array texture layers are treated as one-dimensional textures;

- two-dimensional array, three-dimensional, cube map, cube map array texture layers are treated as two-dimensional textures; and
- two-dimensional multisample array textures are treated as two-dimensional multisample textures.

For cube map textures where *layered* is `FALSE`, the face is taken by mapping the layer number to a face according to table 9.3. For cube map array textures where *layered* is `FALSE`, the selected layer number is mapped to a texture layer and cube face using the following equations and mapping *face* to a face according to table 9.3.

$$layer = \left\lfloor \frac{layer_{orig}}{6} \right\rfloor$$

$$face = layer_{orig} - (layer \times 6)$$

If the texture identified by *texture* does not have multiple layers or faces, the entire texture level is bound, regardless of the values specified for *layered* and *layer*.

*format* specifies the format that the elements of the image will be treated as when doing formatted stores, as described later in this section. This is referred to as the *image unit format*. If *format* is not one of the formats listed in table 8.25, an `INVALID_VALUE` error is generated.

*access* specifies whether the texture bound to the image will be treated as `READ_ONLY`, `WRITE_ONLY`, or `READ_WRITE`. If a shader reads from an image unit with a texture bound as `WRITE_ONLY`, or writes to an image unit with a texture bound as `READ_ONLY`, the results of that shader operation are undefined and may lead to application termination.

If a texture object bound to one or more image units is deleted by **DeleteTextures**, it is detached from each such image unit, as though **BindImageTexture** were called with *unit* identifying the image unit and *texture* set to zero.

When a shader accesses the texture bound to an image unit using a built-in image load, store, or atomic function, it identifies a single texel by providing a one-, two-, or three-dimensional coordinate. Multisample texture accesses also specify a sample number. A coordinate vector is mapped to an individual texel  $\tau_i$ ,  $\tau_{ij}$ , or  $\tau_{ijk}$  according to the target of the texture bound to the image unit using table 8.24. As noted above, single-layer bindings of array or cube map textures are considered to use a texture target corresponding to the bound layer, rather than that of the full texture.

If the texture target has layers or cube map faces, the layer or face number is taken from the *layer* argument of **BindImageTexture** if the texture is bound with

Texture target	Face /			
	i	j	k	layer
TEXTURE_1D	x	-	-	-
TEXTURE_2D	x	y	-	-
TEXTURE_3D	x	y	z	-
TEXTURE_RECTANGLE	x	y	-	-
TEXTURE_CUBE_MAP	x	y	-	z
TEXTURE_BUFFER	x	-	-	-
TEXTURE_1D_ARRAY	x	-	-	y
TEXTURE_2D_ARRAY	x	y	-	z
TEXTURE_CUBE_MAP_ARRAY	x	y	-	z
TEXTURE_2D_MULTISAMPLE	x	y	-	-
TEXTURE_2D_MULTISAMPLE_ARRAY	x	y	-	z

Table 8.24: Mapping of image load, store, and atomic texel coordinate components to texel numbers.

*layered* set to `FALSE`, or from the coordinate identified by table 8.24 otherwise. For cube map and cube map array textures with *layered* set to `TRUE`, the coordinate is mapped to a layer and face in the same manner as the *layer* argument of **BindImageTexture**.

If the individual texel identified for an image load, store, or atomic operation doesn't exist, the access is treated as invalid. Invalid image loads will return zero. Invalid image stores will have no effect. Invalid image atomics will not update any texture bound to the image unit and will return zero. An access is considered invalid if:

- no texture is bound to the selected image unit;
- the texture bound to the selected image unit is incomplete;
- the texture level bound to the image unit is less than the base level or greater than the maximum level of the texture;
- the internal format of the texture bound to the image unit is not found in table 8.25;
- the internal format of the texture bound to the image unit is incompatible with the specified *format* according to table 8.26;

- the texture bound to the image unit has layers, and the selected layer or cube map face doesn't exist;
- the selected texel  $\tau_i$ ,  $\tau_{ij}$ , or  $\tau_{ijk}$  doesn't exist;
- the image has more samples than the implementation-dependent value of `MAX_IMAGE_SAMPLES`.

Additionally, there are a number of cases where image load, store, or atomic operations are considered to involve a format mismatch. In such cases, undefined values will be returned by image loads and atomic operations and undefined values will be written by stores and atomic operations. A format mismatch will occur if:

- the type of image variable used to access the image unit does not match the target of a texture bound to the image unit with *layered* set to `TRUE`;
- the type of image variable used to access the image unit does not match the target corresponding to a single layer of a multi-layer texture target bound to the image unit with *layered* set to `FALSE`;
- the type of image variable used to access the image unit has a component data type (floating-point, signed integer, unsigned integer) incompatible with the format of the image unit;
- the format `layout` qualifier for an image variable used for an image load or atomic operation does not match the format of the image unit, according to table 8.25; or
- the image variable used for an image store has a format `layout` qualifier, and that qualifier does not match the format of the image unit, according to table 8.25.

For textures with multiple samples per texel, the sample selected for an image load, store, or atomic is undefined if the *sample* coordinate is negative or greater than or equal to the number of samples in the texture.

If a shader performs an image load, store, or atomic operation using an image variable declared as an array, and if the index used to select an individual element is negative or greater than or equal to the size of the array, the results of the operation are undefined but may not lead to termination.

Accesses to textures bound to image units do format conversions based on the *format* argument specified when the image is bound. Loads always return a value as a `vec4`, `ivec4`, or `uvec4`, and stores always take the source data as a

`vec4`, `ivec4`, or `uvec4`. Data are converted to/from the specified format according to the process described for a **TexImage2D** or **GetTexImage** command with *format* and *type* as `RGBA` and `FLOAT` for `vec4` data, as `RGBA_INTEGER` and `INT` for `ivec4` data, or as `RGBA_INTEGER` and `UNSIGNED_INT` for `uvec4` data, respectively. Unused components are filled in with (0, 0, 0, 1) (where 0 and 1 are either floating-point or integer values, depending on the format).

Any image variable used for shader loads or atomic memory operations must be declared with a format `layout` qualifier matching the format of its associated image unit, as enumerated in table 8.25. Otherwise, the access is considered to involve a format mismatch, as described above. Image variables used exclusively for image stores need not include a format `layout` qualifier, but any declared qualifier must match the image unit format to avoid a format mismatch.

Image Unit Format	Format Qualifer
RGBA32F	rgba32f
RGBA16F	rgba16f
RG32F	rg32f
RG16F	rg16f
R11F_G11F_B10F	r11f_g11f_b10f
R32F	r32f
R16F	r16f
RGBA32UI	rgba32ui
RGBA16UI	rgba16ui
RGB10_A2UI	rgb10_a2ui
RGBA8UI	rgba8ui
RG32UI	rg32ui
RG16UI	rg16ui
RG8UI	rg8ui
R32UI	r32ui
R16UI	r16ui
R8UI	r8ui
RGBA32I	rgba32i
RGBA16I	rgba16i
RGBA8I	rgba8i
RG32I	rg32i
RG16I	rg16i
RG8I	rg8i
(Continued on next page)	

Supported image unit formats (continued)	
Image Unit Format	Format Qualifer
R32I	r32i
R16I	r16i
R8I	r8i
RGBA16	rgba16
RGB10_A2	rgb10_a2
RGBA8	rgba8
RG16	rg16
RG8	rg8
R16	r16
R8	r8
RGBA16_SNORM	rgba16_snorm
RGBA8_SNORM	rgba8_snorm
RG16_SNORM	rg16_snorm
RG8_SNORM	rg8_snorm
R16_SNORM	r16_snorm
R8_SNORM	r8_snorm

Table 8.25: Supported image unit formats, with equivalent format layout qualifiers.

When a texture is bound to an image unit, the *format* parameter for the image unit need not exactly match the texture internal format as long as the formats are considered compatible. A pair of formats is considered to match in size if the corresponding entries in the *Size* column of table 8.26 are identical. A pair of formats is considered to match by class if the corresponding entries in the *Class* column of table 8.26 are identical. For textures allocated by the GL, an image unit format is compatible with a texture internal format if they match by size. For textures allocated outside the GL, format compatibility is determined by matching by size or by class, in an implementation dependent manner. The matching criterion used for a given texture may be determined by calling **GetTexParameter** with *value* set to `IMAGE_FORMAT_COMPATIBILITY_TYPE`, with return values of `IMAGE_FORMAT_COMPATIBILITY_BY_SIZE` and `IMAGE_FORMAT_COMPATIBILITY_BY_CLASS`, specifying matches by size and class, respectively.

When the format associated with an image unit does not exactly match the internal format of the texture bound to the image unit, image loads, stores, and

atomic operations re-interpret the memory holding the components of an accessed texel according to the format of the image unit. The re-interpretation for image loads and the read portion of image atomics is performed as though data were copied from the texel of the bound texture to a similar texel represented in the format of the image unit. Similarly, the re-interpretation for image stores and the write portion of image atomics is performed as though data were copied from a texel represented in the format of the image unit to the texel in the bound texture. In both cases, this copy operation would be performed by:

- reading the texel from the source format to scratch memory according to the process described for **GetTexImage** (see section 8.11), using default pixel storage modes and *format* and *type* parameters corresponding to the source format in table 8.26; and
- writing the texel from scratch memory to the destination format according to the process described for **TexSubImage3D** (see section 8.6), using default pixel storage modes and *format* and *type* parameters corresponding to the destination format in table 8.26.

Image Format	Size	Class	Pixel <i>format</i>	Pixel <i>type</i>
RGBA32F	128	4x32	RGBA	FLOAT
RGBA16F	64	4x16	RGBA	HALF_FLOAT
RG32F	64	2x32	RG	FLOAT
RG16F	32	2x16	RG	HALF_FLOAT
R11F_G11F_B10F	32	(a)	RGB	UNSIGNED_INT_10F_11F_11F_REV
R32F	32	1x32	RED	FLOAT
R16F	16	1x16	RED	HALF_FLOAT
RGBA32UI	128	4x32	RGBA_INTEGER	UNSIGNED_INT
RGBA16UI	64	4x16	RGBA_INTEGER	UNSIGNED_SHORT
RGB10_A2UI	32	(b)	RGBA_INTEGER	UNSIGNED_INT_2_10_10_10_REV
RGBA8UI	32	4x8	RGBA_INTEGER	UNSIGNED_BYTE
RG32UI	64	2x32	RG_INTEGER	UNSIGNED_INT
RG16UI	32	2x16	RG_INTEGER	UNSIGNED_SHORT
RG8UI	16	2x8	RG_INTEGER	UNSIGNED_BYTE
R32UI	32	1x32	RED_INTEGER	UNSIGNED_INT
R16UI	16	1x16	RED_INTEGER	UNSIGNED_SHORT
R8UI	8	1x8	RED_INTEGER	UNSIGNED_BYTE
RGBA32I	128	4x32	RGBA_INTEGER	INT

(Continued on next page)

Texel sizes, compatibility classes ... (continued)				
Image Format	Size	Class	Pixel <i>format</i>	Pixel <i>type</i>
RGBA16I	64	4x16	RGBA_INTEGER	SHORT
RGBA8I	32	4x8	RGBA_INTEGER	BYTE
RG32I	64	2x32	RG_INTEGER	INT
RG16I	32	2x16	RG_INTEGER	SHORT
RG8I	16	2x8	RG_INTEGER	BYTE
R32I	32	1x32	RED_INTEGER	INT
R16I	16	1x16	RED_INTEGER	SHORT
R8I	8	1x8	RED_INTEGER	BYTE
RGBA16	64	4x16	RGBA	UNSIGNED_SHORT
RGB10_A2	32	(b)	RGBA	UNSIGNED_INT_2_10_10_10_REV
RGBA8	32	4x8	RGBA	UNSIGNED_BYTE
RG16	32	2x16	RG	UNSIGNED_SHORT
RG8	16	2x8	RG	UNSIGNED_BYTE
R16	16	1x16	RED	UNSIGNED_SHORT
R8	8	1x8	RED	UNSIGNED_BYTE
RGBA16_SNORM	64	4x16	RGBA	SHORT
RGBA8_SNORM	32	4x8	RGBA	BYTE
RG16_SNORM	32	2x16	RG	SHORT
RG8_SNORM	16	2x8	RG	BYTE
R16_SNORM	16	1x16	RED	SHORT
R8_SNORM	8	1x8	RED	BYTE

Table 8.26: Texel sizes, compatibility classes, and pixel format/type combinations for each image format. Class (a) is for 11/11/10 packed floating-point formats; class (b) is for 10/10/10/2 packed formats.

Implementations may support a limited combined number of shader storage blocks (see section 7.8), image units and active fragment shader outputs (see section 17.4.1). A link error is generated if the sum of the number of active shader storage blocks, the number of active image uniforms used in all shaders and the number of active fragment shader outputs exceeds the implementation-dependent value of `MAX_COMBINED_SHADER_OUTPUT_RESOURCES`.



## Chapter 9

# Framebuffers and Framebuffer Objects

As described in chapter 1 and section 2.1, the GL renders into (and reads values from) a framebuffer.

Initially, the GL uses the window-system provided *default framebuffer*. The storage, dimensions, allocation, and format of the images attached to this framebuffer are managed entirely by the window system. Consequently, the state of the default framebuffer, including its images, can not be changed by the GL, nor can the default framebuffer be deleted by the GL.

This chapter begins with an overview of the structure and contents of the framebuffer in section 9.1, followed by describing the commands used to create, destroy, and modify the state and attachments of application-created *framebuffer objects* which may be used instead of the default framebuffer.

### 9.1 Framebuffer Overview

The framebuffer consists of a set of pixels arranged as a two-dimensional array. For purposes of this discussion, each pixel in the framebuffer is simply a set of some number of bits. The number of bits per pixel may vary depending on the GL implementation, the type of framebuffer selected, and parameters specified when the framebuffer was created. Creation and management of the default framebuffer is outside the scope of this specification, while creation and management of framebuffer objects is described in detail in section 9.2.

Corresponding bits from each pixel in the framebuffer are grouped together into a *bitplane*; each bitplane contains a single bit from each pixel. These bitplanes are grouped into several *logical buffers*. These are the *color*, *depth*, and *stencil*

buffers. The color buffer actually consists of a number of buffers, and these color buffers serve related but slightly different purposes depending on whether the GL is bound to the default framebuffer or a framebuffer object.

For the default framebuffer, the color buffers are the *front left* buffer, the *front right* buffer, the *back left* buffer, and the *back right* buffer. Typically the contents of the front buffers are displayed on a color monitor while the contents of the back buffers are invisible. (Monoscopic contexts display only the front left buffer; stereoscopic contexts display both the front left and the front right buffers.) All color buffers must have the same number of bitplanes, although an implementation or context may choose not to provide right buffers, or back buffers at all. Further, an implementation or context may choose not to provide depth or stencil buffers. If no default framebuffer is associated with the GL context, the framebuffer is incomplete except when a framebuffer object is bound (see sections 9.2 and 9.4).

Framebuffer objects are not visible, and do not have any of the color buffers present in the default framebuffer. Instead, the buffers of a framebuffer object are specified by attaching individual textures or renderbuffers (see section 9) to a set of attachment points. A framebuffer object has an array of color buffer attachment points, numbered zero through  $n$ , a depth buffer attachment point, and a stencil buffer attachment point. In order to be used for rendering, a framebuffer object must be *complete*, as described in section 9.4. Not all attachments of a framebuffer object need to be populated.

Each pixel in a color buffer consists of up to four color components. The four color components are named R, G, B, and A, in that order; color buffers are not required to have all four color components. R, G, B, and A components may be represented as signed or unsigned normalized fixed-point, floating-point, or signed or unsigned integer values; all components must have the same representation. Each pixel in a depth buffer consists of a single unsigned integer value in the format described in section 13.6.1 or a floating-point value. Each pixel in a stencil buffer consists of a single unsigned integer value.

The number of bitplanes in the color, depth, and stencil buffers is dependent on the currently bound framebuffer. For the default framebuffer, the number of bitplanes is fixed. For framebuffer objects, the number of bitplanes in a given logical buffer may change if the image attached to the corresponding attachment point changes.

The GL has two active framebuffers; the *draw framebuffer* is the destination for rendering operations, and the *read framebuffer* is the source for readback operations. The same framebuffer may be used for both drawing and reading. Section 9.2 describes the mechanism for controlling framebuffer usage.

The default framebuffer is initially used as the draw and read framebuffer <sup>1</sup>, and the initial state of all provided bitplanes is undefined. The format and encoding of buffers in the draw and read framebuffers can be queried as described in section 9.2.3.

## 9.2 Binding and Managing Framebuffer Objects

Framebuffer objects encapsulate the state of a framebuffer in a similar manner to the way texture objects encapsulate the state of a texture. In particular, a framebuffer object encapsulates state necessary to describe a collection of color, depth, and stencil logical buffers (other types of buffers are not allowed). For each logical buffer, a framebuffer-attachable image can be attached to the framebuffer to store the rendered output for that logical buffer. Examples of framebuffer-attachable images include texture images and renderbuffer images. Renderbuffers are described further in section 9.2.4

By allowing the images of a renderbuffer to be attached to a framebuffer, the GL provides a mechanism to support *off-screen* rendering. Further, by allowing the images of a texture to be attached to a framebuffer, the GL provides a mechanism to support *render to texture*.

The default framebuffer for rendering and readback operations is provided by the window system. In addition, named framebuffer objects can be created and operated upon. The name space for framebuffer objects is the unsigned integers, with zero reserved by the GL for the default framebuffer.

A framebuffer object is created by binding a name returned by **GenFramebuffers** (see below) to `DRAW_FRAMEBUFFER` or `READ_FRAMEBUFFER`. The binding is effected by calling

```
void BindFramebuffer( enum target, uint framebuffer );
```

with *target* set to the desired framebuffer target and *framebuffer* set to the framebuffer object name. The resulting framebuffer object is a new state vector, comprising all the state and with the same initial values listed in table 23.24, as well as one set of the state values listed in table 23.25 for each attachment point of the framebuffer, with the same initial values. There are the value of `MAX_COLOR_ATTACHMENTS` color attachment points, plus one each for the depth and stencil attachment points.

---

<sup>1</sup>The window system binding API may allow associating a GL context with two separate “default framebuffers” provided by the window system as the draw and read framebuffers, but if so, both default framebuffers are referred to by the name zero at their respective binding points.

**BindFramebuffer** may also be used to bind an existing framebuffer object to `DRAW_FRAMEBUFFER` and/or `READ_FRAMEBUFFER`. If the bind is successful no change is made to the state of the newly bound framebuffer object, and any previous binding to *target* is broken.

**BindFramebuffer** fails and an `INVALID_OPERATION` error is generated if *framebuffer* is not zero or a name returned from a previous call to **GenFramebuffers**, or if such a name has since been deleted with **DeleteFramebuffers**.

If a framebuffer object is bound to `DRAW_FRAMEBUFFER` or `READ_FRAMEBUFFER`, it becomes the target for rendering or readback operations, respectively, until it is deleted or another framebuffer object is bound to the corresponding bind point. Calling **BindFramebuffer** with *target* set to `FRAMEBUFFER` binds *framebuffer* to both the draw and read targets.

While a framebuffer object is bound, GL operations on the target to which it is bound affect the images attached to the bound framebuffer object, and queries of the target to which it is bound return state from the bound object. Queries of the values specified in tables 23.73 and 23.24 are derived from the framebuffer object bound to `DRAW_FRAMEBUFFER`, with the exception of those marked as properties of the read framebuffer, which are derived from the framebuffer object bound to `READ_FRAMEBUFFER`.

The initial state of `DRAW_FRAMEBUFFER` and `READ_FRAMEBUFFER` refers to the default framebuffer. In order that access to the default framebuffer is not lost, it is treated as a framebuffer object with the name of zero. The default framebuffer is therefore rendered to and read from while zero is bound to the corresponding targets. On some implementations, the properties of the default framebuffer can change over time (e.g., in response to window system events such as attaching the context to a new window system drawable.)

Framebuffer objects (those with a non-zero name) differ from the default framebuffer in a few important ways. First and foremost, unlike the default framebuffer, framebuffer objects have modifiable attachment points for each logical buffer in the framebuffer. Framebuffer-attachable images can be attached to and detached from these attachment points, which are described further in section 9.2.2. Also, the size and format of the images attached to framebuffer objects are controlled entirely within the GL interface, and are not affected by window system events, such as pixel format selection, window resizes, and display mode changes.

Additionally, when rendering to or reading from an application created-framebuffer object,

- The pixel ownership test always succeeds. In other words, framebuffer objects own all of their pixels.

- There are no visible color buffer bitplanes. This means there is no color buffer corresponding to the back, front, left, or right color bitplanes.
- The only color buffer bitplanes are the ones defined by the framebuffer attachment points named `COLOR_ATTACHMENT0` through `COLOR_ATTACHMENTn`.
- The only depth buffer bitplanes are the ones defined by the framebuffer attachment point `DEPTH_ATTACHMENT`.
- The only stencil buffer bitplanes are the ones defined by the framebuffer attachment point `STENCIL_ATTACHMENT`.
- If the attachment sizes are not all identical, rendering will be limited to the largest area that can fit in all of the attachments (an intersection of rectangles having a lower left of  $(0, 0)$  and an upper right of  $(width, height)$  for each attachment). If there are no attachments, rendering will be limited to a rectangle having a lower left of  $(0, 0)$  and an upper right of  $(width, height)$ , where *width* and *height* are the framebuffer object's default width and height.
- If the number of layers of each attachment are not all identical, rendering will be limited to the smallest number of layers of any attachment. If there are no attachments, the number of layers will be taken from the framebuffer object's default layer count.
- If the attachment sizes are not all identical, the values of pixels outside the common intersection area after rendering are undefined.

The command

```
void GenFramebuffers( sizei n, uint *framebuffers );
```

returns *n* previously unused framebuffer object names in *framebuffers*. These names are marked as used, for the purposes of **GenFramebuffers** only, but they acquire state and type only when they are first bound.

### Errors

An `INVALID_VALUE` error is generated if *n* is negative.

Framebuffer objects are deleted by calling

```
void DeleteFramebuffers( size_t n, const
    uint *framebuffers );
```

*framebuffers* contains *n* names of framebuffer objects to be deleted. After a framebuffer object is deleted, it has no attachments, and its name is again unused. If a framebuffer that is currently bound to one or more of the targets `DRAW_FRAMEBUFFER` or `READ_FRAMEBUFFER` is deleted, it is as though **BindFramebuffer** had been executed with the corresponding *target* and *framebuffer* zero. Unused names in *framebuffers* that have been marked as used for the purposes of **GenFramebuffers** are marked as unused again. Unused names in *framebuffers* are silently ignored, as is the value zero.

### Errors

An `INVALID_VALUE` error is generated if *n* is negative.

The command

```
boolean IsFramebuffer( uint framebuffer );
```

returns `TRUE` if *framebuffer* is the name of a framebuffer object. If *framebuffer* is zero, or if *framebuffer* is a non-zero value that is not the name of a framebuffer object, **IsFramebuffer** returns `FALSE`.

The names bound to the draw and read framebuffer bindings can be queried by calling **GetIntegerv** with the symbolic constants `DRAW_FRAMEBUFFER_BINDING` and `READ_FRAMEBUFFER_BINDING`, respectively. `FRAMEBUFFER_BINDING` is equivalent to `DRAW_FRAMEBUFFER_BINDING`.

### 9.2.1 Framebuffer Object Parameters

Parameters of a framebuffer object are set using the command

```
void FramebufferParameteri( enum target, enum pname,
    int param );
```

*target* must be `DRAW_FRAMEBUFFER`, `READ_FRAMEBUFFER`, or `FRAMEBUFFER`. `FRAMEBUFFER` is equivalent to `DRAW_FRAMEBUFFER`. *pname* specifies the parameter of the framebuffer object bound to *target* to set.

When a framebuffer has one or more attachments, the width, height, layer count (see section 9.8), sample count, and sample location pattern of the framebuffer are derived from the properties of the framebuffer attachments. When the framebuffer

has no attachments, these properties are taken from framebuffer parameters. When *pname* is `FRAMEBUFFER_DEFAULT_WIDTH`, `FRAMEBUFFER_DEFAULT_HEIGHT`, `FRAMEBUFFER_DEFAULT_LAYERS`, `FRAMEBUFFER_DEFAULT_SAMPLES`, or `FRAMEBUFFER_DEFAULT_FIXED_SAMPLE_LOCATIONS`, *param* specifies the width, height, layer count, sample count, or sample location pattern, respectively, used when the framebuffer has no attachments.

When a framebuffer has no attachments, it is considered layered (see section 9.8) if and only if the value of `FRAMEBUFFER_DEFAULT_LAYERS` is non-zero. It is considered to have sample buffers if and only if the value of `FRAMEBUFFER_DEFAULT_SAMPLES` is non-zero. The number of samples in the framebuffer is derived from the value of `FRAMEBUFFER_DEFAULT_SAMPLES` in an implementation-dependent manner similar to that described for the command **RenderbufferStorageMultisample** (see section 9.2.2). If the framebuffer has sample buffers and the value of `FRAMEBUFFER_DEFAULT_FIXED_SAMPLE_LOCATIONS` is non-zero, it is considered to have a fixed sample location pattern as described for **TexImage2DMultisample** (see section 8.8).

### Errors

An `INVALID_ENUM` error is generated if *target* is not `DRAW_FRAMEBUFFER`, `READ_FRAMEBUFFER`, or `FRAMEBUFFER`.

An `INVALID_ENUM` error is generated if *pname* is not `FRAMEBUFFER_DEFAULT_WIDTH`, `FRAMEBUFFER_DEFAULT_HEIGHT`, `FRAMEBUFFER_DEFAULT_LAYERS`, `FRAMEBUFFER_DEFAULT_SAMPLES`, or `FRAMEBUFFER_DEFAULT_FIXED_SAMPLE_LOCATIONS`.

An `INVALID_VALUE` error is generated if *param* is negative or greater than the value of implementation-dependent limits `MAX_FRAMEBUFFER_WIDTH`, `MAX_FRAMEBUFFER_HEIGHT`, `MAX_FRAMEBUFFER_LAYERS`, `MAX_FRAMEBUFFER_SAMPLES` when *pname* is `FRAMEBUFFER_DEFAULT_WIDTH`, `FRAMEBUFFER_DEFAULT_HEIGHT`, `FRAMEBUFFER_DEFAULT_LAYERS`, or `FRAMEBUFFER_DEFAULT_SAMPLES`, respectively.

An `INVALID_OPERATION` error is generated if the default framebuffer is bound to *target*.

## 9.2.2 Attaching Images to Framebuffer Objects

Framebuffer-attachable images may be attached to, and detached from, framebuffer objects. In contrast, the image attachments of the default framebuffer may not be changed by the GL.

A single framebuffer-attachable image may be attached to multiple framebuffer

objects, potentially avoiding some data copies, and possibly decreasing memory consumption.

For each logical buffer, a framebuffer object stores a set of state which defines the logical buffer's *attachment point*. The attachment point state contains enough information to identify the single image attached to the attachment point, or to indicate that no image is attached. The per-logical buffer attachment point state is listed in table 23.25

There are several types of framebuffer-attachable images:

- The image of a renderbuffer object, which is always two-dimensional.
- A single level of a one-dimensional texture, which is treated as a two-dimensional image with a height of one.
- A single level of a two-dimensional, two-dimensional multisample, or rectangle texture.
- A single face of a cube map texture level, which is treated as a two-dimensional image.
- A single layer of a one-or two-dimensional array texture, two-dimensional multisample array texture, or three-dimensional texture, which is treated as a two-dimensional image.
- A single layer-face of a cube map array texture, which is treated as a two-dimensional image.

Additionally, an entire level of a three-dimensional, cube map, cube map array, or one-or two-dimensional array texture can be attached to an attachment point. Such attachments are treated as an array of two-dimensional images, arranged in layers, and the corresponding attachment point is considered to be *layered* (also see section 9.8).

### 9.2.3 Framebuffer Object Queries

The command

```
void GetFramebufferParameteriv( enum target, enum pname,  
    int *params );
```

returns the values of the framebuffer parameter *pname* of the framebuffer object bound to *target*.



*target* must be `DRAW_FRAMEBUFFER`, `READ_FRAMEBUFFER`, or `FRAMEBUFFER`. `FRAMEBUFFER` is equivalent to `DRAW_FRAMEBUFFER`. *pname* specifies the parameter of the framebuffer object bound to *target* to set.

### Errors

An `INVALID_ENUM` error is generated if *target* is not `DRAW_FRAMEBUFFER`, `READ_FRAMEBUFFER`, or `FRAMEBUFFER`.

An `INVALID_ENUM` error is generated if *pname* is not `FRAMEBUFFER_DEFAULT_WIDTH`, `FRAMEBUFFER_DEFAULT_HEIGHT`, `FRAMEBUFFER_DEFAULT_LAYERS`, `FRAMEBUFFER_DEFAULT_SAMPLES`, or `FRAMEBUFFER_DEFAULT_FIXED_SAMPLE_LOCATIONS`.

An `INVALID_OPERATION` error is generated if the default framebuffer is bound to *target*.

The command

```
void GetFramebufferAttachmentParameteriv( enum target,
      enum attachment, enum pname, int *params );
```

returns information about attachments of a bound framebuffer object. *target* must be `DRAW_FRAMEBUFFER`, `READ_FRAMEBUFFER`, or `FRAMEBUFFER`. `FRAMEBUFFER` is equivalent to `DRAW_FRAMEBUFFER`.

If the default framebuffer is bound to *target*, then *attachment* must be one of `FRONT_LEFT`, `FRONT_RIGHT`, `BACK_LEFT`, or `BACK_RIGHT`, identifying a color buffer; `DEPTH`, identifying the depth buffer; or `STENCIL`, identifying the stencil buffer.

If a framebuffer object is bound to *target*, then *attachment* must be one of the attachment points of the framebuffer listed in table 9.2.

If *attachment* is `DEPTH_STENCIL_ATTACHMENT`, and different objects are bound to the depth and stencil attachment points of *target*, the query will fail and generate an `INVALID_OPERATION` error. If the same object is bound to both attachment points, information about that object will be returned.

Upon successful return from **GetFramebufferAttachmentParameteriv**, if *pname* is `FRAMEBUFFER_ATTACHMENT_OBJECT_TYPE`, then *param* will contain one of `NONE`, `FRAMEBUFFER_DEFAULT`, `TEXTURE`, or `RENDERBUFFER`, identifying the type of object which contains the attached image. Other values accepted for *pname* depend on the type of object, as described below.

If the value of `FRAMEBUFFER_ATTACHMENT_OBJECT_TYPE` is `NONE`, no framebuffer is bound to *target*. In this case querying *pname* `FRAMEBUFFER_`

ATTACHMENT\_OBJECT\_NAME will return zero, and all other queries will generate an INVALID\_OPERATION error.

If the value of FRAMEBUFFER\_ATTACHMENT\_OBJECT\_TYPE is not NONE, these queries apply to all other framebuffer types:

- If *pname* is FRAMEBUFFER\_ATTACHMENT\_RED\_SIZE, FRAMEBUFFER\_ATTACHMENT\_GREEN\_SIZE, FRAMEBUFFER\_ATTACHMENT\_BLUE\_SIZE, FRAMEBUFFER\_ATTACHMENT\_ALPHA\_SIZE, FRAMEBUFFER\_ATTACHMENT\_DEPTH\_SIZE, or FRAMEBUFFER\_ATTACHMENT\_STENCIL\_SIZE, then *param* will contain the number of bits in the corresponding red, green, blue, alpha, depth, or stencil component of the specified *attachment*. Zero is returned if the requested component is not present in *attachment*.
- If *pname* is FRAMEBUFFER\_ATTACHMENT\_COMPONENT\_TYPE, *param* will contain the format of components of the specified attachment, one of FLOAT, INT, UNSIGNED\_INT, SIGNED\_NORMALIZED, or UNSIGNED\_NORMALIZED for floating-point, signed integer, unsigned integer, signed normalized fixed-point, or unsigned normalized fixed-point components respectively. Only color buffers may have integer components.
- If *pname* is FRAMEBUFFER\_ATTACHMENT\_COLOR\_ENCODING, *param* will contain the encoding of components of the specified attachment, one of LINEAR or SRGB for linear or sRGB-encoded components, respectively. Only color buffer components may be sRGB-encoded; such components are treated as described in sections 17.3.8 and 17.3.9. For the default framebuffer, color encoding is determined by the implementation. For framebuffer objects, components are sRGB-encoded if the internal format of a color attachment is one of the color-renderable SRGB formats described in section 8.23.

If the value of FRAMEBUFFER\_ATTACHMENT\_OBJECT\_TYPE is RENDERBUFFER, then

- If *pname* is FRAMEBUFFER\_ATTACHMENT\_OBJECT\_NAME, *params* will contain the name of the renderbuffer object which contains the attached image.

If the value of FRAMEBUFFER\_ATTACHMENT\_OBJECT\_TYPE is TEXTURE, then

- If *pname* is FRAMEBUFFER\_ATTACHMENT\_OBJECT\_NAME, then *params* will contain the name of the texture object which contains the attached image.

- If *pname* is `FRAMEBUFFER_ATTACHMENT_TEXTURE_LEVEL`, then *params* will contain the mipmap level of the texture object which contains the attached image.
- If *pname* is `FRAMEBUFFER_ATTACHMENT_TEXTURE_CUBE_MAP_FACE` and the texture object named `FRAMEBUFFER_ATTACHMENT_OBJECT_NAME` is a cube map texture, then *params* will contain the cube map face of the cube-map texture object which contains the attached image. Otherwise *params* will contain the value zero.
- If *pname* is `FRAMEBUFFER_ATTACHMENT_TEXTURE_LAYER` and the texture object named `FRAMEBUFFER_ATTACHMENT_OBJECT_NAME` is a layer of a three-dimensional texture or a one-or two-dimensional array texture, then *params* will contain the number of the texture layer which contains the attached image. Otherwise *params* will contain the value zero.
- If *pname* is `FRAMEBUFFER_ATTACHMENT_LAYERED`, then *params* will contain `TRUE` if an entire level of a three-dimensional texture, cube map texture, or one-or two-dimensional array texture is attached. Otherwise, *params* will contain `FALSE`.

### Errors

An `INVALID_ENUM` error is generated if *target* is not `DRAW_FRAMEBUFFER`, `READ_FRAMEBUFFER`, or `FRAMEBUFFER`.

An `INVALID_ENUM` error is generated by any combinations of framebuffer type and *pname* not described above.

### 9.2.4 Renderbuffer Objects

A renderbuffer is a data storage object containing a single image of a renderable internal format. The commands described below allocate and delete a renderbuffer's image, and attach a renderbuffer's image to a framebuffer object.

The name space for renderbuffer objects is the unsigned integers, with zero reserved by the GL. A renderbuffer object is created by binding a name returned by **GenRenderbuffers** (see below) to `RENDERBUFFER`. The binding is effected by calling

```
void BindRenderbuffer( enum target, uint renderbuffer );
```

with *target* set to `RENDERBUFFER` and *renderbuffer* set to the renderbuffer object name. If *renderbuffer* is not zero, then the resulting renderbuffer object is a new

state vector, initialized with a zero-sized memory buffer, and comprising all the state and with the same initial values listed in table 23.27. Any previous binding to *target* is broken.

**BindRenderbuffer** may also be used to bind an existing renderbuffer object. If the bind is successful, no change is made to the state of the newly bound renderbuffer object, and any previous binding to *target* is broken.

While a renderbuffer object is bound, GL operations on the target to which it is bound affect the bound renderbuffer object, and queries of the target to which a renderbuffer object is bound return state from the bound object.

The name zero is reserved. A renderbuffer object cannot be created with the name zero. If *renderbuffer* is zero, then any previous binding to *target* is broken and the *target* binding is restored to the initial state.

In the initial state, the reserved name zero is bound to RENDERBUFFER. There is no renderbuffer object corresponding to the name zero, so client attempts to modify or query renderbuffer state for the target RENDERBUFFER while zero is bound will generate GL errors, as described in section 9.2.3.

The current RENDERBUFFER binding can be determined by calling **GetIntegerv** with the symbolic constant RENDERBUFFER\_BINDING.

**BindRenderbuffer** fails and an INVALID\_OPERATION error is generated if *renderbuffer* is not zero or a name returned from a previous call to **GenRenderbuffers**, or if such a name has since been deleted with **DeleteRenderbuffers**.

The command

```
void GenRenderbuffers( sizei n, uint *renderbuffers );
```

returns *n* previously unused renderbuffer object names in *renderbuffers*. These names are marked as used, for the purposes of **GenRenderbuffers** only, but they acquire renderbuffer state only when they are first bound.

### Errors

An INVALID\_VALUE error is generated if *n* is negative.

Renderbuffer objects are deleted by calling

```
void DeleteRenderbuffers( sizei n, const
    uint *renderbuffers );
```

where *renderbuffers* contains *n* names of renderbuffer objects to be deleted. After a renderbuffer object is deleted, it has no contents, and its name is again unused. If a renderbuffer that is currently bound to RENDERBUFFER is deleted, it is as though

**BindRenderbuffer** had been executed with the *target* `RENDERBUFFER` and *name* of zero. Additionally, special care must be taken when deleting a renderbuffer if the image of the renderbuffer is attached to a framebuffer object (see section 9.2.7). Unused names in *renderbuffers* that have been marked as used for the purposes of **GenRenderbuffers** are marked as unused again. Unused names in *renderbuffers* are silently ignored, as is the value zero.

### Errors

An `INVALID_VALUE` error is generated if *n* is negative.

The command

```
boolean IsRenderbuffer( uint renderbuffer );
```

returns `TRUE` if *renderbuffer* is the name of a renderbuffer object. If *renderbuffer* is zero, or if *renderbuffer* is a non-zero value that is not the name of a renderbuffer object, **IsRenderbuffer** returns `FALSE`.

The command

```
void RenderbufferStorageMultisample( enum target,
    sizei samples, enum internalformat, sizei width,
    sizei height );
```

establishes the data storage, format, dimensions, and number of samples of a renderbuffer object's image. *target* must be `RENDERBUFFER`. *internalformat* must be color-renderable, depth-renderable, or stencil-renderable (as defined in section 9.4). *width* and *height* are the dimensions in pixels of the renderbuffer.

Upon success, **RenderbufferStorageMultisample** deletes any existing data store for the renderbuffer image and the contents of the data store after calling **RenderbufferStorageMultisample** are undefined. `RENDERBUFFER_WIDTH` is set to *width*, `RENDERBUFFER_HEIGHT` is set to *height*, and `RENDERBUFFER_INTERNAL_FORMAT` is set to *internalformat*.

If *samples* is zero, then `RENDERBUFFER_SAMPLES` is set to zero. Otherwise *samples* represents a request for a desired minimum number of samples. Since different implementations may support different sample counts for multisampled rendering, the actual number of samples allocated for the renderbuffer image is implementation-dependent. However, the resulting value for `RENDERBUFFER_SAMPLES` is guaranteed to be greater than or equal to *samples* and no more than the next larger sample count supported by the implementation.

Sized Internal Format	Base Internal Format	<i>S</i> bits
STENCIL_INDEX1	STENCIL_INDEX	1
STENCIL_INDEX4	STENCIL_INDEX	4
STENCIL_INDEX8	STENCIL_INDEX	8
STENCIL_INDEX16	STENCIL_INDEX	16

Table 9.1: Correspondence of sized internal formats to base internal formats for formats that can be used only with renderbuffers.

A GL implementation may vary its allocation of internal component resolution based on any **RenderbufferStorage** parameter (except *target*), but the allocation and chosen internal format must not be a function of any other state and cannot be changed once they are established.

### Errors

An `INVALID_ENUM` error is generated if *target* is not `RENDERBUFFER`.

An `INVALID_VALUE` error is generated if *samples*, *width*, or *height* is negative.

An `INVALID_OPERATION` error is generated if *samples* is greater than the maximum number of samples supported for *internalformat* (see **GetInternalFormativ** in section 22.3).

An `INVALID_ENUM` error is generated if *internalformat* is not one of the color-renderable, depth-renderable, or stencil-renderable formats defined in section 9.4.

An `INVALID_VALUE` error is generated if either *width* or *height* is greater than the value of `MAX_RENDERBUFFER_SIZE`.

An `OUT_OF_MEMORY` error is generated if the GL is unable to create a data store of the requested size.

The command

```
void RenderbufferStorage(enum target, enum internalformat,
    sizei width, sizei height);
```

is equivalent to calling **RenderbufferStorageMultisample** with *samples* equal to zero.

### 9.2.5 Required Renderbuffer Formats

Implementations are required to support the same internal formats for renderbuffers as the required formats for textures enumerated in section 8.5.1, with the exception of the color formats labelled “texture-only”. Requesting one of these internal formats for a renderbuffer will allocate at least the internal component sizes and exactly the component types shown for that format in tables 8.12- 8.13.

Implementations are also required to support `STENCIL_INDEX8`.

Implementations must support creation of renderbuffers in these required formats with up to the value of `MAX_SAMPLES` multisamples, with the exception that the signed and unsigned integer formats are required only to support creation of renderbuffers with up to the value of `MAX_INTEGER_SAMPLES` multisamples, which must be at least one.

### 9.2.6 Renderbuffer Object Queries

The command

```
void GetRenderbufferParameteriv( enum target, enum pname,
    int* params );
```

returns information about a bound renderbuffer object. *target* must be `RENDERBUFFER` and *pname* must be one of the symbolic values in table 23.27. If the renderbuffer currently bound to *target* is zero, then an `INVALID_OPERATION` error is generated.

If *pname* is `RENDERBUFFER_WIDTH`, `RENDERBUFFER_HEIGHT`, `RENDERBUFFER_INTERNAL_FORMAT`, or `RENDERBUFFER_SAMPLES`, then *params* will contain the width in pixels, height in pixels, internal format, or number of samples, respectively, of the image of the renderbuffer currently bound to *target*.

If *pname* is `RENDERBUFFER_RED_SIZE`, `RENDERBUFFER_GREEN_SIZE`, `RENDERBUFFER_BLUE_SIZE`, `RENDERBUFFER_ALPHA_SIZE`, `RENDERBUFFER_DEPTH_SIZE`, or `RENDERBUFFER_STENCIL_SIZE`, then *params* will contain the actual resolutions (not the resolutions specified when the image array was defined) for the red, green, blue, alpha depth, or stencil components, respectively, of the image of the renderbuffer currently bound to *target*.

#### Errors

An `INVALID_ENUM` error is generated if *target* is not `RENDERBUFFER`.

An `INVALID_ENUM` error is generated if *pname* is not one of the renderbuffer state names in table 23.27.

### 9.2.7 Attaching Renderbuffer Images to a Framebuffer

A renderbuffer can be attached as one of the logical buffers of a currently bound framebuffer object by calling

```
void FramebufferRenderbuffer( enum target,
                             enum attachment, enum renderbuffertarget,
                             uint renderbuffer );
```

*target* must be `DRAW_FRAMEBUFFER`, `READ_FRAMEBUFFER`, or `FRAMEBUFFER`. `FRAMEBUFFER` is equivalent to `DRAW_FRAMEBUFFER`.

*attachment* must be set to one of the attachment points of the framebuffer listed in table 9.2.

*renderbuffertarget* must be `RENDERBUFFER` and *renderbuffer* is zero or the name of a renderbuffer object of type `renderbuffertarget` to be attached to the framebuffer. If *renderbuffer* is zero, then the value of *renderbuffertarget* is ignored.

If *renderbuffer* is not zero and if **FramebufferRenderbuffer** is successful, then the renderbuffer named *renderbuffer* will be used as the logical buffer identified by *attachment* of the framebuffer object currently bound to *target*. The value of `FRAMEBUFFER_ATTACHMENT_OBJECT_TYPE` for the specified attachment point is set to `RENDERBUFFER` and the value of `FRAMEBUFFER_ATTACHMENT_OBJECT_NAME` is set to *renderbuffer*. All other state values of the attachment point specified by *attachment* are set to their default values listed in table 23.25. No change is made to the state of the renderbuffer object and any previous attachment to the *attachment* logical buffer of the framebuffer object bound to framebuffer *target* is broken. If the attachment is not successful, then no change is made to the state of either the renderbuffer object or the framebuffer object.

Calling **FramebufferRenderbuffer** with the *renderbuffer* name zero will detach the image, if any, identified by *attachment*, in the framebuffer object currently bound to *target*. All state values of the attachment point specified by *attachment* in the object bound to *target* are set to their default values listed in table 23.25.

Setting *attachment* to the value `DEPTH_STENCIL_ATTACHMENT` is a special case causing both the depth and stencil attachments of the framebuffer object to be set to *renderbuffer*, which should have base internal format `DEPTH_STENCIL`.

If a renderbuffer object is deleted while its image is attached to one or more attachment points in a currently bound framebuffer object, then it is as if **FramebufferRenderbuffer** had been called, with a *renderbuffer* of zero, for each attachment



point to which this image was attached in that framebuffer object. In other words, the renderbuffer image is first detached from all attachment points in that framebuffer object. Note that the renderbuffer image is specifically **not** detached from any non-bound framebuffer objects. Detaching the image from any non-bound framebuffer objects is the responsibility of the application.

Name of attachment
COLOR_ATTACHMENT <i>i</i> (see caption)
DEPTH_ATTACHMENT
STENCIL_ATTACHMENT
DEPTH_STENCIL_ATTACHMENT

Table 9.2: Framebuffer attachment points. *i* in COLOR\_ATTACHMENT*i* may range from zero to the value of MAX\_COLOR\_ATTACHMENTS minus one.

### Errors

An INVALID\_ENUM error is generated if *target* is not DRAW\_FRAMEBUFFER, READ\_FRAMEBUFFER, or FRAMEBUFFER.

An INVALID\_ENUM error is generated if *attachment* is not one of the attachment points in table 9.2.

An INVALID\_ENUM error is generated if *renderbuffertarget* is not RENDERBUFFER and *renderbuffer* is not zero.

An INVALID\_OPERATION error is generated if *renderbuffer* is not zero or the name of an existing renderbuffer object of type *renderbuffertarget*.

An INVALID\_OPERATION error is generated if zero is bound to *target*.

### 9.2.8 Attaching Texture Images to a Framebuffer

The GL supports copying the rendered contents of the framebuffer into the images of a texture object through the use of the routines **CopyTexImage\*** and **CopyTexSubImage\***. Additionally, the GL supports rendering directly into the images of a texture object.

To render directly into a texture image, a specified level of a texture object can be attached as one of the logical buffers of the currently bound framebuffer object by calling:

```
void FramebufferTexture( enum target, enum attachment,
                          uint texture, int level );
```

*target* must be `DRAW_FRAMEBUFFER`, `READ_FRAMEBUFFER`, or `FRAMEBUFFER`. `FRAMEBUFFER` is equivalent to `DRAW_FRAMEBUFFER`. *attachment* must be one of the attachment points of the framebuffer listed in table 9.2.

If *texture* is non-zero, the specified mipmap *level* of the texture object named *texture* is attached to the framebuffer attachment point named by *attachment*.

If *texture* is the name of a three-dimensional texture, cube map texture, one-or two-dimensional array texture, or two-dimensional multisample array texture, the texture level attached to the framebuffer attachment point is an array of images, and the framebuffer attachment is considered layered.

### Errors

An `INVALID_ENUM` error is generated if *target* is not `DRAW_FRAMEBUFFER`, `READ_FRAMEBUFFER`, or `FRAMEBUFFER`.

An `INVALID_ENUM` error is generated if *attachment* is not one of the attachments in table 9.2.

An `INVALID_OPERATION` error is generated if zero is bound to *target*.

An `INVALID_VALUE` error is generated if *texture* is not the name of a texture object, or if *level* is not a supported texture level for *texture*.

An `INVALID_OPERATION` error is generated if *texture* is the name of a buffer texture.

Additionally, a specified image from a texture object can be attached as one of the logical buffers of a currently bound framebuffer object by calling one of the following routines, depending on the type of the texture:

```
void FramebufferTexture1D( enum target, enum attachment,
    enum textarget, uint texture, int level );
void FramebufferTexture2D( enum target, enum attachment,
    enum textarget, uint texture, int level );
void FramebufferTexture3D( enum target, enum attachment,
    enum textarget, uint texture, int level, int layer );
```

In all three routines, *target* must be `DRAW_FRAMEBUFFER`, `READ_FRAMEBUFFER`, or `FRAMEBUFFER`. `FRAMEBUFFER` is equivalent to `DRAW_FRAMEBUFFER`. *attachment* must be one of the attachment points of the framebuffer listed in table 9.2.

If *texture* is not zero, then *texture* must either name an existing texture object with a target of *textarget*, or *texture* must name an existing cube map texture and *textarget* must be one of the cube map face targets from table 8.18. Otherwise, an `INVALID_OPERATION` error is generated.

*level* specifies the mipmap level of the texture image to be attached to the framebuffer.

If *textarget* is `TEXTURE_RECTANGLE` or `TEXTURE_2D_MULTISAMPLE`, then *level* must be zero. If *textarget* is `TEXTURE_3D`, then *level* must be greater than or equal to zero and less than or equal to  $\log_2$  of the value of `MAX_3D_TEXTURE_SIZE`. If *textarget* is one of the cube map face targets from table 8.18, then *level* must be greater than or equal to zero and less than or equal to  $\log_2$  of the value of `MAX_CUBE_MAP_TEXTURE_SIZE`. For all other values of *textarget*, *level* must be greater than or equal to zero and no larger than  $\log_2$  of the value of `MAX_TEXTURE_SIZE`. Otherwise, an `INVALID_VALUE` error is generated.

*layer* specifies the layer of a two-dimensional image within a three-dimensional texture.

An `INVALID_VALUE` error is generated if *layer* is larger than the value of `MAX_3D_TEXTURE_SIZE` minus one.

For **FramebufferTexture1D**, if *texture* is not zero, then *textarget* must be `TEXTURE_1D`.

For **FramebufferTexture2D**, if *texture* is not zero, then *textarget* must be one of `TEXTURE_2D`, `TEXTURE_RECTANGLE`, one of the cube map face targets from table 8.18, or `TEXTURE_2D_MULTISAMPLE`.

For **FramebufferTexture3D**, if *texture* is not zero, then *textarget* must be `TEXTURE_3D`.

### Errors

An `INVALID_ENUM` error is generated if *target* is not `DRAW_FRAMEBUFFER`, `READ_FRAMEBUFFER`, or `FRAMEBUFFER`.

An `INVALID_ENUM` error is generated if *attachment* is not one of the attachments in table 9.2.

An `INVALID_OPERATION` error is generated if zero is bound to *target*.

An `INVALID_VALUE` error is generated if *texture* is not the name of a texture object, or if *level* is not a supported texture level for *texture*.

An `INVALID_OPERATION` error is generated if *texture* is the name of a buffer texture.

The command

```
void FramebufferTextureLayer( enum target,
                             enum attachment, uint texture, int level, int layer );
```

operates identically to **FramebufferTexture3D**, except that it attaches a single layer of a three-dimensional, one-or two-dimensional array, cube map array, or

two-dimensional multisample array texture level.

*layer* specifies the layer of a two-dimensional image within *texture* except for cube map array textures, where *layer* is translated into an array layer and a cube map face as described for layer-face numbers in section 8.5.3.

### Errors

An `INVALID_VALUE` error is generated if *layer* is larger than the value of `MAX_3D_TEXTURE_SIZE` minus one (for three-dimensional textures) or larger than the value of `MAX_ARRAY_TEXTURE_LAYERS` minus one (for array textures).

An `INVALID_VALUE` error is generated if *texture* is non-zero and *layer* is negative.

An `INVALID_OPERATION` error is generated if *texture* is non-zero and is not the name of a three dimensional, two-dimensional multisample array, one- or two-dimensional array, or cube map array texture.

Unlike **FramebufferTexture3D**, no *textarget* parameter is accepted.

If *texture* is non-zero and the command does not result in an error, the framebuffer attachment state corresponding to *attachment* is updated as in the other **FramebufferTexture** commands, except that the value of `FRAMEBUFFER_ATTACHMENT_TEXTURE_LAYER` is set to *layer*.

### Effects of Attaching a Texture Image

The remaining comments in this section apply to all forms of **FramebufferTexture\***.

If *texture* is zero, any image or array of images attached to the attachment point named by *attachment* is detached. Any additional parameters (*level*, *textarget*, and/or *layer*) are ignored when *texture* is zero. All state values of the attachment point specified by *attachment* are set to their default values listed in table 23.25.

If *texture* is not zero, and if **FramebufferTexture\*** is successful, then the specified texture image will be used as the logical buffer identified by *attachment* of the framebuffer object currently bound to *target*. State values of the specified attachment point are set as follows:

- The value of `FRAMEBUFFER_ATTACHMENT_OBJECT_TYPE` is set to `TEXTURE`.
- The value of `FRAMEBUFFER_ATTACHMENT_OBJECT_NAME` is set to *texture*.
- The value of `FRAMEBUFFER_ATTACHMENT_TEXTURE_LEVEL` is set to *level*.

### 9.3. FEEDBACK LOOPS BETWEEN TEXTURES AND THE FRAMEBUFFER272

- If **FramebufferTexture2D** is called and *texture* is a cube map texture, then the value of `FRAMEBUFFER_ATTACHMENT_TEXTURE_CUBE_MAP_FACE` is set to *textarget*; otherwise it is set to the default value (NONE).
- If **FramebufferTextureLayer** or **FramebufferTexture3D** is called, then the value of `FRAMEBUFFER_ATTACHMENT_TEXTURE_LAYER` is set to *layer*; otherwise it is set to zero.
- If **FramebufferTexture** is called and *texture* is the name of a three-dimensional, cube map, two-dimensional multisample array, or one- or two-dimensional array texture, the value of `FRAMEBUFFER_ATTACHMENT_LAYERED` is set to TRUE; otherwise it is set to FALSE.

All other state values of the attachment point specified by *attachment* are set to their default values listed in table 23.25. No change is made to the state of the texture object, and any previous attachment to the *attachment* logical buffer of the framebuffer object bound to framebuffer *target* is broken. If the attachment is not successful, then no change is made to the state of either the texture object or the framebuffer object.

Setting *attachment* to the value `DEPTH_STENCIL_ATTACHMENT` is a special case causing both the depth and stencil attachments of the framebuffer object to be set to *texture*. *texture* must have base internal format `DEPTH_STENCIL`, or the depth and stencil framebuffer attachments will be incomplete (see section 9.4.1).

If a texture object is deleted while its image is attached to one or more attachment points in a currently bound framebuffer object, then it is as if **FramebufferTexture\*** had been called, with a *texture* of zero, for each attachment point to which this image was attached in that framebuffer object. In other words, the texture image is first detached from all attachment points in that framebuffer object. Note that the texture image is specifically **not** detached from any non-bound framebuffer objects. Detaching the texture image from any non-bound framebuffer objects is the responsibility of the application.

## 9.3 Feedback Loops Between Textures and the Framebuffer

A *feedback loop* may exist when a texture object is used as both the source and destination of a GL operation. When a feedback loop exists, undefined behavior results. This section describes *rendering feedback loops* (see section 8.14.2.1) and *texture copying feedback loops* (see section 8.6.1) in more detail.

### 9.3.1 Rendering Feedback Loops

The mechanisms for attaching textures to a framebuffer object do not prevent a one- or two-dimensional texture level, a face of a cube map texture level, or a layer of a two-dimensional array or three-dimensional texture from being attached to the draw framebuffer while the same texture is bound to a texture unit. While this condition holds, texturing operations accessing that image will produce undefined results, as described at the end of section 8.14. Conditions resulting in such undefined behavior are defined in more detail below. Such undefined texturing operations are likely to leave the final results of fragment processing operations undefined, and should be avoided.

Special precautions need to be taken to avoid attaching a texture image to the currently bound draw framebuffer object while the texture object is currently bound and enabled for texturing. Doing so could lead to the creation of a rendering feedback loop between the writing of pixels by GL rendering operations and the simultaneous reading of those same pixels when used as texels in the currently bound texture. In this scenario, the framebuffer will be considered framebuffer complete (see section 9.4), but the values of fragments rendered while in this state will be undefined. The values of texture samples may be undefined as well, as described under “Rendering Feedback Loops” in section 8.14.2.1

Specifically, the values of rendered fragments are undefined if all of the following conditions are true:

- an image from texture object *T* is attached to the currently bound draw framebuffer object at attachment point *A*
- the texture object *T* is currently bound to a texture unit *U*, and
- the current programmable vertex and/or fragment processing state makes it possible (see below) to sample from the texture object *T* bound to texture unit *U*

while either of the following conditions are true:

- the value of `TEXTURE_MIN_FILTER` for texture object *T* is `NEAREST` or `LINEAR`, and the value of `FRAMEBUFFER_ATTACHMENT_TEXTURE_LEVEL` for attachment point *A* is equal to the value of `TEXTURE_BASE_LEVEL` for the texture object *T*
- the value of `TEXTURE_MIN_FILTER` for texture object *T* is one of `NEAREST_MIPMAP_NEAREST`, `NEAREST_MIPMAP_LINEAR`, `LINEAR_MIPMAP_NEAREST`, or `LINEAR_MIPMAP_LINEAR`, and the value of

`FRAMEBUFFER_ATTACHMENT_TEXTURE_LEVEL` for attachment point *A* is within the the range specified by the current values of `TEXTURE_BASE_LEVEL` to *q*, inclusive, for the texture object *T*. *q* is defined in section 8.14.3.

For the purpose of this discussion, it is *possible* to sample from the texture object *T* bound to texture unit *U* if the active fragment or vertex shader contains any instructions that might sample from the texture object *T* bound to *U*, even if those instructions might only be executed conditionally.

Note that if `TEXTURE_BASE_LEVEL` and `TEXTURE_MAX_LEVEL` exclude any levels containing image(s) attached to the currently bound draw framebuffer object, then the above conditions will not be met (i.e., the above rule will not cause the values of rendered fragments to be undefined.)

### 9.3.2 Texture Copying Feedback Loops

Similarly to rendering feedback loops, it is possible for a texture image to be attached to the currently bound read framebuffer object while the same texture image is the destination of a **CopyTexImage\*** operation, as described under “Texture Copying Feedback Loops” in section 8.6.1. While this condition holds, a texture copying feedback loop between the writing of texels by the copying operation and the reading of those same texels when used as pixels in the read framebuffer may exist. In this scenario, the values of texels written by the copying operation will be undefined (in the same fashion that overlapping copies via **BlitFramebuffer** are undefined).

Specifically, the values of copied texels are undefined if all of the following conditions are true:

- an image from texture object *T* is attached to the currently bound read framebuffer object at attachment point *A*
- the selected read buffer is attachment point *A*
- *T* is bound to the texture target of a **CopyTexImage\*** operation
- the *level* argument of the copying operation selects the same image that is attached to *A*

## 9.4 Framebuffer Completeness

A framebuffer must be *framebuffer complete* to effectively be used as the draw or read framebuffer of the GL.

The default framebuffer is always complete if it exists; however, if no default framebuffer exists (no window system-provided drawable is associated with the GL context), it is deemed to be incomplete.

A framebuffer object is said to be framebuffer complete if all of its attached images, and all framebuffer parameters required to utilize the framebuffer for rendering and reading, are consistently defined and meet the requirements defined below. The rules of framebuffer completeness are dependent on the properties of the attached images, and on certain implementation-dependent restrictions.

The internal formats of the attached images can affect the completeness of the framebuffer, so it is useful to first define the relationship between the internal format of an image and the attachment points to which it can be attached.

- An internal format is *color-renderable* if it is RED, RG, RGB, RGBA, or one of the sized internal formats from table 8.12 marked as color-renderable in that table. No other formats, including compressed internal formats, are color-renderable.
- An internal format is *depth-renderable* if it is DEPTH\_COMPONENT or one of the formats from table 8.13 whose base internal format is DEPTH\_COMPONENT or DEPTH\_STENCIL. No other formats are depth-renderable.
- An internal format is *stencil-renderable* if it is STENCIL\_INDEX or DEPTH\_STENCIL, if it is one of the STENCIL\_INDEX formats from table 9.1, or if it is one of the formats from table 8.13 whose base internal format is DEPTH\_STENCIL. No other formats are stencil-renderable.

#### 9.4.1 Framebuffer Attachment Completeness

If the value of FRAMEBUFFER\_ATTACHMENT\_OBJECT\_TYPE for the framebuffer attachment point *attachment* is not NONE, then it is said that a framebuffer-attachable image, named *image*, is attached to the framebuffer at the attachment point. *image* is identified by the state in *attachment* as described in section 9.2.2.

The framebuffer attachment point *attachment* is said to be *framebuffer attachment complete* if the value of FRAMEBUFFER\_ATTACHMENT\_OBJECT\_TYPE for *attachment* is NONE (i.e., no image is attached), or if all of the following conditions are true:

- *image* is a component of an existing object with the name specified by the value of FRAMEBUFFER\_ATTACHMENT\_OBJECT\_NAME, and of the type specified by the value of FRAMEBUFFER\_ATTACHMENT\_OBJECT\_TYPE.



- The width and height of *image* are greater than zero and less than or equal to the values of the implementation-dependent limits `MAX_FRAMEBUFFER_WIDTH` and `MAX_FRAMEBUFFER_HEIGHT`, respectively.
- If *image* is a three-dimensional texture or a one- or two-dimensional array texture and the attachment is not layered, the selected layer is less than the depth or layer count of the texture.
- If *image* is a three-dimensional texture or a one- or two-dimensional array texture and the attachment is layered, the depth or layer count of the texture is less than or equal to the value of the implementation-dependent limit `MAX_FRAMEBUFFER_LAYERS`.
- If *image* has multiple samples, its sample count is less than or equal to the value of the implementation-dependent limit `MAX_FRAMEBUFFER_SAMPLES`.
- If *attachment* is `COLOR_ATTACHMENTi`, then *image* must have a color-renderable internal format.
- If *attachment* is `DEPTH_ATTACHMENT`, then *image* must have a depth-renderable internal format.
- If *attachment* is `STENCIL_ATTACHMENT`, then *image* must have a stencil-renderable internal format.

### 9.4.2 Whole Framebuffer Completeness

Each rule below is followed by an error token enclosed in { brackets }. The meaning of these errors is explained below and under “Effects of Framebuffer Completeness on Framebuffer Operations” later in section 9.4.4.

The framebuffer object *target* is said to be *framebuffer complete* if all the following conditions are true:

- if *target* is the default framebuffer, the default framebuffer exists.

{ `FRAMEBUFFER_UNDEFINED` }

- All framebuffer attachment points are *framebuffer attachment complete*.

{ `FRAMEBUFFER_INCOMPLETE_ATTACHMENT` }

- There is at least one image attached to the framebuffer, or the value of the framebuffer's `FRAMEBUFFER_DEFAULT_WIDTH` and `FRAMEBUFFER_DEFAULT_HEIGHT` parameters are both non-zero.

{ `FRAMEBUFFER_INCOMPLETE_MISSING_ATTACHMENT` }

- The combination of internal formats of the attached images does not violate an implementation-dependent set of restrictions.

{ `FRAMEBUFFER_UNSUPPORTED` }

- The value of `RENDERBUFFER_SAMPLES` is the same for all attached renderbuffers; the value of `TEXTURE_SAMPLES` is the same for all attached textures; and, if the attached images are a mix of renderbuffers and textures, the value of `RENDERBUFFER_SAMPLES` matches the value of `TEXTURE_SAMPLES`.

{ `FRAMEBUFFER_INCOMPLETE_MULTISAMPLE` }

- The value of `TEXTURE_FIXED_SAMPLE_LOCATIONS` is the same for all attached textures; and, if the attached images are a mix of renderbuffers and textures, the value of `TEXTURE_FIXED_SAMPLE_LOCATIONS` must be `TRUE` for all attached textures.

{ `FRAMEBUFFER_INCOMPLETE_MULTISAMPLE` }

- If any framebuffer attachment is layered, all populated attachments must be layered. Additionally, all populated color attachments must be from textures of the same target (three-dimensional, one- or two-dimensional array, cube map, or cube map array textures).

{ `FRAMEBUFFER_INCOMPLETE_LAYER_TARGETS` }

The token in brackets after each clause of the framebuffer completeness rules specifies the return value of **CheckFramebufferStatus** (see below) that is generated when that clause is violated. If more than one clause is violated, it is implementation-dependent which value will be returned by **CheckFramebufferStatus**.

Performing any of the following actions may change whether the framebuffer is considered complete or incomplete:

- Binding to a different framebuffer with **BindFramebuffer**.
- Attaching an image to the framebuffer with **FramebufferTexture\*** or **FramebufferRenderbuffer**.
- Detaching an image from the framebuffer with **FramebufferTexture\*** or **FramebufferRenderbuffer**.
- Changing the internal format of a texture image that is attached to the framebuffer by calling **CopyTexImage\*** or **CompressedTexImage\***.
- Changing the internal format of a renderbuffer that is attached to the framebuffer by calling **RenderbufferStorage**.
- Deleting, with **DeleteTextures** or **DeleteRenderbuffers**, an object containing an image that is attached to a currently bound framebuffer object.
- Associating a different window system-provided drawable, or no drawable, with the default framebuffer using a window system binding API such as those described in section 1.3.5.

Although the GL defines a wide variety of internal formats for framebuffer-attachable images, such as texture images and renderbuffer images, some implementations may not support rendering to particular combinations of internal formats. If the combination of formats of the images attached to a framebuffer object are not supported by the implementation, then the framebuffer is not complete under the clause labeled `FRAMEBUFFER_UNSUPPORTED`.

Implementations are required to support certain combinations of framebuffer internal formats as described under “Required Framebuffer Formats” in section 9.4.3.

Because of the *implementation-dependent* clause of the framebuffer completeness test in particular, and because framebuffer completeness can change when the set of attached images is modified, it is strongly advised, though not required, that an application check to see if the framebuffer is complete prior to rendering. The status of the framebuffer object currently bound to *target* can be queried by calling

```
enum CheckFramebufferStatus( enum target );
```

*target* must be `DRAW_FRAMEBUFFER`, `READ_FRAMEBUFFER`, or `FRAMEBUFFER_FRAMEBUFFER`. `FRAMEBUFFER_FRAMEBUFFER` is equivalent to `DRAW_FRAMEBUFFER`.

A value is returned that identifies whether or not the framebuffer object bound to *target* is complete, and if not complete the value identifies one of the rules of

framebuffer completeness that is violated. If the framebuffer object is complete, then `FRAMEBUFFER_COMPLETE` is returned.

The values of `SAMPLE_BUFFERS` and `SAMPLES` are derived from the attachments of the currently bound draw framebuffer object. If the current `DRAW_FRAMEBUFFER_BINDING` is not framebuffer complete, then both `SAMPLE_BUFFERS` and `SAMPLES` are undefined. Otherwise, `SAMPLES` is equal to the value of `RENDERBUFFER_SAMPLES` or `TEXTURE_SAMPLES` (depending on the type of the attached images), which must all have the same value. Further, `SAMPLE_BUFFERS` is one if `SAMPLES` is non-zero. Otherwise, `SAMPLE_BUFFERS` is zero.

If `CheckFramebufferStatus` generates an error, zero is returned.

#### Errors

An `INVALID_ENUM` error is generated if *target* is not `DRAW_FRAMEBUFFER`, `READ_FRAMEBUFFER`, or `FRAMEBUFFER`.

### 9.4.3 Required Framebuffer Formats

Implementations must support framebuffer objects with up to `MAX_COLOR_ATTACHMENTS` color attachments, a depth attachment, and a stencil attachment. Each color attachment may be in any of the required color formats for textures and renderbuffers described in sections 8.5.1 and 9.2.5. The depth attachment may be in any of the required depth or combined depth+stencil formats described in those sections, and the stencil attachment may be in any of the required `stencil` or combined depth+stencil formats. However, when both depth and stencil attachments are present, implementations are only required to support framebuffer objects where both attachments refer to the same image.

There must be at least one default framebuffer format allowing creation of a default framebuffer supporting front-buffered rendering.

### 9.4.4 Effects of Framebuffer Completeness on Framebuffer Operations

An `INVALID_FRAMEBUFFER_OPERATION` error is generated by attempts to render to or read from a framebuffer which is not framebuffer complete. This means that rendering commands such as `DrawArrays` or one of the other drawing commands defined in section 10.5, as well as commands that read the framebuffer such as `ReadPixels`, `CopyTexImage*`, and `CopyTexSubImage*`, will generate an `INVALID_FRAMEBUFFER_OPERATION` error if called while the framebuffer is not framebuffer complete. This error is generated regardless of whether fragments

## 9.5. MAPPING BETWEEN PIXEL AND ELEMENT IN ATTACHED IMAGE280

are actually read from or written to the framebuffer. For example, it is generated when a rendering command is called and the framebuffer is incomplete even if `RASTERIZER_DISCARD` is enabled.

### 9.4.5 Effects of Framebuffer State on Framebuffer Dependent Values

The values of the state variables listed in table 23.73 may change when a change is made to `DRAW_FRAMEBUFFER_BINDING`, to the state of the currently bound draw framebuffer object, or to an image attached to that framebuffer object.

When `DRAW_FRAMEBUFFER_BINDING` is zero, the values of the state variables listed in table 23.73 are implementation defined.

When `DRAW_FRAMEBUFFER_BINDING` is non-zero, if the currently bound draw framebuffer object is not framebuffer complete, then the values of the state variables listed in table 23.73 are undefined.

When `DRAW_FRAMEBUFFER_BINDING` is non-zero and the currently bound draw framebuffer object is framebuffer complete, then the values of the state variables listed in table 23.73 are completely determined by `DRAW_FRAMEBUFFER_BINDING`, the state of the currently bound draw framebuffer object, and the state of the images attached to that framebuffer object. The actual sizes of the color, depth, or stencil bit planes can be obtained by querying an attachment point using `GetFramebufferAttachmentParameteriv`, or querying the object attached to that point. If the value of `FRAMEBUFFER_ATTACHMENT_OBJECT_TYPE` at a particular attachment point is `RENDERBUFFER`, the sizes may be determined by calling `GetRenderbufferParameteriv` as described in section 6.1.3. If the value of `FRAMEBUFFER_ATTACHMENT_OBJECT_TYPE` at a particular attachment point is `TEXTURE`, the sizes may be determined by calling `GetTexParameter`, as described in section 8.11.

## 9.5 Mapping between Pixel and Element in Attached Image

When `DRAW_FRAMEBUFFER_BINDING` is non-zero, an operation that writes to the framebuffer modifies the image attached to the selected logical buffer, and an operation that reads from the framebuffer reads from the image attached to the selected logical buffer.

If the attached image is a renderbuffer image, then the window coordinates  $(x_w, y_w)$  corresponds to the value in the renderbuffer image at the same coordinates.

If the attached image is a texture image, then the window coordinates  $(x_w, y_w)$  correspond to the texel  $(i, j, k)$  from figure 8.3 as follows:

$$\begin{aligned}i &= (x_w - b) \\j &= (y_w - b) \\k &= (\textit{layer} - b)\end{aligned}$$

where  $b$  is the texture image's border width and  $\textit{layer}$  is the value of `FRAMEBUFFER_ATTACHMENT_TEXTURE_LAYER` for the selected logical buffer. For a two-dimensional texture,  $k$  and  $\textit{layer}$  are irrelevant; for a one-dimensional texture,  $j$ ,  $k$ , and  $\textit{layer}$  are irrelevant.

$(x_w, y_w)$  corresponds to a border texel if  $x_w$ ,  $y_w$ , or  $\textit{layer}$  is less than the border width, or if  $x_w$ ,  $y_w$ , or  $\textit{layer}$  is greater than or equal to the border width plus the width, height, or depth, respectively, of the texture image.

## 9.6 Conversion to Framebuffer-Attachable Image Components

When an enabled color value is written to the framebuffer while the draw framebuffer binding is non-zero, for each draw buffer the R, G, B, and A values are converted to internal components as described in table 8.11, according to the table row corresponding to the internal format of the framebuffer-attachable image attached to the selected logical buffer, and the resulting internal components are written to the image attached to logical buffer. The masking operations described in section 17.4.2 are also effective.

## 9.7 Conversion to RGBA Values

When a color value is read while the read framebuffer binding is non-zero, or is used as the source of a logical operation or for blending while the draw framebuffer binding is non-zero, components of that color taken from the framebuffer-attachable image attached to the selected logical buffer are first converted to R, G, B, and A values according to table 15.1 and the internal format of the attached image.

## 9.8 Layered Framebuffers

A framebuffer is considered to be *layered* if it is complete and all of its populated attachments are layered. When rendering to a layered framebuffer, each fragment

generated by the GL is assigned a layer number. The layer number for a fragment is zero if

- geometry shaders are disabled, or
- the current geometry shader does not statically assign a value to the built-in output variable `gl_Layer`.

Otherwise, the layer for each point, line, or triangle emitted by the geometry shader is taken from the `gl_Layer` output of one of the vertices of the primitive. The vertex used is implementation-dependent. To get defined results, all vertices of each primitive emitted should set the same value for `gl_Layer`. Since the `EndPrimitive` built-in function starts a new output primitive, defined results can be achieved if `EndPrimitive` is called between two vertices emitted with different layer numbers. A layer number written by a geometry shader has no effect if the framebuffer is not layered.

When fragments are written to a layered framebuffer, the fragment's layer number selects an image from the array of images at each attachment point to use for the stencil test (see section 17.3.5), depth buffer test (see section 17.3.6), and for blending and color buffer writes (see section 17.3.8). If the fragment's layer number is negative, or greater than or equal to the minimum number of layers of any attachment, the effects of the fragment on the framebuffer contents are undefined.

When the **Clear** or **ClearBuffer\*** commands are used to clear a layered framebuffer attachment, all layers of the attachment are cleared.

When commands such as **ReadPixels** read from a layered framebuffer, the image at layer zero of the selected attachment is always used to obtain pixel values.

When cube map texture levels are attached to a layered framebuffer, there are six layers, numbered zero through five. Each layer number corresponds to a cube map face, as shown in table 9.3.

When cube map array texture levels are attached to a layered framebuffer, the layer number corresponds to a layer-face. The layer-face can be translated into an array layer and a cube map face by

$$\begin{aligned} \text{array\_layer} &= \left\lfloor \frac{\text{layer}}{6} \right\rfloor \\ \text{face} &= \text{layer} \bmod 6 \end{aligned}$$

The face number corresponds to the cube map faces as shown in table 9.3.

Layer Number	Cube Map Face
0	TEXTURE_CUBE_MAP_POSITIVE_X
1	TEXTURE_CUBE_MAP_NEGATIVE_X
2	TEXTURE_CUBE_MAP_POSITIVE_Y
3	TEXTURE_CUBE_MAP_NEGATIVE_Y
4	TEXTURE_CUBE_MAP_POSITIVE_Z
5	TEXTURE_CUBE_MAP_NEGATIVE_Z

Table 9.3: Layer numbers for cube map texture faces. The layers are numbered in the same sequence as the cube map face token values.



## Chapter 10

# Vertex Specification and Drawing Commands

Most geometric primitives are drawn by specifying a series of generic attribute sets corresponding to vertices of a primitive using **DrawArrays** or one of the other drawing commands defined in section 10.5. Points, lines, polygons, and a variety of related geometric primitives (see section 10.1) can be drawn in this way.

The process of specifying attributes of a vertex and passing them to a shader is referred to as *transferring* a vertex to the GL.

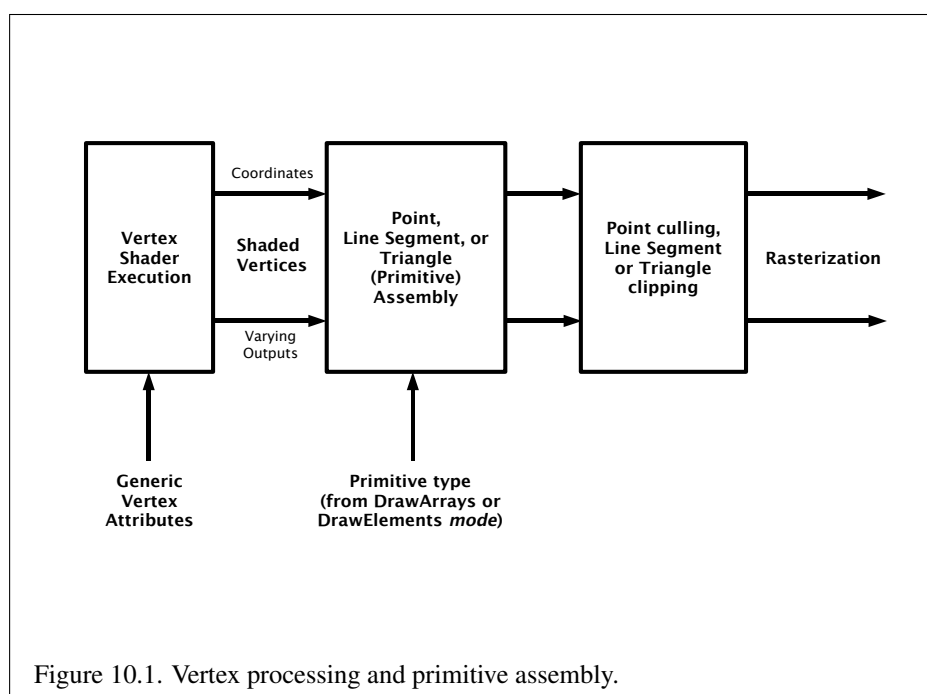
### Vertex Shader Processing and Vertex State

Each vertex is specified with one or more generic vertex attributes. Each attribute is specified with one, two, three, or four scalar values.

Generic vertex attributes can be accessed from within vertex shaders (see section 11.1) and used to compute values for consumption by later processing stages.

Before vertex shader execution, the state required by a vertex is its generic vertex attributes. Vertex shader execution processes vertices producing a homogeneous vertex position and any outputs explicitly written by the vertex shader.

Figure 10.1 shows the sequence of operations that builds a *primitive* (point, line segment, or polygon) from a sequence of vertices. After a primitive is formed, it is clipped to a clip volume. This may modify the primitive by altering vertex coordinates and vertex shader outputs. In the case of line and polygon primitives, clipping may insert new vertices into the primitive. The vertices defining a primitive to be rasterized have output variables associated with them.



## 10.1 Primitive Types

A sequence of vertices is passed to the GL using **DrawArrays** or one of the other drawing commands defined in section 10.5. There is no limit to the number of vertices that may be specified, other than the size of the vertex arrays. The *mode* parameter of these commands determines the type of primitives to be drawn using the vertices. Primitive types and the corresponding *mode* parameters are summarized below, together with any additional state required when assembling primitives from multiple vertices.

### 10.1.1 Points

A series of individual points are specified with *mode* POINTS. Each vertex defines a separate point. No state is required for points, since each point is independent of any previous and following points.

### 10.1.2 Line Strips

A series of one or more connected line segments are specified with *mode* LINE\_STRIP. In this case, the first vertex specifies the first segment's start point while the second vertex specifies the first segment's endpoint and the second segment's start point. In general, the *i*th vertex (for  $i > 1$ ) specifies the beginning of the *i*th segment and the end of the  $i - 1$ st. The last vertex specifies the end of the last segment. If only one vertex is specified, then no primitive is generated.

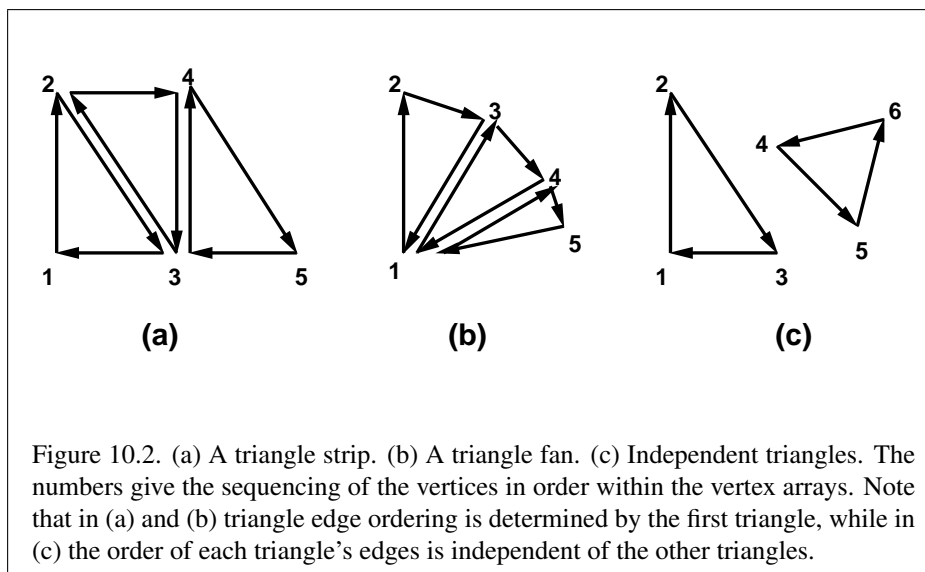
The required state consists of the processed vertex produced from the last vertex that was sent (so that a line segment can be generated from it to the current vertex), and a boolean flag indicating if the current vertex is the first vertex.

### 10.1.3 Line Loops

A line loop is specified with *mode* LINE\_LOOP. Loops are the same as line strips except that a final segment is added from the final specified vertex to the first vertex. The required state consists of the processed first vertex, in addition to the state required for line strips.

### 10.1.4 Separate Lines

Individual line segments, each defined by a pair of vertices, are specified with *mode* LINES. The first two vertices passed define the first segment, with subsequent pairs of vertices each defining one more segment. If the number of vertices passed is odd, then the last vertex is ignored. The state required is the same as for line strips



but it is used differently: a processed vertex holding the first vertex of the current segment, and a boolean flag indicating whether the current vertex is odd or even (a segment start or end).

### 10.1.5 Polygons

This subsection is only defined in the compatibility profile.

### 10.1.6 Triangle Strips

A triangle strip is a series of triangles connected along shared edges, and is specified with *mode* `TRIANGLE_STRIP`. In this case, the first three vertices define the first triangle (and their order is significant). Each subsequent vertex defines a new triangle using that point along with two vertices from the previous triangle. If fewer than three vertices are specified, no primitive is produced. See figure 10.2.

The required state consists of a flag indicating if the first triangle has been completed, two stored processed vertices, (called vertex A and vertex B), and a one bit pointer indicating which stored vertex will be replaced with the next vertex. When a series of vertices are transferred to the GL, the pointer is initialized to point to vertex A. Each successive vertex toggles the pointer. Therefore, the first vertex is stored as vertex A, the second stored as vertex B, the third stored as vertex A,

and so on. Any vertex after the second one sent forms a triangle from vertex A, vertex B, and the current vertex (in that order).

### 10.1.7 Triangle Fans

A triangle fan is specified with *mode* TRIANGLE\_FAN, and is the same as a triangle strip with one exception: each vertex after the first always replaces vertex B of the two stored vertices.

### 10.1.8 Separate Triangles

Separate triangles are specified with *mode* TRIANGLES. In this case, The  $3i + 1$ st,  $3i + 2$ nd, and  $3i + 3$ rd vertices (in that order) determine a triangle for each  $i = 0, 1, \dots, n - 1$ , where there are  $3n + k$  vertices drawn.  $k$  is either 0, 1, or 2; if  $k$  is not zero, the final  $k$  vertices are ignored. For each triangle, vertex A is vertex  $3i$  and vertex B is vertex  $3i + 1$ . Otherwise, separate triangles are the same as a triangle strip.

### 10.1.9 Quadrilateral (quad) strips

This subsection is only defined in the compatibility profile.

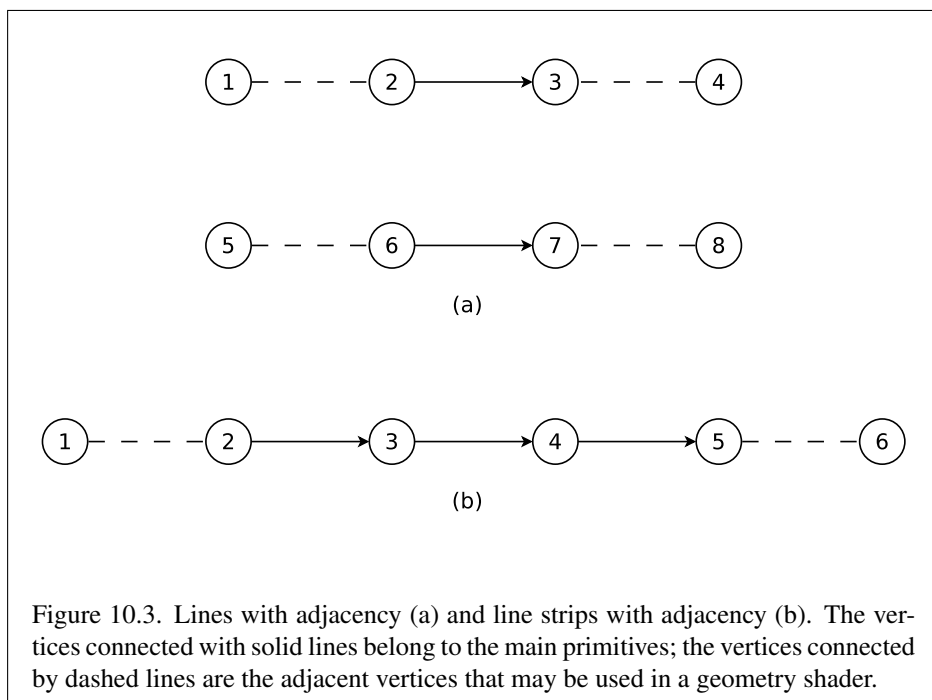
### 10.1.10 Separate Quadrilaterals

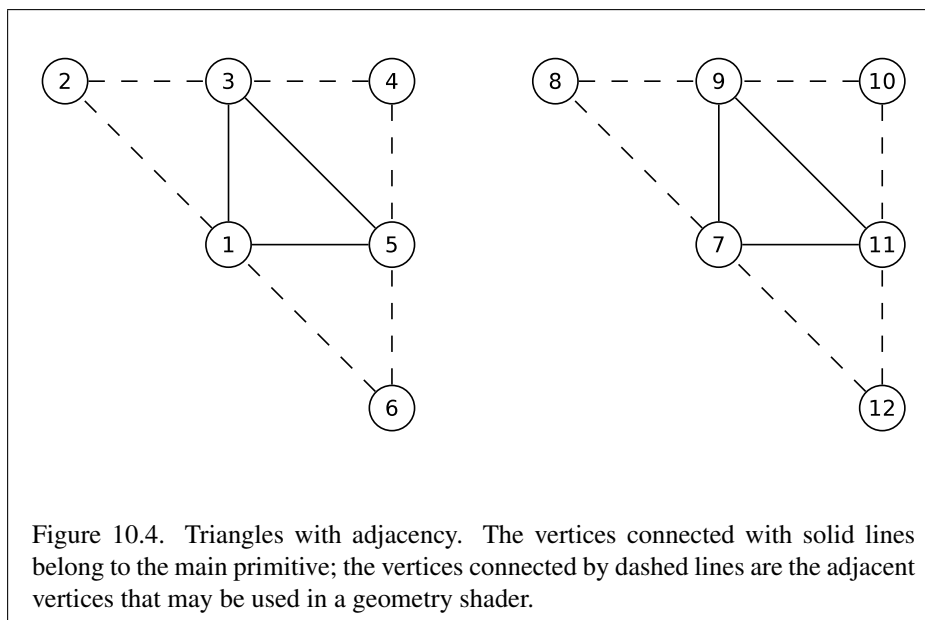
This subsection is only defined in the compatibility profile.

### 10.1.11 Lines with Adjacency

Lines with adjacency are specified with *mode* LINES\_ADJACENCY, and are independent line segments where each endpoint has a corresponding *adjacent* vertex that can be accessed by a geometry shader (section 11.3). If a geometry shader is not active, the adjacent vertices are ignored.

A line segment is drawn from the  $4i + 2$ nd vertex to the  $4i + 3$ rd vertex for each  $i = 0, 1, \dots, n - 1$ , where there are  $4n + k$  vertices passed.  $k$  is either 0, 1, 2, or 3; if  $k$  is not zero, the final  $k$  vertices are ignored. For line segment  $i$ , the  $4i + 1$ st and  $4i + 4$ th vertices are considered adjacent to the  $4i + 2$ nd and  $4i + 3$ rd vertices, respectively (see figure 10.3).





### 10.1.12 Line Strips with Adjacency

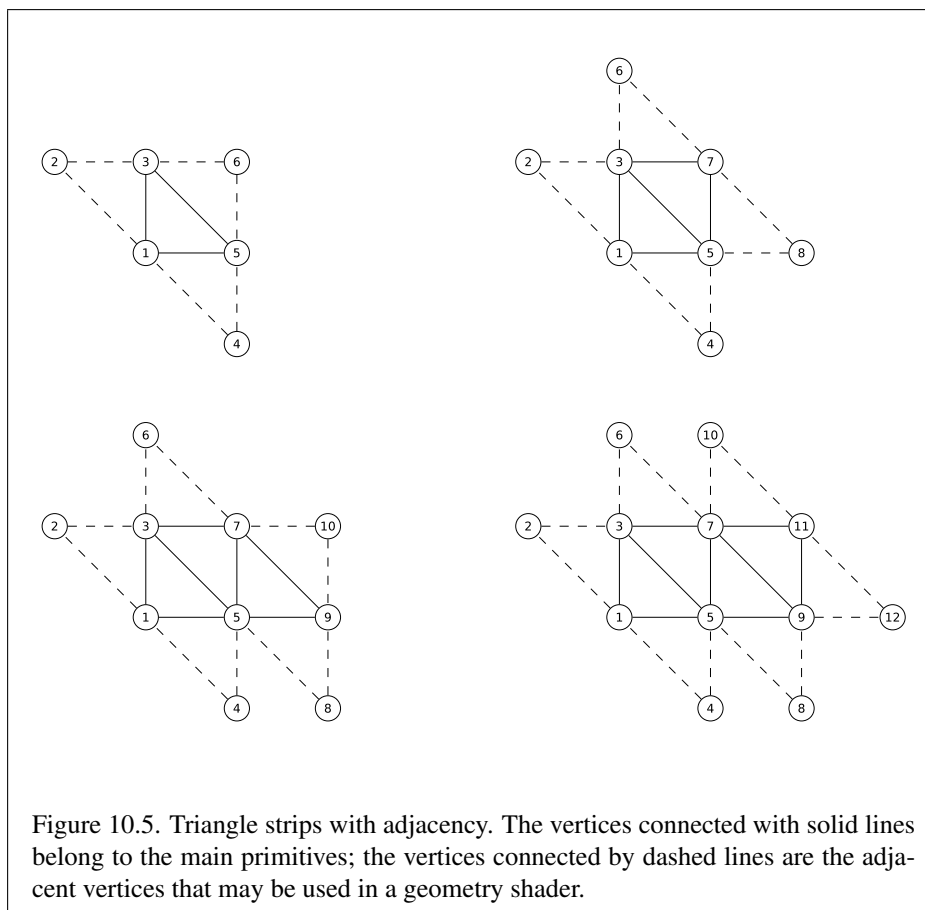
Line strips with adjacency are specified with *mode* `LINE_STRIP_ADJACENCY` and are similar to line strips, except that each line segment has a pair of adjacent vertices that can be accessed by a geometry shader. If a geometry shader is not active, the adjacent vertices are ignored.

A line segment is drawn from the  $i + 2$ nd vertex to the  $i + 3$ rd vertex for each  $i = 0, 1, \dots, n - 1$ , where there are  $n + 3$  vertices passed. If there are fewer than four vertices, all vertices are ignored. For line segment  $i$ , the  $i + 1$ st and  $i + 4$ th vertex are considered adjacent to the  $i + 2$ nd and  $i + 3$ rd vertices, respectively (see figure 10.3).

### 10.1.13 Triangles with Adjacency

Triangles with adjacency are specified with *mode* `TRIANGLES_ADJACENCY`, and are similar to separate triangles except that each triangle edge has an adjacent vertex that can be accessed by a geometry shader. If a geometry shader is not active, the adjacent vertices are ignored.

The  $6i + 1$ st,  $6i + 3$ rd, and  $6i + 5$ th vertices (in that order) determine a triangle for each  $i = 0, 1, \dots, n - 1$ , where there are  $6n + k$  vertices passed.  $k$  is either 0, 1, 2, 3, 4, or 5; if  $k$  is non-zero, the final  $k$  vertices are ignored. For triangle  $i$ ,



the  $i + 2$ nd,  $i + 4$ th, and  $i + 6$ th vertices are considered adjacent to edges from the  $i + 1$ st to the  $i + 3$ rd, from the  $i + 3$ rd to the  $i + 5$ th, and from the  $i + 5$ th to the  $i + 1$ st vertices, respectively (see figure 10.4).

#### 10.1.14 Triangle Strips with Adjacency

Triangle strips with adjacency are specified with *mode* `TRIANGLE_STRIP_ADJACENCY`, and are similar to triangle strips except that each line triangle edge has an adjacent vertex that can be accessed by a geometry shader. If a geometry shader is not active, the adjacent vertices are ignored.

In triangle strips with adjacency,  $n$  triangles are drawn where there are  $2(n + 2) + k$  vertices passed.  $k$  is either 0 or 1; if  $k$  is 1, the final vertex is ignored. If



Primitive	Primitive Vertices			Adjacent Vertices		
	1st	2nd	3rd	1/2	2/3	3/1
only ( $i = 0, n = 1$ )	1	3	5	2	6	4
first ( $i = 0$ )	1	3	5	2	7	4
middle ( $i$ odd)	$2i + 3$	$2i + 1$	$2i + 5$	$2i - 1$	$2i + 4$	$2i + 7$
middle ( $i$ even)	$2i + 1$	$2i + 3$	$2i + 5$	$2i - 1$	$2i + 7$	$2i + 4$
last ( $i = n - 1, i$ odd)	$2i + 3$	$2i + 1$	$2i + 5$	$2i - 1$	$2i + 4$	$2i + 6$
last ( $i = n - 1, i$ even)	$2i + 1$	$2i + 3$	$2i + 5$	$2i - 1$	$2i + 6$	$2i + 4$

Table 10.1: Triangles generated by triangle strips with adjacency. Each triangle is drawn using the vertices whose numbers are in the *1st*, *2nd*, and *3rd* columns under *primitive vertices*, in that order. The vertices in the *1/2*, *2/3*, and *3/1* columns under *adjacent vertices* are considered adjacent to the edges from the first to the second, from the second to the third, and from the third to the first vertex of the triangle, respectively. The six rows correspond to six cases: the first and only triangle ( $i = 0, n = 1$ ), the first triangle of several ( $i = 0, n > 0$ ), “odd” middle triangles ( $i = 1, 3, 5 \dots$ ), “even” middle triangles ( $i = 2, 4, 6, \dots$ ), and special cases for the last triangle, when  $i$  is either even or odd. For the purposes of this table, the first vertex passed is numbered 1 and the first triangle is numbered 0.

there are fewer than 6 vertices, the entire primitive is ignored. Table 10.1 describes the vertices and order used to draw each triangle, and which vertices are considered adjacent to each edge of the triangle (see figure 10.5).

### 10.1.15 Separate Patches

Separate patches are specified with mode `PATCHES`. A patch is an ordered collection of vertices used for primitive tessellation (section 11.2). The vertices comprising a patch have no implied geometric ordering. The vertices of a patch are used by tessellation shaders and the fixed-function tessellator to generate new point, line, or triangle primitives.

Each patch in the series has a fixed number of vertices, which is specified by calling

```
void PatchParameteri( enum pname, int value );
```

with *pname* set to `PATCH_VERTICES`.

**Errors**

An `INVALID_ENUM` error is generated if *pname* is not `PATCH_VERTICES`.

An `INVALID_VALUE` error is generated if *value* is less than or equal to zero, or greater than the implementation-dependent maximum patch size (the value of `MAX_PATCH_VERTICES`). The patch size is initially three vertices.

If the number of vertices in a patch is given by  $v$ , the  $vi + 1$ st through  $vi + v$ th vertices (in that order) determine a patch for each  $i = 0, 1, \dots, n - 1$ , where there are  $vn + k$  vertices.  $k$  is in the range  $[0, v - 1]$ ; if  $k$  is not zero, the final  $k$  vertices are ignored.

**10.1.16 General Considerations For Polygon Primitives**

Depending on the current state of the GL, a *polygon primitive* generated from a drawing command with *mode* `TRIANGLE_FAN`, `TRIANGLE_STRIP`, `TRIANGLES`, `TRIANGLES_ADJACENCY`, or `TRIANGLE_STRIP_ADJACENCY` may be rendered in one of several ways, such as outlining its border or filling its interior. The order of vertices in such a primitive is significant in polygon rasterization (see section 14.6.1) and fragment shading (see section 15.2.2).

**10.1.17 Polygon Edges**

This subsection is only defined in the compatibility profile.

**10.2 Current Vertex Attribute Values**

The commands in this section are used to specify *current attribute values*. These values are used by drawing commands to define the attributes transferred for a vertex when a vertex array defining a required attribute is not enabled, as described in section 10.3.

**10.2.1 Current Generic Attributes**

Vertex shaders (see section 11.1) access an array of 4-component *generic vertex attributes*. The first slot of this array is numbered zero, and the size of the array is specified by the implementation-dependent constant `MAX_VERTEX_ATTRIBS`.

The current values of a generic shader attribute declared as a floating-point scalar, vector, or matrix may be changed at any time by issuing one of the commands

```

void VertexAttrib{1234}{sfd}(uint index, T values);
void VertexAttrib{123}{sfd}v(uint index, const
    T *values);
void VertexAttrib4{bsifd ub us ui}v(uint index, const
    T *values);
void VertexAttrib4Nub(uint index, T values);
void VertexAttrib4N{bsi ub us ui}v(uint index, const
    T *values);
void VertexAttribI{1234}{i ui}(uint index, T values);
void VertexAttribI{1234}{i ui}v(uint index, const
    T *values);
void VertexAttribI4{b s ub us}v(uint index, const
    T *values);
void VertexAttribL{1234}d(uint index, const T values);
void VertexAttribL{1234}dv(uint index, const T *values);
void VertexAttribP{1234}ui(uint index, enum
    type, boolean normalized, uint value);
void VertexAttribP{1234}uiv(uint index, enum
    type, boolean normalized, const uint *value);

```

The **VertexAttrib4N**\* commands specify fixed-point values that are converted to a normalized  $[0, 1]$  or  $[-1, 1]$  range as described in equations 2.1 and 2.2, respectively.

The **VertexAttribI**\* commands specify signed or unsigned fixed-point values that are stored as signed or unsigned integers, respectively. Such values are referred to as *pure integers*.

The **VertexAttribL**\* commands specify double-precision values that will be stored as double-precision values.

The **VertexAttribP**\* commands specify up to four attribute component values packed into a single natural type *type* as described in section 10.3.7. *type* must be `INT_2_10_10_10_REV` or `UNSIGNED_INT_2_10_10_10_REV`, specifying signed or unsigned data respectively. The first one ( $x$ ), two ( $x, y$ ), three ( $x, y, z$ ), or four ( $x, y, z, w$ ) components of the packed data are consumed by **VertexAttribP1ui**, **VertexAttribP2ui**, **VertexAttribP3ui**, and **VertexAttribP4ui**, respectively. If *normalized* is `TRUE`, signed or unsigned components are converted to floating-point by normalizing to  $[-1, 1]$  or  $[0, 1]$  respectively. If *normalized* is false, components are cast directly to floating-point. For **VertexAttribP**\***uiv**, *value* contains the address of a single `uint` containing the packed attribute components.

All other **VertexAttrib**\* commands specify values that are converted directly to the internal floating-point representation.

The resulting value(s) are loaded into the generic attribute at slot *index*, whose components are named *x*, *y*, *z*, and *w*. The **VertexAttrib1\*** family of commands sets the *x* coordinate to the provided single argument while setting *y* and *z* to 0 and *w* to 1. Similarly, **VertexAttrib2\*** commands set *x* and *y* to the specified values, *z* to 0 and *w* to 1; **VertexAttrib3\*** commands set *x*, *y*, and *z*, with *w* set to 1, and **VertexAttrib4\*** commands set all four coordinates.

The **VertexAttrib\*** entry points may also be used to load shader attributes declared as a floating-point matrix. Each column of a matrix takes up one generic 4-component attribute slot out of the `MAX_VERTEX_ATTRIBS` available slots. Matrices are loaded into these slots in column major order. Matrix columns are loaded in increasing slot numbers.

When values for a vertex shader attribute variable are sourced from a current generic attribute value, the attribute must be specified by a command compatible with the data type of the variable. The values loaded into a shader attribute variable bound to generic attribute *index* are undefined if the current value for attribute *index* was not specified by

- **VertexAttrib[1234]\*** or **VertexAttribP\***, for single-precision floating-point scalar, vector, and matrix types
- **VertexAttribI[1234]i** or **VertexAttribI[1234]iv**, for signed integer scalar and vector types
- **VertexAttribI[1234]ui** or **VertexAttribI[1234]uiv**, for unsigned integer scalar and vector types
- **VertexAttribL\***, for double-precision floating-point scalar and vector types.

#### Errors

An `INVALID_VALUE` error is generated for all **VertexAttrib\*** commands if *index* is greater than or equal to the value of `MAX_VERTEX_ATTRIBS`.

### 10.2.2 ~~Current Conventional Attributes~~

This subsection is only defined in the compatibility profile.

### 10.2.3 Vertex Attribute Queries

Current generic vertex attribute values can be queried using the **GetVertexAttrib\*** commands as described in section 10.6.

### 10.2.4 Required State

The state required to support vertex specification consists of the value of `MAX_VERTEX_ATTRIBS` four-component vectors to store generic vertex attributes.

The initial values for all generic vertex attributes are (0.0, 0.0, 0.0, 1.0).

## 10.3 Vertex Arrays

Vertex data are placed into arrays that are stored in the server's address space (described in section 10.3.8). Blocks of data in these arrays may then be used to specify multiple geometric primitives through the execution of a single GL command.

### 10.3.1 Specifying Arrays for Generic Vertex Attributes

A generic vertex attribute array is described by an index into an array of vertex buffer bindings which contain the vertex data and state describing how that data is organized.

The commands

```
void VertexAttribFormat( uint attribindex, int size,
    enum type, boolean normalized, uint relativeoffset );
void VertexAttribIFormat( uint attribindex, int size,
    enum type, uint relativeoffset );
void VertexAttribLFormat( uint attribindex, int size,
    enum type, uint relativeoffset );
```

specify the organization of arrays to store generic vertex attributes. For each command, *attribindex* identifies the generic vertex attribute array being described; *size* indicates the number of values per vertex that are stored in the array, as well as their component ordering; and *type* specifies the data type of the values stored in the array.

Table 10.2 indicates the allowable values for *size* and *type*. A *type* of `BYTE`, `UNSIGNED_BYTE`, `SHORT`, `UNSIGNED_SHORT`, `INT`, `UNSIGNED_INT`, `FLOAT`, `HALF_FLOAT`, or `DOUBLE` indicates the corresponding GL data type shown in table 8.2; `FIXED` indicates the data type `fixed`; and `INT_2_10_10_10_REV` and `UNSIGNED_INT_2_10_10_10_REV` indicate respectively four signed or unsigned elements packed into a single `uint` (both correspond to the term *packed* in table 10.2). *packed* is not a GL type, but indicates commands accepting multiple components packed into a single `uint`.

Command	sizes and Component Ordering	Integer Handling	types
<b>VertexAttribFormat</b>	1, 2, 3, 4, BGRA	flag	byte, ubyte, short, ushort, int, uint, fixed, float, half, double, <i>packed</i>
<b>VertexAttribIFormat</b>	1, 2, 3, 4	integer	byte, ubyte, short, ushort, int, uint
<b>VertexAttribLFormat</b>	1, 2, 3, 4	n/a	double
<b>VertexAttribPointer</b>	1, 2, 3, 4, BGRA	flag	byte, ubyte, short, ushort, int, uint, fixed, float, half, double, <i>packed</i>
<b>VertexAttribIPointer</b>	1, 2, 3, 4	integer	byte, ubyte, short, ushort, int, uint
<b>VertexAttribLPointer</b>	1, 2, 3, 4	n/a	double

Table 10.2: Vertex array sizes (values per vertex) and data types for generic vertex attributes. See the body text for a full description of each column.

The “Integer Handling” column in table 10.2 indicates how fixed-point data types are handled. “integer” means that they remain as integer values, and “flag” means that they are either converted to floating-point directly, or converted by normalizing to  $[0, 1]$  (for unsigned types) or  $[-1, 1]$  (for signed types), depending on the setting of the *normalized* flag in **VertexAttribPointer**.

If *size* is BGRA, vertex array values are always normalized, irrespective of the “normalize” table entry.

Generic attribute arrays with integer *type* arguments can be handled in one of three ways: converted to float by normalizing to  $[0, 1]$  or  $[-1, 1]$  as described in equations 2.1 and 2.2, respectively; converted directly to float, or left as integers. Data for an array specified by **VertexAttribFormat** will be converted to floating-point by normalizing if *normalized* is TRUE, and converted directly to floating-point otherwise. Data for an array specified by **VertexAttribIFormat** will always be left as integer values; such data are referred to as *pure integers*. Data for an array specified by **VertexAttribLFormat** must be specified as double-precision floating-point values.

*relativeoffset* is a byte offset of the first element relative to the start of the vertex

buffer binding this attribute fetches from.

### Errors

An `INVALID_VALUE` error is generated if *attribindex* is greater than or equal to the value of `MAX_VERTEX_ATTRIBS`.

An `INVALID_VALUE` error is generated if *size* is not one of the values shown in table 10.2 for the corresponding command.

An `INVALID_ENUM` error is generated if *type* is not one of the parameter token names from table 8.2 corresponding to one of the allowed GL data types for that command as shown in table 10.2.

An `INVALID_OPERATION` error is generated under any of the following conditions:

- if no vertex array object is currently bound (see section 10.4);
  - size* is `BGRA` and *type* is not `UNSIGNED_BYTE`, `INT_2_10_10_10_REV` or `UNSIGNED_INT_2_10_10_10_REV`;
- *type* is `INT_2_10_10_10_REV` or `UNSIGNED_INT_2_10_10_10_REV`, and *size* is neither 4 nor `BGRA`;
- *size* is `BGRA` and *normalized* is `FALSE`;

An `INVALID_VALUE` error is generated if *relativeoffset* is larger than the value of `MAX_VERTEX_ATTRIB_RELATIVE_OFFSET`.

The command

```
void BindVertexBuffer( uint bindingindex, uint buffer,
                      intptr offset, sizei stride );
```

binds a buffer indicated by *buffer* to the vertex buffer bind point indicated by *bindingindex*, and sets the *stride* between elements and *offset* (in basic machine units) of the first element in the buffer. Pointers to the *i*th and (*i* + 1)st elements of an array differ by stride basic machine units (typically unsigned bytes), the pointer to the (*i* + 1)st element being greater. If *buffer* is zero, any buffer object attached to this bindpoint is detached.

### Errors

An `INVALID_VALUE` error is generated if *bindingindex* is greater than or equal to the value of `MAX_VERTEX_ATTRIB_BINDINGS`.

An `INVALID_VALUE` error is generated if *stride* or *offset* is negative.

An `INVALID_OPERATION` error is generated if no vertex array object is bound.

The association between a vertex attribute and the vertex buffer binding used by that attribute is set by the command

```
void VertexAttribBinding( uint attribindex,
                          uint bindingindex );
```

### Errors

An `INVALID_VALUE` error is generated if *attribindex* is greater than or equal to the value of `MAX_VERTEX_ATTRIBS`.

An `INVALID_VALUE` error is generated if *bindingindex* is greater than or equal to the value of `MAX_VERTEX_ATTRIB_BINDINGS`.

An `INVALID_OPERATION` error is generated if no vertex array object is bound.

The one, two, three, or four values in an array that correspond to a single vertex comprise an array *element*. When *size* is `BGRA`, it indicates four values. The values within each array element are stored sequentially in memory. However, if *size* is `BGRA`, the first, second, third, and fourth values of each array element are taken from the third, second, first, and fourth values in memory respectively.

The commands

```
void VertexAttribPointer( uint index, int size, enum type,
                          boolean normalized, sizei stride, const
                          void *pointer );
void VertexAttribIPointer( uint index, int size, enum type,
                             sizei stride, const void *pointer );
void VertexAttribLPointer( uint index, int size, enum type,
                             sizei stride, const void *pointer );
```

control vertex attribute state, a vertex buffer binding, and the mapping between a vertex attribute and a vertex buffer binding. They are equivalent to (assuming no errors are generated):

```
if (no buffer is bound to ARRAY_BUFFER, and pointer != NULL) {
    generate INVALID_OPERATION;
}
VertexAttrib*Format( index, size, type, { normalized, }, 0 );
```



```

VertexAttribBinding (index, index);
if (stride != 0) {
    effectiveStride = stride;
} else {
    compute effectiveStride based on size and type;
}
VERTEX_ATTRIB_ARRAY_STRIDE[index] = stride;
// This sets VERTEX_BINDING_STRIDE to effectiveStride
BindVertexBuffer (index, buffer bound to ARRAY_BUFFER,
    (char *)pointer - (char *)NULL, effectiveStride);

```

If *stride* is specified as zero, then array elements are stored sequentially.

An individual generic vertex attribute array is enabled or disabled by calling one of

```

void EnableVertexAttribArray(uint index);
void DisableVertexAttribArray(uint index);

```

where *index* identifies the generic vertex attribute array to enable or disable.

#### Errors

An `INVALID_VALUE` error is generated if *index* is greater than or equal to the value of `MAX_VERTEX_ATTRIBS`.

An `INVALID_OPERATION` error is generated if no vertex array object is bound.

### 10.3.2 ~~Specifying Arrays for Fixed-Function Attributes~~

This subsection is only defined in the compatibility profile.

### 10.3.3 Vertex Attribute Divisors

Each generic vertex attribute has a corresponding *divisor* which modifies the rate at which attributes advance, which is useful when rendering multiple instances of primitives in a single draw call. If the *divisor* is zero, the corresponding attributes advance once per vertex. Otherwise, attributes advance once per *divisor* instances of the set(s) of vertices being rendered. A generic attribute is referred to as *instanced* if its corresponding *divisor* value is non-zero.

The command

```
void VertexBindingDivisor( uint bindingindex,  
                          uint divisor );
```

sets the *divisor* value for attributes taken from the buffer bound to *bindingindex*.

#### Errors

An `INVALID_VALUE` error is generated if *bindingindex* is greater than or equal to the value of `MAX_VERTEX_ATTRIB_BINDINGS`.

The command

```
void VertexAttribDivisor( uint index, uint divisor );
```

is equivalent to (assuming no errors are generated):

```
VertexAttribBinding (index, index );  
VertexBindingDivisor (index, divisor );
```

#### Errors

An `INVALID_VALUE` error is generated if *index* is greater than or equal to the value of `MAX_VERTEX_ATTRIBS`.

An `INVALID_OPERATION` error is generated if no vertex array object is bound.

### 10.3.4 Transferring Array Elements

When an vertex is transferred to the GL by `DrawArrays`, `DrawElements`, or the other `Draw*` commands described below, each generic attribute is expanded to four components. If *size* is one then the *x* component of the attribute is specified by the array; the *y*, *z*, and *w* components are implicitly set to 0, 0, and 1, respectively. If *size* is two then the *x* and *y* components of the attribute are specified by the array; the *z* and *w* components are implicitly set to 0 and 1, respectively. If *size* is three then *x*, *y*, and *z* are specified, and *w* is implicitly set to 1. If *size* is four then all components are specified.

### 10.3.5 Primitive Restart

Primitive restarting is enabled or disabled by calling one of the commands

```
void Enable( enum target );
```

and

```
void Disable( enum target );
```

with *target* `PRIMITIVE_RESTART`. The command

```
void PrimitiveRestartIndex( uint index );
```

specifies a vertex array element that is treated specially when primitive restarting is enabled. This value is called the *primitive restart index*.

When one of the **Draw\*** commands transfers a set of generic attribute array elements to the GL, if the index within the vertex arrays corresponding to that set is equal to the primitive restart index, then the GL does not process those elements as a vertex. Instead, it is as if the drawing command ended with the immediately preceding transfer, and another drawing command is immediately started with the same parameters, but only transferring the immediately following element through the end of the originally specified elements.

When one of the **\*BaseVertex** drawing commands specified in section 10.5 is used, the primitive restart comparison occurs before the *basevertex* offset is added to the array index.

Primitive restart can also be enabled or disabled with a *target* of `PRIMITIVE_RESTART_FIXED_INDEX`. In this case, the primitive restart index is equal to  $2^N - 1$ , where  $N$  is 8, 16 or 32 if the type is `UNSIGNED_BYTE`, `UNSIGNED_SHORT`, or `UNSIGNED_INT`, respectively, and the *index* value specified by **PrimitiveRestartIndex** is ignored.

If both `PRIMITIVE_RESTART` and `PRIMITIVE_RESTART_FIXED_INDEX` are enabled, the *index* value determined by `PRIMITIVE_RESTART_FIXED_INDEX` is used. If `PRIMITIVE_RESTART_FIXED_INDEX` is enabled, primitive restart is not performed for array elements transferred by any drawing command not taking a *type* parameter, including all of the **\*Draw\*** commands other than **\*DrawElements\***.

### 10.3.6 Robust Buffer Access

Robust buffer access can be enabled by creating a context with robust access enabled through the window system binding APIs. When enabled, indices within the element array (see section 10.3.9) that reference vertex data that lies on the enabled attribute's vertex buffer object result in reading zero. It is not possible to read vertex data from outside the enabled vertex buffer objects or from another GL context, and these accesses do not result in abnormal program termination. Reading from disabled attributes results in reading zeros for all components.

### 10.3.7 Packed Vertex Data Formats

UNSIGNED\_INT\_2\_10\_10\_10\_REV and INT\_2\_10\_10\_10\_REV vertex data formats describe packed, 4 component formats stored in a single 32-bit word.

For the UNSIGNED\_INT\_2\_10\_10\_10\_REV vertex data format, the first ( $x$ ), second ( $y$ ), and third ( $z$ ) components are represented as 10-bit unsigned integer values and the fourth ( $w$ ) component is represented as a 2-bit unsigned integer value.

For the INT\_2\_10\_10\_10\_REV vertex data format, the  $x$ ,  $y$  and  $z$  components are represented as 10-bit signed two's complement integer values and the  $w$  component is represented as a 2-bit signed two's complement integer value.

The *normalized* value is used to indicate whether to normalize the data to  $[0, 1]$  (for unsigned types) or  $[-1, 1]$  (for signed types). During normalization, the conversion rules specified in equations 2.1 and 2.2 are followed.

Tables 10.3 and 10.4 describe how these components are laid out in a 32-bit word.

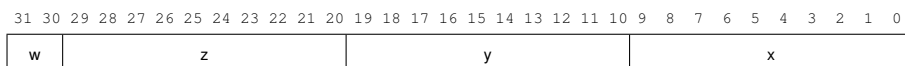


Table 10.3: Packed component layout for non-BGRA formats. Bit numbers are indicated for each component.

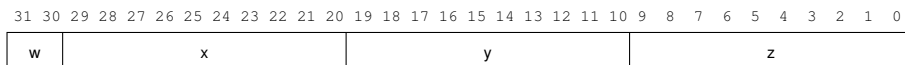


Table 10.4: Packed component layout for BGRA format. Bit numbers are indicated for each component.

### 10.3.8 Vertex Arrays in Buffer Objects

Blocks of vertex array data are stored in buffer objects with the same format and layout options described in section 10.3.

A buffer object binding point is added to the client state associated with each vertex array `index`. The commands that specify the locations and organizations of vertex arrays copy the buffer object name that is bound to `ARRAY_BUFFER` to the binding point corresponding to the vertex array `index` being specified. For example, the **VertexAttribPointer** command copies the value of `ARRAY_BUFFER_`

BINDING (the queryable name of the buffer binding corresponding to the target ARRAY\_BUFFER) to the client state variable VERTEX\_ATTRIB\_ARRAY\_BUFFER\_BINDING for the specified *index*.

Rendering commands **DrawArrays**, and the other drawing commands defined in section 10.5 operate as previously defined, where data for enabled generic attribute arrays are sourced from buffer objects.

When an array is sourced from a buffer object for a vertex attribute, the *bindingindex* set with **VertexAttribBinding** for that attribute indicates which vertex buffer binding is used. The sum of the *relativeoffset* set for the attribute with **VertexAttrib\*Format** and the *offset* set for the vertex buffer with **BindVertexBuffer** is used as the offset in basic machine units of the first element in that buffer's data store.

If any enabled array's buffer binding is zero when **DrawArrays** or one of the other drawing commands defined in section 10.5 is called, the result is undefined.

### 10.3.9 Array Indices in Buffer Objects

Blocks of array indices are stored in buffer objects in the formats described by the *type* parameter of **DrawElements** (see section 10.5).

A buffer object is bound to ELEMENT\_ARRAY\_BUFFER by calling **BindBuffer** with *target* set to ELEMENT\_ARRAY\_BUFFER, and *buffer* set to the name of the buffer object. If no corresponding buffer object exists, one is initialized as defined in section 6.

**DrawElements**, **DrawRangeElements**, and **DrawElementsInstanced** source their indices from the buffer object whose name is bound to ELEMENT\_ARRAY\_BUFFER, using their *indices* parameters as offsets into the buffer object in the same fashion as described in section 10.3.8. **DrawElementsBaseVertex**, **DrawRangeElementsBaseVertex**, and **DrawElementsInstancedBaseVertex** also source their indices from that buffer object, adding the *basevertex* offset to the appropriate vertex index as a final step before indexing into the vertex buffer; this does not affect the calculation of the base pointer for the index array. Finally, **MultiDrawElements** and **MultiDrawElementsBaseVertex** also source their indices from that buffer object, using its *indices* parameter as a pointer to an array of pointers that represent offsets into the buffer object. If zero is bound to ELEMENT\_ARRAY\_BUFFER, the result of these drawing commands is undefined.

In some cases performance will be optimized by storing indices and array data in separate buffer objects, and by creating those buffer objects with the corresponding binding points.

### 10.3.10 Indirect Commands in Buffer Objects

Arguments to the **DrawArraysIndirect**, **DrawElementsIndirect**, **MultiDrawArraysIndirect**, and **MultiDrawElementsIndirect** drawing commands described in section 10.5 may be stored in buffer objects in the formats described in section 10.5 for the `DrawArraysIndirectCommand` and `DrawElementsIndirectCommand` structures, respectively.

A buffer object is bound to `DRAW_INDIRECT_BUFFER` by calling **BindBuffer** with *target* set to `DRAW_INDIRECT_BUFFER`, and *buffer* set to the name of the buffer object. If no corresponding buffer object exists, one is initialized as defined in section 6.

these commands source their arguments from the buffer object whose name is bound to `DRAW_INDIRECT_BUFFER`, using their *indirect* parameters as offsets into the buffer object in the same fashion as described in section 10.3.8.

An `INVALID_OPERATION` error is generated if these commands source data beyond the end of the buffer object, if zero is bound to `DRAW_INDIRECT_BUFFER`, or if *indirect* is not aligned to a multiple of the size, in basic machine units, of `uint`.

Arguments to the **DispatchComputeIndirect** command described in section 19 are stored in buffer objects as a group of three unsigned integers.

A buffer object is bound to `DISPATCH_INDIRECT_BUFFER` by calling **BindBuffer** with *target* set to `DISPATCH_INDIRECT_BUFFER`, and *buffer* set to the name of the buffer object. If no corresponding buffer object exists, one is initialized as defined in section 6. Initially zero is bound to `DISPATCH_INDIRECT_BUFFER`.

**DispatchComputeIndirect** sources its arguments from the buffer object whose name is bound to `DISPATCH_INDIRECT_BUFFER`, using the *indirect* parameter as an offset into the buffer object in the same fashion as described in section 10.3.8.

An `INVALID_OPERATION` error is generated if this command sources data beyond the end of the buffer object, if zero is bound to `DISPATCH_INDIRECT_BUFFER`, if *indirect* is negative, or if *indirect* is not aligned to a multiple of the size, in basic machine units, of `uint`.

## 10.4 Vertex Array Objects

The buffer objects that are to be used by the vertex stage of the GL are collected together to form a vertex array object. All state related to the definition of data used by the vertex processor is encapsulated in a vertex array object.

The name space for vertex array objects is the unsigned integers, with zero reserved by the GL.

The command

```
void GenVertexArrays( sizei n, uint *arrays );
```

returns *n* previous unused vertex array object names in *arrays*. These names are marked as used, for the purposes of **GenVertexArrays** only, but they acquire array state only when they are first bound.

#### Errors

An `INVALID_VALUE` error is generated if *n* is negative.

Vertex array objects are deleted by calling

```
void DeleteVertexArrays( sizei n, const uint *arrays );
```

*arrays* contains *n* names of vertex array objects to be deleted. Once a vertex array object is deleted it has no contents and its name is again unused. If a vertex array object that is currently bound is deleted, the binding for that object reverts to zero and no vertex array object is bound. Unused names in *arrays* that have been marked as used for the purposes of **GenVertexArrays** are marked as unused again. Unused names in *arrays* are silently ignored, as is the value zero.

#### Errors

An `INVALID_VALUE` error is generated if *n* is negative.

A vertex array object is created by binding a name returned by **GenVertexArrays** with the command

```
void BindVertexArray( uint array );
```

*array* is the vertex array object name. The resulting vertex array object is a new state vector, comprising all the state and with the same initial values listed in tables 23.3 and 23.4.

**BindVertexArray** may also be used to bind an existing vertex array object. If the bind is successful no change is made to the state of the bound vertex array object, and any previous binding is broken.

The currently bound vertex array object is used for all commands which modify vertex array state, such as **VertexAttribPointer** and **EnableVertexAttribArray**; all commands which draw from vertex arrays, such as **DrawArrays** and **DrawElements**; and all queries of vertex array state (see chapter 22).

**Errors**

An `INVALID_OPERATION` error is generated if *array* is not zero or a name returned from a previous call to **GenVertexArrays**, or if such a name has since been deleted with **DeleteVertexArrays**.

An `INVALID_OPERATION` error is generated by any commands which modify, draw from, or query vertex array state when no vertex array is bound. This occurs in the initial GL state, and may occur as a result of **BindVertexArray** or a side effect of **DeleteVertexArrays**.

The command

```
boolean IsVertexArray( uint array );
```

returns `TRUE` if *array* is the name of a vertex array object. If *array* is zero, or a non-zero value that is not the name of a vertex array object, **IsVertexArray** returns `FALSE`. No error is generated if *array* is not a valid vertex array object name.

## 10.5 Drawing Commands Using Vertex Arrays

The command

```
void DrawArraysOneInstance( enum mode, int first,  
    sizei count, int instance, uint baseinstance );
```

does not exist in the GL, but is used to describe functionality in the rest of this section. This command constructs a sequence of geometric primitives by successively transferring elements for *count* vertices. Elements *first* through *first* + *count* - 1 of each enabled non-instanced array are transferred to the GL. *mode* specifies what kind of primitives are constructed, and must be one of the primitive types defined in section 10.1.

If an enabled vertex attribute array is instanced (it has a non-zero *divisor* as specified by **VertexAttribDivisor**), the element index that is transferred to the GL, for all vertices, is given by

$$\left\lfloor \frac{\textit{instance}}{\textit{divisor}} \right\rfloor + \textit{baseinstance}$$

If an array corresponding to an attribute required by a vertex shader is not enabled, then the corresponding element is taken from the current attribute state (see section 10.2).



If an array is enabled, the corresponding current vertex attribute value is unaffected by the execution of **DrawArraysOneInstance**.

The value of *instance* may be read by a vertex shader as `gl_InstanceID`, as described in section 11.1.3.9.

### Errors

An `INVALID_ENUM` error is generated if *mode* is not one of the primitive types defined in section 10.1.

Specifying *first* < 0 results in undefined behavior. Generating an `INVALID_VALUE` error is recommended in this case.

An `INVALID_VALUE` error is generated if *count* is negative.

An `INVALID_OPERATION` error is generated if no vertex array object is bound (see section 10.4),

The command

```
void DrawArrays( enum mode, int first, sizei count );
```

is equivalent to

```
DrawArraysOneInstance( mode, first, count, 0, 0 );
```

The command

```
void DrawArraysInstancedBaseInstance( enum mode,
    int first, sizei count, sizei instancecount,
    uint baseinstance );
```

behaves identically to **DrawArrays** except that *instancecount* instances of the range of elements are executed and the value of *instance* advances for each iteration. Those attributes that have non-zero values for *divisor*, as specified by **VertexAttribDivisor**, advance once every *divisor* instances. Additionally, the first element within those instanced vertex attributes is specified in *baseinstance*.

**DrawArraysInstancedBaseInstance** is equivalent to

```
if ( mode, count, or instancecount is invalid )
    generate appropriate error
else {
    for ( i = 0; i < instancecount; i++ ) {
        DrawArraysOneInstance( mode, first, count, i,
```

```

        baseinstance);
    }
}

```

The command

```

void DrawArraysInstanced( enum mode, int first,
   sizei count, sizei instancecount );

```

is equivalent to

```

DrawArraysInstancedBaseInstance( mode, first, count, instancecount, 0 );

```

The command

```

void DrawArraysIndirect( enum mode, const
    void *indirect );

```

is equivalent to

```

typedef struct {
    uint count;
    uint instanceCount;
    uint first;
    uint baseInstance;
} DrawArraysIndirectCommand;

DrawArraysIndirectCommand *cmd =
    (DrawArraysIndirectCommand *)indirect;
DrawArraysInstancedBaseInstance( mode, cmd->first, cmd->count,
    cmd->instanceCount, cmd->baseInstance );

```

Unlike **DrawArraysInstanced**, *first* is unsigned and cannot cause an error.

### Errors

An `INVALID_OPERATION` error is generated if zero is bound to `DRAW_INDIRECT_BUFFER`.

All elements of `DrawArraysIndirectCommand` are tightly packed 32 bit values.

The command

```
void MultiDrawArrays(enum mode, const int *first,
    const sizei *count, sizei drawcount);
```

behaves identically to **DrawArraysInstanced** except that *drawcount* separate ranges of elements are specified instead, all elements are treated as though they are not instanced, and the value of *instance* remains zero. It is equivalent to

```
if (mode or drawcount is invalid)
    generate appropriate error
else {
    for (i = 0; i < drawcount; i++) {
        if (count[i] > 0)
            DrawArraysOneInstance(mode, first[i], count[i],
                0, 0);
    }
}
```

The command

```
void MultiDrawArraysIndirect(enum mode, const
    void *indirect, sizei drawcount, sizei stride);
```

behaves identically to **DrawArraysIndirect** except that *indirect* is treated as an array of *drawcount* `DrawArraysIndirectCommand` structures. *indirect* contains the offset of the first element of the array within the buffer currently bound to the `DRAW_INDIRECT` buffer binding. *stride* specifies the distance, in basic machine units, between the elements of the array. If *stride* is zero, the array elements are treated as tightly packed.

It is equivalent to

```
if (mode is invalid)
    generate appropriate error
else {
    const ubyte *ptr = (const ubyte *)indirect;
    for (i = 0; i < drawcount; i++) {
        DrawArraysIndirect(mode, (DrawArraysIndirectCommand*)ptr);
        if (stride == 0) {
            ptr += sizeof(DrawArraysIndirectCommand);
        } else {
            ptr += stride;
        }
    }
}
```

```

    }
}

```

### Errors

An `INVALID_VALUE` error is generated if *stride* is neither zero nor a multiple of four.

An `INVALID_VALUE` error is generated if *drawcount* is not positive.

The command

```

void DrawElementsOneInstance( enum mode, sizei count,
    enum type, const void *indices, int instance,
    uint baseinstance );

```

does not exist in the GL, but is used to describe functionality in the rest of this section. This command constructs a sequence of geometric primitives by successively transferring elements for *count* vertices to the GL. The *i*th element transferred by **DrawElementsOneInstance** will be taken from the element whose index is stored in the currently bound element array buffer at offset *indices* + *i*.

*type* must be one of `UNSIGNED_BYTE`, `UNSIGNED_SHORT`, or `UNSIGNED_INT`, indicating that the index values are of GL type `ubyte`, `ushort`, or `uint` respectively. *mode* specifies what kind of primitives are constructed, and must be one of the primitive types defined in section 10.1.

If an enabled vertex attribute array is instanced (it has a non-zero *divisor* as specified by **VertexAttribDivisor**), the element index that is transferred to the GL, for all vertices, is given by

$$\left\lfloor \frac{instance}{divisor} \right\rfloor + baseinstance$$

If an array corresponding to an attribute required by a vertex shader is not enabled, then the corresponding element is taken from the current attribute state (see section 10.2).

GL implementations do not restrict index values; any value representable in a `uint` may be used. However, for compatibility with OpenGL ES implementations, the maximum representable index value may be queried by calling **GetInteger64v** with *pname* `MAX_ELEMENT_INDEX`, and will return  $2^{32} - 1$ .

If an array is enabled, the corresponding current vertex attribute value is unaffected by the execution of **DrawElementsOneInstance**.

The value of *instance* may be read by a vertex shader as `gl_InstanceID`, as described in section 11.1.3.9.

An `INVALID_ENUM` error is generated if *mode* is not one of the primitive types defined in section 10.1.

An `INVALID_OPERATION` error is generated if no vertex array object is bound (see section 10.4),

The command

```
void DrawElements( enum mode, sizei count, enum type,
                  const void *indices );
```

behaves identically to **DrawElementsOneInstance** with the *instance* and *baseinstance* parameters set to zero; the effect of calling

```
DrawElements (mode, count, type, indices );
```

is equivalent

```
if (mode, count or type is invalid)
    generate appropriate error
else
    DrawElementsOneInstance (mode, count, type, indices, 0, 0);
```

The command

```
void DrawElementsInstancedBaseInstance( enum mode,
                                         sizei count, enum type, const void *indices,
                                         sizei instancecount, uint baseinstance );
```

behaves identically to **DrawElements** except that *instancecount* instances of the set of elements are executed and the value of *instance* advances between each set. Instanced attributes are advanced as they do during execution of **DrawArraysInstancedBaseInstance**, and *baseinstance* has the same effect. It is equivalent to

```
if (mode, count, type, or instancecount is invalid)
    generate appropriate error
else {
    for (int i = 0; i < instancecount; i++) {
        DrawElementsOneInstance (mode, count, type, indices, i,
                                baseinstance );
    }
}
```

The command

```
void DrawElementsInstanced( enum mode, sizei count,
                           enum type, const void *indices, sizei instancecount );
```

behaves identically to **DrawElementsInstancedBaseInstance** except that *baseinstance* is zero. It is equivalent to

```
DrawElementsInstancedBaseInstance (mode, count, type, indices,
                                     instancecount, 0);
```

The command

```
void MultiDrawElements( enum mode, const
                          sizei *count, enum type, const void *const *indices,
                          sizei drawcount );
```

behaves identically to **DrawElementsInstanced** except that *drawcount* separate sets of elements are specified instead, all elements are treated as though they are not instanced, and the value of *instance* remains zero. It is equivalent to

```
if (mode, count, drawcount, or type is invalid)
    generate appropriate error
else {
    for (int i = 0; i < drawcount; i++)
        DrawElementsOneInstance (mode, count[i], type,
                                   indices[i], 0, 0);
}
```

The command

```
void DrawRangeElements( enum mode, uint start,
                          uint end, sizei count, enum type, const
                          void *indices );
```

is a restricted form of **DrawElements**. *mode*, *count*, *type*, and *indices* match the corresponding arguments to **DrawElements**, with the additional constraint that all index values identified by *indices* must lie between *start* and *end* inclusive.

Implementations denote recommended maximum amounts of vertex and index data, which may be queried by calling **GetIntegerv** with the symbolic constants `MAX_ELEMENTS_VERTICES` and `MAX_ELEMENTS_INDICES`. If  $end - start + 1$  is greater than the value of `MAX_ELEMENTS_VERTICES`, or if *count* is greater than the value of `MAX_ELEMENTS_INDICES`, then the call may operate at reduced performance. There is no requirement that all vertices in the range  $[start, end]$  be referenced. However, the implementation may partially process unused vertices, reducing performance from what could be achieved with an optimal index set.

**Errors**

An `INVALID_VALUE` error is generated if  $end < start$ .

Invalid *mode*, *count*, or *type* parameters generate the same errors as would the corresponding call to **DrawElements**.

It is an error for index values (other than the primitive restart index, when primitive restart is enabled) to lie outside the range  $[start, end]$ , but implementations are not required to check for this. Such indices will cause implementation-dependent behavior.

The commands

```
void DrawElementsBaseVertex( enum mode, sizei count,
                             enum type, const void *indices, int basevertex );
void DrawRangeElementsBaseVertex( enum mode,
                                   uint start, uint end, sizei count, enum type, const
                                   void *indices, int basevertex );
void DrawElementsInstancedBaseVertex( enum mode,
                                       sizei count, enum type, const void *indices,
                                       sizei instancecount, int basevertex );
void DrawElementsInstancedBaseVertexBaseInstance(
    enum mode, sizei count, enum type, const
    void *indices, sizei instancecount, int basevertex,
    uint baseinstance );
```

are equivalent to the commands with the same base name (without the **BaseVertex** suffix), except that the *i*th element transferred by the corresponding draw call will be taken from element  $indices[i] + basevertex$  of each enabled array. If the resulting value is larger than the maximum value representable by *type*, it should behave as if the calculation were upconverted to 32-bit unsigned integers (with wrapping on overflow conditions). The operation is undefined if the sum would be negative and should be handled as described in section 6.4. For **DrawRangeElementsBaseVertex**, the index values must lie between *start* and *end* inclusive, prior to adding the *basevertex* offset. Index values lying outside the range  $[start, end]$  are treated in the same way as **DrawRangeElements**.

For **DrawElementsInstancedBaseVertexBaseInstance**, *baseinstance* is used to offset the element from which instanced vertex attributes (those with a non-zero divisor as specified by **VertexAttribDivisor**) are taken.

The command

```
void DrawElementsIndirect( enum mode, enum type, const
    void *indirect );
```

is equivalent to

```
typedef struct {
    uint count;
    uint instanceCount;
    uint firstIndex;
    int baseVertex;
    uint baseInstance;
} DrawElementsIndirectCommand;

if (no element array buffer is bound) {
    generate appropriate error
} else {
    DrawElementsIndirectCommand *cmd =
    (DrawElementsIndirectCommand *)indirect;

    DrawElementsInstancedBaseVertexBaseInstance (mode,
        cmd->count, type,
        cmd->firstIndex * size-of-type,
        cmd->instanceCount, cmd->baseVertex,
        cmd->baseInstance);
}
```

An `INVALID_OPERATION` error is generated if zero is bound to `DRAW_INDIRECT_BUFFER`, or if no element array buffer is bound.

All elements of `DrawElementsIndirectCommand` are tightly packed.

The command

```
void MultiDrawElementsIndirect( enum mode, enum type,
    const void *indirect, sizei drawcount, sizei stride );
```

behaves identically to `DrawElementsIndirect` except that *indirect* is treated as an array of *drawcount* `DrawElementsIndirectCommand` structures. *indirect* contains the offset of the first element of the array within the buffer currently bound to the `DRAW_INDIRECT` buffer binding. *stride* specifies the distance, in basic machine units, between the elements of the array. If *stride* is zero, the array elements are treated as tightly packed.

It is equivalent to



```

if (mode or type is invalid)
    generate appropriate error
else {
    const ubyte *ptr = (const ubyte *)indirect;
    for (i = 0; i < drawcount; i++) {
        DrawElementsIndirect(mode, type,
            (DrawElementsIndirectCommand*)ptr);
        if (stride == 0) {
            ptr += sizeof(DrawElementsIndirectCommand);
        } else {
            ptr += stride;
        }
    }
}

```

### Errors

An `INVALID_VALUE` error is generated if *stride* is neither zero nor a multiple of four.

An `INVALID_VALUE` error is generated if *drawcount* is not positive.

The command

```

void MultiDrawElementsBaseVertex(enum mode, const
    sizei *count, enum type, const void *const *indices,
    sizei drawcount, const int *basevertex);

```

behaves identically to **DrawElementsBaseVertex**, except that *drawcount* separate lists of elements are specified instead. It is equivalent to

```

if (mode or drawcount is invalid)
    generate appropriate error
else {
    for (int i = 0; i < drawcount; i++)
        if (count[i] > 0)
            DrawElementsBaseVertex(mode, count[i], type,
                indices[i], basevertex[i]);
}

```

### 10.5.1 Interleaved Arrays

This subsection is only defined in the compatibility profile.

## 10.6 Vertex Array and Vertex Array Object Queries

Queries of vertex array state variables are qualified by the value of `VERTEX_ARRAY_BINDING` to determine which vertex array object is queried. Tables 23.3 and 23.4 define the set of state stored in a vertex array object.

The commands

```
void GetVertexAttribdv(uint index, enum pname,
    double *params);
void GetVertexAttribfv(uint index, enum pname,
    float *params);
void GetVertexAttribiv(uint index, enum pname,
    int *params);
void GetVertexAttribIiv(uint index, enum pname,
    int *params);
void GetVertexAttribIuiv(uint index, enum pname,
    uint *params);
void GetVertexAttribLdv(uint index, enum pname,
    double *params);
```

obtain the vertex attribute state named by *pname* for the generic vertex attribute numbered *index* and places the information in the array *params*. *pname* must be one of `VERTEX_ATTRIB_ARRAY_BUFFER_BINDING`, `VERTEX_ATTRIB_ARRAY_ENABLED`, `VERTEX_ATTRIB_ARRAY_SIZE`, `VERTEX_ATTRIB_ARRAY_STRIDE`, `VERTEX_ATTRIB_ARRAY_TYPE`, `VERTEX_ATTRIB_ARRAY_NORMALIZED`, `VERTEX_ATTRIB_ARRAY_INTEGER`, `VERTEX_ATTRIB_ARRAY_LONG`, `VERTEX_ATTRIB_ARRAY_DIVISOR`, or `CURRENT_VERTEX_ATTRIB`. Note that all the queries except `CURRENT_VERTEX_ATTRIB` return values stored in the currently bound vertex array object (the value of `VERTEX_ARRAY_BINDING`).

All but `CURRENT_VERTEX_ATTRIB` return information about generic vertex attribute arrays. The enable state of a generic vertex attribute array is set by the command **EnableVertexAttribArray** and cleared by **DisableVertexAttribArray**. The size, stride, type, normalized flag, and unconverted integer flag are set by the commands **VertexAttribPointer** and **VertexAttribIPointer**. The normalized flag is always set to `FALSE` by **VertexAttribIPointer**. The unconverted integer flag is always set to `FALSE` by **VertexAttribPointer** and `TRUE` by **VertexAttribIPointer**.

The query `CURRENT_VERTEX_ATTRIB` returns the current value for the generic attribute *index*. **GetVertexAttribdv** and **GetVertexAttribfv** read and return the current attribute values as four floating-point values; **GetVertexAttribiv** reads them as floating-point values and converts them to four integer values; **GetVertexAttribIiv** reads and returns them as four signed integers; **GetVertexAttribIuiv** reads and returns them as four unsigned integers; and **GetVertexAttribLdv** reads and returns them as four double-precision floating-point values. The results of the query are undefined if the current attribute values are read using one data type but were specified using a different one.

#### Errors

An `INVALID_VALUE` error is generated if *index* is greater than or equal to the value of `MAX_VERTEX_ATTRIBS`.

An `INVALID_OPERATION` error is generated if no vertex array object is bound (see section 10.4).

An `INVALID_ENUM` error is generated if *pname* is not one of the values listed above.

The command

```
void GetVertexAttribPointerv(uint index, enum pname,
    const void **pointer);
```

obtains the pointer named *pname* for the vertex attribute numbered *index* and places the information in the array *pointer*. *pname* must be `VERTEX_ATTRIB_ARRAY_POINTER`. The value returned is queried from the currently bound vertex array object.

#### Errors

An `INVALID_VALUE` error is generated if *index* is greater than or equal to the value of `MAX_VERTEX_ATTRIBS`.

An `INVALID_OPERATION` error is generated if no vertex array object is bound (see section 10.4).

## 10.7 Required State

Let the number of supported generic vertex attributes (the value of `MAX_VERTEX_ATTRIBS`) be *n*. Let the number of supported generic vertex attribute bindings (the value of `MAX_VERTEX_ATTRIB_BINDINGS`) be *k*.

Then then the state required to implement vertex arrays consists of  $n$  boolean values,  $n$  memory pointers,  $n$  integer stride values,  $n$  symbolic constants representing array types,  $n$  integers representing values per element,  $n$  boolean values indicating normalization,  $n$  boolean values indicating whether the attribute values are pure integers,  $n$  integers representing vertex attribute divisors,  $n$  integer vertex attribute binding indices,  $n$  integer relative offsets,  $k$  64-bit integer vertex binding offsets,  $k$  integer vertex binding strides, an unsigned integer representing the primitive restart index, and two booleans representing the enable state of primitive restart and primitive restart with a fixed index.

In the initial state, the boolean values are each false, the memory pointers are each `NULL`, the strides are each zero, the array types are each `FLOAT`, the integers representing values per element are each four, the normalized and pure integer flags are each false, the divisors are each zero, the binding indices are  $i$  for each attribute  $i$ , the relative offsets are each zero, the vertex binding offsets are each zero, the vertex binding strides are each 16, the restart index is zero, and the restart enables are both `FALSE`.

## 10.8 ~~Drawing Commands Using Begin and End~~

[This section is only defined in the compatibility profile.](#)

## 10.9 Rectangles

[This section is only defined in the compatibility profile.](#)

## 10.10 Conditional Rendering

Conditional rendering can be used to discard rendering commands based on the result of an occlusion query. Conditional rendering is started and stopped using the commands

```
void BeginConditionalRender(uint id, enum mode);  
void EndConditionalRender(void);
```

*id* specifies the name of an occlusion query object whose results are used to determine if the rendering commands are discarded. If the result (`SAMPLES_PASSED`) of the query is zero, or if the result (`ANY_SAMPLES_PASSED` or `ANY_SAMPLES_PASSED_CONSERVATIVE`) is false, all rendering commands between **BeginConditionalRender** and the corresponding **EndConditionalRender** are discarded. In

this case, all drawing commands (see section 10.5), as well as **Clear** and **Clear-Buffer\*** (see section 17.4.3), and compute dispatch through **DispatchCompute\*** (see section 19), have no effect.

The effect of commands setting current vertex state, such as **VertexAttrib**, are undefined. If the result (`SAMPLES_PASSED`) of the query is non-zero, or if the result (`ANY_SAMPLES_PASSED` or `ANY_SAMPLES_PASSED_CONSERVATIVE`) is true, such commands are not discarded.

*mode* specifies how **BeginConditionalRender** interprets the results of the occlusion query given by *id*. If *mode* is `QUERY_WAIT`, the GL waits for the results of the query to be available and then uses the results to determine if subsequent rendering commands are discarded. If *mode* is `QUERY_NO_WAIT`, the GL may choose to unconditionally execute the subsequent rendering commands without waiting for the query to complete.

If *mode* is `QUERY_BY_REGION_WAIT`, the GL will also wait for occlusion query results and discard rendering commands if the result of the occlusion query is zero. If the query result is non-zero, subsequent rendering commands are executed, but the GL may discard the results of the commands for any region of the framebuffer that did not contribute to the sample count in the specified occlusion query. Any such discarding is done in an implementation-dependent manner, but the rendering command results may not be discarded for any samples that contributed to the occlusion query sample count. If *mode* is `QUERY_BY_REGION_NO_WAIT`, the GL operates as in `QUERY_BY_REGION_WAIT`, but may choose to unconditionally execute the subsequent rendering commands without waiting for the query to complete.

### Errors

An `INVALID_OPERATION` error is generated by **BeginConditionalRender** if called while conditional rendering is in progress.

An `INVALID_VALUE` error is generated if *id* is not the name of an existing query object.

An `INVALID_OPERATION` error is generated if *id* is the name of a query object with a target other `SAMPLES_PASSED`, `ANY_SAMPLES_PASSED`, or `ANY_SAMPLES_PASSED_CONSERVATIVE`, or if *id* is the name of a query currently in progress.

An `INVALID_OPERATION` error is generated by **EndConditionalRender** if called while conditional rendering is not in progress,

## Chapter 11

# Programmable Vertex Processing

When the program object currently in use for the vertex stage (see section 7.3) includes a vertex shader, its shader is considered *active* and is used to process vertices transferred to the GL (see section 11.1). Vertices may be further processed by tessellation and geometry shaders (see sections 11.2 and 11.3). The resulting transformed vertices are then processed as described in chapter 13.

If the current vertex stage program object has no vertex shader, or no program object is current for the vertex stage, the results of programmable vertex processing are undefined.

### 11.1 Vertex Shaders

Vertex shaders describe the operations that occur on vertex values and their associated data. When the program object currently in use for the vertex stage includes a vertex shader, its vertex shader is considered *active* and is used to process vertices.

*Vertex attributes* are per-vertex values available to vertex shaders, and are specified as described in section 10.2.

#### 11.1.1 Vertex Attributes

Vertex shaders can define named attribute variables, which are bound to generic vertex attributes transferred by drawing commands. This binding can be specified by the application before the program is linked, or automatically assigned by the GL when the program is linked.

When an attribute variable declared using one of the scalar or vector data types enumerated in table 11.1 is bound to a generic attribute index  $i$ , its value(s) are taken from the components of generic attribute  $i$ . Scalars are extracted from the  $x$

Data type	Command
int	<b>VertexAttrib1i</b>
ivec2	<b>VertexAttrib2i</b>
ivec3	<b>VertexAttrib3i</b>
ivec4	<b>VertexAttrib4i</b>
uint	<b>VertexAttrib1ui</b>
uvec2	<b>VertexAttrib2ui</b>
uvec3	<b>VertexAttrib3ui</b>
uvec4	<b>VertexAttrib4ui</b>
float	<b>VertexAttrib1*</b>
vec2	<b>VertexAttrib2*</b>
vec3	<b>VertexAttrib3*</b>
vec4	<b>VertexAttrib4*</b>
double	<b>VertexAttribL1d</b>
dvec2	<b>VertexAttribL2d</b>
dvec3	<b>VertexAttribL3d</b>
dvec4	<b>VertexAttribL4d</b>

Table 11.1: Scalar and vector vertex attribute types and **VertexAttrib\*** commands used to set the values of the corresponding generic attribute.

component; two-, three-, and four-component vectors are extracted from the  $(x, y)$ ,  $(x, y, z)$ , or  $(x, y, z, w)$  components, respectively.

When an attribute variable is declared as a `mat2`, `mat3x2` or `mat4x2`, its matrix columns are taken from the  $(x, y)$  components of generic attributes  $i$  and  $i + 1$  (`mat2`, `dmat2`), from attributes  $i$  through  $i + 2$  (`mat3x2`), or from attributes  $i$  through  $i + 3$  (`mat4x2`). When an attribute variable is declared as a `mat2x3`, `mat3` or `mat4x3`, its matrix columns are taken from the  $(x, y, z)$  components of generic attributes  $i$  and  $i + 1$  (`mat2x3`), from attributes  $i$  through  $i + 2$  (`mat3`), or from attributes  $i$  through  $i + 3$  (`mat4x3`). When an attribute variable is declared as a `mat2x4`, `mat3x4` or `mat4`, its matrix columns are taken from the  $(x, y, z, w)$  components of generic attributes  $i$  and  $i + 1$  (`mat2x4`), from attributes  $i$  through  $i + 2$  (`mat3x4`), or from attributes  $i$  through  $i + 3$  (`mat4`). When an attribute variable is declared as a double-precision matrix (`dmat2`, `dmat3`, `dmat4`, `dmat2x3`, `dmat2x4`, `dmat3x2`, `dmat3x4`, `dmat4x2`, `dmat4x3`), its matrix columns are taken from the same generic attributes as the equivalent single-precision matrix type, with values specified using the **VertexAttribL\*** or **VertexAttribLPointer** commands.

For the 64-bit double precision types listed in table 11.1, no default attribute values are provided if the values of the vertex attribute variable are specified with fewer components than required for the attribute variable. For example, the fourth component of a variable of type `dvec4` will be undefined if specified using **VertexAttribL3dv**, or using a vertex array specified with **VertexAttribLPointer** and a size of three.

The command

```
void BindAttribLocation(uint program, uint index, const
    char *name );
```

specifies that the attribute variable named *name* in program *program* should be bound to generic vertex attribute *index* when the program is next linked. If *name* was bound previously, its assigned binding is replaced with *index*. *name* must be a null-terminated string. **BindAttribLocation** has no effect until the program is linked. In particular, it doesn't modify the bindings of active attribute variables in a program that has already been linked.

When a program is linked, any active attributes without a binding specified either through **BindAttribLocation** or explicitly set within the shader text will automatically be bound to vertex attributes by the GL. Such bindings can be queried using the command **GetAttribLocation**. **LinkProgram** will fail if the assigned binding of an active attribute variable would cause the GL to reference a non-existent generic attribute (one greater than or equal to the value of `MAX_VERTEX_ATTRIBS`). **LinkProgram** will fail if the attribute bindings specified either by **BindAttribLocation** or explicitly set within the shader text do not leave not enough space to assign a location for an active matrix attribute or an active attribute array, both of which require multiple contiguous generic attributes. If an active attribute has a binding explicitly set within the shader text and a different binding assigned by **BindAttribLocation**, the assignment in the shader text is used.

**BindAttribLocation** may be issued before any vertex shader objects are attached to a program object. Hence it is allowed to bind any name to an index, including a name that is never used as an attribute in any vertex shader object. Assigned bindings for attribute variables that do not exist or are not active are ignored.

### Errors

An `INVALID_VALUE` error is generated if *program* is not the name of either a program or shader object.

An `INVALID_OPERATION` error is generated if *program* is the name of a shader object.

An `INVALID_VALUE` error is generated if *index* is greater than or equal to



the value of `MAX_VERTEX_ATTRIBS`.

To determine the set of active vertex attribute variables used by a program, applications can query the properties and active resources of the `PROGRAM_INPUT` interface of a program including a vertex shader.

Additionally, the command

```
void GetActiveAttrib(uint program, uint index,
    sizei bufSize, sizei *length, int *size, enum *type,
    char *name);
```

can be used to determine properties of the active input variable assigned the index *index* in program object *program*. If no error occurs, the command is equivalent to

```
const enum props[] = { ARRAY_SIZE, TYPE };
GetProgramResourceName (program, PROGRAM_INPUT,
    index, bufSize, length, name);
GetProgramResourceiv (program, PROGRAM_INPUT,
    index, 1, &props[0], 1, NULL, size);
GetProgramResourceiv (program, PROGRAM_INPUT,
    index, 1, &props[1], 1, NULL, (int *)type);
```

For **GetActiveAttrib**, all active vertex shader input variables are enumerated, including the special built-in inputs `gl_VertexID` and `gl_InstanceID`.

### Errors

An `INVALID_VALUE` error is generated if *program* is not the name of either a program or shader object.

An `INVALID_OPERATION` error is generated if *program* is the name of a shader object.

An `INVALID_VALUE` error is generated if *index* is not the index of an active input variable in *program*.

An `INVALID_VALUE` error is generated for all values of *index* if *program* does not include a vertex shader, as it has no active vertex attributes.

An `INVALID_VALUE` error is generated if *bufSize* is negative.

The command

```
int GetAttribLocation(uint program, const char *name);
```

can be used to determine the location assigned to the active input variable named *name* in program object *program*.

### Errors

If *program* has been successfully linked but contains no vertex shader, no error is generated but -1 will be returned.

An `INVALID_VALUE` error is generated if *program* is not the name of either a program or shader object.

An `INVALID_OPERATION` error is generated if *program* is the name of a shader object.

An `INVALID_OPERATION` error is generated and -1 is returned if *program* has not been linked or was last linked unsuccessfully.

Otherwise, the command is equivalent to

**GetProgramResourceLocation** (*program*, `PROGRAM_INPUT`, *name*);

There is an implementation-dependent limit on the number of active attribute variables in a vertex shader. A program with more than the value of `MAX_VERTEX_ATTRIBS` active attribute variables may fail to link, unless device-dependent optimizations are able to make the program fit within available hardware resources. For the purposes of this test, attribute variables of the type `dvec3`, `dvec4`, `dmat2x3`, `dmat2x4`, `dmat3`, `dmat3x4`, `dmat4x3`, and `dmat4` may count as consuming twice as many attributes as equivalent single-precision types. While these types use the same number of generic attributes as their single-precision equivalents, implementations are permitted to consume two single-precision vectors of internal storage for each three- or four-component double-precision vector.

The values of generic attributes sent to generic attribute index *i* are part of current state. If a new program object has been made active, then these values will be tracked by the GL in such a way that the same values will be observed by attributes in the new program object that are also bound to index *i*.

It is possible for an application to bind more than one attribute name to the same location. This is referred to as *aliasing*. This will only work if only one of the aliased attributes is active in the executable program, or if no path through the shader consumes more than one attribute of a set of attributes aliased to the same location. A link error can occur if the linker determines that every path through the shader consumes multiple aliased attributes, but implementations are not required to generate an error in this case. The compiler and linker are allowed to assume that no aliasing is done, and may employ optimizations that work only in the absence of aliasing.

### 11.1.2 Vertex Shader Variables

Vertex shaders can access uniforms belonging to the current program object. Limits on uniform storage and methods for manipulating uniforms are described in section 7.6.

Vertex shaders also have access to samplers to perform texturing operations, as described in section 7.10.

#### 11.1.2.1 Output Variables

A vertex shader may define one or more *output variables* or *outputs* (see the OpenGL Shading Language Specification).

The OpenGL Shading Language Specification also defines a set of built-in outputs that vertex shaders can write to (see section 7.1 (“Built-In Variables”) of the OpenGL Shading Language Specification). These output variables are either used as the mechanism to communicate values to the next active stage in the vertex processing pipeline: either the tessellation control shader, the tessellation evaluation shader, the geometry shader, or the fixed-function vertex processing stages leading to rasterization.

If the output variables are passed directly to the vertex processing stages leading to rasterization, the values of all outputs are expected to be interpolated across the primitive being rendered, unless flatshaded. Otherwise the values of all outputs are collected by the primitive assembly stage and passed on to the subsequent pipeline stage once enough data for one primitive has been collected.

The number of components (individual scalar numeric values) of output variables that can be written by the vertex shader, whether or not a tessellation control, tessellation evaluation, or geometry shader is active, is given by the value of the implementation-dependent constant `MAX_VERTEX_OUTPUT_COMPONENTS`. Outputs declared as vectors, matrices, and arrays will all consume multiple components. For the purposes of counting input and output components consumed by a shader, variables declared as vectors, matrices, and arrays will all consume multiple components. Each component of variables declared as double-precision floating-point scalars, vectors, or matrices may be counted as consuming two components.

When a program is linked, all components of any outputs written by a vertex shader will count against this limit. A program whose vertex shader writes more than the value of `MAX_VERTEX_OUTPUT_COMPONENTS` components worth of outputs may fail to link, unless device-dependent optimizations are able to make the program fit within available hardware resources.

Additionally, when linking a program containing only a vertex and frag-

ment shader, there is a limit on the total number of components used as vertex shader outputs or fragment shader inputs. This limit is given by the value of the implementation-dependent constant `MAX_VARYING_COMPONENTS`. The implementation-dependent constant `MAX_VARYING_VECTORS` has a value equal to the value of `MAX_VARYING_COMPONENTS` divided by four. Each output variable component used as either a vertex shader output or fragment shader input counts against this limit, except for the components of `gl_Position`. A program containing only a vertex and fragment shader that accesses more than this limit's worth of components of outputs may fail to link, unless device-dependent optimizations are able to make the program fit within available hardware resources.

Each program object can specify a set of output variables from one shader to be recorded in transform feedback mode (see section 13.2). The variables that can be recorded are those emitted by the **first** active shader, in order, from the following list:

- geometry shader
- tessellation evaluation shader
- tessellation control shader
- vertex shader

The values to record are specified with the command

```
void TransformFeedbackVaryings( uint program,
    sizei count, const char *const *varyings,
    enum bufferMode );
```

*program* specifies the program object. *count* specifies the number of output variables used for transform feedback. *varyings* is an array of *count* zero-terminated strings specifying the names of the outputs to use for transform feedback. The variables specified in *varyings* can be either built-in (beginning with "gl\_") or user-defined variables. Output variables are written out in the order they appear in the array *varyings*. *bufferMode* is either `INTERLEAVED_ATTRIBS` or `SEPARATE_ATTRIBS`, and identifies the mode used to capture the outputs when transform feedback is active.

If a string in *varyings* is `gl_NextBuffer`, it does not identify an output, but instead serves as a buffer separator value to direct subsequent outputs at the next transform feedback binding point. If a string in *varyings* is `gl_SkipComponents1`, `gl_SkipComponents2`, `gl_SkipComponents3`, or `gl_SkipComponents4`, it also does not identify a specific output. Instead, such values are treated as requesting that the GL skip the next one to four components of

output data. Skipping components this way is equivalent to specifying a one- to four-component output with undefined values, except that the corresponding memory in the buffer object is not modified. Such array entries are counted as being written to the buffer object for the purposes of determining whether the requested attributes exceed per-buffer component count limits and whether recording a new primitive would result in an overflow. Each component skipped is considered to occupy a single float.

### Errors

An `INVALID_VALUE` error is generated if *program* is not the name of either a program or shader object.

An `INVALID_OPERATION` error is generated if *program* is the name of a shader object.

An `INVALID_VALUE` error is generated if *count* is negative.

An `INVALID_ENUM` error is generated if *bufferMode* is not `SEPARATE_ATTRIBUTES` or `INTERLEAVED_ATTRIBUTES`.

An `INVALID_VALUE` error is generated if *bufferMode* is `SEPARATE_ATTRIBUTES` and *count* is greater than the value of the implementation-dependent limit `MAX_TRANSFORM_FEEDBACK_SEPARATE_ATTRIBUTES`.

An `INVALID_OPERATION` error is generated if any pointer in *varyings* identifies the special names `gl_NextBuffer`, `gl_SkipComponents1`, `gl_SkipComponents2`, `gl_SkipComponents3`, or `gl_SkipComponents4` and *bufferMode* is not `INTERLEAVED_ATTRIBUTES`, or if the number of `gl_NextBuffer` pointers in *varyings* is greater than or equal to the value of `MAX_TRANSFORM_FEEDBACK_BUFFERS`.

The state set by **TransformFeedbackVaryings** has no effect on the execution of the program until *program* is subsequently linked. When **LinkProgram** is called, the program is linked so that the values of the specified outputs for the vertices of each primitive generated by the GL are written to a single buffer object (if the buffer mode is `INTERLEAVED_ATTRIBUTES`) or multiple buffer objects (if the buffer mode is `SEPARATE_ATTRIBUTES`). A program will fail to link if:

- the *count* specified by **TransformFeedbackVaryings** is non-zero, but the program object has no vertex, tessellation control, tessellation evaluation, or geometry shader;
- any variable name specified in the *varyings* array is not one of `gl_NextBuffer`, `gl_SkipComponents1`, `gl_SkipComponents2`, `gl_SkipComponents3`, or `gl_SkipComponents4`, and is not declared as a

built-in or user-defined output variable in the shader stage whose outputs can be recorded.

- any two entries in the *varyings* array specify the same output variable;
- the total number of components to capture in any output in *varyings* is greater than the value of `MAX_TRANSFORM_FEEDBACK_SEPARATE_COMPONENTS` and the buffer mode is `SEPARATE_ATTRIBS`;
- the total number of components to capture is greater than the constant `MAX_TRANSFORM_FEEDBACK_INTERLEAVED_COMPONENTS` and the buffer mode is `INTERLEAVED_ATTRIBS`; or
- the set of outputs to capture to any single binding point includes outputs from more than one vertex stream.

For the purposes of counting the total number of components to capture, each component of outputs declared as double-precision floating-point scalars, vectors, or matrices may be counted as consuming two components.

To determine the set of output variables in a linked program object that will be captured in transform feedback mode, applications can query the properties and active resources of the `TRANSFORM_FEEDBACK_VARYING` interface.

Additionally, the command

```
void GetTransformFeedbackVarying( uint program,
    uint index, sizei bufSize, sizei *length, sizei *size,
    enum *type, char *name );
```

can be used to enumerate properties of a single output variable captured in transform feedback mode, and is equivalent to

```
const enum props[] = { ARRAY_SIZE, TYPE };
GetProgramResourceName (program, TRANSFORM_FEEDBACK_VARYING,
    index, bufSize, length, name );
GetProgramResourceiv (program, TRANSFORM_FEEDBACK_VARYING,
    index, 1, &props[0], 1, NULL, size);
GetProgramResourceiv (program, TRANSFORM_FEEDBACK_VARYING,
    index, 1, &props[1], 1, NULL, (int *)type);
```

Special output names (e.g., `gl_NextBuffer`, `gl_SkipComponents1`) passed to **TransformFeedbackVaryings** in the *varyings* array are counted as outputs to be recorded for the purposes of determining the value of `TRANSFORM_FEEDBACK_VARYINGS` and for determining the variable selected by *index* in **GetTransformFeedbackVarying**. If *index* identifies `gl_NextBuffer`, the values

zero and NONE will be written to *size* and *type*, respectively. If *index* is of the form `gl_SkipComponentsn`, the value NONE will be written to *type* and the number of components *n* will be written to *size*.

### 11.1.3 Shader Execution

If there is an active program object present for the vertex, tessellation control, tessellation evaluation, or geometry shader stages, the executable code for these active programs is used to process incoming vertex values, instead of the fixed-function method described in chapter 12. The following sequence of operations is performed:

- Vertices are processed by the vertex shader (see section 11.1) and assembled into primitives as described in sections 10.1 through 10.3.
- If the current program contains a tessellation control shader, each individual patch primitive is processed by the tessellation control shader (section 11.2.1). Otherwise, primitives are passed through unmodified. If active, the tessellation control shader consumes its input patch and produces a new patch primitive, which is passed to subsequent pipeline stages.
- If the current program contains a tessellation evaluation shader, each individual patch primitive is processed by the tessellation primitive generator (section 11.2.2) and tessellation evaluation shader (see section 11.2.3). Otherwise, primitives are passed through unmodified. When a tessellation evaluation shader is active, the tessellation primitive generator produces a new collection of point, line, or triangle primitives to be passed to subsequent pipeline stages. The vertices of these primitives are processed by the tessellation evaluation shader. The patch primitive passed to the tessellation primitive generator is consumed by this process.
- If the current program contains a geometry shader, each individual primitive is processed by the geometry shader (section 11.3). Otherwise, primitives are passed through unmodified. If active, the geometry shader consumes its input patch. However, each geometry shader invocation may emit new vertices, which are arranged into primitives and passed to subsequent pipeline stages.

Following shader execution, the fixed-function operations described in chapter 13 are applied.

Special considerations for vertex shader execution are described in the following sections.

### 11.1.3.1 Shader Only Texturing

This section describes texture functionality that is accessible through shaders (of all types). Also refer to chapter 8 and to section 8.9(“Texture Functions”) of the OpenGL Shading Language Specification ,

### 11.1.3.2 Texel Fetches

The OpenGL Shading Language texel fetch functions provide the ability to extract a single texel from a specified texture image. The integer coordinates passed to the texel fetch functions are used as the texel coordinates  $(i, j, k)$  into the texture image. This in turn means the texture image is point-sampled (no filtering is performed), but the remaining steps of texture access (described below) are still applied.

The level of detail accessed is computed by adding the specified level-of-detail parameter *lod* to the base level of the texture,  $level_{base}$ .

The texel fetch functions can not perform depth comparisons or access cube maps. Unlike filtered texel accesses, texel fetches do not support LOD clamping or any texture wrap mode, and require a mipmapped minification filter to access any level of detail other than the base level.

Texel fetches with incorrect parameters or state occur under any the following conditions:

- the computed level of detail is less than the texture’s base level ( $level_{base}$ ) or greater than the maximum defined level,  $q$  (see section 8.14.3)
- the computed level of detail is not the texture’s base level and the texture’s minification filter is NEAREST or LINEAR
- the layer specified for array textures is negative or greater than the number of layers in the array texture
- the texel coordinates  $(i, j, k)$  refer to a texel outside the defined extents of the specified level of detail, where any of

$$\begin{array}{ll} i < 0 & i \geq w_s \\ j < 0 & j \geq h_s \\ k < 0 & k \geq d_s \end{array}$$

and the size parameters  $w_s$ ,  $h_s$ , and  $d_s$  refer to the width, height, and depth of the image, as in equation 8.3



- the texture being accessed is not complete, as defined in section 8.17.
- the texture being accessed is not bound.

In all the above cases, if the context was created with robust buffer access enabled (see section 10.3.6), the result of the texture fetch is zero, or a texture source color of  $(0, 0, 0, 1)$  in the case of a texel fetch from an incomplete texture. If robust buffer access is not enabled, the result of the texture fetch is undefined in each case.

### 11.1.3.3 Multisample Texel Fetches

Multisample buffers do not have mipmaps, and there is no level of detail parameter for multisample texel fetches. Instead, an integer parameter selects the sample number to be fetched from the buffer. The number identifying the sample is the same as the value used to query the sample location using `GetMultisamplefv`. Multisample textures support only NEAREST filtering.

Additionally, this fetch may only be performed on a multisample texture sampler. No other sample or fetch commands may be performed on a multisample texture sampler.

### 11.1.3.4 Texture Queries

The OpenGL Shading Language `textureSize()` functions provide the ability to query the size of a texture image. The LOD value *lod* passed in as an argument to the texture size functions is added to the  $level_{base}$  of the texture to determine a texture image level. The dimensions of that image level, excluding a possible border, are then returned. If the computed texture image level is outside the range  $[level_{base}, q]$ , the results are undefined. When querying the size of an array texture, both the dimensions and the layer index are returned.

The OpenGL Shading Language `textureQueryLevels()` functions provide the ability to query the number of accessible mipmap levels in a texture object associated with a sampler uniform. If the sampler is associated with an immutable-format texture object (see section 8.19), the value returned will be:

$$\min\{level_{immut} - 1, level_{max}\} - level_{base} + 1.$$

Otherwise, the value returned will be an implementation-dependent value between zero and  $q - level_{base} + 1$ , where *q* is defined in section 8.14.3. The value returned in that case must satisfy the following constraints:

- if all levels of the texture have zero size, zero must be returned

- if the texture is complete, a non-zero value must be returned
- if the texture is complete and is accessed with a minification filter requiring mipmaps,  $q - level_{base} + 1$  must be returned.

### 11.1.3.5 Texture Access

Shaders have the ability to do a lookup into a texture map. The maximum number of texture image units available to shaders are the values of the implementation-dependent constants

- `MAX_VERTEX_TEXTURE_IMAGE_UNITS` (for vertex shaders),
- `MAX_TESS_CONTROL_TEXTURE_IMAGE_UNITS` (for tessellation control shaders),
- `MAX_TESS_EVALUATION_TEXTURE_IMAGE_UNITS` (for tessellation evaluation shaders),
- `MAX_GEOMETRY_TEXTURE_IMAGE_UNITS` (for geometry shaders), and
- `MAX_TEXTURE_IMAGE_UNITS` (for fragment shaders).
- `MAX_COMPUTE_TEXTURE_IMAGE_UNITS` (for compute shaders),

All active shaders combined cannot use more than the value of `MAX_COMBINED_TEXTURE_IMAGE_UNITS` texture image units. If more than one pipeline stage accesses the same texture image unit, each such access counts separately against the `MAX_COMBINED_TEXTURE_IMAGE_UNITS` limit.

When a texture lookup is performed in a shader, the filtered texture value  $\tau$  is computed in the manner described in sections 8.14 and 8.15, and converted to a texture base color  $C_b$  as shown in table 15.1, followed by application of the texture swizzle as described in section 15.2.1 to compute the texture source color  $C_s$  and  $A_s$ .

The resulting four-component vector  $(R_s, G_s, B_s, A_s)$  is returned to the shader. Texture lookup functions (see section 8.9(“Texture Functions”) of the OpenGL Shading Language Specification) may return floating-point, signed, or unsigned integer values depending on the function and the internal format of the texture.

In shaders other than fragment shaders, it is not possible to perform automatic level-of-detail calculations using partial derivatives of the texture coordinates with respect to window coordinates as described in section 8.14. Hence, there is no automatic selection of an image array level. Minification or magnification of a texture

map is controlled by a level-of-detail value optionally passed as an argument in the texture lookup functions. If the texture lookup function supplies an explicit level-of-detail value  $l$ , then the pre-bias level-of-detail value  $\lambda_{base}(x, y) = l$  (replacing equation 8.4). If the texture lookup function does not supply an explicit level-of-detail value, then  $\lambda_{base}(x, y) = 0$ . The scale factor  $\rho(x, y)$  and its approximation function  $f(x, y)$  (see equation 8.8) are ignored.

Texture lookups involving textures with depth component data generate a texture base color  $C_b$  either using depth data directly or by performing a comparison with the  $D_{ref}$  value used to perform the lookup, as described in section 8.22.1, and expanding the resulting value  $R_t$  to a color  $C_b = (R_t, 0, 0, 1)$ . Swizzling is then performed as described above, but only the first component  $C_s[0]$  is returned to the shader. The comparison operation is requested in the shader by using any of the shadow sampler types (`sampler*Shadow`), and in the texture using the `TEXTURE_COMPARE_MODE` parameter. These requests must be consistent; the results of a texture lookup are undefined if any of the following conditions are true:

- The sampler used in a texture lookup function is not one of the shadow sampler types, the texture object's base internal format is `DEPTH_COMPONENT` or `DEPTH_STENCIL`, and the `TEXTURE_COMPARE_MODE` is not `NONE`.
- The sampler used in a texture lookup function is one of the shadow sampler types, the texture object's base internal format is `DEPTH_COMPONENT` or `DEPTH_STENCIL`, and the `TEXTURE_COMPARE_MODE` is `NONE`.
- The sampler used in a texture lookup function is one of the shadow sampler types, and the texture object's base internal format is not `DEPTH_COMPONENT` or `DEPTH_STENCIL`.
- The sampler used in a texture lookup function is one of the shadow sampler types, the texture object's base internal format is `DEPTH_STENCIL`, and the `DEPTH_STENCIL_TEXTURE_MODE` is not `DEPTH_COMPONENT`.

The stencil index texture internal component is ignored if the base internal format is `DEPTH_STENCIL`. `DEPTH_STENCIL` and the `DEPTH_STENCIL_TEXTURE_MODE` is not `STENCIL_INDEX`.

Texture lookups involving texture objects with an internal format of `DEPTH_STENCIL` can read the stencil value as described in section 8.22 by setting the `DEPTH_STENCIL_TEXTURE_MODE` to `STENCIL_COMPONENT`. The stencil value is read as an integer and assigned to  $R_t$ . An unsigned integer sampler should be used to lookup the stencil component, otherwise the results are undefined.

If a sampler is used in a shader and the sampler's associated texture is not complete, as defined in section 8.17, (0, 0, 0, 1) will be returned for a non-shadow sampler and 0 for a shadow sampler.

#### 11.1.3.6 Atomic Counter Access

Shaders have the ability to set and get atomic counters. The maximum number of atomic counters available to shaders are the values of the implementation dependent constants

- `MAX_VERTEX_ATOMIC_COUNTERS` (for vertex shaders),
- `MAX_TESS_CONTROL_ATOMIC_COUNTERS` (for tessellation control shaders),
- `MAX_TESS_EVALUATION_ATOMIC_COUNTERS` (for tessellation evaluation shaders),
- `MAX_GEOMETRY_ATOMIC_COUNTERS` (for geometry shaders), and
- `MAX_FRAGMENT_ATOMIC_COUNTERS` (for fragment shaders).
- `MAX_COMPUTE_ATOMIC_COUNTERS` (for compute shaders),

All active shaders combined cannot use more than the value of `MAX_COMBINED_ATOMIC_COUNTERS` atomic counters. If more than one pipeline stage accesses the same atomic counter, each such access counts separately against the `MAX_COMBINED_ATOMIC_COUNTERS` limit.

#### 11.1.3.7 Image Access

Shaders have the ability to read and write to textures using image uniforms. The maximum number of image uniforms available to individual shader stages are the values of the implementation dependent constants

- `MAX_VERTEX_IMAGE_UNIFORMS` (vertex shaders),
- `MAX_TESS_CONTROL_IMAGE_UNIFORMS` (tessellation control shaders),
- `MAX_TESS_EVALUATION_IMAGE_UNIFORMS` (tessellation evaluation shaders),
- `MAX_GEOMETRY_IMAGE_UNIFORMS` (geometry shaders), and

- `MAX_FRAGMENT_IMAGE_UNIFORMS` (fragment shaders).
- `MAX_COMPUTE_IMAGE_UNIFORMS` (for compute shaders),

All active shaders combined cannot use more than the value of `MAX_COMBINED_IMAGE_UNIFORMS` atomic counters. If more than one shader stage accesses the same image uniform, each such access counts separately against the `MAX_COMBINED_IMAGE_UNIFORMS` limit.

#### 11.1.3.8 Shader Storage Buffer Access

Shaders have the ability to read and write to buffer memory via buffer variables in shader storage blocks. The maximum number of shader storage blocks available to shaders are the values of the implementation dependent constants

- `MAX_VERTEX_SHADER_STORAGE_BLOCKS` (for vertex shaders)
- `MAX_TESS_CONTROL_SHADER_STORAGE_BLOCKS` (for tessellation control shaders)
- `MAX_TESS_EVALUATION_SHADER_STORAGE_BLOCKS` (for tessellation evaluation shaders)
- `MAX_GEOMETRY_SHADER_STORAGE_BLOCKS` (for geometry shaders)
- `MAX_FRAGMENT_SHADER_STORAGE_BLOCKS` (for fragment shaders)
- `MAX_COMPUTE_SHADER_STORAGE_BLOCKS` (for compute shaders)

All active shaders combined cannot use more than the value of `MAX_COMBINED_SHADER_STORAGE_BLOCKS` shader storage blocks. If more than one pipeline stage accesses the same shader storage block, each such access separately against this combined limit.

#### 11.1.3.9 Shader Inputs

Besides having access to vertex attributes and uniform variables, vertex shaders can access the read-only built-in variables `gl_VertexID` and `gl_InstanceID`.

`gl_VertexID` holds the integer index  $i$  implicitly passed by **DrawArrays** or one of the other drawing commands defined in section 10.5.

`gl_InstanceID` holds the integer instance number of the current primitive in an instanced draw call (see section 10.5).

Section 7.1 (“Built-In Variables”) of the OpenGL Shading Language Specification also describes these variables.

### 11.1.3.10 Shader Outputs

A vertex shader can write to user-defined output variables. These values are expected to be interpolated across the primitive it outputs, unless they are specified to be flat shaded. Refer to sections 4.3.6(“Output Variables”), 4.5(“Interpolation Qualifiers”), and 7.1(“Built-In Variables”) of the OpenGL Shading Language Specification for more detail.

The built-in output `gl_Position` is intended to hold the homogeneous vertex position. Writing `gl_Position` is optional.

The built-in output variable `gl_ClipDistance` holds the clip distance(s) used in the clipping stage, as described in section 13.5. If clipping is enabled, `gl_ClipDistance` should be written.

The built-in output `gl_PointSize`, if written, holds the size of the point to be rasterized, measured in pixels.

### 11.1.3.11 Validation

It is not always possible to determine at link time if a program object can execute successfully, given that **LinkProgram** can not know the state of the remainder of the pipeline. Therefore validation is done when the first rendering command is issued, to determine if the set of active program objects can be executed.

An `INVALID_OPERATION` error is generated by any command that transfers vertices to the GL or launches compute work if the current set of active program objects cannot be executed, for reasons including:

- A program object is active for at least one, but not all of the shader stages that were present when the program was linked.
- One program object is active for at least two shader stages and a second program is active for a shader stage between two stages for which the first program was active. The active compute shader is ignored for the purposes of this test.
- There is an active program for tessellation control, tessellation evaluation, or geometry stages with corresponding executable shader, but there is no active program with executable vertex shader.
- There is no current program object specified by **UseProgram**, there is a current program pipeline object, and the current program for any shader stage has been relinked since being applied to the pipeline object via **UseProgramStages** with the `PROGRAM_SEPARABLE` parameter set to `FALSE`.

- Any two active samplers in the set of active program objects are of different types, but refer to the same texture image unit.
- The sum of the number of active samplers for each active program exceeds the maximum number of texture image units allowed.
- The sum of the number of active shader storage blocks used by the current program objects exceeds the combined limit on the number of active shader storage blocks (the value of `MAX_COMBINED_SHADER_STORAGE_BLOCKS`).

The `INVALID_OPERATION` error generated by these rendering commands may not provide enough information to find out why the currently active program object would not execute. No information at all is available about a program object that would still execute, but is inefficient or suboptimal given the current GL state. As a development aid, use the command

```
void ValidateProgram( uint program );
```

to validate the program object *program* against the current GL state. Each program object has a boolean status, `VALIDATE_STATUS`, that is modified as a result of validation. This status can be queried with `GetProgramiv` (see section 7.13). If validation succeeded this status will be set to `TRUE`, otherwise it will be set to `FALSE`. If validation succeeded, no `INVALID_OPERATION` validation error is generated if *program* is made current via `UseProgram`, given the current state. If validation failed, such errors are generated under the current state.

`ValidateProgram` will check for all the conditions that could lead to an `INVALID_OPERATION` error when rendering commands are issued, and may check for other conditions as well. For example, it could give a hint on how to optimize some piece of shader code. The information log of *program* is overwritten with information on the results of the validation, which could be an empty string. The results written to the information log are typically only useful during application development; an application should not expect different GL implementations to produce identical information.

A shader should not fail to compile, and a program object should not fail to link due to lack of instruction space or lack of temporary variables. Implementations should ensure that all valid shaders and program objects may be successfully compiled, linked and executed.

### Errors

An `INVALID_VALUE` error is generated if *program* is not the name of either a program or shader object.

An `INVALID_OPERATION` error is generated if *program* is the name of a shader object.

Separable program objects may have validation failures that cannot be detected without the complete program pipeline. Mismatched interfaces, improper usage of program objects together, and the same state-dependent failures can result in validation errors for such program objects. As a development aid, use the command

```
void ValidateProgramPipeline( uint pipeline );
```

to validate the program pipeline object *pipeline* against the current GL state. Each program pipeline object has a boolean status, `VALIDATE_STATUS`, that is modified as a result of validation. This status can be queried with **GetProgramPipelineiv** (see section 7.13). If validation succeeded, no `INVALID_OPERATION` validation error is generated if *pipeline* is bound and no program is made current via **UseProgram**, given the current state. If validation failed, such errors are generated under the current state.

the program pipeline object is guaranteed to execute given the current GL state.

If *pipeline* is a name that has been generated (without subsequent deletion) by **GenProgramPipelines**, but refers to a program pipeline object that has not been previously bound, the GL first creates a new state vector in the same manner as when **BindProgramPipeline** creates a new program pipeline object.

### Errors

An `INVALID_OPERATION` error is generated if *pipeline* is not a name returned from a previous call to **GenProgramPipelines** or if such a name has since been deleted by **DeleteProgramPipelines**,

#### 11.1.3.12 Undefined Behavior

When using array or matrix variables in a shader, it is possible to access a variable with an index computed at run time that is outside the declared extent of the variable. Such out-of-bounds accesses have undefined behavior, and system errors (possibly including program termination) may occur. The level of protection provided against such errors in the shader is implementation-dependent.

Robust buffer access can be enabled by creating a context with robust access enabled through the window system binding APIs. When enabled, out-of-bounds accesses will be bounded within the working memory of the active program and cannot access memory owned by other GL contexts, and will not result in abnormal program termination. Out-of-bounds access to local and global variables cannot



read values from other program invocations. An out-of-bounds read may return another value from the active program's working memory or zero. An out-of-bounds write may overwrite a value from the active program's working memory or be discarded.

Out-of-bounds accesses to resources backed by buffer objects cannot read or modify data outside of the buffer object. For resources bound to buffer ranges, access is restricted within the buffer object from which the buffer range was created, and not within the buffer range itself. Out-of-bounds reads may return values from within the buffer object or zero. Out-of-bounds writes may modify values within the buffer object or be discarded.

Out-of-bounds accesses to arrays of resources, such as an array of textures, can only access the data of bound resources. Reads from unbound resources return zero and writes are discarded. It is not possible to access data owned by other GL contexts.

Applications that require defined behavior for out-of-bounds accesses should range check all computed indices before dereferencing the array, vector or matrix.

## 11.2 Tessellation

Tessellation is a process that reads a patch primitive and generates new primitives used by subsequent pipeline stages. The generated primitives are formed by subdividing a single triangle or quad primitive according to fixed or shader-computed levels of detail and transforming each of the vertices produced during this subdivision.

Tessellation functionality is controlled by two types of tessellation shaders: tessellation control shaders and tessellation evaluation shaders. Tessellation is considered active if and only if there is an active tessellation control or tessellation evaluation program object.

The tessellation control shader is used to read an input patch provided by the application, and emit an output patch. The tessellation control shader is run once for each vertex in the output patch and computes the attributes of that vertex. Additionally, the tessellation control shader may compute additional per-patch attributes of the output patch. The most important per-patch outputs are the tessellation levels, which are used to control the number of subdivisions performed by the tessellation primitive generator. The tessellation control shader may also write additional per-patch attributes for use by the tessellation evaluation shader. If no tessellation control shader is active, the patch provided is passed through to the tessellation primitive generator stage unmodified.

If a tessellation evaluation shader is active, the tessellation primitive generator

subdivides a triangle or quad primitive into a collection of points, lines, or triangles according to the tessellation levels of the patch and the set of layout declarations specified in the tessellation evaluation shader text. The tessellation levels used to control subdivision are normally written by the tessellation control shader. If no tessellation control shader is active, default tessellation levels are instead used.

When a tessellation evaluation shader is active, it is run on each vertex generated by the tessellation primitive generator to compute the final position and other attributes of the vertex. The tessellation evaluation shader can read the relative location of the vertex in the subdivided output primitive, given by an  $(u, v)$  or  $(u, v, w)$  coordinate, as well as the position and attributes of any or all of the vertices in the input patch.

Tessellation operates only on patch primitives.

An `INVALID_OPERATION` error is generated by any command that transfers vertices to the GL if tessellation is active and the primitive mode is not `PATCHES`.

Patch primitives are not supported by pipeline stages below the tessellation evaluation shader.

An `INVALID_OPERATION` error is generated by any command that transfers vertices to the GL if the primitive *mode* is `PATCHES` and there is no active tessellation evaluation program .

A program object or program pipeline object that includes a tessellation shader of any kind must also include a vertex shader.

An `INVALID_OPERATION` error is generated by any command that transfers vertices to the GL if the current program state has a tessellation shader but no vertex shader.

### 11.2.1 Tessellation Control Shaders

The tessellation control shader consumes an input patch provided by the application and emits a new output patch. The input patch is an array of vertices with attributes corresponding to output variables written by the vertex shader. The output patch consists of an array of vertices with attributes corresponding to per-vertex output variables written by the tessellation control shader and a set of per-patch attributes corresponding to per-patch output variables written by the tessellation control shader. Tessellation control output variables are per-vertex by default, but may be declared as per-patch using the `patch` qualifier.

The number of vertices in the output patch is fixed when the program is linked, and is specified in tessellation control shader source code using the output `layout` qualifier `vertices`, as described in the OpenGL Shading Language Specification. A program will fail to link if the output patch vertex count is not specified by any tessellation control shader object attached to the program, if it is specified

differently by multiple tessellation control shader objects, if it is less than or equal to zero, or if it is greater than the implementation-dependent maximum patch size. The output patch vertex count may be queried by calling **GetProgramiv** with the symbolic constant `TESS_CONTROL_OUTPUT_VERTICES`.

Tessellation control shaders are created as described in section 7.1, using a *type* of `TESS_CONTROL_SHADER`. When a new input patch is received, the tessellation control shader is run once for each vertex in the output patch. The tessellation control shader invocations collectively specify the per-vertex and per-patch attributes of the output patch. The per-vertex attributes are obtained from the per-vertex output variables written by each invocation. Each tessellation control shader invocation may only write to per-vertex output variables corresponding to its own output patch vertex. The output patch vertex number corresponding to a given tessellation control point shader invocation is given by the built-in variable `gl_InvocationID`. Per-patch attributes are taken from the per-patch output variables, which may be written by any tessellation control shader invocation. While tessellation control shader invocations may read any per-vertex and per-patch output variable and write any per-patch output variable, reading or writing output variables also written by other invocations has ordering hazards discussed below.

### 11.2.1.1 Tessellation Control Shader Variables

Tessellation control shaders can access uniforms belonging to the current program object. Limits on uniform storage and methods for manipulating uniforms are described in section 7.6.

Tessellation control shaders also have access to samplers to perform texturing operations, as described in section 7.10.

Tessellation control shaders can access the transformed attributes of all vertices for their input primitive using *input* variables. A vertex shader writing to output variables generates the values of these input variables. Values for any inputs that are not written by a vertex shader are undefined.

Additionally, tessellation control shaders can write to one or more *output* including per-vertex attributes for the vertices of the output patch and per-patch attributes of the patch. Tessellation control shaders can also write to a set of built-in per-vertex and per-patch outputs defined in the OpenGL Shading Language. The per-vertex and per-patch attributes of the output patch are used by the tessellation primitive generator (section 11.2.2) and may be read by tessellation control shader (section 11.2.3).

### 11.2.1.2 Tessellation Control Shader Execution Environment

If there is an active program for the tessellation control stage, the executable version of the program's tessellation control shader is used to process patches resulting from the primitive assembly stage. When tessellation control shader execution completes, the input patch is consumed. A new patch is assembled from the per-vertex and per-patch output variables written by the shader and is passed to subsequent pipeline stages.

There are several special considerations for tessellation control shader execution described in the following sections.

**11.2.1.2.1 Texture Access** Section 11.1.3.1 describes texture lookup functionality accessible to a vertex shader. The texel fetch and texture size query functionality described there also applies to tessellation control shaders.

**11.2.1.2.2 Tessellation Control Shader Inputs** Section 7.1("Built-In Variables") of the OpenGL Shading Language Specification describes the built-in variable array `gl_in` available as input to a tessellation control shader. `gl_in` receives values from equivalent built-in output variables written by the vertex shader (section 11.1.3). Each array element of `gl_in` is a structure holding values for a specific vertex of the input patch. The length of `gl_in` is equal to the implementation-dependent maximum patch size (`gl_MaxPatchVertices`). Behavior is undefined if `gl_in` is indexed with a vertex index greater than or equal to the current patch size. The members of each element of the `gl_in` array are `gl_Position`, `gl_PointSize`, `gl_ClipDistance`, and `gl_ClipVertex`.

Tessellation control shaders have available several other built-in input variables not replicated per-vertex and not contained in `gl_in`, including:

- The variable `gl_PatchVerticesIn` holds the number of vertices in the input patch being processed by the tessellation control shader.
- The variable `gl_PrimitiveID` is filled with the number of primitives processed by the drawing command which generated the input vertices. The first primitive generated by a drawing command is numbered zero, and the primitive ID counter is incremented after every individual point, line, or triangle primitive is processed. Restarting a primitive topology using the primitive restart index has no effect on the primitive ID counter.
- The variable `gl_InvocationID` holds an invocation number for the current tessellation control shader invocation. Tessellation control shaders are

invoked once per output patch vertex, and invocations are numbered beginning with zero.

Similarly to the built-in inputs, each user-defined input variable has a value for each vertex and thus needs to be declared as arrays or inside input blocks declared as arrays. Declaring an array size is optional. If no size is specified, it will be taken from the implementation-dependent maximum patch size (`gl_MaxPatchVertices`). If a size is specified, it must match the maximum patch size; otherwise, a link error will occur. Since the array size may be larger than the number of vertices found in the input patch, behavior is undefined if a per-vertex input variable is accessed using an index greater than or equal to the number of vertices in the input patch. The OpenGL Shading Language doesn't support multi-dimensional arrays; therefore, user-defined tessellation control shader inputs corresponding to vertex shader outputs declared as arrays must be declared as array members of an input block that is itself declared as an array.

Similarly to the limit on vertex shader output components (see section 11.1.2.1), there is a limit on the number of components of input variables that can be read by the tessellation control shader, given by the value of the implementation-dependent constant `MAX_TESS_CONTROL_INPUT_COMPONENTS`.

When a program is linked, all components of any input variable read by a tessellation control shader will count against this limit. A program whose tessellation control shader exceeds this limit may fail to link, unless device-dependent optimizations are able to make the program fit within available hardware resources.

Component counting rules for different variable types and variable declarations are the same as for `MAX_VERTEX_OUTPUT_COMPONENTS`. (see section 11.1.2.1).

**11.2.1.2.3 Tessellation Control Shader Outputs** Section 7.1 (“Built-In Variables”) of the OpenGL Shading Language Specification describes the built-in variable array `gl_out` available as an output for a tessellation control shader. `gl_out` passes values to equivalent built-in input variables read by subsequent shader stages or to subsequent fixed functionality vertex processing pipeline stages. Each array element of `gl_out` is a structure holding values for a specific vertex of the output patch. The length of `gl_out` is equal to the output patch size specified in the tessellation control shader output layout declaration. The members of each element of the `gl_out` array are `gl_Position`, `gl_PointSize`, and `gl_ClipDistance`, and behave identically to equivalently named vertex shader outputs (section 11.1.3).

Tessellation shaders additionally have two built-in per-patch output arrays, `gl_TessLevelOuter` and `gl_TessLevelInner`. These arrays are not repli-

cated for each output patch vertex and are not members of `gl_out`. `gl_TessLevelOuter` is an array of four floating-point values specifying the approximate number of segments that the tessellation primitive generator should use when subdividing each outer edge of the primitive it subdivides. `gl_TessLevelInner` is an array of two floating-point values specifying the approximate number of segments used to produce a regularly-subdivided primitive interior. The values written to `gl_TessLevelOuter` and `gl_TessLevelInner` need not be integers, and their interpretation depends on the type of primitive the tessellation primitive generator will subdivide and other tessellation parameters, as discussed in the following section.

A tessellation control shader may also declare user-defined per-vertex output variables. User-defined per-vertex output variables are declared with the qualifier `out` and have a value for each vertex in the output patch. Such variables must be declared as arrays or inside output blocks declared as arrays. Declaring an array size is optional. If no size is specified, it will be taken from the output patch size declared in the shader. If a size is specified, it must match the maximum patch size; otherwise, a link error will occur. The OpenGL Shading Language doesn't support multi-dimensional arrays; therefore, user-defined per-vertex tessellation control shader outputs with multiple elements per vertex must be declared as array members of an output block that is itself declared as an array.

While per-vertex output variables are declared as arrays indexed by vertex number, each tessellation control shader invocation may write only to those outputs corresponding to its output patch vertex. Tessellation control shaders must use the input variable `gl_InvocationID` as the vertex number index when writing to per-vertex output variables.

Additionally, a tessellation control shader may declare per-patch output variables using the qualifier `patch out`. Unlike per-vertex outputs, per-patch outputs do not correspond to any specific vertex in the patch, and are not indexed by vertex number. Per-patch outputs declared as arrays have multiple values for the output patch; similarly declared per-vertex outputs would indicate a single value for each vertex in the output patch. User-defined per-patch outputs are not used by the tessellation primitive generator, but may be read by tessellation evaluation shaders.

There are several limits on the number of components of output variables that can be written by the tessellation control shader. The number of components of active per-vertex output variables may not exceed the value of `MAX_TESS_CONTROL_OUTPUT_COMPONENTS`. The number of components of active per-patch output variables may not exceed the value of `MAX_TESS_PATCH_COMPONENTS`. The built-in outputs `gl_TessLevelOuter` and `gl_TessLevelInner` are not counted against the per-patch limit. The total number of components of active per-vertex and per-patch outputs is derived by multiplying the per-vertex output com-

ponent count by the output patch size and then adding the per-patch output component count. The total component count may not exceed `MAX_TESS_CONTROL_TOTAL_OUTPUT_COMPONENTS`.

When a program is linked, all components of any output variable written by a tessellation control shader will count against this limit. A program exceeding any of these limits may fail to link, unless device-dependent optimizations are able to make the program fit within available hardware resources.

Counting rules for different variable types and variable declarations are the same as for `MAX_VERTEX_OUTPUT_COMPONENTS`. (see section 11.1.2.1).

**11.2.1.2.4 Tessellation Control Shader Execution Order** For tessellation control shaders with a declared output patch size greater than one, the shader is invoked more than once for each input patch. The order of execution of one tessellation control shader invocation relative to the other invocations for the same input patch is largely undefined. The built-in function `barrier` provides some control over relative execution order. When a tessellation control shader calls the `barrier` function, its execution pauses until all other invocations have also called the same function. Output variable assignments performed by any invocation executed prior to calling `barrier` will be visible to any other invocation after the call to `barrier` returns. Shader output values read in one invocation but written by another may be undefined without proper use of `barrier`; full rules are found in the OpenGL Shading Language Specification.

The `barrier` function may only be called inside the main entry point of the tessellation control shader and may not be called in potentially divergent flow control. In particular, `barrier` may not be called inside a switch statement, in either sub-statement of an if statement, inside a do, for, or while loop, or at any point after a return statement in the function `main`.

## 11.2.2 Tessellation Primitive Generation

If a tessellation evaluation shader is present, the tessellation primitive generator consumes the input patch and produces a new set of basic primitives (points, lines, or triangles). These primitives are produced by subdividing a geometric primitive (rectangle or triangle) according to the per-patch tessellation levels written by the tessellation control shader, if present, or taken from default patch parameter values. This subdivision is performed in an implementation-dependent manner. If no tessellation evaluation shader is present, the tessellation primitive generator passes incoming primitives through without modification.

The type of subdivision performed by the tessellation primitive generator is specified by an input layout declaration in the tessellation evaluation shader using one of the identifiers `triangles`, `quads`, and `isolines`. For `triangles`, the primitive generator subdivides a triangle primitive into smaller triangles. For `quads`, the primitive generator subdivides a rectangle primitive into smaller triangles. For `isolines`, the primitive generator subdivides a rectangle primitive into a collection of line segments arranged in strips stretching horizontally across the rectangle. Each vertex produced by the primitive generator has an associated  $(u, v, w)$  or  $(u, v)$  position in a normalized parameter space, with parameter values in the range  $[0, 1]$ , as illustrated in figure 11.1. For `triangles`, the vertex position is a barycentric coordinate  $(u, v, w)$ , where  $u + v + w = 1$ , and indicates the relative influence of the three vertices of the triangle on the position of the vertex. For `quads` and `isolines`, the position is a  $(u, v)$  coordinate indicating the relative horizontal and vertical position of the vertex relative to the subdivided rectangle. The subdivision process is explained in more detail in subsequent sections.

When no tessellation control shader is present, the tessellation levels are taken from default patch tessellation levels. These default levels are set by calling

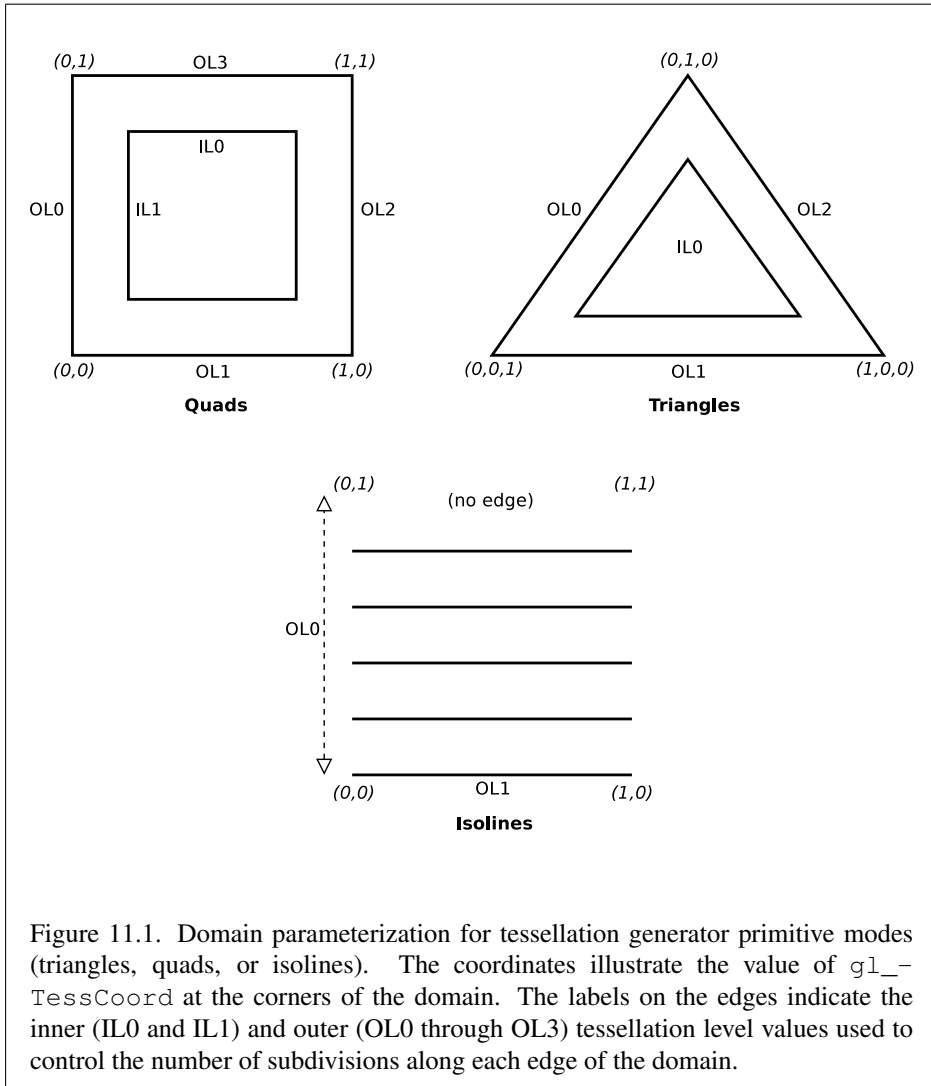
```
void PatchParameterfv( enum pname, const
                        float *values );
```

If *pname* is `PATCH_DEFAULT_OUTER_LEVEL`, *values* specifies an array of four floating-point values corresponding to the four outer tessellation levels for each subsequent patch. If *pname* is `PATCH_DEFAULT_INNER_LEVEL`, *values* specifies an array of two floating-point values corresponding to the two inner tessellation levels.

A patch is discarded by the tessellation primitive generator if any relevant outer tessellation level is less than or equal to zero. Patches will also be discarded if any outer tessellation level corresponds to a floating-point NaN (not a number) in implementations supporting NaN. When patches are discarded, no new primitives will be generated and the tessellation evaluation program will not be run. For `quads`, all four outer levels are relevant. For `triangles` and `isolines`, only the first three or two outer levels, respectively, are relevant. Negative inner levels will not cause a patch to be discarded; they will be clamped as described below.

Each of the tessellation levels is used to determine the number and spacing of segments used to subdivide a corresponding edge. The method used to derive the number and spacing of segments is specified by an input layout declaration in the tessellation evaluation shader using one of the identifiers `equal_spacing`, `fractional_even_spacing`, or `fractional_odd_spacing`. If no spacing is specified in the tessellation evaluation shader, `equal_spacing` will be used.





If `equal_spacing` is used, the floating-point tessellation level is first clamped to the range  $[1, max]$ , where `max` is the implementation-dependent maximum tessellation level (the value of `MAX_TESS_GEN_LEVEL`). The result is rounded up to the nearest integer  $n$ , and the corresponding edge is divided into  $n$  segments of equal length in  $(u, v)$  space.

If `fractional_even_spacing` is used, the tessellation level is first clamped to the range  $[2, max]$  and then rounded up to the nearest even integer  $n$ . If `fractional_odd_spacing` is used, the tessellation level is clamped to the range  $[1, max - 1]$  and then rounded up to the nearest odd integer  $n$ . If  $n$  is one, the edge will not be subdivided. Otherwise, the corresponding edge will be divided into  $n - 2$  segments of equal length, and two additional segments of equal length that are typically shorter than the other segments. The length of the two additional segments relative to the others will decrease monotonically with the value of  $n - f$ , where  $f$  is the clamped floating-point tessellation level. When  $n - f$  is zero, the additional segments will have equal length to the other segments. As  $n - f$  approaches 2.0, the relative length of the additional segments approaches zero. The two additional segments should be placed symmetrically on opposite sides of the subdivided edge. The relative location of these two segments is undefined, but must be identical for any pair of subdivided edges with identical values of  $f$ .

When the tessellation primitive generator produces triangles (in the `triangles` or `quads` modes), the orientation of all triangles can be specified by an input layout declaration in the tessellation evaluation shader using the identifiers `cw` and `ccw`. If the order is `cw`, the vertices of all generated triangles will have a clockwise ordering in  $(u, v)$  or  $(u, v, w)$  space, as illustrated in figure 11.1. If the order is `ccw`, the vertices will be specified in counter-clockwise order. If no layout is specified, `ccw` will be used.

For all primitive modes, the tessellation primitive generator is capable of generating points instead of lines or triangles. If an input layout declaration in the tessellation evaluation shader specifies the identifier `point_mode`, the primitive generator will generate one point for each unique vertex produced by tessellation. Otherwise, the primitive generator will produce a collection of line segments or triangles according to the primitive mode.

The points, lines, or triangles produced by the tessellation primitive generator are passed to subsequent pipeline stages in an implementation-dependent order.

### Errors

An `INVALID_ENUM` error is generated if `pname` is not `PATCH_DEFAULT_OUTER_LEVEL` or `PATCH_DEFAULT_INNER_LEVEL`.

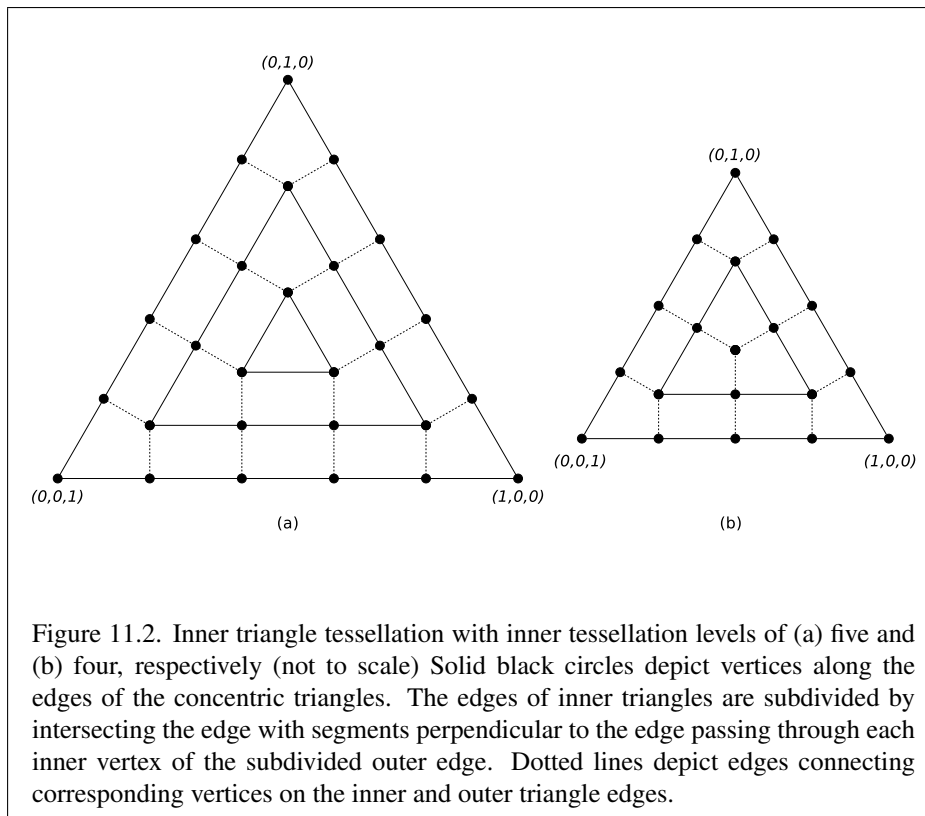
### 11.2.2.1 Triangle Tessellation

If the tessellation primitive mode is `triangles`, an equilateral triangle is subdivided into a collection of triangles covering the area of the original triangle. First, the original triangle is subdivided into a collection of concentric equilateral triangles. The edges of each of these triangles are subdivided, and the area between each triangle pair is filled by triangles produced by joining the vertices on the subdivided edges. The number of concentric triangles and the number of subdivisions along each triangle except the outermost is derived from the first inner tessellation level. The edges of the outermost triangle are subdivided independently, using the first, second, and third outer tessellation levels to control the number of subdivisions of the  $u = 0$  (left),  $v = 0$  (bottom), and  $w = 0$  (right) edges, respectively. The second inner tessellation level and the fourth outer tessellation level have no effect in this mode.

If the first inner tessellation level and all three outer tessellation levels are exactly one after clamping and rounding, only a single triangle with  $(u, v, w)$  coordinates of  $(0, 0, 1)$ ,  $(1, 0, 0)$ , and  $(0, 1, 0)$  is generated. If the inner tessellation level is one and any of the outer tessellation levels is greater than one, the inner tessellation level is treated as though it were originally specified as  $1 + \epsilon$  and will be rounded up to result in a two- or three-segment subdivision according to the tessellation spacing.

If any tessellation level is greater than one, tessellation begins by producing a set of concentric inner triangles and subdividing their edges. First, the three outer edges are temporarily subdivided using the clamped and rounded first inner tessellation level and the specified tessellation spacing, generating  $n$  segments. For the outermost inner triangle, the inner triangle is degenerate – a single point at the center of the triangle – if  $n$  is two. Otherwise, for each corner of the outer triangle, an inner triangle corner is produced at the intersection of two lines extended perpendicular to the corner's two adjacent edges running through the vertex of the subdivided outer edge nearest that corner. If  $n$  is three, the edges of the inner triangle are not subdivided and is the final triangle in the set of concentric triangles. Otherwise, each edge of the inner triangle is divided into  $n - 2$  segments, with the  $n - 1$  vertices of this subdivision produced by intersecting the inner edge with lines perpendicular to the edge running through the  $n - 1$  innermost vertices of the subdivision of the outer edge. Once the outermost inner triangle is subdivided, the previous subdivision process repeats itself, using the generated triangle as an outer triangle. This subdivision process is illustrated in figure 11.2.

Once all the concentric triangles are produced and their edges are subdivided, the area between each pair of adjacent inner triangles is filled completely with a set of non-overlapping triangles. In this subdivision, two of the three vertices of



each triangle are taken from adjacent vertices on a subdivided edge of one triangle; the third is one of the vertices on the corresponding edge of the other triangle. If the innermost triangle is degenerate (i.e., a point), the triangle containing it is subdivided into six triangles by connecting each of the six vertices on that triangle with the center point. If the innermost triangle is not degenerate, that triangle is added to the set of generated triangles as-is.

After the area corresponding to any inner triangles is filled, the primitive generator generates triangles to cover area between the outermost triangle and the outermost inner triangle. To do this, the temporary subdivision of the outer triangle edge above is discarded. Instead, the  $u = 0$ ,  $v = 0$ , and  $w = 0$  edges are subdivided according to the first, second, and third outer tessellation levels, respectively, and the tessellation spacing. The original subdivision of the first inner triangle is retained. The area between the outer and first inner triangles is completely filled by non-overlapping triangles as described above. If the first (and only) inner triangle is degenerate, a set of triangles is produced by connecting each vertex on the outer triangle edges with the center point.

After all triangles are generated, each vertex in the subdivided triangle is assigned a barycentric  $(u, v, w)$  coordinate based on its location relative to the three vertices of the outer triangle.

The algorithm used to subdivide the triangular domain in  $(u, v, w)$  space into individual triangles is implementation-dependent. However, the set of triangles produced will completely cover the domain, and no portion of the domain will be covered by multiple triangles. The order in which the generated triangles passed to subsequent pipeline stages and the order of the vertices in those triangles are both implementation-dependent. However, when depicted in a manner similar to figure 11.2, the order of the vertices in the generated triangles will be either all clockwise or all counter-clockwise, according to the vertex order layout declaration.

#### 11.2.2.2 Quad Tessellation

If the tessellation primitive mode is `quads`, a rectangle is subdivided into a collection of triangles covering the area of the original rectangle. First, the original rectangle is subdivided into a regular mesh of rectangles, where the number of rectangles along the  $u = 0$  and  $u = 1$  (vertical) and  $v = 0$  and  $v = 1$  (horizontal) edges are derived from the first and second inner tessellation levels, respectively. All rectangles, except those adjacent to one of the outer rectangle edges, are decomposed into triangle pairs. The outermost rectangle edges are subdivided independently, using the first, second, third, and fourth outer tessellation levels to control the number of subdivisions of the  $u = 0$  (left),  $v = 0$  (bottom),  $u = 1$

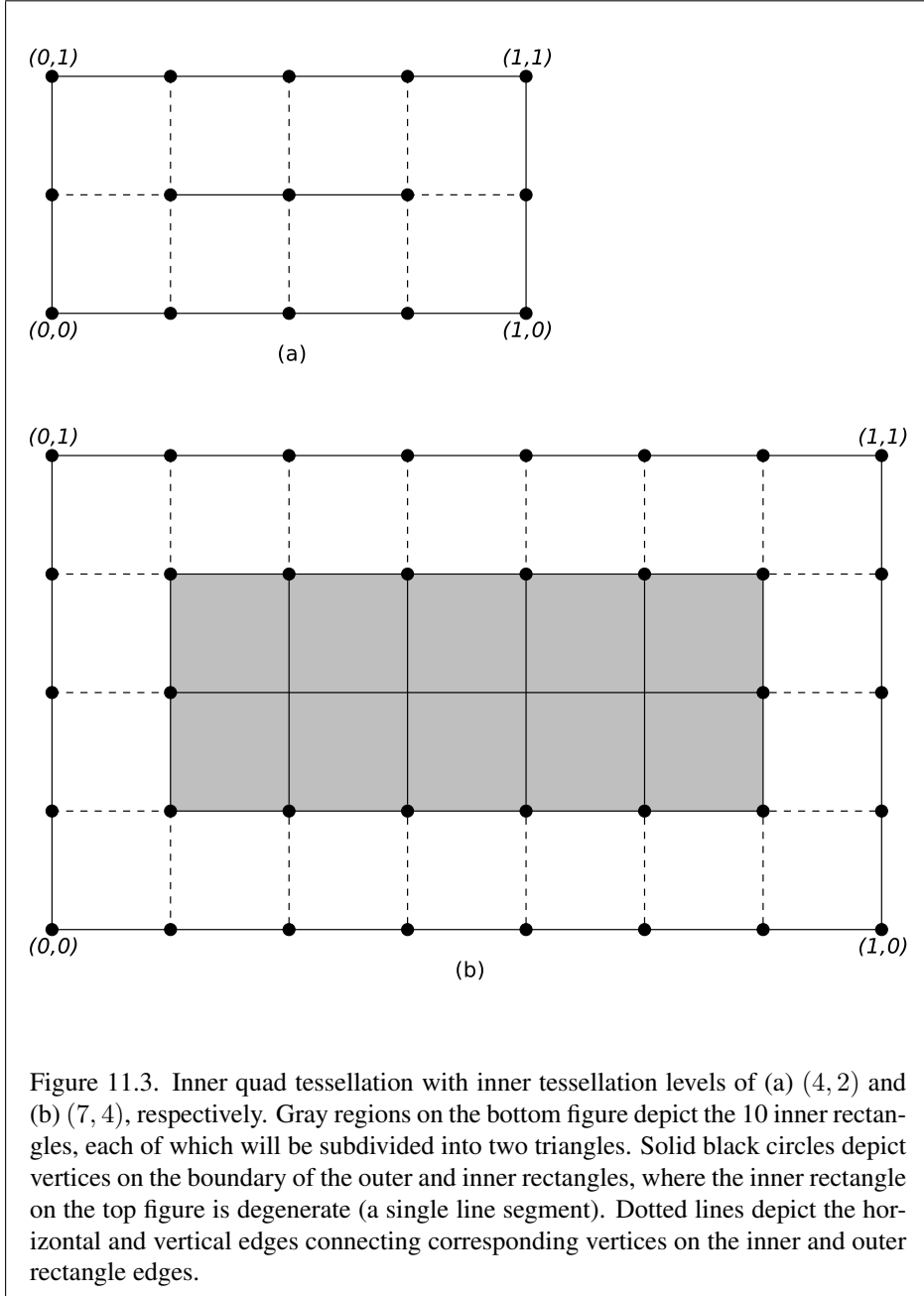
(right), and  $v = 1$  (top) edges, respectively. The area between the inner rectangles of the mesh and the outer rectangle edges are filled by triangles produced by joining the vertices on the subdivided outer edges to the vertices on the edge of the inner rectangle mesh.

If both clamped inner tessellation levels and all four clamped outer tessellation levels are exactly one, only a single triangle pair covering the outer rectangle is generated. Otherwise, if either clamped inner tessellation level is one, that tessellation level is treated as though it were originally specified as  $1 + \epsilon$ , which would rounded up to result in a two- or three-segment subdivision according to the tessellation spacing.

If any tessellation level is greater than one, tessellation begins by subdividing the  $u = 0$  and  $u = 1$  edges of the outer rectangle into  $m$  segments using the clamped and rounded first inner tessellation level and the tessellation spacing. The  $v = 0$  and  $v = 1$  edges are subdivided into  $n$  segments using the second inner tessellation level. Each vertex on the  $u = 0$  and  $v = 0$  edges are joined with the corresponding vertex on the  $u = 1$  and  $v = 1$  edges to produce a set of vertical and horizontal lines that divide the rectangle into a grid of smaller rectangles. The primitive generator emits a pair of non-overlapping triangles covering each such rectangle not adjacent to an edge of the outer rectangle. The boundary of the region covered by these triangles forms an inner rectangle, the edges of which are subdivided by the grid vertices that lie on the edge. If either  $m$  or  $n$  is two, the inner rectangle is degenerate, and one or both of the rectangle's "edges" consist of a single point. This subdivision is illustrated in figure 11.3.

After the area corresponding to the inner rectangle is filled, the primitive generator must produce triangles to cover area between the inner and outer rectangles. To do this, the subdivision of the outer rectangle edge above is discarded. Instead, the  $u = 0$ ,  $v = 0$ ,  $u = 1$ , and  $v = 1$  edges are subdivided according to the first, second, third, and fourth outer tessellation levels, respectively, and the tessellation spacing. The original subdivision of the inner rectangle is retained. The area between the outer and inner rectangles is completely filled by non-overlapping triangles. Two of the three vertices of each triangle are adjacent vertices on a subdivided edge of one rectangle; the third is one of the vertices on the corresponding edge of the other triangle. If either edge of the innermost rectangle is degenerate, the area near the corresponding outer edges is filled by connecting each vertex on the outer edge with the single vertex making up the inner "edge".

The algorithm used to subdivide the rectangular domain in  $(u, v)$  space into individual triangles is implementation-dependent. However, the set of triangles produced will completely cover the domain, and no portion of the domain will be covered by multiple triangles. The order in which the generated triangles passed to subsequent pipeline stages and the order of the vertices in those triangles are



both implementation-dependent. However, when depicted in a manner similar to figure 11.3, the order of the vertices in the generated triangles will be either all clockwise or all counter-clockwise, according to the vertex order layout declaration.

### 11.2.2.3 Isoline Tessellation

If the tessellation primitive mode is `isolines`, a set of independent horizontal line segments is drawn. The segments are arranged into connected strips called *isolines*, where the vertices of each isoline have a constant  $v$  coordinate and  $u$  coordinates covering the full range  $[0, 1]$ . The number of *isolines generated* is derived from the first outer tessellation level; the number of segments in each *isoline* is derived from the second outer tessellation level. Both inner tessellation levels and the third and fourth outer tessellation levels have no effect in this mode.

As with quad tessellation above, isoline tessellation begins with a rectangle. The  $u = 0$  and  $u = 1$  edges of the rectangle are subdivided according to the *first* outer tessellation level. For the purposes of this subdivision, the tessellation spacing is ignored and treated as `equal_spacing`. An *isoline* is drawn connecting each vertex on the  $u = 0$  rectangle edge with the corresponding vertex on the  $u = 1$  rectangle edge, except that no line is drawn between  $(0, 1)$  and  $(1, 1)$ . If the number of *isolines* on the subdivided  $u = 0$  and  $u = 1$  edges is  $n$ , this process will result in  $n$  equally spaced lines with constant  $v$  coordinates of  $0, \frac{1}{n}, \frac{2}{n}, \dots, \frac{n-1}{n}$ .

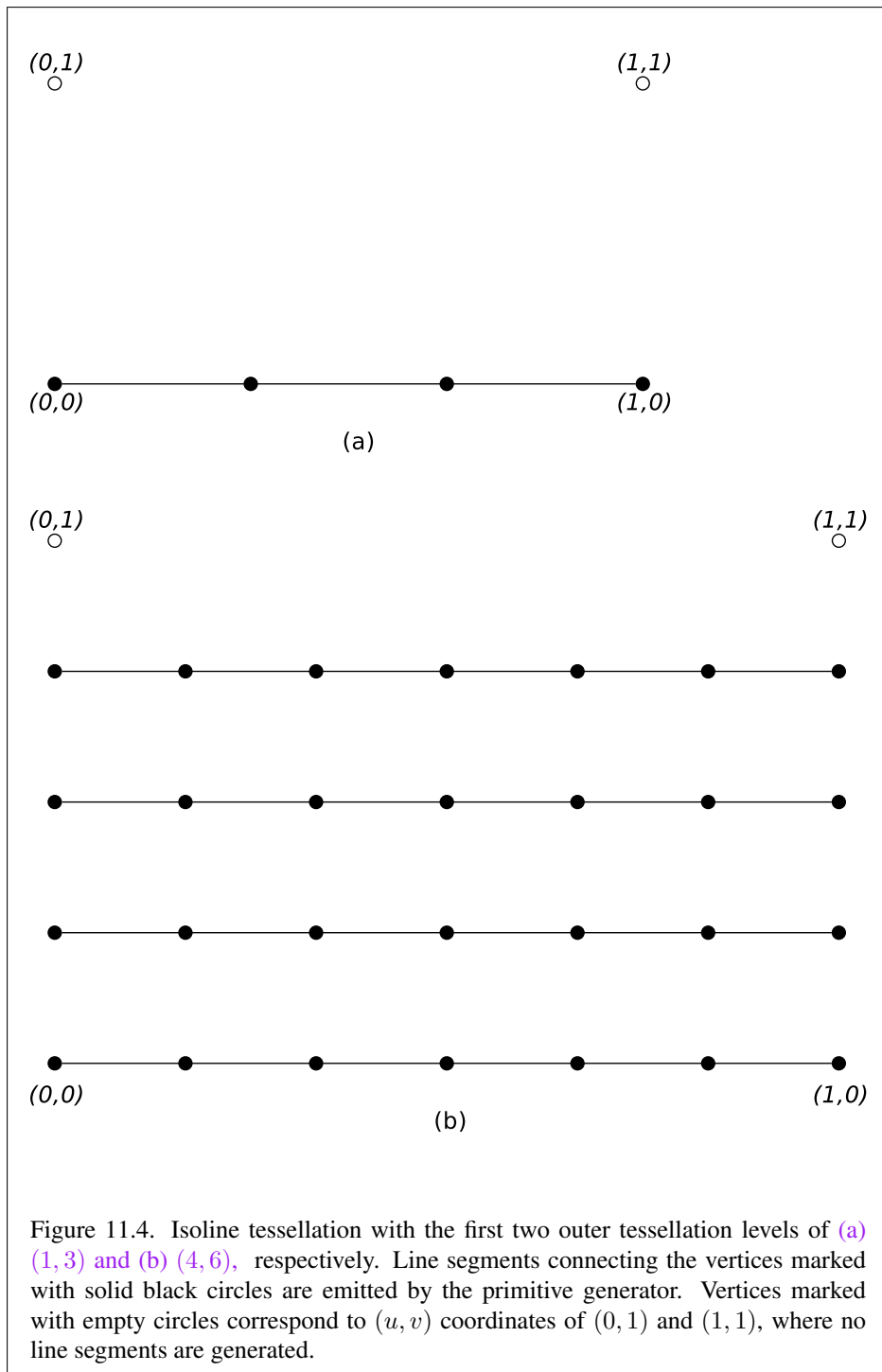
Each of the  $n$  *isolines* is then subdivided according to the *second* outer tessellation level and the tessellation spacing, resulting in  $m$  line segments. Each segment of each line is emitted by the tessellation primitive generator, as illustrated in figure 11.4.

The order in which the generated line segments are passed to subsequent pipeline stages and the order of the vertices in each generated line segment are both implementation-dependent.

### 11.2.3 Tessellation Evaluation Shaders

If active, the tessellation evaluation shader takes the  $(u, v)$  or  $(u, v, w)$  location of each vertex in the primitive subdivided by the tessellation primitive generator, and generates a vertex with a position and associated attributes. The tessellation evaluation shader can read any of the vertices of its input patch, which is the output patch produced by the tessellation control shader (if present) or provided by the application and transformed by the vertex shader (if no control shader is used). Tessellation evaluation shaders are created as described in section 7.1, using a *type* of `TESS_EVALUATION_SHADER`.





Each invocation of the tessellation evaluation shader writes the attributes of exactly one vertex. The number of vertices evaluated per patch depends on the tessellation level values computed by the tessellation control shaders (if present) or specified as patch parameters. Tessellation evaluation shader invocations run independently, and no invocation can access the variables belonging to another invocation. All invocations are capable of accessing all the vertices of their corresponding input patch.

If a tessellation control shader is present, the number of the vertices in the input patch is fixed and is equal to the tessellation control shader output patch size parameter in effect when the program was last linked. If no tessellation control shader is present, the input patch is provided by the application can have a variable number of vertices, as specified by **PatchParameteri**.

### 11.2.3.1 Tessellation Evaluation Shader Variables

Tessellation evaluation shaders can access uniforms belonging to the current program object. Limits on uniform storage and methods for manipulating uniforms are described in section 7.6.

Tessellation evaluation shaders also have access to samplers to perform texturing operations, as described in section 7.10.

Tessellation evaluation shaders can access the transformed attributes of all vertices for their input primitive using input variables. If active, a tessellation control shader writing to output variables generates the values of these input variables. If no tessellation control shader is active, input variables will be obtained from vertex shader outputs. Values for any input variable that are not written by a vertex or tessellation control shader are undefined.

Additionally, tessellation evaluation shaders can write to one or more output variables that will be passed to subsequent programmable shader stages or fixed functionality vertex pipeline stages.

### 11.2.3.2 Tessellation Evaluation Shader Execution Environment

If there is an active program for the tessellation evaluation stage, the executable version of the program's tessellation evaluation shader is used to process vertices produced by the tessellation primitive generator. During this processing, the shader may access the input patch processed by the primitive generator. When tessellation evaluation shader execution completes, a new vertex is assembled from the output variables written by the shader and is passed to subsequent pipeline stages.

There are several special considerations for tessellation evaluation shader execution described in the following sections.

**11.2.3.2.1 Texture Access** Section 11.1.3.1 describes texture lookup functionality accessible to a vertex shader. The texel fetch and texture size query functionality described there also applies to tessellation evaluation shaders.

### 11.2.3.3 Tessellation Evaluation Shader Inputs

Section 7.1 (“Built-In Variables”) of the OpenGL Shading Language Specification describes the built-in variable array `gl_in` available as input to a tessellation evaluation shader. `gl_in` receives values from equivalent built-in output variables written by a previous shader (section 11.1.3). If a tessellation control shader active, the values of `gl_in` will be taken from tessellation control shader outputs. Otherwise, they will be taken from vertex shader outputs. Each array element of `gl_in` is a structure holding values for a specific vertex of the input patch. The length of `gl_in` is equal to the implementation-dependent maximum patch size (`gl_MaxPatchVertices`). Behavior is undefined if `gl_in` is indexed with a vertex index greater than or equal to the current patch size. The members of each element of the `gl_in` array are `gl_Position`, `gl_PointSize`, and `gl_ClipDistance`.

Tessellation evaluation shaders have available several other built-in input variables not replicated per-vertex and not contained in `gl_in`, including:

- The variables `gl_PatchVerticesIn` and `gl_PrimitiveID` are filled with the number of the vertices in the input patch and a primitive number, respectively. They behave exactly as the identically named inputs for tessellation control shaders.
- The variable `gl_TessCoord` is a three-component floating-point vector consisting of the  $(u, v, w)$  coordinate of the vertex being processed by the tessellation evaluation shader. The values of  $u$ ,  $v$ , and  $w$  are in the range  $[0, 1]$ , and vary linearly across the primitive being subdivided. For tessellation primitive modes of `quads` or `isolines`, the  $w$  value is always zero. The  $(u, v, w)$  coordinates are generated by the tessellation primitive generator in a manner dependent on the primitive mode, as described in section 11.2.2. `gl_TessCoord` is not an array; it specifies the location of the vertex being processed by the tessellation evaluation shader, not of any vertex in the input patch.
- The variables `gl_TessLevelOuter` and `gl_TessLevelInner` are arrays holding outer and inner tessellation levels of the patch, as used by the tessellation primitive generator. If a tessellation control shader is active, the tessellation levels will be taken from the corresponding outputs of

the tessellation control shader. Otherwise, the default levels provided as patch parameters are used. Tessellation level values loaded in these variables will be prior to the clamping and rounding operations performed by the primitive generator as described in section 11.2.2. For triangular tessellation, `gl_TessLevelOuter[3]` and `gl_TessLevelInner[1]` will be undefined. For isoline tessellation, `gl_TessLevelOuter[2]`, `gl_TessLevelOuter[3]`, and both values in `gl_TessLevelInner` are undefined.

A tessellation evaluation shader may also declare user-defined per-vertex input variables. User-defined per-vertex input variables are declared with the qualifier `in` and have a value for each vertex in the input patch. User-defined per-vertex input variables have a value for each vertex and thus need to be declared as arrays or inside input blocks declared as arrays. Declaring an array size is optional. If no size is specified, it will be taken from the implementation-dependent maximum patch size (`gl_MaxPatchVertices`). If a size is specified, it must match the maximum patch size; otherwise, a link error will occur. Since the array size may be larger than the number of vertices found in the input patch, behavior is undefined if a per-vertex input variable is accessed using an index greater than or equal to the number of vertices in the input patch. The OpenGL Shading Language doesn't support multi-dimensional arrays; therefore, user-defined tessellation evaluation shader inputs corresponding to vertex shader outputs declared as arrays must be declared as array members of an input block that is itself declared as an array.

Additionally, a tessellation evaluation shader may declare per-patch input variables using the qualifier `patch in`. Unlike per-vertex inputs, per-patch inputs do not correspond to any specific vertex in the patch, and are not indexed by vertex number. Per-patch inputs declared as arrays have multiple values for the input patch; similarly declared per-vertex inputs would indicate a single value for each vertex in the output patch. User-defined per-patch input variables are filled with corresponding per-patch output values written by the tessellation control shader. If no tessellation control shader is active, all such variables are undefined.

Similarly to the limit on vertex shader output components (see section 11.1.2.1), there is a limit on the number of components of per-vertex and per-patch input variables that can be read by the tessellation evaluation shader, given by the values of the implementation-dependent constants `MAX_TESS_EVALUATION_INPUT_COMPONENTS` and `MAX_TESS_PATCH_COMPONENTS`, respectively. The built-in inputs `gl_TessLevelOuter` and `gl_TessLevelInner` are not counted against the per-patch limit.

When a program is linked, all components of any input variable read by a tessellation evaluation shader will count against this limit. A program whose tessella-

tion evaluation shader exceeds this limit may fail to link, unless device-dependent optimizations are able to make the program fit within available hardware resources.

Component counting rules for different variable types and variable declarations are the same as for `MAX_VERTEX_OUTPUT_COMPONENTS`. (see section 11.1.2.1).

#### 11.2.3.4 Tessellation Evaluation Shader Outputs

Tessellation evaluation shaders have a number of built-in output variables used to pass values to equivalent built-in input variables read by subsequent shader stages or to subsequent fixed functionality vertex processing pipeline stages. These variables are `gl_Position`, `gl_PointSize`, and `gl_ClipDistance`, and all behave identically to equivalently named vertex shader outputs (see section 11.1.3). A tessellation evaluation shader may also declare user-defined per-vertex output variables.

Similarly to the limit on vertex shader output components (see section 11.1.2.1), there is a limit on the number of components of output variables that can be written by the tessellation evaluation shader, given by the values of the implementation-dependent constant `MAX_TESS_EVALUATION_OUTPUT_COMPONENTS`.

When a program is linked, all components of any output variable written by a tessellation evaluation shader will count against this limit. A program whose tessellation evaluation shader exceeds this limit may fail to link, unless device-dependent optimizations are able to make the program fit within available hardware resources.

Counting rules for different variable types and variable declarations are the same as for `MAX_VERTEX_OUTPUT_COMPONENTS`. (see section 11.1.2.1).

## 11.3 Geometry Shaders

After vertices are processed, they are arranged into primitives, as described in section 10.8. This section describes optional *geometry shaders*, an additional pipeline stage defining operations to further process those primitives. Geometry shaders operate on a single primitive at a time and emit one or more output primitives, all of the same type, which are then processed like an equivalent OpenGL primitive specified by the application. The original primitive is discarded after geometry shader execution. The inputs available to a geometry shader are the transformed attributes of all the vertices that belong to the primitive. Additional *adjacency primitives* are available which also make the transformed attributes of neighboring vertices available to the shader. The results of the shader are a new set of transformed vertices,

arranged into primitives by the shader.

The geometry shader pipeline stage is inserted after primitive assembly, prior to transform feedback (section 13.2).

Geometry shaders are created as described in section 7.1 using a *type* of `GEOMETRY_SHADER`. They are attached to and used in program objects as described in section 7.3. When the program object currently in use includes a geometry shader, its geometry shader is considered active, and is used to process primitives. If the program object has no geometry shader, this stage is bypassed.

A program object or program pipeline object that includes a geometry shader must also include a vertex shader.

An `INVALID_OPERATION` error is generated by any command that transfers vertices to the GL if the current program state has a geometry shader but no vertex shader.

### 11.3.1 Geometry Shader Input Primitives

A geometry shader can operate on one of five input primitive types. Depending on the input primitive type, one to six input vertices are available when the shader is executed. Each input primitive type supports a subset of the primitives provided by the GL.

An `INVALID_OPERATION` error is generated by any command that transfers vertices to the GL if a geometry shader is active and the primitive *mode* parameter is incompatible with the input primitive type of the geometry shader of the active geometry program object, as discussed below.

A geometry shader that accesses more input vertices than are available for a given input primitive type can be successfully compiled, because the input primitive type is not part of the shader object. However, a program object containing a shader object that accesses more input vertices than are available for the input primitive type of the program object will not link.

The input primitive type is specified in the geometry shader source code using an input `layout` qualifier, as described in the OpenGL Shading Language Specification. A program will fail to link if the input primitive type is not specified by any geometry shader object attached to the program, or if it is specified differently by multiple geometry shader objects. The input primitive type may be queried by calling **GetProgramiv** with the symbolic constant `GEOMETRY_INPUT_TYPE`. The supported types and the corresponding OpenGL Shading Language input `layout` qualifier keywords are:

**Points** (`points`)

Geometry shaders that operate on points are valid only for the `POINTS` primitive type. There is only a single vertex available for each geometry shader invocation.

#### **Lines** (`lines`)

Geometry shaders that operate on line segments are valid only for the `LINES`, `LINE_STRIP`, and `LINE_LOOP` primitive types. There are two vertices available for each geometry shader invocation. The first vertex refers to the vertex at the beginning of the line segment and the second vertex refers to the vertex at the end of the line segment. See also section 11.3.4.

#### **Lines with Adjacency** (`lines_adjacency`)

Geometry shaders that operate on line segments with adjacent vertices are valid only for the `LINES_ADJACENCY` and `LINE_STRIP_ADJACENCY` primitive types. There are four vertices available for each program invocation. The second vertex refers to attributes of the vertex at the beginning of the line segment and the third vertex refers to the vertex at the end of the line segment. The first and fourth vertices refer to the vertices adjacent to the beginning and end of the line segment, respectively.

#### **Triangles** (`triangles`)

Geometry shaders that operate on triangles are valid for the `TRIANGLES`, `TRIANGLE_STRIP` and `TRIANGLE_FAN` primitive types. There are three vertices available for each program invocation. The first, second and third vertices refer to attributes of the first, second and third vertex of the triangle, respectively.

#### **Triangles with Adjacency** (`triangles_adjacency`)

Geometry shaders that operate on triangles with adjacent vertices are valid for the `TRIANGLES_ADJACENCY` and `TRIANGLE_STRIP_ADJACENCY` primitive types. There are six vertices available for each program invocation. The first, third and fifth vertices refer to attributes of the first, second and third vertex of the triangle, respectively. The second, fourth and sixth vertices refer to attributes of the vertices adjacent to the edges from the first to the second vertex, from the second to the third vertex, and from the third to the first vertex, respectively.

### **11.3.2 Geometry Shader Output Primitives**

A geometry shader can generate primitives of one of three types. The supported output primitive types are points (`POINTS`), line strips (`LINE_STRIP`), and triangle strips (`TRIANGLE_STRIP`). The vertices output by the geometry shader are assembled into points, lines, or triangles based on the output primitive type in the manner

described in section 10.8. The resulting primitives are then further processed as described in section 11.3.4. If the number of vertices emitted by the geometry shader is not sufficient to produce a single primitive, nothing is drawn. The number of vertices output by the geometry shader is limited to a maximum count specified in the shader.

The output primitive type and maximum output vertex count are specified in the geometry shader source code using an output `layout` qualifier, as described in section 4.4.2.2(“Geometry Outputs”) of the OpenGL Shading Language Specification . A program will fail to link if either the output primitive type or maximum output vertex count are not specified by any geometry shader object attached to the program, or if they are specified differently by multiple geometry shader objects. The output primitive type and maximum output vertex count of a linked program may be queried by calling **GetProgramiv** with the symbolic constants `GEOMETRY_OUTPUT_TYPE` and `GEOMETRY_VERTICES_OUT`, respectively.

### 11.3.3 Geometry Shader Variables

Geometry shaders can access uniforms belonging to the current program object. Limits on uniform storage and methods for manipulating uniforms are described in section 7.6.

Geometry shaders also have access to samplers to perform texturing operations, as described in section 7.10.

Geometry shaders can access the transformed attributes of all vertices for their input primitive type using input variables. A vertex shader writing to output variables generates the values of these input variables. Values for any inputs that are not written by a vertex shader are undefined. Additionally, a geometry shader has access to a built-in input that holds the ID of the current primitive. This ID is generated by the primitive assembly stage that sits in between the vertex and geometry shader.

Additionally, geometry shaders can write to one or more output variables for each vertex they output. These values are optionally flatshaded (using the OpenGL Shading Language qualifier `flat`) and clipped, then the clipped values interpolated across the primitive (if not flatshaded). The results of these interpolations are available to the fragment shader.

### 11.3.4 Geometry Shader Execution Environment

If there is an active program for the geometry stage, the executable version of the program’s geometry shader is used to process primitives resulting from the primitive assembly stage.



There are several special considerations for geometry shader execution described in the following sections.

#### 11.3.4.1 Texture Access

Section 11.1.3.1 describes texture lookup functionality accessible to a vertex shader. The texel fetch and texture size query functionality described there also applies to geometry shaders.

#### 11.3.4.2 Instanced Geometry Shaders

For each input primitive received by the geometry shader pipeline stage, the geometry shader may be run once or multiple times. The number of times a geometry shader should be executed for each input primitive may be specified using a `layout` qualifier in a geometry shader of a linked program. If the invocation count is not specified in any `layout` qualifier, the invocation count will be one.

Each separate geometry shader invocation is assigned a unique invocation number. For a geometry shader with  $N$  invocations, each input primitive spawns  $N$  invocations, numbered 0 through  $N - 1$ . The built-in uniform `gl_InvocationID` may be used by a geometry shader invocation to determine its invocation number.

When executing instanced geometry shaders, the output primitives generated from each input primitive are passed to subsequent pipeline stages using the shader invocation number to order the output. The first primitives received by the subsequent pipeline stages are those emitted by the shader invocation numbered zero, followed by those from the shader invocation numbered one, and so forth. Additionally, all output primitives generated from a given input primitive are passed to subsequent pipeline stages before any output primitives generated from subsequent input primitives.

#### 11.3.4.3 Geometry Shader Vertex Streams

Geometry shaders may emit primitives to multiple independent vertex streams. Each vertex emitted by the geometry shader is directed at one of the vertex streams. As vertices are received on each stream, they are arranged into primitives of the type specified by the geometry shader output primitive type. The shading language built-in functions `EndPrimitive` and `EndStreamPrimitive` may be used to end the primitive being assembled on a given vertex stream and start a new empty primitive of the same type. If an implementation supports  $N$  vertex streams, the individual streams are numbered 0 through  $N - 1$ . There is no requirement on the

order of the streams to which vertices are emitted, and the number of vertices emitted to each stream may be completely independent, subject only to implementation-dependent output limits.

The primitives emitted to all vertex streams are passed to the transform feedback stage to be captured and written to buffer objects in the manner specified by the transform feedback state. The primitives emitted to all streams but stream zero are discarded after transform feedback. Primitives emitted to stream zero are passed to subsequent pipeline stages for clipping, rasterization, and subsequent fragment processing.

Geometry shaders that emit vertices to multiple vertex streams are currently limited to using only the `points` output primitive type. A program will fail to link if it includes a geometry shader that calls the `EmitStreamVertex` built-in function and has any other output primitive type parameter.

#### 11.3.4.4 Geometry Shader Inputs

Section 7.1(“Built-In Variables”) of the OpenGL Shading Language Specification describes the built-in variable array `gl_in[]` available as input to a geometry shader. `gl_in[]` receives values from equivalent built-in output variables written by the vertex shader, and each array element of `gl_in[]` is a structure holding values for a specific vertex of the input primitive. The length of `gl_in[]` is determined by the geometry shader input type (see section 11.3.1). The members of each element of the `gl_in[]` array are:

- Structure member `gl_ClipDistance[]` holds the per-vertex array of clip distances, as written by the vertex shader to its built-in output variable `gl_ClipDistance[]`.
- Structure member `gl_PointSize` holds the per-vertex point size written by the vertex shader to its built-in output variable `gl_PointSize`. If the vertex shader does not write `gl_PointSize`, the value of `gl_PointSize` is undefined, regardless of the value of the enable `PROGRAM_POINT_SIZE`.
- Structure member `gl_Position` holds the per-vertex position, as written by the vertex shader to its built-in output variable `gl_Position`. Note that writing to `gl_Position` from either the vertex or geometry shader is optional (also see section 7.1(“Built-In Variables”) of the OpenGL Shading Language Specification )

Geometry shaders also have available the built-in input variable `gl_PrimitiveIDIn`, which is not an array and has no vertex shader equivalent. It

is filled with the number of primitives processed by the drawing command which generated the input vertices. The first primitive generated by a drawing command is numbered zero, and the primitive ID counter is incremented after every individual point, line, or triangle primitive is processed. For triangles drawn in point or line mode, the primitive ID counter is incremented only once, even though multiple points or lines may eventually be drawn. Restarting a primitive topology using the primitive restart index has no effect on the primitive ID counter.

Similarly to the built-in inputs, each user-defined input has a value for each vertex and thus needs to be declared as arrays or inside input blocks declared as arrays. Declaring an array size is optional. If no size is specified, it will be inferred by the linker from the input primitive type. If a size is specified, it must match the number of vertices for the input primitive type; otherwise, a link error will occur. The OpenGL Shading Language doesn't support multi-dimensional arrays; therefore, user-defined geometry shader inputs corresponding to vertex shader outputs declared as arrays must be declared as array members of an input block that is itself declared as an array. See sections 4.3.6("a") and 7.6("o") of the OpenGL Shading Language Specification for more information.

Similarly to the limit on vertex shader output components (see section 11.1.2.1), there is a limit on the number of components of input variables that can be read by the geometry shader, given by the value of the implementation-dependent constant `MAX_GEOMETRY_INPUT_COMPONENTS`.

When a program is linked, all components of any input read by a geometry shader will count against this limit. A program whose geometry shader exceeds this limit may fail to link, unless device-dependent optimizations are able to make the program fit within available hardware resources.

Component counting rules for different variable types and variable declarations are the same as for `MAX_VERTEX_OUTPUT_COMPONENTS`. (see section 11.1.2.1).

#### 11.3.4.5 Geometry Shader Outputs

A geometry shader is limited in the number of vertices it may emit per invocation. The maximum number of vertices a geometry shader can possibly emit is specified in the geometry shader source and may be queried after linking by calling **GetProgramiv** with the symbolic constant `GEOMETRY_VERTICES_OUT`. If a single invocation of a geometry shader emits more vertices than this value, the emitted vertices may have no effect.

There are two implementation-dependent limits on the value of `GEOMETRY_VERTICES_OUT`; it may not exceed the value of `MAX_GEOMETRY_OUTPUT_VERTICES`, and the product of the total number of vertices and the sum of all components of all active output variables may not exceed the value of `MAX_`

GEOMETRY\_TOTAL\_OUTPUT\_COMPONENTS. **LinkProgram** will fail if it determines that the total component limit would be violated.

A geometry shader can write to built-in as well as user-defined output variables. These values are expected to be interpolated across the primitive it outputs, unless they are specified to be flat shaded. To enable seamlessly inserting or removing a geometry shader from a program object, the rules, names and types of the built-in and user-defined output variables are the same as for the vertex shader. Refer to section 11.1.2.1, and to sections 4.3(“Storage Qualifiers”) and 7.1(“Built-In Variables”) of the OpenGL Shading Language Specification for more detail.

After a geometry shader emits a vertex, all output variables are undefined, as described in section 8.15(“Geometry Shader Functions”) of the OpenGL Shading Language Specification .

The built-in output `gl_Position` is intended to hold the homogeneous vertex position. Writing `gl_Position` is optional.

The built-in output `gl_ClipDistance` holds the clip distance used in the clipping stage, as described in section 13.5.

The built-in output `gl_PointSize`, if written, holds the size of the point to be rasterized, measured in pixels.

The built-in output `gl_PrimitiveID` holds the primitive ID counter read by the fragment shader, replacing the value of `gl_PrimitiveID` generated by drawing commands when no geometry shader is active. The geometry shader must write to `gl_PrimitiveID` for the provoking vertex (see section 13.4) of a primitive being generated, or the primitive ID counter read by the fragment shader for that primitive is undefined.

The built-in output `gl_Layer` is used in layered rendering, and discussed further in the next section.

The built-in output `gl_ViewportIndex` is used to direct rendering to one of several viewports and is discussed further in the next section.

Similarly to the limit on vertex shader output components (see section 11.1.2.1), there is a limit on the number of components of output variables that can be written by the geometry shader, given by the value of the implementation-dependent constant `MAX_GEOMETRY_OUTPUT_COMPONENTS`.

When a program is linked, all components of any output variable written by a geometry shader will count against this limit. A program whose geometry shader exceeds this limit may fail to link, unless device-dependent optimizations are able to make the program fit within available hardware resources.

Component counting rules for different variable types and variable declarations are the same as for `MAX_VERTEX_OUTPUT_COMPONENTS`. (see section 11.1.2.1).

#### 11.3.4.6 Layer and Viewport Selection

Geometry shaders can be used to render to one of several different layers of cube map textures, three-dimensional textures, or one-or two-dimensional texture arrays. This functionality allows an application to bind an entire complex texture to a framebuffer object, and render primitives to arbitrary layers computed at run time. For example, it can be used to project and render a scene onto all six faces of a cubemap texture in one pass. The layer to render to is specified by writing to the built-in output variable `gl_Layer`. Layered rendering requires the use of framebuffer objects (see section 9.8).

Geometry shaders may also select the destination viewport for each output primitive. The destination viewport for a primitive may be selected in the geometry shader by writing to the built-in output variable `gl_ViewportsIndex`. This functionality allows a geometry shader to direct its output to a different viewport for each primitive, or to draw multiple versions of a primitive into several different viewports.

The specific vertex of a primitive that is used to select the rendering layer or viewport index is implementation-dependent and thus portable applications will assign the same layer and viewport index for all vertices in a primitive. The vertex conventions followed for `gl_Layer` and `gl_ViewportsIndex` may be determined by calling **GetInteger** with the symbolic constants `LAYER_PROVOKING_VERTEX` and `VIEWPORT_INDEX_PROVOKING_VERTEX`, respectively. For either query, if the value returned is `PROVOKING_VERTEX`, then vertex selection follows the convention specified by **ProvokingVertex** (see section 13.4). If the value returned is `FIRST_VERTEX_CONVENTION`, selection is always taken from the first vertex of a primitive. If the value returned is `LAST_VERTEX_CONVENTION`, the selection is always taken from the last vertex of a primitive. If the value returned is `UNDEFINED_VERTEX`, the selection is not guaranteed to be taken from any specific vertex in the primitive. The vertex considered the provoking vertex for particular primitive types is given in table 13.2.

#### 11.3.4.7 Primitive Type Mismatches and Drawing Commands

An `INVALID_OPERATION` error is generated by any command that transfers vertices to the GL, and no fragments will be rendered, if a mismatch exists between the type of primitive being drawn and the input primitive type of a geometry shader. A mismatch exists under any of the following conditions:

- the input primitive type of the current geometry shader is `POINTS` and *mode* is not `POINTS`;

- the input primitive type of the current geometry shader is `LINES` and *mode* is not `LINES`, `LINE_STRIP`, or `LINE_LOOP`;
- the input primitive type of the current geometry shader is `TRIANGLES` and *mode* is not `TRIANGLES`, `TRIANGLE_STRIP` or `TRIANGLE_FAN`;
- the input primitive type of the current geometry shader is `LINES_ADJACENCY` and *mode* is not `LINES_ADJACENCY` or `LINE_STRIP_ADJACENCY`; or,
- the input primitive type of the current geometry shader is `TRIANGLES_ADJACENCY` and *mode* is not `TRIANGLES_ADJACENCY` or `TRIANGLE_STRIP_ADJACENCY`.

## Chapter 12

# ~~Fixed-Function Vertex Processing~~

This chapter is only defined in the compatibility profile.

## Chapter 13

# Fixed-Function Vertex Post-Processing

After programmable vertex processing, the following fixed-function operations are applied to vertices of the resulting primitives:

- Transform feedback (see section 13.2).
- Primitive queries (see section 13.3).
- Flatshading (see section 13.4).
- Primitive clipping, including client-defined half-spaces (see section 13.5).
- Shader output clipping (see section 13.5.1).
- Perspective division on clip coordinates (see section 13.6).
- Viewport mapping, including depth range scaling (see section 13.6.1).
- Front face determination for polygon primitives (see section 14.6.1).
- Generic attribute clipping (see section 13.5.1).

Next, rasterization is performed on primitives as described in chapter 14).

### 13.1 Clamping or Masking

This section is only defined in the compatibility profile.



## 13.2 Transform Feedback

In transform feedback mode, attributes of the vertices of transformed primitives passed to the transform feedback stage are written out to one or more buffer objects. The vertices are fed back before flatshading and clipping. The transformed vertices may be optionally discarded after being stored into one or more buffer objects, or they can be passed on down to the clipping stage for further processing. The set of attributes captured is determined when a program is linked.

The data captured in transform feedback mode depends on the active programs on each of the shader stages. If a program is active for the geometry shader stage, transform feedback captures the vertices of each primitive emitted by the geometry shader. Otherwise, if a program is active for the tessellation evaluation shader stage, transform feedback captures each primitive produced by the tessellation primitive generator, whose vertices are processed by the tessellation evaluation shader. Otherwise, transform feedback captures each primitive processed by the vertex shader.

If separable program objects are in use, the set of attributes captured is taken from the program object active on the last shader stage processing the primitives captured by transform feedback. The set of attributes to capture in transform feedback mode for any other program active on a previous shader stage is ignored.

### 13.2.1 Transform Feedback Objects

The set of buffer objects used to capture vertex attributes and related state are stored in a transform feedback object. The set of attributes captured in transform feedback mode is determined using the state of the active program object. The name space for transform feedback objects is the unsigned integers. The name zero designates the default transform feedback object.

The command

```
void GenTransformFeedbacks(sizei n, uint *ids);
```

returns *n* previously unused transform feedback object names in *ids*. These names are marked as used, for the purposes of **GenTransformFeedbacks** only, but they acquire transform feedback state only when they are first bound.

#### Errors

An `INVALID_VALUE` error is generated if *n* is negative.

Transform feedback objects are deleted by calling

```
void DeleteTransformFeedbacks( size_t n, const
    uint *ids );
```

*ids* contains *n* names of transform feedback objects to be deleted. After a transform feedback object is deleted it has no contents, and its name is again unused. Unused names in *ids* that have been marked as used for the purposes of **GenTransformFeedbacks** are marked as unused again. Unused names in *ids* are silently ignored, as is the value zero. The default transform feedback object cannot be deleted.

### Errors

An `INVALID_VALUE` error is generated if *n* is negative.

An `INVALID_OPERATION` error is generated if the transform feedback operation for any object named by *ids* is currently active.

The command

```
boolean IsTransformFeedback( uint id );
```

returns `TRUE` if *id* is the name of a transform feedback object. If *id* is zero, or a non-zero value that is not the name of a transform feedback object, **IsTransformFeedback** returns `FALSE`. No error is generated if *id* is not a valid transform feedback object name.

A transform feedback object is created by binding a name returned by **GenTransformFeedbacks** with the command

```
void BindTransformFeedback( enum target, uint id );
```

*target* must be `TRANSFORM_FEEDBACK` and *id* is the transform feedback object name. The resulting transform feedback object is a new state vector, comprising all the state and with the same initial values listed in table 23.48. Additionally, the new object is bound to the GL state vector and is used for subsequent transform feedback operations.

**BindTransformFeedback** can also be used to bind an existing transform feedback object to the GL state for subsequent use. If the bind is successful, no change is made to the state of the newly bound transform feedback object and any previous binding to *target* is broken.

While a transform feedback buffer is bound, GL operations on the target to which it is bound affect the bound transform feedback object, and queries of the target to which a transform feedback object is bound return state from the bound

object. When buffer objects are bound for transform feedback, they are attached to the currently bound transform feedback object. Buffer objects are used for transform feedback only if they are attached to the currently bound transform feedback object.

In the initial state, a default transform feedback object is bound and treated as a transform feedback object with a name of zero. That object is bound any time **BindTransformFeedback** is called with *id* of zero.

### Errors

An `INVALID_ENUM` error is generated if *target* is not `TRANSFORM_FEEDBACK`.

An `INVALID_OPERATION` error is generated if the transform feedback operation is active on the currently bound transform feedback object, and that operation is not paused (as described below).

An `INVALID_OPERATION` error is generated if *id* is not zero or a name returned from a previous call to **GenTransformFeedbacks**, or if such a name has since been deleted with **DeleteTransformFeedbacks**.

### 13.2.2 Transform Feedback Primitive Capture

Transform feedback for the currently bound transform feedback object is started (made *active*) and finished (made *inactive*) with the commands

```
void BeginTransformFeedback( enum primitiveMode );
```

and

```
void EndTransformFeedback( void );
```

respectively. *primitiveMode* must be of `TRIANGLES`, `LINES`, or `POINTS`, and specifies the output type of primitives that will be recorded into the buffer objects bound for transform feedback (see below). *primitiveMode* restricts the primitive types that may be rendered while transform feedback is active, as shown in table 13.1.

**EndTransformFeedback** first performs an implicit **ResumeTransformFeedback** (see below) if transform feedback is paused.

**BeginTransformFeedback** and **EndTransformFeedback** calls must be paired. Transform feedback is initially inactive.

Transform feedback mode captures the values of output variables written by the vertex shader (or, if active, geometry shader).

**Errors**

An `INVALID_ENUM` error is generated by **BeginTransformFeedback** if *primitiveMode* is not `TRIANGLES`, `LINES`, or `POINTS`.

An `INVALID_OPERATION` error is generated by **BeginTransformFeedback** if transform feedback is active for the current transform feedback object.

An `INVALID_OPERATION` error is generated by **EndTransformFeedback** if transform feedback is inactive.

Transform feedback operations for the currently bound transform feedback object may be paused and resumed by calling

```
void PauseTransformFeedback( void );
```

and

```
void ResumeTransformFeedback( void );
```

respectively. When transform feedback operations are paused, transform feedback is still considered active and changing most transform feedback state related to the object results in an error. However, a new transform feedback object may be bound while transform feedback is paused.

When transform feedback is active and not paused, all geometric primitives generated must be compatible with the value of *primitiveMode* passed to **BeginTransformFeedback**. An `INVALID_OPERATION` error is generated by any command that transfers vertices to the GL if *mode* is not one of the allowed modes in table 13.1. If a tessellation evaluation or geometry shader is active, the type of primitive emitted by that shader is used instead of the *mode* parameter passed to drawing commands for the purposes of this error check. If tessellation evaluation and geometry shaders are both active, the output primitive type of the geometry shader will be used for the purposes of this error. Any primitive type may be used while transform feedback is paused.

**Errors**

An `INVALID_OPERATION` error is generated by **PauseTransformFeedback** if the currently bound transform feedback object is not active or is paused.

An `INVALID_OPERATION` error is generated by **ResumeTransformFeedback** if the currently bound transform feedback object is not active or is not

Transform Feedback <i>primitiveMode</i>	Allowed render primitive <i>modes</i>
POINTS	POINTS
LINES	LINES, LINE_LOOP, LINE_STRIP
TRIANGLES	TRIANGLES, TRIANGLE_STRIP, TRIANGLE_FAN

Table 13.1: Legal combinations of the transform feedback primitive mode, as passed to **BeginTransformFeedback**, and the current primitive mode.

paused.

Regions of buffer objects are bound as the targets of transform feedback by calling one of the commands **BindBufferRange** or **BindBufferBase** (see section 6.1.1) with *target* set to `TRANSFORM_FEEDBACK_BUFFER`.

When an individual point, line, or triangle primitive reaches the transform feedback stage while transform feedback is active and not paused, the values of the specified output variables of the vertex are appended to the buffer objects bound to the transform feedback binding points. The attributes of the first vertex received after **BeginTransformFeedback** are written at the starting offsets of the bound buffer objects set by **BindBufferRange**, and subsequent vertex attributes are appended to the buffer object. When capturing line and triangle primitives, all attributes of the first vertex are written first, followed by attributes of the subsequent vertices. When writing output variables that are arrays, individual array elements are written in order. For multi-component output variables, elements of output arrays, or transformed vertex attributes, the individual components are written in order. The value for any attribute specified to be streamed to a buffer object but not actually written by a vertex or geometry shader is undefined. The results of appending an output variable to a transform feedback buffer are undefined if any component of that variable would be written at an offset not aligned to the size of the component.

When transform feedback is paused, no vertices are recorded. When transform feedback is resumed, subsequent vertices are appended to the bound buffer objects immediately following the last vertex written before transform feedback was paused.

Individual lines or triangles of a strip or fan primitive will be extracted and recorded separately. Incomplete primitives are not recorded.

Transform feedback can operate in either `INTERLEAVED_ATTRIBS` or `SEPARATE_ATTRIBS` mode.

In `INTERLEAVED_ATTRIBS` mode, the values of one or more output variables written by a vertex or geometry shader are written, interleaved, into the buffer ob-

jects bound to one or more transform feedback binding points. The list of outputs provided for capture in interleaved mode may include special separator values, which can be used to direct subsequent outputs to the next binding point. Each non-separator output is written to the binding point numbered  $n$ , where  $n$  is the number of separator values preceding it in the list. If more than one output variable is written to a buffer object, they will be recorded in the order specified by **TransformFeedbackVaryings** (see section 11.1.2.1).

In `SEPARATE_ATTRIBS` mode, the first output variable or transformed vertex attribute specified by **TransformFeedbackVaryings** is written to the first transform feedback binding point; subsequent output variables are written to the subsequent transform feedback binding points. The total number of variables that may be captured in separate mode is given by `MAX_TRANSFORM_FEEDBACK_SEPARATE_ATTRIBS`.

When using a geometry shader or program that writes vertices to multiple vertex streams, each vertex emitted may trigger a new primitive in the vertex stream to which it was emitted. If transform feedback is active, the outputs of the primitive are written to a transform feedback binding point if and only if the outputs directed at that binding point belong to the vertex stream in question. All outputs assigned to a given binding point are required to come from a single vertex stream.

If recording the vertices of a primitive to the buffer objects being used for transform feedback purposes would result in either exceeding the limits of any buffer object's size, or in exceeding the end position  $offset + size - 1$ , as set by **BindBufferRange**, then no vertices of that primitive are recorded in any buffer object, and the counter corresponding to the asynchronous query target `TRANSFORM_FEEDBACK_PRIMITIVES_WRITTEN` (see section 13.3) is not incremented. For the purposes of this test, `gl_SkipComponents` variables are counted as recording data to a buffer object.

Transform feedback binding points zero through *count* minus one must have buffer objects bound when **BeginTransformFeedback** is called, where *count* is the parameter passed to **TransformFeedbackVaryings** in separate mode, or one more than the number of `gl_NextBuffer` elements in the *varyings* parameter to **TransformFeedbackVaryings** in interleaved mode.

An `INVALID_OPERATION` error is generated by **BeginTransformFeedback** if any of these binding points does not have a buffer object bound.

An `INVALID_OPERATION` error is generated by **BeginTransformFeedback** if no binding points would be used, either because no program object is active or because the active program object has specified no output variables to record.

When **BeginTransformFeedback** is called with an active program object containing a vertex or geometry shader, the set of output variables captured during transform feedback is taken from the active program object and may not be changed

while transform feedback is active. That program object must be active until the **EndTransformFeedback** is called, except while the transform feedback object is paused.

An `INVALID_OPERATION` error is generated :

- by **UseProgram** if the current transform feedback object is active and not paused;
- by **UseProgramStages** if the program pipeline object it refers to is current and the current transform feedback object is active and not paused;
- by **BindProgramPipeline** if the current transform feedback object is active and not paused;
- by **LinkProgram** or **ProgramBinary** if *program* is the name of a program being used by one or more transform feedback objects, even if the objects are not currently bound or are paused;
- by **ResumeTransformFeedback** if the program object being used by the current transform feedback object is not active, or has been re-linked since transform feedback became active for the current transform feedback object.
- by **ResumeTransformFeedback** if the program pipeline object being used by the current transform feedback object is not bound, if any of its shader stage bindings has changed, or if a single program object is active and overriding it; and
- by **BindBufferRange** or **BindBufferBase** if *target* is `TRANSFORM_FEEDBACK_BUFFER` and transform feedback is currently active.

Buffers should not be bound or in use for both transform feedback and other purposes in the GL. Specifically, if a buffer object is simultaneously bound to a transform feedback buffer binding point and elsewhere in the GL, any writes to or reads from the buffer generate undefined values. Examples of such bindings include **ReadPixels** to a pixel buffer object binding point and client access to a buffer mapped with **MapBuffer**.

However, if a buffer object is written and read sequentially by transform feedback and other mechanisms, it is the responsibility of the GL to ensure that data are accessed consistently, even if the implementation performs the operations in a pipelined manner. For example, **MapBuffer** may need to block pending the completion of a previous transform feedback operation.

### 13.2.3 Transform Feedback Draw Operations

When transform feedback is active, the values of output variables or transformed vertex attributes are captured into the buffer objects attached to the current transform feedback object. After transform feedback is complete, subsequent rendering operations may use the contents of these buffer objects (see section 6). The number of vertices captured from each vertex stream during transform feedback is stored in the corresponding transform feedback object and may be used in conjunction with the commands

```
void DrawTransformFeedback( enum mode, uint id );  
void DrawTransformFeedbackInstanced( enum mode,  
    uint id, sizei instancecount );  
void DrawTransformFeedbackStream( enum mode, uint id,  
    uint stream );  
void DrawTransformFeedbackStreamInstanced( enum mode,  
    uint id, uint stream, sizei instancecount );
```

to replay the captured vertices.

**DrawTransformFeedbackStreamInstanced** is equivalent to calling **DrawArraysInstanced** with *mode* as specified, *first* set to zero, *count* set to the number of vertices captured from the vertex stream numbered *stream* the last time transform feedback was active on the transform feedback object named *id*, and *instancecount* as specified.

Calling **DrawTransformFeedbackInstanced** is equivalent to calling **DrawTransformFeedbackStreamInstanced** with *stream* set to zero.

Calling **DrawTransformFeedbackStream** is equivalent to calling **DrawTransformFeedbackStreamInstanced** with *instancecount* set to one.

Finally, calling **DrawTransformFeedback** is equivalent to calling **DrawTransformFeedbackStreamInstanced** with *stream* set to zero and *instancecount* set to one.

Note that the vertex count is from the number of vertices recorded to the selected vertex stream during the transform feedback operation. If no outputs belonging to the selected vertex stream are recorded, the corresponding vertex count will be zero even if complete primitives were emitted to the selected stream.

No error is generated if the transform feedback object named by *id* is active; the vertex count used for the rendering operation is set by the previous **EndTransformFeedback** command.



**Errors**

An `INVALID_VALUE` error is generated if *stream* is greater than or equal to the value of `MAX_VERTEX_STREAMS`.

An `INVALID_VALUE` error is generated if *id* is not the name of a transform feedback object.

An `INVALID_VALUE` error is generated if *instancecount* is negative.

An `INVALID_OPERATION` error is generated if **EndTransformFeedback** has never been called while the object named by *id* was bound.

### 13.3 Primitive Queries

Primitive queries use query objects to track the number of primitives in each vertex stream that are generated by the GL and the number of primitives in each vertex stream that are written to buffer objects in transform feedback mode.

When **BeginQueryIndexed** is called with a *target* of `PRIMITIVES_GENERATED`, the primitives generated count maintained by the GL for the vertex stream *index* is set to zero. There is a separate query and counter for each vertex stream. The number of vertex streams is given by the value of the implementation-dependent constant `MAX_VERTEX_STREAMS`. When a generated primitive query for a vertex stream is active, the primitives-generated count is incremented every time a primitive emitted to that stream reaches the transform feedback stage (see section 13.2), whether or not transform feedback is active. This counter counts the number of primitives emitted by a geometry shader, if active, possibly further tessellated into separate primitives during the transform feedback stage, if active.

When **BeginQueryIndexed** is called with a *target* of `TRANSFORM_FEEDBACK_PRIMITIVES_WRITTEN`, the transform feedback primitives written count maintained by the GL for vertex stream *index* is set to zero. There is a separate query and counter for each vertex stream. When a transform feedback primitives written query for a vertex stream is active, the counter for that vertex stream is incremented every time the vertices of a primitive written to that stream are recorded into one or more buffer objects. If transform feedback is not active or if a primitive to be recorded does not fit in a buffer object, the counter is not incremented.

These two types of queries can be used together to determine if all primitives in a given vertex stream have been written to the bound feedback buffers; if both queries are run simultaneously and the query results are equal, all primitives have been written to the buffer(s). If the number of primitives written is less than the number of primitives generated, one or more buffers overflowed.

Primitive type of polygon $i$	First vertex convention	Last vertex convention
point	$i$	$i$
independent line	$2i - 1$	$2i$
line loop	$i$	$i + 1$ , if $i < n$ $1$ , if $i = n$
line strip	$i$	$i + 1$
independent triangle	$3i - 2$	$3i$
triangle strip	$i$	$i + 2$
triangle fan	$i + 1$	$i + 2$
line adjacency	$4i - 2$	$4i - 1$
line strip adjacency	$i + 1$	$i + 2$
triangle adjacency	$6i - 5$	$6i - 1$
triangle strip adjacency	$2i - 1$	$2i + 3$

Table 13.2: Provoking vertex selection. The output values used for flatshading the  $i$ th primitive generated by drawing commands with the indicated primitive type are derived from the corresponding values of the vertex whose index is shown in the table. Vertices are numbered 1 through  $n$ , where  $n$  is the number of vertices drawn.

## 13.4 Flatshading

*Flatshading* a vertex shader output means to assign all vertices of the primitive the same value for that output.

The output values assigned are those of the *provoking vertex* of the primitive. The provoking vertex is controlled with the command

```
void ProvokingVertex( enum provokeMode );
```

*provokeMode* must be either `FIRST_VERTEX_CONVENTION` or `LAST_VERTEX_CONVENTION`, and controls selection of the vertex whose values are assigned to flatshaded colors and outputs, as shown in table 13.2

If a vertex or geometry shader is active, user-defined output variables may be flatshaded by using the `flat` qualifier when declaring the output, as described in section 4.5(“Interpolation Qualifiers”) of the OpenGL Shading Language Specification .

The state required for flatshading is one bit for the provoking vertex mode, and one implementation-dependent bit for the provoking vertex behavior of quad

primitives. The initial value of the provoking vertex mode is `LAST_VERTEX_CONVENTION`.

## 13.5 Primitive Clipping

Primitives are clipped to the *clip volume*. In clip coordinates, the *view volume* is defined by

$$\begin{aligned} -w_c &\leq x_c \leq w_c \\ -w_c &\leq y_c \leq w_c \\ -w_c &\leq z_c \leq w_c. \end{aligned}$$

This view volume may be further restricted by as many as  $n$  client-defined half-spaces. ( $n$  is an implementation-dependent maximum that must be at least 8.) The clip volume is the intersection of all such half-spaces with the view volume (if no client-defined half-spaces are enabled, the clip volume is the view volume).

A vertex shader may write a single clip distance for each supported half-space to elements of the `gl_ClipDistance[]` array. Half-space  $n$  is then given by the set of points satisfying the inequality

$$c_n(P) \geq 0,$$

where  $c_n(P)$  is the value of clip distance  $n$  at point  $P$ . For point primitives,  $c_n(P)$  is simply the clip distance for the vertex in question. For line and triangle primitives, per-vertex clip distances are interpolated using a weighted mean, with weights derived according to the algorithms described in sections 14.5 and 14.6.

Client-defined half-spaces are enabled with the generic **Enable** command and disabled with the **Disable** command. The value of the argument to either command is `CLIP_DISTANCEi`, where  $i$  is an integer between 0 and  $n - 1$ ; specifying a value of  $i$  enables or disables the plane equation with index  $i$ . The constants obey `CLIP_DISTANCEi = CLIP_DISTANCE0 + i`.

Depth clamping is enabled with the generic **Enable** command and disabled with the **Disable** command. The value of the argument to either command is `DEPTH_CLAMP`. If depth clamping is enabled, the

$$-w_c \leq z_c \leq w_c$$

plane equation is ignored by view volume clipping (effectively, there is no near or far plane clipping).

If the primitive under consideration is a point, then clipping passes it unchanged if it lies within the clip volume; otherwise, it is discarded.

If the primitive is a line segment, then clipping does nothing to it if it lies entirely within the clip volume, and discards it if it lies entirely outside the volume.

If part of the line segment lies in the volume and part lies outside, then the line segment is clipped and new vertex coordinates are computed for one or both vertices. A clipped line segment endpoint lies on both the original line segment and the boundary of the clip volume.

This clipping produces a value,  $0 \leq t \leq 1$ , for each clipped vertex. If the coordinates of a clipped vertex are  $\mathbf{P}$  and the original vertices' coordinates are  $\mathbf{P}_1$  and  $\mathbf{P}_2$ , then  $t$  is given by

$$\mathbf{P} = t\mathbf{P}_1 + (1 - t)\mathbf{P}_2.$$

The value of  $t$  is used to clip vertex shader outputs as described in section 13.5.1.

If the primitive is a polygon, then it is passed if every one of its edges lies entirely inside the clip volume and either clipped or discarded otherwise. Polygon clipping may cause polygon edges to be clipped, but because polygon connectivity must be maintained, these clipped edges are connected by new edges that lie along the clip volume's boundary. Thus, clipping may require the introduction of new vertices into a polygon.

If it happens that a polygon intersects an edge of the clip volume's boundary, then the clipped polygon must include a point on this boundary edge.

Primitives rendered with user-defined half-spaces must satisfy a complementarity criterion. Suppose a series of primitives is drawn where each vertex  $i$  has a single specified clip distance  $d_i$  (or a number of similarly specified clip distances, if multiple half-spaces are enabled). Next, suppose that the same series of primitives are drawn again with each such clip distance replaced by  $-d_i$  (and the GL is otherwise in the same state). In this case, primitives must not be missing any pixels, nor may any pixels be drawn twice in regions where those primitives are cut by the clip planes.

The state required for clipping is at least 8 bits indicating which of the client-defined half-spaces are enabled. In the initial state, all half-spaces are disabled.

### 13.5.1 Clipping Shader Outputs

Next, vertex shader outputs are clipped. The output values associated with a vertex that lies within the clip volume are unaffected by clipping. If a primitive is clipped, however, the output values assigned to vertices produced by clipping are clipped.

Let the output values assigned to the two vertices  $\mathbf{P}_1$  and  $\mathbf{P}_2$  of an unclipped edge be  $\mathbf{c}_1$  and  $\mathbf{c}_2$ . The value of  $t$  (section 13.5) for a clipped point  $\mathbf{P}$  is used to

obtain the output value associated with  $\mathbf{P}$  as <sup>1</sup>

$$\mathbf{c} = t\mathbf{c}_1 + (1 - t)\mathbf{c}_2.$$

(Multiplying an output value by a scalar means multiplying each of  $x$ ,  $y$ ,  $z$ , and  $w$  by the scalar.)

Polygon clipping may create a clipped vertex along an edge of the clip volume's boundary. This situation is handled by noting that polygon clipping proceeds by clipping against one half-space at a time. Output value clipping is done in the same way, so that clipped points always occur at the intersection of polygon edges (possibly already clipped) with the clip volume's boundary.

For vertex shader outputs specified to be interpolated without perspective correction (using the `noperspective` qualifier), the value of  $t$  used to obtain the output value associated with  $\mathbf{P}$  will be adjusted to produce results that vary linearly in screen space.

Outputs of integer or unsigned integer type must always be declared with the `flat` qualifier. Since such outputs are constant over the primitive being rasterized (see sections 14.5.1 and 14.6.1), no interpolation is performed.

### 13.5.2 Clip Plane Queries

This subsection is only defined in the compatibility profile.

## 13.6 Coordinate Transformations

*Clip coordinates* for a vertex result from shader execution, which yields a vertex coordinate `gl_Position`.

Perspective division on clip coordinates yields *normalized device coordinates*, followed by a *viewport* transformation (see section 13.6.1) to convert these coordinates into *window coordinates*.

If a vertex in clip coordinates is given by  $\begin{pmatrix} x_c \\ y_c \\ z_c \\ w_c \end{pmatrix}$

then the vertex's normalized device coordinates are

$$\begin{pmatrix} x_d \\ y_d \\ z_d \end{pmatrix} = \begin{pmatrix} \frac{x_c}{w_c} \\ \frac{y_c}{w_c} \\ \frac{z_c}{w_c} \end{pmatrix}.$$

<sup>1</sup> Since this computation is performed in clip space before division by  $w_c$ , clipped output values are perspective-correct.

### 13.6.1 Controlling the Viewport

The viewport transformation is determined by the selected viewport's width and height in pixels,  $p_x$  and  $p_y$ , respectively, and its center  $(o_x, o_y)$  (also in pixels).

The vertex's window coordinates,  $\begin{pmatrix} x_w \\ y_w \\ z_w \end{pmatrix}$ , are given by

$$\begin{pmatrix} x_w \\ y_w \\ z_w \end{pmatrix} = \begin{pmatrix} \frac{p_x}{2}x_d + o_x \\ \frac{p_y}{2}y_d + o_y \\ \frac{f-n}{2}z_d + \frac{n+f}{2} \end{pmatrix}.$$

Multiple viewports are available and are numbered zero through the value of `MAX_VIEWPORTS` minus one. If a geometry shader is active and writes to `gl_ViewportsIndex`, the viewport transformation uses the viewport corresponding to the value assigned to `gl_ViewportsIndex` taken from an implementation-dependent primitive vertex. If the value of the viewport index is outside the range zero to the value of `MAX_VIEWPORTS` minus one, the results of the viewport transformation are undefined. If no geometry shader is active, or if the active geometry shader does not write to `gl_ViewportsIndex`, the viewport numbered zero is used by the viewport transformation.

A single vertex may be used in more than one individual primitive, in primitives such as `TRIANGLE_STRIP`. In this case, the viewport transformation is applied separately for each primitive.

The factor and offset applied to  $z_d$  for each viewport encoded by  $n$  and  $f$  are set using

```
void DepthRangeArrayv(uint first, sizei count, const
    double *v);
void DepthRangeIndexed(uint index, double n,
    double f);
void DepthRange(double n, double f);
void DepthRangef(float n, float f);
```

**DepthRangeArrayv** is used to specify the depth range for multiple viewports simultaneously. *first* specifies the index of the first viewport to modify and *count* specifies the number of viewports. Viewports whose indices lie outside the range  $[first, first + count)$  are not modified. The *v* parameter contains the address of an array of **double** types specifying near (*n*) and far (*f*) for each viewport in that order. **Values in *v* are each clamped to the range  $[0, 1]$  when specified.**

**Errors**

An `INVALID_VALUE` error is generated if  $(first + count)$  is greater than the value of `MAX_VIEWPORTS`.

An `INVALID_VALUE` error is generated if  $count$  is negative.

**DepthRangeIndexed** specifies the depth range for a single viewport and is equivalent (assuming no errors are generated) to:

```
double v[] = { n, f };
DepthRangeArrayv(index, 1, v);
```

**DepthRange** sets the depth range for all viewports to the same values and is equivalent (assuming no errors are generated) to:

```
for (uint i = 0; i < MAX_VIEWPORTS; i++)
    DepthRangeIndexed(i, n, f);
```

$z_w$  may be represented using either a fixed-point or floating-point representation. However, a floating-point representation must be used if the draw framebuffer has a floating-point depth buffer. If an  $m$ -bit fixed-point representation is used, we assume that it represents each value  $\frac{k}{2^m-1}$ , where  $k \in \{0, 1, \dots, 2^m-1\}$ , as  $k$  (e.g. 1.0 is represented in binary as a string of all ones). ~~If a fixed-point representation is used, the parameters  $n$  and  $f$  are clamped to the range  $[0, 1]$  when computing  $z_w$ .~~

Viewport transformation parameters are specified using

```
void ViewportArrayv(uint first, sizei count, const
    float *v);
void ViewportIndexedf(uint index, float x, float y,
    float w, float h);
void ViewportIndexedfv(uint index, const float *v);
void Viewport(int x, int y, sizei w, sizei h);
```

**ViewportArrayv** specifies parameters for multiple viewports simultaneously.  $first$  specifies the index of the first viewport to modify and  $count$  specifies the number of viewports. Viewports whose indices lie outside the range  $[first, first + count)$  are not modified.  $v$  contains the address of an array of floating-point values specifying the left ( $x$ ), bottom ( $y$ ), width ( $w$ ) and height ( $h$ ) of each viewport, in that order.  $x$  and  $y$  give the location of the viewport's lower left corner and  $w$  and  $h$  give the viewport's width and height, respectively.

**Errors**

An `INVALID_VALUE` error is generated if  $first + count$  is greater than the value of `MAX_VIEWPORTS`.

An `INVALID_VALUE` error is generated if  $count$  is negative.

**ViewportIndexedf** and **ViewportIndexedfv** specify parameters for a single viewport and are equivalent (assuming no errors are generated) to:

```
float v[4] = { x, y, w, h };
ViewportArrayv(index, 1, v);
```

and

```
ViewportArrayv(index, 1, v);
```

respectively.

**Viewport** sets the parameters for all viewports to the same values and is equivalent (assuming no errors are generated) to:

```
for (uint i = 0; i < MAX_VIEWPORTS; i++)
    ViewportIndexedf(i, 1, (float)x, (float)y, (float)w, (float)h);
```

The viewport parameters shown in the above equations are found from these values as

$$\begin{aligned}o_x &= x + \frac{w}{2} \\o_y &= y + \frac{h}{2} \\p_x &= w \\p_y &= h.\end{aligned}$$

The location of the viewport's bottom-left corner, given by  $(x, y)$ , are clamped to be within the implementation-dependent viewport bounds range. The viewport bounds range  $[min, max]$  tuple may be determined by calling **GetFloatv** with the symbolic constant `VIEWPORT_BOUNDS_RANGE` (see section 22).

Viewport width and height are clamped to implementation-dependent maximums when specified. The maximum width and height may be found by calling **GetFloatv** with the symbolic constant `MAX_VIEWPORT_DIMS`. The maximum viewport dimensions must be greater than or equal to the larger of the visible dimensions of the display being rendered to (if a display exists), and the largest renderbuffer image which can be successfully created and attached to a framebuffer object (see chapter 9).



**Errors**

An `INVALID_VALUE` error is generated if either  $w$  or  $h$  is negative.

The state required to implement the viewport transformation is four integers and two clamped floating-point values for each viewport. In the initial state,  $w$  and  $h$  for each viewport are set to the width and height, respectively, of the window into which the GL is to do its rendering. If the default framebuffer is bound but no default framebuffer is associated with the GL context (see chapter 9), then  $w$  and  $h$  are initially set to zero.  $o_x$ ,  $o_y$ ,  $n$ , and  $f$  are set to  $\frac{w}{2}$ ,  $\frac{h}{2}$ , 0.0, and 1.0, respectively.

The precision with which the GL interprets the floating-point viewport bounds is implementation-dependent and may be determined by querying the implementation-defined constant `VIEWPORT_SUBPIXEL_BITS`.

## 13.7 Final Color Processing

[This section is only defined in the compatibility profile.](#)

## Chapter 14

# Fixed-Function Primitive Assembly and Rasterization

Rasterization is the process by which a primitive is converted to a two-dimensional image. Each point of this image contains such information as color and depth. Thus, rasterizing a primitive consists of two parts. The first is to determine which squares of an integer grid in window coordinates are occupied by the primitive. The second is assigning a depth value and one or more color values to each such square. The results of this process are passed on to the next stage of the GL (per-fragment operations), which uses the information to update the appropriate locations in the framebuffer. Figure 14.1 diagrams the rasterization process. The color values assigned to a fragment are determined by a fragment shader as defined in section 15. The final depth value is initially determined by the rasterization operations and may be modified or replaced by a fragment shader. The results from rasterizing a point, line, or polygon are routed through a fragment shader.

A grid square along with its  $z$  (depth) and shader output parameters is called a *fragment*; the parameters are collectively dubbed the fragment's *associated data*. A fragment is located by its lower left corner, which lies on integer grid coordinates. Rasterization operations also refer to a fragment's *center*, which is offset by  $(\frac{1}{2}, \frac{1}{2})$  from its lower left corner (and so lies on half-integer coordinates).

Grid squares need not actually be square in the GL. Rasterization rules are not affected by the actual aspect ratio of the grid squares. Display of non-square grids, however, will cause rasterized points and line segments to appear fatter in one direction than the other. We assume that fragments are square, since it simplifies antialiasing and texturing.

Several factors affect rasterization. Primitives may be discarded before rasterization. Points may be given differing diameters and line segments differing

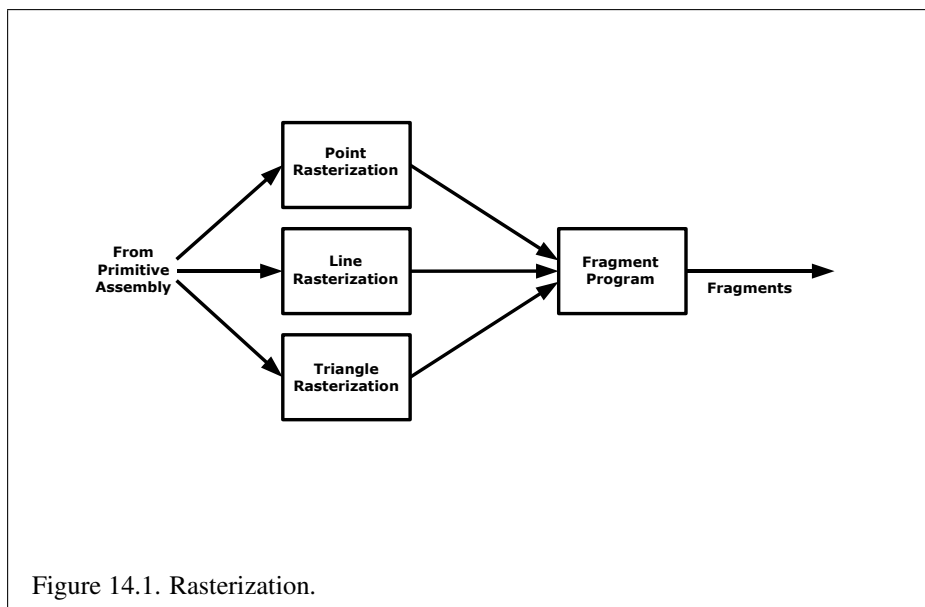


Figure 14.1. Rasterization.

widths. A point, line segment, or polygon may be antialiased.

Rasterization only produces fragments corresponding to pixels in the framebuffer. Fragments which would be produced by application of any of the primitive rasterization rules described below but which lie outside the framebuffer are not produced, nor are they processed by any later stage of the GL, including any of the early per-fragment tests described in section 14.9.

## 14.1 Discarding Primitives Before Rasterization

Primitives sent to vertex stream zero (see section 13.2) are processed further; primitives emitted to any other stream are discarded. When geometry shaders are disabled, all vertices are considered to be emitted to stream zero.

Primitives can be optionally discarded before rasterization by calling **Enable** and **Disable** with `RASTERIZER_DISCARD`. When enabled, primitives are discarded immediately before the rasterization stage, but after the optional transform feedback stage (see section 13.2). When disabled, primitives are passed through to the rasterization stage to be processed normally. When enabled, `RASTERIZER_DISCARD` also causes the **Clear** and **ClearBuffer\*** commands to be ignored.

The state required to control primitive discard is a bit indicating whether discard is enabled or disabled. The initial value of primitive discard is `FALSE`.

## 14.2 Invariance

Consider a primitive  $p'$  obtained by translating a primitive  $p$  through an offset  $(x, y)$  in window coordinates, where  $x$  and  $y$  are integers. As long as neither  $p'$  nor  $p$  is clipped, it must be the case that each fragment  $f'$  produced from  $p'$  is identical to a corresponding fragment  $f$  from  $p$  except that the center of  $f'$  is offset by  $(x, y)$  from the center of  $f$ .

## 14.3 Antialiasing

The R, G, and B values of the rasterized fragment are left unaffected, but the A value is multiplied by a floating-point value in the range  $[0, 1]$  that describes a fragment's screen pixel coverage. The per-fragment stage of the GL can be set up to use the A value to blend the incoming fragment with the corresponding pixel already present in the framebuffer.

The details of how antialiased fragment coverage values are computed are difficult to specify in general. The reason is that high-quality antialiasing may take into account perceptual issues as well as characteristics of the monitor on which the contents of the framebuffer are displayed. Such details cannot be addressed within the scope of this document. Further, the coverage value computed for a fragment of some primitive may depend on the primitive's relationship to a number of grid squares neighboring the one corresponding to the fragment, and not just on the fragment's grid square. Another consideration is that accurate calculation of coverage values may be computationally expensive; consequently we allow a given GL implementation to approximate true coverage values by using a fast but not entirely accurate coverage computation.

In light of these considerations, we chose to specify the behavior of exact antialiasing in the prototypical case that each displayed pixel is a perfect square of uniform intensity. The square is called a *fragment square* and has lower left corner  $(x, y)$  and upper right corner  $(x + 1, y + 1)$ . We recognize that this simple box filter may not produce the most favorable antialiasing results, but it provides a simple, well-defined model.

A GL implementation may use other methods to perform antialiasing, subject to the following conditions:

1. If  $f_1$  and  $f_2$  are two fragments, and the portion of  $f_1$  covered by some primitive is a subset of the corresponding portion of  $f_2$  covered by the primitive, then the coverage computed for  $f_1$  must be less than or equal to that computed for  $f_2$ .

2. The coverage computation for a fragment  $f$  must be local: it may depend only on  $f$ 's relationship to the boundary of the primitive being rasterized. It may not depend on  $f$ 's  $x$  and  $y$  coordinates.

Another property that is desirable, but not required, is:

3. The sum of the coverage values for all fragments produced by rasterizing a particular primitive must be constant, independent of any rigid motions in window coordinates, as long as none of those fragments lies along window edges.

In some implementations, varying degrees of antialiasing quality may be obtained by providing GL hints (section 21.5), allowing a user to make an image quality versus speed tradeoff.

### 14.3.1 Multisampling

Multisampling is a mechanism to antialias all GL primitives: points, lines, and polygons. The technique is to sample all primitives multiple times at each pixel. The color sample values are resolved to a single, displayable color each time a pixel is updated, so the antialiasing appears to be automatic at the application level. Because each sample includes color, depth, and stencil information, the color (including texture operation), depth, and stencil functions perform equivalently to the single-sample mode.

An additional buffer, called the multisample buffer, is added to the framebuffer. Pixel sample values, including color, depth, and stencil values, are stored in this buffer. Samples contain separate color values for each fragment color. When the framebuffer includes a multisample buffer, it does not include depth or stencil buffers, even if the multisample buffer does not store depth or stencil values. Color buffers do coexist with the multisample buffer, however.

Multisample antialiasing is most valuable for rendering polygons, because it requires no sorting for hidden surface elimination, and it correctly handles adjacent polygons, object silhouettes, and even intersecting polygons. If only lines are being rendered, the “smooth” antialiasing mechanism provided by the base GL may result in a higher quality image. This mechanism is designed to allow multi-sample and smooth antialiasing techniques to be alternated during the rendering of a single scene.

If the value of `SAMPLE_BUFFERS` is one, the rasterization of all primitives is changed, and is referred to as multisample rasterization. Otherwise, primitive rasterization is referred to as single-sample rasterization. The value of `SAMPLE_BUFFERS` is queried by calling `GetIntegerv` with `pname` set to `SAMPLE_BUFFERS`.

During multisample rendering the contents of a pixel fragment are changed in two ways. First, each fragment includes a coverage value with `SAMPLES` bits. The value of `SAMPLES` is an implementation-dependent constant, and is queried by calling **GetIntegerv** with *pname* set to `SAMPLES`.

The location of a given sample is queried with the command

```
void GetMultisamplefv( enum pname, uint index,  
                        float *val );
```

*pname* must be `SAMPLE_POSITION`, and *index* corresponds to the sample for which the location should be returned. The sample location is returned as two floating-point values in *val[0]* and *val[1]*, each between 0 and 1, corresponding to the *x* and *y* locations respectively in GL pixel space of that sample. (0.5, 0.5) thus corresponds to the pixel center. If the multisample mode does not have fixed sample locations, the returned values may only reflect the locations of samples within some pixels.

#### Errors

An `INVALID_VALUE` error is generated if *index* is greater than or equal to the value of `SAMPLES`.

Second, each fragment includes `SAMPLES` depth values and sets of associated data, instead of the single depth value and set of associated data that is maintained in single-sample rendering mode. An implementation may choose to assign the same associated data to more than one sample. The location for evaluating such associated data can be anywhere within the pixel including the fragment center or any of the sample locations. The different associated data values need not all be evaluated at the same location. Each pixel fragment thus consists of integer *x* and *y* grid coordinates, `SAMPLES` depth values and sets of associated data, and a coverage value with a maximum of `SAMPLES` bits.

Multisample rasterization is enabled or disabled by calling **Enable** or **Disable** with the symbolic constant `MULTISAMPLE`.

If `MULTISAMPLE` is disabled, multisample rasterization of all primitives is equivalent to single-sample (fragment-center) rasterization, except that the fragment coverage value is set to full coverage. The color and depth values and the sets of texture coordinates may all be set to the values that would have been assigned by single-sample rasterization, or they may be assigned as described below for multisample rasterization.

If `MULTISAMPLE` is enabled, multisample rasterization of all primitives differs substantially from single-sample rasterization. It is understood that each pixel in

the framebuffer has `SAMPLES` locations associated with it. These locations are exact positions, rather than regions or areas, and each is referred to as a sample point. The sample points associated with a pixel may be located inside or outside of the unit square that is considered to bound the pixel. Furthermore, the relative locations of sample points may be identical for each pixel in the framebuffer, or they may differ.

If `MULTISAMPLE` is enabled and the current program object includes a fragment shader with one or more input variables qualified with `sample in`, the data associated with those variables will be assigned independently. The values for each sample must be evaluated at the location of the sample. The data associated with any other variables not qualified with `sample in` need not be evaluated independently for each sample.

If the sample locations differ per pixel, they should be aligned to window, not screen, boundaries. Otherwise rendering results will be window-position specific. The invariance requirement described in section 14.2 is relaxed for all multisample rasterization, because the sample locations may be a function of pixel location.

#### 14.3.1.1 Sample Shading

Sample shading can be used to specify a minimum number of unique samples to process for each fragment. Sample shading is controlled by calling **Enable** or **Disable** with the symbolic constant `SAMPLE_SHADING`.

If `MULTISAMPLE` or `SAMPLE_SHADING` is disabled, sample shading has no effect. Otherwise, an implementation must provide a minimum of

$$\max(\lceil mss \times samples \rceil, 1)$$

unique color values for each fragment, where *mss* is the value of `MIN_SAMPLE_SHADING_VALUE` and *samples* is the number of samples (the value of `SAMPLES`). These are associated with the samples in an implementation-dependent manner. The value of `MIN_SAMPLE_SHADING_VALUE` is specified by calling

```
void MinSampleShading( float value );
```

with *value* set to the desired minimum sample shading fraction. *value* is clamped to  $[0, 1]$  when specified. The sample shading fraction may be queried by calling **GetFloatv** with the symbolic constant `MIN_SAMPLE_SHADING_VALUE`.

When the sample shading fraction is 1.0, a separate set of colors and other associated data are evaluated for each sample, and each set of values is evaluated at the sample location.

## 14.4 Points

A point is drawn by generating a set of fragments in the shape of a square or circle centered around the vertex of the point. Each vertex has an associated point size that controls the size of that square or circle.

If program point size mode is enabled, the derived point size is taken from the (potentially clipped) shader built-in `gl_PointSize` written by:

- the geometry shader, if active;
- the tessellation evaluation shader, if active and no geometry shader is active;
- the tessellation control shader, if active and no geometry or tessellation evaluation shader is active; or
- the vertex shader, otherwise

and clamped to the implementation-dependent point size range. If the value written to `gl_PointSize` is less than or equal to zero, or if no value was written to `gl_PointSize`, results are undefined. If program point size mode is disabled, the derived point size is specified with the command

```
void PointSize( float size );
```

*size* specifies the requested size of a point. The default value is 1.0.

### Errors

An `INVALID_VALUE` error is generated if *size* is less than or equal to zero.

Program point size mode is enabled and disabled by calling **Enable** or **Disable** with the symbolic value `PROGRAM_POINT_SIZE`.

If multisampling is enabled, an implementation may optionally fade the point alpha (see section 17.2) instead of allowing the point width to go below a given threshold. In this case, the width of the rasterized point is

$$width = \begin{cases} derived\_size & derived\_size \geq threshold \\ threshold & otherwise \end{cases} \quad (14.1)$$

and the fade factor is computed as follows:

$$fade = \begin{cases} 1 & derived\_size \geq threshold \\ \left(\frac{derived\_size}{threshold}\right)^2 & otherwise \end{cases} \quad (14.2)$$

The point fade *threshold*, is specified with



```
void PointParameter{if}( enum pname, T param );
void PointParameter{if}v( enum pname, const T *params );
```

If *pname* is POINT\_FADE\_THRESHOLD\_SIZE, then *param* specifies, or *params* points to the point fade *threshold*.

Data conversions are performed as specified in section 2.2.1.

The point sprite texture coordinate origin is set with the **PointParameter\*** commands where *pname* is POINT\_SPRITE\_COORD\_ORIGIN and *param* is LOWER\_LEFT or UPPER\_LEFT. The default value is UPPER\_LEFT.

### Errors

An INVALID\_ENUM error is generated if *pname* is not POINT\_FADE\_THRESHOLD\_SIZE or POINT\_SPRITE\_COORD\_ORIGIN.

An INVALID\_VALUE error is generated if negative values are specified for POINT\_FADE\_THRESHOLD\_SIZE.

#### 14.4.1 Basic Point Rasterization

Point rasterization produces a fragment for each framebuffer pixel whose center lies inside a square centered at the point's  $(x_w, y_w)$ , with side length equal to the current point size.

All fragments produced in rasterizing a point sprite are assigned the same associated data, which are those of the vertex corresponding to the point. However, the fragment shader built-in `gl_PointCoord` contains point sprite texture coordinates. The *s* point sprite texture coordinate varies from 0 to 1 across the point horizontally left-to-right. If POINT\_SPRITE\_COORD\_ORIGIN is LOWER\_LEFT, the *t* coordinate varies from 0 to 1 vertically bottom-to-top. Otherwise if the point sprite texture coordinate origin is UPPER\_LEFT, the *t* coordinate varies from 0 to 1 vertically top-to-bottom. The following formula is used to evaluate the *s* and *t* point sprite texture coordinates:

$$s = \frac{1}{2} + \frac{(x_f + \frac{1}{2} - x_w)}{size} \quad (14.3)$$

$$t = \begin{cases} \frac{1}{2} + \frac{(y_f + \frac{1}{2} - y_w)}{size}, & \text{POINT\_SPRITE\_COORD\_ORIGIN} = \text{LOWER\_LEFT} \\ \frac{1}{2} - \frac{(y_f + \frac{1}{2} - y_w)}{size}, & \text{POINT\_SPRITE\_COORD\_ORIGIN} = \text{UPPER\_LEFT} \end{cases} \quad (14.4)$$

where *size* is the point's size,  $x_f$  and  $y_f$  are the (integral) window coordinates of the fragment, and  $x_w$  and  $y_w$  are the exact, unrounded window coordinates of the vertex for the point.

Not all point widths need be supported, but the width 1.0 must be provided. The range of supported widths and the width of evenly-spaced gradations within that range are implementation-dependent. The range and gradations may be obtained using the query mechanism described in chapter 22. If, for instance, the width range is from 0.1 to 2.0 and the gradation width is 0.1, then the widths 0.1, 0.2, . . . , 1.9, 2.0 are supported. Additional point widths may also be supported. There is no requirement that these widths must be equally spaced. If an unsupported width is requested, the nearest supported width is used instead.

#### 14.4.2 Point Rasterization State

The state required to control point rasterization consists of the floating-point point width, a bit indicating whether or not vertex program point size mode is enabled, a bit for the point sprite texture coordinate origin, and a floating-point value specifying the point fade threshold size.

#### 14.4.3 Point Multisample Rasterization

If `MULTISAMPLE` is enabled, and the value of `SAMPLE_BUFFERS` is one, then points are rasterized using the following algorithm. Point rasterization produces a fragment for each framebuffer pixel with one or more sample points that intersect a region centered at the point's  $(x_w, y_w)$ . This region is a square with side equal to the current point width. Coverage bits that correspond to sample points that intersect the region are 1, other coverage bits are 0. All data associated with each sample for the fragment are the data associated with the point being rasterized.

The set of point sizes supported is equivalent to those for point sprites without multisample .

### 14.5 Line Segments

A line segment results from a line strip, a line loop, or a series of separate line segments. Line segment rasterization is controlled by several variables. Line width, which may be set by calling

```
void LineWidth( float width );
```

with an appropriate positive floating-point width, controls the width of rasterized line segments. The default width is 1.0. Antialiasing is controlled with **Enable** and **Disable** using the symbolic constant `LINE_SMOOTH`.

### Errors

An `INVALID_VALUE` error is generated if *width* is less than or equal to zero.

#### 14.5.1 Basic Line Segment Rasterization

Line segment rasterization begins by characterizing the segment as either *x-major* or *y-major*. *x-major* line segments have slope in the closed interval  $[-1, 1]$ ; all other line segments are *y-major* (slope is determined by the segment's endpoints). We shall specify rasterization only for *x-major* segments except in cases where the modifications for *y-major* segments are not self-evident.

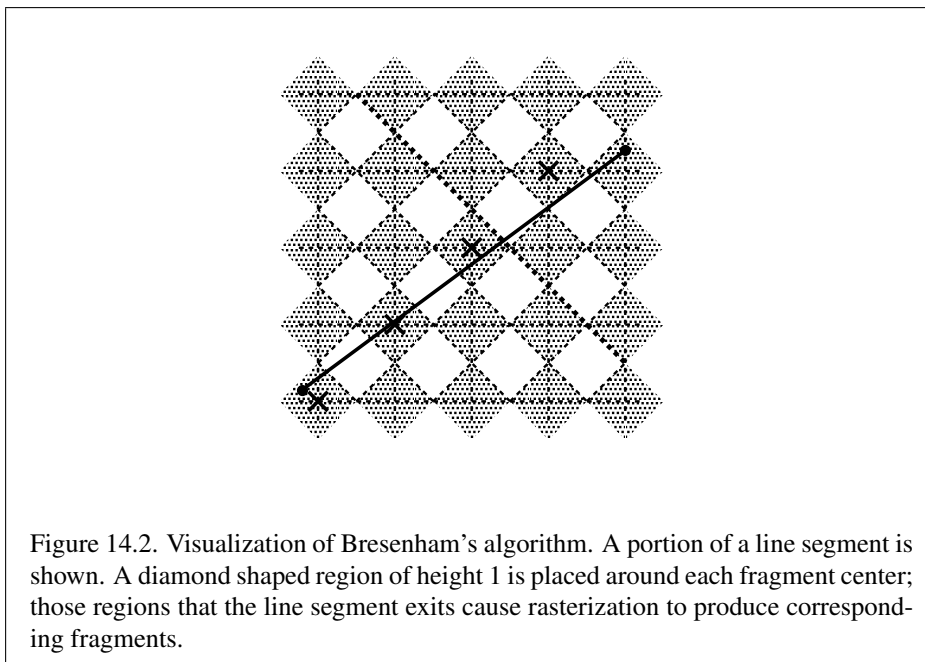
Ideally, the GL uses a “diamond-exit” rule to determine those fragments that are produced by rasterizing a line segment. For each fragment *f* with center at window coordinates  $x_f$  and  $y_f$ , define a diamond-shaped region that is the intersection of four half planes:

$$R_f = \{ (x, y) \mid |x - x_f| + |y - y_f| < \frac{1}{2} \}$$

Essentially, a line segment starting at  $\mathbf{p}_a$  and ending at  $\mathbf{p}_b$  produces those fragments *f* for which the segment intersects  $R_f$ , except if  $\mathbf{p}_b$  is contained in  $R_f$ . See figure 14.2.

To avoid difficulties when an endpoint lies on a boundary of  $R_f$  we (in principle) perturb the supplied endpoints by a tiny amount. Let  $\mathbf{p}_a$  and  $\mathbf{p}_b$  have window coordinates  $(x_a, y_a)$  and  $(x_b, y_b)$ , respectively. Obtain the perturbed endpoints  $\mathbf{p}'_a$  given by  $(x_a, y_a) - (\epsilon, \epsilon^2)$  and  $\mathbf{p}'_b$  given by  $(x_b, y_b) - (\epsilon, \epsilon^2)$ . Rasterizing the line segment starting at  $\mathbf{p}_a$  and ending at  $\mathbf{p}_b$  produces those fragments *f* for which the segment starting at  $\mathbf{p}'_a$  and ending on  $\mathbf{p}'_b$  intersects  $R_f$ , except if  $\mathbf{p}'_b$  is contained in  $R_f$ .  $\epsilon$  is chosen to be so small that rasterizing the line segment produces the same fragments when  $\delta$  is substituted for  $\epsilon$  for any  $0 < \delta \leq \epsilon$ .

When  $\mathbf{p}_a$  and  $\mathbf{p}_b$  lie on fragment centers, this characterization of fragments reduces to Bresenham's algorithm with one modification: lines produced in this description are “half-open,” meaning that the final fragment (corresponding to  $\mathbf{p}_b$ ) is not drawn. This means that when rasterizing a series of connected line segments, shared endpoints will be produced only once rather than twice (as would occur with Bresenham's algorithm).



Because the initial and final conditions of the diamond-exit rule may be difficult to implement, other line segment rasterization algorithms are allowed, subject to the following rules:

1. The coordinates of a fragment produced by the algorithm may not deviate by more than one unit in either  $x$  or  $y$  window coordinates from a corresponding fragment produced by the diamond-exit rule.
2. The total number of fragments produced by the algorithm may differ from that produced by the diamond-exit rule by no more than one.
3. For an  $x$ -major line, no two fragments may be produced that lie in the same window-coordinate column (for a  $y$ -major line, no two fragments may appear in the same row).
4. If two line segments share a common endpoint, and both segments are either  $x$ -major (both left-to-right or both right-to-left) or  $y$ -major (both bottom-to-top or both top-to-bottom), then rasterizing both segments may not produce duplicate fragments, nor may any fragments be omitted so as to interrupt continuity of the connected segments.

Next we must specify how the data associated with each rasterized fragment are obtained. Let the window coordinates of a produced fragment center be given by  $\mathbf{p}_r = (x_d, y_d)$  and let  $\mathbf{p}_a = (x_a, y_a)$  and  $\mathbf{p}_b = (x_b, y_b)$ . Set

$$t = \frac{(\mathbf{p}_r - \mathbf{p}_a) \cdot (\mathbf{p}_b - \mathbf{p}_a)}{\|\mathbf{p}_b - \mathbf{p}_a\|^2}. \quad (14.5)$$

(Note that  $t = 0$  at  $\mathbf{p}_a$  and  $t = 1$  at  $\mathbf{p}_b$ .) The value of an associated datum  $f$  for the fragment, whether it be a shader output or the clip  $w$  coordinate, is found as

$$f = \frac{(1-t)f_a/w_a + tf_b/w_b}{(1-t)/w_a + t/w_b} \quad (14.6)$$

where  $f_a$  and  $f_b$  are the data associated with the starting and ending endpoints of the segment, respectively;  $w_a$  and  $w_b$  are the clip  $w$  coordinates of the starting and ending endpoints of the segments, respectively. However, depth values for lines must be interpolated by

$$z = (1-t)z_a + tz_b \quad (14.7)$$

where  $z_a$  and  $z_b$  are the depth values of the starting and ending endpoints of the segment, respectively.

The `noperspective` and `flat` keywords used to declare shader outputs affect how they are interpolated. When neither keyword is specified, interpolation is performed as described in equation 14.6. When the `noperspective` keyword is specified, interpolation is performed in the same fashion as for depth values, as described in equation 14.7. When the `flat` keyword is specified, no interpolation is performed, and outputs are taken from the corresponding input value of the provoking vertex corresponding to that primitive (see section 13.4).

## 14.5.2 Other Line Segment Features

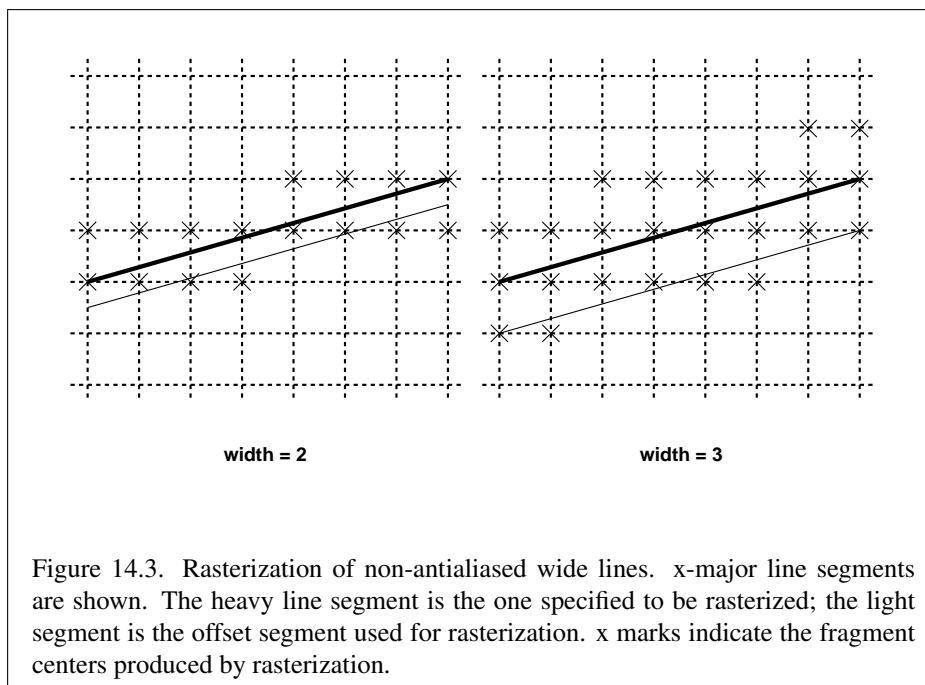
We have just described the rasterization of non-antialiased line segments of width one. We now describe the rasterization of line segments for general values of the line segment rasterization parameters.

### 14.5.2.1 Line Stipple

This subsection is only defined in the compatibility profile.

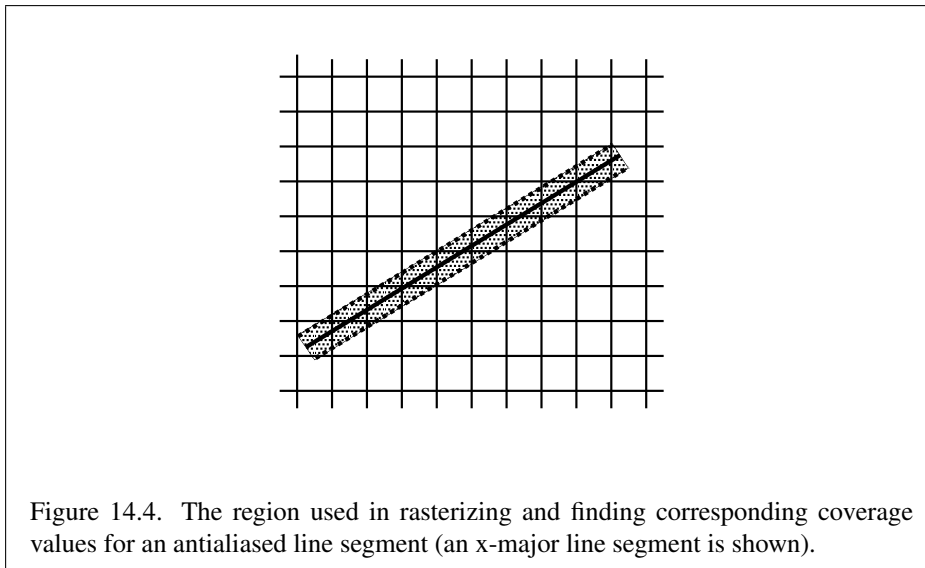
### 14.5.2.2 Wide Lines

The actual width of non-antialiased lines is determined by rounding the supplied width to the nearest integer, then clamping it to the implementation-dependent



maximum non-antialiased line width. This implementation-dependent value must be no less than the implementation-dependent maximum antialiased line width, rounded to the nearest integer value, and in any event no less than 1. If rounding the specified width results in the value 0, then it is as if the value were 1.

Non-antialiased line segments of width other than one are rasterized by offsetting them in the minor direction (for an  $x$ -major line, the minor direction is  $y$ , and for a  $y$ -major line, the minor direction is  $x$ ) and replicating fragments in the minor direction (see figure 14.3). Let  $w$  be the width rounded to the nearest integer (if  $w = 0$ , then it is as if  $w = 1$ ). If the line segment has endpoints given by  $(x_0, y_0)$  and  $(x_1, y_1)$  in window coordinates, the segment with endpoints  $(x_0, y_0 - (w - 1)/2)$  and  $(x_1, y_1 - (w - 1)/2)$  is rasterized, but instead of a single fragment, a column of fragments of height  $w$  (a row of fragments of length  $w$  for a  $y$ -major segment) is produced at each  $x$  ( $y$  for  $y$ -major) location. The lowest fragment of this column is the fragment that would be produced by rasterizing the segment of width 1 with the modified coordinates. The whole column is not produced if the stipple bit for the column's  $x$  location is zero; otherwise, the whole column is produced.



### 14.5.2.3 Antialiasing

Rasterized antialiased line segments produce fragments whose fragment squares intersect a rectangle centered on the line segment. Two of the edges are parallel to the specified line segment; each is at a distance of one-half the current width from that segment: one above the segment and one below it. The other two edges pass through the line endpoints and are perpendicular to the direction of the specified line segment. Coverage values are computed for each fragment by computing the area of the intersection of the rectangle with the fragment square (see figure 14.4; see also section 14.3). Equation 14.6 is used to compute associated data values just as with non-antialiased lines; equation 14.5 is used to find the value of  $t$  for each fragment whose square is intersected by the line segment's rectangle. Not all widths need be supported for line segment antialiasing, but width 1.0 antialiased segments must be provided. As with the point width, a GL implementation may be queried for the range and number of gradations of available antialiased line widths.

### 14.5.3 Line Rasterization State

The state required for line rasterization consists of the floating-point line width and a bit indicating whether line antialiasing is on or off. The initial value of the line width is 1.0. The initial state of line segment antialiasing is disabled.

### 14.5.4 Line Multisample Rasterization

If `MULTISAMPLE` is enabled, and the value of `SAMPLE_BUFFERS` is one, then lines are rasterized using the following algorithm, regardless of whether line antialiasing (`LINE_SMOOTH`) is enabled or disabled. Line rasterization produces a fragment for each framebuffer pixel with one or more sample points that intersect the rectangular region that is described in the **Antialiasing** portion of section 14.5.2 (Other Line Segment Features).

Coverage bits that correspond to sample points that intersect a retained rectangle are 1, other coverage bits are 0. Each depth value and set of associated data is produced by substituting the corresponding sample location into equation 14.5, then using the result to evaluate equation 14.7. An implementation may choose to assign the associated data to more than one sample by evaluating equation 14.5 at any location within the pixel including the fragment center or any one of the sample locations, then substituting into equation 14.6. The different associated data values need not be evaluated at the same location.

Line width range and number of gradations are equivalent to those supported for antialiased lines.

## 14.6 Polygons

A polygon results from a triangle arising from a triangle strip, triangle fan, or series of separate triangles. Like points and line segments, polygon rasterization is controlled by several variables. Polygon antialiasing is controlled with **Enable** and **Disable** with the symbolic constant `POLYGON_SMOOTH`.

### 14.6.1 Basic Polygon Rasterization

The first step of polygon rasterization is to determine if the polygon is *back-facing* or *front-facing*. This determination is made based on the sign of the (clipped or unclipped) polygon's area computed in window coordinates. One way to compute this area is

$$a = \frac{1}{2} \sum_{i=0}^{n-1} x_w^i y_w^{i \oplus 1} - x_w^{i \oplus 1} y_w^i \quad (14.8)$$

where  $x_w^i$  and  $y_w^i$  are the  $x$  and  $y$  window coordinates of the  $i$ th vertex of the  $n$ -vertex polygon (vertices are numbered starting at zero for purposes of this computation) and  $i \oplus 1$  is  $(i + 1) \bmod n$ . The interpretation of the sign of this value is controlled with



```
void FrontFace( enum dir );
```

Setting *dir* to `CCW` (corresponding to counter-clockwise orientation of the projected polygon in window coordinates) uses *a* as computed above. Setting *dir* to `CW` (corresponding to clockwise orientation) indicates that the sign of *a* should be reversed prior to use. Front face determination requires one bit of state, and is initially set to `CCW`.

If the sign of *a* (including the possible reversal of this sign as determined by **FrontFace**) is positive, the polygon is front-facing; otherwise, it is back-facing. This determination is used in conjunction with the **CullFace** enable bit and mode value to decide whether or not a particular polygon is rasterized. The **CullFace** mode is set by calling

```
void CullFace( enum mode );
```

*mode* is a symbolic constant: one of `FRONT`, `BACK` or `FRONT_AND_BACK`. Culling is enabled or disabled with **Enable** or **Disable** using the symbolic constant `CULL_FACE`. Front-facing polygons are rasterized if either culling is disabled or the **CullFace** mode is `BACK` while back-facing polygons are rasterized only if either culling is disabled or the **CullFace** mode is `FRONT`. The initial setting of the **CullFace** mode is `BACK`. Initially, culling is disabled.

The rule for determining which fragments are produced by polygon rasterization is called *point sampling*. The two-dimensional projection obtained by taking the *x* and *y* window coordinates of the polygon's vertices is formed. Fragment centers that lie inside of this polygon are produced by rasterization. Special treatment is given to a fragment whose center lies on a polygon edge. In such a case we require that if two polygons lie on either side of a common edge (with identical endpoints) on which a fragment center lies, then exactly one of the polygons results in the production of the fragment during rasterization.

As for the data associated with each fragment produced by rasterizing a polygon, we begin by specifying how these values are produced for fragments in a triangle. Define *barycentric coordinates* for a triangle. Barycentric coordinates are a set of three numbers, *a*, *b*, and *c*, each in the range  $[0, 1]$ , with  $a + b + c = 1$ . These coordinates uniquely specify any point *p* within the triangle or on the triangle's boundary as

$$p = ap_a + bp_b + cp_c,$$

where  $p_a$ ,  $p_b$ , and  $p_c$  are the vertices of the triangle. *a*, *b*, and *c* can be found as

$$a = \frac{A(pp_b p_c)}{A(p_a p_b p_c)}, \quad b = \frac{A(pp_a p_c)}{A(p_a p_b p_c)}, \quad c = \frac{A(pp_a p_b)}{A(p_a p_b p_c)},$$

where  $A(lmn)$  denotes the area in window coordinates of the triangle with vertices  $l$ ,  $m$ , and  $n$ .

Denote an associated datum at  $p_a$ ,  $p_b$ , or  $p_c$  as  $f_a$ ,  $f_b$ , or  $f_c$ , respectively. Then the value  $f$  of a datum at a fragment produced by rasterizing a triangle is given by

$$f = \frac{af_a/w_a + bf_b/w_b + cf_c/w_c}{a/w_a + b/w_b + c/w_c} \quad (14.9)$$

where  $w_a$ ,  $w_b$  and  $w_c$  are the clip  $w$  coordinates of  $p_a$ ,  $p_b$ , and  $p_c$ , respectively.  $a$ ,  $b$ , and  $c$  are the barycentric coordinates of the fragment for which the data are produced.  $a$ ,  $b$ , and  $c$  must correspond precisely to the exact coordinates of the center of the fragment. Another way of saying this is that the data associated with a fragment must be sampled at the fragment's center. However, depth values for polygons must be interpolated by

$$z = az_a + bz_b + cz_c \quad (14.10)$$

where  $z_a$ ,  $z_b$ , and  $z_c$  are the depth values of  $p_a$ ,  $p_b$ , and  $p_c$ , respectively.

The `noperspective` and `flat` keywords used to declare shader outputs affect how they are interpolated. When neither keyword is specified, interpolation is performed as described in equation 14.9. When the `noperspective` keyword is specified, interpolation is performed in the same fashion as for depth values, as described in equation 14.10. When the `flat` keyword is specified, no interpolation is performed, and outputs are taken from the corresponding input value of the provoking vertex corresponding to that primitive (see section 13.4).

For a polygon with more than three edges, such as may be produced by clipping a triangle, we require only that a convex combination of the values of the datum at the polygon's vertices can be used to obtain the value assigned to each fragment produced by the rasterization algorithm. That is, it must be the case that at every fragment

$$f = \sum_{i=1}^n a_i f_i$$

where  $n$  is the number of vertices in the polygon,  $f_i$  is the value of the  $f$  at vertex  $i$ ; for each  $i$   $0 \leq a_i \leq 1$  and  $\sum_{i=1}^n a_i = 1$ . The values of the  $a_i$  may differ from fragment to fragment, but at vertex  $i$ ,  $a_j = 0, j \neq i$  and  $a_i = 1$ .

One algorithm that achieves the required behavior is to triangulate a polygon (without adding any vertices) and then treat each triangle individually as already discussed. A scan-line rasterizer that linearly interpolates data along each edge and then linearly interpolates data across each horizontal span from edge to edge

also satisfies the restrictions (in this case, the numerator and denominator of equation 14.9 should be iterated independently and a division performed for each fragment).

### 14.6.2 Stippling

This subsection is only defined in the compatibility profile.

### 14.6.3 Antialiasing

Polygon antialiasing rasterizes a polygon by producing a fragment wherever the interior of the polygon intersects that fragment's square. A coverage value is computed at each such fragment, and this value is saved to be applied as described in section 17.1. An associated datum is assigned to a fragment by integrating the datum's value over the region of the intersection of the fragment square with the polygon's interior and dividing this integrated value by the area of the intersection. For a fragment square lying entirely within the polygon, the value of a datum at the fragment's center may be used instead of integrating the value across the fragment.

### 14.6.4 Options Controlling Polygon Rasterization

The interpretation of polygons for rasterization is controlled using

```
void PolygonMode( enum face, enum mode );
```

*face* must be `FRONT_AND_BACK`, indicating that the rasterizing method described by *mode* replaces the rasterizing method for both front- and back-facing polygons. *mode* is one of the symbolic constants `POINT`, `LINE`, or `FILL`. Calling **PolygonMode** with `POINT` causes the vertices of a polygon to be treated, for rasterization purposes, as if they had been drawn with *mode* `POINTS`. `LINE` causes edges to be rasterized as line segments. `FILL` is the default mode of polygon rasterization, corresponding to the description in sections 14.6.1, and 14.6.3. Note that these modes affect only the final rasterization of polygons: in particular, a polygon's vertices are lit, and the polygon is clipped and possibly culled before these modes are applied.

Polygon antialiasing applies only to the `FILL` state of **PolygonMode**. For `POINT` or `LINE`, point antialiasing or line segment antialiasing, respectively, apply.

### 14.6.5 Depth Offset

The depth values of all fragments generated by the rasterization of a polygon may be offset by a single value that is computed for that polygon. The function that determines this value is specified by calling

```
void PolygonOffset( float factor, float units );
```

*factor* scales the maximum depth slope of the polygon, and *units* scales an implementation-dependent constant that relates to the usable resolution of the depth buffer. The resulting values are summed to produce the polygon offset value. Both *factor* and *units* may be either positive or negative.

The maximum depth slope  $m$  of a triangle is

$$m = \sqrt{\left(\frac{\partial z_w}{\partial x_w}\right)^2 + \left(\frac{\partial z_w}{\partial y_w}\right)^2} \quad (14.11)$$

where  $(x_w, y_w, z_w)$  is a point on the triangle.  $m$  may be approximated as

$$m = \max \left\{ \left| \frac{\partial z_w}{\partial x_w} \right|, \left| \frac{\partial z_w}{\partial y_w} \right| \right\}. \quad (14.12)$$

The minimum resolvable difference  $r$  is an implementation-dependent parameter that depends on the depth buffer representation. It is the smallest difference in window coordinate  $z$  values that is guaranteed to remain distinct throughout polygon rasterization and in the depth buffer. All pairs of fragments generated by the rasterization of two polygons with otherwise identical vertices, but  $z_w$  values that differ by  $r$ , will have distinct depth values.

For fixed-point depth buffer representations,  $r$  is constant throughout the range of the entire depth buffer. For floating-point depth buffers, there is no single minimum resolvable difference. In this case, the minimum resolvable difference for a given polygon is dependent on the maximum exponent,  $e$ , in the range of  $z$  values spanned by the primitive. If  $n$  is the number of bits in the floating-point mantissa, the minimum resolvable difference,  $r$ , for the given primitive is defined as

$$r = 2^{e-n}.$$

If no depth buffer is present,  $r$  is undefined.

The offset value  $o$  for a polygon is

$$o = m \times \textit{factor} + r \times \textit{units}. \quad (14.13)$$

$m$  is computed as described above. If the depth buffer uses a fixed-point representation,  $m$  is a function of depth values in the range  $[0, 1]$ , and  $o$  is applied to depth values in the same range.

Boolean state values `POLYGON_OFFSET_POINT`, `POLYGON_OFFSET_LINE`, and `POLYGON_OFFSET_FILL` determine whether  $o$  is applied during the rasterization of polygons in `POINT`, `LINE`, and `FILL` modes. These boolean state values are enabled and disabled as argument values to the commands **Enable** and **Disable**. If `POLYGON_OFFSET_POINT` is enabled,  $o$  is added to the depth value of each fragment produced by the rasterization of a polygon in `POINT` mode. Likewise, if `POLYGON_OFFSET_LINE` or `POLYGON_OFFSET_FILL` is enabled,  $o$  is added to the depth value of each fragment produced by the rasterization of a polygon in `LINE` or `FILL` modes, respectively.

For fixed-point depth buffers, fragment depth values are always limited to the range  $[0, 1]$  by clamping after offset addition is performed. Fragment depth values are clamped even when the depth buffer uses a floating-point representation.

### 14.6.6 Polygon Multisample Rasterization

If `MULTISAMPLE` is enabled, and the value of `SAMPLE_BUFFERS` is one, then polygons are rasterized using the following algorithm, regardless of whether polygon antialiasing (`POLYGON_SMOOTH`) is enabled or disabled. Polygon rasterization produces a fragment for each framebuffer pixel with one or more sample points that satisfy the point sampling criteria described in section 14.6.1. If a polygon is culled, based on its orientation and the **CullFace** mode, then no fragments are produced during rasterization.

Coverage bits that correspond to sample points that satisfy the point sampling criteria are 1, other coverage bits are 0. Each associated datum is produced as described in section 14.6.1, but using the corresponding sample location instead of the fragment center. An implementation may choose to assign the same associated data values to more than one sample by barycentric evaluation using any location within the pixel including the fragment center or one of the sample locations.

When using a vertex shader, the `noperspective` and `flat` qualifiers affect how shader outputs are interpolated in the same fashion as described for basic polygon rasterization in section 14.6.1.

The rasterization described above applies only to the `FILL` state of **Polygon-Mode**. For `POINT` and `LINE`, the rasterizations described in sections 14.4.3 (Point Multisample Rasterization) and 14.5.4 (Line Multisample Rasterization) apply.

### 14.6.7 Polygon Rasterization State

The state required for polygon rasterization consists of the current state of polygon antialiasing (enabled or disabled), the current values of the **PolygonMode** setting, whether point, line, and fill mode polygon offsets are enabled or disabled, and the factor and bias values of the polygon offset equation. The initial setting of polygon antialiasing is disabled. The initial state for **PolygonMode** is `FILL`. The initial polygon offset factor and bias values are both 0; initially polygon offset is disabled for all modes.

## 14.7 ~~Current Raster Position~~

This section is only defined in the compatibility profile.

## 14.8 ~~Bitmaps~~

This section is only defined in the compatibility profile.

## 14.9 Early Per-Fragment Tests

Once fragments are produced by rasterization, a number of per-fragment operations may be performed prior to fragment shader execution. If a fragment is discarded during any of these operations, it will not be processed by any subsequent stage, including fragment shader execution.

Up to five operations are performed on each fragment, in the following order:

- the pixel ownership test (see section [17.3.1](#));
- the scissor test (see section [17.3.2](#));
- the stencil test (see section [17.3.5](#));
- the depth buffer test (see section [17.3.6](#)); and
- occlusion query sample counting (see section [17.3.7](#)).

The pixel ownership and scissor tests are always performed.

The other operations are performed if and only if early fragment tests are enabled in the active fragment shader (see section [15.2](#)). When early per-fragment operations are enabled, the stencil test, depth buffer test, and occlusion query sample counting operations are performed prior to fragment shader execution, and the

stencil buffer, depth buffer, and occlusion query sample counts will be updated accordingly. When early per-fragment operations are enabled, these operations will not be performed again after fragment shader execution. When the active program has no fragment shader, or the active program was linked with early fragment tests disabled, these operations are performed only after fragment program execution, in the order described in chapter 9.

If early fragment tests are enabled, any depth value computed by the fragment shader has no effect. Additionally, the depth buffer, stencil buffer, and occlusion query sample counts may be updated even for fragments or samples that would be discarded after fragment shader execution due to per-fragment operations such as alpha-to-coverage tests.

## Chapter 15

# Programmable Fragment Processing

When the program object currently in use for the fragment stage (see section 7.3) includes a fragment shader, its shader is considered *active* and is used to process fragments resulting from rasterization (see section 14).

If the current fragment stage program object has no fragment shader, or no fragment program object is current for the fragment stage, the results of fragment shader execution are undefined.

The processed fragments resulting from fragment shader execution are then further processed and written to the framebuffer as described in chapter 17.

### 15.1 Fragment Shader Variables

Fragment shaders can access uniforms belonging to the current program object. Limits on uniform storage and methods for manipulating uniforms are described in section 7.6.

Fragment shaders also have access to samplers to perform texturing operations, as described in section 7.10.

Fragment shaders can read *input variables* or *inputs* that correspond to the attributes of the fragments produced by rasterization.

The OpenGL Shading Language Specification defines a set of built-in inputs that can be accessed by a fragment shader. These built-in inputs include data associated with a fragment such as the fragment's position.

Additionally, the previous active shader stage may define one or more input variables (see section 11.1.2.1 and the OpenGL Shading Language Specification). The values of these user-defined inputs are, if not flat shaded, interpolated across



the primitive being rendered. The results of these interpolations are available when inputs of the same name are defined in the fragment shader.

When interpolating input variables, the default screen-space location at which these variables are sampled is defined in previous rasterization sections. The default location may be overridden by interpolation qualifiers. When interpolating variables declared using `centroid in`, the variable is sampled at a location within the pixel covered by the primitive generating the fragment. When interpolating variables declared using `sample in` when `MULTISAMPLE` is enabled, the fragment shader will be invoked separately for each covered sample and the variable will be sampled at the corresponding sample point.

Additionally, built-in fragment shader functions provide further fine-grained control over interpolation. The built-in functions `interpolateAtCentroid` and `interpolateAtSample` will sample variables as though they were declared with the `centroid` or `sample` qualifiers, respectively. The built-in function `interpolateAtOffset` will sample variables at a specified  $(x, y)$  offset relative to the center of the pixel. The range and granularity of offsets supported by this function is implementation-dependent. If either component of the specified offset is less than the value of `MIN_FRAGMENT_INTERPOLATION_OFFSET` or greater than the value of `MAX_FRAGMENT_INTERPOLATION_OFFSET`, the position used to interpolate the variable is undefined. Not all values of *offset* may be supported;  $x$  and  $y$  offsets may be rounded to fixed-point values with the number of fraction bits given by the value of the implementation-dependent constant `FRAGMENT_INTERPOLATION_OFFSET_BITS`.

A fragment shader can also write to output variables. Values written to these outputs are used in the subsequent per-fragment operations. Output variables can be used to write floating-point, integer or unsigned integer values destined for buffers attached to a framebuffer object, or destined for color buffers attached to the default framebuffer. Section 15.2.3 describes how to direct these values to buffers.

## 15.2 Shader Execution

If there is an active program object present for the fragment stage, the executable code for that program is used to process incoming fragments that are the result of rasterization, instead of the fixed-function method described in chapter 16.

Following shader execution, the fixed-function operations described in chapter 17 are performed.

Special considerations for fragment shader execution are described in the following sections.

### 15.2.1 Texture Access

Section 11.1.3.1 describes texture lookup functionality accessible to a vertex shader. The texel fetch and texture size query functionality described there also applies to fragment shaders.

When a texture lookup is performed in a fragment shader, the GL computes the filtered texture value  $\tau$  in the manner described in sections 8.14 and 8.15, and converts it to a texture base color  $C_b$  as shown in table 15.1, followed by *swizzling* the components of  $C_b$ , controlled by the values of the texture parameters TEXTURE\_SWIZZLE\_R, TEXTURE\_SWIZZLE\_G, TEXTURE\_SWIZZLE\_B, and TEXTURE\_SWIZZLE\_A. If the value of TEXTURE\_SWIZZLE\_R is denoted by  $swizzle_r$ , swizzling computes the first component of  $C_s$  according to

```

if (swizzle_r == RED)
    C_s[0] = C_b[0];
else if (swizzle_r == GREEN)
    C_s[0] = C_b[1];
else if (swizzle_r == BLUE)
    C_s[0] = C_b[2];
else if (swizzle_r == ALPHA)
    C_s[0] = A_b;
else if (swizzle_r == ZERO)
    C_s[0] = 0;
else if (swizzle_r == ONE)
    C_s[0] = 1; // float or int depending on texture component type

```

Swizzling of  $C_s[1]$ ,  $C_s[2]$ , and  $A_s$  are similarly controlled by the values of TEXTURE\_SWIZZLE\_G, TEXTURE\_SWIZZLE\_B, and TEXTURE\_SWIZZLE\_A, respectively.

The resulting four-component vector  $(R_s, G_s, B_s, A_s)$  is returned to the fragment shader. For the purposes of level-of-detail calculations, the derivatives  $\frac{du}{dx}$ ,  $\frac{du}{dy}$ ,  $\frac{dv}{dx}$ ,  $\frac{dv}{dy}$ ,  $\frac{dw}{dx}$  and  $\frac{dw}{dy}$  may be approximated by a differencing algorithm as described in section 8.13.1 (“Derivative Functions”) of the OpenGL Shading Language Specification .

Texture lookups involving textures with depth component data generate a texture base color  $C_b$  either using depth data directly or by performing a comparison with the  $D_{ref}$  value used to perform the lookup, as described in section 8.22.1, and expanding the resulting value  $R_t$  to a color  $C_b = (R_t, 0, 0, 1)$ . Swizzling is then performed as described above, but only the first component  $C_s[0]$  is returned to the shader. The comparison operation is requested in the shader by using

Texture Base Internal Format	Texture base color	
	$C_b$	$A_b$
RED	$(R_t, 0, 0)$	1
RG	$(R_t, G_t, 0)$	1
RGB	$(R_t, G_t, B_t)$	1
RGBA	$(R_t, G_t, B_t)$	$A_t$

Table 15.1: Correspondence of filtered texture components to texture base components.

any of the shadow sampler types (`sampler*Shadow`), and in the texture using the `TEXTURE_COMPARE_MODE` parameter. These requests must be consistent; the results of a texture lookup are undefined if any of the following conditions are true:

- The sampler used in a texture lookup function is not one of the shadow sampler types, the texture object's internal format is `DEPTH_COMPONENT` or `DEPTH_STENCIL`, and the `TEXTURE_COMPARE_MODE` is not `NONE`.
- The sampler used in a texture lookup function is one of the shadow sampler types, the texture object's internal format is `DEPTH_COMPONENT` or `DEPTH_STENCIL`, and the `TEXTURE_COMPARE_MODE` is `NONE`.
- The sampler used in a texture lookup function is one of the shadow sampler types, and the texture object's internal format is not `DEPTH_COMPONENT` or `DEPTH_STENCIL`.

The stencil index texture internal component is ignored if the base internal format is `DEPTH_STENCIL`.

If a sampler is used in a shader and the sampler's associated texture is not complete, as defined in section 8.17,  $(0, 0, 0, 1)$  will be returned for a non-shadow sampler and 0 for a shadow sampler.

The number of separate texture units that can be accessed from within a fragment shader during the rendering of a single primitive is specified by the implementation-dependent constant `MAX_TEXTURE_IMAGE_UNITS`.

### 15.2.2 Shader Inputs

The OpenGL Shading Language Specification describes the values that are available as inputs to the fragment shader.

The built-in variable `gl_FragCoord` holds the fragment coordinate  $(x_f \ y_f \ z_f \ w_f)$  for the fragment. Computing the fragment coordinate depends on the fragment processing pixel-center and origin conventions (discussed below) as follows:

$$\begin{aligned}
 x_f &= \begin{cases} x_w - \frac{1}{2}, & \text{pixel-center convention is integer} \\ x_w, & \text{otherwise} \end{cases} \\
 y'_f &= \begin{cases} H - y_w, & \text{origin convention is upper-left} \\ y_w, & \text{otherwise} \end{cases} \\
 y_f &= \begin{cases} y'_f - \frac{1}{2}, & \text{pixel-center convention is integer} \\ y'_f & \text{otherwise} \end{cases} \\
 z_f &= z_w \\
 w_f &= \frac{1}{w_c}
 \end{aligned} \tag{15.1}$$

where  $(x_w \ y_w \ z_w)$  is the fragment's window-space position,  $w_c$  is the  $w$  component of the fragment's clip-space position, and  $H$  is the window's height in pixels. Note that  $z_w$  already has a polygon offset added in, if enabled (see section 14.6.5).  $z_f$  must be precisely 0 or 1 in the case where  $z_w$  is either 0 or 1, respectively. The  $\frac{1}{w}$  value is computed from the  $w_c$  coordinate (see section 13.6).

Unless otherwise specified by `layout` qualifiers in the fragment shader (see section 4.4.1.3("Fragment Shader Inputs") of the OpenGL Shading Language Specification), the fragment processing pixel-center convention is half-integer and the fragment processing origin convention is lower-left.

The built-in variable `gl_FrontFacing` is set to `TRUE` if the fragment is generated from a front-facing primitive, and `FALSE` otherwise. For fragments generated from triangle primitives (including ones resulting from primitives rendered as points or lines), the determination is made by examining the sign of the area computed by equation 14.8 of section 14.6.1 (including the possible reversal of this sign controlled by **FrontFace**). If the sign is positive, fragments generated by the primitive are front-facing; otherwise, they are back-facing. All other fragments are considered front-facing.

If a geometry shader is active, the built-in variable `gl_PrimitiveID` contains the ID value emitted by the geometry shader for the provoking vertex. If no geometry shader is active, `gl_PrimitiveID` contains the number of primitives processed by the rasterizer since the last drawing command was called. The first primitive generated by a drawing command is numbered zero, and the primitive ID

counter is incremented after every individual point, line, or polygon primitive is processed. For polygons drawn in point or line mode, the primitive ID counter is incremented only once, even though multiple points or lines may be drawn.

Restarting a primitive using the primitive restart index (see section 10.3) has no effect on the primitive ID counter.

`gl_PrimitiveID` is only defined under the same conditions that `gl_VertexID` is defined, as described under “Shader Inputs” in section 11.1.3.9.

Similarly to the limit on geometry shader output components (see section 11.3.4.5), there is a limit on the number of components of built-in and user-defined input variables that can be read by the fragment shader, given by the value of the implementation-dependent constant `MAX_FRAGMENT_INPUT_COMPONENTS`.

The built-in variable `gl_SampleMaskIn` is an integer array holding bitfields indicating the set of fragment samples covered by the primitive corresponding to the fragment shader invocation. The number of elements in the array is

$$\left\lceil \frac{s}{32} \right\rceil,$$

where  $s$  is the maximum number of color samples supported by the implementation. Bit  $n$  of element  $w$  in the array is set if and only if the sample numbered  $32w + n$  is considered covered for this fragment shader invocation. When rendering to a non-multisample buffer, or if multisample rasterization is disabled, all bits are zero except for bit zero of the first array element. That bit will be one if the pixel is covered and zero otherwise. Bits in the sample mask corresponding to covered samples that will be killed due to `SAMPLE_COVERAGE` or `SAMPLE_MASK` will not be set (see section 17.3.3). When per-sample shading is active due to the use of a fragment input qualified by `sample`, only the bit for the current sample is set in `gl_SampleMaskIn`. When state specifies multiple fragment shader invocations for a given fragment, the sample mask for any single fragment shader invocation may specify a subset of the covered samples for the fragment. In this case, the bit corresponding to each covered sample will be set in exactly one fragment shader invocation.

The built-in read-only variable `gl_SampleID` is filled with the sample number of the sample currently being processed. This variable is in the range zero to `gl_NumSamples` minus one, where `gl_NumSamples` is the total number of samples in the framebuffer, or one if rendering to a non-multisample framebuffer. Using this variable in a fragment shader causes the entire shader to be evaluated per-sample. When rendering to a non-multisample buffer, or if multisample rasterization is disabled, `gl_SampleID` will always be zero. `gl_NumSamples` is the sample count of the framebuffer regardless of whether multisample rasterization is

enabled or not.

The built-in read-only variable `gl_SamplePosition` contains the position of the current sample within the multi-sample draw buffer. The  $x$  and  $y$  components of `gl_SamplePosition` contain the sub-pixel coordinate of the current sample and will have values in the range  $[0, 1]$ . The sub-pixel coordinates of the center of the pixel are always  $(0.5, 0.5)$ . Using this variable in a fragment shader causes the entire shader to be evaluated per-sample. When rendering to a non-multisample buffer, or if multisample rasterization is disabled, `gl_SamplePosition` will always be  $(0.5, 0.5)$ .

When a program is linked, all components of any input variables read by a fragment shader will count against this limit. A program whose fragment shader exceeds this limit may fail to link, unless device-dependent optimizations are able to make the program fit within available hardware resources.

Component counting rules for different variable types and variable declarations are the same as for `MAX_VERTEX_OUTPUT_COMPONENTS`. (see section 11.1.2.1).

### 15.2.3 Shader Outputs

The OpenGL Shading Language Specification describes the values that may be output by a fragment shader. These outputs are split into two categories, user-defined outputs and the built-in outputs `gl_FragDepth` and `gl_SampleMask`.

For fixed-point depth buffers, the final fragment depth written by a fragment shader is first clamped to  $[0, 1]$  and then converted to fixed-point as if it were a window  $z$  value (see section 13.6.1). For floating-point depth buffers, conversion is not performed but clamping is. Note that the depth range computation is not applied here, only the conversion to fixed-point.

The built-in integer array `gl_SampleMask` can be used to change the sample coverage for a fragment from within the shader. The number of elements in the array is

$$\left\lceil \frac{s}{32} \right\rceil,$$

where  $s$  is the maximum number of color samples supported by the implementation. If bit  $n$  of element  $w$  in the array is set to zero, sample  $32w + n$  should be considered uncovered for the purposes of multisample fragment operations (see section 17.3.3). Modifying the sample mask in this way may exclude covered samples from being processed further at a per-fragment granularity. However, setting sample mask bits to one will never enable samples not covered by the original primitive. If the fragment shader is being evaluated at any frequency other than per-fragment, bits of the sample mask not corresponding to the current fragment shader invocation are ignored.

Color values written by a fragment shader may be floating-point, signed integer, or unsigned integer. If the color buffer has a signed or unsigned normalized fixed-point format, color values are assumed to be floating-point and are converted to fixed-point as described in equations 2.4 or 2.3, respectively; otherwise no type conversion is applied. If the values written by the fragment shader do not match the format(s) of the corresponding color buffer(s), the result is undefined.

A fragment shader may not statically assign values to more than one user-defined output variable. In this case, a compile or link error will result. A shader statically assigns a value to a variable if, after pre-processing, it contains a statement that would write to the variable, whether or not run-time flow of control will cause that statement to be executed.

Writing to `gl_FragDepth` specifies the depth value for the fragment being processed. If the active fragment shader does not statically assign a value to `gl_FragDepth`, then the depth value generated during rasterization is used by subsequent stages of the pipeline. Otherwise, the value assigned to `gl_FragDepth` is used, and is undefined for any fragments where statements assigning a value to `gl_FragDepth` are not executed. Thus, if a shader statically assigns a value to `gl_FragDepth`, then it is responsible for always writing it.

The binding of a user-defined output variable to a fragment color number can be specified explicitly. The command

```
void BindFragDataLocationIndexed(uint program,
    uint colorNumber, uint index, const char *name);
```

specifies that the output variable *name* in *program* should be bound to fragment color *colorNumber* when the program is next linked. *index* may be zero or one to specify that the color be used as either the first or second color input to the blend equation, respectively, as described in section 17.3.8.

If *name* was bound previously, its assigned binding is replaced with *colorNumber*. *name* must be a null-terminated string.

### Errors

An `INVALID_VALUE` error is generated if *program* is not the name of either a program or shader object.

An `INVALID_OPERATION` error is generated if *program* is the name of a shader object.

An `INVALID_VALUE` error is generated if *index* is greater than one, if *colorNumber* is greater than or equal to the value of `MAX_DRAW_BUFFERS` and *index* is zero, or if *colorNumber* is greater than or equal to the value of `MAX_DUAL_SOURCE_DRAW_BUFFERS` and *index* is greater than or equal to

one.

The command

```
void BindFragDataLocation( uint program,  
    uint colorNumber, const char * name );
```

is equivalent to

```
BindFragDataLocationIndexed (program, colorNumber, 0, name);
```

**BindFragDataLocation** has no effect until the program is linked. In particular, it doesn't modify the bindings of outputs in a program that has already been linked.

### Errors

An `INVALID_OPERATION` error is generated if *name* starts with the reserved `gl_` prefix.

When a program is linked, any output variables without a binding specified either through **BindFragDataLocationIndexed** or **BindFragDataLocation**, or explicitly set within the shader text will automatically be bound to fragment colors and indices. All such assignments will use color indices of zero. Such bindings can be queried using the commands **GetFragDataLocation** and **GetFragDataIndex**. If an output has a binding explicitly set within the shader text and a different binding assigned by **BindFragDataLocationIndexed** or **BindFragDataLocation**, the assignment in the shader text is used. Output binding assignments will cause **LinkProgram** to fail:

- if the number of active outputs is greater than the value of `MAX_DRAW_BUFFERS`;
- if the program has an active output assigned to a location greater than or equal to the value of `MAX_DUAL_SOURCE_DRAW_BUFFERS` and has an active output assigned an index greater than or equal to one;
- if more than one output variable is bound to the same number and index; or
- if the explicit binding assignments do not leave enough space for the linker to automatically assign a location for an output array, which requires multiple contiguous locations.



**BindFragDataLocationIndexed** may be issued before any shader objects are attached to a program object. Hence it is allowed to bind any name (except a name starting with `gl_`) to a color number and index, including a name that is never used as an output in any fragment shader object. Assigned bindings for variables that do not exist are ignored.

To determine the set of fragment shader output attribute variables used by a program, applications can query the properties and active resources of the `PROGRAM_OUTPUT` interface of a program including a fragment shader.

Additionally, commands are provided to query the location and fragment color index assigned to a fragment shader output variable. For the commands

```
int GetFragDataLocation(uint program, const
    char *name);
int GetFragDataIndex(uint program, const char *name);
```

#### Errors

If *program* has been successfully linked but contains no fragment shader, no error is generated but -1 will be returned.

An `INVALID_OPERATION` error is generated and -1 is returned if *program* has not been linked or was last linked unsuccessfully.

Otherwise, the commands are equivalent to

```
GetProgramResourceLocation (program, PROGRAM_OUTPUT, name);
```

and

```
GetProgramResourceLocationIndex (program, PROGRAM_OUTPUT, name);
```

respectively.

#### 15.2.4 Early Fragment Tests

An explicit control is provided to allow fragment shaders to enable early fragment tests. If the fragment shader specifies the `early_fragment_tests` layout qualifier, the per-fragment tests described in section 14.9 will be performed prior to fragment shader execution. Otherwise, they will be performed after fragment shader execution.

## **Chapter 16**

# **Fixed-Function Fragment Processing**

[This chapter is only defined in the compatibility profile.](#)

## Chapter 17

# Writing Fragments and Samples to the Framebuffer

After programmable fragment processing, the following fixed-function operations are applied to the resulting fragments:

- Antialiasing application (see section 17.1).
- Multisample point fade (see section 17.2).
- Per-fragment operations and writing to the framebuffer (see section 17.3).

Writing to the framebuffer is the final set of operations performed as a result of drawing primitives.

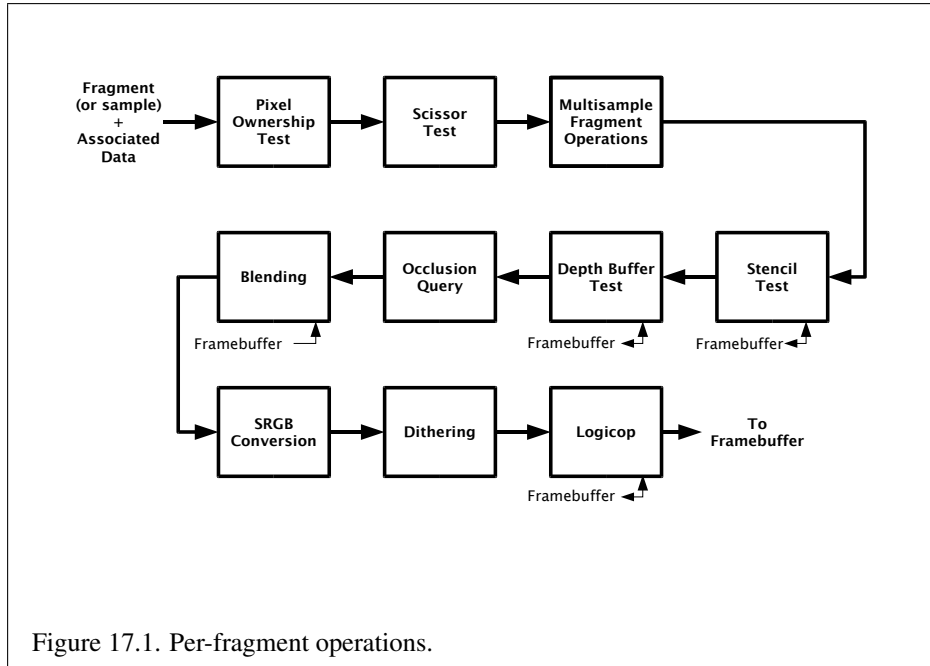
Additional commands controlling the framebuffer as a whole are described in section 17.4.

### 17.1 Antialiasing Application

If antialiasing is enabled for the primitive from which a rasterized fragment was produced, then the computed coverage value is applied to the fragment. The value is multiplied by the fragment's alpha value to yield a final alpha value. The coverage value is applied separately to each fragment color, and only applied if the corresponding color buffer in the framebuffer has a fixed- or floating-point format.

### 17.2 Multisample Point Fade

If multisampling is enabled and the rasterized fragment results from a point primitive, then the computed fade factor from equation 14.2 is applied to the fragment.



The fade factor is multiplied by the fragment's alpha value to yield a final alpha value. The fade factor is applied separately to each fragment color, and only applied if the corresponding color buffer in the framebuffer has a fixed- or floating-point format.

## 17.3 Per-Fragment Operations

A fragment produced by rasterization with window coordinates of  $(x_w, y_w)$  modifies the pixel in the framebuffer at that location based on a number of parameters and conditions. We describe these modifications and tests, diagrammed in figure 17.1, in the order in which they are performed. Figure 17.1 diagrams these modifications and tests.

### 17.3.1 Pixel Ownership Test

The first test is to determine if the pixel at location  $(x_w, y_w)$  in the framebuffer is currently owned by the GL (more precisely, by this GL context). If it is not, the window system decides the fate of the incoming fragment. Possible results are that the fragment is discarded or that some subset of the subsequent per-fragment

operations are applied to the fragment. This test allows the window system to control the GL's behavior, for instance, when a GL window is obscured.

If the draw framebuffer is a framebuffer object (see section 17.4.1), the pixel ownership test always passes, since the pixels of framebuffer objects are owned by the GL, not the window system. If the draw framebuffer is the default framebuffer, the window system controls pixel ownership.

### 17.3.2 Scissor Test

The scissor test determines if  $(x_w, y_w)$  lies within the scissor rectangle defined by four values for each viewport. These values are set with

```
void ScissorArrayv( uint first, sizei count, const
    int *v );
void ScissorIndexed( uint index, int left, int bottom,
    sizei width, sizei height );
void ScissorIndexedv( uint index, int *v );
void Scissor( int left, int bottom, sizei width,
    sizei height );
```

**ScissorArrayv** defines a set of scissor rectangles that are each applied to the corresponding viewport (see section 13.6.1). *first* specifies the index of the first scissor rectangle to modify, and *count* specifies the number of scissor rectangles. *v* contains the address of an array of integers containing the left, bottom, width and height of the scissor rectangles, in that order.

If  $left \leq x_w < left + width$  and  $bottom \leq y_w < bottom + height$  for the selected scissor rectangle, then the scissor test passes. Otherwise, the test fails and the fragment is discarded. For points, lines, and polygons, the scissor rectangle for a primitive is selected in the same manner as the viewport (see section 13.6.1). For buffer clears (see section 17.4.3) and pixel rectangles, the scissor rectangle numbered zero is used for the scissor test.

#### Errors

An `INVALID_VALUE` error is generated by **ScissorArrayv** if *first* + *count* is greater than the value of `MAX_VIEWPORTS`.

An `INVALID_VALUE` error is generated if *width* or *height* is negative.

The scissor test is enabled or disabled for all viewports using **Enable** or **Disable** with the symbolic constant `SCISSOR_TEST`. The test is enabled or disabled

for a specific viewport using **Enablei** or **Disablei** with the constant `SCISSOR_TEST` and the index of the selected viewport. When disabled, it is as if the scissor test always passes. The value of the scissor test enable for viewport  $i$  can be queried by calling **IsEnabledi** with *target* `SCISSOR_TEST` and *index*  $i$ . The value of the scissor test enable for viewport zero may also be queried by calling **IsEnabled** with the same symbolic constant, but no *index* parameter.

### Errors

An `INVALID_VALUE` error is generated by **Enablei**, **Disablei** and **IsEnabledi** if *target* is `SCISSOR_TEST` and *index* is greater than or equal to the value of `MAX_VIEWPORTS`.

The state required consists of four integer values per viewport, and a bit indicating whether the test is enabled or disabled for each viewport. In the initial state,  $left = bottom = 0$ , and  $width$  and  $height$  are determined by the size of the window into which the GL is to do its rendering for all viewports. If the default framebuffer is bound but no default framebuffer is associated with the GL context (see chapter 9), then  $width$  and  $height$  are initially set to zero. Initially, the scissor test is disabled for all viewports.

**ScissorIndexed** and **ScissorIndexedv** specify the scissor rectangle for a single viewport and are equivalent (assuming no errors are generated) to:

```
int v[] = { left, bottom, width, height };
ScissorArrayv(index, 1, v);
```

and

```
ScissorArrayv(index, 1, v);
```

respectively.

**Scissor** sets the scissor rectangle for all viewports to the same values and is equivalent (assuming no errors are generated) to:

```
for (uint i = 0; i < MAX_VIEWPORTS; i++) {
    ScissorIndexed(i, left, bottom, width, height);
}
```

Calling **Enable** or **Disable** with the symbolic constant `SCISSOR_TEST` is equivalent, assuming no errors, to:

```
for (uint i = 0; i < MAX_VIEWPORTS; i++) {  
    Enablei(SCISSOR_TEST, i);  
    /* or */  
    Disablei(SCISSOR_TEST, i);  
}
```

### 17.3.3 Multisample Fragment Operations

This step modifies fragment alpha and coverage values based on the values of `SAMPLE_ALPHA_TO_COVERAGE`, `SAMPLE_ALPHA_TO_ONE`, `SAMPLE_COVERAGE`, `SAMPLE_COVERAGE_VALUE`, `SAMPLE_COVERAGE_INVERT`, `SAMPLE_MASK`, `SAMPLE_MASK_VALUE`, and an output sample mask optionally written by the fragment shader. No changes to the fragment alpha or coverage values are made at this step if `MULTISAMPLE` is disabled, or if the value of `SAMPLE_BUFFERS` is not one.

All alpha values in this section refer only to the alpha component of the fragment shader output linked to color number zero, index zero (see section 15.2.3). If the fragment shader does not write to this output, the alpha value is undefined.

`SAMPLE_ALPHA_TO_COVERAGE`, `SAMPLE_ALPHA_TO_ONE`, `SAMPLE_COVERAGE`, and `SAMPLE_MASK` are enabled and disabled by calling **Enable** and **Disable** with the desired token value. All four values are queried by calling **IsEnabled** with the desired token value. If drawbuffer zero references a buffer with an integer format, the `SAMPLE_ALPHA_TO_COVERAGE` and `SAMPLE_ALPHA_TO_ONE` operations are skipped.

If `SAMPLE_ALPHA_TO_COVERAGE` is enabled, a temporary coverage value is generated where each bit is determined by the alpha value at the corresponding sample location. The temporary coverage value is then ANDed with the fragment coverage value to generate a new fragment coverage value. If the fragment shader outputs an integer to color number zero, index zero when not rendering to an integer format, the coverage value is undefined.

No specific algorithm is required for converting the sample alpha values to a temporary coverage value. It is intended that the number of 1's in the temporary coverage be proportional to the set of alpha values for the fragment, with all 1's corresponding to the maximum of all alpha values, and all 0's corresponding to all alpha values being 0. The alpha values used to generate a coverage value are clamped to the range [0, 1]. It is also intended that the algorithm be pseudo-random in nature, to avoid image artifacts due to regular coverage sample locations. The algorithm can and probably should be different at different pixel locations. If it does differ, it should be defined relative to window, not screen, coordinates, so that rendering results are invariant with respect to window position.

Next, if `SAMPLE_ALPHA_TO_ONE` is enabled, each alpha value is replaced by the maximum representable alpha value for fixed-point color buffers, or by 1.0 for floating-point buffers. Otherwise, the alpha values are not changed.

Next, if a fragment shader is active and statically assigns to the built-in output variable `gl_SampleMask`, the fragment coverage is ANDed with the bits of the sample mask. If such a fragment shader did not assign a value to `gl_SampleMask` due to flow control, the value ANDed with the fragment coverage is undefined. If no fragment shader is active, or if the active fragment shader does not statically assign values to `gl_SampleMask`, the fragment coverage is not modified.

Next, if `SAMPLE_COVERAGE` is enabled, the fragment coverage is ANDed with another temporary coverage. This temporary coverage is generated in the same manner as the one described above, but as a function of the value of `SAMPLE_COVERAGE_VALUE`. The function need not be identical, but it must have the same properties of proportionality and invariance. If `SAMPLE_COVERAGE_INVERT` is `TRUE`, the temporary coverage is inverted (all bit values are inverted) before it is ANDed with the fragment coverage.

The values of `SAMPLE_COVERAGE_VALUE` and `SAMPLE_COVERAGE_INVERT` are specified by calling

```
void SampleCoverage( float value, boolean invert );
```

with *value* set to the desired coverage value, and *invert* set to `TRUE` or `FALSE`. *value* is clamped to  $[0, 1]$  before being stored as `SAMPLE_COVERAGE_VALUE`. `SAMPLE_COVERAGE_VALUE` is queried by calling **GetFloatv** with *pname* set to `SAMPLE_COVERAGE_VALUE`. `SAMPLE_COVERAGE_INVERT` is queried by calling **GetBooleanv** with *pname* set to `SAMPLE_COVERAGE_INVERT`.

Finally, if `SAMPLE_MASK` is enabled, the fragment coverage is ANDed with the coverage value `SAMPLE_MASK_VALUE`. The value of `SAMPLE_MASK_VALUE` is specified using

```
void SampleMaski( uint maskNumber, bitfield mask );
```

with *mask* set to the desired mask for mask word *maskNumber*. `SAMPLE_MASK_VALUE` is queried by calling **GetIntegeriv** with *target* set to `SAMPLE_MASK_VALUE` and the index set to *maskNumber*. Bit *B* of mask word *M* corresponds to sample  $32 \times M + B$  as described in section 14.3.1.

### Errors

An `INVALID_VALUE` error is generated if *maskNumber* is greater than or



equal to the value of `MAX_SAMPLE_MASK_WORDS`.

#### 17.3.4 Alpha Test

This subsection is only defined in the compatibility profile.

#### 17.3.5 Stencil Test

The stencil test conditionally discards a fragment based on the outcome of a comparison between the value in the stencil buffer at location  $(x_w, y_w)$  and a reference value. The test is enabled or disabled with the **Enable** and **Disable** commands, using the symbolic constant `STENCIL_TEST`. When disabled, the stencil test and associated modifications are not made, and the fragment is always passed.

The stencil test is controlled with

```
void StencilFunc( enum func, int ref, uint mask );
void StencilFuncSeparate( enum face, enum func, int ref,
    uint mask );
void StencilOp( enum sfail, enum dpfail, enum dppass );
void StencilOpSeparate( enum face, enum sfail, enum dpfail,
    enum dppass );
```

There are two sets of stencil-related state, the front stencil state set and the back stencil state set. Stencil tests and writes use the front set of stencil state when processing fragments rasterized from non-polygon primitives (points and lines) and front-facing polygon primitives while the back set of stencil state is used when processing fragments rasterized from back-facing polygon primitives. For the purposes of stencil testing, a primitive is still considered a polygon even if the polygon is to be rasterized as points or lines due to the current polygon mode. Whether a polygon is front- or back-facing is determined in the same manner used for face culling (see section 14.6.1).

**StencilFuncSeparate** and **StencilOpSeparate** take a *face* argument which can be `FRONT`, `BACK`, or `FRONT_AND_BACK` and indicates which set of state is affected. **StencilFunc** and **StencilOp** set front and back stencil state to identical values.

**StencilFunc** and **StencilFuncSeparate** take three arguments that control whether the stencil test passes or fails. *ref* is an integer reference value that is used in the unsigned stencil comparison. Stencil comparison operations and queries of *ref* clamp its value to the range  $[0, 2^s - 1]$ , where *s* is the number of bits in the stencil buffer attached to the draw framebuffer. The *s* least significant bits of *mask* are bitwise ANDed with both the reference and the stored stencil value, and the resulting masked values are those that participate in the comparison controlled by

*func*. *func* is a symbolic constant that determines the stencil comparison function; the eight symbolic constants are NEVER, ALWAYS, LESS, LEQUAL, EQUAL, GEQUAL, GREATER, or NOTEQUAL. Accordingly, the stencil test passes never, always, and if the masked reference value is less than, less than or equal to, equal to, greater than or equal to, greater than, or not equal to the masked stored value in the stencil buffer.

**StencilOp** and **StencilOpSeparate** take three arguments that indicate what happens to the stored stencil value if this or certain subsequent tests fail or pass. *sfail* indicates what action is taken if the stencil test fails. The symbolic constants are KEEP, ZERO, REPLACE, INCR, DECR, INVERT, INCR\_WRAP, and DECR\_WRAP. These correspond to keeping the current value, setting to zero, replacing with the reference value, incrementing with saturation, decrementing with saturation, bit-wise inverting it, incrementing without saturation, and decrementing without saturation.

For purposes of increment and decrement, the stencil bits are considered as an unsigned integer. Incrementing or decrementing with saturation clamps the stencil value at 0 and the maximum representable value. Incrementing or decrementing without saturation will wrap such that incrementing the maximum representable value results in 0, and decrementing 0 results in the maximum representable value.

The same symbolic values are given to indicate the stencil action if the depth buffer test (see section 17.3.6) fails (*dpfail*), or if it passes (*dppass*).

If the stencil test fails, the incoming fragment is discarded. The state required consists of the most recent values passed to **StencilFunc** or **StencilFuncSeparate** and to **StencilOp** or **StencilOpSeparate**, and a bit indicating whether stencil testing is enabled or disabled. In the initial state, stenciling is disabled, the front and back stencil reference value are both zero, the front and back stencil comparison functions are both ALWAYS, and the front and back stencil mask are both set to the value  $2^s - 1$ , where  $s$  is greater than or equal to the number of bits in the deepest stencil buffer supported by the GL implementation. Initially, all three front and back stencil operations are KEEP.

If there is no stencil buffer, no stencil modification can occur, and it is as if the stencil tests always pass, regardless of any calls to **StencilFunc**.

### 17.3.6 Depth Buffer Test

The depth buffer test discards the incoming fragment if a depth comparison fails. The comparison is enabled or disabled with the generic **Enable** and **Disable** commands using the symbolic constant DEPTH\_TEST. When disabled, the depth comparison and subsequent possible updates to the depth buffer value are bypassed and the fragment is passed to the next operation. The stencil value, however, is modi-

fied as indicated below as if the depth buffer test passed. If enabled, the comparison takes place and the depth buffer and stencil value may subsequently be modified.

The comparison is specified with

```
void DepthFunc( enum func );
```

This command takes a single symbolic constant: one of NEVER, ALWAYS, LESS, LEQUAL, EQUAL, GREATER, GEQUAL, NOTEQUAL. Accordingly, the depth buffer test passes never, always, if the incoming fragment's  $z_w$  value is less than, less than or equal to, equal to, greater than, greater than or equal to, or not equal to the depth value stored at the location given by the incoming fragment's  $(x_w, y_w)$  coordinates.

If depth clamping (see section 13.5) is enabled, before the incoming fragment's  $z_w$  is compared  $z_w$  is clamped to the range  $[\min(n, f), \max(n, f)]$ , where  $n$  and  $f$  are the current near and far depth range values (see section 13.6.1)

If the depth buffer test fails, the incoming fragment is discarded. The stencil value at the fragment's  $(x_w, y_w)$  coordinates is updated according to the function currently in effect for depth buffer test failure. Otherwise, the fragment continues to the next operation and the value of the depth buffer at the fragment's  $(x_w, y_w)$  location is set to the fragment's  $z_w$  value. In this case the stencil value is updated according to the function currently in effect for depth buffer test success.

The necessary state is an eight-valued integer and a single bit indicating whether depth buffering is enabled or disabled. In the initial state the function is LESS and the test is disabled.

If there is no depth buffer, it is as if the depth buffer test always passes.

### 17.3.7 Occlusion Queries

Occlusion queries use query objects to track the number of fragments or samples that pass the depth test. An occlusion query can be started and finished by calling **BeginQuery** and **EndQuery**, respectively, with a *target* of SAMPLES\_PASSED, ANY\_SAMPLES\_PASSED, or ANY\_SAMPLES\_PASSED\_CONSERVATIVE.

When an occlusion query is started with *target* SAMPLES\_PASSED, the samples-passed count maintained by the GL is set to zero. When an occlusion query is active, the samples-passed count is incremented for each fragment that passes the depth test. If the value of SAMPLE\_BUFFERS is 0, then the samples-passed count is incremented by 1 for each fragment. If the value of SAMPLE\_BUFFERS is 1, then the samples-passed count is incremented by the number of samples whose coverage bit is set. However, implementations, at their discretion, may instead increase the samples-passed count by the value of SAMPLES if any sample in the fragment is covered.

When an occlusion query finishes and all fragments generated by commands issued prior to **EndQuery** have been generated, the samples-passed count is written to the corresponding query object as the query result value, and the query result for that object is marked as available.

When an occlusion query is started with the target `ANY_SAMPLES_PASSED`, the samples-boolean state maintained by the GL is set to `FALSE`. While that occlusion query is active, the samples-boolean state is set to `TRUE` if any fragment or sample passes the depth test. When the target is `ANY_SAMPLES_PASSED_CONSERVATIVE`, an implementation may choose to use a less precise version of the test which can additionally set the samples-boolean state to `TRUE` in some other implementation-dependent cases. This may offer better performance on some implementations at the expense of false positives. When the occlusion query finishes, the samples-boolean state of `FALSE` or `TRUE` is written to the corresponding query object as the query result value, and the query result for that object is marked as available.

### 17.3.8 Blending

Blending combines the incoming *source* fragment's R, G, B, and A values with the *destination* R, G, B, and A values stored in the framebuffer at the fragment's  $(x_w, y_w)$  location.

Source and destination values are combined according to the *blend equation*, quadruplets of source and destination weighting factors determined by the *blend functions*, and a constant *blend color* to obtain a new set of R, G, B, and A values, as described below.

If the color buffer is fixed-point, the components of the source and destination values and blend factors are each clamped to  $[0, 1]$  or  $[-1, 1]$  respectively for an unsigned normalized or signed normalized color buffer prior to evaluating the blend equation. If the color buffer is floating-point, no clamping occurs. The resulting four values are sent to the next operation.

Blending applies only if the color buffer has a fixed-point or floating-point format. If the color buffer has an integer format, proceed to the next operation.

Blending is enabled or disabled for an individual draw buffer with the commands

```
void Enablei( enum target, uint index );
void Disablei( enum target, uint index );
```

*target* is the symbolic constant `BLEND` and *index* is an integer *i* specifying the draw buffer associated with the symbolic constant `DRAW_BUFFERi`. If the color buffer

associated with `DRAW_BUFFERi` is one of `FRONT`, `BACK`, `LEFT`, `RIGHT`, or `FRONT_AND_BACK` (specifying multiple color buffers), then the state enabled or disabled is applicable for all of the buffers. Blending can be enabled or disabled for all draw buffers using **Enable** or **Disable** with the symbolic constant `BLEND`. If blending is disabled for a particular draw buffer, or if logical operation on color values is enabled (section 17.3.11), proceed to the next operation.

If multiple fragment colors are being written to multiple buffers (see section 17.4.1), blending is computed and applied separately for each fragment color and the corresponding buffer.

### Errors

An `INVALID_VALUE` error is generated by **Enable*i***, **Disable*i*** and **IsEnabled*i*** if *target* is `BLEND` and *index* is greater than or equal to the value of `MAX_DRAW_BUFFERS`.

#### 17.3.8.1 Blend Equation

Blending is controlled by the blend equation. This equation can be simultaneously set to the same value for all draw buffers using the commands

```
void BlendEquation( enum mode );
void BlendEquationSeparate( enum modeRGB,
                             enum modeAlpha );
```

or for an individual draw buffer using the indexed commands

```
void BlendEquationi( uint buf, enum mode );
void BlendEquationSeparatei( uint buf, enum modeRGB,
                              enum modeAlpha );
```

**BlendEquationSeparate** and **BlendEquationSeparatei** argument *modeRGB* determines the RGB blend equation while *modeAlpha* determines the alpha blend equation. **BlendEquation** and **BlendEquationi** argument *mode* determines both the RGB and alpha blend equations. *mode*, *modeRGB*, and *modeAlpha* must be one of the blend equation modes in table 17.1. **BlendEquation** and **BlendEquationSeparate** modify the blend equations for all draw buffers. **BlendEquationi** and **BlendEquationSeparatei** modify the blend equations associated with an individual draw buffer. The *buf* argument is an integer *i* that indicates that the blend equations should be modified for `DRAW_BUFFERi`.

**Errors**

An `INVALID_VALUE` error is generated if *buf* is not in the range zero to the value of `MAX_DRAW_BUFFERS` minus one.

An `INVALID_VALUE` error is generated if any of *mode*, *modeRGB*, or *modeAlpha* are not one of the blend equation modes in table 17.1.

Signed or unsigned normalized fixed-point destination (framebuffer) components are represented as described in section 2.3.4. Constant color components, floating-point destination components, and source (fragment) components are taken to be floating-point values. If source components are represented internally by the GL as fixed-point values, they are also interpreted according to section 2.3.4.

Prior to blending, signed and unsigned normalized fixed-point color components undergo an implied conversion to floating-point using equations 2.2 and 2.1, respectively. This conversion must leave the values 0 and 1 invariant. Blending computations are treated as if carried out in floating-point, and will be performed with a precision and dynamic range no lower than that used to represent destination components.

If `FRAMEBUFFER_SRGB` is enabled and the value of `FRAMEBUFFER_ATTACHMENT_COLOR_ENCODING` for the framebuffer attachment corresponding to the destination buffer is `SRGB` (see section 9.2.3), the R, G, and B destination color values (after conversion from fixed-point to floating-point) are considered to be encoded for the sRGB color space and hence must be linearized prior to their use in blending. Each R, G, and B component is converted in the same fashion described for sRGB texture components in section 8.23.

If `FRAMEBUFFER_SRGB` is disabled or the value of `FRAMEBUFFER_ATTACHMENT_COLOR_ENCODING` is not `SRGB`, no linearization is performed.

The resulting linearized R, G, and B and unmodified A values are recombined as the destination color used in blending computations.

Table 17.1 provides the corresponding per-component blend equations for each mode, whether acting on RGB components for *modeRGB* or the alpha component for *modeAlpha*.

In the table, the *s* subscript on a color component abbreviation (R, G, B, or A) refers to the source color component for an incoming fragment, the *d* subscript on a color component abbreviation refers to the destination color component at the corresponding framebuffer location, and the *c* subscript on a color component abbreviation refers to the constant blend color component. A color component abbreviation without a subscript refers to the new color component resulting from blending. Additionally,  $S_r$ ,  $S_g$ ,  $S_b$ , and  $S_a$  are the red, green, blue, and alpha com-

Mode	RGB Components	Alpha Component
FUNC_ADD	$R = R_s * S_r + R_d * D_r$ $G = G_s * S_g + G_d * D_g$ $B = B_s * S_b + B_d * D_b$	$A = A_s * S_a + A_d * D_a$
FUNC_SUBTRACT	$R = R_s * S_r - R_d * D_r$ $G = G_s * S_g - G_d * D_g$ $B = B_s * S_b - B_d * D_b$	$A = A_s * S_a - A_d * D_a$
FUNC_REVERSE_SUBTRACT	$R = R_d * D_r - R_s * S_r$ $G = G_d * D_g - G_s * S_g$ $B = B_d * D_b - B_s * S_b$	$A = A_d * D_a - A_s * S_a$
MIN	$R = \min(R_s, R_d)$ $G = \min(G_s, G_d)$ $B = \min(B_s, B_d)$	$A = \min(A_s, A_d)$
MAX	$R = \max(R_s, R_d)$ $G = \max(G_s, G_d)$ $B = \max(B_s, B_d)$	$A = \max(A_s, A_d)$

Table 17.1: RGB and alpha blend equations.

ponents of the source weighting factors determined by the source blend function, and  $D_r$ ,  $D_g$ ,  $D_b$ , and  $D_a$  are the red, green, blue, and alpha components of the destination weighting factors determined by the destination blend function. Blend functions are described below.

### 17.3.8.2 Blend Functions

The weighting factors used by the blend equation are determined by the blend functions. There are four possible sources for weighting factors. These are the constant color ( $R_c, G_c, B_c, A_c$ ) set with **BlendColor** (see below), the first source color ( $R_{s0}, G_{s0}, B_{s0}, A_{s0}$ ), the second source color ( $R_{s1}, G_{s1}, B_{s1}, A_{s1}$ ), and the destination color (the existing content of the draw buffer). Additionally the special constants ZERO and ONE are available as weighting factors.

Blend functions are simultaneously specified for all draw buffers using the commands

```
void BlendFunc( enum src, enum dst );
void BlendFuncSeparate( enum srcRGB, enum dstRGB,
    enum srcAlpha, enum dstAlpha );
```

or for an individual draw buffer using the indexed commands

```
void BlendFunci(uint buf, enum src, enum dst);
void BlendFuncSeparatei(uint buf, enum srcRGB,
    enum dstRGB, enum srcAlpha, enum dstAlpha);
```

**BlendFuncSeparate** and **BlendFuncSeparatei** arguments *srcRGB* and *dstRGB* determine the source and destination RGB blend functions, respectively, while *srcAlpha* and *dstAlpha* determine the source and destination alpha blend functions. **BlendFunc** and **BlendFunci** argument *src* determines both RGB and alpha source functions, while *dst* determines both RGB and alpha destination functions. **BlendFuncSeparate** and **BlendFunc** modify the blend functions for all draw buffers. **BlendFuncSeparatei** and **BlendFunci** modify the blend functions associated with an individual draw buffer. The *buf* argument is an integer *i* that indicates that the blend equations should be modified for `DRAW_BUFFERi`.

The possible source and destination blend functions and their corresponding computed blend factors are summarized in table 17.2.

#### Errors

An `INVALID_VALUE` error is generated if *buf* is not in the range zero to the value of `MAX_DRAW_BUFFERS` minus one.

An `INVALID_VALUE` error is generated if any of *src*, *dst*, *srcRGB*, *dstRGB*, *srcAlpha*, or *dstAlpha* are not one of the blend functions in table 17.2.

#### 17.3.8.3 Dual Source Blending and Multiple Draw Buffers

Blend functions that require the second color input,  $(R_{s1}, G_{s1}, B_{s1}, A_{s1})$  (`SRC1_COLOR`, `SRC1_ALPHA`, `ONE_MINUS_SRC1_COLOR`, or `ONE_MINUS_SRC1_ALPHA`) may consume hardware resources that could otherwise be used for rendering to multiple draw buffers. Therefore, the number of draw buffers that can be attached to a frame buffer may be lower when using dual-source blending.

The maximum number of draw buffers that may be attached to a single frame buffer when using dual-source blending functions is implementation dependent and can be queried by calling **GetIntegerv** with the symbolic constant `MAX_DUAL_SOURCE_DRAW_BUFFERS`. When using dual-source blending, `MAX_DUAL_SOURCE_DRAW_BUFFERS` should be used in place of `MAX_DRAW_BUFFERS` to determine the maximum number of draw buffers that may be attached to a single frame buffer. The value of `MAX_DUAL_SOURCE_DRAW_BUFFERS` must be at least 1. If the value of `MAX_DUAL_SOURCE_DRAW_BUFFERS` is 1, then dual-source blending and multiple draw buffers cannot be used simultaneously.

An `INVALID_OPERATION` error is generated by any command that transfers vertices to the GL if either blend function requires the second color input for any



Function	RGB Blend Factors ( $S_r, S_g, S_b$ ) or ( $D_r, D_g, D_b$ )	Alpha Blend Factor $S_a$ or $D_a$
ZERO	(0, 0, 0)	0
ONE	(1, 1, 1)	1
SRC_COLOR	( $R_{s0}, G_{s0}, B_{s0}$ )	$A_{s0}$
ONE_MINUS_SRC_COLOR	$(1, 1, 1) - (R_{s0}, G_{s0}, B_{s0})$	$1 - A_{s0}$
DST_COLOR	( $R_d, G_d, B_d$ )	$A_d$
ONE_MINUS_DST_COLOR	$(1, 1, 1) - (R_d, G_d, B_d)$	$1 - A_d$
SRC_ALPHA	( $A_{s0}, A_{s0}, A_{s0}$ )	$A_{s0}$
ONE_MINUS_SRC_ALPHA	$(1, 1, 1) - (A_{s0}, A_{s0}, A_{s0})$	$1 - A_{s0}$
DST_ALPHA	( $A_d, A_d, A_d$ )	$A_d$
ONE_MINUS_DST_ALPHA	$(1, 1, 1) - (A_d, A_d, A_d)$	$1 - A_d$
CONSTANT_COLOR	( $R_c, G_c, B_c$ )	$A_c$
ONE_MINUS_CONSTANT_COLOR	$(1, 1, 1) - (R_c, G_c, B_c)$	$1 - A_c$
CONSTANT_ALPHA	( $A_c, A_c, A_c$ )	$A_c$
ONE_MINUS_CONSTANT_ALPHA	$(1, 1, 1) - (A_c, A_c, A_c)$	$1 - A_c$
SRC_ALPHA_SATURATE	( $f, f, f$ ) <sup>1</sup>	1
SRC1_COLOR	( $R_{s1}, G_{s1}, B_{s1}$ )	$A_{s1}$
ONE_MINUS_SRC1_COLOR	$(1, 1, 1) - (R_{s1}, G_{s1}, B_{s1})$	$1 - A_{s1}$
SRC1_ALPHA	( $A_{s1}, A_{s1}, A_{s1}$ )	$A_{s1}$
ONE_MINUS_SRC1_ALPHA	$(1, 1, 1) - (A_{s1}, A_{s1}, A_{s1})$	$1 - A_{s1}$

Table 17.2: RGB and ALPHA source and destination blending functions and the corresponding blend factors. Addition and subtraction of triplets is performed component-wise.

<sup>1</sup>  $f = \min(A_{s0}, 1 - A_d)$ .

draw buffer, and any draw buffers greater than or equal to the value of `MAX_DUAL_SOURCE_DRAW_BUFFERS` have values other than `NONE`.

#### 17.3.8.4 Generation of Second Color Source for Blending

When using a fragment shader with dual-source blending functions, the color outputs are bound to the first and second inputs of a draw buffer using **BindFrag-DataLocationIndexed** as described in section 15.2.3. Data written to the first of these outputs becomes the first source color input to the blender (corresponding to `SRC_COLOR` and `SRC_ALPHA`). Data written to the second of these outputs generates the second source color input to the blender (corresponding to `SRC1_COLOR` and `SRC1_ALPHA`).

If the second color input to the blender is not written in the shader, or if no output is bound to the second input of a blender, the result of the blending operation is not defined.

#### 17.3.8.5 Blend Color

The constant color  $C_c$  to be used in blending is specified with the command

```
void BlendColor( float red, float green, float blue,  
                  float alpha );
```

The constant color can be used in both the source and destination blending functions. If destination framebuffer components use an unsigned normalized fixed-point representation, the constant color components are clamped to the range  $[0, 1]$  when computing blend factors.

#### 17.3.8.6 Blending State

The state required for blending, for each draw buffer, is two integers for the RGB and alpha blend equations, four integers indicating the source and destination RGB and alpha blending functions, and a bit indicating whether blending is enabled or disabled. Additionally, four floating-point values to store the RGBA constant blend color are required.

For all draw buffers, the initial blend equations for RGB and alpha are both `FUNC_ADD`, and the initial blending functions are `ONE` for the source RGB and alpha functions and `ZERO` for the destination RGB and alpha functions. Initially, blending is disabled for all draw buffers. The initial constant blend color is  $(R, G, B, A) = (0, 0, 0, 0)$ .

The value of the blend enable for draw buffer  $i$  can be queried by calling **IsEnabledi** with *target* BLEND and *index*  $i$ , and the values of the blend equations and functions can be queried by calling **GetIntegeri\_v** with the corresponding *target* as shown in table 23.21 and *index*  $i$ .

The value of the blend enable, or the blend equations and functions for draw buffer zero may also be queried by calling **IsEnabled**, or **GetInteger**, respectively, with the same symbolic constants but no *index* parameter.

Blending occurs once for each color buffer currently enabled for blending and for writing (section 17.4.1) using each buffer's color for  $C_d$ . If a color buffer has no  $A$  value, then  $A_d$  is taken to be 1.

### 17.3.9 sRGB Conversion

If FRAMEBUFFER\_SRGB is enabled and the value of FRAMEBUFFER\_ATTACHMENT\_COLOR\_ENCODING for the framebuffer attachment corresponding to the destination buffer is SRGB<sup>1</sup> (see section 9.2.3), the R, G, and B values after blending are converted into the non-linear sRGB color space by computing

$$c_s = \begin{cases} 0.0, & c_l \leq 0 \\ 12.92c_l, & 0 < c_l < 0.0031308 \\ 1.055c_l^{0.41666} - 0.055, & 0.0031308 \leq c_l < 1 \\ 1.0, & c_l \geq 1 \end{cases} \quad (17.1)$$

where  $c_l$  is the R, G, or B element and  $c_s$  is the result (effectively converted into an sRGB color space).

If FRAMEBUFFER\_SRGB is disabled or the value of FRAMEBUFFER\_ATTACHMENT\_COLOR\_ENCODING is not SRGB, then

$$c_s = c_l.$$

The resulting  $c_s$  values for R, G, and B, and the unmodified A form a new RGBA color value. If the color buffer is fixed-point, each component is clamped to the range  $[0, 1]$  and then converted to a fixed-point value using equation 2.3. The resulting four values are sent to the subsequent dithering operation.

### 17.3.10 Dithering

Dithering selects between two representable color values or indices. A representable value is a value that has an exact representation in the color buffer. Dither-

<sup>1</sup>Note that only unsigned normalized fixed-point color buffers may be SRGB-encoded. Signed normalized fixed-point + SRGB encoding is not defined.

ing selects, for each color component, either the largest representable color value (for that particular color component) that is less than or equal to the incoming color component value,  $c$ , or the smallest representable color value that is greater than or equal to  $c$ . The selection may depend on the  $x_w$  and  $y_w$  coordinates of the pixel, as well as on the exact value of  $c$ . If one of the two values does not exist, then the selection defaults to the other value.

Many dithering selection algorithms are possible, but an individual selection must depend only on the incoming component value and the fragment's  $x$  and  $y$  window coordinates. If dithering is disabled, then one of the two values above is selected, in an implementation-dependent manner that must not depend on the  $x_w$  and  $y_w$  coordinates of the pixel.

Dithering is enabled with **Enable** and disabled with **Disable** using the symbolic constant `DITHER`. The state required is thus a single bit. Initially, dithering is enabled.

### 17.3.11 Logical Operation

Finally, a logical operation is applied between the incoming fragment's color values and the color values stored at the corresponding location in the framebuffer. The result replaces the values in the framebuffer at the fragment's  $(x_w, y_w)$  coordinates. If the selected draw buffers refer to the same framebuffer-attachable image more than once, then the values stored in that image are undefined.

The logical operation on color values is enabled or disabled with **Enable** or **Disable** using the symbolic constant `COLOR_LOGIC_OP`. If the logical operation is enabled for color values, it is as if blending were disabled, regardless of the value of `BLEND`. If multiple fragment colors are being written to multiple buffers (see section 17.4.1), the logical operation is computed and applied separately for each fragment color and the corresponding buffer.

Logical operation has no effect on a floating-point destination color buffer, or when `FRAMEBUFFER_SRGB` is enabled and the value of `FRAMEBUFFER_ATTACHMENT_COLOR_ENCODING` for the framebuffer attachment corresponding to the destination buffer is `SRGB` (see section 9.2.3). However, if logical operation is enabled, blending is still disabled.

The logical operation is selected by

```
void LogicOp( enum op );
```

*op* must be one of the logicop modes in table 17.3, which also describes the resulting operation when that mode is selected. *s* is the value of the incoming fragment and *d* is the value stored in the framebuffer.

Logicop Mode	Operation
CLEAR	0
AND	$s \wedge d$
AND_REVERSE	$s \wedge \neg d$
COPY	$s$
AND_INVERTED	$\neg s \wedge d$
NOOP	$d$
XOR	$s \text{ xor } d$
OR	$s \vee d$
NOR	$\neg(s \vee d)$
EQUIV	$\neg(s \text{ xor } d)$
INVERT	$\neg d$
OR_REVERSE	$s \vee \neg d$
COPY_INVERTED	$\neg s$
OR_INVERTED	$\neg s \vee d$
NAND	$\neg(s \wedge d)$
SET	all 1's

Table 17.3: Logical operation *op* arguments to **LogicOp** and their corresponding operations.

Logical operations are performed independently for each red, green, blue, and alpha value of each color buffer that is selected for writing. The required state is an integer indicating the logical operation, and a bit indicating whether the logical operation is enabled or disabled. The initial state is for the logic operation to be given by `COPY`, and to be disabled.

#### Errors

An `INVALID_VALUE` error is generated if *op* is not one of the logicop modes in table 17.3.

### 17.3.12 Additional Multisample Fragment Operations

If the **DrawBuffer** mode is `NONE`, no change is made to any multisample or color buffer. Otherwise, fragment processing is as described below.

If `MULTISAMPLE` is enabled, and the value of `SAMPLE_BUFFERS` is one, the stencil test, depth test, blending, dithering, and logical operations are performed for each pixel sample, rather than just once for each fragment. Failure of the stencil or depth test results in termination of the processing of that sample, rather than discarding of the fragment. All operations are performed on the color, depth, and stencil values stored in the multisample renderbuffer attachments if a draw framebuffer object is bound, or otherwise in the multisample buffer of the default framebuffer. The contents of the color buffers are not modified at this point.

Stencil, depth, blending, dithering, and logical operations are performed for a pixel sample only if that sample's fragment coverage bit is a value of 1. If the corresponding coverage bit is 0, no operations are performed for that sample.

If `MULTISAMPLE` is disabled, and the value of `SAMPLE_BUFFERS` is one, the fragment may be treated exactly as described above, with optimization possible because the fragment coverage must be set to full coverage. Further optimization is allowed, however. An implementation may choose to identify a centermost sample, and to perform stencil and depth tests on only that sample. Regardless of the outcome of the stencil test, all multisample buffer stencil sample values are set to the appropriate new stencil value. If the depth test passes, all multisample buffer depth sample values are set to the depth of the fragment's centermost sample's depth value, and all multisample buffer color sample values are set to the color value of the incoming fragment. Otherwise, no change is made to any multisample buffer color or depth value.

If a draw framebuffer object is not bound, after all operations have been completed on the multisample buffer, the sample values for each color in the multisample buffer are combined to produce a single color value, and that value is written

into the corresponding color buffers selected by **DrawBuffer** or **DrawBuffers**. An implementation may defer the writing of the color buffers until a later time, but the state of the framebuffer must behave as if the color buffers were updated as each fragment was processed. The method of combination is not specified. If the framebuffer contains sRGB values, then it is recommended that the an average of sample values is computed in a linearized space, as for blending (see section 17.3.8). Otherwise, a simple average computed independently for each color component is recommended.

## 17.4 Whole Framebuffer Operations

The preceding sections described the operations that occur as individual fragments are sent to the framebuffer. This section describes operations that control or affect the whole framebuffer.

### 17.4.1 Selecting Buffers for Writing

The first such operation is controlling the color buffers into which each of the fragment color values is written. This is accomplished with either **DrawBuffer** or **DrawBuffers**.

The command

```
void DrawBuffer( enum buf );
```

defines the set of color buffers to which fragment color zero is written. *buf* must be one of the values from tables 17.4 or 17.5. In addition, acceptable values for *buf* depend on whether the GL is using the default framebuffer (i.e., `DRAW_FRAMEBUFFER_BINDING` is zero), or a framebuffer object (i.e., `DRAW_FRAMEBUFFER_BINDING` is non-zero). In the initial state, the GL is bound to the default framebuffer. For more information about framebuffer objects, see section 9.

If the GL is bound to the default framebuffer, then *buf* must be one of the values listed in table 17.4, which summarizes the constants and the buffers they indicate. In this case, *buf* is a symbolic constant specifying zero, one, two, or four buffers for writing. These constants refer to the four potentially visible buffers (front left, front right, back left, and back right). Arguments that omit reference to `LEFT` or `RIGHT` refer to both left and right buffers. Arguments that omit reference to `FRONT` or `BACK` refer to both front and back buffers.

If the GL is bound to a draw framebuffer object, *buf* must be one of the values listed in table 17.5, which summarizes the constants and the buffers they indicate. In this case, *buf* is a symbolic constant specifying a single color buffer for writing.

Symbolic Constant	Front Left	Front Right	Back Left	Back Right
NONE				
FRONT_LEFT	•			
FRONT_RIGHT		•		
BACK_LEFT			•	
BACK_RIGHT				•
FRONT	•	•		
BACK			•	•
LEFT	•		•	
RIGHT		•		•
FRONT_AND_BACK	•	•	•	•

Table 17.4: Arguments to **DrawBuffer** and **ReadBuffer** when the context is bound to a default framebuffer, and the buffers they indicate.

Specifying `COLOR_ATTACHMENTi` enables drawing only to the image attached to the framebuffer at `COLOR_ATTACHMENTi`. Each `COLOR_ATTACHMENTi` adheres to `COLOR_ATTACHMENTi = COLOR_ATTACHMENT0 + i`. The initial value of `DRAW_BUFFER` for framebuffer objects is `COLOR_ATTACHMENT0`.

### Errors

An `INVALID_ENUM` error is generated if `buf` is not one of the values in tables 17.5 or 17.6.

An `INVALID_OPERATION` error is generated if the GL is bound to the default framebuffer and `buf` is a value (other than `NONE`) that does not indicate any of the color buffers allocated to the GL context,

An `INVALID_OPERATION` error is generated if the GL is bound to a draw framebuffer object and `buf` is one of the constants from table 17.4 (other than `NONE`).

An `INVALID_OPERATION` error is generated if `buf` is `COLOR_ATTACHMENTm` and `m` is greater than or equal to the value of `MAX_COLOR_ATTACHMENTS`,

**DrawBuffer** will set the draw buffer for fragment colors other than zero to `NONE`.

The command



Symbolic Constant	Meaning
NONE	No buffer
COLOR_ATTACHMENT <i>i</i> (see caption)	Output fragment color to image attached at color attachment point <i>i</i>

Table 17.5: Arguments to **DrawBuffer(s)** and **ReadBuffer** when the context is bound to a framebuffer object, and the buffers they indicate. *i* in COLOR\_ATTACHMENT*i* may range from zero to the value of MAX\_COLOR\_ATTACHMENTS minus one.

Symbolic Constant	Front Left	Front Right	Back Left	Back Right
NONE				
FRONT_LEFT	•			
FRONT_RIGHT		•		
BACK_LEFT			•	
BACK_RIGHT				•

Table 17.6: Arguments to **DrawBuffers** when the context is bound to the default framebuffer, and the buffers they indicate.

```
void DrawBuffers(size_t n, const enum *bufs);
```

defines the draw buffers to which all fragment colors are written. *n* specifies the number of buffers in *bufs*. *bufs* is a pointer to an array of symbolic constants specifying the buffer to which each fragment color is written.

Each buffer listed in *bufs* must be one of the values from tables 17.5 or 17.6. Further, acceptable values for the constants in *bufs* depend on whether the GL is using the default framebuffer (i.e., DRAW\_FRAMEBUFFER\_BINDING is zero), or a framebuffer object (i.e., DRAW\_FRAMEBUFFER\_BINDING is non-zero). For more information about framebuffer objects, see section 9.

If the GL is bound to the default framebuffer, then each of the constants must be one of the values listed in table 17.6.

If the GL is bound to a draw framebuffer object, then each of the constants must be one of the values listed in table 17.5.

In both cases, the draw buffers being defined correspond in order to the respective fragment colors. The draw buffer for fragment colors beyond *n* is set to NONE.

The maximum number of draw buffers is implementation-dependent. The number of draw buffers supported can be queried by calling **GetIntegerv** with the symbolic constant `MAX_DRAW_BUFFERS`.

Except for `NONE`, a buffer may not appear more than once in the array pointed to by *bufs*.

If a fragment shader writes to a user-defined output variable, **DrawBuffers** specifies a set of draw buffers into which each of the multiple output colors defined by these variables are separately written. If a fragment shader writes to no user-defined output variables, the values of the fragment colors following shader execution are undefined, and may differ for each fragment color. *If some, but not all user-defined output variables are written, the values of fragment colors corresponding to unwritten variables are similarly undefined.*

### Errors

An `INVALID_VALUE` error is generated if *n* is negative, or greater than the value of `MAX_DRAW_BUFFERS`.

An `INVALID_ENUM` error is generated if any value in *bufs* is not one of the values in tables 17.5 or 17.6.

An `INVALID_OPERATION` error is generated if a buffer other than `NONE` is specified more than once in the array pointed to by *bufs*.

An `INVALID_ENUM` error is generated if any of the constants `FRONT`, `BACK`, `LEFT`, `RIGHT`, or `FRONT_AND_BACK` are present in the *bufs* array passed to **DrawBuffers**. This restriction applies to both the default framebuffer and framebuffer objects, and exists because these constants may themselves refer to multiple buffers, as shown in table 17.4.

An `INVALID_OPERATION` error is generated if the GL is bound to the default framebuffer and **DrawBuffers** is supplied with a constant (other than `NONE`) that does not indicate any of the color buffers allocated to the GL context by the window system,

An `INVALID_OPERATION` error is generated if the GL is bound to a draw framebuffer object and **DrawBuffers** is supplied with a constant from table 17.6, or `COLOR_ATTACHMENTm` where *m* is greater than or equal to the value of `MAX_COLOR_ATTACHMENTS`.

Indicating a buffer or buffers using **DrawBuffer** or **DrawBuffers** causes subsequent pixel color value writes to affect the indicated buffers. If the GL is bound to a draw framebuffer object and a draw buffer selects an attachment that has no image attached, then that fragment color is not written. *to any buffer:*

Specifying `NONE` as the draw buffer for a fragment color will inhibit that frag-

ment color from being written. [to any buffer.](#)

Monoscopic contexts include only left buffers, while stereoscopic contexts include both left and right buffers. Likewise, single buffered contexts include only front buffers, while double buffered contexts include both front and back buffers. The type of context is selected at GL initialization.

The state required to handle color buffer selection for each framebuffer is an integer for each supported fragment color. For the default framebuffer, in the initial state the draw buffer for fragment color zero is `BACK` if there is a back buffer; `FRONT` if there is no back buffer; and `NONE` if no default framebuffer is associated with the context. For framebuffer objects, in the initial state the draw buffer for fragment color zero is `COLOR_ATTACHMENT0`. For both the default framebuffer and framebuffer objects, the initial state of draw buffers for fragment colors other than zero is `NONE`.

The value of the draw buffer selected for fragment color *i* can be queried by calling `GetIntegerv` with the symbolic constant `DRAW_BUFFERi`. `DRAW_BUFFER` is equivalent to `DRAW_BUFFER0`.

### 17.4.2 Fine Control of Buffer Updates

Writing of bits to each of the logical framebuffers after all per-fragment operations have been performed may be *masked*. The commands

```
void ColorMask(boolean r, boolean g, boolean b,
                boolean a);
void ColorMaski(uint buf, boolean r, boolean g,
                 boolean b, boolean a);
```

control writes to the active draw buffers.

`ColorMask` and `ColorMaski` are used to mask the writing of R, G, B and A values to the draw buffer or buffers. `ColorMaski` sets the mask for a particular draw buffer. The mask for `DRAW_BUFFERi` is modified by passing *i* as the parameter *buf*. *r*, *g*, *b*, and *a* indicate whether R, G, B, or A values, respectively, are written or not (a value of `TRUE` means that the corresponding value is written). The mask specified by *r*, *g*, *b*, and *a* is applied to the color buffer associated with `DRAW_BUFFERi`. If `DRAW_BUFFERi` is one of `FRONT`, `BACK`, `LEFT`, `RIGHT`, or `FRONT_AND_BACK` (specifying multiple color buffers) then the mask is applied to all of the buffers.

`ColorMask` sets the mask for all draw buffers to the same values as specified by *r*, *g*, *b*, and *a*.

An `INVALID_VALUE` error is generated if *index* is greater than the value of `MAX_DRAW_BUFFERS` minus one.

In the initial state, all color values are enabled for writing for all draw buffers.

The value of the color writemask for draw buffer *i* can be queried by calling **GetBooleani\_v** with *target* COLOR\_WRITEMASK and *index* *i*. The value of the color writemask for draw buffer zero may also be queried by calling **GetBooleanv** with the symbolic constant COLOR\_WRITEMASK.

The depth buffer can be enabled or disabled for writing  $z_w$  values using

```
void DepthMask( boolean mask );
```

If *mask* is non-zero, the depth buffer is enabled for writing; otherwise, it is disabled. In the initial state, the depth buffer is enabled for writing.

The commands

```
void StencilMask( uint mask );
void StencilMaskSeparate( enum face, uint mask );
```

control the writing of particular bits into the stencil planes.

The least significant *s* bits of *mask*, where *s* is the number of bits in the stencil buffer, specify an integer mask. Where a 1 appears in this mask, the corresponding bit in the stencil buffer is written; where a 0 appears, the bit is not written. The *face* parameter of **StencilMaskSeparate** can be FRONT, BACK, or FRONT\_AND\_BACK and indicates whether the front or back stencil mask state is affected. **StencilMask** sets both front and back stencil mask state to identical values.

Fragments generated by front-facing primitives use the front mask and fragments generated by back-facing primitives use the back mask (see section 17.3.5). The clear operation always uses the front stencil write mask when clearing the stencil buffer.

The state required for the various masking operations is two integers for the front and back stencil values, and a bit for depth values. A set of four bits is also required indicating which color components of an RGBA value should be written. In the initial state, the integer masks are all ones, as are the bits controlling depth value and RGBA component writing.

#### 17.4.2.1 Fine Control of Multisample Buffer Updates

When the value of SAMPLE\_BUFFERS is one, **ColorMask**, **DepthMask**, and **StencilMask** or **StencilMaskSeparate** control the modification of values in the multi-sample buffer. The color mask has no effect on modifications to the color buffers. If the color mask is entirely disabled, the color sample values must still be combined (as described above) and the result used to replace the color values of the buffers enabled by **DrawBuffer**.

### 17.4.3 Clearing the Buffers

The GL provides a means for setting portions of every pixel in a particular buffer to the same value. The argument to

```
void Clear(bitfield buf);
```

is zero or the bitwise OR of one or more values indicating which buffers are to be cleared. The values are `COLOR_BUFFER_BIT`, `DEPTH_BUFFER_BIT`, and `STENCIL_BUFFER_BIT`, indicating the buffers currently enabled for color writing, the depth buffer, and the stencil buffer (see below), respectively. The value to which each buffer is cleared depends on the setting of the clear value for that buffer. If *buf* is zero, no buffers are cleared.

#### Errors

An `INVALID_VALUE` error is generated if *buf* contains any bits other than `COLOR_BUFFER_BIT`, `DEPTH_BUFFER_BIT`, or `STENCIL_BUFFER_BIT`.

```
void ClearColor(float r, float g, float b, float a);
```

sets the clear value for fixed-point and floating-point color buffers. The specified components are stored as floating-point values.

The command

```
void ClearDepth(double d);  
void ClearDepthf(float d);
```

sets the depth value used when clearing the depth buffer. *d* is clamped to the range `[0, 1]` when specified. When clearing a fixed-point depth buffer, *d* is converted to fixed-point according to the rules for a window *z* value given in section 13.6.1. No conversion is applied when clearing a floating-point depth buffer.

The command

```
void ClearStencil(int s);
```

takes a single integer argument that is the value to which to clear the stencil buffer. *s* is masked to the number of bitplanes in the stencil buffer.

When **Clear** is called, the only per-fragment operations that are applied (if enabled) are the pixel ownership test, the scissor test, sRGB conversion (see section 17.3.9), and dithering. The masking operations described in section 17.4.2 are

also applied. If a buffer is not present, then a **Clear** directed at that buffer has no effect.

Unsigned normalized fixed-point and signed normalized fixed-point RGBA color buffers are cleared to color values derived by clamping each component of the clear color to the range  $[0, 1]$  or  $[-1, 1]$  respectively, then converting the (possibly sRGB converted and/or dithered) color to fixed-point using equations 2.3 or 2.4, respectively. The result of clearing integer color buffers is undefined.

The state required for clearing is a clear value for each of the color buffer, the depth buffer, and the stencil buffer. Initially, the RGBA color clear value is  $(0.0, 0.0, 0.0, 0.0)$ , the depth buffer clear value is 1.0, and the stencil buffer clear index is 0.

Individual buffers of the currently bound draw framebuffer may be cleared with the command

```
void ClearBuffer{if ui}v( enum buffer, int drawbuffer,
    const T *value );
```

where *buffer* and *drawbuffer* identify a buffer to clear, and *value* specifies the value or values to clear it to.

If *buffer* is COLOR, a particular draw buffer DRAW\_BUFFER*i* is specified by passing *i* as the parameter *drawbuffer*, and *value* points to a four-element vector specifying the R, G, B, and A color to clear that draw buffer to. If the draw buffer is one of FRONT, BACK, LEFT, RIGHT, or FRONT\_AND\_BACK, identifying multiple buffers, each selected buffer is cleared to the same value. The **ClearBufferfv**, **ClearBufferiv**, and **ClearBufferuiv** commands should be used to clear fixed- and floating-point, signed integer, and unsigned integer color buffers respectively. Clamping and conversion for fixed-point color buffers are performed in the same fashion as **ClearColor**.

If *buffer* is DEPTH, *drawbuffer* must be zero, and *value* points to the single depth value to clear the depth buffer to. Clamping and type conversion for fixed-point depth buffers are performed in the same fashion as **ClearDepth**. Only **ClearBufferfv** should be used to clear depth buffers.

If *buffer* is STENCIL, *drawbuffer* must be zero, and *value* points to the single stencil value to clear the stencil buffer to. Masking is performed in the same fashion as **ClearStencil**. Only **ClearBufferiv** should be used to clear stencil buffers.

The command

```
void ClearBufferfi( enum buffer, int drawbuffer,
    float depth, int stencil );
```

clears both depth and stencil buffers of the currently bound draw framebuffer. *buffer* must be `DEPTH_STENCIL` and *drawbuffer* must be zero. *depth* and *stencil* are the values to clear the depth and stencil buffers to, respectively. Clamping and type conversion of *depth* for fixed-point depth buffers is performed in the same fashion as **ClearDepth**. Masking of *stencil* for stencil buffers is performed in the same fashion as **ClearStencil**. **ClearBufferfi** is equivalent to clearing the depth and stencil buffers separately, but may be faster when a buffer of internal format `DEPTH_STENCIL` is being cleared.

The result of **ClearBuffer\*** is undefined if no conversion between the type of the specified *value* and the type of the buffer being cleared is defined (for example, if **ClearBufferiv** is called for a fixed- or floating-point buffer, or if **ClearBufferfv** is called for a signed or unsigned integer buffer). This is not an error.

When **ClearBuffer\*** is called, the same per-fragment and masking operations defined for **Clear** are applied.

#### Errors

An `INVALID_ENUM` error is generated by **ClearBuffer{if ui}v** if *buffer* is not `COLOR`, `DEPTH`, or `STENCIL`.

An `INVALID_ENUM` error is generated by **ClearBufferfi** if *buffer* is not `DEPTH_STENCIL`.

An `INVALID_VALUE` error is generated by **ClearBuffer\*** if *buffer* is `COLOR` and *drawbuffer* is negative, or greater than the value of `MAX_DRAW_BUFFERS` minus one; or if *buffer* is `DEPTH`, `STENCIL`, or `DEPTH_STENCIL` and *drawbuffer* is not zero.

#### 17.4.3.1 Clearing the Multisample Buffer

The color samples of the multisample buffer are cleared when one or more color buffers are cleared, as specified by the **Clear** mask bit `COLOR_BUFFER_BIT` and the **DrawBuffer** mode. If the **DrawBuffer** mode is `NONE`, the color samples of the multisample buffer cannot be cleared using **Clear**.

If the **Clear** mask bits `DEPTH_BUFFER_BIT` or `STENCIL_BUFFER_BIT` are set, then the corresponding depth or stencil samples, respectively, are cleared.

The **ClearBuffer** commands also clear color, depth, or stencil samples of multisample buffers corresponding to the specified buffer.

Masking and scissoring affect clearing the multisample buffer in the same way as they affect clearing the corresponding color, depth, and stencil buffers.

### 17.4.4 Invalidating Framebuffer Contents

The GL provides a means for invalidating portions of every pixel or a subregion of pixels in a particular buffer, effectively leaving their contents undefined. The command

```
void InvalidateSubFramebuffer( enum target,
                               sizei numAttachments, const enum *attachments, int x,
                               int y, sizei width, sizei height );
```

signals the GL that it need not preserve all contents of a bound framebuffer object. *numAttachments* indicates how many attachments are supplied in the *attachments* list. If an attachment is specified that does not exist in the framebuffer bound to *target*, it is ignored. *target* must be FRAMEBUFFER, DRAW\_FRAMEBUFFER, or READ\_FRAMEBUFFER. FRAMEBUFFER is treated as DRAW\_FRAMEBUFFER. *x* and *y* are the origin (with lower left-hand corner at (0, 0)) and *width* and *height* are the width and height, respectively, of the pixel rectangle to be invalidated. Any of these pixels lying outside of the window allocated to the current GL context, or outside of the attachments of the currently bound framebuffer object, are ignored.

If the framebuffer object is not complete, **InvalidateFramebuffer** may be ignored.

#### Errors

An INVALID\_ENUM error is generated if a framebuffer object is bound to *target* and any elements of *attachments* are not [one of the attachments in table 9.2](#).

An INVALID\_OPERATION error is generated if *attachments* contains COLOR\_ATTACHMENT $m$  where  $m$  is greater than or equal to the value of MAX\_COLOR\_ATTACHMENTS.

An INVALID\_VALUE error is generated if *numAttachments*, *width*, or *height* is negative.

An INVALID\_ENUM error is generated if the default framebuffer is bound to *target* and any elements of *attachments* are not one of:

- FRONT\_LEFT, FRONT\_RIGHT, BACK\_LEFT, and BACK\_RIGHT, identifying that specific buffer
- COLOR, which is treated as BACK\_LEFT for a double-buffered context and FRONT\_LEFT for a single-buffered context
- DEPTH, identifying the depth buffer



- STENCIL, identifying the stencil buffer.

The command

```
void InvalidateFramebuffer( enum target,  
                             sizei numAttachments, const enum *attachments );
```

is equivalent to

```
InvalidateSubFramebuffer (target, numAttachments, attachments,  
                            0, 0, vw, vh);
```

where `vw` and `vh` are equal to the maximum viewport width and height, respectively, obtained by querying `MAX_VIEWPORT_DIMS`.

#### 17.4.5 ~~The Accumulation Buffer~~

[This subsection is only defined in the compatibility profile.](#)

## Chapter 18

# Reading and Copying Pixels

Pixels may be read from the framebuffer using **ReadPixels**. **BlitFramebuffer** can be used to copy a block of pixels from one portion of the framebuffer to another.

### 18.1 Drawing Pixels

[This section is only defined in the compatibility profile.](#)

### 18.2 Reading Pixels

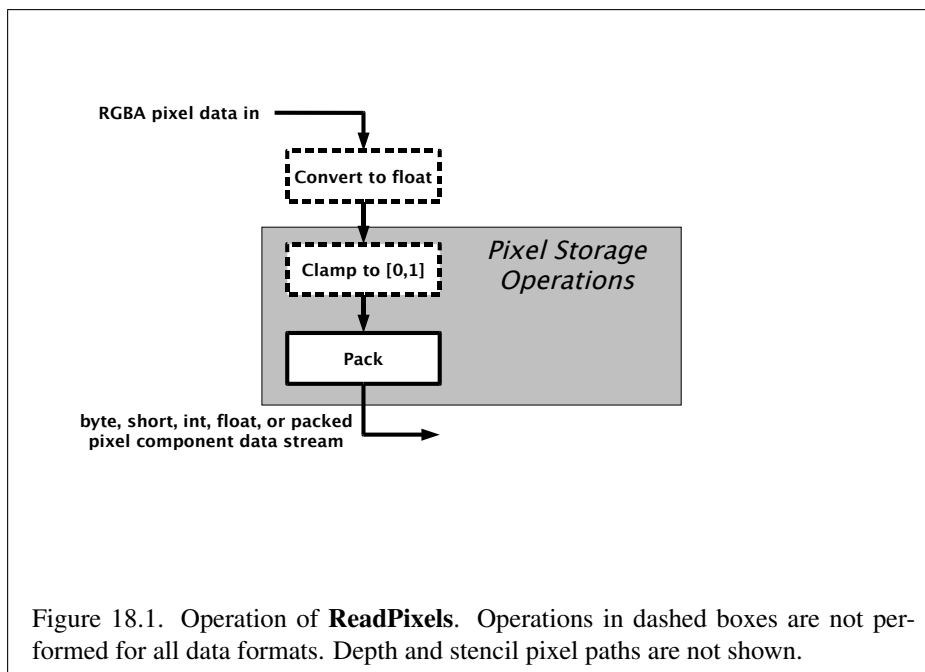
The method for reading pixels from the framebuffer and placing them in pixel pack buffer or client memory is diagrammed in figure 18.1. We describe the stages of the pixel reading process in the order in which they occur.

Initially, zero is bound for the `PIXEL_PACK_BUFFER`, indicating that image read and query commands such as **ReadPixels** return pixel results into client memory pointer parameters. However, if a non-zero buffer object is bound as the current pixel pack buffer, then the pointer parameter is treated as an offset into the designated buffer object.

Pixels are read using

```
void ReadPixels( int x, int y, sizei width, sizei height,  
                enum format, enum type, void *data );
```

The arguments after *x* and *y* to **ReadPixels** are described in section 8.4.4. The pixel storage modes that apply to **ReadPixels** and other commands that query images (see section 8.11) are summarized in table 18.1.



If the current read buffer is neither floating-point nor integer, calling `GetIntegerv` with `pnames` `IMPLEMENTATION_COLOR_READ_FORMAT` and `IMPLEMENTATION_COLOR_READ_TYPE` will return `RGBA` and `UNSIGNED_BYTE`, respectively.

An `INVALID_OPERATION` error is generated by `GetIntegerv` if `pname` is `IMPLEMENTATION_COLOR_READ_FORMAT` or `IMPLEMENTATION_COLOR_READ_TYPE`, and the format of the current read buffer (see section 18.2) is floating-point or integer.

### Errors

An `INVALID_OPERATION` error is generated if the value of `READ_FRAMEBUFFER_BINDING` (see section 9) is non-zero, the read framebuffer is framebuffer complete, and the value of `SAMPLE_BUFFERS` for the read framebuffer is greater than zero.

#### 18.2.1 Obtaining Pixels from the Framebuffer

If the `format` is `DEPTH_COMPONENT`, then values are obtained from the depth buffer.

Parameter Name	Type	Initial Value	Valid Range
PACK_SWAP_BYTES	boolean	FALSE	TRUE/FALSE
PACK_LSB_FIRST	boolean	FALSE	TRUE/FALSE
PACK_ROW_LENGTH	integer	0	[0, ∞)
PACK_SKIP_ROWS	integer	0	[0, ∞)
PACK_SKIP_PIXELS	integer	0	[0, ∞)
PACK_ALIGNMENT	integer	4	1,2,4,8
PACK_IMAGE_HEIGHT	integer	0	[0, ∞)
PACK_SKIP_IMAGES	integer	0	[0, ∞)
PACK_COMPRESSED_BLOCK_WIDTH	integer	0	[0, ∞)
PACK_COMPRESSED_BLOCK_HEIGHT	integer	0	[0, ∞)
PACK_COMPRESSED_BLOCK_DEPTH	integer	0	[0, ∞)
PACK_COMPRESSED_BLOCK_SIZE	integer	0	[0, ∞)

Table 18.1: **PixelStore** parameters pertaining to **ReadPixels**, **GetCompressedTexImage** and **GetTexImage**.

If there is a multisample buffer (the value of `SAMPLE_BUFFERS` is one), then values are obtained from the depth samples in this buffer. It is recommended that the depth value of the centermost sample be used, though implementations may choose any function of the depth sample values at each pixel.

If the *format* is `DEPTH_STENCIL`, then values are taken from both the depth buffer and the stencil buffer. *type* must be `UNSIGNED_INT_24_8` or `FLOAT_32_UNSIGN_INT_24_8_REV`.

If there is a multisample buffer, then values are obtained from the depth and stencil samples in this buffer. It is recommended that the depth and stencil values of the centermost sample be used, though implementations may choose any function of the depth and stencil sample values at each pixel.

If the *format* is `STENCIL_INDEX`, then values are taken from the stencil buffer.

If there is a multisample buffer, then values are obtained from the stencil samples in this buffer. It is recommended that the stencil value of the centermost sample be used, though implementations may choose any function of the stencil sample values at each pixel.

For all other formats, the *read buffer* from which values are obtained is one of the color buffers; the selection of color buffer is controlled with **ReadBuffer**.

## Errors

An `INVALID_ENUM` error is generated if *format* is `DEPTH_STENCIL` and *type* is not `UNSIGNED_INT_24_8` or `FLOAT_32_UNSIGNED_INT_24_8_REV`.

An `INVALID_OPERATION` error is generated if *format* is `DEPTH_COMPONENT` and there is no depth buffer; if *format* is `STENCIL_INDEX` and there is no stencil buffer; or if *format* is `DEPTH_STENCIL` and either there is no depth buffer, or there is no stencil buffer.

The command

```
void ReadBuffer( enum src );
```

takes a symbolic constant as argument. *src* must be one of the values from tables 17.4 or 17.5. Otherwise, an `INVALID_ENUM` error is generated. Further, the acceptable values for *src* depend on whether the GL is using the default framebuffer (i.e., `READ_FRAMEBUFFER_BINDING` is zero), or a framebuffer object (i.e., `READ_FRAMEBUFFER_BINDING` is non-zero). For more information about framebuffer objects, see section 9.

When `READ_FRAMEBUFFER_BINDING` is zero, i.e. the default framebuffer, *src* must be one of the values listed in table 17.4, including `NONE`. `FRONT_AND_BACK`, `FRONT`, and `LEFT` refer to the front left buffer, `BACK` refers to the back left buffer, and `RIGHT` refers to the front right buffer. The other constants correspond directly to the buffers that they name. If the requested buffer is missing, then an `INVALID_OPERATION` error is generated. For the default framebuffer, the initial setting for **ReadBuffer** is `FRONT` if there is no back buffer; `BACK` if there is a back buffer; and `NONE` if no default framebuffer is associated with the context.

When the GL is using a framebuffer object, *src* must be one of the values listed in table 17.5, including `NONE`. In a manner analogous to how the `DRAW_BUFFERS` state is handled, specifying `COLOR_ATTACHMENTi` enables reading from the image attached to the framebuffer at `COLOR_ATTACHMENTi`. For framebuffer objects, the initial setting for **ReadBuffer** is `COLOR_ATTACHMENT0`.

### Errors

An `INVALID_FRAMEBUFFER_OPERATION` error is generated is generated by **ReadPixels** if the object bound to `READ_FRAMEBUFFER_BINDING` is not *framebuffer complete* (as defined in section 9.4.2).

An `INVALID_ENUM` error is generated if *src* is not one of the values from tables 17.4 or 17.5.

An `INVALID_OPERATION` error is generated by **ReadPixels** if it attempts to select a color buffer while `READ_BUFFER` is `NONE`, or if the GL is using a

framebuffer object (the value of `READ_FRAMEBUFFER_BINDING` is non-zero) and the read buffer selects an attachment that has no image attached.

**ReadPixels** obtains values from the selected buffer from each pixel with lower left hand corner at  $(x + i, y + j)$  for  $0 \leq i < width$  and  $0 \leq j < height$ ; this pixel is said to be the  $i$ th pixel in the  $j$ th row. If any of these pixels lies outside of the window allocated to the current GL context, or outside of the image attached to the currently bound read framebuffer object, then the values obtained for those pixels are undefined. When `READ_FRAMEBUFFER_BINDING` is zero, values are also undefined for individual pixels that are not owned by the current context. Otherwise, **ReadPixels** obtains values from the selected buffer, regardless of how those values were placed there.

If *format* is one of `RED`, `GREEN`, `BLUE`, `RG`, `RGB`, `RGBA`, `BGR`, or `BGRA`, then red, green, blue, and alpha values are obtained from the selected buffer at each pixel location.

An `INVALID_OPERATION` error is generated if *format* is an integer format and the color buffer is not an integer format, or if the color buffer is an integer format and *format* is not an integer format.

When `READ_FRAMEBUFFER_BINDING` is non-zero, the red, green, blue, and alpha values are obtained by first reading the internal component values of the corresponding value in the image attached to the selected logical buffer. Internal components are converted to an RGBA color by taking each R, G, B, and A component present according to the base internal format of the buffer (as shown in table 8.11). If G, B, or A values are not present in the internal format, they are taken to be zero, zero, and one respectively.

### 18.2.2 Conversion of RGBA values

This step applies only if *format* is not `STENCIL_INDEX`, `DEPTH_COMPONENT`, or `DEPTH_STENCIL`. The R, G, B, and A values form a group of elements.

For a signed or unsigned normalized fixed-point color buffer, each element is converted to floating-point using equations 2.2 or 2.1, respectively. For an integer or floating-point color buffer, the elements are unmodified.

### 18.2.3 Conversion of Depth values

This step applies only if *format* is `DEPTH_COMPONENT` or `DEPTH_STENCIL` and the depth buffer uses a fixed-point representation. An element is taken to be a fixed-point value in  $[0, 1]$  with  $m$  bits, where  $m$  is the number of bits in the depth buffer (see section 13.6.1). No conversion is necessary if the depth buffer uses a

floating-point representation.

### 18.2.4 Pixel Transfer Operations

This subsection is only defined in the compatibility profile.

### 18.2.5 Conversion to L

This subsection is only defined in the compatibility profile.

### 18.2.6 Final Conversion

Read color clamping is controlled by calling

```
void ClampColor( enum target, enum clamp );
```

with *target* set to CLAMP\_READ\_COLOR. If *clamp* is TRUE, read color clamping is enabled; if *clamp* is FALSE, read color clamping is disabled. If *clamp* is FIXED\_ONLY, read color clamping is enabled if the selected read color buffer has fixed-point components.

For an integer RGBA color, each component is clamped to the representable range of *type*.

For a floating-point RGBA color, if *type* is FLOAT or HALF\_FLOAT, each component is clamped to [0, 1] if read color clamping is enabled. Then the appropriate conversion formula from table 18.2 is applied to the component.

If *type* is UNSIGNED\_INT\_10F\_11F\_11F\_REV and *format* is RGB, each component is clamped to [0, 1] if read color clamping is enabled. The returned data are then packed into a series of uint values. The red, green, and blue components are converted to unsigned 11-bit floating-point, unsigned 11-bit floating-point, and unsigned 10-bit floating-point as described in sections 2.3.3 and 2.3.3. The resulting red 11 bits, green 11 bits, and blue 10 bits are then packed as the 1st, 2nd, and 3rd components of the UNSIGNED\_INT\_10F\_11F\_11F\_REV format as shown in table 8.8.

If *type* is UNSIGNED\_INT\_5\_9\_9\_9\_REV and *format* is RGB, each component is clamped to [0, 1] if read color clamping is enabled. The returned data are then packed into a series of uint values. The red, green, and blue components are converted to  $red_s$ ,  $green_s$ ,  $blue_s$ , and  $exp_s$  integers as described in section 8.5.2 when *internalformat* is RGB9\_E5. The  $red_s$ ,  $green_s$ ,  $blue_s$ , and  $exp_s$  are then packed as the 1st, 2nd, 3rd, and 4th components of the UNSIGNED\_INT\_5\_9\_9\_9\_REV format as shown in table 8.8.

For other *types*, and for a floating-point or unsigned normalized fixed-point color buffer, each component is clamped to  $[0, 1]$  whether or not read color clamping is enabled. For a signed normalized fixed-point color buffer, each component is clamped to  $[0, 1]$  if read color clamping is enabled, or if *type* represents unsigned integer components; otherwise *type* represents signed integer components, and each component is clamped to  $[-1, 1]$ . Following clamping, the appropriate conversion formula from table 18.2 is applied to the component<sup>1</sup>

For an index, if the *type* is not `FLOAT` or `HALF_FLOAT`, final conversion consists of masking the index with the value given in table 18.3. If the *type* is `FLOAT` or `HALF_FLOAT`, then the integer index is converted to a GL `float` or `half` data value.

### 18.2.7 Placement in Pixel Pack Buffer or Client Memory

If a pixel pack buffer is bound (as indicated by a non-zero value of `PIXEL_PACK_BUFFER_BINDING`), *data* is an offset into the pixel pack buffer and the pixels are packed into the buffer relative to this offset; otherwise, *data* is a pointer to a block client memory and the pixels are packed into the client memory relative to the pointer.

An `INVALID_OPERATION` error is generated if a pixel pack buffer object is bound and packing the pixel data according to the pixel pack storage state would access memory beyond the size of the pixel pack buffer's memory size.

An `INVALID_OPERATION` error is generated if a pixel pack buffer object is bound and *data* is not evenly divisible by the number of basic machine units needed to store in memory the corresponding GL data type from table 8.2 for the *type* parameter.

Groups of elements are placed in memory just as they are taken from memory when transferring pixel rectangles to the GL. That is, the *i*th group of the *j*th row (corresponding to the *i*th pixel in the *j*th row) is placed in memory just where the *i*th group of the *j*th row would be taken from when transferring pixels. See **Unpacking** under section 8.4.4.1. The only difference is that the storage mode parameters whose names begin with `PACK_` are used instead of those whose names begin with `UNPACK_`. If the *format* is `RED`, `GREEN`, or `BLUE`, only the corresponding single element is written. Likewise if the *format* is `RG`, `RGB`, or `BGR`, only the corresponding two or three elements are written. Otherwise all the elements of each group are written.

---

<sup>1</sup> OpenGL 4.2 changes the behavior of **ReadPixels** to allow readbacks from a signed normalized color buffer to a signed integer type without loss of information.



<i>type</i> Parameter	GL Data Type	Component Conversion Formula
UNSIGNED_BYTE	ubyte	Equation 2.3, $b = 8$
BYTE	byte	Equation 2.4, $b = 8$
UNSIGNED_SHORT	ushort	Equation 2.3, $b = 16$
SHORT	short	Equation 2.4, $b = 16$
UNSIGNED_INT	uint	Equation 2.3, $b = 32$
INT	int	Equation 2.4, $b = 32$
HALF_FLOAT	half	$c = f$
FLOAT	float	$c = f$
UNSIGNED_BYTE_3_3_2	ubyte	Equation 2.3, $b = \text{bitfield width}$
UNSIGNED_BYTE_2_3_3_REV	ubyte	Equation 2.3, $b = \text{bitfield width}$
UNSIGNED_SHORT_5_6_5	ushort	Equation 2.3, $b = \text{bitfield width}$
UNSIGNED_SHORT_5_6_5_REV	ushort	Equation 2.3, $b = \text{bitfield width}$
UNSIGNED_SHORT_4_4_4_4	ushort	Equation 2.3, $b = \text{bitfield width}$
UNSIGNED_SHORT_4_4_4_4_REV	ushort	Equation 2.3, $b = \text{bitfield width}$
UNSIGNED_SHORT_5_5_5_1	ushort	Equation 2.3, $b = \text{bitfield width}$
UNSIGNED_SHORT_1_5_5_5_REV	ushort	Equation 2.3, $b = \text{bitfield width}$
UNSIGNED_INT_8_8_8_8	uint	Equation 2.3, $b = \text{bitfield width}$
UNSIGNED_INT_8_8_8_8_REV	uint	Equation 2.3, $b = \text{bitfield width}$
UNSIGNED_INT_10_10_10_2	uint	Equation 2.3, $b = \text{bitfield width}$
UNSIGNED_INT_2_10_10_10_REV	uint	Equation 2.3, $b = \text{bitfield width}$
UNSIGNED_INT_24_8	uint	Equation 2.3, $b = \text{bitfield width}$
UNSIGNED_INT_10F_11F_11F_REV	uint	Special
UNSIGNED_INT_5_9_9_9_REV	uint	Special
FLOAT_32_UNSIGNED_INT_24_8_REV	float	$c = f$ (depth only)

Table 18.2: Reversed component conversions, used when component data are being returned to client memory. Color and depth components are converted from the internal floating-point representation ( $f$ ) to a datum of the specified GL data type ( $c$ ). All arithmetic is done in the internal floating-point format. These conversions apply to component data returned by GL query commands and to components of pixel data returned to client memory. The equations remain the same even if the implemented ranges of the GL data types are greater than the minimum required ranges (see table 2.2).

<i>type</i> Parameter	Index Mask
UNSIGNED_BYTE	$2^8 - 1$
BYTE	$2^7 - 1$
UNSIGNED_SHORT	$2^{16} - 1$
SHORT	$2^{15} - 1$
UNSIGNED_INT	$2^{32} - 1$
INT	$2^{31} - 1$
UNSIGNED_INT_24_8	$2^8 - 1$
FLOAT_32_UNSIGNED_INT_24_8_REV	$2^8 - 1$

Table 18.3: Index masks used by **ReadPixels**. Floating point data are not masked.

## 18.3 Copying Pixels

### 18.3.1 Blitting Pixel Rectangles

The command

```
void BlitFramebuffer( int srcX0, int srcY0, int srcX1,
    int srcY1, int dstX0, int dstY0, int dstX1, int dstY1,
    bitfield mask, enum filter );
```

transfers a rectangle of pixel values from one region of the read framebuffer to another in the draw framebuffer.

*mask* is zero or the bitwise OR of one or more values indicating which buffers are to be copied. The values are COLOR\_BUFFER\_BIT, DEPTH\_BUFFER\_BIT, and STENCIL\_BUFFER\_BIT, which are described in section 17.4.3. The pixels corresponding to these buffers are copied from the source rectangle bounded by the locations (*srcX0*, *srcY0*) and (*srcX1*, *srcY1*) to the destination rectangle bounded by the locations (*dstX0*, *dstY0*) and (*dstX1*, *dstY1*). The lower bounds of the rectangle are inclusive, while the upper bounds are exclusive.

If *mask* is zero, no buffers are copied.

When the color buffer is transferred, values are taken from the read buffer of the read framebuffer and written to each of the draw buffers of the draw framebuffer.

The actual region taken from the read framebuffer is limited to the intersection of the source buffers being transferred, which may include the color buffer selected by the read buffer, the depth buffer, and/or the stencil buffer depending on *mask*. The actual region written to the draw framebuffer is limited to the intersection of the destination buffers being written, which may include multiple draw buffers,

the depth buffer, and/or the stencil buffer depending on *mask*. Whether or not the source or destination regions are altered due to these limits, the scaling and offset applied to pixels being transferred is performed as though no such limits were present.

If the source and destination rectangle dimensions do not match, the source image is stretched to fit the destination rectangle. *filter* must be `LINEAR` or `NEAREST`, and specifies the method of interpolation to be applied if the image is stretched. `LINEAR` filtering is allowed only for the color buffer. If the source and destination dimensions are identical, no filtering is applied. If either the source or destination rectangle specifies a negative width or height ( $X1 < X0$  or  $Y1 < Y0$ ), the image is reversed in the corresponding direction. If both the source and destination rectangles specify a negative width or height for the same direction, no reversal is performed. If a linear filter is selected and the rules of `LINEAR` sampling would require sampling outside the bounds of a source buffer, it is as though `CLAMP_TO_EDGE` texture sampling were being performed. If a linear filter is selected and sampling would be required outside the bounds of the specified source region, but within the bounds of a source buffer, the implementation may choose to clamp while sampling or not.

If the source and destination buffers are identical, and the source and destination rectangles overlap, the result of the blit operation is undefined.

When values are taken from the read buffer, if the value of `FRAMEBUFFER_ATTACHMENT_COLOR_ENCODING` for the framebuffer attachment corresponding to the read buffer is `SRGB` (see section 9.2.3), the red, green, and blue components are converted from the non-linear sRGB color space according to equation 8.14.

When values are written to the draw buffers, blit operations bypass most of the fragment pipeline. The only fragment operations which affect a blit are the pixel ownership test, the scissor test, and sRGB conversion (see section 17.3.9). Color, depth, and stencil masks (see section 17.4.2) are ignored.

If the read framebuffer is layered (see section 9.8), pixel values are read from layer zero. If the draw framebuffer is layered, pixel values are written to layer zero. If both read and draw framebuffers are layered, the blit operation is still performed only on layer zero.

If a buffer is specified in *mask* and does not exist in both the read and draw framebuffers, the corresponding bit is silently ignored.

If the color formats of the read and draw buffers do not match, and *mask* includes `COLOR_BUFFER_BIT`, pixel groups are converted to match the destination format. However, colors are clamped only if all draw color buffers have fixed-point components. Format conversion is not supported for all data types, as described below.

If `SAMPLE_BUFFERS` for the read framebuffer is greater than zero and `SAMPLE_BUFFERS` for the draw framebuffer is zero, the samples corresponding to each pixel location in the source are converted to a single sample before being written to the destination.

If `SAMPLE_BUFFERS` for the read framebuffer is zero and `SAMPLE_BUFFERS` for the draw framebuffer is greater than zero, the value of the source sample is replicated in each of the destination samples.

If `SAMPLE_BUFFERS` for either the read framebuffer or draw framebuffer is greater than zero, no copy is performed and an `INVALID_OPERATION` error is generated if the dimensions of the source and destination rectangles provided to **BlitFramebuffer** are not identical, or if the formats of the read and draw framebuffers are not identical.

If `SAMPLE_BUFFERS` for both the read and draw framebuffers are greater than zero, and the values of `SAMPLES` for the read and draw framebuffers are identical, the samples are copied without modification from the read framebuffer to the draw framebuffer. Otherwise, no copy is performed and an `INVALID_OPERATION` error is generated. Note that the samples in the draw buffer are not guaranteed to be at the same sample location as the read buffer, so rendering using this newly created buffer can potentially have geometry cracks or incorrect antialiasing. This may occur if the sizes of the framebuffers do not match or if the source and destination rectangles are not defined with the same  $(X0, Y0)$  and  $(X1, Y1)$  bounds.

### Errors

An `INVALID_VALUE` error is generated if *mask* contains any bits other than `COLOR_BUFFER_BIT`, `DEPTH_BUFFER_BIT`, or `STENCIL_BUFFER_BIT`.

An `INVALID_ENUM` error is generated if *filter* is not `LINEAR` or `NEAREST`.

An `INVALID_OPERATION` error is generated if *mask* includes `DEPTH_BUFFER_BIT` or `STENCIL_BUFFER_BIT`, and *filter* is not `NEAREST`.

An `INVALID_FRAMEBUFFER_OPERATION` error is generated if the objects bound to `DRAW_FRAMEBUFFER_BINDING` and `READ_FRAMEBUFFER_BINDING` are not framebuffer complete (section 9.4.2).

An `INVALID_OPERATION` error is generated if *mask* includes `DEPTH_BUFFER_BIT` or `STENCIL_BUFFER_BIT`, and the source and destination depth and stencil buffer formats do not match.

An `INVALID_OPERATION` error is generated if *filter* is `LINEAR` and read buffer contains integer data.

An `INVALID_OPERATION` error is generated if format conversions are not supported, which occurs under any of the following conditions:

- The read buffer contains fixed-point or floating-point values and any draw buffer contains neither fixed-point nor floating-point values.
- The read buffer contains unsigned integer values and any draw buffer does not contain unsigned integer values.
- The read buffer contains signed integer values and any draw buffer does not contain signed integer values.

### 18.3.2 Copying Between Images

The command

```
void CopyImageSubData( uint srcName, enum srcTarget,
    int srcLevel, int srcX, int srcY, int srcZ,
    uint dstName, enum dstTarget, int dstLevel, int dstX,
    int dstY, int dstZ, sizei srcWidth, sizei srcHeight,
    sizei srcDepth );
```

may be used to copy a region of texel data between two image objects. An image object may be either a texture or a renderbuffer.

**CopyImageSubData** does not perform general-purpose conversions such as scaling, resizing, blending, color-space, or format conversions. It should be considered to operate in a manner similar to a CPU memcopy. **CopyImageSubData** can copy between images with different internal formats, provided the formats are compatible.

**CopyImageSubData** also allows copying between certain types of compressed and uncompressed internal formats as described in table 18.4. This copy does not perform on-the-fly compression or decompression. When copying from an uncompressed internal format to a compressed internal format, each texel of uncompressed data becomes a single block of compressed data. When copying from a compressed internal format to an uncompressed internal format, a block of compressed data becomes a single texel of uncompressed data. The texel size of the uncompressed format must be the same size the block size of the compressed formats. Thus it is permitted to copy between a 128-bit uncompressed format and a compressed format which uses 8-bit  $4 \times 4$  blocks, or between a 64-bit uncompressed format and a compressed format which uses 4-bit  $4 \times 4$  blocks.

The source object is identified by *srcName* and *srcTarget*. Similarly the destination object is identified by *dstName* and *dstTarget*. The interpretation of the name depends on the value of the corresponding target parameter. If the target parameter is `RENDERBUFFER`, the name is interpreted as the name of a renderbuffer object. If the target parameter is a texture target, the name is interpreted as

a texture object. All non-proxy texture targets are accepted, with the exception of `TEXTURE_BUFFER` and the cubemap face selectors described in table 8.18.

*srcLevel* and *dstLevel* identify the source and destination level of detail. For textures, this must be a valid level of detail in the texture object. For renderbuffers, this value must be zero.

*srcX*, *srcY*, and *srcZ* specify the lower left texel coordinates of a *srcWidth*-wide by *srcHeight*-high by *srcDepth*-deep rectangular subregion of the source texel array. Similarly, *dstX*, *dstY* and *dstZ* specify the coordinates of a subregion of the destination texel array. The source and destination subregions must be contained entirely within the specified level of the corresponding image objects. The dimensions are always specified in texels, even for compressed texture formats. But it should be noted that if only one of the source and destination textures is compressed then the number of texels touched in the compressed image will be a factor of the block size larger than in the uncompressed image.

Slices of a `TEXTURE_1D_ARRAY`, `TEXTURE_2D_ARRAY`, `TEXTURE_CUBE_MAP_ARRAY` `TEXTURE_3D` and faces of `TEXTURE_CUBE_MAP` are all compatible provided they share a compatible internal format, and multiple slices or faces may be copied between these objects with a single call by specifying the starting slice with *srcZ* and *dstZ*, and the number of slices to be copied with *srcDepth*. Cubemap textures always have six faces which are selected by a zero-based face index, according to the order specified in table 8.18.

For the purposes of **CopyImageSubData**, two internal formats are considered compatible if any of the following conditions are met:

- the formats are the same
- the formats are considered compatible according to the compatibility rules used for texture views as defined in section 8.18. In particular, if both internal formats are listed in the same entry of table 8.21, they are considered compatible
- one format is compressed and the other is uncompressed and table 18.4 lists the two formats in the same row.

### Errors

An `INVALID_OPERATION` error is generated if the texel size of the uncompressed image is not equal to the block size of the compressed image.

An `INVALID_ENUM` error is generated if either target is not `RENDERBUFFER` or a valid non-proxy texture target; is `TEXTURE_BUFFER` or one of the cubemap face selectors described in table 8.18; or if the target does

Texel / Block Size	Uncompressed internal format	Compressed internal format
128-bit	RGBA32UI, RGBA32I, RGBA32F	COMPRESSED_RG_RGTC2, COMPRESSED_SIGNED_RG_RGTC2, COMPRESSED_RGBA_BPTC_UNORM, COMPRESSED_SRGB_ALPHA_BPTC_UNORM, COMPRESSED_RGB_BPTC_SIGNED_FLOAT, COMPRESSED_RGB_BPTC_UNSIGNED_FLOAT
64-bit	RGBA16F, RG32F, RGBA16UI, RG32UI, RGBA16I, RG32I, RGBA16, RGBA16_SNORM	COMPRESSED_RED_RGTC1, COMPRESSED_SIGNED_RED_RGTC1

Table 18.4: Compatible internal formats for copying between compressed and uncompressed internal formats with **CopyImageSubData**. Formats in the same row can be copied between each other.

not match the type of the object.

An `INVALID_OPERATION` error is generated if either object is a texture and the texture is not complete (as defined in section 8.17), if the source and destination internal formats are not compatible (see below), or if the number of samples do not match.

An `INVALID_VALUE` error is generated if either name does not correspond to a valid renderbuffer or texture object according to the corresponding target parameter.

An `INVALID_VALUE` error is generated if *srcLevel* and *dstLevel* are not valid levels for the corresponding images.

An `INVALID_VALUE` error is generated if *srcWidth*, *srcHeight*, or *srcDepth* is negative.

An `INVALID_VALUE` error is generated if the dimensions of either subregion exceeds the boundaries of the corresponding image object, or if the image format is compressed and the dimensions of the subregion fail to meet the alignment constraints of the format.

An `INVALID_OPERATION` error is generated if the formats are not compatible.

## 18.4 Pixel Draw and Read State

The state required for pixel operations consists of the parameters that are set with **PixelStore**. This state has been summarized in [table 8.1](#). Additional state includes `GL_CLAMP_TO_EDGE` and a three-valued integer controlling clamping during final conversion. The initial value of read color clamping is `GL_FIXED_ONLY`. State set with **PixelStore** is GL client state.



## Chapter 19

# Compute Shaders

In addition to graphics-oriented shading operations such as vertex, tessellation, geometry and fragment shading, generic computation may be performed by the GL through the use of compute shaders. The compute pipeline is a form of single-stage machine that runs generic shaders. Compute shaders are created as described in section 7.1 using a *type* parameter of `COMPUTE_SHADER`. They are attached to and used in program objects as described in section 7.3.

Compute workloads are formed from groups of work items called work groups and processed by the executable code for a compute program. A work group is a collection of shader invocations that execute the same code, potentially in parallel. An invocation within a work group may share data with other members of the same workgroup through shared variables (see section 4.3.8(“Shared Variables”) of the OpenGL Shading Language Specification ) and issue memory and control barriers to synchronize with other members of the same work group. One or more work groups is launched by calling:

```
void DispatchCompute( uint num_groups_x,  
                      uint num_groups_y, uint num_groups_z );
```

Each work group is processed by the active program object for the compute shader stage. The active program for the compute shader stage will be determined in the same manner as the active program for other pipeline stages, as described in section 7.3. While the individual shader invocations within a work group are executed as a unit, work groups are executed completely independently and in unspecified order.

*num\_groups\_x*, *num\_groups\_y* and *num\_groups\_z* specify the number of local work groups that will be dispatched in the X, Y and Z dimensions, respectively.

The builtin vector variable `gl_NumWorkGroups` will be initialized with the contents of the `num_groups_x`, `num_groups_y` and `num_groups_z` parameters. The maximum number of work groups that may be dispatched at one time may be determined by calling **GetIntegeriv** with *target* set to `MAX_COMPUTE_WORK_GROUP_COUNT` and *index* set to `N`. If the work group count in any dimension is zero, no work groups are dispatched.

The local work size in each dimension are specified at compile time using an input `layout` qualifier in one or more of the compute shaders attached to the program (see section 4.4.1.4(“Compute Shader Inputs”) of the OpenGL Shading Language Specification ). After the program has been linked, the local work group size of the program may be queried by calling **GetProgramiv** with *pname* set to `COMPUTE_WORK_GROUP_SIZE`, as described in section 7.13.

The maximum size of a local work group may be determined by calling **GetIntegeriv** with *target* set to `MAX_COMPUTE_WORK_GROUP_SIZE` and *index* set to 0, 1, or 2 to retrieve the maximum work size in the X, Y and Z dimension, respectively. Furthermore, the maximum number of invocations in a single local work group (i.e., the product of the three dimensions) may be determined by calling **GetIntegeriv** with *pname* set to `MAX_COMPUTE_WORK_GROUP_INVOCATIONS`.

### Errors

An `INVALID_OPERATION` error is generated if there is no active program for the compute shader stage.

An `INVALID_VALUE` error is generated if any of `num_groups_x`, `num_groups_y` and `num_groups_z` are greater than or equal to the maximum work group count for the corresponding dimension.

The command

```
void DispatchComputeIndirect( intptr indirect );
```

is equivalent to calling **DispatchCompute** with `num_groups_x`, `num_groups_y` and `num_groups_z` initialized with the three `uint` values contained in the buffer currently bound to the `DISPATCH_INDIRECT_BUFFER` binding at an offset, in basic machine units, specified in *indirect*. If any of `num_groups_x`, `num_groups_y` or `num_groups_z` is greater than the value of `MAX_COMPUTE_WORK_GROUP_COUNT` for the corresponding dimension then the results are undefined.

### Errors

An `INVALID_OPERATION` error is generated if there is no active program

for the compute shader stage.

An `INVALID_VALUE` error is generated if *indirect* is negative or is not a multiple of four.

An `INVALID_OPERATION` error is generated if no buffer is bound to the `DRAW_INDIRECT_BUFFER` binding, or if the command would source data beyond the end of the buffer object.

## 19.1 Compute Shader Variables

Compute shaders can access variables belonging to the current program object. Limits on uniform storage and methods for manipulating uniforms are described in section 7.6.

There is a limit to the total size of all variables declared as `shared` in a single program object. This limit, expressed in units of basic machine units, may be queried as the value of `MAX_COMPUTE_SHARED_MEMORY_SIZE`.

## Chapter 20

# Debug Output

Application developers can obtain details about errors, undefined behavior, implementation-dependent performance warnings, or other useful hints from the GL in the form of *debug output*.

Debug output is communicated through a stream of *debug messages* that are generated as GL commands are executed. The application can choose to receive these messages either through a callback routine, or by querying for them from a message log.

Controls are provided for disabling messages that the application does not care about, and for inserting application-generated messages into the stream.

Different levels of debug output may be provided, depending on how the context was created. If the context is not a *debug context*<sup>1</sup> (e.g. if it was created without the `CONTEXT_FLAG_DEBUG_BIT` set in the `CONTEXT_FLAGS` state, as described in section 22.2), then the GL may optionally not generate any debug messages, but the commands described in this chapter will otherwise operate without error.

Debug output functionality is enabled or disabled with **Enable** or **Disable** using the symbolic constant `DEBUG_OUTPUT`. If the context is a *debug context* (if it was created with the `CONTEXT_FLAG_DEBUG_BIT` set in `CONTEXT_FLAGS`) then the initial value of `DEBUG_OUTPUT` is `TRUE`; otherwise the initial value is `FALSE`.

In a debug context, if `DEBUG_OUTPUT` is disabled the GL will not generate any debug output logs or callbacks. Enabling `DEBUG_OUTPUT` again will enable full debug output functionality.

In a non-debug context, if `DEBUG_OUTPUT` is later enabled, the level of debug output logging is defined by the GL implementation, which may have zero debug

---

<sup>1</sup>Debug contexts are specified at context creation time, using window-system binding APIs such as those specified in the `GLX_ARB_create_context` and `WGL_ARB_create_context` extensions for GLX and WGL, respectively.

Debug Output Message Source	Messages Generated by
DEBUG_SOURCE_API	The GL
DEBUG_SOURCE_SHADER_COMPILER	The GLSL shader compiler or compilers for other extension-provided languages
DEBUG_SOURCE_WINDOW_SYSTEM	The window system, such as WGL or GLX
DEBUG_SOURCE_THIRD_PARTY	External debuggers or third-party middleware libraries
DEBUG_SOURCE_APPLICATION	The application
DEBUG_SOURCE_OTHER	Sources that do not fit to any of the ones listed above

Table 20.1: Sources of debug output messages. Each message must originate from a source listed in this table.

output.

Full debug output support is guaranteed only in a debug context.

## 20.1 Debug Messages

A debug message is uniquely identified by the source that generated it, a type within that source, and an unsigned integer ID identifying the message within that type. The message source is one of the symbolic constants listed in table 20.1. The message type is one of the symbolic constants listed in table 20.2.

Each message source and type pair contains its own namespace of messages with every message being associated with an ID. The assignment of IDs to messages within a namespace is implementation-dependent. There can potentially be overlap between the namespaces of two different pairs of source and type, so messages can only be uniquely distinguished from each other by the full combination of source, type and ID.

Each message is also assigned a severity level that roughly describes its importance across all sources and types along a single global axis. The severity of a message is one of the symbolic constants defined in table 20.3. Because messages can be disabled by their severity, this allows for quick control the global volume of debug output.

Every message also has a null-terminated string representation that is used to describe the message. The contents of the string can change slightly between different instances of the same message (e.g. which parameter value caused a specific

Debug Output Message Type	Informs about
DEBUG_TYPE_ERROR	Events that generated an error
DEBUG_TYPE_DEPRECATED_BEHAVIOR	Behavior that has been marked for deprecation
DEBUG_TYPE_UNDEFINED_BEHAVIOR	Behavior that is undefined according to the specification
DEBUG_TYPE_PERFORMANCE	Implementation-dependent performance warnings
DEBUG_TYPE_PORTABILITY	Use of extensions or shaders in a way that is highly vendor-specific
DEBUG_TYPE_MARKER	Annotation of the command stream
DEBUG_TYPE_PUSH_GROUP	Entering a debug group
DEBUG_TYPE_POP_GROUP	Leaving a debug group
DEBUG_TYPE_OTHER	Types of events that do not fit any of the ones listed above

Table 20.2: Types of debug output messages. Each message is associated with one of these types that describes the nature of the message.

Severity Level Token	Suggested examples of messages
DEBUG_SEVERITY_HIGH	Any GL error; dangerous undefined behavior; any GLSL or ARB shader compiler and linker errors;
DEBUG_SEVERITY_MEDIUM	Severe performance warnings; GLSL or other shader compiler and linker warnings; use of currently deprecated behavior
DEBUG_SEVERITY_LOW	Performance warnings from redundant state changes; trivial undefined behavior
DEBUG_SEVERITY_NOTIFICATION	Any message which is not an error or performance concern

Table 20.3: Severity levels of messages. Each debug output message is associated with one of these severity levels.

GL error to occur). The format of a message string is left as implementation-dependent, although it should at least represent a concise description of the event that caused the message to be generated. Messages with different IDs should also have sufficiently distinguishable string representations to warrant their separation.

The lengths of all messages, including their null terminators, is guaranteed to be less or equal to the value of the implementation-dependent constant `MAX_DEBUG_MESSAGE_LENGTH`.

Messages can be either enabled or disabled. Messages that are disabled will not be generated. All messages are initially enabled unless their assigned severity is `DEBUG_SEVERITY_LOW`. The enabled state of messages can be changed using the command `DebugMessageControl`.

## 20.2 Debug Message Callback

Applications can provide a callback function for receiving debug messages using the command

```
void DebugMessageCallback( DEBUGPROC callback,
    void *userParam );
```

with *callback* storing the address of the callback function. *callback* must be a function whose prototype is of the form

```
void callback( enum source, enum type, uint id,
    enum severity, size_t length, const char *message,
    void *userParam );
```

Additionally, *callback* must be declared with the same platform-dependent calling convention used in the definition of the type `DEBUGPROC`. Anything else will result in undefined behavior.

Only one debug callback can be specified for the current context, and further calls overwrite the previous callback. Specifying `NULL` as the value of *callback* clears the current callback and disables message output through callbacks. Applications can provide user-specified data through the pointer *userParam*. The context will store this pointer and will include it as one of the parameters in each call to the callback function.

If the application has specified a callback function for receiving debug output, the implementation will call that function whenever any enabled message is generated. The source, type, ID, and severity of the message are specified by the `DEBUGPROC` parameters *source*, *type*, *id*, and *severity*, respectively. The string

representation of the message is stored in *message* and its length (excluding the null-terminator) is stored in *length*. The parameter *userParam* is the user-specified parameter that was given when calling **DebugMessageCallback**.

Applications that specify a callback function must be aware of certain special conditions when executing code inside a callback when it is called by the GL, regardless of the debug source.

The memory for *message* is owned and managed by the GL, and should only be considered valid for the duration of the function call.

The behavior of calling any GL or window system function from within the callback function is undefined and may lead to program termination.

Care must also be taken in securing debug callbacks for use with asynchronous debug output by multi-threaded GL implementations. section 20.8 describes this in further detail.

If `DEBUG_OUTPUT` is disabled, then the GL will not call the *callback* function.

### 20.3 Debug Message Log

If `DEBUG_CALLBACK_FUNCTION` is `NULL`, then debug messages are instead stored in an internal message log up to some maximum number of messages as defined by the value of `MAX_DEBUG_LOGGED_MESSAGES`.

Each context stores its own message log and will only store messages generated by commands operating in that context. If the message log fills up, then any subsequently generated messages will not be placed in the log until the message log is cleared, and will instead be discarded.

Applications can query the number of messages currently in the log by obtaining the value of `DEBUG_LOGGED_MESSAGES`, and the string length (including its null terminator) of the oldest message in the log through the value of `DEBUG_NEXT_LOGGED_MESSAGE_LENGTH`.

To fetch message data stored in the log, the command **GetDebugMessageLog** can be used.

If `DEBUG_CALLBACK_FUNCTION` is not `NULL`, no generated messages will be stored in the log but will instead be passed to the debug callback routine as described in section 20.2.

If `DEBUG_OUTPUT` is disabled, then no messages are added to the message log.

### 20.4 Controlling Debug Messages

Applications can control the volume of debug output in the active debug group (see section 20.6) by disabling specific groups of messages with the command:



```
void DebugMessageControl( enum source, enum type,
    enum severity, size_t count, const uint *ids,
    boolean enabled );
```

If *enabled* is TRUE, the referenced subset of messages will be enabled. If FALSE, then those messages will be disabled.

This command can reference different subsets of messages by first considering the set of all messages, and filtering out messages based on the following ways:

- If *source*, *type*, or *severity* is DONT\_CARE, then messages from all sources, of all types, or of all severities are referenced respectively.
- When values other than DONT\_CARE are specified, all messages whose source, type, or severity match the specified *source*, *type*, or *severity* respectively will be referenced.
- If *count* is greater than zero, then *ids* is an array of *count* message IDs for the specified combination of *source* and *type*. In this case, *source* or *type* must not be DONT\_CARE, and *severity* must be DONT\_CARE,

If *count* is zero, the value of *ids* is ignored.

Although messages are grouped into an implicit hierarchy by their sources and types, there is no explicit per-source, per-type or per-severity enabled state. Instead, the enabled state is stored individually for each message. There is no difference between disabling all messages from one source in a single call, and individually disabling all messages from that source using their types and IDs.

If DEBUG\_OUTPUT is disabled, then it is as if messages of every *source*, *type*, or *severity* are disabled.

### Errors

An INVALID\_ENUM error is generated if any of *source*, *type*, and *severity* is neither DONT\_CARE nor one of the symbols from, respectively, tables 20.1, 20.2, and 20.3.

An INVALID\_VALUE error is generated if *count* is negative,

An INVALID\_OPERATION error is generated if *count* is greater than zero and either *source* or *type* is DONT\_CARE, or *severity* is not DONT\_CARE.

## 20.5 Externally Generated Messages

To support applications and third-party libraries generating their own messages, such as ones containing timestamp information or signals about specific render system events, the following function can be called

```
void DebugMessageInsert( enum source, enum type, uint id,
                        enum severity, int length, const char *buf );
```

The value of *id* specifies the ID for the message and *severity* indicates its severity level as defined by the caller. The string *buf* contains the string representation of the message. The parameter *length* contains the number of characters in *buf*. If *length* is negative, it is implied that *buf* contains a null terminated string.

### Errors

If `DEBUG_OUTPUT` is disabled, then calls to `DebugMessageInsert` are discarded, but do not generate an error.

An `INVALID_ENUM` error is generated if *type* is not one of the values from table 20.2, or if *source* is not `DEBUG_SOURCE_APPLICATION` or `DEBUG_SOURCE_THIRD_PARTY`.

An `INVALID_VALUE` error is generated if *severity* is not one of the severity levels listed in table 20.3.

An `INVALID_VALUE` error is generated if the number of characters in *buf*, excluding the null terminator when *length* is negative, is not less than the value of `MAX_DEBUG_MESSAGE_LENGTH`.

## 20.6 Debug Groups

*Debug groups* provide a method for annotating a command stream with discrete groups of commands using a descriptive text. Debug output messages, either generated by the implementation or inserted by the application with `DebugMessageInsert` are written to the *active debug group* (the top of the debug group stack). Debug groups are strictly hierarchical. Their sequences may be nested within other debug groups but can not overlap. If no debug group has been pushed by the application then the active debug group is the default debug group.

The command

```
void PushDebugGroup( enum source, uint id, size_t length,
                    const char *message );
```

pushes a debug group described by the string *message* into the command stream. The value of *id* specifies the ID of messages generated. The parameter *length* contains the number of characters in *message*. If *length* is negative, it is implied that *message* contains a null terminated string. The message has the specified *source* and *id*, *type* `DEBUG_TYPE_PUSH_GROUP`, and *severity* `DEBUG_SEVERITY_NOTIFICATION`. The GL will put a new debug group on top of the debug group stack which inherits control of the volume of debug output of the debug group previously residing on the top of the debug group stack. Because debug groups are strictly hierarchical, any additional control of the debug output volume will only apply within the active debug group and the debug groups pushed on top of the active debug group.

### Errors

An `INVALID_ENUM` error is generated if the value of *source* is neither `DEBUG_SOURCE_APPLICATION` nor `DEBUG_SOURCE_THIRD_PARTY`.

An `INVALID_VALUE` error is generated if *length* is negative and the number of characters in *message*, excluding the null-terminator, is not less than the value of `MAX_DEBUG_MESSAGE_LENGTH`.

A `STACK_OVERFLOW` error is generated if **PushDebugGroup** is called and the stack contains the value of `MAX_DEBUG_GROUP_STACK_DEPTH` minus one elements.

The command

```
void PopDebugGroup( void );
```

pops the active debug group. After popping a debug group, the GL will also generate a debug output message describing its cause based on the *message* string, the *source*, and an *id* submitted to the associated **PushDebugGroup** command. `DEBUG_TYPE_PUSH_GROUP` and `DEBUG_TYPE_POP_GROUP` share a single namespace for message *id*. *severity* has the value `DEBUG_SEVERITY_NOTIFICATION` and *type* has the value `DEBUG_TYPE_POP_GROUP`. Popping a debug group restores the debug output volume control of the parent debug group.

### Errors

A `STACK_UNDERFLOW` error is generated if **PopDebugGroup** is called and only the default debug group is on the stack.

Identifier	Object Type
BUFFER	buffer
FRAMEBUFFER	frame buffer
PROGRAM_PIPELINE	program pipeline
PROGRAM	program
QUERY	query
RENDERBUFFER	render buffer
SAMPLER	sampler
SHADER	shader
TEXTURE	texture
TRANSFORM_FEEDBACK	transform feedback
VERTEX_ARRAY	vertex array

Table 20.4: Object namespace identifiers and the corresponding object types.

## 20.7 Debug Labels

Debug labels provide a method for annotating any object (texture, buffer, shader, etc.) with a descriptive text label. These labels may then be used by the debug output (see chapter 20) or an external tool such as a debugger or profiler to describe labelled objects.

The command

```
void ObjectLabel( enum identifier, uint name, sizei length,
                  const char *label );
```

labels the object identified by *name* and its namespace *identifier*. *identifier* must be one of the tokens in table 20.4, indicating the type of the object corresponding to *name*.

*label* contains a string used to label an object. *length* contains the number of characters in *label*. If *length* is negative, then *label* contains a null-terminated string. If *label* is NULL, any debug label is effectively removed from the object.

### Errors

An `INVALID_ENUM` error is generated if *identifier* is not one of the object types listed in table 20.4.

An `INVALID_VALUE` error is generated if *name* is not the name of a valid object of the type specified by *identifier*.

An `INVALID_VALUE` error is generated if the number of characters in *label*, excluding the null terminator when *length* is negative, is not less than the value of `MAX_LABEL_LENGTH`.

The command

```
void ObjectPtrLabel( void *ptr, sizei length, const
                    char *label );
```

labels the sync object identified by *ptr*. *length* and *label* match the corresponding arguments of **ObjectLabel**.

### Errors

An `INVALID_VALUE` error is generated if *ptr* is not the name of a sync object.

An `INVALID_VALUE` error is generated if the number of characters in *label*, excluding the null terminator when *length* is negative, is not less than the value of `MAX_LABEL_LENGTH`.

A label is part of the state of the object to which it is associated. The initial state of an object's label is the empty string. Labels need not be unique.

## 20.8 Asynchronous and Synchronous Debug Output

The behavior of how and when the GL driver is allowed to generate debug messages, and subsequently either call back to the application or place the message in the debug message log, is affected by the state `DEBUG_OUTPUT_SYNCHRONOUS`. This state can be modified by the **Enable** and **Disable** commands. Its initial value is `FALSE`.

When `DEBUG_OUTPUT_SYNCHRONOUS` is disabled, the driver is optionally allowed to concurrently call the debug callback routine from potentially multiple threads, including threads that the context that generated the message is not currently bound to. The implementation may also call the callback routine asynchronously after the GL command that generated the message has already returned. The application is fully responsible for ensuring thread safety due to debug callbacks under these circumstances. In this situation the *userParam* value may be helpful in identifying which application thread's command originally generated the debug callback.

When `DEBUG_OUTPUT_SYNCHRONOUS` is enabled, the driver guarantees synchronous calls to the callback routine by the context. When synchronous callbacks

are enabled, all calls to the callback routine will be made by the thread that owns the current context; all such calls will be made serially by the current context; and each call will be made before the GL command that generated the debug message is allowed to return.

When no callback is specified and `DEBUG_OUTPUT_SYNCHRONOUS` is disabled, the driver can still asynchronously place messages in the debug message log, even after the context thread has returned from the GL function that generated those messages. When `DEBUG_OUTPUT_SYNCHRONOUS` is enabled, the driver guarantees that all messages are added to the log before the GL function returns.

Enabling synchronous debug output greatly simplifies the responsibilities of the application for making its callback functions thread-safe, but may potentially result in drastically reduced driver performance.

The `DEBUG_OUTPUT_SYNCHRONOUS` only guarantees intra-context synchronization for the callbacks of messages generated by that context, and does not guarantee synchronization across multiple contexts. If multiple contexts are concurrently used by the application, it is allowed for those contexts to also concurrently call their designated callbacks, and the application is responsible for handling thread safety in that situation even if `DEBUG_OUTPUT_SYNCHRONOUS` is enabled in all contexts.

## 20.9 Debug Output Queries

Pointers set with debug output commands are queried with the generic **GetPointerv** command (see section 22.2). *pnames* `DEBUG_CALLBACK_FUNCTION` and `DEBUG_CALLBACK_USER_PARAM` respectively query the current callback function and the user parameter to that function set with **DebugMessageCallback**.

When no debug callback is set, debug messages are stored in a debug message log as described in section 20.3. Messages can be queried from the log by calling

```
uint GetDebugMessageLog( uint count, sizei bufSize,
                        enum *sources, enum *types, enum *ids, enum *severities,
                        sizei *lengths, char *messageLog );
```

**GetDebugMessageLog** fetches a maximum of *count* messages from the message log, and will return the number of messages successfully fetched.

Messages will be fetched from the log in order of oldest to newest. Those messages that were fetched will be removed from the log.

The sources, types, severities, IDs, and string lengths of fetched messages will be stored in the application-provided arrays *sources*, *types*, *severities*, *ids*, and *lengths*, respectively. The application is responsible for allocating enough space

for each array to hold up to *count* elements. The string representations of all fetched messages are stored in the *messageLog* array. If multiple messages are fetched, their strings are concatenated into the same *messageLog* array and will be separated by single null terminators. The last string in the array will also be null-terminated. The maximum size of *messageLog*, including the space used by all null terminators, is given by *bufSize*.

If a message's string, including its null terminator, can not fully fit within the *messageLog* array's remaining space, then that message and any subsequent messages will not be fetched and will remain in the log. The string lengths stored in the array *lengths* include the space for the null terminator of each string.

Any or all of the arrays *sources*, *types*, *ids*, *severities*, *lengths* and *messageLog* can also be NULL pointers, which causes attributes for such arrays to be discarded when messages are fetched. However, those messages will still be removed from the log. Thus to simply delete up to *count* messages from the message log while ignoring their attributes, the application can call **GetDebugMessageLog** with NULL pointers for all attribute arrays. If *messageLog* is NULL, the value of *bufSize* is ignored.

If the context is not a debug context, then the GL can opt to never add messages to the message log, so that **GetDebugMessageLog** will always return zero.

### Errors

An `INVALID_VALUE` error is generated if *bufSize* is negative.

The command

```
void GetObjectLabel( enum identifier, uint name,
                     sizei bufSize, sizei *length, char *label );
```

returns in *label* the string labelling an object. *identifier* and *name* specify the namespace and name of the object, and match the corresponding arguments of **ObjectLabel** (see section 20.7).

*label* will be null-terminated. The actual number of characters written into *label*, excluding the null terminator, is returned in *length*. If *length* is NULL, no length is returned. The maximum number of characters that may be written into *label*, including the null terminator, is specified by *bufSize*. If no debug label was specified for the object then *label* will contain a null-terminated empty string, and zero will be returned in *length*. If *label* is NULL and *length* is non-NULL then no string will be returned and the length of the label will be returned in *length*.

**Errors**

An `INVALID_ENUM` error is generated if *identifier* is not one of the object types listed in table 20.4.

An `INVALID_VALUE` error is generated if *name* is not the name of a valid object of the type specified by *identifier*.

An `INVALID_VALUE` error is generated if *bufSize* is negative.

The command

```
void GetObjectPtrLabel( void *ptr, sizei bufSize,  
                        size *length, char *label );
```

returns in *label* the string labelling the sync object identified by *ptr*. *bufSize*, *length*, and *label* match the corresponding arguments of **GetObjectLabel**.

**Errors**

An `INVALID_VALUE` error is generated if *ptr* is not the name of a sync object.

An `INVALID_VALUE` error is generated if *bufSize* is negative.



## Chapter 21

# Special Functions

This chapter describes additional functionality that does not fit easily into any of the preceding chapters, including hints influencing GL behavior (see section [21.5](#)).

### 21.1 Evaluators

This section is only defined in the compatibility profile.

### 21.2 Selection

This section is only defined in the compatibility profile.

### 21.3 Feedback

This section is only defined in the compatibility profile.

### 21.4 Display Lists

This section is only defined in the compatibility profile.

### 21.5 Hints

Certain aspects of GL behavior, when there is room for variation, may be controlled with hints. A hint is specified using

```
void Hint( enum target, enum hint );
```

Target	Hint description
LINE_SMOOTH_HINT	Line sampling quality
POLYGON_SMOOTH_HINT	Polygon sampling quality
TEXTURE_COMPRESSION_HINT	Quality and performance of texture image compression
FRAGMENT_SHADER_DERIVATIVE_HINT	Derivative accuracy for fragment processing built-in functions dFdx, dFdy and fwidth

Table 21.1: Hint targets and descriptions.

*target* is a symbolic constant indicating the behavior to be controlled, and *hint* is a symbolic constant indicating what type of behavior is desired. The possible *targets* are described in table 21.1. For each *target*, *hint* must be one of `FASTEST`, indicating that the most efficient option should be chosen; `NICEST`, indicating that the highest quality option should be chosen; and `DONT_CARE`, indicating no preference in the matter.

For the texture compression hint, a *hint* of `FASTEST` indicates that texture images should be compressed as quickly as possible, while `NICEST` indicates that the texture images be compressed with as little image degradation as possible. `FASTEST` should be used for one-time texture compression, and `NICEST` should be used if the compression results are to be retrieved by **GetCompressedTexImage** (section 8.11) for reuse.

The interpretation of hints is implementation-dependent. An implementation may ignore them entirely.

The initial value of all hints is `DONT_CARE`.

## 21.6 Saving and Restoring State

This section is only defined in the compatibility profile.

## Chapter 22

# Context State Queries

The state required to describe the GL machine is enumerated in chapter 23, and is set using commands described in previous chapters.

State that is part of GL objects can usually be queried using commands described together with the commands to set that state. Such commands operate either directly on a named object, or indirectly through a binding in the GL context (such as a currently bound framebuffer object).

The commands in this chapter describe queries for state directly associated with the context, rather than with an object. Data conversions may be done when querying context state, as described in section 2.2.2.

### 22.1 Simple Queries

Much of the GL state is completely identified by symbolic constants. The values of these state variables can be obtained using a set of **Get** commands.

Valid values of the symbolic constants allowed as parameter names to the various queries in this section are not summarized here, because there are many allowed parameters. Instead they are described elsewhere in the Specification together with the commands such state is relevant to, as well as in the state tables in chapter 23.

There are five commands for obtaining simple state variables:

```
void GetBooleanv( enum pname, boolean *data );  
void GetIntegerv( enum pname, int *data );  
void GetInteger64v( enum pname, int64 *data );  
void GetFloatv( enum pname, float *data );  
void GetDoublev( enum pname, double *data );
```

The commands obtain boolean, integer, 64-bit integer, floating-point, or double-precision state variables. *pname* is a symbolic constant indicating the state variable to return. *data* is a pointer to a scalar or array of the indicated type in which to place the returned data.

### Errors

An `INVALID_ENUM` error is generated if *pname* is not state queriable with these commands.

Indexed simple state variables are queried with the commands

```
void GetBooleani_v( enum target, uint index,
    boolean *data );
void GetIntegeri_v( enum target, uint index, int *data );
void GetFloati_v( enum target, uint index, float *data );
void GetDoublei_v( enum target, uint index, double *data );
void GetInteger64i_v( enum target, uint index,
    int64 *data );
```

*target* is the name of the indexed state and *index* is the index of the particular element being queried. *data* is a pointer to a scalar or array of the indicated type in which to place the returned data.

### Errors

An `INVALID_ENUM` error is generated if *target* is not indexed state queriable with these commands.

An `INVALID_VALUE` error is generated if *index* is outside the valid range for the indexed state *target*.

Finally,

```
boolean IsEnabled( enum cap );
```

can be used to determine if *cap* is currently enabled (as with **Enable**) or disabled, and

### Errors

An `INVALID_ENUM` error is generated if *cap* is not enable state queriable with **IsEnabled**.

An `INVALID_VALUE` error is generated if *index* is outside the valid range for the indexed state *target*.

```
boolean IsEnabledi( enum target, uint index );
```

can be used to determine if the indexed state corresponding to *target* and *index* is enabled or disabled.

### Errors

An `INVALID_ENUM` error is generated if *target* is not indexed enable state queriable with **IsEnabled**.

An `INVALID_VALUE` error is generated if *index* is outside the valid range for the indexed state *target*.

## 22.2 String Queries

Pointers in the current GL context are queried with the command

```
void GetPointerv( enum pname, void **params );
```

*pname* is a symbolic constant indicating the pointer to return. *params* is a pointer to a variable in which to place the single returned pointer value.

*pnames* of `DEBUG_CALLBACK_FUNCTION` and `DEBUG_CALLBACK_USER_PARAM`, return debug output state as described in section 20.9.

String queries return pointers to UTF-8 encoded, null-terminated static strings describing properties of the current GL context <sup>1</sup>. The command

```
ubyte *GetString( enum name );
```

accepts *name* values of `RENDERER`, `VENDOR`, `VERSION`, and `SHADING_LANGUAGE_VERSION`. The format of the `RENDERER` and `VENDOR` strings is implementation-dependent. The `VERSION` and `SHADING_LANGUAGE_VERSION` strings are laid out as follows:

```
<version number><space><vendor-specific information>
```

<sup>1</sup>Applications making copies of these static strings should never use a fixed-length buffer, because the strings may grow unpredictably between releases, resulting in buffer overflow when copying.

Value	OpenGL Profile
CONTEXT_CORE_PROFILE_BIT	Core
CONTEXT_COMPATIBILITY_PROFILE_BIT	Compatibility

Table 22.1: Context profile bits returned by the `CONTEXT_PROFILE_MASK` query.

The version number is either of the form *major\_number.minor\_number* or *major\_number.minor\_number.release\_number*, where the numbers all have one or more digits. The *minor\_number* for `SHADING_LANGUAGE_VERSION` is always two digits, matching the OpenGL Shading Language Specification release number. For example, this query might return the string "4.20" while the corresponding `VERSION` query returns "4.2". The *release\_number* and vendor specific information are optional. However, if present, then they pertain to the server and their format and contents are implementation-dependent.

**GetString** returns the version number (in the `VERSION` string) that can be supported by the current GL context. Thus, if the client and server support different versions a compatible version is returned.

The context version may also be queried by calling **GetIntegerv** with *values* `MAJOR_VERSION` and `MINOR_VERSION`, which respectively return the same values as *major\_number* and *minor\_number* in the `VERSION` string.

The profile implemented by the context may be queried by calling **GetIntegerv** with *value* `CONTEXT_PROFILE_MASK`, which returns a mask containing one of the bits in table 22.1, corresponding to the API profile implemented by the context (see appendix D.1).

Flags defining additional properties of the context may be queried by calling **GetIntegerv** with *value* `CONTEXT_FLAGS`. If `CONTEXT_FLAG_FORWARD_COMPATIBLE_BIT` is set in `CONTEXT_FLAGS`, then the context is a forward-compatible context as defined in appendix D, and the deprecated features described in that appendix are not supported; otherwise the context is a full context, and all features described in the specification are supported. If `CONTEXT_FLAG_DEBUG_BIT` is set in `CONTEXT_FLAGS`, then the context is a *debug context*, enabling full support for debug output as described in chapter 20.

Indexed strings are queried with the command

```
ubyte *GetStringi( enum name, uint index );
```

*name* is the name of the indexed state and *index* is the index of the particular element being queried.

If *name* is `EXTENSIONS`, the extension name corresponding to the *index*th supported extension will be returned. *index* may range from zero to the value of `NUM_EXTENSIONS` minus one. There is no defined relationship between any particular extension name and the *index* values; an extension name may correspond to a different *index* in different GL contexts and/or implementations.

If *name* is `SHADING_LANGUAGE_VERSION`, a version string for one of the supported versions of the OpenGL Shading Language and OpenGL ES Shading Language is returned. *index* may range from zero to the value of `NUM_SHADING_LANGUAGE_VERSIONS` minus one. The format of the returned string is identical to the text that may follow `#version` in shader program source and is formatted as the version number followed, for versions in which language profiles are defined, by a space and a profile name. For example, a returned string containing `"420 core"` indicates support for OpenGL Shading Language 4.20, core profile. An empty string indicates support for OpenGL Shading Language 1.10, which did not include the `#version` compiler directive. The profile string will always be present in the returned string when it is accepted by that version of the Shading Language, even though there is a default profile string in versions 1.50 and greater. Version strings `100` and `300 es` correspond to OpenGL ES Shading Language versions 100 and 300.

An *index* of zero will always return the string for the version of the most recent shading language supported by the GL and the profile of the shading language corresponding to the profile of the API (e.g. the first entry returned in an OpenGL 4.30 core profile context will be `"430 core"` and the first entry returned in an OpenGL 4.30 compatibility profile context will be `"430 compatibility"`). There is no defined ordering of the returned strings for other values of *index*.

#### Errors

An `INVALID_ENUM` error is generated if *name* is not `SHADING_LANGUAGE_VERSION` or `EXTENSIONS`.

An `INVALID_VALUE` error is generated if *index* is outside the valid range for the indexed state *name*.

## 22.3 Internal Format Queries

Information about implementation-dependent support for internal formats can be queried with the command

```
void GetInternalformat( enum target, enum internalformat,
                        enum pname, sizei bufSize, int *params );
```

Target	Usage
TEXTURE_1D	1D texture
TEXTURE_1D_ARRAY	1D array texture
TEXTURE_2D	2D texture
TEXTURE_2D_ARRAY	2D array texture
TEXTURE_2D_MULTISAMPLE	2D multisample texture
TEXTURE_2D_MULTISAMPLE_ARRAY	2D multisample array texture
TEXTURE_3D	3D texture
TEXTURE_BUFFER	buffer texture
TEXTURE_CUBE_MAP	cube map texture
TEXTURE_CUBE_MAP_ARRAY	cube map array texture
TEXTURE_RECTANGLE	rectangle texture
RENDERBUFFER	renderbuffer

Table 22.2: Possible targets that *internalformat* can be used with and the corresponding usage meaning.

```
void GetInternalformati64v( enum target,
    enum internalformat, enum pname, sizei bufSize,
    int64 *params );
```

*internalformat* can be any value. The `INTERNALFORMAT_SUPPORTED` *pname* can be used to determine if the internal format is supported, and the other *pnames* are defined in terms of whether or not the format is supported.

*target* indicates the usage of the *internalformat*, and must be one the targets listed in table 22.2.

No more than *bufSize* integers will be written into *params*. If more data are available, they will be ignored and no error will be generated.

*pname* indicates the information to query. The following list provides the valid values for *pname* and defines the meaning and the possible responses. In the following descriptions, the term *resource* is used to generically refer to an object of the appropriate type that has been created with *internalformat* and *target*. If the particular *target* and *internalformat* combination do not make sense, or if a particular type of *target* is not supported by the implementation the *unsupported* answer should be given. This is not an error.

All properties can be queried via either **GetInternalformat\*** command. Data conversions are done as defined in section 2.2.2.



For *pname* queries that return information about supported type of operation in *params*, they have the following meanings:

- NONE: the requested capability is not supported at all by the implementation.
- CAVEAT\_SUPPORT: the requested capability is supported by the implementation, but there may be some implementation-specific caveats that make support less than optimal. For example using the feature may result in reduced performance (relative to other formats or features), such as software rendering or other mechanisms of emulating the desired feature.

If a query reports that there is a caveat and the debug output functionality is enabled (see section 20), the GL will generate a debug output message describing the caveat. The message has the source `DEBUG_SOURCE_API`, the type `DEBUG_TYPE_PERFORMANCE`, and an implementation-dependent ID.

- FULL\_SUPPORT: the requested capability is fully supported by the implementation.

The supported values for *pname* and their meanings are:

- INTERNALFORMAT\_SUPPORTED: If *internalformat* is an internal format that is supported by the implementation in at least some subset of possible operations, `TRUE` is written to *params*. If *internalformat* is not a valid token for any internal format usage, `FALSE` is returned.

*internalformats* that must be supported include:

- sized internal formats from tables 8.12- 8.13 and 8.15,
- any specific compressed internal format from table 8.14,
- any image unit format from table 8.25,
- any generic compressed internal format from table 8.14, if the implementation accepts it for any texture specification commands, and
- any unsized or base internal format, if the implementation accepts it for texture or image specification.

In other words, any *internalformat* accepted by any of the commands: **ClearBufferData**, **ClearBufferSubData**, **CompressedTexImage1D**, **CompressedTexImage2D**, **CompressedTexImage3D**, **CopyTexImage1D**, **CopyTexImage2D**, **RenderbufferStorage**, **RenderbufferStorageMultisample**, **TexBuffer**, **TexImage1D**, **TexImage2D**, **TexIm-**

**age3D**, **TexImage2DMultisample**, **TexImage3DMultisample**, **TexStorage1D**, **TexStorage2D**, **TexStorage3D**, **TexStorage2DMultisample**, **TexStorage3DMultisample**, and **TextureView**, and any valid *format* accepted by **BindImageTexture**, must be supported.

- **NUM\_SAMPLE\_COUNTS**: The number of sample counts that would be returned by querying **SAMPLES** is returned in *params*.
  - If *internalformat* is not color-renderable, depth-renderable, or stencil-renderable (as defined in section 9.4), or if *target* does not support multiple samples (ie other than **TEXTURE\_2D\_MULTISAMPLE**, **TEXTURE\_2D\_MULTISAMPLE\_ARRAY**, or **RENDERBUFFER**), zero is returned.
- **SAMPLES**: The sample counts supported for *internalformat* and *target* are written into *params*, in descending numeric order. Only positive values are returned.
  - Note that querying **SAMPLES** with a *bufSize* of 1 will return just the maximum supported number of samples for this format.
  - The maximum value in **SAMPLES** is guaranteed to be at least the lowest of the following:
    - \* The value of **MAX\_INTEGER\_SAMPLES**, if *internalformat* is a signed or unsigned integer format.
    - \* The value of **MAX\_DEPTH\_TEXTURE\_SAMPLES**, if *internalformat* is a depth/stencil-renderable format and *target* is **TEXTURE\_2D\_MULTISAMPLE** or **TEXTURE\_2D\_MULTISAMPLE\_ARRAY**.
    - \* The value of **MAX\_COLOR\_TEXTURE\_SAMPLES**, if *internalformat* is a color-renderable format and *target* is **TEXTURE\_2D\_MULTISAMPLE** or **TEXTURE\_2D\_MULTISAMPLE\_ARRAY**.
    - \* The value of **MAX\_SAMPLES**.
  - If *internalformat* is not color-renderable, depth-renderable, or stencil-renderable (as defined in section 9.4), or if *target* does not support multiple samples (ie other than **TEXTURE\_2D\_MULTISAMPLE**, **TEXTURE\_2D\_MULTISAMPLE\_ARRAY**, or **RENDERBUFFER**), *params* is not modified.
- **INTERNALFORMAT\_PREFERRED**: The implementation-preferred internal format for representing resources of the specified *internalformat* is returned

in *params*. The preferred internal format should have no less precision than the requested one. If the specified *internalformat* is already a preferred format, or if there is no better format that is compatible, the queried *internalformat* value is written to *params*. If the *internalformat* is not supported, NONE is returned.

- INTERNALFORMAT\_RED\_SIZE, INTERNALFORMAT\_GREEN\_SIZE, INTERNALFORMAT\_BLUE\_SIZE, INTERNALFORMAT\_ALPHA\_SIZE, INTERNALFORMAT\_DEPTH\_SIZE, INTERNALFORMAT\_STENCIL\_SIZE, or INTERNALFORMAT\_SHARED\_SIZE

For uncompressed internal formats, queries of these values return the actual resolutions that would be used for storing image array components for the resource. For compressed internal formats, the resolutions returned specify the component resolution of an uncompressed internal format that produces an image of roughly the same quality as the compressed algorithm. For textures this query will return the same information as querying **GetTexLevelParameter\*** for TEXTURE\_\*\_SIZE would return. If the internal format is unsupported, or if a particular component is not present in the format, 0 is written to *params*.

- INTERNALFORMAT\_RED\_TYPE, INTERNALFORMAT\_GREEN\_TYPE, INTERNALFORMAT\_BLUE\_TYPE, INTERNALFORMAT\_ALPHA\_TYPE, INTERNALFORMAT\_DEPTH\_TYPE, or INTERNALFORMAT\_STENCIL\_TYPE

For uncompressed internal formats, queries for these values return the data type used to store the component. For compressed internal formats the types returned specify how components are interpreted after decompression. For textures this query returns the same information as querying **GetTexLevelParameter\*** for TEXTURE\_\*\_TYPE would return. Possible values returned include NONE, SIGNED\_NORMALIZED, UNSIGNED\_NORMALIZED, FLOAT, INT, and UNSIGNED\_INT, representing missing, signed normalized fixed point, unsigned normalized fixed point, floating-point, signed unnormalized integer, and unsigned unnormalized integer components respectively. NONE is returned for all component types if the format is unsupported.

- MAX\_WIDTH: The maximum supported width for the resource is returned in *params*. For resources with only one-dimension, this one dimension is considered the width. If the resource is unsupported, zero is returned.
- MAX\_HEIGHT: The maximum supported height for the resource is returned in *params*. For resources with two or more dimensions, the second dimension

is considered the height. If the resource does not have at least two dimensions, or if the resource is unsupported, zero is returned.

- **MAX\_DEPTH**: The maximum supported depth for the resource is returned in *params*. For resources with three or more dimensions, the third dimension is considered the depth. If the resource does not have at least three dimensions, or if the resource is unsupported, zero is returned.
- **MAX\_LAYERS**: The maximum supported number of layers for the resource is returned in *params*. For 1D array targets, the value returned is the same as the **MAX\_HEIGHT**. For 2D and cube array targets, the value returned is the same as the **MAX\_DEPTH**. If the resource does not support layers, or if the resource is unsupported, zero is returned.
- **MAX\_COMBINED\_DIMENSIONS**: The maximum combined dimensions for the resource is returned in *params*. The combined dimensions is the product of the individual dimensions of the resource. For multisampled surfaces the number of samples is considered an additional dimension. Note that the value returned can be  $\geq 2^{32}$  and should be queried with **GetInternalFormati64v**.

This value should be considered a recommendations for applications. There may be system-dependant reasons why allocations larger than this size may fail, even if there might appear to be sufficient memory available when queried via some other means. This also does not provide a guarantee that allocations smaller than this will succeed because this value is not affected by existing resource allocations.

For one-dimensional targets this is the maximum single dimension. For one-dimensional array targets this is the maximum combined width and layers. For two-dimensional targets this is the maximum combined width and height. For two-dimensional multisample targets this is the combined width, height and samples. For two-dimensional array targets this is the max combined width, height and layers. For two-dimensional multisample array targets, this is the max combined width, height, layers and samples. For three-dimensional targets this is the maximum combined width, height and depth. For cube map targets this is the maximum combined width, height and faces. For cube map array targets this is the maximum width, height and layer-faces. If the resource is unsupported, zero is returned.

- **COLOR\_COMPONENTS**: If the internal format contains any color components (R, G, B, or A), **TRUE** is returned in *params*. If the internal format is unsupported or contains no color components, **FALSE** is returned.

- `DEPTH_COMPONENTS`: If the internal format contains a depth component (D), `TRUE` is returned in *params*. If the internal format is unsupported or contains no depth component, `FALSE` is returned.
- `STENCIL_COMPONENTS`: If the internal format contains a stencil component (S), `TRUE` is returned in *params*. If the internal format is unsupported or contains no stencil component, `FALSE` is returned.
- `COLOR_RENDERABLE`: If *internalformat* is color-renderable (as defined in section 9.4), `TRUE` is returned in *params*. If the internal format is unsupported, or the internal format is not color-renderable, `FALSE` is returned.
- `DEPTH_RENDERABLE`: If *internalformat* is depth-renderable (as defined in section 9.4), `TRUE` is returned in *params*. If the internal format is unsupported, or if the internal format is not depth-renderable, `FALSE` is returned.
- `STENCIL_RENDERABLE`: If *internalformat* is stencil-renderable (as defined in section 9.4), `TRUE` is returned in *params*. If the internal format is unsupported, or if the internal format is not stencil-renderable, `FALSE` is returned.
- `FRAMEBUFFER_RENDERABLE`: The support for rendering to the resource via framebuffer attachment is returned in *params*. Possible values returned are `FULL_SUPPORT`, `CAVEAT_SUPPORT`, or `NONE`. If the resource is unsupported, `NONE` is returned.
- `FRAMEBUFFER_RENDERABLE_LAYERED`: The support for layered rendering to the resource via framebuffer attachment is returned in *params*. Possible values returned are `FULL_SUPPORT`, `CAVEAT_SUPPORT`, or `NONE`. If the resource is unsupported, `NONE` is returned.
- `FRAMEBUFFER_BLEND`: The support for rendering to the resource via framebuffer attachment when blending is enabled is returned in *params*. Possible values returned are `FULL_SUPPORT`, `CAVEAT_SUPPORT`, or `NONE`. If the resource is unsupported, `NONE` is returned.
- `READ_PIXELS`: The support for reading pixels from the resource when it is attached to a framebuffer is returned in *params*. Possible values returned are `FULL_SUPPORT`, `CAVEAT_SUPPORT`, or `NONE`. If the resource is unsupported, `NONE` is returned.
- `READ_PIXELS_FORMAT`: The *format* to pass to **ReadPixels** to obtain the best performance and image quality when reading from framebuffers with *internalformat* is returned in *params*. Possible values include any value that

is legal to pass for the *format* parameter to **ReadPixels**, or `NONE` if *internal-format* is not supported or can never be a valid source for **ReadPixels**.

- `READ_PIXELS_TYPE`: The *type* to pass to **ReadPixels** to obtain the best performance and image quality when reading from framebuffers with *internal-format* is returned in *params*. Possible values include any value that is legal to pass for the *type* parameter to **ReadPixels**, or `NONE` if the internal format is not supported or can never be a source for **ReadPixels**.
- `TEXTURE_IMAGE_FORMAT`: The implementation-preferred *format* to pass to **TexImage\*D** or **TexSubImage\*D** when specifying texture image data for this resource is returned in *params*. Possible values include any value that is legal to pass for the *format* parameter to the **Tex\*Image\*D** commands, or `NONE` if the resource is not supported for this operation.
- `TEXTURE_IMAGE_TYPE`: The implementation-preferred *type* to pass to **TexImage\*D** or **TexSubImage\*D** when specifying texture image data for this resource is returned in *params*. Possible values include any value that is legal to pass for the *type* parameter to the **Tex\*Image\*D** commands, or `NONE` if the resource is not supported for this operation.
- `GET_TEXTURE_IMAGE_FORMAT`: The implementation-preferred *format* to pass to **GetTexImage** when querying texture image data from this resource. Possible values include any value that is legal to pass for the *format* parameter to **GetTexImage**, or `NONE` if the resource does not support this operation, or if **GetTexImage** is not supported.
- `GET_TEXTURE_IMAGE_TYPE`: The implementation-preferred *type* to pass to **GetTexImage** when querying texture image data from this resource. Possible values include any value that is legal to pass for the *type* parameter to **GetTexImage**, or `NONE` if the resource does not support this operation, or if **GetTexImage** is not supported.
- `MIPMAP`: If the resource supports mipmaps, `TRUE` is returned in *params*. If the resource is not supported, or if mipmaps are not supported for this type of resource, `FALSE` is returned.
- `MANUAL_GENERATE_MIPMAP`: The support for manually generating mipmaps for the resource is returned in *params*. Possible values returned are `FULL_SUPPORT`, `CAVEAT_SUPPORT`, or `NONE`. If the resource is not supported, or if the operation is not supported, `NONE` is returned.

- **COLOR\_ENCODING**: The color encoding for the resource is returned in *params*. Possible values for color buffers are `LINEAR` or `SRGB`, for linear or sRGB-encoded color components, respectively. For non-color formats (such as depth or stencil), or for unsupported resources, the value `NONE` is returned.
- **SRGB\_READ**: The support for converting from sRGB colorspace on read operations (see section 8.23) from the resource is returned in *params*. Possible values returned are `FULL_SUPPORT`, `CAVEAT_SUPPORT`, or `NONE`. If the resource or operation is not supported, `NONE` is returned.
- **SRGB\_WRITE**: The support for converting to sRGB colorspace on write operations to the resource is returned in *params*. This indicates that writing to framebuffers with this internalformat will encode to sRGB color spaces when `FRAMEBUFFER_SRGB` is enabled (see section 17.3.9). Possible values returned are `FULL_SUPPORT`, `CAVEAT_SUPPORT`, or `NONE`. If the resource or operation is not supported, `NONE` is returned.
- **FILTER**: The support for filter types other than `NEAREST` or `NEAREST_MIPMAP_NEAREST` for the resource is written to *params*. This indicates if sampling from such resources supports setting the `MIN/MAG` filters to `LINEAR` values. Possible values returned are `FULL_SUPPORT`, `CAVEAT_SUPPORT`, or `NONE`. If the resource or operation is not supported, `NONE` is returned.
- **VERTEX\_TEXTURE**: The support for using the resource as a source for texture sampling in a vertex shader is written to *params*. Possible values returned are `FULL_SUPPORT`, `CAVEAT_SUPPORT`, or `NONE`. If the resource or operation is not supported, `NONE` is returned.
- **TESS\_CONTROL\_TEXTURE**: The support for using the resource as a source for texture sampling in a tessellation control shader is written to *params*. Possible values returned are `FULL_SUPPORT`, `CAVEAT_SUPPORT`, or `NONE`. If the resource or operation is not supported, `NONE` is returned.
- **TESS\_EVALUATION\_TEXTURE**: The support for using the resource as a source for texture sampling in a tessellation evaluation shader is written to *params*. Possible values returned are `FULL_SUPPORT`, `CAVEAT_SUPPORT`, or `NONE`. If the resource or operation is not supported, `NONE` is returned.
- **GEOMETRY\_TEXTURE**: The support for using the resource as a source for texture sampling in a geometry shader is written to *params*. Possible values

returned are `FULL_SUPPORT`, `CAVEAT_SUPPORT`, or `NONE`. If the resource or operation is not supported, `NONE` is returned.

- `FRAGMENT_TEXTURE`: The support for using the resource as a source for texture sampling in a fragment shader is written to *params*. Possible values returned are `FULL_SUPPORT`, `CAVEAT_SUPPORT`, or `NONE`. If the resource or operation is not supported, `NONE` is returned.
- `COMPUTE_TEXTURE`: The support for using the resource as a source for texture sampling in a compute shader is written to *params*. Possible values returned are `FULL_SUPPORT`, `CAVEAT_SUPPORT`, or `NONE`. If the resource or operation is not supported, `NONE` is returned.
- `TEXTURE_SHADOW`: The support for using the resource with shadow samplers is written to *params*. Possible values returned are `FULL_SUPPORT`, `CAVEAT_SUPPORT`, or `NONE`. If the resource or operation is not supported, `NONE` is returned.
- `TEXTURE_GATHER`: The support for using the resource with texture gather operations is written to *params*. Possible values returned are `FULL_SUPPORT`, `CAVEAT_SUPPORT`, or `NONE`. If the resource or operation is not supported, `NONE` is returned.
- `TEXTURE_GATHER_SHADOW`: The support for using resource with texture gather operations with shadow samplers is written to *params*. Possible values returned are `FULL_SUPPORT`, `CAVEAT_SUPPORT`, or `NONE`. If the resource or operation is not supported, `NONE` is returned.
- `SHADER_IMAGE_LOAD`: The support for using the resource with image load operations in shaders is written to *params*. In this case the *internalformat* is the value of the *format* parameter that would be passed to **BindImageTexture**. Possible values returned are `FULL_SUPPORT`, `CAVEAT_SUPPORT`, or `NONE`. If the resource or operation is not supported, `NONE` is returned.
- `SHADER_IMAGE_STORE`: The support for using the resource with image store operations in shaders is written to *params*. In this case the *internalformat* is the value of the *format* parameter that is passed to **BindImageTexture**. Possible values returned are `FULL_SUPPORT`, `CAVEAT_SUPPORT`, or `NONE`. If the resource or operation is not supported, `NONE` is returned.
- `SHADER_IMAGE_ATOMIC`: The support for using the resource with atomic memory operations from shaders is written to *params*. Possible values re-



turned are `FULL_SUPPORT`, `CAVEAT_SUPPORT`, or `NONE`. If the resource or operation is not supported, `NONE` is returned.

- `IMAGE_TEXEL_SIZE`: The size of a texel when the resource when used as an image texture is returned in *params*. This is the value from the **Size** column in table 8.26. If the resource is not supported for image textures, or if image textures are not supported, zero is returned.
- `IMAGE_COMPATIBILITY_CLASS`: The compatibility class of the resource when used as an image texture is returned in *params*. This corresponds to the value from the **Class** column in table 8.26. The possible values returned are `IMAGE_CLASS_4_X_32`, `IMAGE_CLASS_2_X_32`, `IMAGE_CLASS_1_X_32`, `IMAGE_CLASS_4_X_16`, `IMAGE_CLASS_2_X_16`, `IMAGE_CLASS_1_X_16`, `IMAGE_CLASS_4_X_8`, `IMAGE_CLASS_2_X_8`, `IMAGE_CLASS_1_X_8`, `IMAGE_CLASS_11_11_10`, and `IMAGE_CLASS_10_10_10_2`, which correspond to the 4x32, 2x32, 1x32, 4x16, 2x16, 1x16, 4x8, 2x8, 1x8, the class (a) 11/11/10 packed floating-point format, and the class (b) 10/10/10/2 packed formats, respectively. If the resource is not supported for image textures, or if image textures are not supported, `NONE` is returned.
- `IMAGE_PIXEL_FORMAT`: The pixel format of the resource when used as an image texture is returned in *params*. This is the value from the **Pixel format** column in table 8.26. If the resource is not supported for image textures, or if image textures are not supported, `NONE` is returned.
- `IMAGE_PIXEL_TYPE`: The pixel type of the resource when used as an image texture is returned in *params*. This is the value from the **Pixel type** column in table 8.26. If the resource is not supported for image textures, or if image textures are not supported, `NONE` is returned.
- `IMAGE_FORMAT_COMPATIBILITY_TYPE`: The matching criteria use for the resource when used as an image textures is returned in *params*. This is equivalent to calling **GetTexParameter** with *value* set to `IMAGE_FORMAT_COMPATIBILITY_TYPE`. Possible values are `IMAGE_FORMAT_COMPATIBILITY_BY_SIZE` or `IMAGE_FORMAT_COMPATIBILITY_BY_CLASS`. If the resource is not supported for image textures, or if image textures are not supported, `NONE` is returned.
- `SIMULTANEOUS_TEXTURE_AND_DEPTH_TEST`: The support for using the resource both as a source for texture sampling while it is bound as a buffer

for depth test is written to *params*. For example, a depth (or stencil) texture could be bound simultaneously for texturing while it is bound as a depth (and/or stencil) buffer without causing a feedback loop, provided that depth writes are disabled. Possible values returned are `FULL_SUPPORT`, `CAVEAT_SUPPORT`, or `NONE`. If the resource or operation is not supported, `NONE` is returned.

- `SIMULTANEOUS_TEXTURE_AND_STENCIL_TEST`: The support for using the resource both as a source for texture sampling while it is bound as a buffer for stencil test is written to *params*. For example, a depth (or stencil) texture could be bound simultaneously for texturing while it is bound as a depth (and/or stencil) buffer without causing a feedback loop, provided that stencil writes are disabled. Possible values returned are `FULL_SUPPORT`, `CAVEAT_SUPPORT`, or `NONE`. If the resource or operation is not supported, `NONE` is returned.
- `SIMULTANEOUS_TEXTURE_AND_DEPTH_WRITE`: The support for using the resource both as a source for texture sampling while performing depth writes to the resources is written to *params*. For example, a depth-stencil texture could be bound simultaneously for stencil texturing while it is bound as a depth buffer. Feedback loops cannot occur because sampling a stencil texture only returns the stencil portion, and thus writes to the depth buffer do not modify the stencil portions. Possible values returned are `FULL_SUPPORT`, `CAVEAT_SUPPORT`, or `NONE`. If the resource or operation is not supported, `NONE` is returned.
- `SIMULTANEOUS_TEXTURE_AND_STENCIL_WRITE`: The support for using the resource both as a source for texture sampling while performing stencil writes to the resources is written to *params*. For example, a depth-stencil texture could be bound simultaneously for depth-texturing while it is bound as a stencil buffer. Feedback loops cannot occur because sampling a depth texture only returns the depth portion, and thus writes to the stencil buffer could not modify the depth portions. Possible values returned are `FULL_SUPPORT`, `CAVEAT_SUPPORT`, or `NONE`. If the resource or operation is not supported, `NONE` is returned.
- `TEXTURE_COMPRESSED`: If *internalformat* is a compressed format that is supported for this type of resource, `TRUE` is returned in *params*. If the internal format is not compressed, or the type of resource is not supported, `FALSE` is returned.

- **TEXTURE\_COMPRESSED\_BLOCK\_WIDTH**: If the resource contains a compressed format, the width of a compressed block (in bytes) is returned in *params*. If the internal format is not compressed, or the resource is not supported, 0 is returned.
- **TEXTURE\_COMPRESSED\_BLOCK\_HEIGHT**: If the resource contains a compressed format, the height of a compressed block (in bytes) is returned in *params*. If the internal format is not compressed, or the resource is not supported, 0 is returned.
- **TEXTURE\_COMPRESSED\_BLOCK\_SIZE**: If the resource contains a compressed format the number of bytes per block is returned in *params*. If the internal format is not compressed, or the resource is not supported, 0 is returned. (combined with the above, allows the bitrate to be computed, and may be useful in conjunction with `ARB_compressed_texture_pixel_storage`).
- **CLEAR\_BUFFER**: The support for using the resource with **ClearBuffer\*Data** commands is returned in *params*. Possible values returned are `FULL_SUPPORT`, `CAVEAT_SUPPORT`, or `NONE`. If the resource or operation is not supported, `NONE` is returned.
- **TEXTURE\_VIEW**: The support for using the resource with the **TextureView** command is returned in *params*. Possible values returned are `FULL_SUPPORT`, `CAVEAT_SUPPORT`, or `NONE`. If the resource or operation is not supported, `NONE` is returned.
- **VIEW\_COMPATIBILITY\_CLASS**: The compatibility class of the resource when used as a texture view is returned in *params*. This corresponds to the value from the **Class** column in table 8.21. The possible values returned are `VIEW_CLASS_128_BITS`, `VIEW_CLASS_96_BITS`, `VIEW_CLASS_64_BITS`, `VIEW_CLASS_48_BITS`, `VIEW_CLASS_32_BITS`, `VIEW_CLASS_24_BITS`, `VIEW_CLASS_16_BITS`, `VIEW_CLASS_8_BITS`, `VIEW_CLASS_RGTC1_RED`, `VIEW_CLASS_RGTC2_RG`, `VIEW_CLASS_BPTC_UNORM`, and `VIEW_CLASS_BPTC_FLOAT`. If the resource has no other formats that are compatible, if resource does not support views, or if texture views are not supported, `NONE` is returned.

### Errors

An `INVALID_ENUM` error is generated if *target* is not one of the targets in

table 22.2, or if *pname* is not one of the parameters described above.  
An `INVALID_VALUE` error is generated if *bufSize* is negative.

## Chapter 23

# State Tables

The tables on the following pages indicate which state variables are obtained with what commands. State variables that can be obtained using any of **GetBooleanv**, **GetIntegerv**, **GetInteger64v**, **GetFloatv**, or **GetDoublev** are listed with just one of these commands – the one that is most appropriate given the type of the data to be returned. These state variables cannot be obtained using **IsEnabled**. However, state variables for which **IsEnabled** is listed as the query command can also be obtained using **GetBooleanv**, **GetIntegerv**, **GetInteger64v**, **GetFloatv**, and **GetDoublev**. State variables for which any other command is listed as the query command can be obtained by using that command or any of its typed variants, although information may be lost when not using the listed command. Unless otherwise specified, when floating-point state is returned as integer values or integer state is returned as floating-point values it is converted in the fashion described in section 2.2.2.

State table entries indicate a type for each variable. Table 23.1 explains these types. The type actually identifies all state associated with the indicated description; in certain cases only a portion of this state is returned. This is the case with textures, where only the selected texture or texture parameter is returned.

The  $M$  and  $m$  entries for initial minmax table values represent the maximum and minimum possible representable values, respectively.

The abbreviations *max*, *min*, and *no.* are used interchangeably with *maximum*, *minimum*, and *number*, respectively, to help fit tables without overflowing pages.

Type code	Explanation
$B$	Boolean
$BMU$	Basic machine units
$C$	Color (floating-point R, G, B, and A values)
$E$	Enumerated value (as described in spec body)
$Z$	Integer
$Z^+$	Non-negative integer or enumerated value
$Z_k, Z_{k*}$	$k$ -valued integer ( $k*$ indicates $k$ is minimum)
$R$	Floating-point number
$R^+$	Non-negative floating-point number
$R^{[a,b]}$	Floating-point number in the range $[a, b]$
$R^k$	$k$ -tuple of floating-point numbers
$S$	null-terminated string
$I$	Image
$Y$	Pointer (data type unspecified)
$n \times type$	$n$ copies of type $type$ ( $n*$ indicates $n$ is minimum)

Table 23.1: State Variable Types

Get value	Type	Get Command	Initial Value	Description	Sec.
PATCH_VERTICES	$Z^+$	<b>GetIntegerv</b>	3	No. of vertices in input patch	<b>10.1</b>
PATCH_DEFAULT_OUTER_LEVEL	$4 \times R$	<b>GetFloatv</b>	(1.0, 1.0, 1.0, 1.0)	Default outer tess. level w/o control shader	<b>11.2.2</b>
PATCH_DEFAULT_INNER_LEVEL	$2 \times R$	<b>GetFloatv</b>	(1.0, 1.0)	Default inner tess. level w/o control shader	<b>11.2.2</b>

Table 23.2. Current Values and Associated Data

Get value	Type	Get Command	Initial Value	Description	Sec.
VERTEX_ATTRIB_ARRAY_ENABLED	$16 * \times B$	<b>GetVertexAttribiv</b>	FALSE	Vertex attrib array enable	<b>10.3</b>
VERTEX_ATTRIB_ARRAY_SIZE	$16 * \times Z_5$	<b>GetVertexAttribiv</b>	4	Vertex attrib array size	<b>10.3</b>
VERTEX_ATTRIB_ARRAY_STRIDE	$16 * \times Z^+$	<b>GetVertexAttribiv</b>	0	Vertex attrib array stride	<b>10.3</b>
VERTEX_ATTRIB_ARRAY_TYPE	$16 * \times E$	<b>GetVertexAttribiv</b>	FLOAT	Vertex attrib array type	<b>10.3</b>
VERTEX_ATTRIB_ARRAY_NORMALIZED	$16 * \times B$	<b>GetVertexAttribiv</b>	FALSE	Vertex attrib array normalized	<b>10.3</b>
VERTEX_ATTRIB_ARRAY_INTEGER	$16 * \times B$	<b>GetVertexAttribiv</b>	FALSE	Vertex attrib array has unconverted integers	<b>10.3</b>
VERTEX_ATTRIB_ARRAY_LONG	$16 * \times B$	<b>GetVertexAttribiv</b>	FALSE	Vertex attrib array has unconverted doubles	<b>10.3</b>
VERTEX_ATTRIB_ARRAY_DIVISOR	$16 * \times Z^+$	<b>GetVertexAttribiv</b>	0	Vertex attrib array instance divisor	<b>10.5</b>
VERTEX_ATTRIB_ARRAY_POINTER	$16 * \times Y$	<b>GetVertexAttribPointer</b>	NULL	Vertex attrib array pointer	<b>10.3</b>
LABEL	$S$	<b>GetObjectLabel</b>	empty	Debug label	<b>20.9</b>

Table 23.3. Vertex Array Object State (cont.)



Get value	Type	Get Command	Initial Value	Description	Sec.
ELEMENT_ARRAY_BUFFER_BINDING	$Z^+$	<b>GetIntegerv</b>	0	Element array buffer binding	<b>10.3.9</b>
VERTEX_ATTRIB_ARRAY_BUFFER_BINDING	$16 * \times Z^+$	<b>GetVertexAttribiv</b>	0	Attribute array buffer binding	<b>6</b>
VERTEX_ATTRIB_BINDING	$16 \times Z_{16*}$	<b>GetVertexAttribiv</b>	$i^\dagger$	Vertex buffer binding used by vertex attrib $i$	<b>10.3</b>
VERTEX_ATTRIB_RELATIVE_OFFSET	$16 \times Z$	<b>GetVertexAttribiv</b>	0	Byte offset added to vertex binding offset for this attribute	<b>10.3</b>
VERTEX_BINDING_OFFSET	$16 \times Z$	<b>GetInteger64i_v</b>	0	Byte offset of the first element in the bound buffer's data store	<b>10.3</b>
VERTEX_BINDING_STRIDE	$16 \times Z$	<b>GetIntegeri_v</b>	16	Vertex binding stride	<b>10.3</b>

Table 23.4. Vertex Array Object State (cont.)

† The  $i$ th attribute defaults to a value of  $i$ .

Get value	Type	Get Command	Initial Value	Description	Sec.
ARRAY_BUFFER_BINDING	$Z^+$	<b>GetInteger</b>	0	Current buffer binding	<b>6</b>
DRAW_INDIRECT_BUFFER_BINDING	$Z^+$	<b>GetInteger</b>	0	Indirect command buffer binding	<b>10.3.10</b>
VERTEX_ARRAY_BINDING	$Z^+$	<b>GetInteger</b>	0	Current vertex array object binding	<b>10.4</b>
PRIMITIVE_RESTART	$B$	<b>IsEnabled</b>	FALSE	Primitive restart enable	<b>10.3</b>
PRIMITIVE_RESTART_INDEX	$Z^+$	<b>GetInteger</b>	0	Primitive restart index	<b>10.3</b>

Table 23.5. Vertex Array Data (not in Vertex Array objects)

Get value	Type	Get Command	Initial Value	Description	Sec.
-	$n \times BMU$	<b>GetBufferSubData</b>	-	Buffer data	<b>6</b>
BUFFER_SIZE	$n \times Z^+$	<b>GetBufferParameteriv</b>	0	Buffer data size	<b>6</b>
BUFFER_USAGE	$n \times E$	<b>GetBufferParameteriv</b>	STATIC_DRAW	Buffer usage pattern	<b>6</b>
BUFFER_ACCESS	$n \times E$	<b>GetBufferParameteriv</b>	READ_WRITE	Buffer access flag	<b>6.3</b>
BUFFER_ACCESS_FLAGS	$n \times Z^+$	<b>GetBufferParameteriv</b>	0	Extended buffer access flag	<b>6.3</b>
BUFFER_MAPPED	$n \times B$	<b>GetBufferParameteriv</b>	FALSE	Buffer map flag	<b>6.3</b>
BUFFER_MAP_POINTER	$n \times Y$	<b>GetBufferPointerv</b>	NULL	Mapped buffer pointer	<b>6.3</b>
BUFFER_MAP_OFFSET	$n \times Z^+$	<b>GetBufferParameteriv</b>	0	Start of mapped buffer range	<b>6.3</b>
BUFFER_MAP_LENGTH	$n \times Z^+$	<b>GetBufferParameteriv</b>	0	Size of mapped buffer range	<b>6.3</b>
LABEL	$S$	<b>GetObjectLabel</b>	empty	Debug label	<b>20.9</b>

Table 23.6. Buffer Object State

Get value	Type	Get Command	Initial Value	Description	Sec.
VIEWPORT	$16 * 4 \times R$	<b>GetFloati_v</b>	see sec. <b>13.6.1</b>	Viewport origin & extent	<b>13.6.1</b>
DEPTHRANGE	$16 * R^{[0,1]}$	<b>GetDoublei_v</b>	0,1	Depth range near & far	<b>13.6.1</b>
CLIP_DISTANCEz	$6 * B$	<b>IsEnabled</b>	FALSE	<i>i</i> th user clipping plane enabled	<b>13.5</b>
DEPTHCLAMP	$B$	<b>IsEnabled</b>	FALSE	Depth clamping enabled	<b>13.5</b>
TRANSFORM_FEEDBACK_BINDING	$Z^+$	<b>GetIntegerv</b>	0	Object bound for transform feedback operations	<b>13.2</b>

Table 23.7. Transformation state

Get value	Type	Get Command	Initial Value	Description	Sec.
CLAMP.READ.COLOR	<i>E</i>	<b>GetIntegerv</b>	FIXED_ONLY	Read color clamping	18.2.6
PROVOKING.VERTEX	<i>E</i>	<b>GetIntegerv</b>	LAST_VERTEX_CONVENTION	Provoking vertex convention	13.4

Table 23.8. Coloring

Get value	Type	Get Command	Initial Value	Description	Sec.
RASTERIZER-DISCARD	<i>B</i>	<b>IsEnabled</b>	FALSE	Discard primitives before rasterization	14.1
POINT-SIZE	<i>R</i> <sup>+</sup>	<b>GetFloatv</b>	1.0	Point size	14.4
POINT-FADE-THRESHOLD-SIZE	<i>R</i> <sup>+</sup>	<b>GetFloatv</b>	1.0	Threshold for alpha attenuation	14.4
POINT-SPRITE-COORD-ORIGIN	<i>E</i>	<b>GetIntegerv</b>	UPPER_LEFT	Origin orientation for point sprites	14.4
LINE-WIDTH	<i>R</i> <sup>+</sup>	<b>GetFloatv</b>	1.0	Line width	14.5
LINE-SMOOTH	<i>B</i>	<b>IsEnabled</b>	FALSE	Line antialiasing on	14.5

Table 23.9. Rasterization

Get value	Type	Get Command	Initial Value	Description	Sec.
CULL_FACE	<i>B</i>	<b>IsEnabled</b>	FALSE	Polygon culling enabled	<b>14.6.1</b>
CULL_FACE_MODE	<i>E</i>	<b>GetIntegerv</b>	BACK	Cull front-/back-facing polygons	<b>14.6.1</b>
FRONT_FACE	<i>E</i>	<b>GetIntegerv</b>	CCW	Polygon frontface CW/CCW indicator	<b>14.6.1</b>
POLYGON_SMOOTH	<i>B</i>	<b>IsEnabled</b>	FALSE	Polygon antialiasing on	<b>14.6</b>
POLYGON_MODE	<i>E</i>	<b>GetIntegerv</b>	FILL	Polygon rasterization mode (front & back)	<b>14.6.4</b>
POLYGON_OFFSET_FACTOR	<i>R</i>	<b>GetFloatv</b>	0	Polygon offset factor	<b>14.6.5</b>
POLYGON_OFFSET_UNITS	<i>R</i>	<b>GetFloatv</b>	0	Polygon offset units	<b>14.6.5</b>
POLYGON_OFFSET_POINT	<i>B</i>	<b>IsEnabled</b>	FALSE	Polygon offset enable for POINT mode rasterization	<b>14.6.5</b>
POLYGON_OFFSET_LINE	<i>B</i>	<b>IsEnabled</b>	FALSE	Polygon offset enable for LINE mode rasterization	<b>14.6.5</b>
POLYGON_OFFSET_FILL	<i>B</i>	<b>IsEnabled</b>	FALSE	Polygon offset enable for FILL mode rasterization	<b>14.6.5</b>

Table 23.10. Rasterization (cont.)

Get value	Type	Get Command	Initial Value	Description	Sec.
MULTISAMPLE	$B$	<b>IsEnabled</b>	TRUE	Multisample rasterization	<a href="#">14.3.1</a>
SAMPLE_ALPHA_TO_COVERAGE	$B$	<b>IsEnabled</b>	FALSE	Modify coverage from alpha	<a href="#">17.3.3</a>
SAMPLE_ALPHA_TO_ONE	$B$	<b>IsEnabled</b>	FALSE	Set alpha to max	<a href="#">17.3.3</a>
SAMPLE_COVERAGE	$B$	<b>IsEnabled</b>	FALSE	Mask to modify coverage	<a href="#">17.3.3</a>
SAMPLE_COVERAGE_VALUE	$R^+$	<b>GetFloatv</b>	1	Coverage mask value	<a href="#">17.3.3</a>
SAMPLE_COVERAGE_INVERT	$B$	<b>GetBooleanv</b>	FALSE	Invert coverage mask value	<a href="#">17.3.3</a>
SAMPLE_SHADING	$B$	<b>IsEnabled</b>	FALSE	Sample shading enable	<a href="#">17.3.3</a>
MIN_SAMPLE_SHADING_VALUE	$R^+$	<b>GetFloatv</b>	0	Fraction of multisamples to use for sample shading	<a href="#">14.3.1.1</a>
SAMPLE_MASK	$B$	<b>IsEnabled</b>	FALSE	Sample mask enable	<a href="#">17.3.3</a>
SAMPLE_MASK_VALUE	$n \times Z^+$	<b>GetIntegeriv</b>	all bits of all words set	Sample mask words	<a href="#">17.3.3</a>

Table 23.11. Multisampling



Get value	Type	Get Command	Initial Value	Description	Sec.
TEXTURE_BINDING_3D	$80 * \times 3 \times Z^+$	<b>GetIntegerv</b>	0	Texture object bound to TEXTURE_3D	<b>8.1</b>
TEXTURE_BINDING_ID_ARRAY	$80 * \times Z^+$	<b>GetIntegerv</b>	0	Texture object bound to TEXTURE_1D_ARRAY	<b>8.1</b>
TEXTURE_BINDING_2D_ARRAY	$80 * \times Z^+$	<b>GetIntegerv</b>	0	Texture object bound to TEXTURE_2D_ARRAY	<b>8.1</b>
TEXTURE_BINDING_CUBE_MAP_ARRAY	$80 * \times Z^+$	<b>GetIntegerv</b>	0	Texture object bound to TEXTURE_CUBE_MAP_ARRAY	<b>8.1</b>
TEXTURE_BINDING_RECTANGLE	$80 * \times Z^+$	<b>GetIntegerv</b>	0	Texture object bound to TEXTURE_RECTANGLE	<b>8.1</b>
TEXTURE_BINDING_BUFFER	$80 * \times Z^+$	<b>GetIntegerv</b>	0	Texture object bound to TEXTURE_BUFFER	<b>8.1</b>
TEXTURE_BINDING_CUBE_MAP	$80 * \times Z^+$	<b>GetIntegerv</b>	0	Texture object bound to TEXTURE_CUBE_MAP	<b>8.1</b>
TEXTURE_BINDING_2D_MULTISAMPLE	$80 * \times Z^+$	<b>GetIntegerv</b>	0	Texture object bound to TEXTURE_2D_MULTISAMPLE	<b>8.21</b>
TEXTURE_BINDING_2D_MULTISAMPLE_ARRAY	$80 * \times Z^+$	<b>GetIntegerv</b>	0	Texture object bound to TEXTURE_2D_MULTISAMPLE_ARRAY	<b>8.21</b>

Table 23.12. Textures (state per texture unit)

Get value	Type	Get Command	Initial Value	Description	Sec.
SAMPLER_BINDING	$80 * \times Z^+$	<b>GetIntegerv</b>	0	Sampler object bound to active texture unit	<b>8.2</b>
TEXTURE_0D	$0 * \times 3 \times I$	<b>GetTexImage</b>	see ch. <b>8</b>	$x$ D texture image at l.o.d. $i$	<b>8</b>
TEXTURE_1D_ARRAY	$0 * \times I$	<b>GetTexImage</b>	see ch. <b>8</b>	1D texture array image at row $i$	<b>8</b>
TEXTURE_2D_ARRAY	$0 * \times I$	<b>GetTexImage</b>	see ch. <b>8</b>	2D texture array image at slice $i$	<b>8</b>
TEXTURE_CUBE_MAP_ARRAY	$0 * \times I$	<b>GetTexImage</b>	see ch. <b>8</b>	Cube map array texture image at l.o.d. $i$	<b>8</b>
TEXTURE_RECTANGLE	$0 * \times I$	<b>GetTexImage</b>	see ch. <b>8</b>	Rectangle texture image at l.o.d. zero	<b>8</b>
TEXTURE_CUBE_MAP_POSITIVE_X	$0 * \times I$	<b>GetTexImage</b>	see sec. <b>8.5</b>	$+x$ face cube map texture image at l.o.d. $i$	<b>8.5</b>
TEXTURE_CUBE_MAP_NEGATIVE_X	$0 * \times I$	<b>GetTexImage</b>	see sec. <b>8.5</b>	$-x$ face cube map texture image at l.o.d. $i$	<b>8.5</b>
TEXTURE_CUBE_MAP_POSITIVE_Y	$0 * \times I$	<b>GetTexImage</b>	see sec. <b>8.5</b>	$+y$ face cube map texture image at l.o.d. $i$	<b>8.5</b>
TEXTURE_CUBE_MAP_NEGATIVE_Y	$0 * \times I$	<b>GetTexImage</b>	see sec. <b>8.5</b>	$-y$ face cube map texture image at l.o.d. $i$	<b>8.5</b>
TEXTURE_CUBE_MAP_POSITIVE_Z	$0 * \times I$	<b>GetTexImage</b>	see sec. <b>8.5</b>	$+z$ face cube map texture image at l.o.d. $i$	<b>8.5</b>
TEXTURE_CUBE_MAP_NEGATIVE_Z	$0 * \times I$	<b>GetTexImage</b>	see sec. <b>8.5</b>	$-z$ face cube map texture image at l.o.d. $i$	<b>8.5</b>

Table 23.13. Textures (state per texture unit (cont.))

Get value	Type	Get Command	Initial Value	Description	Sec.
TEXTURE_SWIZZLE_R	<i>E</i>	<b>GetTexParameter</b>	RED	Red component swizzle	<b>8.10</b>
TEXTURE_SWIZZLE_G	<i>E</i>	<b>GetTexParameter</b>	GREEN	Green component swizzle	<b>8.10</b>
TEXTURE_SWIZZLE_B	<i>E</i>	<b>GetTexParameter</b>	BLUE	Blue component swizzle	<b>8.10</b>
TEXTURE_SWIZZLE_A	<i>E</i>	<b>GetTexParameter</b>	ALPHA	Alpha component swizzle	<b>8.10</b>
TEXTURE_BORDER_COLOR	<i>C</i>	<b>GetTexParameter</b>	0.0,0.0,0.0,0.0	Border color	<b>8</b>
TEXTURE_MIN_FILTER	<i>E</i>	<b>GetTexParameter</b>	see sec. <b>8.21</b>	Minification function	<b>8.14</b>
TEXTURE_MAG_FILTER	<i>E</i>	<b>GetTexParameter</b>	LINEAR	Magnification function	<b>8.15</b>
TEXTURE_WRAP_S	<i>Z</i> <sub>4</sub>	<b>GetTexParameter</b>	see sec. <b>8.21</b>	Texcoord <i>s</i> wrap mode	<b>8.14.2</b>
TEXTURE_WRAP_T	<i>Z</i> <sub>4</sub>	<b>GetTexParameter</b>	see sec. <b>8.21</b>	Texcoord <i>t</i> wrap mode (2D, 3D, cube map textures only)	<b>8.14.2</b>
TEXTURE_WRAP_R	<i>Z</i> <sub>4</sub>	<b>GetTexParameter</b>	see sec. <b>8.21</b>	Texcoord <i>r</i> wrap mode (3D textures only)	<b>8.14.2</b>
TEXTURE_MIN_LOD	<i>R</i>	<b>GetTexParameterfv</b>	-1000	Min level of detail	<b>8</b>
TEXTURE_MAX_LOD	<i>R</i>	<b>GetTexParameterfv</b>	1000	Max level of detail	<b>8</b>
TEXTURE_BASE_LEVEL	<i>Z</i> <sup>+</sup>	<b>GetTexParameterfv</b>	0	Base texture array	<b>8</b>
TEXTURE_MAX_LEVEL	<i>Z</i> <sup>+</sup>	<b>GetTexParameterfv</b>	1000	Max texture array level	<b>8</b>
TEXTURE_LOD_BIAS	<i>R</i>	<b>GetTexParameterfv</b>	0.0	Texture level of detail bias ( <i>bias<sub>textureobj</sub></i> )	<b>8.14</b>

Table 23.14. Textures (state per texture object)

Get value	Type	Get Command	Initial Value	Description	Sec.
DEPTH_STENCIL_TEXTURE_MODE	$n \times E$	<b>GetTexParameteriv</b>	DEPTH_COMPONENT	Depth stencil texture mode	8.16
TEXTURE_COMPARE_MODE	$E$	<b>GetTexParameteriv</b>	NONE	Comparison mode	8.22
TEXTURE_COMPARE_FUNC	$E$	<b>GetTexParameteriv</b>	LEQUAL	Comparison function	8.22
IMAGE_FORMAT_COMPATIBILITY_TYPE	$E$	<b>GetTexParameteriv</b>	see sec. 8.25	Compatibility rules for texture use with image units	8.25
TEXTURE_IMMUTABLE_FORMAT	$B$	<b>GetTexParameter</b>	FALSE	Size and format immutable	8.19
TEXTURE_IMMUTABLE_LEVELS	$Z^+$	<b>GetTexParameter</b>	0	storage no. of levels	8.18
TEXTURE_VIEW_MIN_LEVEL	$Z^+$	<b>GetTexParameter</b>	0	view base texture level	8.18
TEXTURE_VIEW_NUM_LEVELS	$Z^+$	<b>GetTexParameter</b>	0	view no. of texture levels	8.18
TEXTURE_VIEW_MIN_LAYER	$Z^+$	<b>GetTexParameter</b>	0	view min array layer	8.18
TEXTURE_VIEW_NUM_LAYERS	$Z^+$	<b>GetTexParameter</b>	0	view no. of array layers	8.18
LABEL	$S$	<b>GetObjectLabel</b>	empty	Debug label	20.9

Table 23.15. Textures (state per texture object) (cont.)

Get value	Type	Get Command	Initial Value	Description	Sec.
TEXTURE_WIDTH	$Z^+$	<b>GetTexLevelParameter</b>	0	Specified width	<b>8</b>
TEXTURE_HEIGHT	$Z^+$	<b>GetTexLevelParameter</b>	0	Specified height (2D/3D)	<b>8</b>
TEXTURE_DEPTH	$Z^+$	<b>GetTexLevelParameter</b>	0	Specified depth (3D)	<b>8</b>
TEXTURE_SAMPLES	$Z^+$	<b>GetTexLevelParameter</b>	0	No. of samples per texel	<b>8.8</b>
TEXTURE_FIXED_SAMPLE_LOCATIONS	$B$	<b>GetTexLevelParameter</b>	TRUE	Whether the image uses a fixed sample pattern	<b>8.8</b>
TEXTURE_INTERNAL_FORMAT	$E$	<b>GetTexLevelParameter</b>	RGBA or R8	Internal format (see section <b>8.21</b> )	<b>8</b>
TEXTURE_*.*.SIZE	$6 \times Z^+$	<b>GetTexLevelParameter</b>	0	Component resolution ( $x$ is RED, GREEN, BLUE, ALPHA, DEPTH, or STENCIL)	<b>8</b>
TEXTURE_SHARED_SIZE	$Z^+$	<b>GetTexLevelParameter</b>	0	Shared exponent field resolution	<b>8</b>
TEXTURE_*.*.TYPE	$E$	<b>GetTexLevelParameter</b>	NONE	Component type ( $x$ is RED, GREEN, BLUE, ALPHA, or DEPTH)	<b>8.11</b>

Table 23.16. Textures (state per texture image)

Get value	Type	Get Command	Initial Value	Description	Sec.
TEXTURE.COMPRESSED	$B$	<b>GetTexLevelParameter</b>	FALSE	True if image has a compressed internal format	<b>8.7</b>
TEXTURE.COMPRESSED_IMAGE_SIZE	$Z^+$	<b>GetTexLevelParameter</b>	0	Size (in bytes) of compressed image	<b>8.7</b>
TEXTURE.BUFFER_DATA_STORE_BINDING	$Z^+$	<b>GetTexLevelParameter</b>	0	Buffer object bound as the data store for the active image unit's buffer texture	<b>8.1</b>
TEXTURE.BUFFER_OFFSET	$n \times Z$	<b>GetTexLevelParameter</b>	0	Offset into buffer's data store used for the active image unit's buffer texture	<b>8.9</b>
TEXTURE.BUFFER_SIZE	$n \times Z$	<b>GetTexLevelParameter</b>	0	Size of the buffer's data store used for the active image unit's buffer texture	<b>8.9</b>

Table 23.17. Textures (state per texture image) (cont.)

Get value	Type	Get Command	Initial Value	Description	Sec.
TEXTURE.BORDER.COLOR	<i>C</i>	<b>GetSamplerParameter</b>	0.0,0.0,0.0,0.0	Border color	<b>8</b>
TEXTURE.COMPARE.FUNC	<i>E</i>	<b>GetSamplerParameteriv</b>	LEQUAL	Comparison function	<b>8.22</b>
TEXTURE.COMPARE.MODE	<i>E</i>	<b>GetSamplerParameteriv</b>	NONE	Comparison mode	<b>8.22</b>
TEXTURE.LOD.BIAS	<i>R</i>	<b>GetSamplerParameterfv</b>	0.0	Texture level of detail bias ( <i>bias<sub>texobj</sub></i> )	<b>8.14</b>
TEXTURE.MAX.LOD	<i>R</i>	<b>GetSamplerParameterfv</b>	1000	Max level of detail	<b>8</b>
TEXTURE.MAG.FILTER	<i>E</i>	<b>GetSamplerParameter</b>	LINEAR	Magnification function	<b>8.15</b>
TEXTURE.MIN.FILTER	<i>E</i>	<b>GetSamplerParameter</b>	see sec. <b>8.21</b>	Minification function	<b>8.14</b>
TEXTURE.MIN.LOD	<i>R</i>	<b>GetSamplerParameterfv</b>	-1000	Min level of detail	<b>8</b>
TEXTURE.WRAP.S	<i>Z</i> <sub>4</sub>	<b>GetSamplerParameter</b>	see sec. <b>8.21</b>	Texcoord <i>s</i> wrap mode	<b>8.14.2</b>
TEXTURE.WRAP.T	<i>Z</i> <sub>4</sub>	<b>GetSamplerParameter</b>	see sec. <b>8.21</b>	Texcoord <i>t</i> wrap mode (2D, 3D, cube map textures only)	<b>8.14.2</b>
TEXTURE.WRAP.R	<i>Z</i> <sub>4</sub>	<b>GetSamplerParameter</b>	see sec. <b>8.21</b>	Texcoord <i>r</i> wrap mode (3D textures only)	<b>8.14.2</b>
LABEL	<i>S</i>	<b>GetObjectLabel</b>	empty	Debug label	<b>20.9</b>

Table 23.18. Textures (state per sampler object)

Get value	Type	Get Command	Initial Value	Description	Sec.
ACTIVE_TEXTURE	Z80*	<b>GetInteger</b>	TEXTURE0	Active texture unit selector	<b>10.2</b>

Table 23.19. Texture Environment and Generation



Get value	Type	Get Command	Initial Value	Description	Sec.
SCISSOR_TEST	$16 * \times B$	<b>IsEnabledi</b>	FALSE	Scissoring enabled	<a href="#">17.3.2</a>
SCISSOR_BOX	$16 * \times 4 \times Z$	<b>GetIntegerv</b>	see sec. <a href="#">17.3.2</a>	Scissor box	<a href="#">17.3.2</a>
STENCIL_TEST	<i>B</i>	<b>IsEnabled</b>	FALSE	Stenciling enabled	<a href="#">17.3.5</a>
STENCIL_FUNC	<i>E</i>	<b>GetIntegerv</b>	ALWAYS	Front stencil function	<a href="#">17.3.5</a>
STENCIL_VALUE_MASK	$Z^+$	<b>GetIntegerv</b>	see sec. <a href="#">17.3.5</a>	Front stencil mask	<a href="#">17.3.5</a>
STENCIL_REF	$Z^+$	<b>GetIntegerv</b>	0	Front stencil reference value	<a href="#">17.3.5</a>
STENCIL_FAIL	<i>E</i>	<b>GetIntegerv</b>	KEEP	Front stencil fail action	<a href="#">17.3.5</a>
STENCIL_PASS_DEPTH_FAIL	<i>E</i>	<b>GetIntegerv</b>	KEEP	Front stencil depth buffer fail action	<a href="#">17.3.5</a>
STENCIL_PASS_DEPTH_PASS	<i>E</i>	<b>GetIntegerv</b>	KEEP	Front stencil depth buffer pass action	<a href="#">17.3.5</a>
STENCIL_BACK_FUNC	<i>E</i>	<b>GetIntegerv</b>	ALWAYS	Back stencil function	<a href="#">17.3.5</a>
STENCIL_BACK_VALUE_MASK	$Z^+$	<b>GetIntegerv</b>	see sec. <a href="#">17.3.5</a>	Back stencil mask	<a href="#">17.3.5</a>
STENCIL_BACK_REF	$Z^+$	<b>GetIntegerv</b>	0	Back stencil reference value	<a href="#">17.3.5</a>
STENCIL_BACK_FAIL	<i>E</i>	<b>GetIntegerv</b>	KEEP	Back stencil fail action	<a href="#">17.3.5</a>
STENCIL_BACK_PASS_DEPTH_FAIL	<i>E</i>	<b>GetIntegerv</b>	KEEP	Back stencil depth buffer fail action	<a href="#">17.3.5</a>
STENCIL_BACK_PASS_DEPTH_PASS	<i>E</i>	<b>GetIntegerv</b>	KEEP	Back stencil depth buffer pass action	<a href="#">17.3.5</a>
DEPTH_TEST	<i>B</i>	<b>IsEnabled</b>	FALSE	Depth buffer enabled	<a href="#">17.3.6</a>
DEPTH_FUNC	<i>E</i>	<b>GetIntegerv</b>	LESS	Depth buffer test function	<a href="#">17.3.6</a>

Table 23.20. Pixel Operations

Get value	Type	Get Command	Initial Value	Description	Sec.
BLEND	$8 * \times B$	<b>IsEnabledi</b>	FALSE	Blending enabled for draw buffer <i>i</i>	<a href="#">17.3.8</a>
BLEND_SRC_RGB	$8 * \times E$	<b>GetIntegeri_v</b>	ONE	Blending source RGB function for draw buffer <i>i</i>	<a href="#">17.3.8</a>
BLEND_SRC_ALPHA	$8 * \times E$	<b>GetIntegeri_v</b>	ONE	Blending source A function for draw buffer <i>i</i>	<a href="#">17.3.8</a>
BLEND_DST_RGB	$8 * \times E$	<b>GetIntegeri_v</b>	ZERO	Blending dest. RGB function for draw buffer <i>i</i>	<a href="#">17.3.8</a>
BLEND_DST_ALPHA	$8 * \times E$	<b>GetIntegeri_v</b>	ZERO	Blending dest. A function for draw buffer <i>i</i>	<a href="#">17.3.8</a>
BLEND_EQUATION_RGB	$8 * \times E$	<b>GetIntegeri_v</b>	FUNC_ADD	RGB blending equation for draw buffer <i>i</i>	<a href="#">17.3.8</a>
BLEND_EQUATION_ALPHA	$8 * \times E$	<b>GetIntegeri_v</b>	FUNC_ADD	Alpha blending equation for draw buffer <i>i</i>	<a href="#">17.3.8</a>
BLEND_COLOR	<i>C</i>	<b>GetFloatv</b>	0.0,0.0,0.0,0.0	Constant blend color	<a href="#">17.3.8</a>
FRAMEBUFFER_SRGB	<i>B</i>	<b>IsEnabled</b>	FALSE	sRGB update and blending enable	<a href="#">17.3.8</a>
DITHER	<i>B</i>	<b>IsEnabled</b>	TRUE	Dithering enabled	<a href="#">17.3.10</a>
COLOR_LOGIC_OP	<i>B</i>	<b>IsEnabled</b>	FALSE	Color logic op enabled	<a href="#">17.3.11</a>
LOGIC_OP_MODE	<i>E</i>	<b>GetIntegeri_v</b>	COPY	Logic op function	<a href="#">17.3.11</a>

Table 23.21. Pixel Operations (cont.)

Get value	Type	Get Command	Initial Value	Description	Sec.
COLOR_WRITEMASK	$8 * 4 * B$	<b>GetBooleanv</b>	(TRUE,TRUE,TRUE,TRUE)	Color write enables (R,G,B,A) for draw buffer <i>i</i>	17.4.2
DEPTH_WRITEMASK	$B$	<b>GetBooleanv</b>	TRUE	Depth buffer enabled for writing	17.4.2
STENCIL_WRITEMASK	$Z^+$	<b>GetIntegerv</b>	1's	Front stencil buffer writemask	17.4.2
STENCIL_BACK_WRITEMASK	$Z^+$	<b>GetIntegerv</b>	1's	Back stencil buffer writemask	17.4.2
COLOR_CLEAR_VALUE	$C$	<b>GetFloatv</b>	0.0,0.0,0.0,0.0	Color buffer clear value	17.4.3
DEPTH_CLEAR_VALUE	$R^+$	<b>GetFloatv</b>	1	Depth buffer clear value	17.4.3
STENCIL_CLEAR_VALUE	$Z^+$	<b>GetIntegerv</b>	0	Stencil clear value	17.4.3

Table 23.22. Framebuffer Control

Get value	Type	Get Command	Initial Value	Description	Sec.
DRAW_FRAMEBUFFER_BINDING	Z <sup>+</sup>	<b>GetIntegerv</b>	0	Framebuffer object bound to DRAW_FRAMEBUFFER	9.2
READ_FRAMEBUFFER_BINDING	Z <sup>+</sup>	<b>GetIntegerv</b>	0	Framebuffer object bound to READ_FRAMEBUFFER	9.2

Table 23.23. Framebuffer (state per target binding point)

Get value	Type	Get Command	Initial Value	Description	Sec.
DRAW_BUFFER <i>i</i>	$8 * \times E$	<b>GetIntegerv</b>	see sec. <b>17.4.1</b>	Draw buffer selected for color output <i>i</i>	<b>17.4.1</b>
READ_BUFFER	<i>E</i>	<b>GetIntegerv</b>	see sec. <b>18.2</b>	Read source buffer †	<b>18.2</b>
LABEL	<i>S</i>	<b>GetObjectLabel</b>	empty	Debug label	<b>20.9</b>

Table 23.24. Framebuffer (state per framebuffer object)

† This state is queried from the currently bound read framebuffer.

Get value	Type	Get Command	Initial Value	Description	Sec.
FRAMEBUFFER_ATTACHMENT_OBJECT_TYPE	$E$	<b>GetFramebufferAttachmentParameteriv</b>	NONE	Type of image attached to framebuffer attachment point	9.2.2
FRAMEBUFFER_ATTACHMENT_OBJECT_NAME	$Z^+$	<b>GetFramebufferAttachmentParameteriv</b>	0	Name of object attached to framebuffer attachment point	9.2.2
FRAMEBUFFER_ATTACHMENT_TEXTURE_LEVEL	$Z^+$	<b>GetFramebufferAttachmentParameteriv</b>	0	Mipmap level of texture image attached, if object attached is texture	9.2.8
FRAMEBUFFER_ATTACHMENT_TEXTURE_CUBE_MAP_FACE	$Z^+$	<b>GetFramebufferAttachmentParameteriv</b>	NONE	Cubemap face of texture image attached, if object attached is cubemap texture	9.2.8
FRAMEBUFFER_ATTACHMENT_TEXTURE_LAYER	$Z$	<b>GetFramebufferAttachmentParameteriv</b>	0	Layer of texture image attached, if object attached is 3D texture	9.2.8
FRAMEBUFFER_ATTACHMENT_LAYERED	$n \times B$	<b>GetFramebufferAttachmentParameteriv</b>	FALSE	Framebuffer attachment is layered	9.8
FRAMEBUFFER_ATTACHMENT_COLOR_ENCODING	$E$	<b>GetFramebufferAttachmentParameteriv</b>	-	Encoding of components in the attached image	9.2.3
FRAMEBUFFER_ATTACHMENT_COMPONENT_TYPE	$E$	<b>GetFramebufferAttachmentParameteriv</b>	-	Data type of components in the attached image	9.2.3
FRAMEBUFFER_ATTACHMENT_TEXTURE_FORMAT_SIZE	$Z^+$	<b>GetFramebufferAttachmentParameteriv</b>	-	Size in bits of attached image's $x$ component; $x$ is RED, GREEN, BLUE, ALPHA, DEPTH, or STENCIL	9.2.3

Table 23.25. Framebuffer (state per attachment point)

Get value	Type	Get Command	Initial Value	Description	Sec.
RENDERBUFFER_BINDING	Z	<b>GetIntegerv</b>	0	Renderbuffer object bound to RENDERBUFFER	<b>9.2.4</b>

Table 23.26. Renderbuffer (state per target and binding point)

Get value	Type	Get Command	Initial Value	Description	Sec.
RENDERBUFFER_WIDTH	Z <sup>+</sup>	<b>GetRenderbufferParameteriv</b>	0	Width of renderbuffer	9.2.4
RENDERBUFFER_HEIGHT	Z <sup>+</sup>	<b>GetRenderbufferParameteriv</b>	0	Height of renderbuffer	9.2.4
RENDERBUFFER_INTERNAL_FORMAT	Z <sup>+</sup>	<b>GetRenderbufferParameteriv</b>	RGBA	Internal format of renderbuffer	9.2.4
RENDERBUFFER_RED_SIZE	Z <sup>+</sup>	<b>GetRenderbufferParameteriv</b>	0	Size in bits of renderbuffer image's red component	9.2.4
RENDERBUFFER_GREEN_SIZE	Z <sup>+</sup>	<b>GetRenderbufferParameteriv</b>	0	Size in bits of renderbuffer image's green component	9.2.4
RENDERBUFFER_BLUE_SIZE	Z <sup>+</sup>	<b>GetRenderbufferParameteriv</b>	0	Size in bits of renderbuffer image's blue component	9.2.4
RENDERBUFFER_ALPHA_SIZE	Z <sup>+</sup>	<b>GetRenderbufferParameteriv</b>	0	Size in bits of renderbuffer image's alpha component	9.2.4
RENDERBUFFER_DEPTH_SIZE	Z <sup>+</sup>	<b>GetRenderbufferParameteriv</b>	0	Size in bits of renderbuffer image's depth component	9.2.4
RENDERBUFFER_STENCIL_SIZE	Z <sup>+</sup>	<b>GetRenderbufferParameteriv</b>	0	Size in bits of renderbuffer image's stencil component	9.2.4
RENDERBUFFER_SAMPLES	Z <sup>+</sup>	<b>GetRenderbufferParameteriv</b>	0	No. of samples	9.2.4
LABEL	S	<b>GetObjectLabel</b>	empty	Debug label	20.9

Table 23.27. Renderbuffer (state per renderbuffer object)



Get value	Type	Get Command	Initial Value	Description	Sec.
UNPACK_SWAP_BYTES	B	<b>GetBooleanv</b>	FALSE	Value of UNPACK_SWAP_BYTES	8.4.1
UNPACK_LSB_FIRST	B	<b>GetBooleanv</b>	FALSE	Value of UNPACK_LSB_FIRST	8.4.1
UNPACK_IMAGE_HEIGHT	Z <sup>+</sup>	<b>GetIntegerv</b>	0	Value of UNPACK_IMAGE_HEIGHT	8.4.1
UNPACK_SKIP_IMAGES	Z <sup>+</sup>	<b>GetIntegerv</b>	0	Value of UNPACK_SKIP_IMAGES	8.4.1
UNPACK_ROW_LENGTH	Z <sup>+</sup>	<b>GetIntegerv</b>	0	Value of UNPACK_ROW_LENGTH	8.4.1
UNPACK_SKIP_ROWS	Z <sup>+</sup>	<b>GetIntegerv</b>	0	Value of UNPACK_SKIP_ROWS	8.4.1
UNPACK_SKIP_PIXELS	Z <sup>+</sup>	<b>GetIntegerv</b>	0	Value of UNPACK_SKIP_PIXELS	8.4.1
UNPACK_ALIGNMENT	Z <sup>+</sup>	<b>GetIntegerv</b>	4	Value of UNPACK_ALIGNMENT	8.4.1
UNPACK_COMPRESSED_BLOCK_WIDTH	Z <sup>+</sup>	<b>GetIntegerv</b>	0	Value of UNPACK_COMPRESSED_BLOCK_WIDTH	8.4.1
UNPACK_COMPRESSED_BLOCK_HEIGHT	Z <sup>+</sup>	<b>GetIntegerv</b>	0	Value of UNPACK_COMPRESSED_BLOCK_HEIGHT	8.4.1
UNPACK_COMPRESSED_BLOCK_DEPTH	Z <sup>+</sup>	<b>GetIntegerv</b>	0	Value of UNPACK_COMPRESSED_BLOCK_DEPTH	8.4.1
UNPACK_COMPRESSED_BLOCK_SIZE	Z <sup>+</sup>	<b>GetIntegerv</b>	0	Value of UNPACK_COMPRESSED_BLOCK_SIZE	8.4.1
PIXEL_UNPACK_BUFFER_BINDING	Z <sup>+</sup>	<b>GetIntegerv</b>	0	Pixel unpack buffer binding	6.7

Table 23.28. Pixels

Get value	Type	Get Command	Initial Value	Description	Sec.
PACK_SWAP_BYTES	<i>B</i>	<b>GetBooleanv</b>	FALSE	Value of PACK_SWAP_BYTES	18.2
PACK_LSB_FIRST	<i>B</i>	<b>GetBooleanv</b>	FALSE	Value of PACK_LSB_FIRST	18.2
PACK_IMAGE_HEIGHT	<i>Z<sup>+</sup></i>	<b>GetIntegerv</b>	0	Value of PACK_IMAGE_HEIGHT	18.2
PACK_SKIP_IMAGES	<i>Z<sup>+</sup></i>	<b>GetIntegerv</b>	0	Value of PACK_SKIP_IMAGES	18.2
PACK_ROW_LENGTH	<i>Z<sup>+</sup></i>	<b>GetIntegerv</b>	0	Value of PACK_ROW_LENGTH	18.2
PACK_SKIP_ROWS	<i>Z<sup>+</sup></i>	<b>GetIntegerv</b>	0	Value of PACK_SKIP_ROWS	18.2
PACK_SKIP_PIXELS	<i>Z<sup>+</sup></i>	<b>GetIntegerv</b>	0	Value of PACK_SKIP_PIXELS	18.2
PACK_ALIGNMENT	<i>Z<sup>+</sup></i>	<b>GetIntegerv</b>	4	Value of PACK_ALIGNMENT	18.2
PACK_COMPRESSED_BLOCK_WIDTH	<i>Z<sup>+</sup></i>	<b>GetIntegerv</b>	0	Value of PACK_COMPRESSED_BLOCK_WIDTH	18.2
PACK_COMPRESSED_BLOCK_HEIGHT	<i>Z<sup>+</sup></i>	<b>GetIntegerv</b>	0	Value of PACK_COMPRESSED_BLOCK_HEIGHT	18.2
PACK_COMPRESSED_BLOCK_DEPTH	<i>Z<sup>+</sup></i>	<b>GetIntegerv</b>	0	Value of PACK_COMPRESSED_BLOCK_DEPTH	18.2
PACK_COMPRESSED_BLOCK_SIZE	<i>Z<sup>+</sup></i>	<b>GetIntegerv</b>	0	Value of PACK_COMPRESSED_BLOCK_SIZE	18.2
PIXEL_PACK_BUFFER_BINDING	<i>Z<sup>+</sup></i>	<b>GetIntegerv</b>	0	Pixel pack buffer binding	18.2

Table 23.29. Pixels (cont.)

Get value	Type	Get Command	Initial Value	Description	Sec.
SHADER_TYPE	<i>E</i>	<b>GetShaderiv</b>	-	Type of shader (vertex, geometry, or fragment)	7.1
DELETE_STATUS	<i>B</i>	<b>GetShaderiv</b>	FALSE	Shader flagged for deletion	7.1
COMPILE_STATUS	<i>B</i>	<b>GetShaderiv</b>	FALSE	Last compile succeeded	7.1
-	<i>S</i>	<b>GetShaderInfoLog</b>	empty string	Info log for shader objects	7.13
INFO_LOG_LENGTH	<i>Z<sup>+</sup></i>	<b>GetShaderiv</b>	0	Length of info log	7.13
-	<i>S</i>	<b>GetShaderSource</b>	empty string	Source code for a shader	7.1
SHADER_SOURCE_LENGTH	<i>Z<sup>+</sup></i>	<b>GetShaderiv</b>	0	Length of source code	7.13
LABEL	<i>S</i>	<b>GetObjectLabel</b>	empty	Debug label	20.9

Table 23.30. Shader Object State

Get value	Type	Get Command	Initial Value	Description	Sec.
ACTIVE_PROGRAM	Z <sup>+</sup>	<b>GetProgramPipelineiv</b>	0	Program object updated by <b>Uniform*</b> when PPO bound	7.4
VERTEX_SHADER	Z <sup>+</sup>	<b>GetProgramPipelineiv</b>	0	Name of current vertex shader program object	7.4
GEOMETRY_SHADER	Z <sup>+</sup>	<b>GetProgramPipelineiv</b>	0	Name of current geometry shader program object	7.4
FRAGMENT_SHADER	Z <sup>+</sup>	<b>GetProgramPipelineiv</b>	0	Name of current fragment shader program object	7.4
TESS_CONTROL_SHADER	Z <sup>+</sup>	<b>GetProgramPipelineiv</b>	0	Name of current TCS program object	7.4
TESS_EVALUATION_SHADER	Z <sup>+</sup>	<b>GetProgramPipelineiv</b>	0	Name of current TES program object	7.4
VALIDATE_STATUS	B	<b>GetProgramPipelineiv</b>	FALSE	Validate status of program pipeline object	7.4
-	S	<b>GetProgramPipelineInfoLog</b>	empty	Info log for program pipeline object	7.13
INFO_LOG_LENGTH_LABEL	Z <sup>+</sup>	<b>GetProgramPipelineiv</b>	0	Length of info log	7.4
	S	<b>GetObjectLabel</b>	empty	Debug label	20.9

Table 23.31. Program Pipeline Object State

Get value	Type	Get Command	Initial Value	Description	Sec.
CURRENT_PROGRAM	Z <sup>+</sup>	<b>GetIntegerv</b>	0	Name of current program object	7.3
PROGRAM_PIPELINE_BINDING	Z <sup>+</sup>	<b>GetIntegerv</b>	0	Current program pipeline object binding	7.4
PROGRAM_SEPARABLE	B	<b>GetProgramiv</b>	FALSE	Program object can be bound for separate pipeline stages	7.3
DELETE_STATUS	B	<b>GetProgramiv</b>	FALSE	Program object deleted	7.3
LINK_STATUS	B	<b>GetProgramiv</b>	FALSE	Last link attempt succeeded	7.3
VALIDATE_STATUS	B	<b>GetProgramiv</b>	FALSE	Last validate attempt succeeded	7.3
ATTACHED_SHADERS	Z <sup>+</sup>	<b>GetProgramiv</b>	0	No. of attached shader objects	7.13
-	0 * × Z <sup>+</sup>	<b>GetAttachedShaders</b>	empty	Shader objects attached	7.13
-	S	<b>GetProgramInfoLog</b>	empty	Info log for program object	7.13
INFO_LOG_LENGTH	Z <sup>+</sup>	<b>GetProgramiv</b>	0	Length of info log	7.3
PROGRAM_BINARY_LENGTH	Z <sup>+</sup>	<b>GetProgramiv</b>	0	Length of program binary	7.5
PROGRAM_BINARY_RETRIEVABLE_HINT	B	<b>GetProgramiv</b>	FALSE	Retrievable binary hint enabled	7.5
--	0 * × BMU	<b>GetProgramBinary</b>	-	Binary representation of program	7.5
COMPUTE_WORK_GROUP_SIZE	3 × Z <sup>+</sup>	<b>GetProgramiv</b>	{0, ...}	Local work size of a linked compute program	19
LABEL	S	<b>GetObjectLabel</b>	empty	Debug label	20.9

Table 23.32. Program Object State

Get value	Type	Get Command	Initial Value	Description	Sec.
ACTIVE_UNIFORMS	$Z^+$	<b>GetProgramiv</b>	0	No. of active uniforms	<b>7.6</b>
-	$0 * \times Z$	<b>GetUniformLocation</b>	-	Location of active uniforms	<b>7.13</b>
-	$0 * \times Z^+$	<b>GetActiveUniform</b>	-	Size of active uniform	<b>7.6</b>
-	$0 * \times Z^+$	<b>GetActiveUniform</b>	-	Type of active uniform	<b>7.6</b>
-	$0 * \times \text{char}$	<b>GetActiveUniform</b>	empty	Name of active uniform	<b>7.6</b>
ACTIVE_UNIFORM_MAX_LENGTH	$Z^+$	<b>GetProgramiv</b>	0	Max active uniform name length	<b>7.13</b>
-	-	<b>GetUniform</b>	0	Uniform value	<b>7.6</b>
ACTIVE_ATTRIBUTES	$Z^+$	<b>GetProgramiv</b>	0	No. of active attributes	<b>11.1.1</b>
-	$0 * \times Z$	<b>GetAttribLocation</b>	-	Location of active generic attribute	<b>11.1.1</b>
-	$0 * \times Z^+$	<b>GetActiveAttrib</b>	-	Size of active attribute	<b>11.1.1</b>
-	$0 * \times Z^+$	<b>GetActiveAttrib</b>	-	Type of active attribute	<b>11.1.1</b>
-	$0 * \times \text{char}$	<b>GetActiveAttrib</b>	empty	Name of active attribute	<b>11.1.1</b>
ACTIVE_ATTRIBUTE_MAX_LENGTH	$Z^+$	<b>GetProgramiv</b>	0	Max active attribute name length	<b>7.13</b>

Table 23.33. Program Object State (cont.)

Get value	Type	Get Command	Initial Value	Description	Sec.
GEOMETRY_VERTICES_OUT	Z <sup>+</sup>	<b>GetProgramiv</b>	0	Max no. of output vertices	11.3.4
GEOMETRY_INPUT_TYPE	E	<b>GetProgramiv</b>	TRIANGLES	Primitive input type	11.3.1
GEOMETRY_OUTPUT_TYPE	E	<b>GetProgramiv</b>	TRIANGLE_STRIP	Primitive output type	11.3.2
GEOMETRY_SHADER_INVOCATIONS	Z <sup>+</sup>	<b>GetProgramiv</b>	1	No. of times a geom. shader should be executed for each input primitive	11.3.4.2
TRANSFORM_FEEDBACK_BUFFER_MODE	E	<b>GetProgramiv</b>	INTERLEAVED_ATTRIBUTES	Transform feedback mode for the program	7.13
TRANSFORM_FEEDBACK_VARYINGS	Z <sup>+</sup>	<b>GetProgramiv</b>	0	No. of outputs to stream to buffer object(s)	7.13
TRANSFORM_FEEDBACK_VARYING_MAX_LENGTH	Z <sup>+</sup>	<b>GetProgramiv</b>	0	Max transform feedback output variable name length	7.13
-	Z <sup>+</sup>	<b>GetTransform-FeedbackVarying</b>	-	Size of each transform feedback output variable	11.1.2.1
-	Z <sup>+</sup>	<b>GetTransform-FeedbackVarying</b>	-	Type of each transform feedback output variable	11.1.2.1
-	0 <sup>+</sup> × char	<b>GetTransform-FeedbackVarying</b>	-	Name of each transform feedback output variable	11.1.2.1

Table 23.34. Program Object State (cont.)

Get value	Type	Get Command	Initial Value	Description	Sec.
ACTIVE_UNIFORM_BLOCKS	$Z^+$	<b>GetProgramiv</b>	0	No. of active uniform blocks in a program	7.6.2
ACTIVE_UNIFORM_BLOCK_MAX_NAME_LENGTH	$Z^+$	<b>GetProgramiv</b>	0	Length of longest active uniform block name	7.6.2
UNIFORM_TYPE	$0 * \times E$	<b>GetActiveUniformsiv</b>	-	Type of active uniform	7.6.2
UNIFORM_SIZE	$0 * \times Z^+$	<b>GetActiveUniformsiv</b>	-	Size of active uniform	7.6.2
UNIFORM_NAME_LENGTH	$0 * \times Z^+$	<b>GetActiveUniformsiv</b>	-	Uniform name length	7.6.2
UNIFORM_BLOCK_INDEX	$0 * \times Z$	<b>GetActiveUniformsiv</b>	-	Uniform block index	7.6.2
UNIFORM_OFFSET	$0 * \times Z$	<b>GetActiveUniformsiv</b>	-	Uniform buffer offset	7.6.2

Table 23.35. Program Object State (cont.)



Get value	Type	Get Command	Initial Value	Description	Sec.
UNIFORM_ARRAY_STRIDE	$0 * \times Z$	<b>GetActiveUniformsiv</b>	-	Uniform buffer array stride	7.6.2
UNIFORM_MATRIX_STRIDE	$0 * \times Z$	<b>GetActiveUniformsiv</b>	-	Uniform buffer intra-matrix stride	7.6.2
UNIFORM_IS_ROW_MAJOR	$0 * \times B$	<b>GetActiveUniformsiv</b>	-	Whether uniform is a row-major matrix	7.6.2
UNIFORM_BLOCK_BINDING	$Z^+$	<b>GetActive-UniformBlockiv</b>	0	Uniform buffer binding points associated with the specified uniform block	7.6.2
UNIFORM_BLOCK_DATA_SIZE	$Z^+$	<b>GetActive-UniformBlockiv</b>	-	Size of the storage needed to hold this uniform block's data	7.6.2
UNIFORM_BLOCK_ACTIVE_UNIFORMS	$Z^+$	<b>GetActive-UniformBlockiv</b>	-	Count of active uniforms in the specified uniform block	7.6.2
UNIFORM_BLOCK_ACTIVE_UNIFORM_INDICES	$n \times Z^+$	<b>GetActive-UniformBlockiv</b>	-	Array of active uniform indices of the specified uniform block	7.6.2
UNIFORM_BLOCK_REFERENCED_BY_VERTEX_SHADER	$B$	<b>GetActive-UniformBlockiv</b>	0	True if uniform block is actively referenced by the vertex stage	7.6.2
UNIFORM_BLOCK_REFERENCED_BY_TESS_CONTROL_SHADER	$B$	<b>GetActive-UniformBlockiv</b>	0	True if uniform block is actively referenced by tess. control stage	7.6.2
UNIFORM_BLOCK_REFERENCED_BY_TESS_EVALUATION_SHADER	$B$	<b>GetActive-UniformBlockiv</b>	0	True if uniform block is actively referenced by tess evaluation stage	7.6.2

Table 23.36. Program Object State (cont.)

Get value	Type	Get Command	Initial Value	Description	Sec.
UNIFORM_BLOCK_REFERENCED_BY_GEOMETRY_SHADER	<i>B</i>	<b>GetActiveUniformBlockiv</b>	0	True if uniform block is actively referenced by the geometry stage	7.6.2
UNIFORM_BLOCK_REFERENCED_BY_FRAGMENT_SHADER	<i>B</i>	<b>GetActiveUniformBlockiv</b>	0	True if uniform block is actively referenced by the fragment stage	7.6.2
UNIFORM_BLOCK_REFERENCED_BY_COMPUTE_SHADER	<i>B</i>	<b>GetActiveUniformBlockiv</b>	FALSE	True if uniform block is referenced by the compute stage	7.6.2
TESS_CONTROL_OUTPUT_VERTICES	<i>Z</i> <sup>+</sup>	<b>GetProgramiv</b>	0	Output patch size for tess. control shader	11.2.1
TESS_GEN_MODE	<i>E</i>	<b>GetProgramiv</b>	QUADS	Base primitive type for tess. prim. generator	11.2.2
TESS_GEN_SPACING	<i>E</i>	<b>GetProgramiv</b>	EQUAL	Spacing of tess. prim. generator edge subdivision	11.2.2
TESS_GEN_VERTEX_ORDER	<i>E</i>	<b>GetProgramiv</b>	CCW	Order of vertices in primitives generated by tess. prim generator	11.2.2
TESS_GEN_POINT_MODE	<i>B</i>	<b>GetProgramiv</b>	FALSE	Tess. prim. generator emits points?	11.2.2

Table 23.37. Program Object State (cont.)

Get value	Type	Get Command	Initial Value	Description	Sec.
ACTIVE.SUBROUTINE.UNIFORM-LOCATIONS	$5 \times Z^+$	<b>GetProgramStageiv</b>	0	No. of subroutine unif. locations in the shader	7.9
ACTIVE.SUBROUTINE.UNIFORMS	$5 \times Z^+$	<b>GetProgramStageiv</b>	0	No. of subroutine unif. variables in the shader	7.9
ACTIVE.SUBROUTINES	$5 \times Z^+$	<b>GetProgramStageiv</b>	0	No. of subroutine functions in the shader	7.9
ACTIVE.SUBROUTINE.UNIFORM-MAX-LENGTH	$5 \times Z^+$	<b>GetProgramStageiv</b>	0	Max subroutine uniform name length	7.9
ACTIVE.SUBROUTINE-MAX-LENGTH	$5 \times Z^+$	<b>GetProgramStageiv</b>	0	Max subroutine name length	7.9
NUM.COMPATIBLE.SUBROUTINES	$5 \times 0 * \times Z^+$	<b>GetActive-SubroutineUniformiv</b>	-	No. of subroutines compatible with a sub. uniform	7.9
COMPATIBLE.SUBROUTINES	$5 \times 0 * \times 0 * \times Z^+$	<b>GetActive-SubroutineUniformiv</b>	-	List of subroutines compatible with a sub. uniform	7.9
UNIFORM.SIZE	$5 \times 0 * \times Z^+$	<b>GetActive-SubroutineUniformiv</b>	-	No. of elements in sub. uniform array	7.9
UNIFORM.NAME.LENGTH	$5 \times 0 * \times Z^+$	<b>GetActive-SubroutineUniformiv</b>	-	Length of sub. uniform name	7.9
-	$5 \times 0 * \times S$	<b>GetActive-SubroutineUniformName</b>	-	Sub. uniform name string	7.9
-	$5 \times 0 * \times S$	<b>GetActive-SubroutineName</b>	-	Length of subroutine name	7.9
-	$5 \times 0 * \times S$	<b>GetActive-SubroutineName</b>	-	Subroutine name string	7.9

Table 23.38. Program Object State (cont.)

Get value	Type	Get Command	Initial Value	Description	Sec.
ACTIVE_ATOMIC_COUNTER_BUFFERS	$Z^+$	<b>GetProgramiv</b>	0	No. of active atomic counter buffers (AACBs) used by a program	7.7
ATOMIC_COUNTER_BUFFER_BINDING	$n \times Z^+$	<b>GetActiveAtomicCounterBufferiv</b>	-	Binding point associated with an AACB	7.7
ATOMIC_COUNTER_BUFFER_DATA_SIZE	$n \times Z^+$	<b>GetActiveAtomicCounterBufferiv</b>	-	Min size required by an AACB	7.7
ATOMIC_COUNTER_BUFFER_ACTIVE_ATOMIC_COUNTERS	$n \times Z^+$	<b>GetActiveAtomicCounterBufferiv</b>	-	No. of active atomic counters in an AACB	7.7
ATOMIC_COUNTER_BUFFER_ACTIVE_ATOMIC_COUNTER_INDICES	$m \times n \times Z^+$	<b>GetActiveAtomicCounterBufferiv</b>	-	List of active atomic counters in an AACB	7.7
ATOMIC_COUNTER_BUFFER_REFERENCED_BY_VERTEX_SHADER	$n \times B$	<b>GetActiveAtomicCounterBufferiv</b>	FALSE	AACB has a counter used by vertex shaders	7.7
ATOMIC_COUNTER_BUFFER_REFERENCED_BY_TESS_CONTROL_SHADER	$n \times B$	<b>GetActiveAtomicCounterBufferiv</b>	FALSE	AACB has a counter used by tess. control shaders	7.7
ATOMIC_COUNTER_BUFFER_REFERENCED_BY_TESS_EVALUATION_SHADER	$n \times B$	<b>GetActiveAtomicCounterBufferiv</b>	FALSE	AACB has a counter used by tess. evaluation shaders	7.7
ATOMIC_COUNTER_BUFFER_REFERENCED_BY_GEOMETRY_SHADER	$n \times B$	<b>GetActiveAtomicCounterBufferiv</b>	FALSE	AACB has a counter used by geometry shaders	7.7
ATOMIC_COUNTER_BUFFER_REFERENCED_BY_FRAGMENT_SHADER	$n \times B$	<b>GetActiveAtomicCounterBufferiv</b>	FALSE	AACB has a counter used by fragment shaders	7.7
ATOMIC_COUNTER_BUFFER_REFERENCED_BY_COMPUTE_SHADER	$B$	<b>GetActiveAtomicCounterBufferiv</b>	FALSE	AACB has a counter used by compute shaders	7.7
UNIFORM_ATOMIC_COUNTER_BUFFER_INDEX	$n \times Z^+$	<b>GetActiveUniformsiv</b>	-	AACB associated with an active uniform	7.7

Table 23.39. Program Object State (cont.)

Get value	Type	Get Command	Initial Value	Description	Sec.
ACTIVE_RESOURCES	$n \times Z^+$	<b>GetProgram-Interfaceiv</b>	0	No. of active resources on an interface	<b>7.3.1</b>
MAX_NAME_LENGTH	$n \times Z^+$	<b>GetProgram-Interfaceiv</b>	0	Max name length for active resources	<b>7.3.1</b>
MAX_NUM_ACTIVE_VARIABLES	$n \times Z^+$	<b>GetProgram-Interfaceiv</b>	0	Max no. of active variables for active resources	<b>7.3.1</b>
MAX_NUM_COMPATIBLE_SUBROUTINES	$n \times Z^+$	<b>GetProgram-Interfaceiv</b>	0	Max no. of compatible subroutines for subroutine uniforms	<b>7.3.1</b>

Table 23.40. Program Interface State

Get value	Type	Get Command	Initial Value	Description	Sec.
NAME.LENGTH	Z <sup>+</sup>	<b>GetProgram-Resourceiv</b>	-	length of active resource name	7.3.1
TYPE	Z <sup>+</sup>	<b>GetProgram-Resourceiv</b>	-	active resource data type	7.3.1
ARRAY.SIZE	Z <sup>+</sup>	<b>GetProgram-Resourceiv</b>	-	active resource array size	7.3.1
OFFSET	Z <sup>+</sup>	<b>GetProgram-Resourceiv</b>	-	active resource offset in memory	7.3.1
BLOCK.INDEX	Z <sup>+</sup>	<b>GetProgram-Resourceiv</b>	-	index of interface block owning resource	7.3.1
ARRAY.STRIDE	Z <sup>+</sup>	<b>GetProgram-Resourceiv</b>	-	active resource array stride in memory	7.3.1
MATRIX.STRIDE	Z <sup>+</sup>	<b>GetProgram-Resourceiv</b>	-	active resource matrix stride in memory	7.3.1
IS.ROW.MAJOR	Z <sup>+</sup>	<b>GetProgram-Resourceiv</b>	-	active resource stored as a row major matrix?	7.3.1
ATOMIC.COUNTER.BUFFER.INDEX	Z <sup>+</sup>	<b>GetProgram-Resourceiv</b>	-	index of atomic counter buffer owning resource	7.3.1
BUFFER.BINDING	Z <sup>+</sup>	<b>GetProgram-Resourceiv</b>	-	buffer binding assigned to active resource	7.3.1
BUFFER.DATA.SIZE	Z <sup>+</sup>	<b>GetProgram-Resourceiv</b>	-	Min buffer data size required for resource	7.3.1
NUM.ACTIVE.VARIABLES	Z <sup>+</sup>	<b>GetProgram-Resourceiv</b>	-	No. of active variables owned by active resource	7.3.1
ACTIVE.VARIABLES	Z <sup>+</sup>	<b>GetProgram-Resourceiv</b>	-	list of active variables owned by active resource	7.3.1

Table 23.41. Program Object Resource State

Get value	Type	Get Command	Initial Value	Description	Sec.
REFERENCED_BY_VERTEX_SHADER	Z+	<b>GetProgramResourceiv</b>	-	active resource used by vertex shader?	7.3.1
REFERENCED_BY_TESS_CONTROL_SHADER	Z+	<b>GetProgramResourceiv</b>	-	active resource used by tess. control shader?	7.3.1
REFERENCED_BY_TESS_EVALUATION_SHADER	Z+	<b>GetProgramResourceiv</b>	-	active resource used by tess evaluation shader?	7.3.1
REFERENCED_BY_GEOMETRY_SHADER	Z+	<b>GetProgramResourceiv</b>	-	active resource used by geometry shader?	7.3.1
REFERENCED_BY_FRAGMENT_SHADER	Z+	<b>GetProgramResourceiv</b>	-	active resource used by fragment shader?	7.3.1
REFERENCED_BY_COMPUTE_SHADER	Z+	<b>GetProgramResourceiv</b>	-	active resource used by compute shader?	7.3.1
TOP_LEVEL_ARRAY_SIZE	Z+	<b>GetProgramResourceiv</b>	-	array size of top level shd. storage block member	7.3.1
TOP_LEVEL_ARRAY_STRIDE	Z+	<b>GetProgramResourceiv</b>	-	array stride of top level shd. storage block member	7.3.1
LOCATION	Z+	<b>GetProgramResourceiv</b>	-	location assigned to active resource	7.3.1
LOCATION_INDEX	Z+	<b>GetProgramResourceiv</b>	-	location index assigned to active resource	7.3.1
IS_PER_PATCH	Z+	<b>GetProgramResourceiv</b>	-	is active input/output a per-patch attribute?	7.3.1
NUM_COMPATIBLE_SUBROUTINES	Z+	<b>GetProgramResourceiv</b>	-	No. of compatible sub-routines for active sub-routine uniform	7.3.1
COMPATIBLE_SUBROUTINES	Z+	<b>GetProgramResourceiv</b>	-	list of compatible sub-routines for active sub-routine uniform	7.3.1

Table 23.42. Program Object Resource State (cont.)

Get value	Type	Get Command	Initial Value	Description	Sec.
CURRENT_VERTEX_ATTRIB	$16 * \times R^4$	<b>GetVertexAttribfv</b>	0.0,0.0,0.0,1.0	Current generic vertex attribute values	<b>10.2</b>
PROGRAM_POINT_SIZE	$B$	<b>IsEnabled</b>	FALSE	Point size mode	<b>14.4</b>

Table 23.43. Vertex and Geometry Shader State (not part of program objects)



Get value	Type	Get Command	Initial Value	Description	Sec.
QUERY_RESULT	$Z^+$	<b>GetQueryObjectiv</b>	0 or FALSE	Query object result	<b>4.2.1</b>
QUERY_RESULT_AVAILABLE	$B$	<b>GetQueryObjectiv</b>	FALSE	Is the query object result available?	<b>4.2.1</b>
LABEL	$S$	<b>GetObjectLabel</b>	empty	Debug label	<b>20.9</b>

Table 23.44. Query Object State

Get value	Type	Get Command	Initial Value	Description	Sec.
IMAGE.BINDING_NAME	$8 * \times Z^+$	<b>GetIntegeri_v</b>	0	Name of bound texture object	8.25
IMAGE.BINDING_LEVEL	$8 * \times Z^+$	<b>GetIntegeri_v</b>	0	Level of bound texture object	8.25
IMAGE.BINDING_LAYERED	$8 * \times B$	<b>GetBooleani_v</b>	FALSE	Texture object bound with multiple layers	8.25
IMAGE.BINDING_LAYER	$8 * \times Z^+$	<b>GetIntegeri_v</b>	0	Layer of bound texture, if not layered	8.25
IMAGE.BINDING_ACCESS	$8 * \times E$	<b>GetIntegeri_v</b>	READ_ONLY	Read and/or write access for bound texture	8.25
IMAGE.BINDING_FORMAT	$8 * \times Z^+$	<b>GetIntegeri_v</b>	R8	Format used for accesses to bound texture	8.25

Table 23.45. Image State (state per image unit)

Get value	Type	Get Command	Initial Value	Description	Sec.
ATOMIC_COUNTER_BUFFER_BINDING	$Z^+$	<b>GetInteger</b>	0	Current value of generic atomic counter buffer binding	<b>6.8</b>
ATOMIC_COUNTER_BUFFER_BINDING	$n \times Z^+$	<b>GetInteger<sub>v</sub></b>	0	Buffer object bound to each atomic counter buffer binding point	<b>6.8</b>
ATOMIC_COUNTER_BUFFER_START	$n \times Z^+$	<b>GetInteger64<sub>v</sub></b>	0	Start offset of binding range for each atomic counter buffer	<b>6.8</b>
ATOMIC_COUNTER_BUFFER_SIZE	$n \times Z^+$	<b>GetInteger64<sub>v</sub></b>	0	Size of binding range for each atomic counter buffer	<b>6.8</b>

Table 23.46. Atomic Counter Buffer Binding State

Get value	Type	Get Command	Initial Value	Description	Sec.
SHADER_STORAGE_BUFFER_BINDING	$Z^+$	<b>GetInteger</b>	0	Current value of generic shader storage buffer binding	<b>7.8</b>
SHADER_STORAGE_BUFFER_BINDING	$n \times Z^+$	<b>GetInteger<sub>v</sub></b>	0	Buffer object bound to each shader storage buffer binding point	<b>7.8</b>
SHADER_STORAGE_BUFFER_START	$n \times Z^+$	<b>GetInteger<sub>64i_v</sub></b>	0	Start offset of binding range for each shader storage buffer	<b>7.8</b>
SHADER_STORAGE_BUFFER_SIZE	$n \times Z^+$	<b>GetInteger<sub>64i_v</sub></b>	0	Size of binding range for each shader storage buffer	<b>7.8</b>

Table 23.47. Shader Storage Buffer **Binding** State

Get value	Type	Get Command	Initial Value	Description	Sec.
TRANSFORM_FEEDBACK_BUFFER_BINDING	$Z^+$	<b>GetIntegerv</b>	0	Buffer object bound to generic bind point for transform feedback	<a href="#">6.7</a>
TRANSFORM_FEEDBACK_BUFFER_BINDING	$n \times Z^+$	<b>GetIntegeri_v</b>	0	Buffer object bound to each transform feedback attribute stream	<a href="#">6.7</a>
TRANSFORM_FEEDBACK_BUFFER_START	$n \times Z^+$	<b>GetInteger64i_v</b>	0	Start offset of binding range for each transform feedback attrib. stream	<a href="#">6.7</a>
TRANSFORM_FEEDBACK_BUFFER_SIZE	$n \times Z^+$	<b>GetInteger64i_v</b>	0	Size of binding range for each transform feedback attrib. stream	<a href="#">6.7</a>
TRANSFORM_FEEDBACK_PAUSED	$B$	<b>GetBooleanv</b>	FALSE	Is transform feedback paused on this object?	<a href="#">6.7</a>
TRANSFORM_FEEDBACK_ACTIVE	$B$	<b>GetBooleanv</b>	FALSE	Is transform feedback active on this object?	<a href="#">6.7</a>
LABEL	$S$	<b>GetObjectLabel</b>	empty	Debug label	<a href="#">20.9</a>

Table 23.48. Transform Feedback State

Get value	Type	Get Command	Initial Value	Description	Sec.
UNIFORM_BUFFER_BINDING	$Z^+$	<b>GetIntegerv</b>	0	Uniform buffer object bound to the context for buffer object manipulation	7.6.2
UNIFORM_BUFFER_BINDING	$n \times Z^+$	<b>GetIntegeri_v</b>	0	Uniform buffer object bound to the specified context binding point	7.6.2
UNIFORM_BUFFER_START	$n \times Z^+$	<b>GetInteger64i_v</b>	0	Start of bound uniform buffer region	6.7
UNIFORM_BUFFER_SIZE	$n \times Z^+$	<b>GetInteger64i_v</b>	0	Size of bound uniform buffer region	6.7

Table 23.49. Uniform Buffer Binding State

Get value	Type	Get Command	Initial Value	Description	Sec.
OBJECT.TYPE	<i>E</i>	<b>GetSynciv</b>	SYNC_FENCE	Type of sync object	4.1
SYNC.STATUS	<i>E</i>	<b>GetSynciv</b>	UNSIGNED	Sync object status	4.1
SYNC.CONDITION	<i>E</i>	<b>GetSynciv</b>	SYNC_GPU_COMMANDS_COMPLETE	Sync object condition	4.1
SYNC.FLAGS	<i>Z</i>	<b>GetSynciv</b>	0	Sync object flags	4.1
LABEL	<i>S</i>	<b>GetObjectPtrLabel</b>	empty	Debug label	20.9

Table 23.50. Sync (state per sync object)

Get value	Type	Get Command	Initial Value	Description	Sec.
LINE_SMOOTH_HINT	<i>E</i>	<b>GetIntegerv</b>	DONT_CARE	Line smooth hint	<b>21.5</b>
POLYGON_SMOOTH_HINT	<i>E</i>	<b>GetIntegerv</b>	DONT_CARE	Polygon smooth hint	<b>21.5</b>
TEXTURE_COMPRESSION_HINT	<i>E</i>	<b>GetIntegerv</b>	DONT_CARE	Texture compression quality hint	<b>21.5</b>
FRAGMENT_SHADER_DERIVATIVE_HINT	<i>E</i>	<b>GetIntegerv</b>	DONT_CARE	Fragment shader derivative accuracy hint	<b>21.5</b>

Table 23.51. Hints



Get value	Type	Get Command	Initial Value	Description	Sec.
DISPATCHINDIRECT_BUFFER_BINDING	Z <sup>+</sup>	<b>GetIntegerv</b>	0	Indirect dispatch buffer binding	<b>19</b>

Table 23.52. Compute Dispatch State

Get value	Type	Get Command	Minimum Value	Description	Sec.
MAX_CLIP_DISTANCES	Z <sup>+</sup>	<b>GetInteger</b>	8	Max no. of user clipping planes	13.5
SUBPIXEL_BITS	Z <sup>+</sup>	<b>GetInteger</b>	4	No. of bits of subpixel precision in screen $x_w$ and $y_w$	14
MAX_ELEMENT_INDEX	Z <sup>+</sup>	<b>GetInteger64v</b>	$2^{32} - 1$	Max element index	10.5
IMPLEMENTATION_COLOR_READ_FORMAT	E	<b>GetInteger</b>	RGBA	Implementation preferred pixel <i>format</i>	18.2
IMPLEMENTATION_COLOR_READ_TYPE	E	<b>GetInteger</b>	UNSIGNED_BYTE	Implementation preferred pixel <i>type</i>	18.2
MAX_3D_TEXTURE_SIZE	Z <sup>+</sup>	<b>GetInteger</b>	2048	Max 3D texture image dimension	8.5
MAX_TEXTURE_SIZE	Z <sup>+</sup>	<b>GetInteger</b>	16384	Max 2D/1D texture image dimension	8.5
MAX_ARRAY_TEXTURE_LAYERS	Z <sup>+</sup>	<b>GetInteger</b>	2048	Max no. of layers for texture arrays	8.5
MAX_TEXTURE_LOD_BIAS	R <sup>+</sup>	<b>GetFloatv</b>	2.0	Max absolute texture level of detail bias	8.14
MAX_CUBE_MAP_TEXTURE_SIZE	Z <sup>+</sup>	<b>GetInteger</b>	16384	Max cube map texture image dimension	8.5
MAX_RENDERBUFFER_SIZE	Z <sup>+</sup>	<b>GetInteger</b>	16384	Max width and height of render buffers	9.2.4

Table 23.53. Implementation Dependent Values

Get value	Type	Get Command	Minimum Value	Description	Sec.
MAX.VIEWPORT_DIMS	$2 \times Z^+$	<b>GetFloatv</b>	see 13.6.1	Max viewport dimensions	13.6.1
MAX.VIEWPORTS	$Z^+$	<b>GetIntegerv</b>	16	Max no. of active viewports	13.6.1
VIEWPORT.SUBPIXEL_BITS	$Z^+$	<b>GetIntegerv</b>	0	No. of bits of sub-pixel precision for viewport bounds	13.6.1
VIEWPORT.BOUNDS.RANGE	$2 \times R$	<b>GetFloatv</b>	†	Viewport bounds range [ <i>min</i> , <i>max</i> ] † (at least [-32768, 32767])	13.6.1
LAYER.PROVOKING_VERTEX	$E$	<b>GetIntegerv</b>	see 11.3.4	Vertex convention followed by <code>gl_Layer</code>	11.3.4
VIEWPORT.INDEX.PROVOKING_VERTEX	$E$	<b>GetIntegerv</b>	see 11.3.4	Vertex convention followed by <code>gl_ViewPortIndex</code>	11.3.4
POINT.SIZE.RANGE	$2 \times R^+$	<b>GetFloatv</b>	1,1	Range (lo to hi) of point sprite sizes	14.4
POINT.SIZE.GRANULARITY	$R^+$	<b>GetFloatv</b>	–	Point sprite size granularity	14.4
ALIASED.LINE.WIDTH.RANGE	$2 \times R^+$	<b>GetFloatv</b>	1,1	Range (lo to hi) of aliased line widths	14.5
SMOOTH.LINE.WIDTH.RANGE	$2 \times R^+$	<b>GetFloatv</b>	1,1	Range (lo to hi) of antialiased line widths	14.5
SMOOTH.LINE.WIDTH.GRANULARITY	$R^+$	<b>GetFloatv</b>	–	Antialiased line width granularity	14.5
MAX.ELEMENTS.INDICES	$Z^+$	<b>GetIntegerv</b>	–	Recommended max no. of <b>DrawRangeElements</b> indices	10.3
MAX.ELEMENTS.VERTICES	$Z^+$	<b>GetIntegerv</b>	–	Recommended max no. of <b>DrawRangeElements</b> vertices	10.3

Table 23.54. Implementation Dependent Values (cont.)

Get value	Type	Get Command	Minimum Value	Description	Sec.
MAX_VERTEX_ATTRIB_RELATIVE_OFFSET	Z	<b>GetIntegerv</b>	2047	Max offset added to vertex buffer binding offset	10.3
MAX_VERTEX_ATTRIB_BINDINGS	Z <sub>16*</sub>	<b>GetIntegerv</b>	16	Max no. of vertex buffers	10.3
COMPRESSED_TEXTURE_FORMATS	4 * × Z <sup>+</sup>	<b>GetIntegerv</b>	-	Enumerated compressed texture formats	8.7
NUM_COMPRESSED_TEXTURE_FORMATS	Z <sup>+</sup>	<b>GetIntegerv</b>	0	No. of compressed texture formats	8.7
MAX_TEXTURE_BUFFER_SIZE	Z <sup>+</sup>	<b>GetIntegerv</b>	65536	No. of addressable texels for buffer textures	8.9
MAX_RECTANGLE_TEXTURE_SIZE	Z <sup>+</sup>	<b>GetIntegerv</b>	16384	Max width & height of rectangle textures	8.5
PROGRAM_BINARY_FORMATS	0 * × Z <sup>+</sup>	<b>GetIntegerv</b>	N/A	Enumerated program binary formats	7.5
NUM_PROGRAM_BINARY_FORMATS	Z <sup>+</sup>	<b>GetIntegerv</b>	0	No. of program binary formats	7.5
SHADER_BINARY_FORMATS	0 * × Z <sup>+</sup>	<b>GetIntegerv</b>	-	Enumerated shader binary formats	7.2
NUM_SHADER_BINARY_FORMATS	Z <sup>+</sup>	<b>GetIntegerv</b>	0	No. of shader binary formats	7.2
SHADER_COMPILER	B	<b>GetBooleanv</b>	-	Shader compiler supported	7
MIN_MAP_BUFFER_ALIGNMENT	Z <sup>+</sup>	<b>GetIntegerv</b>	64	Min byte alignment of pointers returned by <b>Map*Buffer</b>	6.3
TEXTURE_BUFFER_OFFSET_ALIGNMENT	Z <sup>+</sup>	<b>GetIntegerv</b>	1	Min required alignment for texture buffer offsets	8.9

Table 23.55. Implementation Dependent Values (cont.)

Get value	Type	Get Command	Minimum Value	Description	Sec.
MAJOR_VERSION	$Z^+$	<b>GetIntegerv</b>	–	Major version no. supported	22.2
MINOR_VERSION	$Z^+$	<b>GetIntegerv</b>	–	Minor version no. supported	22.2
CONTEXT_FLAGS	$Z^+$	<b>GetIntegerv</b>	–	Context full/forward-compatible flag	22.2
EXTENSIONS	$n \times S$	<b>GetStringi</b>	–	Supported individual extension names	22.2
NUM_EXTENSIONS	$Z^+$	<b>GetIntegerv</b>	0	No. of individual extension names	22.2
RENDERER	$S$	<b>GetString</b>	–	Renderer string	22.2
SHADING_LANGUAGE_VERSION	$S$	<b>GetString</b>	–	Latest Shading Language version supported	22.2
SHADING_LANGUAGE_VERSION	$n \times S$	<b>GetStringi</b>	–	Supported Shading Language versions	22.2
NUM_SHADING_LANGUAGE_VERSIONS	$Z^+$	<b>GetIntegerv</b>	3	No. of supported Shading Language versions	22.2
VENDOR	$S$	<b>GetString</b>	–	Vendor string	22.2
VERSION	$S$	<b>GetString</b>	–	OpenGL version supported	22.2

Table 23.56. Implementation Dependent Version and Extension Support

Get value	Type	Get Command	Minimum Value	Description	Sec.
MAX_VERTEX_ATTRIBS	Z <sup>+</sup>	<b>GetIntegerv</b>	16	No. of active vertex attributes	10.2
MAX_VERTEX_UNIFORM_COMPONENTS	Z <sup>+</sup>	<b>GetIntegerv</b>	1024	No. of components for vertex shader uniform variables	7.6
MAX_VERTEX_UNIFORM_VECTORS	Z <sup>+</sup>	<b>GetIntegerv</b>	256	No. of vectors for vertex shader uniform variables	7.6
MAX_VERTEX_UNIFORM_BLOCKS	Z <sup>+</sup>	<b>GetIntegerv</b>	14*	Max no. of vertex uniform buffers per program	7.6.2
MAX_VERTEX_OUTPUT_COMPONENTS	Z <sup>+</sup>	<b>GetIntegerv</b>	64	Max no. of components of outputs written by a vertex shader	11.1.2.1
MAX_VERTEX_TEXTURE_IMAGE_UNITS	Z <sup>+</sup>	<b>GetIntegerv</b>	16	No. of texture image units accessible by a vertex shader	11.1.3.5
MAX_VERTEX_ATOMIC_COUNTER_BUFFERS	Z <sup>+</sup>	<b>GetIntegerv</b>	0	No. of atomic counter buffers accessed by a vertex shader	7.7
MAX_VERTEX_ATOMIC_COUNTERS	Z <sup>+</sup>	<b>GetIntegerv</b>	0	No. of atomic counters accessed by a vertex shader	11.1.3.6
MAX_VERTEX_SHADER_STORAGE_BLOCKS	Z <sup>+</sup>	<b>GetIntegerv</b>	0	No. of shader storage blocks accessed by a vertex shader	7.8

Table 23.57. Implementation Dependent Vertex Shader Limits

Get value	Type	Get Command	Minimum Value	Description	Sec.
MAX_TESS_GEN_LEVEL	Z <sup>+</sup>	<b>GetIntegerv</b>	64	Max level supported by tess. primitive generator	11.2.2
MAX_PATCH_VERTICES	Z <sup>+</sup>	<b>GetIntegerv</b>	32	Max patch size	10.1
MAX_TESS_CONTROL_UNIFORM_COMPONENTS	Z <sup>+</sup>	<b>GetIntegerv</b>	1024	No. of words for tess. control shader (TCS) uniforms	11.2.1.1
MAX_TESS_CONTROL_TEXTURE_IMAGE_UNITS	Z <sup>+</sup>	<b>GetIntegerv</b>	16	No. of tex. image units for TCS	11.1.3
MAX_TESS_CONTROL_OUTPUT_COMPONENTS	Z <sup>+</sup>	<b>GetIntegerv</b>	128	No. components for TCS per-vertex outputs	11.2.1.2
MAX_TESS_PATCH_COMPONENTS	Z <sup>+</sup>	<b>GetIntegerv</b>	120	No. components for TCS per-patch outputs	11.2.1.2
MAX_TESS_CONTROL_TOTAL_OUTPUT_COMPONENTS	Z <sup>+</sup>	<b>GetIntegerv</b>	4096	No. components for TCS per-vertex outputs	11.2.1.2
MAX_TESS_CONTROL_INPUT_COMPONENTS	Z <sup>+</sup>	<b>GetIntegerv</b>	128	No. components for TCS per-vertex inputs	11.2.1.2
MAX_TESS_CONTROL_UNIFORM_BLOCKS	Z <sup>+</sup>	<b>GetIntegerv</b>	14*	No. of supported uniform blocks for TCS	7.6.2
MAX_TESS_CONTROL_ATOMIC_COUNTER_BUFFERS	Z <sup>+</sup>	<b>GetIntegerv</b>	0	No. of atomic counter (AC) buffers accessed by a TCS	7.7
MAX_TESS_CONTROL_ATOMIC_COUNTERS	Z <sup>+</sup>	<b>GetIntegerv</b>	0	No. of ACs accessed by a TCS	7.7
MAX_TESS_CONTROL_SHADER_STORAGE_BLOCKS	Z <sup>+</sup>	<b>GetIntegerv</b>	0	No. of shader storage blocks accessed by a tess. control shader	7.8

Table 23.58. Implementation Dependent Tessellation Shader Limits

Get value	Type	Get Command	Minimum Value	Description	Sec.
MAX_TESS_EVALUATION_UNIFORM_COMPONENTS	Z <sup>+</sup>	<b>GetIntegerv</b>	1024	No. of words for tess. evaluation shader (TES) uniforms	<b>11.2.3.1</b>
MAX_TESS_EVALUATION_TEXTURE_IMAGE_UNITS	Z <sup>+</sup>	<b>GetIntegerv</b>	16	No. of tex. image units for TES	<b>11.1.3</b>
MAX_TESS_EVALUATION_OUTPUT_COMPONENTS	Z <sup>+</sup>	<b>GetIntegerv</b>	128	No. components for TES per-vertex outputs	<b>11.2.3.2</b>
MAX_TESS_EVALUATION_INPUT_COMPONENTS	Z <sup>+</sup>	<b>GetIntegerv</b>	128	No. components for TES per-vertex inputs	<b>11.2.3.2</b>
MAX_TESS_EVALUATION_UNIFORM_BLOCKS	Z <sup>+</sup>	<b>GetIntegerv</b>	14*	No. of supported uniform blocks for TES	<b>7.6.2</b>
MAX_TESS_EVALUATION_ATOMIC_COUNTER_BUFFERS	Z <sup>+</sup>	<b>GetIntegerv</b>	0	No. of AC buffers accessed by a TES	<b>11.1.3.6</b>
MAX_TESS_EVALUATION_ATOMIC_COUNTERS	Z <sup>+</sup>	<b>GetIntegerv</b>	0	No. of ACs accessed by a TES	<b>11.1.3.6</b>
MAX_TESS_EVALUATION_SHADER_STORAGE_BLOCKS	Z <sup>+</sup>	<b>GetIntegerv</b>	0	No. of shader storage blocks accessed by a tess. evaluation shader	<b>7.8</b>

Table 23.59. Implementation Dependent Tessellation Shader Limits (cont.)



Get value	Type	Get Command	Minimum Value	Description	Sec.
MAX.GEOMETRY_UNIFORM_COMPONENTS	Z <sup>+</sup>	<b>GetInteger</b>	512	No. of components for geometry shader (GS) uniform variables	11.3.3
MAX.GEOMETRY_UNIFORM_BLOCKS	Z <sup>+</sup>	<b>GetInteger</b>	14*	Max no. of GS uniform buffers per program	7.6.2
MAX.GEOMETRY_INPUT_COMPONENTS	Z <sup>+</sup>	<b>GetInteger</b>	64	Max no. of components of inputs read by a GS	11.3.4.4
MAX.GEOMETRY_OUTPUT_COMPONENTS	Z <sup>+</sup>	<b>GetInteger</b>	128	Max no. of components of outputs written by a GS	11.3.4.5
MAX.GEOMETRY_OUTPUT_VERTICES	Z <sup>+</sup>	<b>GetInteger</b>	256	Max no. of vertices that any GS can emit	11.3.4
MAX.GEOMETRY_TOTAL_OUTPUT_COMPONENTS	Z <sup>+</sup>	<b>GetInteger</b>	1024	Max no. of total components (all vertices) of active outputs that a GS can emit	11.3.4
MAX.GEOMETRY_TEXTURE_IMAGE_UNITS	Z <sup>+</sup>	<b>GetInteger</b>	16	No. of texture image units accessible by a GS	11.3.4
MAX.GEOMETRY_SHADER_INVOCATIONS	Z <sup>+</sup>	<b>GetInteger</b>	32	Max supported GS invocation count	11.3.4.2
MAX.VERTICES_STREAMS	Z <sup>+</sup>	<b>GetInteger</b>	4	Total no. of vertex streams	11.3.4.2
MAX.GEOMETRY_ATOMIC_COUNTER_BUFFERS	Z <sup>+</sup>	<b>GetInteger</b>	0	No. of atomic counter buffers accessed by a GS	7.7
MAX.GEOMETRY_ATOMIC_COUNTERS	Z <sup>+</sup>	<b>GetInteger</b>	0	No. of atomic counters accessed by a GS	11.1.3.6
MAX.GEOMETRY_SHADER_STORAGE_BLOCKS	Z <sup>+</sup>	<b>GetInteger</b>	0	No. of shader storage blocks accessed by a GS	7.8

Table 23.60. Implementation Dependent Geometry Shader Limits

Get value	Type	Get Command	Minimum Value	Description	Sec.
MAX_FRAGMENT_UNIFORM_COMPONENTS	Z <sup>+</sup>	<b>GetIntegerv</b>	1024	No. of components for fragment shader (FS) uniform variables	<b>15.1</b>
MAX_FRAGMENT_UNIFORM_VECTORS	Z <sup>+</sup>	<b>GetIntegerv</b>	256	No. of vectors for FS uniform variables	<b>15.1</b>
MAX_FRAGMENT_UNIFORM_BLOCKS	Z <sup>+</sup>	<b>GetIntegerv</b>	14*	Max no. of FS uniform buffers per program	<b>7.6.2</b>
MAX_FRAGMENT_INPUT_COMPONENTS	Z <sup>+</sup>	<b>GetIntegerv</b>	128	Max no. of components of inputs read by a FS	<b>15.2.2</b>
MAX_TEXTURE_IMAGE_UNITS	Z <sup>+</sup>	<b>GetIntegerv</b>	16	No. of texture image units accessible by a FS	<b>11.1.3.5</b>
MIN_PROGRAM_TEXTURE_GATHER_OFFSET	Z	<b>GetIntegerv</b>	-8	Min texel offset for textureGather	<b>8.14.1</b>
MAX_PROGRAM_TEXTURE_GATHER_OFFSET	Z <sup>+</sup>	<b>GetIntegerv</b>	7	Max texel offset for textureGather	<b>8.14.1</b>
MAX_FRAGMENT_ATOMIC_COUNTER_BUFFERS	Z <sup>+</sup>	<b>GetIntegerv</b>	1	No. of atomic counter buffers accessed by a FS	<b>7.7</b>
MAX_FRAGMENT_ATOMIC_COUNTERS	Z <sup>+</sup>	<b>GetIntegerv</b>	8	No. of atomic counters accessed by a FS	<b>11.1.3.6</b>
MAX_FRAGMENT_SHADER_STORAGE_BLOCKS	Z <sup>+</sup>	<b>GetIntegerv</b>	8	No. of shader storage blocks accessed by a FS	<b>7.8</b>

Table 23.61. Implementation Dependent Fragment Shader Limits

Get value	Type	Get Command	Minimum Value	Description	Sec.
MAX_COMPUTE_WORK_GROUP_COUNT	$3 \times Z^+$	<b>GetIntegeri_v</b>	65535	Max no. of work groups (WG) that may be dispatched by a single dispatch command (per dimension)	19
MAX_COMPUTE_WORK_GROUP_SIZE	$3 \times Z^+$	<b>GetIntegeri_v</b>	1024 (x, y), 64 (z)	Max local size of a compute WG (per dimension)	19
MAX_COMPUTE_WORK_GROUP_INVOCATIONS	$Z^+$	<b>GetInteger_v</b>	1024	Max total compute shader (CS) invocations in a single local WG	19
MAX_COMPUTE_UNIFORM_BLOCKS	$Z^+$	<b>GetInteger_v</b>	14*	Max no. of uniform blocks per compute program	7.6.2
MAX_COMPUTE_TEXTURE_IMAGE_UNITS	$Z^+$	<b>GetInteger_v</b>	16	Max no. of texture image units accessible by a CS	11.1.3.5
MAX_COMPUTE_ATOMIC_COUNTER_BUFFERS	$Z^+$	<b>GetInteger_v</b>	8	No. of atomic counter buffers accessed by a CS	7.7
MAX_COMPUTE_ATOMIC_COUNTERS	$Z^+$	<b>GetInteger_v</b>	8	No. of atomic counters accessed by a CS	11.1.3.6
MAX_COMPUTE_SHARED_MEMORY_SIZE	$Z^+$	<b>GetInteger_v</b>	32768	Max total storage size of all variables declared as <i>shared</i> in all CSs linked into a single program object	19.1
MAX_COMPUTE_UNIFORM_COMPONENTS	$Z^+$	<b>GetInteger_v</b>	512	No. of components for CS uniform variables	19.1
MAX_COMPUTE_IMAGE_UNIFORMS	$Z^+$	<b>GetInteger_v</b>	8	No. of image variables in compute shaders	11.1.3
MAX_COMBINED_COMPUTE_UNIFORM_COMPONENTS	$Z^+$	<b>GetInteger_v</b>	*	No. of words for compute shader uniform variables in all uniform blocks, including the default	19.1
MAX_COMPUTE_SHADER_STORAGE_BLOCKS	$Z^+$	<b>GetInteger_v</b>	8	No. of shader storage blocks accessed by a compute shader	7.8

Table 23.62. Implementation Dependent Compute Shader Limits

Get value	Type	Get Command	Minimum Value	Description	Sec.
MIN_PROGRAM_TEXTURE_OFFSET	Z	<b>GetIntegerv</b>	-8	Min texel offset allowed in lookup	<b>11.1.3.5</b>
MAX_PROGRAM_TEXTURE_OFFSET	Z	<b>GetIntegerv</b>	7	Max texel offset allowed in lookup	<b>11.1.3.5</b>
MAX_UNIFORM_BUFFER_BINDINGS	Z+	<b>GetIntegerv</b>	84	Max no. of uniform buffer binding points on the context	<b>7.6.2</b>
MAX_UNIFORM_BLOCK_SIZE	Z+	<b>GetIntegerv</b>	16384	Max size in basic machine units of a uniform block	<b>7.6.2</b>
UNIFORM_BUFFER_OFFSET_ALIGNMENT	Z+	<b>GetIntegerv</b>	1	Min required alignment for uniform buffer sizes and offsets	<b>7.6.2</b>
MAX_COMBINED_UNIFORM_BLOCKS	Z+	<b>GetIntegerv</b>	70*	Max no. of uniform buffers per program	<b>7.6.2</b>
MAX_VARYING_COMPONENTS	Z+	<b>GetIntegerv</b>	60	No. of components for output variables	<b>11.1.2.1</b>
MAX_VARYING_VECTORS	Z+	<b>GetIntegerv</b>	15	No. of vectors for output variables	<b>11.1.2.1</b>
MAX_COMBINED_TEXTURE_IMAGE_UNITS	Z+	<b>GetIntegerv</b>	96	Total no. of texture units accessible by the GL	<b>11.1.3.5</b>
MAX_SUBROUTINES	Z+	<b>GetIntegerv</b>	256	Max no. of subroutines per shader stage	<b>7.9</b>
MAX_SUBROUTINE_UNIFORM_LOCATIONS	Z+	<b>GetIntegerv</b>	1024	Max no. of subroutine uniform locations per stage	<b>7.9</b>
MAX_UNIFORM_LOCATIONS	Z+	<b>GetIntegerv</b>	1024	Max no. of user-assignable uniform locations	<b>7.6</b>

Table 23.63. Implementation Dependent Aggregate Shader Limits

Get value	Type	Get Command	Minimum Value	Description	Sec.
MAX_ATOMIC_COUNTER_BUFFER_BINDINGS	Z <sup>+</sup>	<b>GetIntegerv</b>	1	Max no. of atomic counter buffer bindings	6.8
MAX_ATOMIC_COUNTER_BUFFER_SIZE	Z <sup>+</sup>	<b>GetIntegerv</b>	32	Max size in basic machine units of an atomic counter buffer	7.7
MAX_COMBINED_ATOMIC_COUNTER_BUFFERS	Z <sup>+</sup>	<b>GetIntegerv</b>	1	Max no. of atomic counter buffers per program	7.7
MAX_COMBINED_ATOMIC_COUNTERS	Z <sup>+</sup>	<b>GetIntegerv</b>	8	Max no. of atomic counter uniforms per program	11.1.3.6
MAX_SHADER_STORAGE_BUFFER_BINDINGS	Z <sup>+</sup>	<b>GetIntegerv</b>	8	Max no. of shader storage buffer bindings in the context	7.8
MAX_SHADER_STORAGE_BLOCK_SIZE	Z <sup>+</sup>	<b>GetInteger64v</b>	2 <sup>24</sup>	Max size in basic machine units of a shader storage block	7.8
MAX_COMBINED_SHADER_STORAGE_BLOCKS	Z <sup>+</sup>	<b>GetIntegerv</b>	8	No. of shader storage blocks accessed by a program	7.8
SHADER_STORAGE_BUFFER_OFFSET_ALIGNMENT	Z <sup>+</sup>	<b>GetIntegerv</b>	256	Min required alignment for shader storage buffer binding offsets	7.8

Table 23.64. Implementation Dependent Aggregate Shader Limits (cont.)

Get value	Type	Get Command	Minimum Value	Description	Sec.
MAX_IMAGE_UNITS	Z <sup>+</sup>	<b>GetIntegerv</b>	8	No. of units for image load/store/atom	8.25
MAX_COMBINED_SHADER_OUTPUT_RESOURCES	Z <sup>+</sup>	<b>GetIntegerv</b>	8	Limit on active image units + fragment outputs	8.25
MAX_IMAGE_SAMPLES	Z <sup>+</sup>	<b>GetIntegerv</b>	0	Max allowed samples for a texture level bound to an image unit	8.25
MAX_VERTEX_IMAGE_UNIFORMS	Z <sup>+</sup>	<b>GetIntegerv</b>	0	No. of image variables in vertex shaders	11.1.3.7
MAX_TESS_CONTROL_IMAGE_UNIFORMS	Z <sup>+</sup>	<b>GetIntegerv</b>	0	No. of image variables in tess. control shaders	11.1.3.7
MAX_TESS_EVALUATION_IMAGE_UNIFORMS	Z <sup>+</sup>	<b>GetIntegerv</b>	0	No. of image variables in tess. eval. shaders	11.1.3.7
MAX_GEOMETRY_IMAGE_UNIFORMS	Z <sup>+</sup>	<b>GetIntegerv</b>	0	No. of image variables in geometry shaders	11.1.3.7
MAX_FRAGMENT_IMAGE_UNIFORMS	Z <sup>+</sup>	<b>GetIntegerv</b>	8	No. of image variables in fragment shaders	11.1.3.7
MAX_COMBINED_IMAGE_UNIFORMS	Z <sup>+</sup>	<b>GetIntegerv</b>	8	No. of image variables in all shaders	11.1.3.7

Table 23.65. Implementation Dependent Aggregate Shader Limits (cont.)

Get value	Type	Get Command	Minimum Value	Description	Sec.
MAX_COMBINED_VERTEX_UNIFORM_COMPONENTS	Z <sup>+</sup>	<b>GetIntegerv</b>	†	No. of words for vertex shader uniform variables in all uniform blocks (including default)	7.6.2
MAX_COMBINED_GEOMETRY_UNIFORM_COMPONENTS	Z <sup>+</sup>	<b>GetIntegerv</b>	†	No. of words for geometry shader uniform variables in all uniform blocks (including default)	7.6.2
MAX_COMBINED_TESS_CONTROL_UNIFORM_COMPONENTS	Z <sup>+</sup>	<b>GetIntegerv</b>	†	No. of words for TCS uniform variables in all uniform blocks (including default)	11.2.1.1
MAX_COMBINED_TESS_EVALUATION_UNIFORM_COMPONENTS	Z <sup>+</sup>	<b>GetIntegerv</b>	†	No. of words for TES uniform variables in all uniform blocks (including default)	11.2.3.1
MAX_COMBINED_FRAGMENT_UNIFORM_COMPONENTS	Z <sup>+</sup>	<b>GetIntegerv</b>	†	No. of words for fragment shader uniform variables in all uniform blocks (including default)	7.6.2

Table 23.66. Implementation Dependent Aggregate Shader Limits (cont.)

† The minimum value for each stage is  $\text{MAX\_stage\_UNIFORM\_BLOCKS} \times \text{MAX\_UNIFORM\_BLOCK\_SIZE} / 4 + \text{MAX\_stage\_UNIFORM\_COMPONENTS}$

Get value	Type	Get Command	Initial Value	Description	Sec.
DEBUG.CALLBACK_FUNCTION	<i>Y</i>	<b>GetPointerv</b>	NULL	The current debug output callback function pointer	<b>20.2</b>
DEBUG.CALLBACK_USER_PARAM	<i>Y</i>	<b>GetPointerv</b>	NULL	The current debug output callback user parameter	<b>20.2</b>
DEBUG.LOGGED_MESSAGES	<i>Z</i> <sup>+</sup>	<b>GetIntegerv</b>	0	The no. of messages currently in the debug message log	<b>20.3</b>
DEBUG.NEXT_LOGGED_MESSAGE_LENGTH	<i>Z</i> <sup>+</sup>	<b>GetIntegerv</b>	0	The string length of the oldest debug message in the debug message log	<b>20.3</b>
DEBUG.OUTPUT_SYNCHRONOUS	<i>B</i>	<b>IsEnabled</b>	FALSE	The enabled state for synchronous debug message callbacks	<b>20.8</b>
DEBUG.GROUP_STACK_DEPTH	<i>Z</i> <sup>+</sup>	<b>GetIntegerv</b>	1	Debug group stack pointer	<b>20.6</b>
DEBUG.OUTPUT	<i>B</i>	<b>IsEnabled</b>	Depends on the context <sup>†</sup>	The enabled state for debug output functionality	<b>20</b>

Table 23.67. Debug Output State

<sup>†</sup> The initial value of `DEBUG_OUTPUT` is `TRUE` in a debug context and `FALSE` in a non-debug context.



Get value	Type	Get Command	Minimum Value	Description	Sec.
MAX_DEBUG_MESSAGE_LENGTH	Z <sup>+</sup>	<b>GetIntegerv</b>	1	The max length of a debug message string, including its null terminator	<b>20.1</b>
MAX_DEBUG_LOGGED_MESSAGES	Z <sup>+</sup>	<b>GetIntegerv</b>	1	The max no. of messages stored in the debug message log	<b>20.3</b>
MAX_DEBUG_GROUP_STACK_DEPTH	Z <sup>+</sup>	<b>GetIntegerv</b>	64	Max group stack depth	<b>20.6</b>
MAX_LABEL_LENGTH	Z <sup>+</sup>	<b>GetIntegerv</b>	256	Max length of a label string	<b>20.7</b>

Table 23.68. Implementation Dependent Debug Output State

Get value	Type	Get Command	Minimum Value	Description	Sec.
MAX_SAMPLE_MASK_WORDS	Z <sup>+</sup>	<b>GetIntegerv</b>	1	Max no. of sample mask words	<b>17.3.3</b>
MAX_SAMPLES	Z <sup>+</sup>	<b>GetIntegerv</b>	4	Max no. of samples supported for all non-integer formats	<b>22.3</b>
MAX_COLOR_TEXTURE_SAMPLES	Z <sup>+</sup>	<b>GetIntegerv</b>	1	Max no. of samples supported for all color formats in a multisample texture	<b>22.3</b>
MAX_DEPTH_TEXTURE_SAMPLES	Z <sup>+</sup>	<b>GetIntegerv</b>	1	Max no. of samples supported for all depth/stencil formats in a multisample texture	<b>22.3</b>
MAX_INTEGER_SAMPLES	Z <sup>+</sup>	<b>GetIntegerv</b>	1	Max no. of samples supported for all integer format multisample buffers	<b>22.3</b>
QUERY_COUNTER_BITS	5 × Z <sup>+</sup>	<b>GetQueryiv</b>	see sec. <b>4.2.1</b>	Asynchronous query counter bits	<b>4.2.1</b>
MAX_SERVER_WAIT_TIMEOUT	Z <sup>+</sup>	<b>GetIntegerv64v</b>	0	Max <b>WaitSync</b> timeout interval	<b>4.1.1</b>

Table 23.69. Implementation Dependent Values (cont.)

Get value	Type	Get Command	Minimum Value	Description	Sec.
MIN.FRAGMENT.INTERPOLATION.OFFSET	$R$	<b>GetFloatv</b>	-0.5	Furthest negative offset for interpolate-AtOffset	<b>15.1</b>
MAX.FRAGMENT.INTERPOLATION.OFFSET	$R$	<b>GetFloatv</b>	+0.5	Furthest positive offset for interpolate-AtOffset	<b>15.1</b>
FRAGMENT.INTERPOLATION.OFFSET.BITS	$Z^+$	<b>GetIntegerv</b>	4	Subpixel bits for interpolate-AtOffset	<b>15.1</b>
MAX.DRAW.BUFFERS	$Z^+$	<b>GetIntegerv</b>	8	Max no. of active draw buffers	<b>17.4.1</b>
MAX.DUAL.SOURCE.DRAW.BUFFERS	$Z^+$	<b>GetIntegerv</b>	1	Max no. of active draw buffers when using dual-source blending	<b>17.3.8</b>
MAX.COLOR.ATTACHMENTS	$Z^+$	<b>GetIntegerv</b>	8	Max no. of FBO attachment points for color buffers	<b>9.2.7</b>

Table 23.70. Implementation Dependent Values (cont.)

Get value	Type	Get Command	Minimum Value	Description	Sec.
SAMPLES	$0 * \times Z^+$	<b>GetInternalformativ</b>	†	Supported sample counts † See section 22.3	22.3
NUM-SAMPLE-COUNTS	$Z^+$	<b>GetInternalformativ</b>	1	No. of supported sample counts	22.3

Table 23.71. Internal Format Dependent Values

Get value	Type	Get Command	Minimum Value	Description	Sec.
MAX_TRANSFORM_FEEDBACK_INTERLEAVED_COMPONENTS	Z <sup>+</sup>	<b>GetIntegerv</b>	64	Max no. of components to write to a single buffer in interleaved mode	13.2
MAX_TRANSFORM_FEEDBACK_SEPARATE_ATTRIBS	Z <sup>+</sup>	<b>GetIntegerv</b>	4	Max no. of separate attributes or outputs that can be captured in transform feedback	13.2
MAX_TRANSFORM_FEEDBACK_SEPARATE_COMPONENTS	Z <sup>+</sup>	<b>GetIntegerv</b>	4	Max no. of components per attribute or output in separate mode	13.2
MAX_TRANSFORM_FEEDBACK_BUFFERS	Z <sup>+</sup>	<b>GetIntegerv</b>	4	Max no. of buffer objs to write with transform feedback	13.2

Table 23.72. Implementation Dependent Transform Feedback Limits

Get value	Type	Get Command	Minimum Value	Description	Sec.
DOUBLEBUFFER	$B$	<b>GetBooleanv</b>	-	True if front & back buffers exist	<b>17.4.1</b>
STEREO	$B$	<b>GetBooleanv</b>	-	True if left & right buffers exist	<b>22</b>
SAMPLE_BUFFERS	$Z^+$	<b>GetIntegerv</b>	0	No. of multisample buffers	<b>14.3.1</b>
SAMPLES	$Z^+$	<b>GetIntegerv</b>	0	Coverage mask size	<b>14.3.1</b>
SAMPLE_POSITION	$n \times 2 \times R^{[0,1]}$	<b>GetMultisamplefv</b>	-	Explicit sample positions	<b>14.3.1</b>

Table 23.73. Framebuffer Dependent Values

Get value	Type	Get Command	Initial Value	Description	Sec.
-	$n \times E$	<b>GetError</b>	0	Current error code(s)	<b>2.3.1</b>
-	$n \times B$	-	FALSE	True if there is a corresponding error	<b>2.3.1</b>
CURRENT_QUERY	$5 \times Z^+$	<b>GetQueryiv</b>	0	Active query object names	<b>4.2.1</b>
COPY_READ_BUFFER_BINDING	$Z^+$	<b>GetIntegerv</b>	0	Buffer object bound to copy buffer “read” bind point	<b>6.6</b>
COPY_WRITE_BUFFER_BINDING	$Z^+$	<b>GetIntegerv</b>	0	Buffer object bound to copy buffer “write” bind point	<b>6.6</b>
TEXTURE_CUBE_MAP_SEAMLESS	$B$	<b>IsEnabled</b>	FALSE	Seamless cube map filtering enable	<b>8.13</b>

Table 23.74. Miscellaneous

# Appendix A

## Invariance

The OpenGL specification is not pixel exact. It therefore does not guarantee an exact match between images produced by different GL implementations. However, the specification does specify exact matches, in some cases, for images produced by the same implementation. The purpose of this appendix is to identify and provide justification for those cases that require exact matches.

### A.1 Repeatability

The obvious and most fundamental case is repeated issuance of a series of GL commands. For any given GL and framebuffer state *vector*, and for any GL command, the resulting GL and framebuffer state must be identical whenever the command is executed on that initial GL and framebuffer state. This repeatability requirement doesn't apply when using shaders containing side effects (image and buffer variable stores and atomic operations, and atomic counter operations), because these memory operations are not guaranteed to be processed in a defined order.

One purpose of repeatability is avoidance of visual artifacts when a double-buffered scene is redrawn. If rendering is not repeatable, swapping between two buffers rendered with the same command sequence may result in visible changes in the image. Such false motion is distracting to the viewer. Another reason for repeatability is testability.

Repeatability, while important, is a weak requirement. Given only repeatability as a requirement, two scenes rendered with one (small) polygon changed in position might differ at every pixel. Such a difference, while within the law of repeatability, is certainly not within its spirit. Additional invariance rules are desirable to ensure useful operation.



## A.2 Multi-pass Algorithms

Invariance is necessary for a whole set of useful multi-pass algorithms. Such algorithms render multiple times, each time with a different GL mode vector, to eventually produce a result in the framebuffer. Examples of these algorithms include:

- “Erasing” a primitive from the framebuffer by redrawing it, either in a different color or using the XOR logical operation.
- Using stencil operations to compute capping planes.

On the other hand, invariance rules can greatly increase the complexity of high-performance implementations of the GL. Even the weak repeatability requirement significantly constrains a parallel implementation of the GL. Because GL implementations are required to implement ALL GL capabilities, not just a convenient subset, those that utilize hardware acceleration are expected to alternate between hardware and software modules based on the current GL mode vector. A strong invariance requirement forces the behavior of the hardware and software modules to be identical, something that may be very difficult to achieve (for example, if the hardware does floating-point operations with different precision than the software).

What is desired is a compromise that results in many compliant, high-performance implementations, and in many software vendors choosing to port to OpenGL.

## A.3 Invariance Rules

For a given instantiation of an OpenGL rendering context:

**Rule 1** *For any given GL and framebuffer state vector, and for any given GL command, the resulting GL and framebuffer state must be identical each time the command is executed on that initial GL and framebuffer state.*

**Rule 2** *Changes to the following state values have no side effects (the use of any other state value is not affected by the change):*

**Required:**

- *Framebuffer contents (all bitplanes)*
- *The color buffers enabled for writing*
- *Scissor parameters (other than enable)*

- *Writemasks (color, depth, stencil)*
- *Clear values (color, depth, stencil)*

**Strongly suggested:**

- *Stencil parameters (other than enable)*
- *Depth test parameters (other than enable)*
- *Blend parameters (other than enable)*
- *Logical operation parameters (other than enable)*
- *Pixel storage state*
- *Polygon offset parameters (other than enables, and except as they affect the depth values of fragments)*

**Corollary 1** *Fragment generation is invariant with respect to the state values marked with • in Rule 2.*

**Rule 3** *The arithmetic of each per-fragment operation is invariant except with respect to parameters that directly control it.*

**Corollary 2** *Images rendered into different color buffers sharing the same framebuffer, either simultaneously or separately using the same command sequence, are pixel identical.*

**Rule 4** *The same vertex or fragment shader will produce the same result when run multiple times with the same input. The wording ‘the same shader’ means a program object that is populated with the same source strings, which are compiled and then linked, possibly multiple times, and which program object is then executed using the same GL state vector. Invariance is relaxed for shaders with side effects, such as accessing atomic counters (see section A.5).*

**Rule 5** *All fragment shaders that either conditionally or unconditionally assign `gl_FragCoord.z` to `gl_FragDepth` are depth-invariant with respect to each other, for those fragments where the assignment to `gl_FragDepth` actually is done.*

If a sequence of GL commands specifies primitives to be rendered with shaders containing side effects (image and buffer variable stores and atomic operations, and atomic counter operations), invariance rules are relaxed. In particular, Rule 1, Corollary 3, and Rule 4 do not apply in the presence of shader side effects.

The following weaker versions of Rule 1 and 4 apply to GL commands involving shader side effects:

**Rule 6** *For any given GL and framebuffer state vector, and for any given GL command, the contents of any framebuffer state not directly or indirectly affected by results of shader image or buffer variable stores or atomic operations, or atomic counter operations must be identical each time the command is executed on that initial GL and framebuffer state.*

**Rule 7** *The same vertex or fragment shader will produce the same result when run multiple times with the same input as long as:*

- *shader invocations do not use image atomic operations or atomic counters;*
- *no framebuffer memory is written to more than once by image stores, unless all such stores write the same value; and*
- *no shader invocation, or other operation performed to process the sequence of commands, reads memory written to by an image store.*

*When any sequence of GL commands triggers shader invocations that perform image stores, atomic operations, or atomic counter operations, and subsequent GL commands read the memory written by those shader invocations, these operations must be explicitly synchronized. For more details, see section 7.12.*

## A.4 Tessellation Invariance

When using a program containing tessellation evaluation shaders, the fixed-function tessellation primitive generator consumes the input patch specified by an application and emits a new set of primitives. The following invariance rules are intended to provide repeatability guarantees. Additionally, they are intended to allow an application with a carefully crafted tessellation evaluation shader to ensure that the sets of triangles generated for two adjacent patches have identical vertices along shared patch edges, avoiding “cracks” caused by minor differences in the positions of vertices along shared edges.

**Rule 1** *When processing two patches with identical outer and inner tessellation levels, the tessellation primitive generator will emit an identical set of point, line, or triangle primitives as long as the active program used to process the patch primitives has tessellation evaluation shaders specifying the same tessellation mode, spacing, vertex order, and point mode input layout qualifiers. Two sets of primitives are considered identical if and only if they contain the same number and type of primitives and the generated tessellation coordinates for the vertex numbered  $m$  of the primitive numbered  $n$  are identical for all values of  $m$  and  $n$ .*

**Rule 2** *The set of vertices generated along the outer edge of the subdivided primitive in triangle and quad tessellation, and the tessellation coordinates of each, depends only on the corresponding outer tessellation level and the spacing input layout qualifier in the tessellation evaluation shader of the active program.*

**Rule 3** *The set of vertices generated when subdividing any outer primitive edge is always symmetric. For triangle tessellation, if the subdivision generates a vertex with tessellation coordinates of the form  $(0, x, 1 - x)$ ,  $(x, 0, 1 - x)$ , or  $(x, 1 - x, 0)$ , it will also generate a vertex with coordinates of exactly  $(0, 1 - x, x)$ ,  $(1 - x, 0, x)$ , or  $(1 - x, x, 0)$ , respectively. For quad tessellation, if the subdivision generates a vertex with coordinates of  $(x, 0)$  or  $(0, x)$ , it will also generate a vertex with coordinates of exactly  $(1 - x, 0)$  or  $(0, 1 - x)$ , respectively. For isoline tessellation, if it generates vertices at  $(0, x)$  and  $(1, x)$  where  $x$  is not zero, it will also generate vertices at exactly  $(0, 1 - x)$  and  $(1, 1 - x)$ , respectively.*

**Rule 4** *The set of vertices generated when subdividing outer edges in triangular and quad tessellation must be independent of the specific edge subdivided, given identical outer tessellation levels and spacing. For example, if vertices at  $(x, 1 - x, 0)$  and  $(1 - x, x, 0)$  are generated when subdividing the  $w = 0$  edge in triangular tessellation, vertices must be generated at  $(x, 0, 1 - x)$  and  $(1 - x, 0, x)$  when subdividing an otherwise identical  $v = 0$  edge. For quad tessellation, if vertices at  $(x, 0)$  and  $(1 - x, 0)$  are generated when subdividing the  $v = 0$  edge, vertices must be generated at  $(0, x)$  and  $(0, 1 - x)$  when subdividing an otherwise identical  $u = 0$  edge.*

**Rule 5** *When processing two patches that are identical in all respects enumerated in rule 1 except for vertex order, the set of triangles generated for triangle and quad tessellation must be identical except for vertex and triangle order. For each triangle  $n_1$  produced by processing the first patch, there must be a triangle  $n_2$  produced when processing the second patch each of whose vertices has the same tessellation coordinates as one of the vertices in  $n_1$ .*

**Rule 6** *When processing two patches that are identical in all respects enumerated in rule 1 other than matching outer tessellation levels and/or vertex order, the set of interior triangles generated for triangle and quad tessellation must be identical in all respects except for vertex and triangle order. For each interior triangle  $n_1$  produced by processing the first patch, there must be a triangle  $n_2$  produced when processing the second patch each of whose vertices has the same tessellation coordinates as one of the vertices in  $n_1$ . A triangle produced by the tessellator is considered an interior triangle if none of its vertices lie on an outer edge of the subdivided primitive.*

**Rule 7** *For quad and triangle tessellation, the set of triangles connecting an inner and outer edge depends only on the inner and outer tessellation levels corresponding to that edge and the spacing input layout qualifier.*

**Rule 8** *The value of all defined components of `gl_TessCoord` will be in the range  $[0, 1]$ . Additionally, for any defined component  $x$  of `gl_TessCoord`, the results of computing  $1.0 - x$  in a tessellation evaluation shader will be exact. Some floating-point values in the range  $[0, 1]$  may fail to satisfy this property, but such values may never be used as tessellation coordinate components.*

## A.5 Atomic Counter Invariance

When using a program containing atomic counters, the following invariance rules are intended to provide repeatability guarantees but within certain constraints.

**Rule 1** *When a single shader type within a program accesses an atomic counter with only `atomicCounterIncrement`, any individual shader invocation is guaranteed to get a unique value returned.*

**Corollary 1** *Also holds true with `atomicCounterDecrement`.*

**Corollary 2** *This does not hold true for `atomicCounter`.*

**Corollary 3** *Repeatability is relaxed. While a unique value is returned to the shader, even given the same initial state vector and buffer contents, it is not guaranteed that the **same** unique value will be returned for each individual invocation of a shader (for example, on any single vertex, or any single fragment). It is wholly the shader writer's responsibility to respect this constraint.*

**Rule 2** *When two or more shader types within a program access an atomic counter with only `atomicCounterIncrement`, there is no repeatability of the ordering of operations between stages. For example, some number of vertices may be processed, then some number of fragments may be processed.*

**Corollary 4** *This also holds true with `atomicCounterDecrement` and `atomicCounter`.*

## A.6 What All This Means

Hardware accelerated GL implementations are expected to default to software operation when some GL state vectors are encountered. Even the weak repeatability requirement means, for example, that OpenGL implementations cannot apply hysteresis to this swap, but must instead guarantee that a given mode vector implies that a subsequent command *always* is executed in either the hardware or the software machine.

The stronger invariance rules constrain when the switch from hardware to software rendering can occur, given that the software and hardware renderers are not pixel identical. For example, the switch can be made when blending is enabled or disabled, but it should not be made when a change is made to the blending parameters.

Because floating-point values may be represented using different formats in different renderers (hardware and software), many OpenGL state values may change subtly when renderers are swapped. This is the type of state value change that invariance rule 1 seeks to avoid.

## Appendix B

# Corollaries

The following observations are derived from the body and the other appendixes of the specification. Absence of an observation from this list in no way impugns its veracity.

1. The error semantics of upward compatible OpenGL revisions may change, and features deprecated in a previous revision may be removed. Otherwise, only additions can be made to upward compatible revisions.
2. GL query commands are not required to satisfy the semantics of the **Flush** or the **Finish** commands. All that is required is that the queried state be consistent with complete execution of all previously executed GL commands.
3. Application specified point size and line width must be returned as specified when queried. Implementation-dependent clamping affects the values only while they are in use.
4. The mask specified as the third argument to **StencilFunc** affects the operands of the stencil comparison function, but has no direct effect on the update of the stencil buffer. The mask specified by **StencilMask** has no effect on the stencil comparison function; it limits the effect of the update of the stencil buffer.
5. There is no atomicity requirement for OpenGL rendering commands, even at the fragment level.
6. Because rasterization of non-antialiased polygons is point sampled, polygons that have no area generate no fragments when they are rasterized in `FILL` mode, and the fragments generated by the rasterization of “narrow” polygons may not form a continuous array.

7. OpenGL does not force left- or right-handedness on any of its coordinates systems.
8. (No pixel dropouts or duplicates.) Let two polygons share an identical edge. That is, there exist vertices A and B of an edge of one polygon, and vertices C and D of an edge of the other polygon; the positions of vertex A and C are identical; and the positions of vertex B and D are identical. Vertex positions are identical if the `gl_Position` values output by the vertex (or if active, geometry) shader are identical. Then, when the fragments produced by rasterization of both polygons are taken together, each fragment intersecting the interior of the shared edge is produced exactly once.
9. Dithering algorithms may be different for different components. In particular, alpha may be dithered differently from red, green, or blue, and an implementation may choose to not dither alpha at all.



## Appendix C

# Compressed Texture Image Formats

### C.1 RGTC Compressed Texture Image Formats

Compressed texture images stored using the RGTC compressed image encodings are represented as a collection of  $4 \times 4$  texel blocks, where each block contains 64 or 128 bits of texel data. The image is encoded as a normal 2D raster image in which each  $4 \times 4$  block is treated as a single pixel. If an RGTC image has a width or height that is not a multiple of four, the data corresponding to texels outside the image are irrelevant and undefined.

When an RGTC image with a width of  $w$ , height of  $h$ , and block size of *blocksize* (8 or 16 bytes) is decoded, the corresponding image size (in bytes) is:

$$\left\lceil \frac{w}{4} \right\rceil \times \left\lceil \frac{h}{4} \right\rceil \times \textit{blocksize}.$$

When decoding an RGTC image, the block containing the texel at offset  $(x, y)$  begins at an offset (in bytes) relative to the base of the image of:

$$\textit{blocksize} \times \left( \left\lceil \frac{w}{4} \right\rceil \times \left\lfloor \frac{y}{4} \right\rfloor + \left\lfloor \frac{x}{4} \right\rfloor \right).$$

The data corresponding to a specific texel  $(x, y)$  are extracted from a  $4 \times 4$  texel block using a relative  $(x, y)$  value of

$$(x \bmod 4, y \bmod 4).$$

There are four distinct RGTC image formats:

**C.1.1 Format** COMPRESSED\_RED\_RGTC1

Each  $4 \times 4$  block of texels consists of 64 bits of unsigned red image data.

Each red image data block is encoded as a sequence of 8 bytes, called (in order of increasing address):

$$red_0, red_1, bits_0, bits_1, bits_2, bits_3, bits_4, bits_5$$

The 6  $bits_*$  bytes of the block are decoded into a 48-bit bit vector:

$$bits = bits_0 + 256 \times (bits_1 + 256 \times (bits_2 + 256 \times (bits_3 + 256 \times (bits_4 + 256 \times bits_5))))$$

$red_0$  and  $red_1$  are 8-bit unsigned integers that are unpacked to red values  $RED_0$  and  $RED_1$

$bits$  is a 48-bit unsigned integer, from which a three-bit control code is extracted for a texel at location  $(x, y)$  in the block using:

$$code(x, y) = bits [3 \times (4 \times y + x) + 2 \dots 3 \times (4 \times y + x) + 0]$$

where bit 47 is the most significant and bit 0 is the least significant bit.

The red value  $R$  for a texel at location  $(x, y)$  in the block is given by:

$$R = \begin{cases} RED_0, & red_0 > red_1, code(x, y) = 0 \\ RED_1, & red_0 > red_1, code(x, y) = 1 \\ \frac{6RED_0 + RED_1}{7}, & red_0 > red_1, code(x, y) = 2 \\ \frac{5RED_0 + 2RED_1}{7}, & red_0 > red_1, code(x, y) = 3 \\ \frac{4RED_0 + 3RED_1}{7}, & red_0 > red_1, code(x, y) = 4 \\ \frac{3RED_0 + 4RED_1}{7}, & red_0 > red_1, code(x, y) = 5 \\ \frac{2RED_0 + 5RED_1}{7}, & red_0 > red_1, code(x, y) = 6 \\ \frac{RED_0 + 6RED_1}{7}, & red_0 > red_1, code(x, y) = 7 \\ RED_0, & red_0 \leq red_1, code(x, y) = 0 \\ RED_1, & red_0 \leq red_1, code(x, y) = 1 \\ \frac{4RED_0 + RED_1}{5}, & red_0 \leq red_1, code(x, y) = 2 \\ \frac{3RED_0 + 2RED_1}{5}, & red_0 \leq red_1, code(x, y) = 3 \\ \frac{2RED_0 + 3RED_1}{5}, & red_0 \leq red_1, code(x, y) = 4 \\ \frac{RED_0 + 4RED_1}{5}, & red_0 \leq red_1, code(x, y) = 5 \\ RED_{min}, & red_0 \leq red_1, code(x, y) = 6 \\ RED_{max}, & red_0 \leq red_1, code(x, y) = 7 \end{cases}$$

$RED_{min}$  and  $RED_{max}$  are 0.0 and 1.0 respectively.

Since the decoded texel has a red format, the resulting RGBA value for the texel is  $(R, 0, 0, 1)$ .

### C.1.2 Format COMPRESSED\_SIGNED\_RED\_RGTC1

Each  $4 \times 4$  block of texels consists of 64 bits of signed red image data. The red values of a texel are extracted in the same way as COMPRESSED\_RED\_RGTC1 except  $red_0$ ,  $red_1$ ,  $RED_0$ ,  $RED_1$ ,  $RED_{min}$ , and  $RED_{max}$  are signed values defined as follows:

$red_0$  and  $red_1$  are 8-bit signed (twos complement) integers.

$$RED_0 = \begin{cases} \frac{red_0}{127.0}, & red_0 > -128 \\ -1.0, & red_0 = -128 \end{cases}$$

$$RED_1 = \begin{cases} \frac{red_1}{127.0}, & red_1 > -128 \\ -1.0, & red_1 = -128 \end{cases}$$

$$RED_{min} = -1.0$$

$$RED_{max} = 1.0$$

CAVEAT for signed  $red_0$  and  $red_1$  values: the expressions  $red_0 > red_1$  and  $red_0 \leq red_1$  above are considered undefined (read: may vary by implementation) when  $red_0 = -127$  and  $red_1 = -128$ . This is because if  $red_0$  were remapped to  $-127$  prior to the comparison to reduce the latency of a hardware decompressor, the expressions would reverse their logic. Encoders for the signed red-green formats should avoid encoding blocks where  $red_0 = -127$  and  $red_1 = -128$ .

### C.1.3 Format COMPRESSED\_RG\_RGTC2

Each  $4 \times 4$  block of texels consists of 64 bits of compressed unsigned red image data followed by 64 bits of compressed unsigned green image data.

The first 64 bits of compressed red are decoded exactly like COMPRESSED\_RED\_RGTC1 above.

The second 64 bits of compressed green are decoded exactly like COMPRESSED\_RED\_RGTC1 above except the decoded value  $R$  for this second block is considered the resulting green value  $G$ .

Since the decoded texel has a red-green format, the resulting RGBA value for the texel is  $(R, G, 0, 1)$ .

**C.1.4 Format** COMPRESSED\_SIGNED\_RG\_RGTC2

Each  $4 \times 4$  block of texels consists of 64 bits of compressed signed red image data followed by 64 bits of compressed signed green image data.

The first 64 bits of compressed red are decoded exactly like COMPRESSED\_SIGNED\_RED\_RGTC1 above.

The second 64 bits of compressed green are decoded exactly like COMPRESSED\_SIGNED\_RED\_RGTC1 above except the decoded value  $R$  for this second block is considered the resulting green value  $G$ .

Since this image has a red-green format, the resulting RGBA value is  $(R, G, 0, 1)$ .

**C.2 BPTC Compressed Texture Image Formats**

Compressed texture images stored using the BPTC compressed image formats are represented as a collection of  $4 \times 4$  texel blocks, where each block contains 128 bits of texel data. The image is encoded as a normal 2D raster image in which each  $4 \times 4$  block is treated as a single pixel. If a BPTC image has a width or height that is not a multiple of four, the data corresponding to texels outside the image are irrelevant and undefined.

When a BPTC image with a width of  $w$ , height of  $h$ , and block size of *blocksize* (16 bytes) is decoded, the corresponding image size (in bytes) is:

$$\left\lceil \frac{w}{4} \right\rceil \times \left\lceil \frac{h}{4} \right\rceil \times \text{blocksize}.$$

When decoding a BPTC image, the block containing the texel at offset  $(x, y)$  begins at an offset (in bytes) relative to the base of the image of:

$$\text{blocksize} \times \left( \left\lceil \frac{w}{4} \right\rceil \times \left\lfloor \frac{y}{4} \right\rfloor + \left\lfloor \frac{x}{4} \right\rfloor \right).$$

The data corresponding to a specific texel  $(x, y)$  are extracted from a  $4 \times 4$  texel block using a relative  $(x, y)$  value of

$$(x \bmod 4, y \bmod 4).$$

There are two distinct BPTC image formats each of which has two variants. COMPRESSED\_RGBA\_BPTC\_UNORM and COMPRESSED\_SRGB\_ALPHA\_BPTC\_UNORM compress 8-bit fixed-point data. COMPRESSED\_RGB\_BPTC\_SIGNED\_FLOAT and COMPRESSED\_RGB\_BPTC\_UNSIGNED\_FLOAT compress

high dynamic range floating-point values. The formats are similar, so the description of the float format will reference significant sections of the UNORM description.

### C.2.1 Formats COMPRESSED\_RGBA\_BPTC\_UNORM and COMPRESSED\_SRGB\_ALPHA\_BPTC\_UNORM

Each  $4 \times 4$  block of texels consists of 128 bits of RGBA or SRGB\_ALPHA image data.

Each block contains enough information to select and decode a pair of colors called endpoints, interpolate between those endpoints in a variety of ways, then remap the result into the final output.

Each block can contain data in one of eight modes. The mode is identified by the lowest bits of the lowest byte. It is encoded as zero or more zeros followed by a one. For example, using *x* to indicate a bit not included in the mode number, mode 0 is encoded as xxxxxxx1 in the low byte in binary, mode 5 is xx100000, and mode 7 is 10000000. Encoding the low byte as zero is reserved and should not be used when encoding a BPTC texture.

All further decoding is driven by the values derived from the mode listed in table C.1. The fields in the block are always in the same order for all modes. Starting at the lowest bit after the mode and going up, these fields are: partition number, rotation, index selection, color, alpha, per-endpoint P-bit, shared P-bit, primary indices, and secondary indices. The number of bits to be read in each field is determined directly from the table.

Each block can be divided into between 1 and 3 groups of pixels with independent compression parameters called subsets. A texel in a block with one subset is always considered to be in subset zero. Otherwise, a number determined by the number of partition bits is used to look up in the partition tables C.2 or C.3 for 2 and 3 subsets respectively. This partitioning is indexed by the X and Y within the block to generate the subset index.

Each block has two colors for each subset, stored first by endpoint, then by subset, then by color. For example, a format with two subsets and five color bits would have five bits of red for endpoint 0 of the first subset, then five bits of red for endpoint 1, then the two ends of the second subset, then green and blue stored similarly. If a block has non-zero alpha bits, the alpha data follows the color data with the same organization. If not, alpha is overridden to 1.0. These bits are treated as the high bits of a fixed-point value in a byte. If the format has a shared P-bit, there are two bits for endpoints 0 and 1 from low to high. If the format has a per-endpoint P-bits, then there are  $2 * \text{subsets}$  P-bits stored in the same order as color and alpha. Both kinds of P-bits are added as a bit below the color data stored in the

byte. So, for a format with 5 red bits, the P-bit ends up in bit 2. For final scaling, the top bits of the value are replicated into any remaining bits in the byte. For the preceding example, bits 6 and 7 would be written to bits 0 and 1.

The endpoint colors are interpolated using index values stored in the block. The index bits are stored in x-major order. Each index has the number of bits indicated by the mode except for one special index per subset called the anchor index. Since the ordering of the endpoints is unimportant, we can save one bit on one index per subset by ordering the endpoints such that the highest bit is guaranteed to be zero. In partition zero, the anchor index is always index zero. In other partitions, the anchor index is specified by tables C.4, C.5, and C.6. If secondary index bits are present, they are read in the same manner. The anchor index information is only used to determine the number of bits each index has when it's read from the block data.

The endpoint color and alpha values used for final interpolation are the decoded values corresponding to the applicable subset as selected above. The index value for interpolating color comes from the secondary index for the texel if the format has an index selection bit and its value is one and from the primary index otherwise. The alpha index comes from the secondary index if the block has a secondary index and the block either doesn't have an index selection bit or that bit is zero and the primary index otherwise.

Interpolation is always performed using a 6-bit interpolation factor. The effective interpolation factors for 2, 3, and 4 bit indices are given below:

**2** 0, 21, 43, 64

**3** 0, 9, 18, 27, 37, 46, 55, 64

**4** 0, 4, 9, 13, 17, 21, 26, 30, 34, 38, 43, 47, 51, 55, 60, 64

The interpolation results in an RGBA color. If rotation bits are present, this color is remapped according to:

**0** no change

**1** swap(a,r)

**2** swap(a,g)

**3** swap(a,b)

These 8-bit values show up in the shader interpreted as either `RGBA8` or `SRGB8_ALPHA8` for `COMPRESSED_RGBA_BPTC_UNORM` and `COMPRESSED_SRGB_ALPHA_BPTC_UNORM` respectively.

Mode	NS	PB	RB	ISB	CB	AB	EPB	SPB	IB	IB2
0	3	4	0	0	4	0	1	0	3	0
1	2	6	0	0	6	0	0	1	3	0
2	3	6	0	0	5	0	0	0	2	0
3	2	6	0	0	7	0	1	0	2	0
4	1	0	2	1	5	6	0	0	2	3
5	1	0	2	0	7	8	0	0	2	2
6	1	0	0	0	7	7	1	0	4	0
7	2	6	0	0	5	5	1	0	2	0

Table C.1: Mode-dependent BPTC parameters. The full descriptions of each column are as follows:

Mode: As described previously

NS: Number of subsets in each partition

PB: Partition bits

RB: Rotation bits

ISB: Index selection bits

CB: Color bits

AB: Alpha bits

EPB: Endpoint P-bits

SPB: Shared P-bits

IB: Index bits per element

IB2: Secondary index bits per element

0	0	1	1	0	0	1	1	0	0	1	1	0	0	1	1
0	0	0	1	0	0	0	1	0	0	0	1	0	0	0	1
0	1	1	1	0	1	1	1	0	1	1	1	0	1	1	1
0	0	0	1	0	0	1	1	0	0	1	1	0	1	1	1
0	0	0	0	0	0	0	1	0	0	0	1	0	0	1	1
0	0	1	1	0	1	1	1	0	1	1	1	1	1	1	1
0	0	0	1	0	0	1	1	0	1	1	1	1	1	1	1
0	0	0	0	0	0	0	1	0	0	1	1	0	1	1	1
0	0	0	0	0	0	0	0	0	0	0	1	0	0	1	1
0	0	1	1	0	1	1	1	1	1	1	1	1	1	1	1
0	0	0	0	0	0	0	1	0	1	1	1	1	1	1	1
0	0	0	0	0	0	0	0	0	0	0	1	0	1	1	1
0	0	0	1	0	1	1	1	1	1	1	1	1	1	1	1
0	0	0	0	0	0	0	0	1	1	1	1	1	1	1	1
0	0	0	0	0	0	0	0	0	0	0	1	0	1	1	1
0	0	0	0	1	0	0	0	1	1	1	0	1	1	1	1
0	1	1	1	0	0	0	1	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	1	0	0	0	1	1	1	0
0	1	1	1	0	0	1	1	0	0	1	1	0	0	0	1
0	0	1	1	0	0	0	1	0	0	0	1	0	0	0	0
0	0	0	0	1	0	0	0	1	1	0	0	1	1	1	0
0	0	0	0	0	0	0	0	1	0	0	0	1	1	0	0
0	1	1	1	0	0	1	1	0	0	1	1	0	0	0	1
0	0	1	1	0	0	0	1	0	0	0	1	0	0	0	0
0	0	0	0	1	1	1	1	0	0	0	0	1	1	1	1
0	1	0	1	1	0	1	0	0	1	0	1	1	0	1	0
0	0	1	1	0	0	1	1	1	1	0	0	1	1	0	0
0	0	0	0	1	1	1	1	1	1	1	1	1	1	1	1
0	1	1	1	0	0	1	1	0	0	0	1	1	1	1	0
0	0	1	1	1	0	0	1	1	0	0	1	1	1	0	0
0	1	0	1	0	1	0	1	0	1	0	1	0	1	0	1
0	0	0	0	1	1	1	1	0	0	0	0	1	1	1	1
0	1	0	1	0	1	0	1	0	1	0	0	1	0	0	1
0	1	0	1	1	0	1	0	1	0	1	0	0	1	0	1
0	1	1	1	0	0	1	1	1	1	0	0	1	1	1	0
0	0	0	1	0	0	1	1	1	1	0	0	1	0	0	0
0	0	0	1	1	0	0	1	0	0	1	0	0	1	1	0
0	0	1	1	1	0	1	1	1	1	0	1	1	1	0	0
0	1	1	0	1	0	0	1	1	0	0	1	0	1	1	0
0	0	1	1	1	1	0	0	1	1	0	0	0	0	1	1
0	1	1	0	0	1	1	1	0	0	1	1	0	0	1	1
0	0	0	1	1	0	0	1	0	0	1	1	0	0	1	1
0	0	0	0	1	1	1	1	0	0	1	1	0	0	1	1
0	0	1	1	0	0	1	1	1	1	1	1	0	0	0	0
0	0	1	0	0	0	1	0	1	1	1	0	1	1	1	0
0	1	0	0	0	1	0	0	0	1	1	1	0	1	1	1
0	1	0	0	0	1	0	0	0	1	1	1	0	1	1	1

Table C.2: Partition table for 2 subset. Each row is one  $4 \times 4$  block.



0	0	1	1	0	0	1	1	0	2	2	1	2	2	2	2
0	0	0	1	0	0	1	1	2	2	1	1	2	2	2	1
0	0	0	0	2	0	0	1	2	2	1	1	2	2	1	1
0	2	2	2	0	0	2	2	0	0	1	1	0	1	1	1
0	0	0	0	0	0	0	0	1	1	2	2	1	1	2	2
0	0	1	1	0	0	1	1	0	0	2	2	0	0	2	2
0	0	2	2	0	0	2	2	1	1	1	1	1	1	1	1
0	0	1	1	0	0	1	1	2	2	1	1	2	2	1	1
0	0	0	0	0	0	0	0	1	1	1	1	2	2	2	2
0	0	0	0	1	1	1	1	1	1	1	1	2	2	2	2
0	0	0	0	1	1	1	1	2	2	2	2	2	2	2	2
0	0	1	2	0	0	1	2	0	0	1	2	0	0	1	2
0	1	1	2	0	1	1	2	0	1	1	2	0	1	1	2
0	1	2	2	0	1	2	2	0	1	2	2	0	1	2	2
0	0	1	1	0	1	1	2	1	1	2	2	1	2	2	2
0	0	1	1	2	0	0	1	2	2	0	0	2	2	2	0
0	0	0	1	0	0	1	1	0	1	1	2	1	1	2	2
0	1	1	1	0	0	1	1	2	0	0	1	2	2	0	0
0	0	0	0	1	1	2	2	1	1	2	2	1	1	2	2
0	0	2	2	0	0	2	2	0	0	2	2	1	1	1	1
0	1	1	1	0	1	1	1	0	2	2	2	2	0	2	2
0	0	0	1	0	0	0	1	2	2	2	1	2	2	2	1
0	0	0	0	0	0	1	1	0	1	2	2	0	1	2	2
0	0	0	0	1	1	0	0	2	2	1	0	2	2	1	0
0	1	2	2	0	1	2	2	0	0	1	1	0	0	0	0
0	0	1	2	0	0	1	2	1	1	2	2	2	2	2	2
0	1	1	0	1	2	2	1	1	2	2	1	0	1	1	0
0	0	0	0	0	1	1	0	1	2	2	1	1	2	2	1
0	0	2	2	1	1	0	2	1	1	0	2	0	0	2	2
0	1	1	0	0	1	1	0	2	0	0	2	2	2	2	2
0	0	1	1	0	1	2	2	0	1	2	2	0	0	1	1
0	0	0	0	2	0	0	0	2	2	1	1	2	2	2	1
0	0	0	0	0	0	0	2	1	1	2	2	1	2	2	2
0	2	2	2	0	0	2	2	0	0	1	2	0	0	1	1
0	0	1	1	0	0	1	2	0	0	2	2	0	2	2	2
0	1	2	0	0	1	2	0	0	1	2	0	0	1	2	0
0	0	0	0	1	1	1	1	2	2	2	2	0	0	0	0
0	1	2	0	1	2	0	1	2	0	1	2	0	1	2	0
0	1	2	0	2	0	1	2	1	2	0	1	0	1	2	0
0	0	1	1	2	2	0	0	1	1	2	2	0	0	1	1
0	0	1	1	1	1	2	2	2	2	0	0	0	0	1	1
0	1	0	1	0	1	0	1	2	2	2	2	2	2	2	2
0	0	0	0	0	0	0	0	2	1	2	1	2	1	2	1
0	0	2	2	1	1	2	2	0	0	2	2	1	1	2	2
0	0	2	2	0	0	1	1	0	0	2	2	0	0	1	1
0	2	2	0	1	2	2	1	0	2	2	0	1	2	2	1
0	1	0	1	2	2	2	2	2	2	2	2	0	1	0	1
0	0	0	0	2	1	2	1	2	1	2	1	2	1	2	1
0	1	0	1	0	1	0	1	0	1	0	1	2	2	2	2
0	2	2	2	0	1	1	1	0	2	2	2	0	1	1	1
0	0	0	2	1	1	1	2	0	0	0	2	1	1	1	2
0	0	0	0	2	1	1	2	2	1	1	2	2	1	1	2
0	2	2	2	0	1	1	1	0	1	1	1	0	2	2	2
0	0	0	2	1	1	1	2	1	1	1	2	0	0	0	2
0	1	1	0	0	1	1	0	0	1	1	0	2	2	2	2
0	0	0	0	0	0	0	0	2	1	1	2	2	1	1	2
0	0	0	2	0	0	0	1	0	0	0	2	0	0	0	1
0	2	2	2	1	2	2	2	0	2	2	2	1	2	2	2
0	1	0	1	2	2	2	2	2	2	2	2	2	2	2	2
0	1	1	1	1	2	0	1	1	2	0	1	2	2	2	0

Table C.3: Partition table for 3 subset. Each row is one  $4 \times 4$  block.

15	15	15	15	15	15	15	15
15	15	15	15	15	15	15	15
15	2	8	2	2	8	8	15
2	8	2	2	8	8	2	2
15	15	6	8	2	8	15	15
2	8	2	2	2	15	15	6
6	2	6	8	15	15	2	2
15	15	15	15	15	2	2	15

Table C.4: Anchor index values for the second subset of two-subset partitioning. Values run right, then down.

3	3	15	15	8	3	15	15
8	8	6	6	6	5	3	3
3	3	8	15	3	3	6	10
5	8	8	6	8	5	15	15
8	15	3	5	6	10	8	15
15	3	15	5	15	15	15	15
3	15	5	5	5	8	5	10
5	10	8	13	15	12	3	3

Table C.5: Anchor index values for the second subset of three-subset partitioning. Values run right, then down.

15	8	8	3	15	15	3	8
15	15	15	15	15	15	15	8
15	8	15	3	15	8	15	8
3	15	6	10	15	15	10	8
15	3	15	10	10	8	9	10
6	15	8	15	3	6	6	8
15	3	15	15	15	15	15	15
15	15	15	15	3	15	15	8

Table C.6: Anchor index values for the third subset of three-subset partitioning. Values run right, then down.

### C.2.2 Formats `COMPRESSED_RGB_BPTC_SIGNED_FLOAT` and `COMPRESSED_RGB_BPTC_UNSIGNED_FLOAT`

Each  $4 \times 4$  block of texels consists of 128 bits of RGB data. These formats are very similar and will be described together. In the description and pseudocode below, *signed* will be used as a condition which is true for the `SIGNED` format and false for the `UNSIGNED` format. Both formats only contain RGB data, so the returned alpha value is 1.0. If a block uses a reserved or invalid encoding, the return value is (0, 0, 0, 1).

Each block can contain data in one of 14 modes. The mode number is encoded in either the low two bits or the low five bits. If the low two bits are less than two, that is the mode number, otherwise the low five bits the mode number. Mode numbers not listed in table C.7 are reserved (19, 23, 27, and 31).

The data for the compressed blocks is stored in a different format for each mode. The formats are specified in table C.8. The format strings are intended to be read from left to right with the LSB on the left. Each element is of the form  $v[a : b]$ . If  $a \geq b$ , this indicates extracting  $b - a + 1$  bits from the block at that location and put them in the corresponding bits of the variable  $v$ . If  $a < b$ , then the bits are reversed.  $v[a]$  is used as a shorthand for the one bit  $v[a : a]$ . As an example,  $m[1 : 0]$ ,  $g2[4]$  would move the low two bits from the block into the low two bits of  $m$  then the next bit of the block into bit 4 of  $g2$ . The variable names given in the table will be referred to in the language below.

Subsets and indices work in much the same way as described for the fixed-point formats above. If a float block has no partition bits, then it is a single-subset block. If it has partition bits, then it is a 2 subset block. The partition index references the first half of table C.2. Indices are read in the same way as the fixed-point formats including obeying the anchor values for index 0 and as needed by table C.4.

In a single-subset blocks, the two endpoints are contained in  $r_0, g_0, b_0$  (hence  $e_0$ ) and  $r_1, g_1, b_1$  (hence  $e_1$ ). In a two-subset block, the endpoints for the second subset are in  $r_2, g_2, b_2$  and  $r_3, g_3, b_3$ . The value in  $e_0$  is sign-extended if the format of the texture is signed. The values in  $e_1$  (and  $e_2$  and  $e_3$  if the block is two-subset) are sign-extended if the format of the texture is signed or if the block mode has transformed endpoints. If the mode has transformed endpoints, the values from  $e_0$  are used as a base to offset all other endpoints, wrapped at the number of endpoint bits. For example,  $r_1 = (r_0 + r_1) \& ((1 \ll EPB) - 1)$ .

Next, the endpoints are unquantized to maximize the usage of the bits and to ensure that the negative ranges are oriented properly to interpolate as a two's complement value. The following pseudocode assumes the computation is being done using sufficiently large intermediate values to avoid overflow. For the unsigned float format, we unquantize a value  $x$  to `unq` by:

```

if (EPB >= 15)
    unq = x;
else if (x == 0)
    unq = 0;
else if (x == ((1<<EPB)-1))
    unq = 0xFFFF;
else
    unq = ((x << 15) + 0x4000) >> (EPB-1);

```

The signed float unquantization is similar, but needs to worry about orienting the negative range:

```

s = 0;
if (EPB >= 16)
    unq = x;
else {
    if (x < 0) {
        s = 1;
        x = -x;
    }

    if (x == 0)
        unq = 0;
    else if (x >= ((1<<(EPB-1))-1))
        unq = 0x7FFF;
    else
        unq = ((x << 15) + 0x4000) >> (EPB-1);

    if (s)
        unq = -unq;
}

```

After the endpoints are unquantized, interpolation proceeds as in the fixed-point formats above including the interpolation weight table.

The interpolated values are passed through a final unquantization step. For the unsigned format, this step simply multiplies by  $\frac{31}{64}$ . The signed format negates negative components, multiplies by  $\frac{31}{32}$ , then ORs in the sign bit if the original value was negative.

The resultant value should be a legal 16-bit half float which is then returned as a float to the shader.

Mode Number	Transformed Endpoints	Partition Bits (PB)	Endpoint Bits (EPB)	Delta Bits
0	1	5	10	5, 5, 5
1	1	5	7	6, 6, 6
2	1	5	11	5, 4, 4
6	1	5	11	4, 5, 4
10	1	5	11	4, 4, 5
14	1	5	9	5, 5, 5
18	1	5	8	6, 5, 5
22	1	5	8	5, 6, 5
26	1	5	8	5, 5, 6
30	0	5	6	6, 6, 6
3	0	0	10	10, 10, 10
7	1	0	11	9, 9, 9
11	1	0	12	8, 8, 8
15	1	0	16	4, 4, 4

Table C.7: Endpoint and partition parameters for block modes

### C.3 ETC Compressed Texture Image Formats

The ETC formats form a family of related compressed texture image formats. They are designed to do different tasks, but also to be similar enough that hardware can be reused between them. Each one is described in detail below, but we will first give an overview of each format and describe how it is similar to others and the main differences.

`COMPRESSED_RGB8_ETC2` is a format for compressing RGB8 data. It is a superset of the older `OES_compressed_ETC1_RGB8_texture` format. This means that an older ETC1 texture can be decoded using by a `COMPRESSED_RGB8_ETC2`-compliant decoder, using the enum-value for `COMPRESSED_RGB8_ETC2`. The main difference is that the newer version contains three new modes; the ‘T-mode’ and the ‘H-mode’ which are good for sharp chrominance blocks and the ‘Planar’ mode which is good for smooth blocks.

`COMPRESSED_SRGB8_ETC2` is the same as `COMPRESSED_RGB8_ETC2` with the difference that the values should be interpreted as sRGB-values instead of RGB-values.

`COMPRESSED_RGBA8_ETC2_EAC` encodes RGBA8 data. The RGB part is encoded exactly the same way as `COMPRESSED_RGB8_ETC2`. The alpha part is en-

Mode Number	Block Format
0	m[1:0], g2[4], b2[4], b3[4], r0[9:0], g0[9:0], b0[9:0], r1[4:0], g3[4], g2[3:0], g1[4:0], b3[0], g3[3:0], b1[4:0], b3[1], b2[3:0], r2[4:0], b3[2], r3[4:0], b3[3]
1	m[1:0], g2[5], g3[4], g3[5], r0[6:0], b3[0], b3[1], b2[4], g0[6:0], b2[5], b3[2], g2[4], b0[6:0], b3[3], b3[5], b3[4], r1[5:0], g2[3:0], g1[5:0], g3[3:0], b1[5:0], b2[3:0], r2[5:0], r3[5:0]
2	m[4:0], r0[9:0], g0[9:0], b0[9:0], r1[4:0], r0[10], g2[3:0], g1[3:0], g0[10], b3[0], g3[3:0], b1[3:0], b0[10], b3[1], b2[3:0], r2[4:0], b3[2], r3[4:0], b3[3]
6	m[4:0], r0[9:0], g0[9:0], b0[9:0], r1[3:0], r0[10], g3[4], g2[3:0], g1[4:0], g0[10], g3[3:0], b1[3:0], b0[10], b3[1], b2[3:0], r2[3:0], b3[0], b3[2], r3[3:0], g2[4], b3[3]
10	m[4:0], r0[9:0], g0[9:0], b0[9:0], r1[3:0], r0[10], b2[4], g2[3:0], g1[3:0], g0[10], b3[0], g3[3:0], b1[4:0], b0[10], b2[3:0], r2[3:0], b3[1], b3[2], r3[3:0], b3[4], b3[3]
14	m[4:0], r0[8:0], b2[4], g0[8:0], g2[4], b0[8:0], b3[4], r1[4:0], g3[4], g2[3:0], g1[4:0], b3[0], g3[3:0], b1[4:0], b3[1], b2[3:0], r2[4:0], b3[2], r3[4:0], b3[3]
18	m[4:0], r0[7:0], g3[4], b2[4], g0[7:0], b3[2], g2[4], b0[7:0], b3[3], b3[4], r1[5:0], g2[3:0], g1[4:0], b3[0], g3[3:0], b1[4:0], b3[1], b2[3:0], r2[5:0], r3[5:0]
22	m[4:0], r0[7:0], b3[0], b2[4], g0[7:0], g2[5], g2[4], b0[7:0], g3[5], b3[4], r1[4:0], g3[4], g2[3:0], g1[5:0], g3[3:0], b1[4:0], b3[1], b2[3:0], r2[4:0], b3[2], r3[4:0], b3[3]
26	m[4:0], r0[7:0], b3[1], b2[4], g0[7:0], b2[5], g2[4], b0[7:0], b3[5], b3[4], r1[4:0], g3[4], g2[3:0], g1[4:0], b3[0], g3[3:0], b1[5:0], b2[3:0], r2[4:0], b3[2], r3[4:0], b3[3]
30	m[4:0], r0[5:0], g3[4], b3[0], b3[1], b2[4], g0[5:0], g2[5], b2[5], b3[2], g2[4], b0[5:0], g3[5], b3[3], b3[5], b3[4], r1[5:0], g2[3:0], g1[5:0], g3[3:0], b1[5:0], b2[3:0], r2[5:0], r3[5:0]
3	m[4:0], r0[9:0], g0[9:0], b0[9:0], r1[9:0], g1[9:0], b1[9:0]
7	m[4:0], r0[9:0], g0[9:0], b0[9:0], r1[8:0], r0[10], g1[8:0], g0[10], b1[8:0], b0[10]
11	m[4:0], r0[9:0], g0[9:0], b0[9:0], r1[7:0], r0[10:11], g1[7:0], g0[10:11], b1[7:0], b0[10:11]
15	m[4:0], r0[9:0], g0[9:0], b0[9:0], r1[3:0], r0[10:15], g1[3:0], g0[10:15], b1[3:0], b0[10:15]

OpenGL 4.3 (Core Profile) - February 14, 2013

Table C.8: Block formats for block modes

coded separately.

COMPRESSED\_SRGB8\_ALPHA8\_ETC2\_EAC is the same as COMPRESSED\_RGBA8\_ETC2\_EAC but here the RGB-values (but not the alpha value) should be interpreted as sRGB-values.

COMPRESSED\_R11\_EAC is a one-channel unsigned format. It is similar to the alpha part of COMPRESSED\_SRGB8\_ALPHA8\_ETC2\_EAC but not exactly the same; it delivers higher precision. It is possible to make hardware that can decode both formats with minimal overhead.

COMPRESSED\_RG11\_EAC is a two-channel unsigned format. Each channel is decoded exactly as COMPRESSED\_R11\_EAC.

COMPRESSED\_SIGNED\_R11\_EAC is a one-channel signed format. This is good in situations when it is important to be able to preserve zero exactly, and still use both positive and negative values. It is designed to be similar enough to COMPRESSED\_R11\_EAC so that hardware can decode both with minimal overhead, but it is not exactly the same. For example; the signed version does not add 0.5 to the base codeword, and the extension from 11 bits differ. For all details, see the corresponding sections.

COMPRESSED\_SIGNED\_RG11\_EAC is a two-channel signed format. Each channel is decoded exactly as COMPRESSED\_SIGNED\_R11\_EAC.

COMPRESSED\_RGB8\_PUNCHTHROUGH\_ALPHA1\_ETC2 is very similar to COMPRESSED\_RGBA8\_ETC2, but has the ability to represent “punchthrough”-alpha (completely opaque or transparent). Each block can select to be completely opaque using one bit. To fit this bit, there is no individual mode in COMPRESSED\_RGB8\_PUNCHTHROUGH\_ALPHA1\_ETC2. In other respects, the opaque blocks are decoded as in COMPRESSED\_RGBA8\_ETC2. For the transparent blocks, one index is reserved to represent transparency, and the decoding of the RGB channels are also affected. For details, see the corresponding sections.

COMPRESSED\_SRGB8\_PUNCHTHROUGH\_ALPHA1\_ETC2 is the same as COMPRESSED\_RGBA8\_PUNCHTHROUGH\_ALPHA1\_ETC2 but should be interpreted as sRGB.

A texture compressed using any of the ETC texture image formats is described as a number of  $4 \times 4$  pixel blocks.

Pixel  $a_1$  (see table C.9) of the first block in memory will represent the texture coordinate ( $u = 0, v = 0$ ). Pixel  $a_2$  in the second block in memory will be adjacent to pixel  $m_1$  in the first block, etc. until the width of the texture. Then pixel  $a_3$  in the following block (third block in memory for a  $8 \times 8$  texture) will be adjacent to pixel  $d_1$  in the first block, etc. until the height of the texture. Calling **CompressedTexImage2D** to get an  $8 \times 8$  texture using the first, second, third and fourth block shown in table C.9 would have the same effect as calling **TexImage2D** where the bytes describing the pixels would come in the following memory order:

$a_1 e_1 i_1 m_1 a_2 e_2 i_2 m_2 b_1 f_1 j_1 n_1 b_2 f_2 j_2 n_2 c_1 g_1 k_1 o_1 c_2 g_2 k_2 o_2 d_1 h_1 l_1 p_1$   
 $d_2 h_2 l_2 p_2 a_3 e_3 i_3 m_3 a_4 e_4 i_4 m_4 b_3 f_3 j_3 n_3 b_4 f_4 j_4 n_4 c_3 g_3 k_3 o_3 c_4 g_4 k_4 o_4$   
 $d_3 h_3 l_3 p_3 d_4 h_4 l_4 p_4.$

If the width or height of the texture (or a particular mip-level) is not a multiple of

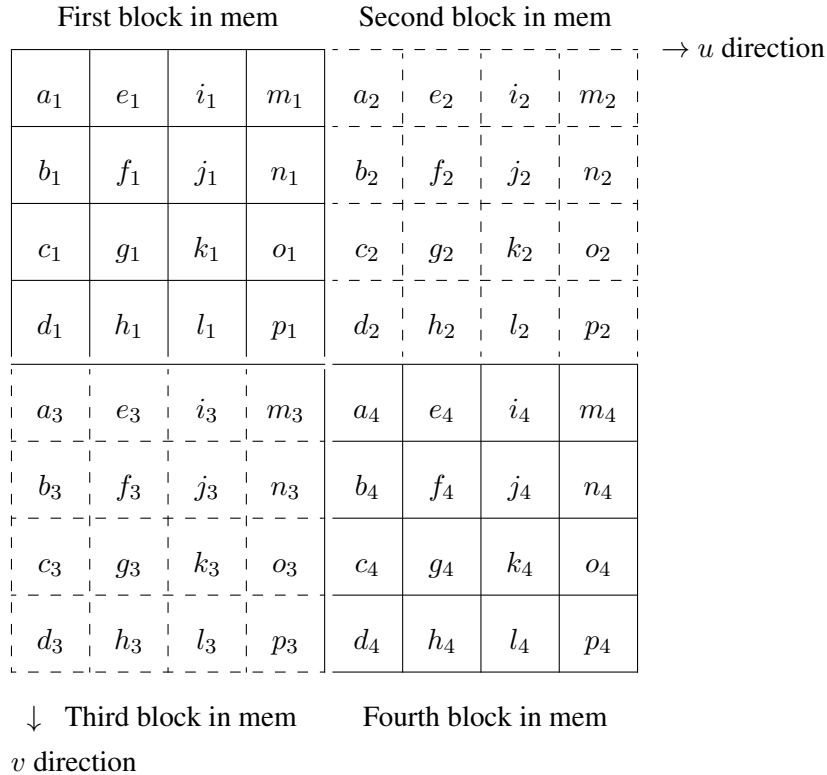


Table C.9: Pixel layout for a  $8 \times 8$  texture using four COMPRESSED\_RGB8\_ETC2 compressed blocks. Note how pixel  $a_3$  in the third block is adjacent to pixel  $d_1$  in the first block.

four, then padding is added to ensure that the texture contains a whole number of  $4 \times 4$  blocks in each dimension. The padding does not affect the texel coordinates. For example, the texel shown as  $a_1$  in table C.9 always has coordinates  $i = 0, j = 0$ . The values of padding texels are irrelevant, e.g., in a  $3 \times 3$  texture, the texels marked as  $m_1, n_1, o_1, d_1, h_1, l_1$  and  $p_1$  form padding and have no effect on the final texture image.

It is possible to update part of a compressed texture using **CompressedTexSubImage2D**: Since ETC images are easily edited along  $4 \times 4$  texel boundaries,



the limitations on **CompressedTexSubImage2D** are relaxed. **CompressedTexSubImage2D** will result in an `INVALID_OPERATION` error only if one of the following conditions occurs:

- *width* is not a multiple of four, and *width* plus *xoffset* is not equal to the texture width;
- *height* is not a multiple of four, and *height* plus *yoffset* is not equal to the texture height; or
- *xoffset* or *yoffset* is not a multiple of four.

The number of bits that represent a  $4 \times 4$  texel block is 64 bits if *internalformat* is given by `COMPRESSED_RGB8_ETC2`, `COMPRESSED_SRGB8_ETC2`, `COMPRESSED_RGB8_PUNCHTHROUGH_ALPHA1_ETC2` or `COMPRESSED_SRGB8_PUNCHTHROUGH_ALPHA1_ETC2`.

In those cases the data for a block is stored as a number of bytes,  $\{q_0, q_1, q_2, q_3, q_4, q_5, q_6, q_7\}$ , where byte  $q_0$  is located at the lowest memory address and  $q_7$  at the highest. The 64 bits specifying the block are then represented by the following 64 bit integer:

$$\text{int64bit} = 256 \times (256 \times (256 \times (256 \times (256 \times (256 \times (256 \times q_0 + q_1) + q_2) + q_3) + q_4) + q_5) + q_6) + q_7$$

The number of bits that represent a  $4 \times 4$  texel block is 128 bits if *internalformat* is given by `COMPRESSED_RGBA8_ETC2_EAC` or `COMPRESSED_SRGB8_ALPHA8_ETC2_EAC`. In those cases the data for a block is stored as a number of bytes:  $\{q_0, q_1, q_2, q_3, q_4, q_5, q_6, q_7, q_8, q_9, q_{10}, q_{11}, q_{12}, q_{13}, q_{14}, q_{15}\}$ , where byte  $q_0$  is located at the lowest memory address and  $q_{15}$  at the highest. This is split into two 64-bit integers, one used for color channel decompression and one for alpha channel decompression:

$$\begin{aligned} \text{int64bitAlpha} = \\ 256 \times (256 \times (256 \times (256 \times (256 \times (256 \times q_0 + q_1) + q_2) + q_3) + q_4) + q_5) + q_6) + q_7 \end{aligned}$$

$$\begin{aligned} \text{int64bitColor} = \\ 256 \times (256 \times (256 \times (256 \times (256 \times (256 \times q_8 + q_9) + q_{10}) + q_{11}) + q_{12}) + q_{13}) + q_{14}) + q_{15} \end{aligned}$$

### C.3.1 Format `COMPRESSED_RGB8_ETC2`

For `COMPRESSED_RGB8_ETC2`, each 64-bit word contains information about a three-channel  $4 \times 4$  pixel block as shown in table C.10.

a	e	i	m	→ <i>u</i> direction
b	f	j	n	
c	g	k	o	
d	h	l	p	

↓  
*v* direction

Table C.10: Pixel layout for an COMPRESSED\_RGB8\_ETC2 compressed block.

The blocks are compressed using one of five different ‘modes’. Table C.11a shows the bits used for determining the mode used in a given block. First, if the bit marked ‘D’ is set to 0, the ‘individual’ mode is used. Otherwise, the three 5-bit values R, G and B, and the three 3-bit values dR, dG and dB are examined. R, G and B are treated as integers between 0 and 31 and dR, dG and dB as two’s-complement integers between  $-4$  and  $+3$ . First, R and dR are added, and if the sum is not within the interval  $[0,31]$ , the ‘T’ mode is selected. Otherwise, if the sum of G and dG is outside the interval  $[0,31]$ , the ‘H’ mode is selected. Otherwise, if the sum of B and dB is outside of the interval  $[0,31]$ , the ‘planar’ mode is selected. Finally, if the ‘D’ bit is set to 1 and all of the aforementioned sums lie between 0 and 31, the ‘differential’ mode is selected.

The layout of the bits used to decode the ‘individual’ and ‘differential’ modes are shown in table C.11b and table C.11c, respectively. Both of these modes share several characteristics. In both modes, the  $4 \times 4$  block is split into two subblocks of either size  $2 \times 4$  or  $4 \times 2$ . This is controlled by bit 32, which we dub the ‘flip bit’. If the ‘flip bit’ is 0, the block is divided into two  $2 \times 4$  subblocks side-by-side, as shown in table C.12. If the ‘flip bit’ is 1, the block is divided into two  $4 \times 2$  subblocks on top of each other, as shown in table C.13. In both modes, a ‘base color’ for each subblock is stored, but the way they are stored is different in the two modes:

In the ‘individual’ mode, following the layout shown in table C.11b, the base color for subblock 1 is derived from the codewords R1 (bit 63–60), G1 (bit 55–52) and B1 (bit 47–44). These four bit values are extended to RGB888 by replicating the four higher order bits in the four lower order bits. For instance, if  $R1 = 14 =$

a) location of bits for mode selection:

63	62	61	60	59	58	57	56	55	54	53	52	51	50	49	48	47	46	45	44	43	42	41	40	39	38	37	36	35	34	33	32
R					dR			G			dG			B			dB			-----					D	-					

b) bit layout for bits 63 through 32 for 'individual' mode:

63	62	61	60	59	58	57	56	55	54	53	52	51	50	49	48	47	46	45	44	43	42	41	40	39	38	37	36	35	34	33	32
R1				R2				G1				G2				B1				B2				table1		table2		0	FB		

c) bit layout for bits 63 through 32 for 'differential' mode:

63	62	61	60	59	58	57	56	55	54	53	52	51	50	49	48	47	46	45	44	43	42	41	40	39	38	37	36	35	34	33	32
R					dR			G			dG			B			dB			table1		table2		1	FB						

d) bit layout for bits 63 through 32 for 'T' mode:

63	62	61	60	59	58	57	56	55	54	53	52	51	50	49	48	47	46	45	44	43	42	41	40	39	38	37	36	35	34	33	32	
---			R1a			-	R1b			G1				B1				R2				G2				B2				da	1	db

e) bit layout for bits 63 through 32 for 'H' mode:

63	62	61	60	59	58	57	56	55	54	53	52	51	50	49	48	47	46	45	44	43	42	41	40	39	38	37	36	35	34	33	32									
-	R1				G1a				---				G1b				B1a				-	B1b				R2				G2				B2				da	1	db

f) bit layout for bits 31 through 0 for 'individual', 'diff', 'T' and 'H' modes:

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
p0	o0	n0	m0	l0	k0	j0	i0	h0	g0	f0	e0	d0	c0	b0	a0	p1	o1	n1	m1	l1	k1	j1	i1	h1	g1	f1	e1	d1	c1	b1	a1

g) bit layout for bits 63 through 0 for 'planar' mode:

63	62	61	60	59	58	57	56	55	54	53	52	51	50	49	48	47	46	45	44	43	42	41	40	39	38	37	36	35	34	33	32								
-	RO				GO1				-	GO2				BO1				---				BO2				-	BO3				RH1				1	RH2			
31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0								
GH								BH								RV								GV								BV							

Table C.11: Texel Data format for RGB8\_ETC2 compressed textures formats

1110 binary (1110b for short),  $G1 = 3 = 0011b$  and  $B1 = 8 = 1000b$ , then the red component of the base color of subblock 1 becomes  $11101110b = 238$ , and the green and blue components become  $00110011b = 51$  and  $10001000b = 136$ . The base color for subblock 2 is decoded the same way, but using the 4-bit codewords R2 (bit 59–56), G2 (bit 51–48) and B2 (bit 43–40) instead. In summary, the base colors for the subblocks in the individual mode are:

$$base\ col\ subblock1 = extend\_4to8bits(R1, G1, B1)$$

$$base\ col\ subblock2 = extend\_4to8bits(R2, G2, B2)$$

In the 'differential' mode, following the layout shown in table C.11c, the base color for subblock 1 is derived from the five-bit codewords R, G and B. These five-bit codewords are extended to eight bits by replicating the top three highest order bits to the three lowest order bits. For instance, if  $R = 28 = 11100b$ , the resulting eight-

subblock1		subblock2	
a	e	i	m
b	f	j	n
c	g	k	o
d	h	l	p

Table C.12: Two  $2 \times 4$ -pixel subblocks side-by-side.

a	e	i	m	subblock 1
b	f	j	n	
c	g	k	o	subblock 2
d	h	l	p	

Table C.13: Two  $4 \times 2$ -pixel subblocks on top of each other.

bit red color component becomes  $11100111b = 231$ . Likewise, if  $G = 4 = 00100b$  and  $B = 3 = 00011b$ , the green and blue components become  $00100001b = 33$  and  $00011000b = 24$  respectively. Thus, in this example, the base color for subblock 1 is  $(231, 33, 24)$ . The five-bit representation for the base color of subblock 2 is obtained by modifying the five-bit codewords  $R$ ,  $G$  and  $B$  by the codewords  $dR$ ,  $dG$  and  $dB$ . Each of  $dR$ ,  $dG$  and  $dB$  is a 3-bit two's-complement number that can hold values between  $-4$  and  $+3$ . For instance, if  $R = 28$  as above, and  $dR = 100b = -4$ , then the five bit representation for the red color component is  $28 + (-4) = 24 = 11000b$ , which is then extended to eight bits to  $11000110b = 198$ . Likewise, if  $G = 4$ ,  $dG = 2$ ,  $B = 3$  and  $dB = 0$ , the base color of subblock 2 will be  $RGB = (198, 49, 24)$ . In summary, the base colors for the subblocks in the differential mode are:

$$\begin{aligned} \text{base col subblock1} &= \text{extend\_5to8bits}(R, G, B) \\ \text{base col subblock2} &= \text{extend\_5to8bits}(R + dR, G + dG, B + dB) \end{aligned}$$

Note that these additions will not under- or overflow, or one of the alternative decompression modes would have been chosen instead of the ‘differential’ mode.

After obtaining the base color, the operations are the same for the two modes ‘individual’ and ‘differential’. First a table is chosen using the table codewords: For subblock 1, table codeword 1 is used (bits 39–37), and for subblock 2, table codeword 2 is used (bits 36–34), see table C.11b or C.11c. The table codeword is used to select one of eight modifier tables, see table C.14. For instance, if the table code word is 010 binary = 2, then the modifier table [−29, −9, 9, 29] is selected for the corresponding sub-block. Note that the values in table C.14 are valid for all textures and can therefore be hardcoded into the decompression unit. Next, we

table codeword	modifier table			
0	-8	-2	2	8
1	-17	-5	5	17
2	-29	-9	9	29
3	-42	-13	13	42
4	-60	-18	18	60
5	-80	-24	24	80
6	-106	-33	33	106
7	-183	-47	47	183

Table C.14: Intensity modifier sets for ‘individual’ and ‘differential’ modes:

identify which modifier value to use from the modifier table using the two ‘pixel index’ bits. The pixel index bits are unique for each pixel. For instance, the pixel index for pixel d (see table C.10) can be found in bits 19 (most significant bit, MSB), and 3 (least significant bit, LSB), see table C.11f. Note that the pixel index for a particular texel is always stored in the same bit position, irrespectively of bits ‘diffbit’ and ‘flipbit’. The pixel index bits are decoded using table C.15. If, for instance, the pixel index bits are 01 binary = 1, and the modifier table [−29, −9, 9, 29] is used, then the modifier value selected for that pixel is 29 (see table C.15). This modifier value is now used to additively modify the base color. For example, if we have the base color (231, 8, 16), we should add the modifier value 29 to all three components: (231 + 29, 8 + 29, 16 + 29) resulting in (260, 37, 45). These values are then clamped to [0, 255], resulting in the color (255, 37, 45), and we are finished decoding the texel.

The ‘T’ and ‘H’ compression modes also share some characteristics: both use two base colors stored using 4 bits per channel decoded as in the individual mode. Unlike the ‘individual’ mode however, these bits are not stored sequentially, but in

pixel index value		resulting modifier value
msb	lsb	
1	1	-b (large negative value)
1	0	-a (small negative value)
0	0	a (small positive value)
0	1	b (large positive value)

Table C.15: Mapping from pixel index values to modifier values for COMPRESSED\_RGB8\_ETC2 compressed textures

the layout shown in C.11d and C.11e. To clarify, in the ‘T’ mode, the two colors are constructed as follows:

$$\begin{aligned} \text{base col 1} &= \text{extend\_4to8bits}((R1a \ll 2) | R1b, G1, B1) \\ \text{base col 2} &= \text{extend\_4to8bits}(R2, G2, B2) \end{aligned}$$

where  $\ll$  denotes bit-wise left shift and  $|$  denotes bit-wise OR. In the ‘H’ mode, the two colors are constructed as follows:

$$\begin{aligned} \text{base col 1} &= \text{extend\_4to8bits}(R1, (G1a \ll 1) | G1b, (B1a \ll 3) | B1b) \\ \text{base col 2} &= \text{extend\_4to8bits}(R2, G2, B2) \end{aligned}$$

Both the ‘T’ and ‘H’ modes have four ‘paint colors’ which are the colors that will be used in the decompressed block, but they are assigned in a different manner. In the ‘T’ mode, ‘paint color 0’ is simply the first base color, and ‘paint color 2’ is the second base color. To obtain the other ‘paint colors’, a ‘distance’ is first determined, which will be used to modify the luminance of one of the base colors. This is done by combining the values ‘da’ and ‘db’ shown in table C.11d by  $(da \ll 1) | db$ , and then using this value as an index into the small look-up table shown in table C.16. For example, if ‘da’ is 10 binary and ‘db’ is 1 binary, the index is 101 binary and the selected distance will be 32. ‘Paint color 1’ is then equal to the second base color with the ‘distance’ added to each channel, and ‘paint color 3’ is the second base color with the ‘distance’ subtracted. In summary, to determine the four ‘paint colors’ for a ‘T’ block:

$$\begin{aligned} \text{paint color 0} &= \text{base col 1} \\ \text{paint color 1} &= \text{base col 2} + (d, d, d) \\ \text{paint color 2} &= \text{base col 2} \\ \text{paint color 3} &= \text{base col 2} - (d, d, d) \end{aligned}$$

In both cases, the value of each channel is clamped to within [0,255].

distance index	distance
0	3
1	6
2	11
3	16
4	23
5	32
6	41
7	64

Table C.16: Distance table for ‘T’ and ‘H’ modes.

A ‘distance’ value is computed for the ‘H’ mode as well, but doing so is slightly more complex. In order to construct the three-bit index into the distance table shown in table C.16, ‘da’ and ‘db’ shown in table C.11e are used as the most significant bit and middle bit, respectively, but the least significant bit is computed as (base col 1 value  $\geq$  base col 2 value), the ‘value’ of a color for the comparison being equal to  $(R \lll 16) + (G \lll 8) + B$ . Once the ‘distance’  $d$  has been determined for an ‘H’ block, the four ‘paint colors’ will be:

$$\begin{aligned} \text{paint color } 0 &= \text{base col } 1 + (d, d, d) \\ \text{paint color } 1 &= \text{base col } 1 - (d, d, d) \\ \text{paint color } 2 &= \text{base col } 2 + (d, d, d) \\ \text{paint color } 3 &= \text{base col } 2 - (d, d, d) \end{aligned}$$

Again, all color components are clamped to within [0,255]. Finally, in both the ‘T’ and ‘H’ modes, every pixel is assigned one of the four ‘paint colors’ in the same way the four modifier values are distributed in ‘individual’ or ‘differential’ blocks. For example, to choose a paint color for pixel  $d$ , an index is constructed using bit 19 as most significant bit and bit 3 as least significant bit. Then, if a pixel has index 2, for example, it will be assigned paint color 2.

The final mode possible in an COMPRESSED\_RGB8\_ETC2-compressed block is the ‘planar’ mode. Here, three base colors are supplied and used to form a color plane used to determine the color of the individual pixels in the block.

All three base colors are stored in RGB 676 format, and stored in the manner shown in table C.11g. The three colors are there labelled ‘O’, ‘H’ and ‘V’, so that the three components of color ‘V’ are RV, GV and BV, for example. Some color channels are split into non-consecutive bit-ranges, for example BO is reconstructed using BO1 as the most significant bit, BO2 as the two following bits, and BO3 as the three least significant bits.

Once the bits for the base colors have been extracted, they must be extended to 8 bits per channel in a manner analogous to the method used for the base colors in other modes. For example, the 6-bit blue and red channels are extended by replicating the two most significant of the six bits to the two least significant of the final 8 bits.

With three base colors in RGB888 format, the color of each pixel can then be determined as:

$$\begin{aligned} R(x, y) &= x \times (RH - RO)/4.0 + y \times (RV - RO)/4.0 + RO \\ G(x, y) &= x \times (GH - GO)/4.0 + y \times (GV - GO)/4.0 + GO \\ B(x, y) &= x \times (BH - BO)/4.0 + y \times (BV - BO)/4.0 + BO \end{aligned}$$

where  $x$  and  $y$  are values from 0 to 3 corresponding to the pixels coordinates within the block,  $x$  being in the  $u$  direction and  $y$  in the  $v$  direction. For example, the pixel  $g$  in table C.10 would have  $x = 1$  and  $y = 2$ .

These values are then rounded to the nearest integer (to the larger integer if there is a tie) and then clamped to a value between 0 and 255. Note that this is equivalent to

$$\begin{aligned} R(x, y) &= \text{clamp}_{255}((x \times (RH - RO) + y \times (RV - RO) + 4 \times RO + 2) \gg 2) \\ G(x, y) &= \text{clamp}_{255}((x \times (GH - GO) + y \times (GV - GO) + 4 \times GO + 2) \gg 2) \\ B(x, y) &= \text{clamp}_{255}((x \times (BH - BO) + y \times (BV - BO) + 4 \times BO + 2) \gg 2) \end{aligned}$$

where  $\text{clamp}_{255}$  clamps the value to a number in the range  $[0, 255]$  and where  $\gg$  performs bit-wise right shift.

This specification gives the output for each compression mode in 8-bit integer colors between 0 and 255, and these values all need to be divided by 255 for the final floating point representation.

### C.3.2 Format COMPRESSED\_SRGB8\_ETC2

Decompression of floating point sRGB values in COMPRESSED\_SRGB8\_ETC2 follows that of floating point RGB values of COMPRESSED\_RGB8\_ETC2. The result is sRGB values between 0.0 and 1.0. The further conversion from an sRGB encoded component,  $c_s$ , to a linear component,  $c_l$ , is as described in section 8.23. Assume  $c_s$  is the sRGB component in the range  $[0, 1]$ .

### C.3.3 Format COMPRESSED\_RGBA8\_ETC2\_EAC

If *internalformat* is COMPRESSED\_RGBA8\_ETC2\_EAC, each  $4 \times 4$  block of RGBA8888 information is compressed to 128 bits. To decode a block, the



two 64-bit integers `int64bitAlpha` and `int64bitColor` are calculated as described in Section C.3. The RGB component is then decoded the same way as for `COMPRESSED_RGBA8_ETC2` (see Section C.3.1), using `int64bitColor` as the `int64bit` codeword.

a) bit layout in bits 63 through 48

63	62	61	60	59	58	57	56	55	54	53	52	51	50	49	48
base_codeword								multiplier				table index			

b) bit layout in bits 47 through 0, with pixels named as in Table C.10, bits labelled from 0 being the LSB to 47 being the MSB.

47	46	45	44	43	42	41	40	39	38	37	36	35	34	33	32
a0	a1	a2	b0	b1	b2	c0	c1	c2	d0	d1	d2	e0	e1	e2	f0
31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
f1	f2	g0	g1	g2	h0	h1	h2	i0	i1	i2	j0	j1	j2	k0	k1
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
k2	l0	l1	l2	m0	m1	m2	n0	n1	n2	o0	o1	o2	p0	p1	p2

Table C.17: Texel Data format for alpha part of `COMPRESSED_RGBA8_ETC2_EAC` compressed textures.

The 64-bits in `int64bitAlpha` used to decompress the alpha channel are laid out as shown in table C.17. The information is split into two parts. The first 16 bits comprise a base codeword, a table codeword and a multiplier, which are used together to compute 8 pixel values to be used in the block. The remaining 48 bits are divided into 16 3-bit indices, which are used to select one of these 8 possible values for each pixel in the block.

The decoded value of a pixel is a value between 0 and 255 and is calculated the following way:

$$\mathit{clamp}255((\mathit{base\_codeword}) + \mathit{modifier} \times \mathit{multiplier}), \quad (\text{C.1})$$

where  $\mathit{clamp}255(\cdot)$  maps values outside the range  $[0, 255]$  to 0.0 or 255.0.

The `base_codeword` is stored in the first 8 bits (bits 63–56) as shown in table C.17a. This is the first term in Equation C.1.

Next, we want to obtain the modifier. Bits 51–48 in table C.17a form a 4-bit index used to select one of 16 pre-determined ‘modifier tables’, shown in table C.18. For example, a table index of 13 (1101 binary) means that we should use table  $[-1, -2, -3, -10, 0, 1, 2, 9]$ . To select which of these values we should use, we consult the pixel index of the pixel we want to decode. As shown in table C.17b, bits 47–0 are used to store a 3-bit index for each pixel in the block, selecting one of the 8

table index	modifier table							
0	-3	-6	-9	-15	2	5	8	14
1	-3	-7	-10	-13	2	6	9	12
2	-2	-5	-8	-13	1	4	7	12
3	-2	-4	-6	-13	1	3	5	12
4	-3	-6	-8	-12	2	5	7	11
5	-3	-7	-9	-11	2	6	8	10
6	-4	-7	-8	-11	3	6	7	10
7	-3	-5	-8	-11	2	4	7	10
8	-2	-6	-8	-10	1	5	7	9
9	-2	-5	-8	-10	1	4	7	9
10	-2	-4	-8	-10	1	3	7	9
11	-2	-5	-7	-10	1	4	6	9
12	-3	-4	-7	-10	2	3	6	9
13	-1	-2	-3	-10	0	1	2	9
14	-4	-6	-8	-9	3	5	7	8
15	-3	-5	-7	-9	2	4	6	8

Table C.18: Intensity modifier sets for alpha component.

possible values. Assume we are interested in pixel  $b$ . Its pixel indices are stored in bit 44–42, with the most significant bit stored in 44 and the least significant bit stored in 42. If the pixel index is 011 binary = 3, this means we should take the value 3 from the left in the table, which is  $-10$ . This is now our modifier, which is the starting point of our second term in the addition.

In the next step we obtain the multiplier value; bits 55–52 form a four-bit ‘multiplier’ between 0 and 15. This value should be multiplied with the modifier. An encoder is not allowed to produce a multiplier of zero, but the decoder should still be able to handle also this case (and produce  $0 \times \text{modifier} = 0$  in that case).

The modifier times the multiplier now provides the third and final term in the sum in Equation C.1. The sum is calculated and the value is clamped to the interval  $[0, 255]$ . The resulting value is the 8-bit output value.

For example, assume a base\_codeword of 103, a ‘table index’ of 13, a pixel index of 3 and a multiplier of 2. We will then start with the base codeword 103 (01100111 binary). Next, a ‘table index’ of 13 selects table  $[-1, -2, -3, -10, 0, 1, 2, 9]$ , and using a pixel index of 3 will result in a modifier of  $-10$ . The multiplier is 2, forming  $-10 \times 2 = -20$ . We now add this to the base value and get  $103 - 20 = 83$ . After clamping we still get  $83 = 01010011$  binary. This is our

8-bit output value.

This specification gives the output for each channel in 8-bit integer values between 0 and 255, and these values all need to be divided by 255 to obtain the final floating point representation.

Note that hardware can be effectively shared between the alpha decoding part of this format and that of COMPRESSED\_R11\_EAC texture. For details on how to reuse hardware, see Section C.3.5.

### C.3.4 Format COMPRESSED\_SRGB8\_ALPHA8\_ETC2\_EAC

Decompression of floating point sRGB values in COMPRESSED\_SRGB8\_ALPHA8\_ETC2\_EAC follows that of floating point RGB values of RGBA8\_ETC2\_EAC. The result is sRGB values between 0.0 and 1.0. The further conversion from an sRGB encoded component,  $c_s$ , to a linear component,  $c_l$ , is as described in section 8.23. Assume  $c_s$  is the sRGB component in the range  $[0, 1]$ .

The alpha component of COMPRESSED\_SRGB8\_ALPHA8\_ETC2\_EAC is done in the same way as for COMPRESSED\_RGBA8\_ETC2\_EAC.

### C.3.5 Format COMPRESSED\_R11\_EAC

The number of bits to represent a  $4 \times 4$  texel block is 64 bits if *internalformat* is given by COMPRESSED\_R11\_EAC. In that case the data for a block is stored as a number of bytes,  $\{q_0, q_1, q_2, q_3, q_4, q_5, q_6, q_7\}$ , where byte  $q_0$  is located at the lowest memory address and  $q_7$  at the highest. The red component of the  $4 \times 4$  block is then represented by the following 64 bit integer:

$$\text{int64bit} = 256 \times (256 \times (256 \times (256 \times (256 \times (256 \times (256 \times q_0 + q_1) + q_2) + q_3) + q_4) + q_5) + q_6) + q_7$$

This 64-bit word contains information about a single-channel  $4 \times 4$  pixel block as shown in table C.10. The 64-bit word is split into two parts. The first 16 bits comprise a base codeword, a table codeword and a multiplier. The remaining 48 bits are divided into 16 3-bit indices, which are used to select one of the 8 possible values for each pixel in the block, as shown in table C.17.

The decoded value is calculated as

$$\text{clamp1}((\text{base\_codeword} + 0.5) \times \frac{1}{255.875} + \text{modifier} \times \text{multiplier} \times \frac{1}{255.875}), \quad (\text{C.2})$$

where  $\text{clamp1}(\cdot)$  maps values outside the range  $[0.0, 1.0]$  to 0.0 or 1.0.

We will now go into detail how the decoding is done. The result will be an 11-bit fixed point number where 0 represents 0.0 and 2047 represents 1.0. This is the exact representation for the decoded value. However, some implementations

may use, e.g., 16-bits of accuracy for filtering. In such a case the 11-bit value will be extended to 16 bits in a predefined way, which we will describe later.

To get a value between 0 and 2047 we must multiply Equation C.2 by 2047.0:

$$\text{clamp2}\left(\left(\text{base\_codeword} + 0.5\right) \times \frac{2047.0}{255.875} + \text{modifier} \times \text{multiplier} \times \frac{2047.0}{255.875}\right), \quad (\text{C.3})$$

where  $\text{clamp2}(\cdot)$  clamps to the range  $[0.0, 2047.0]$ . Since  $2047.0/255.875$  is exactly 8.0, the above equation can be written as

$$\text{clamp2}(\text{base\_codeword} \times 8 + 4 + \text{modifier} \times \text{multiplier} \times 8) \quad (\text{C.4})$$

The `base_codeword` is stored in the first 8 bits as shown in table C.17a. Bits 63–56 in each block represent an eight-bit integer (`base_codeword`) which is multiplied by 8 by shifting three steps to the left. We can add 4 to this value without addition logic by just inserting 100 binary in the last three bits after the shift. For example, if `base_codeword` is  $129 = 10000001$  binary (or 10000001b for short), the shifted value is 10000001000b and the shifted value including the +4 term is 10000001100b =  $1036 = 129 \times 8 + 4$ . Hence we have summed together the first two terms of the sum in Equation C.4.

Next, we want to obtain the modifier. Bits 51–48 form a 4-bit index used to select one of 16 pre-determined ‘modifier tables’, shown in table C.18. For example, a table index of 13 (1101 binary) means that we should use table  $[-1, -2, -3, -10, 0, 1, 2, 9]$ . To select which of these values we should use, we consult the pixel index of the pixel we want to decode. Bits 47–0 are used to store a 3-bit index for each pixel in the block, selecting one of the 8 possible values. Assume we are interested in pixel  $b$ . Its pixel indices are stored in bit 44–42, with the most significant bit stored in 44 and the least significant bit stored in 42. If the pixel index is 011 binary = 3, this means we should take the value 3 from the left in the table, which is  $-10$ . This is now our modifier, which is the starting point of our second term in the sum.

In the next step we obtain the multiplier value; bits 55–52 form a four-bit ‘multiplier’ between 0 and 15. We will later treat what happens if the multiplier value is zero, but if it is nonzero, it should be multiplied with the modifier. This product should then be shifted three steps to the left to implement the  $\times 8$  multiplication. The result now provides the third and final term in the sum in C.4. The sum is calculated and the result is clamped to a value in the interval  $[0, 2047]$ . The resulting value is the 11-bit output value.

For example, assume a `base_codeword` of 103, a ‘table index’ of 13, a pixel index of 3 and a multiplier of 2. We will then first multiply the `base_codeword` 103 (01100111b) by 8 by left-shifting it (0110111000b) and then add 4 resulting

in  $0110111100b = 828 = 103 \times 8 + 4$ . Next, a ‘table index’ of 13 selects table  $[-1, -2, -3, -10, 0, 1, 2, 9]$ , and using a pixel index of 3 will result in a modifier of  $-10$ . The multiplier is nonzero, which means that we should multiply it with the modifier, forming  $-10 \times 2 = -20 = 11111101100b$ . This value should in turn be multiplied by 8 by left-shifting it three steps:  $111101100000b = -160$ . We now add this to the base value and get  $828 - 160 = 668$ . After clamping we still get  $668 = 01010011100b$ . This is our 11-bit output value, which represents the value  $668/2047 = 0.32633121\dots$

If the multiplier\_value is zero (i.e., the multiplier bits 55–52 are all zero), we should set the multiplier to 1.0/8.0. Equation C.4 can then be simplified to

$$\text{clamp2}(\text{base\_codeword} \times 8 + 4 + \text{modifier}) \quad (\text{C.5})$$

As an example, assume a base\_codeword of 103, a ‘table index’ of 13, a pixel index of 3 and a multiplier\_value of 0. We treat the base\_codeword the same way, getting  $828 = 103 \times 8 + 4$ . The modifier is still -10. But the multiplier should now be 1/8, which means that third term becomes  $-10 \times (1/8) \times 8 = -10$ . The sum therefore becomes  $828 - 10 = 818$ . After clamping we still get  $818 = 01100110010b$ , and this is our 11-bit output value, and it represents  $818/2047 = 0.39960918\dots$

Some GL implementations may find it convenient to use 16-bit values for further processing. In this case, the 11-bit value should be extended using bit replication. An 11-bit value  $x$  is extended to 16 bits through  $(x \ll 5) + (x \gg 6)$ . For example, the value  $668 = 01010011100b$  should be extended to  $0101001110001010b = 21386$ .

In general, the implementation may extend the value to any number of bits that is convenient for further processing, e.g., 32 bits. In these cases, bit replication should be used. On the other hand, an implementation is not allowed to truncate the 11-bit value to less than 11 bits.

Note that the method does not have the same reconstruction levels as the alpha part in the COMPRESSED\_RGBA8\_ETC2\_EAC-format. For instance, for a base\_value of 255 and a table\_value of 0, the alpha part of the COMPRESSED\_RGBA8\_ETC2\_EAC-format will represent a value of  $(255 + 0)/255.0 = 1.0$  exactly. In COMPRESSED\_R11\_EAC the same base\_value and table\_value will instead represent  $(255.5 + 0)/255.875 = 0.99853444\dots$ . That said, it is still possible to decode the alpha part of the COMPRESSED\_RGBA8\_ETC2\_EAC-format using COMPRESSED\_R11\_EAC-hardware. This is done by truncating the 11-bit number to 8 bits. As an example, if base\_value = 255 and table\_value = 0, we get the 11-bit value  $(255 \times 8 + 4 + 0) = 2044 = 1111111100b$ , which after truncation becomes the 8-bit value  $11111111b = 255$  which is exactly the correct value according to the

COMPRESSED\_RGBA8\_ETC2\_EAC. Clamping has to be done to  $[0, 255]$  after truncation for COMPRESSED\_RGBA8\_ETC2\_EAC-decoding. Care must also be taken to handle the case when the multiplier value is zero. In the 11-bit version, this means multiplying by  $1/8$ , but in the 8-bit version, it really means multiplication by 0. Thus, the decoder will have to know if it is a COMPRESSED\_RGBA8\_ETC2\_EAC texture or a COMPRESSED\_R11\_EAC texture to decode correctly, but the hardware can be 100% shared.

As stated above, a base\_value of 255 and a table\_value of 0 will represent a value of  $(255.5 + 0)/255.875 = 0.99853444\dots$ , and this does not reach 1.0 even though 255 is the highest possible base\_codeword. However, it is still possible to reach a pixel value of 1.0 since a modifier other than 0 can be used. Indeed, half of the modifiers will often produce a value of 1.0. As an example, assume we choose the base\_value 255, a multiplier of 1 and the modifier table  $[-3 \ -5 \ -7 \ -9 \ 2 \ 4 \ 6 \ 8]$ . Starting with C.4,

$$\text{clamp1}\left(\left(\text{base\_codeword}+0.5\right)\times\frac{1}{255.875}+\text{table\_value}\times\text{multiplier}\times\frac{1}{255.875}\right)$$

we get

$$\text{clamp1}\left(\left(255+0.5\right)\times\frac{1}{255.875}+\left[-3 \ -5 \ -7 \ -9 \ 2 \ 4 \ 6 \ 8\right]\times\frac{1}{255.875}\right)$$

which equals

$$\text{clamp1}\left(\left[0.987 \ 0.979 \ 0.971 \ 0.963 \ 1.00 \ 1.01 \ 1.02 \ 1.03\right]\right)$$

or after clamping

$$\left[0.987 \ 0.979 \ 0.971 \ 0.963 \ 1.00 \ 1.00 \ 1.00 \ 1.00\right]$$

which shows that several values can be 1.0, even though the base value does not reach 1.0. The same reasoning goes for 0.0.

### C.3.6 Format COMPRESSED\_RG11\_EAC

The number of bits to represent a  $4 \times 4$  texel block is 128 bits if *internalformat* is given by COMPRESSED\_RG11\_EAC. In that case the data for a block is stored as a number of bytes,  $\{q_0, q_1, q_2, q_3, q_4, q_5, q_6, q_7, p_0, p_1, p_2, p_3, p_4, p_5, p_6, p_7\}$  where byte  $q_0$  is located at the lowest memory address and  $p_7$  at the highest. The 128 bits specifying the block are then represented by the following two 64 bit integers:

$$\text{int64bit0} = 256 \times (256 \times (256 \times (256 \times (256 \times (256 \times (256 \times q_0 + q_1) + q_2) + q_3) + q_4) + q_5) + q_6) + q_7$$

$$\text{int64bit1} = 256 \times (256 \times (256 \times (256 \times (256 \times (256 \times (256 \times p_0 + p_1) + p_2) + p_3) + p_4) + p_5) + p_6) + p_7$$

The 64-bit word `int64bit0` contains information about the red component of a two-channel 4x4 pixel block as shown in table C.10, and the word `int64bit1` contains information about the green component. Both 64-bit integers are decoded in the same way as `COMPRESSED_R11_EAC` described in Section C.3.5.

### C.3.7 Format `COMPRESSED_SIGNED_R11_EAC`

The number of bits to represent a  $4 \times 4$  texel block is 64 bits if *internalformat* is given by `COMPRESSED_SIGNED_R11_EAC`. In that case the data for a block is stored as a number of bytes,  $\{q_0, q_1, q_2, q_3, q_4, q_5, q_6, q_7\}$ , where byte  $q_0$  is located at the lowest memory address and  $q_7$  at the highest. The red component of the  $4 \times 4$  block is then represented by the following 64 bit integer:

$$\text{int64bit} = 256 \times (256 \times (256 \times (256 \times (256 \times (256 \times (256 \times q_0 + q_1) + q_2) + q_3) + q_4) + q_5) + q_6) + q_7$$

This 64-bit word contains information about a single-channel  $4 \times 4$  pixel block as shown in table C.10. The 64-bit word is split into two parts. The first 16 bits comprise a base codeword, a table codeword and a multiplier. The remaining 48 bits are divided into 16 3-bit indices, which are used to select one of the 8 possible values for each pixel in the block, as shown in table C.17.

The decoded value is calculated as

$$\text{clamp1}(\text{base\_codeword} \times \frac{1}{127.875} + \text{modifier} \times \text{multiplier} \times \frac{1}{127.875}) \quad (\text{C.6})$$

where `clamp1(.)` maps values outside the range  $[-1.0, 1.0]$  to  $-1.0$  or  $1.0$ . We will now go into detail how the decoding is done. The result will be an 11-bit two's-complement fixed point number where  $-1023$  represents  $-1.0$  and  $1023$  represents  $1.0$ . This is the exact representation for the decoded value. However, some implementations may use, e.g., 16-bits of accuracy for filtering. In such a case the 11-bit value will be extended to 16 bits in a predefined way, which we will describe later.

To get a value between  $-1023$  and  $1023$  we must multiply Equation C.6 by  $1023.0$ :

$$\text{clamp2}(\text{base\_codeword} \times \frac{1023.0}{127.875} + \text{modifier} \times \text{multiplier} \times \frac{1023.0}{127.875}), \quad (\text{C.7})$$

where `clamp2(.)` clamps to the range  $[-1023.0, 1023.0]$ . Since  $1023.0/127.875$  is exactly 8, the above formula can be written as

$$\text{clamp2}(\text{base\_codeword} \times 8 + \text{modifier} \times \text{multiplier} \times 8). \quad (\text{C.8})$$

The `base_codeword` is stored in the first 8 bits as shown in table C.17a. It is a two's-complement value in the range  $[-127, 127]$ , and where the value  $-128$  is not allowed; however, if it should occur anyway it must be treated as  $-127$ . The `base_codeword` is then multiplied by 8 by shifting it left three steps. For example the value  $65 = 01000001$  binary (or `01000001b` for short) is shifted to `01000001000b`  $= 520 = 65 \times 8$ .

Next, we want to obtain the modifier. Bits 51–48 form a 4-bit index used to select one of 16 pre-determined ‘modifier tables’, shown in table C.18. For example, a table index of 13 (1101 binary) means that we should use table  $[-1, -2, -3, -10, 0, 1, 2, 9]$ . To select which of these values we should use, we consult the pixel index of the pixel we want to decode. Bits 47–0 are used to store a 3-bit index for each pixel in the block, selecting one of the 8 possible values. Assume we are interested in pixel  $b$ . Its pixel indices are stored in bit 44–42, with the most significant bit stored in 44 and the least significant bit stored in 42. If the pixel index is 011 binary  $= 3$ , this means we should take the value 3 from the left in the table, which is  $-10$ . This is now our modifier, which is the starting point of our second term in the sum.

In the next step we obtain the multiplier value; bits 55–52 form a four-bit ‘multiplier’ between 0 and 15. We will later treat what happens if the multiplier value is zero, but if it is nonzero, it should be multiplied with the modifier. This product should then be shifted three steps to the left to implement the  $\times 8$  multiplication. The result now provides the third and final term in the sum in Equation C.8. The sum is calculated and the result is clamped to a value in the interval  $[-1023, 1023]$ . The resulting value is the 11-bit output value.

For example, assume a `base_codeword` of 60, a ‘table index’ of 13, a pixel index of 3 and a multiplier of 2. We start by multiplying the `base_codeword` (`00111100b`) by 8 using bit shift, resulting in (`00111100000b`)  $= 480 = 60 \times 8$ . Next, a ‘table index’ of 13 selects table  $[-1, -2, -3, -10, 0, 1, 2, 9]$ , and using a pixel index of 3 will result in a modifier of  $-10$ . The multiplier is nonzero, which means that we should multiply it with the modifier, forming  $-10 \times 2 = -20 = 11111101100b$ . This value should in turn be multiplied by 8 by left-shifting it three steps: `111101100000b`  $= -160$ . We now add this to the base value and get  $480 - 160 = 320$ . After clamping we still get  $320 = 00101000000b$ . This is our 11-bit output value, which represents the value  $320/1023 = 0.31280547\dots$

If the multiplier value is zero (i.e., the multiplier bits 55–52 are all zero), we should set the multiplier to  $1.0/8.0$ . Equation C.8 can then be simplified to

$$\text{clamp2}(\text{base\_codeword} \times 8 + \text{modifier}) \quad (\text{C.9})$$

As an example, assume a `base_codeword` of 65, a ‘table index’ of 13, a pixel index of 3 and a multiplier value of 0. We treat the `base_codeword` the same way,



getting  $480 = 60 \times 8$ . The modifier is still  $-10$ . But the multiplier should now be  $1/8$ , which means that third term becomes  $-10 * (1/8) \times 8 = -10$ . The sum therefore becomes  $480 - 10 = 470$ . Clamping does not affect the value since it is already in the range  $[-1023, 1023]$ , and the 11-bit output value is therefore  $470 = 00111010110b$ . This represents  $470/1023 = 0.45943304\dots$

Some GL implementations may find it convenient to use two's-complement 16-bit values for further processing. In this case, a positive 11-bit value should be extended using bit replication on all the bits except the sign bit. An 11-bit value  $x$  is extended to 16 bits through  $(x \ll 5) + (x \gg 5)$ . Since the sign bit is zero for a positive value, no addition logic is needed for the bit replication in this case. For example, the value  $470 = 00111010110b$  in the above example should be expanded to  $0011101011001110b = 15054$ . A negative 11-bit value must first be made positive before bit replication, and then made negative again:

```

if( result11bit >= 0)
    result16bit = (result11bit << 5) + (result11bit >> 5);
else
    result11bit = -result11bit;
    result16bit = (result11bit << 5) + (result11bit >> 5);
    result16bit = -result16bit;
end

```

Simply bit replicating a negative number without first making it positive will not give a correct result.

In general, the implementation may extend the value to any number of bits that is convenient for further processing, e.g., 32 bits. In these cases, bit replication according to the above should be used. On the other hand, an implementation is not allowed to truncate the 11-bit value to less than 11 bits.

Note that it is not possible to specify a base value of  $1.0$  or  $-1.0$ . The largest possible base\_codeword is  $+127$ , which represents  $127/127.875 = 0.993\dots$ . However, it is still possible to reach a pixel value of  $1.0$  or  $-1.0$ , since the base value is modified by the table before the pixel value is calculated. Indeed, half of the modifiers will often produce a value of  $1.0$ . As an example, assume the base\_codeword is  $+127$ , the modifier table is  $[-3 -5 -7 -9 2 4 6 8]$  and the multiplier is one. Starting with Equation C.6,

$$base\_codeword \times \frac{1}{127.875} + modifier \times multiplier \times \frac{1}{127.875}$$

we get

$$\frac{127}{127.875} + [-3 -5 -7 -9 2 4 6 8] \times \frac{1}{127.875}$$

which equals

$$\left[ \begin{array}{cccccccc} 0.970 & 0.954 & 0.938 & 0.923 & 1.01 & 1.02 & 1.04 & 1.06 \end{array} \right]$$

or after clamping

$$\left[ \begin{array}{cccccccc} 0.970 & 0.954 & 0.938 & 0.923 & 1.00 & 1.00 & 1.00 & 1.00 \end{array} \right]$$

This shows that it is indeed possible to arrive at the value 1.0. The same reasoning goes for  $-1.0$ .

Note also that Equations C.8/C.9 are very similar to Equations C.4/C.5 in the unsigned version EAC\_R11. Apart from the  $+4$ , the clamping and the extension to bitsizes other than 11, the same decoding hardware can be shared between the two codecs.

### C.3.8 Format COMPRESSED\_SIGNED\_RG11\_EAC

The number of bits to represent a  $4 \times 4$  texel block is 128 bits if *internalformat* is given by COMPRESSED\_SIGNED\_RG11\_EAC. In that case the data for a block is stored as a number of bytes,  $\{q_0, q_1, q_2, q_3, q_4, q_5, q_6, q_7, p_0, p_1, p_2, p_3, p_4, p_5, p_6, p_7\}$  where byte  $q_0$  is located at the lowest memory address and  $p_7$  at the highest. The 128 bits specifying the block are then represented by the following two 64 bit integers:

$$\text{int64bit0} = 256 \times (256 \times (256 \times (256 \times (256 \times (256 \times (256 \times q_0 + q_1) + q_2) + q_3) + q_4) + q_5) + q_6) + q_7$$

$$\text{int64bit1} = 256 \times (256 \times (256 \times (256 \times (256 \times (256 \times p_0 + p_1) + p_2) + p_3) + p_4) + p_5) + p_6) + p_7$$

The 64-bit word int64bit0 contains information about the red component of a two-channel  $4 \times 4$  pixel block as shown in table C.10, and the word int64bit1 contains information about the green component. Both 64-bit integers are decoded in the same way as COMPRESSED\_SIGNED\_R11\_EAC described in Section C.3.7.

### C.3.9 Format COMPRESSED\_RGB8\_PUNCHTHROUGH\_ALPHA1\_ETC2

For COMPRESSED\_RGB8\_PUNCHTHROUGH\_ALPHA1\_ETC2, each 64-bit word contains information about a four-channel  $4 \times 4$  pixel block as shown in table C.10.

The blocks are compressed using one of four different ‘modes’. table C.19a shows the bits used for determining the mode used in a given block.

To determine the mode, the three 5-bit values R, G and B, and the three 3-bit values dR, dG and dB are examined. R, G and B are treated as integers between 0 and 31 and dR, dG and dB as two’s-complement integers between  $-4$  and  $+3$ .

a) location of bits for mode selection:

63 62 61 60 59 58 57 56 55 54 53 52 51 50 49 48 47 46 45 44 43 42 41 40 39 38 37 36 35 34 33	32							
R	dR	G	dG	B	dB	-----	Op	-

b) bit layout for bits 63 through 32 for 'differential' mode:

63 62 61 60 59 58 57 56 55 54 53 52 51 50 49 48 47 46 45 44 43 42 41 40 39 38 37 36 35 34 33	32								
R	dR	G	dG	B	dB	table1	table2	Op	FB

c) bit layout for bits 63 through 32 for 'T' mode:

63 62 61 60 59 58 57 56 55 54 53 52 51 50 49 48 47 46 45 44 43 42 41 40 39 38 37 36 35 34 33	32										
---	R1a	-	R1b	G1	B1	R2	G2	B2	da	Op	db

d) bit layout for bits 63 through 32 for 'H' mode:

63 62 61 60 59 58 57 56 55 54 53 52	51	50	49 48 47 46 45 44 43 42 41 40 39 38 37 36 35 34	33	32								
-	R1	G1a	---	G1b	B1a	-	B1b	R2	G2	B2	da	Op	db

e) bit layout for bits 31 through 0 for 'individual', 'diff', 'T' and 'H' modes:

31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
p0 o0 n0 m0 l0 k0 j0 i0 h0 g0 f0 e0 d0 c0 b0 a0 p1 o1 n1 m1 l1 k1 j1 i1 h1 g1 f1 e1 d1 c1 b1 a1

f) bit layout for bits 63 through 0 for 'planar' mode:

63 62 61 60 59 58 57 56	55 54 53 52 51 50 49 48	47 46 45 44 43 42 41 40 39 38 37 36 35 34 33	32									
-	RO	GO1	-	GO2	BO1	---	BO2	-	BO3	RH1	1	RH2
31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0												
GH	BH	RV	GV	BV								

Table C.19: Texel Data format for RGB8\_PUNCHTHROUGH\_ALPHA1\_ETC2 compressed textures formats

First, R and dR are added, and if the sum is not within the interval [0,31], the 'T' mode is selected. Otherwise, if the sum of G and dG is outside the interval [0,31], the 'H' mode is selected. Otherwise, if the sum of B and dB is outside of the interval [0,31], the 'planar' mode is selected. Finally, if all of the aforementioned sums lie between 0 and 31, the 'differential' mode is selected.

The layout of the bits used to decode the 'differential' mode is shown in table C.19b. In this mode, the 4 × 4 block is split into two subblocks of either size 2 × 4 or 4 × 2. This is controlled by bit 32, which we dub the 'flip bit'. If the 'flip bit' is 0, the block is divided into two 2 × 4 subblocks side-by-side, as shown in table C.12. If the 'flip bit' is 1, the block is divided into two 4 × 2 subblocks on top of each other, as shown in table C.13. For each subblock, a 'base color' is stored.

In the 'differential' mode, following the layout shown in table C.19b, the base color for subblock 1 is derived from the five-bit codewords R, G and B. These five-bit codewords are extended to eight bits by replicating the top three highest order

bits to the three lowest order bits. For instance, if  $R = 28 = 11100$  binary (11100b for short), the resulting eight-bit red color component becomes  $11100111b = 231$ . Likewise, if  $G = 4 = 00100b$  and  $B = 3 = 00011b$ , the green and blue components become  $00100001b = 33$  and  $00011000b = 24$  respectively. Thus, in this example, the base color for subblock 1 is (231, 33, 24). The five bit representation for the base color of subblock 2 is obtained by modifying the 5-bit codewords R, G and B by the codewords dR, dG and dB. Each of dR, dG and dB is a 3-bit two's-complement number that can hold values between  $-4$  and  $+3$ . For instance, if  $R = 28$  as above, and  $dR = 100b = -4$ , then the five bit representation for the red color component is  $28 + (-4) = 24 = 11000b$ , which is then extended to eight bits to  $11000110b = 198$ . Likewise, if  $G = 4$ ,  $dG = 2$ ,  $B = 3$  and  $dB = 0$ , the base color of subblock 2 will be  $RGB = (198, 49, 24)$ . In summary, the base colors for the subblocks in the differential mode are:

$$\begin{aligned} \text{base col subblock1} &= \text{extend\_5to8bits}(R, G, B) \\ \text{base col subblock2} &= \text{extend\_5to8bits}(R + dR, G + dG, B + dB) \end{aligned}$$

Note that these additions will not under- or overflow, or one of the alternative decompression modes would have been chosen instead of the 'differential' mode.

After obtaining the base color, a table is chosen using the table codewords: For subblock 1, table codeword 1 is used (bits 39–37), and for subblock 2, table codeword 2 is used (bits 36–34), see table C.19b. The table codeword is used to select one of eight modifier tables. If the 'opaque'-bit (bit 33) is set, table C.20a is used. If it is unset, table C.20b is used. For instance, if the 'opaque'-bit is 1 and the table code word is 010 binary = 2, then the modifier table  $[-29, -9, 9, 29]$  is selected for the corresponding sub-block. Note that the values in Tables C.20a and C.20b are valid for all textures and can therefore be hardcoded into the decompression unit.

Next, we identify which modifier value to use from the modifier table using the two 'pixel index' bits. The pixel index bits are unique for each pixel. For instance, the pixel index for pixel d (see table C.10) can be found in bits 19 (most significant bit, MSB), and 3 (least significant bit, LSB), see table C.19e. Note that the pixel index for a particular texel is always stored in the same bit position, irrespectively of the 'flipbit'.

If the 'opaque'-bit (bit 33) is set, the pixel index bits are decoded using table C.21a. If the 'opaque'-bit is unset, table C.21b will be used instead. If, for instance, the 'opaque'-bit is 1, and the pixel index bits are 01 binary = 1, and the modifier table  $[-29, -9, 9, 29]$  is used, then the modifier value selected for that pixel is 29 (see table C.21a). This modifier value is now used to additively modify the base color. For example, if we have the base color (231, 8, 16), we should add the modifier value 29 to all three components:  $(231 + 29, 8 + 29, 16 + 29)$  resulting

a) Intensity modifier sets for the ‘differential’ if ‘opaque’ is set:

table codeword	modifier table			
0	-8	-2	2	8
1	-17	-5	5	17
2	-29	-9	9	29
3	-42	-13	13	42
4	-60	-18	18	60
5	-80	-24	24	80
6	-106	-33	33	106
7	-183	-47	47	183

b) Intensity modifier sets for the ‘differential’ if ‘opaque’ is unset:

table codeword	modifier table			
0	-8	0	0	8
1	-17	0	0	17
2	-29	0	0	29
3	-42	0	0	42
4	-60	0	0	60
5	-80	0	0	80
6	-106	0	0	106
7	-183	0	0	183

Table C.20: Intensity modifier sets if ‘opaque’ is set and if ‘opaque’ is unset.

in (260, 37, 45). These values are then clamped to [0, 255], resulting in the color (255, 37, 45).

The alpha component is decoded using the ‘opaque’-bit, which is positioned in bit 33 (see table C.19b). If the ‘opaque’-bit is set, alpha is always 255. However, if the ‘opaque’-bit is zero, the alpha-value depends on the pixel indices; if MSB==1 and LSB==0, the alpha value will be zero, otherwise it will be 255. Finally, if the alpha value equals 0, the red-, green- and blue components will also be zero.

```

if( opaque == 0 && MSB == 1 && LSB == 0)
    red = 0;
    green = 0;
    blue = 0;
    alpha = 0;
else
    alpha = 255;

```

a) Mapping from pixel index values to modifier values when ‘opaque’-bit is set.

pixel index value		resulting modifier value
msb	lsb	
1	1	-b (large negative value)
1	0	-a (small negative value)
0	0	a (small positive value)
0	1	b (large positive value)

b) Mapping from pixel index values to modifier values when ‘opaque’-bit is unset.

pixel index value		resulting modifier value
msb	lsb	
1	1	-b (large negative value)
1	0	0 (zero)
0	0	0 (zero)
0	1	b (large positive value)

Table C.21: Mapping from pixel index values to modifier values for COMPRESSED\_RGB8\_PUNCHTHROUGH\_ALPHA1\_ETC2 compressed textures

end

Hence paint color 2 will equal RGBA = (0,0,0,0) if opaque == 0.

In the example above, assume that the ‘opaque’-bit was instead 0. Then, since the MSB = 0 and LSB 1, alpha will be 255, and the final decoded RGBA-tuple will be (255, 37, 45, 255).

The ‘T’ and ‘H’ compression modes share some characteristics: both use two base colors stored using 4 bits per channel. These bits are not stored sequentially, but in the layout shown in Tables C.19c and C.19d. To clarify, in the ‘T’ mode, the two colors are constructed as follows:

$$\begin{aligned} \text{base col 1} &= \text{extend\_4to8bits}((R1a \ll 2) | R1b, G1, B1) \\ \text{base col 2} &= \text{extend\_4to8bits}(R2, G2, B2) \end{aligned}$$

In the ‘H’ mode, the two colors are constructed as follows:

$$\begin{aligned} \text{base col 1} &= \text{extend\_4to8bits}(R1, (G1a \ll 1) | G1b, (B1a \ll 3) | B1b) \\ \text{base col 2} &= \text{extend\_4to8bits}(R2, G2, B2) \end{aligned}$$

The function `extend_4to8bits()` just replicates the four bits twice. This is equivalent to multiplying by 17. As an example, `extend_4to8bits(1101b)` equals `11011101b = 221`.

Both the ‘T’ and ‘H’ modes have four ‘paint colors’ which are the colors that will be used in the decompressed block, but they are assigned in a different manner. In the ‘T’ mode, ‘paint color 0’ is simply the first base color, and ‘paint color 2’ is the second base color. To obtain the other ‘paint colors’, a ‘distance’ is first determined, which will be used to modify the luminance of one of the base colors. This is done by combining the values ‘da’ and ‘db’ shown in table C.19c by  $(da \ll 1) | db$ , and then using this value as an index into the small look-up table shown in table C.16. For example, if ‘da’ is 10 binary and ‘db’ is 1 binary, the index is 101 binary and the selected distance will be 32. ‘Paint color 1’ is then equal to the second base color with the ‘distance’ added to each channel, and ‘paint color 3’ is the second base color with the ‘distance’ subtracted. In summary, to determine the four ‘paint colors’ for a ‘T’ block:

$$\begin{aligned} \text{paint color } 0 &= \text{base col } 1 \\ \text{paint color } 1 &= \text{base col } 2 + (d, d, d) \\ \text{paint color } 2 &= \text{base col } 2 \\ \text{paint color } 3 &= \text{base col } 2 - (d, d, d) \end{aligned}$$

In both cases, the value of each channel is clamped to within [0,255].

Just as for the differential mode, the RGB channels are set to zero if alpha is zero, and the alpha component is calculated the same way:

```
if (opaque == 0 && MSB == 1 && LSB == 0)
    red = 0;
    green = 0;
    blue = 0;
    alpha = 0;
else
    alpha = 255;
end
```

A ‘distance’ value is computed for the ‘H’ mode as well, but doing so is slightly more complex. In order to construct the three-bit index into the distance table shown in table C.16, ‘da’ and ‘db’ shown in table C.19d are used as the most significant bit and middle bit, respectively, but the least significant bit is computed as  $(\text{base col } 1 \text{ value} \geq \text{base col } 2 \text{ value})$ , the ‘value’ of a color for the comparison being equal to  $(R \ll 16) + (G \ll 8) + B$ . Once the ‘distance’ d has been determined for an ‘H’ block, the four ‘paint colors’ will be:

$$\begin{aligned} \text{paint color } 0 &= \text{base col } 1 + (d, d, d) \\ \text{paint color } 1 &= \text{base col } 1 - (d, d, d) \\ \text{paint color } 2 &= \text{base col } 2 + (d, d, d) \\ \text{paint color } 3 &= \text{base col } 2 - (d, d, d) \end{aligned}$$

Yet again, RGB is zeroed if alpha is 0 and the alpha component is determined the same way:

```
if( opaque == 0 && MSB == 1 && LSB == 0)
    red = 0;
    green = 0;
    blue = 0;
    alpha = 0;
else
    alpha = 255;
end
```

Hence paint color 2 will have R=G=B=alpha=0 if opaque == 0.

Again, all color components are clamped to within [0,255]. Finally, in both the 'T' and 'H' modes, every pixel is assigned one of the four 'paint colors' in the same way the four modifier values are distributed in 'individual' or 'differential' blocks. For example, to choose a paint color for pixel d, an index is constructed using bit 19 as most significant bit and bit 3 as least significant bit. Then, if a pixel has index 2, for example, it will be assigned paint color 2.

The final mode possible in an COMPRESSED\_RGB8\_PUNCHTHROUGH\_ALPHA1\_ETC2- compressed block is the 'planar' mode. In this mode, the 'opaque'-bit must be 1 (a valid encoder should not produce an 'opaque'-bit equal to 0 in the planar mode), but should the 'opaque'-bit anyway be 0 the decoder should treat it as if it were 1. In the 'planar' mode, three base colors are supplied and used to form a color plane used to determine the color of the individual pixels in the block.

All three base colors are stored in RGB 676 format, and stored in the manner shown in table C.19f. The three colors are there labelled 'O', 'H' and 'V', so that the three components of color 'V' are RV, GV and BV, for example. Some color channels are split into non-consecutive bit-ranges, for example BO is reconstructed using BO1 as the most significant bit, BO2 as the two following bits, and BO3 as the three least significant bits.

Once the bits for the base colors have been extracted, they must be extended to 8 bits per channel in a manner analogous to the method used for the base colors in other modes. For example, the 6-bit blue and red channels are extended by replicating the two most significant of the six bits to the two least significant of the final 8 bits.

With three base colors in RGB888 format, the color of each pixel can then be determined as:



$$\begin{aligned}
 R(x, y) &= x \times (RH - RO)/4.0 + y \times (RV - RO)/4.0 + RO \\
 G(x, y) &= x \times (GH - GO)/4.0 + y \times (GV - GO)/4.0 + GO \\
 B(x, y) &= x \times (BH - BO)/4.0 + y \times (BV - BO)/4.0 + BO \\
 A(x, y) &= 255,
 \end{aligned}$$

where  $x$  and  $y$  are values from 0 to 3 corresponding to the pixels coordinates within the block,  $x$  being in the  $u$  direction and  $y$  in the  $v$  direction. For example, the pixel  $g$  in table C.10 would have  $x = 1$  and  $y = 2$ .

These values are then rounded to the nearest integer (to the larger integer if there is a tie) and then clamped to a value between 0 and 255. Note that this is equivalent to

$$\begin{aligned}
 R(x, y) &= \text{clamp}_{255}((x \times (RH - RO) + y \times (RV - RO) + 4 \times RO + 2) \gg 2) \\
 G(x, y) &= \text{clamp}_{255}((x \times (GH - GO) + y \times (GV - GO) + 4 \times GO + 2) \gg 2) \\
 B(x, y) &= \text{clamp}_{255}((x \times (BH - BO) + y \times (BV - BO) + 4 \times BO + 2) \gg 2) \\
 A(x, y) &= 255,
 \end{aligned}$$

where  $\text{clamp}_{255}$  clamps the value to a number in the range  $[0, 255]$ .

Note that the alpha component is always 255 in the planar mode.

This specification gives the output for each compression mode in 8-bit integer colors between 0 and 255, and these values all need to be divided by 255 for the final floating point representation.

### C.3.10 Format COMPRESSED\_SRGB8\_PUNCHTHROUGH\_ALPHA1\_ETC2

Decompression of floating point sRGB values in COMPRESSED\_SRGB8\_PUNCHTHROUGH\_ALPHA1\_ETC2 follows that of floating point RGB values of COMPRESSED\_RGB8\_PUNCHTHROUGH\_ALPHA1\_ETC2. The result is sRGB values between 0.0 and 1.0. The further conversion from an sRGB encoded component,  $c_s$ , to a linear component,  $c_l$ , is as described in section 8.23. Assume  $c_s$  is the sRGB component in the range  $[0,1]$ . Note that the alpha component is not gamma corrected, and hence does not use the above formula.

## Appendix D

# Profiles and the Deprecation Model

OpenGL 3.0 introduced a deprecation model in which certain features are marked as *deprecated*. Deprecated features are expected to be completely removed from a future version of OpenGL. Deprecated features are summarized in section [D.2](#).

To aid developers in writing applications which will run on such future versions, it is possible to create an OpenGL context which does not support deprecated features. Such a context is called a *forward compatible context*, while a context supporting all OpenGL features is called a *full context*. Forward compatible contexts cannot restore deprecated functionality through extensions, but they may support additional, non-deprecated functionality through extensions.

*Profiles* define subsets of OpenGL functionality targeted to specific application domains. Starting with OpenGL 3.2, two profiles are defined (see below). Future versions may define additional profiles addressing embedded systems or other domains. OpenGL implementations are not required to support all defined profiles, but must support the *core* profile described below.

To enable application control of deprecation and profiles, new *context creation APIs* have been defined as extensions to GLX, WGL and EGL. These APIs allow specifying a particular version, profile, and full or forward compatible status, and will either create a context compatible with the request, or fail (if, for example, requesting an OpenGL version or profile not supported by the implementation),

Only the ARB may define OpenGL profiles and deprecated features.

## D.1 Core and Compatibility Profiles

The *core profile* of OpenGL defines essential functionality for the modern programmable shading model introduced in OpenGL 2.0, but does not include features marked as removed for that version of the Specification (see section D.2).

The *compatibility profile* does not remove any functionality.

It is not possible to implement both core and compatibility profiles in a single GL context, since the core profile mandates functional restrictions not present in the compatibility profile. Refer to the `WGL_ARB_create_context_profile` and `GLX_ARB_create_context_profile` extensions (see appendix G.3.3.66) for information on creating a context implementing a specific profile.

## D.2 Deprecated and Removed Features

OpenGL 3.0 defined a set of *deprecated features*. OpenGL 3.1 removed most of the deprecated features and moved them into the optional `GL_ARB_compatibility` extension. The OpenGL 3.2 core profile removes the same features as OpenGL 3.1, while the optional compatibility profile supports all those features.

Deprecated and removed features are summarized below in two groups: features which are marked deprecated by the core profile, but have not yet been removed, and features actually removed from the core profile of the current version of OpenGL (no features have been removed from or deprecated in the compatibility profile).

Functions which have been removed will generate an `INVALID_OPERATION` error if called in the core profile or in a forward-compatible context. Functions which are partially removed (e.g. no longer accept some parameter values) will generate the errors appropriate for any other unrecognized value of that parameter when a removed parameter value is passed in the core profile or a forward-compatible context. Functions which are deprecated but have not yet been removed from the core profile continue to operate normally except in a forward-compatible context, where they are also removed.

### D.2.1 Deprecated But Still Supported Features

The following features are deprecated, but still present in the core profile. They may be removed from a future version of OpenGL, and are removed in a forward-compatible context implementing the core profile.

- Wide lines - **LineWidth** values greater than 1.0 will generate an `INVALID_VALUE` error.

- Global component limit query - the implementation-dependent values `MAX_VARYING_COMPONENTS` and `MAX_VARYING_FLOATS`.
- The query targets `NUM_COMPRESSED_TEXTURE_FORMATS` and `COMPRESSED_TEXTURE_FORMATS` (see section 8.5).
- Bitmap pack/unpack state for bitmaps - the pixel pack parameters `UNPACK_LSB_FIRST` and `PACK_LSB_FIRST`.

### D.2.2 Removed Features

- Application-generated object names - the names of all object types, such as buffer, query, and texture objects, must be generated using the corresponding **Gen\*** commands. Trying to bind an object name not returned by a **Gen\*** command will result in an `INVALID_OPERATION` error. This behavior is already the case for framebuffer, renderbuffer, and vertex array objects. Object types which have default objects (objects named zero), such as vertex array, framebuffer, and texture objects, may also bind the default object, even though it is not returned by **Gen\***.
- Color index mode - No color index visuals are supplied by the window system-binding APIs such as GLX and WGL, so the default framebuffer is always in RGBA mode. All language and state related to color index mode vertex, rasterization, and fragment processing behavior is removed. `COLOR_INDEX` formats are also deprecated.
- OpenGL Shading Language versions 1.10 and 1.20. These versions of the shading language depend on many API features that have also been deprecated.
- **Begin / End** primitive specification - **Begin**, **End**, and **EdgeFlag\***; **Color\***, **FogCoord\***, **Index\***, **Normal3\***, **SecondaryColor3\***, **TexCoord\***, **Vertex\***; and all associated state. Vertex arrays and array drawing commands must be used to draw primitives. However, **VertexAttrib\*** and the current vertex attribute state are retained in order to provide default attribute values for disabled attribute arrays.
- Edge flags and fixed-function vertex processing - **ColorPointer**, **EdgeFlagPointer**, **FogCoordPointer**, **IndexPointer**, **NormalPointer**, **SecondaryColorPointer**, **TexCoordPointer**, **VertexPointer**, **EnableClientState**, **DisableClientState**, and **InterleavedArrays**, **ClientActiveTexture**; **Frustum**, **LoadIdentity**, **LoadMatrix**, **LoadTransposeMatrix**, **MatrixMode**,

**MultiMatrix**, **MultiTransposeMatrix**, **Ortho**, **PopMatrix**, **PushMatrix**, **Rotate**, **Scale**, and **Translate**; **Enable/Disable** targets `RESCALE_NORMAL` and `NORMALIZE`; **TexGen\*** and **Enable/Disable** targets `TEXTURE_GEN_*`, **Material\***, **Light\***, **LightModel\***, and **ColorMaterial**, **ShadeModel**, and **Enable/Disable** targets `LIGHTING`, `VERTEX_PROGRAM_TWO_SIDE`, `LIGHT%i`, and `COLOR_MATERIAL`; **ClipPlane**; and all associated fixed-function vertex array, multitexture, matrix and matrix stack, normal and texture coordinate, lighting, and clipping state. A vertex shader must be defined in order to draw primitives.

Language referring to edge flags in the current specification is modified as though all edge flags are `TRUE`.

Note that the **FrontFace** and **ClampColor** commands are **not** deprecated, as they still affect other non-deprecated functionality; however, the **ClampColor** targets `CLAMP_VERTEX_COLOR` and `CLAMP_FRAGMENT_COLOR` are deprecated.

- Client vertex and index arrays - all vertex array attribute and element array index pointers must refer to buffer objects. The default vertex array object (the name zero) is also deprecated. Calling **VertexAttribPointer** when no buffer object or no vertex array object is bound will generate an `INVALID_OPERATION` error, as will calling any array drawing command when no vertex array object is bound.
- Rectangles - **Rect\***.
- Current raster position - **RasterPos\*** and **WindowPos\***, and all associated state.
- Two-sided color selection - **Enable** target `VERTEX_PROGRAM_TWO_SIDE`; OpenGL Shading Language built-ins `gl_BackColor` and `gl_BackSecondaryColor`; and all associated state.
- Non-sprite points - **Enable/Disable** targets `POINT_SMOOTH` and `POINT_SPRITE`, and all associated state. Point rasterization is always performed as though `POINT_SPRITE` were enabled.
- Wide lines and line stipple - **LineWidth** is not deprecated, but values greater than 1.0 will generate an `INVALID_VALUE` error; **LineStipple** and **Enable/Disable** target `LINE_STIPPLE`, and all associated state.

- Quadrilateral and polygon primitives - vertex array drawing modes `POLYGON`, `QUADS`, and `QUAD_STRIP`, related descriptions of rasterization of non-triangle polygons, and all associated state.
- Separate polygon draw mode - **PolygonMode** *face* values of `FRONT` and `BACK`; polygons are always drawn in the same mode, no matter which face is being rasterized.
- Polygon Stipple - **PolygonStipple** and **Enable/Disable** target `POLYGON_STIPPLE`, and all associated state.
- Pixel transfer modes and operations - all pixel transfer modes, including pixel maps, shift and bias, color table lookup, color matrix, and convolution commands and state, and all associated state and commands defining that state.
- Pixel drawing - **DrawPixels** and **PixelZoom**. However, the language describing pixel rectangles in section 8.4 is retained as it is required for **TexImage\*** and **ReadPixels**.
- Bitmaps - **Bitmap** and the `BITMAP` external format.
- Legacy OpenGL 1.0 pixel formats - the values 1, 2, 3, and 4 are no longer accepted as internal formats by **TexImage\*** or any other command taking an internal format argument. The initial internal format of a texel array is `RGBA` instead of 1. `TEXTURE_COMPONENTS` is deprecated; always use `TEXTURE_INTERNAL_FORMAT`.
- Legacy pixel formats - all `ALPHA`, `LUMINANCE`, `LUMINANCE_ALPHA`, and `INTENSITY` external and internal formats, including compressed, floating-point, and integer variants; all references to luminance and intensity formats elsewhere in the specification, including conversion to and from those formats; and all associated state. including state describing the allocation or format of luminance and intensity texture or framebuffer components.
- Depth texture mode - `DEPTH_TEXTURE_MODE`. Section 8.22.1 is to be changed so that *r* is returned to texture samplers directly, and the OpenGL Shading Language 1.30 Specification is to be changed so that  $(r, 0, 0, 1)$  is always returned from depth texture samplers in this case.
- Texture wrap mode `CLAMP` - `CLAMP` is no longer accepted as a value of texture parameters `TEXTURE_WRAP_S`, `TEXTURE_WRAP_T`, or `TEXTURE_WRAP_R`.

- Texture borders - the *border* value to **TexImage\*** must always be zero, or an `INVALID_VALUE` error is generated (section 8.5); all language in section 8 referring to nonzero border widths during texture image specification and texture sampling; and all associated state.
- Automatic mipmap generation - **TexParameter\*** *target* `GENERATE_MIPMAP`, and all associated state.
- Fixed-function fragment processing - **AreTexturesResident**, **PrioritizeTextures**, and **TexParameter** *target* `TEXTURE_PRIORITY`; **TexEnv** *target* `TEXTURE_ENV`, and all associated parameters; **TexEnv** *target* `TEXTURE_FILTER_CONTROL`, and parameter name `TEXTURE_LOD_BIAS`; **Enable** *targets* of all dimensionalities (`TEXTURE_1D`, `TEXTURE_2D`, `TEXTURE_3D`, `TEXTURE_1D_ARRAY`, `TEXTURE_2D_ARRAY`, and `TEXTURE_CUBE_MAP`); **Enable** *target* `COLOR_SUM`; **Enable** *target* `FOG`, **Fog**, and all associated parameters; the implementation-dependent values `MAX_TEXTURE_UNITS` and `MAX_TEXTURE_COORDS`; and all associated state.
- Alpha test - **AlphaFunc** and **Enable/Disable** *target* `ALPHA_TEST`, and all associated state.
- Accumulation buffers - **ClearAccum**, and `ACCUM_BUFFER_BIT` is not valid as a bit in the argument to **Clear** (section 17.4.3); **Accum**; the `ACCUM_*_BITS` framebuffer state describing the size of accumulation buffer components; and all associated state.

Window system-binding APIs such as GLX and WGL may choose to either not expose window configs containing accumulation buffers, or to ignore accumulation buffers when the default framebuffer bound to a GL context contains them.

- Pixel copying - **CopyPixels** (the comments also applying to **CopyTexImage** will be moved to section 8.6).
- Auxiliary color buffers, including `AUXi` targets of the default framebuffer.
- Context framebuffer size queries - `RED_BITS`, `GREEN_BITS`, `BLUE_BITS`, `ALPHA_BITS`, `DEPTH_BITS`, and `STENCIL_BITS`.
- Evaluators - **Map\***, **EvalCoord\***, **MapGrid\***, **EvalMesh\***, **EvalPoint\***, and all evaluator map enables, and all associated state.
- Selection and feedback modes - **RenderMode**, **InitName**, **PopName**, **PushName**, **LoadName**, and **SelectBuffer**; **FeedbackBuffer** and **PassThrough**; and all associated state.

- Display lists - **NewList**, **EndList**, **CallList**, **CallLists**, **ListBase**, **GenLists**, **IsList**, and **DeleteLists**; all references to display lists and behavior when compiling commands into display lists elsewhere in the specification; and all associated state.
- Hints - the `PERSPECTIVE_CORRECTION_HINT`, `POINT_SMOOTH_HINT`, `FOG_HINT`, and `GENERATE_MIPMAP_HINT` targets to **Hint** (section 21.5).
- Attribute stacks - **PushAttrib**, **PushClientAttrib**, **PopAttrib**, **PopClientAttrib**, the `MAX_ATTRIB_STACK_DEPTH`, `MAX_CLIENT_ATTRIB_STACK_DEPTH`, `ATTRIB_STACK_DEPTH`, and `CLIENT_ATTRIB_STACK_DEPTH` state, the client and server attribute stacks, and the values `ALL_ATTRIB_BITS` and `CLIENT_ALL_ATTRIB_BITS`.
- Unified extension string - `EXTENSIONS` target to **GetString**.
- Token names and queries - all token names and queries not otherwise mentioned above for deprecated state, as well as all query entry points where all valid targets of that query are deprecated state (chapter 22 and the state tables)



# Appendix E

## Version 4.2

OpenGL version 4.2, released on August 8, 2011, is the fourteenth revision since the original version 1.0.

Separate versions of the OpenGL 4.2 Specification exist for the *core* and *compatibility* profiles described in appendix D, respectively subtitled the “Core Profile” and the “Compatibility Profile”. This document describes the Core Profile. An OpenGL 4.2 implementation *must* be able to create a context supporting the core profile, and may also be able to create a context supporting the compatibility profile.

Material specific to the compatibility profile specification is marked in a distinct color to clearly call out differences between the two profiles.

The OpenGL 4.2 compatibility and core profiles are upward compatible with the OpenGL 4.1 compatibility and core profiles, respectively.

Following are brief descriptions of changes and additions to OpenGL 4.2.

### E.1 New Features

New features in OpenGL 4.2, including the extension or extensions if any on which they were based, include:

- Support for BPTC compressed textures (`ARB_texture_compression_bptc`).
- Allow pixel storage parameters to affect packing and unpacking of compressed textures (`ARB_compressed_texture_pixel_storage`).
- Shader atomic counters (`ARB_shader_atomic_counters`).
- Immutable texture images (`ARB_texture_storage`).

- Instanced transformed feedback drawing (`ARB_transform_feedback_instanced`).
- Allow the offset within buffer objects used for instanced rendering to be specified (`ARB_base_instance`).
- OpenGL Shading Language built-in functions allowing loads from and stores to texture images from any shader stage, and application control over the ordering of image load/store operations relative to other OpenGL pipeline operations accessing the same memory (`ARB_shader_image_load_store`).
- New OpenGL Shading Language features with no OpenGL API impact (`ARB_conservative_depth` and `ARB_shading_language_420pack` - see the OpenGL Shading Language Specification for details).
- Queries for sample counts available for a given internal format and usage (`ARB_internalformat_query`).
- More restrictive alignment constraints for mapped buffers (`ARB_map_buffer_alignment`).

## E.2 Deprecation Model

The following features are newly deprecated by the OpenGL 4.2 core profile:

- The query targets `NUM_COMPRESSED_TEXTURE_FORMATS` and `COMPRESSED_TEXTURE_FORMATS` (see section 8.5).

Features deprecated by OpenGL 4.1 remain deprecated, but have not yet been removed.

## E.3 Changed Tokens

New token names are introduced to be used in place of old, less general names. However, the old token names continue to be supported, for backwards compatibility with code written for previous versions of OpenGL. The new names, and the old names they replace, are shown in table E.1. Note that `COPY_READ_BUFFER` and `COPY_WRITE_BUFFER` continue to be used as buffer *targets* for e.g. **Bind-Buffer**; the `_BINDING` forms are used only when querying the buffer object bound to those targets.

New Token Name	Old Token Name
COPY_READ_BUFFER_BINDING	COPY_READ_BUFFER
COPY_WRITE_BUFFER_BINDING	COPY_WRITE_BUFFER
TRANSFORM_FEEDBACK_ACTIVE	TRANSFORM_FEEDBACK_BUFFER_ACTIVE
TRANSFORM_FEEDBACK_PAUSED	TRANSFORM_FEEDBACK_BUFFER_PAUSED

Table E.1: New token names and the old names they replace.

## E.4 Change Log for Released Specifications

Changes in the specification update of January 19, 2012:

- Corrections to figure 3.1 (Bug 7997).
- Minor bugfixes and typos in sections 3, 10.3, 11.1, 11.1.1, 11.1.3.5, 4.2, 13.2.3, 14.5.2 (restored description of non-antialiased wide line rendering to the core profile since they are deprecated, but not yet removed), 8.2 (fixed prototypes for **SamplerParameter** commands), 15.2.1, 17.3.12 (specify that multisample buffer is only resolved at this time if the default framebuffer is bound), 9.2.8 (correct limits on *layer* for different types of attached textures), 9.4.2, 8.11 (remove redundant description by **IsTexture** that unbound object names created by **GenTextures** are not the names of texture objects), 23 (add **GetInteger64v** as a supported state query), appendix 5, and tables 23.31, 23.32, 23.55, and 23.72 (Bug 7895).
- Add missing automatic unbinding of previously bound buffer objects for **BindBufferRange** and **BindBufferBase** in section 6.1.1 (Bug 8196).
- More clearly specify interface matching rules for shader inputs and outputs in section 7.4.1, for cases where both sides of an interface are found in the same program and where they are in different programs (Bug 7030).
- Clarify in section 11.1.1 that `dvec3` and `dvec4` vertex shader inputs consume only a single attribute location for the purpose of matching inputs to generic vertex attributes, but may consume two vectors for the purposes of determining if too many attribute vectors are used (Bug 7809). Also, add missing language describing the set of attributes consumed by matrix vertex attributes, with fixes to explicitly address `dmat*` types.
- Remove dangling references to nonexistent `gl_VerticesOut` in section 11.2.1.2.3 (Bug 8357).

- Fix names of cube map sampler type tokens in table 7.3 (Bug 8303).
- Fix behavior of **DeleteTransformFeedbacks** in section 13.2.1 to generate an error if any of the objects being deleted has transform feedback active (Bug 8323).
- Remove ambiguity in the order of operations and which vertices are appended by transform feedback when it is resumed in section 13.2.2 (Bug 8202).
- Updated description of errors resulting from specifying texture images of level 1 or greater which exceed implementation-dependent limits, in sections 8.5 and 8.17.3 (Bug 8210).
- Remove clamping of  $D_t$  and  $D_{ref}$  prior to depth texture comparison in section 8.22.1, since it doesn't reflect hardware reality (Bug 7975).
- Update description of texture access from shadow samplers in section 15.2.1 to interact with texture swizzle (Bug 7962) and clarify that swizzling is not performed on the results of incomplete texture lookups (Bug 7917).
- Add buffer clearing to the list of operations affected by scissor rectangle zero in section 17.3.2 (Bug 8368).
- Remove error (from the core profile only) for querying `CURRENT_VERTEX_ATTRIB` for attribute zero with **GetVertexAttrib\*** in section 7.13 (Bug 8352).
- Clarify that the initial state of `SAMPLE_MASK_VALUE` is for all bits to be set in table 23.11 (Bug 8441).
- Add missing `PROGRAM_SEPARABLE` state to table 23.32 (Bug 8442).
- Numerous minor fixes to state table type fields and formatting (Bugs 8430, 8431).
- Clarified that automatic unbinding of deleted objects, as described in section 5.1.2, does not affect attachments to unbound container objects the deleted objects are themselves attached to (Bug 8233).
- Add version in which several extensions were introduced to core GL in section G.3 (Bug 8418).

Changes in the specification update of August 22, 2011:

- More clearly specify interface matching rules for shader inputs and outputs in section 7.4.1, for cases where both sides of an interface are found in the same program and where they are in different programs (Bug 7030).
- Clarify in section 11.1.1 that `dvec3` and `dvec4` vertex shader inputs consume only a single attribute location for the purpose of matching inputs to generic vertex attributes, but may consume two vectors for the purposes of determining if too many attribute vectors are used (Bug 7809). Also, add missing language describing the set of attributes consumed by matrix vertex attributes, with fixes to explicitly address `dmat*` types.

Changes in the released specification of August 8, 2011:

- Update name of `MIN_MAP_BUFFER_ALIGNMENT` to follow GL conventions in section 6.3 and table 23.55 (Bug 7825).
- Change query object state description in section 4.2 so the initial state of the query result available flag agrees with the state table (Bug 7823).
- Minor cleanups to atomic counter language in section 7.6 and to atomic counter token names in tables 23.57, 23.58, 23.60, and 23.61 (Bug 7834).
- Clarify that completeness affects texture lookup and fetch operations in all shader stages in section 8.17 (Bug 7856).
- Change **BindImageTexture** parameter name from *index* to *unit* and fix minor language issues in section 8.25 (Bugs 7744, 7850, 7851).
- Fix typos in section 22.3 (Bug 7843).
- Fix minimum maximums for `MAX_FRAGMENT_IMAGE_UNIFORMS` and `MAX_COMBINED_IMAGE_UNIFORMS` in table 23.65 (Bug 7805).
- Change minimum maximum for `MAX_ATOMIC_COUNTER_BUFFER_SIZE` to 32 in table 23.64 (Bug 7855).

## E.5 Credits and Acknowledgements

OpenGL 4.2 is the result of the contributions of many people and companies. Members of the Khronos OpenGL ARB Working Group during the development of OpenGL 4.2, including the company that they represented at the time of their contributions, follow. Some major contributions made by individuals are listed together with their name, including specific functionality developed in the form of

new ARB extensions together with OpenGL 4.2. In addition, many people participated in developing earlier vendor and EXT extensions on which the OpenGL 4.2 functionality is based in part; those individuals are listed in the respective extension specifications in the OpenGL Extension Registry.

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Pat Brown, NVIDIA Corporation (ARB\_shader\_image\_load\_store, ARB\_shading\_language\_packing)  
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The ARB gratefully acknowledges administrative support by the members of Gold Standard Group, including Andrew Riegel, Elizabeth Riegel, Glenn Fredericks, and Michelle Clark, and technical support from James Riordon, webmaster of Khronos.org and OpenGL.org.

# Appendix F

## Version 4.3

OpenGL version 4.3, released on August 6, 2012, is the fifteenth revision since the original version 1.0.

Separate versions of the OpenGL 4.3 Specification exist for the *core profile* and *compatibility profile* described in appendix D, respectively subtitled the “Core Profile” and the “Compatibility Profile”. This document describes the Core Profile. An OpenGL 4.3 implementation *must* be able to create a context supporting the core profile, and may also be able to create a context supporting the compatibility profile.

Material specific to the compatibility profile specification is marked in a distinct color to clearly call out differences between the two profiles.

The OpenGL 4.3 compatibility and core profiles are upward compatible with the OpenGL 4.2 compatibility and core profiles, respectively (see appendix E).

Following are brief descriptions of changes and additions to OpenGL 4.3. Descriptions of changes and additions in versions of OpenGL prior to 4.2 are omitted in this Specification, but may be found in the OpenGL 3.0 Specification (for features in versions 1.0 - 3.0, inclusive) and the OpenGL 4.2 Specification (for features in versions 3.1 - 4.1, inclusive). These Specifications are available in the OpenGL Registry.

### F.1 Restructuring

The Specification has been substantially restructured to introduce high-level concepts and describe objects before their use, and more cleanly split descriptions of programmable and fixed-function processing. Chapter and section numbering has been aligned between the two profile Specifications so that a section number will always refer to the same concept in both profiles (although that section may be



empty in the core profile).

## F.2 New Features

New features in OpenGL 4.3, including the extension or extensions if any on which they were based, include:

- ARB\_arrays\_of\_arrays (OpenGL Shading Language only)
- ARB\_ES3\_compatibility
- ARB\_clear\_buffer\_object
- ARB\_compute\_shader
- ARB\_copy\_image
- ARB\_debug\_group
- ARB\_debug\_label
- ARB\_debug\_output2
- ARB\_debug\_output
- ARB\_explicit\_uniform\_location
- ARB\_fragment\_layer\_viewport (OpenGL Shading Language only)
- ARB\_framebuffer\_no\_attachments
- ARB\_internalformat\_query2
- ARB\_invalidate\_subdata
- ARB\_multi\_draw\_indirect
- ARB\_program\_interface\_query
- ARB\_robust\_buffer\_access\_behavior
- ARB\_shader\_image\_size (OpenGL Shading Language only)
- ARB\_shader\_storage\_buffer\_object
- ARB\_stencil\_texturing

- ARB\_texture\_buffer\_range
- ARB\_texture\_query\_levels
- ARB\_texture\_storage\_multisample
- ARB\_texture\_view
- ARB\_vertex\_attrib\_binding
- Add VERTEX\_ATTRIB\_ARRAY\_LONG query for whether a vertex attribute is stored as an unconverted double (Bug 8272).
- Add queries for #version strings of all OpenGL Shading Language versions supported by the GL (Bug 7811).
- Increase required number of uniform blocks per program stage from 12 to 14 (Bug 8891).

### F.3 Deprecation Model

The following features are deprecated by the OpenGL 4.3 core profile.

- Bitmap pack/unpack state for bitmaps - the pixel pack parameters UNPACK\_LSB\_FIRST PACK\_LSB\_FIRST and (see sections 8.4.1 and 18.2).

The following features which were previously deprecated have been reintroduced to the OpenGL 4.3 core profile:

- The **GetPointerv** command (see section 22.2) and the STACK\_OVERFLOW and STACK\_UNDERFLOW errors (see table 2.3). These features are used by the debug functionality in chapter 20.

Other features deprecated by OpenGL 4.2 remain deprecated, but have not yet been removed.

### F.4 Changed Tokens

New token names are introduced to be used in place of old, less general names. However, the old token names continue to be supported, for backwards compatibility with code written for previous versions of OpenGL. The new names, and the old names they replace, are shown in table F.1.

New Token Name	Old Token Name
MAX_COMBINED_SHADER_OUTPUT_RESOURCES	MAX_COMBINED_IMAGE_UNITS_AND_FRAGMENT_OUTPUTS

Table F.1: New token names and the old names they replace.

## F.5 Change Log for Released Specifications

Changes in the specification update of February 14, 2012:

- Do not perform validity checks on the **BindBufferRange** *size* and *offset* arguments when a zero *buffer* is specified to unbind a buffer, in section 6.1.1 (Bug 9765).
- Clean up descriptions of **BindBufferBase** in section 6.1.1 so it is described without reference to **BindBufferRange**, and note in section 6.7.1 that a zero size query result for a buffer binding is a sentinel indicating the entire buffer is bound (Bug 9513).
- Fix typo in error descriptions in section 6.7 (Bug 9720).
- Update section 6.8 to reference the tables of buffer binding state of different types, and move uniform buffer binding state from table 23.35 to new table 23.49 to match (Bug 9566).
- Clarify that **Uniform\*d** cannot be used to load uniforms with `boolean` types in section 7.6.1 (Bug 9345).
- Added double-precision matrix types to the description of uniform buffer object storage layouts in section 7.6.2.1, and cleaned up description of the matrix stride and how to query it (Bug 9375).
- Correct off-by-one error for valid range of sampler values in introduction to section 7.10 (Bug 8905).
- Clarify in section 7.14 that table 23.43 is not part of program object state, and update the table caption to match (Bug 9781).
- Clarify description of the *data* argument to **TexSubImage\*** in section 8.6 so that it may not be `NULL`, unlike **TexImage\*** (Bug 9750).
- Fix typo in description of **TexParameter\*** in section 8.10 (Bug 9625).

- Add a color-renderable column to table 8.12 and modify section 9.4 to define color-renderable formats with respect to the table, rather than with respect to base formats. This results in the `RGB9_E5` format no longer being color-renderable, which was an error (Bug 9338).
- Allow vector forms of **TexParameter\*** to be used to set scalar parameters in section 8.10, reversing an old spec change made in error (vector parameters, however, still cannot be set with the scalar calls) (Bug 7346).
- Restore missing clamp for  $D_t$  and  $D_{ref}$  (depth texture comparison mode parameters) in section 8.22.1 when using a fixed-point texture (Bug 7975).
- Correct *exp<sub>shared</sub>* to *exp<sub>s</sub>* terminology and include missing  $N$  term when describing shared exponent texture color conversion and final conversion in sections 8.24 and 18.2.6 (Bug 9486).
- Specify that `FRAMEBUFFER` is equivalent to `DRAW_FRAMEBUFFER` for **GetFramebufferParameteriv** in section 9.2.3 (Bug 9344).
- Added `STENCIL_INDEX8` as a required stencil-only renderbuffer format in sections 9.2.5 and 9.4.3, for compatibility with OpenGL ES 3.0 (Bug 9418).
- Fixes to description of isoline tessellation in section 11.2.2.3 to describe use of outer tessellation levels in the correct order (Bug 9607).
- Clamp values at specification time for **DepthRange\*** (section 13.6.1) and **ClearDepth** (section 17.4.3), to avoid subtle issues when using floating-point depth buffers. However, this change does not reintroduce use of the `clampf` and `clampd` types eliminated in OpenGL 4.2 (Bug 9517).
- Change **DrawBuffer** error for `COLOR_ATTACHMENT $m$`  out of range from `INVALID_VALUE` to `INVALID_OPERATION` in section 17.4.1, to match **DrawBuffers** and OpenGL ES 3.0 (Bug 8568).
- Modify language describing buffer writes in section 17.4.1 so that fragment colors are not written only to draw buffers with no color attachment, or with `NONE` as the draw buffer, allowing writes to other draw buffers to succeed. Specify that when only some output variables are written, only the fragment colors corresponding to unwritten variables are undefined (Bug 9494).
- Allow attachment parameters to **InvalidateSubFramebuffer** in section 17.4.4 to include `DEPTH_STENCIL_ATTACHMENT` (Bug 9480).

- Specify that the **BlitFramebuffer** *mask* may be zero in section 18.3.1 (Bug 9748).
- Cleaned up language describing parameters to **DebugMessageControl** in section 20.4 to avoid triple negatives (Bug 9392).
- Increase minimum value for `MAX_UNIFORM_BUFFER_BINDINGS` to 84 in table 23.63 to account for correct number of bindings/stage (14) (Bug 9424).

Changes in the released Specification of August 6, 2012:

- Restructured as described in section F.1.
- Added new features as described in section F.2.
- Add title image page using the “pipeline metro” diagram.
- Miscellaneous minor typos and fixes to better match OpenGL ES 3.0 spec language (Bugs 7885, 7904, 7919).
- Changed “rectangular texture” to “rectangle texture” throughout the spec for consistency (Bug 9262). Other consistency changes including using “equivalent to” consistently for pseudocode samples defining the operation of a command.
- Many cleanups and additions to error language throughout the spec to add previously implicit errors explicitly (however, this is still a work in progress). In particular, added explicit errors for all commands taking *program* or *shader* arguments as described at the start of section 7.1, and for commands taking *shadertype* arguments (Bug 9145); and added explicit `INVALID_VALUE` errors for negative values of `sizei` and `sizeiptr` arguments (Bug 9320).
- Cleaned up description of function prototypes from the old `T` notation to `T *` or `const T *` as appropriate for the actual C binding of the corresponding command.
- Added `NUM_SHADING_LANGUAGE_VERSIONS` and `SHADING_LANGUAGE_VERSION` queries for supported GLSL `#version` strings in sections 1.3.1, 1.3.3 and 22.2, and in table 23.56 (see Bug 7811). Still need enum assignments for these.
- Remove assertion that draw and read framebuffers must be of the same class in section 2.1 (Bug 9134).

- Clarify in the caption to table 2.2 that `sync` is defined as a pointer type in the C binding (Bug 9140).
- Reintroduced `STACK_OVERFLOW` and `STACK_UNDERFLOW` errors to the core profile in table 2.3, since they are used by the debug group APIs (Bug 9158).
- Describe new, more complete error summary and typesetting style in section 2.3.1. Convert (most) error summaries beginning with section 4.1, adding implicit error conditions that have not been described with the commands they apply to before. This is a work in progress.
- Clean up query objects in section 4.2 to clarify that `TIME_ELAPSED` and `TIMESTAMP` queries are different type of queries, and remove an inapplicable error condition for `TIMESTAMP` queries (Bug 9268).
- Add language to **DeleteBuffers** in section 6 and **BufferData** in section 6.2 specifying that these commands cause any existing mappings of a buffer being operated on in any context to be unmapped, per a rather offhand reference in section 6.3.1 (Bug 9323).
- Restore `COPY_READ_BUFFER` and `COPY_WRITE_BUFFER` as buffer *target* names in sections 6.1 and 6.6. The `_BINDING` aliases are used only when querying those binding points (Bugs 8475,9115).
- Bring compute shader language in sync with changes to the extension spec. In particular, add `DISPATCH_INDIRECT_BUFFER` binding section 6.1, describe it in section 10.3.10, update **DispatchComputeIndirect** to use it in section 19, add new table 23.52, and update aggregate shader limits in section 23.63 (Bug 9130).
- Add create-on-bind behavior for **BindBufferRange** and **BindBufferBase** in section 6.1.1, mirroring **BindBuffer** (Bug 9216).
- Clarify that offset and alignment constraints for **ClearBufferSubData** in section 6.2.1 are based on the total size of a texel of type *internalformat* (size of base type times no. of components) (Bug 9211).
- Update errors for **ClearBuffer\*Data** and mention them and **InvalidateBuffer\*Data** among the commands that can modify buffer object storage in sections 6.2.1, 7.6, 7.8, and 7.12 (Bug 9154).
- Clarify that buffer mappings are not affected by whether or not a context is current in section 6.3.1 (Bug 9323).

- Add language in section 6.3.2 specifying that commands which write to (as well as read from) mapped buffers are also supposed to generate errors (Bug 9115).
- Make **InvalidateBuffer\*Data** generate errors for invalid object handles in section 6.5 (Bug 9341).
- Merge description of different types of indexed array buffer bindings into section 6.7.1, and move description of *target*-specific **BindBufferRange** errors into section 6.1.1 with reference to section 6.7.1 (Bug 9115 and general cleanup).
- Extend **ShaderBinary** in section 7.2 to allow support for shader binary formats including all shader types, not just vertex and fragment shaders (Bug 9282).
- Add description of “top-level arrays” to active shader storage block discussion in section 7.3.1 (Bug 9115). This probably needs to migrate back to the extension as well, along with a few other language changes in this section which Pat suggested in his PDF review but hasn’t put into the extension yet.
- Clarify error descriptions for **UseProgramStages** and **ActiveShaderProgram** (section 7.4), **UseProgram** (section 7.6.1), and **ProgramUniform\*** (section 7.6.1) to generate an `INVALID_OPERATION` error “if *program* has not been linked, or was last linked unsuccessfully” rather than “if *program* has not been successfully linked” (Bug 8640, tracking similar changes to other commands previously).
- Merge similar descriptions of uniform variable component limits for each separate shader stage into section 7.6.
- Fix nonexistent token `ATOMIC_COUNTER_ARRAY_STRIDE` to `UNIFORM_ARRAY_STRIDE` in section 7.7.1 (Bug 9346).
- Removed redundant definition of **GetSubroutineUniformLocation** from the beginning of section 7.9.
- Added `INVALID_VALUE` error in section 7.10 if **Uniform1i{v}** is used to set a sampler to a value less than zero or greater than or equal to the value of `MAX_COMBINED_TEXTURE_IMAGE_UNITS`, matching the similar error for setting image uniforms.
- Add `VERTEX_ATTRIB_ARRAY_LONG` state in section 7.13 and table 23.3 (Bug 8272).

- Add all specific compressed texture formats to the required format list in section 8.5.1. Include EAC and ETC2 format in specific format language in table 8.14 and sections 8.6, 8.7, and 8.23 (Bug 9156).
- Add additional `INVALID_OPERATION` errors depending on odd combinations of read buffer and FBO state for **CopyTexImage\*** and **CopyTexSubImage\*** in section 8.6 (Bug 8559).
- Disallow **CopyTexImage\*** between sRGB and linear formats in section 8.6, and define **BlitFramebuffer** to linearize sRGB data from the read buffer in section 18.3.1 (Bug 8560).
- Allow multisample texture targets as arguments to **TexParameter\*** in section 8.10, with additional error conditions when attempting to set a disallowed min filter or base level parameter value.
- Replace listings of all six cube map face selection targets with references to tables 8.18 or 9.3, in several places throughout the spec.
- Fix error generated for invalid texture handle passed to **TextureView** in section 8.18 (Bug 9337)
- Tweaked descriptions of transferring vertices in sections 10.3.3 and 10.5 to more closely match OpenGL ES 3.0 (Bug 8686).
- Restore missing description of **DrawElementsInstanced** in section 10.5.
- Renamed the formal parameter *primcount* to *instancecount* for **DrawArraysInstancedBaseInstance**, **DrawArraysInstanced**, **DrawElementsInstancedBaseInstance**, **DrawElementsInstanced**, **DrawElementsInstancedBaseVertex**, and **DrawElementsInstancedBaseVertexBaseInstance** (section 10.5), and for **DrawTransformFeedbackInstanced** and **DrawTransformFeedbackStreamInstanced** (section 13.2.3). Used equivalent terminology in the pseudocode descriptions of **DrawElementsIndirect** and **DrawArraysIndirect** (section 10.5). Renamed the formal parameter *primcount* to *drawcount* for **MultiDrawArrays**, **MultiDrawArraysIndirect**, **MultiDrawElements**, **MultiDrawElementsIndirect**, **MultiDrawElementsBaseVertex** (section 10.5) (Bug 9230).
- Moved description of **GetVertexAttrib\*** into section 10.6 (Bug 9115).



- Specify in section 11.1.1 that special built-in inputs and outputs such as `gl_VertexID` should be enumerated in the `PROGRAM_INPUT` and `PROGRAM_OUTPUT` interfaces, as well as the legacy function `GetActiveAttrib`. Add spec language counting the built-ins `gl_VertexID` and `gl_InstanceID` against the active attribute limit (Bug 9201).
- Swap order of tessellation levels in describing isoline tessellation in section 11.2.2.3, to match actual hardware (Bug 9195).
- Remove language about deferred deletion for `DeleteTransformFeedbacks` in section 13.2.1 (Bug 8948).
- Add transform feedback-related error for `ProgramBinary` (matching existing error for `LinkProgram` in section 13.2.2 when *program* is the name of a program being used by one or more transform feedback objects (Bug 7928).
- Add description of `MAX_COMPUTE_SHARED_MEMORY_SIZE` in section 19.1, lifted from GLSL spec (Bug 9069).
- Add description of the type of the debug callback function, including platform-dependent calling conventions, in section 20.2. 21.1
- Remove inaccurate description of GLSL version string sort order in section 22.2. Instead, ensure that the most recent GLSL version corresponding to the context profile is returned first, and other entries have no defined ordering (Bug 7811).
- Change  $Z_n$  terminology used in state tables to describe enumerated state with  $n$  possible values to  $E$  throughout, since maintaining the  $n$  was always tricky as features were added and the possible values are fully described in the spec body. This affects hundreds of state table entries as well as adding a description of  $E$  in table 23.1.
- Move `IMPLEMENTATION_COLOR_READ_FORMAT` and `IMPLEMENTATION_COLOR_READ_TYPE` from table 23.73 to table 23.53 since they are not framebuffer-dependent values, unlike OpenGL ES (Bug 8561).
- Increased minimum values for `MAX_VERTEX_UNIFORM_BLOCKS`, `MAX_TESS_CONTROL_UNIFORM_BLOCKS`, `MAX_TESS_EVALUATION_UNIFORM_BLOCKS`, `MAX_GEOMETRY_UNIFORM_BLOCKS`, `MAX_FRAGMENT_UNIFORM_BLOCKS`, and `MAX_COMPUTE_UNIFORM_BLOCKS` to 14 in tables 23.57, 23.58, 23.59, 23.60, 23.61, and 23.62 respectively, and of `MAX_COMBINED_UNIFORM_BLOCKS` to 70 in table 23.63 (Bug 8891).

- Added `UNPACK_LSB_FIRST` and `PACK_LSB_FIRST` state to the deprecated features list in section F.3 (Bug 7865).

## F.6 Credits

OpenGL 4.3 is the result of the contributions of many people and companies. Members of the Khronos OpenGL ARB Working Group during the development of OpenGL 4.3, including the company that they represented at the time of their contributions, follow.

Some major contributions made by individuals are listed together with their name, including specific functionality developed in the form of new ARB extensions together with OpenGL 4.3. In addition, many people participated in developing earlier vendor and EXT extensions on which the OpenGL 4.3 functionality is based in part; those individuals are listed in the respective extension specifications in the OpenGL Registry.

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 Christophe Riccio (ARB\_debug\_group, ARB\_debug\_label, ARB\_shader\_image\_size, ARB\_texture\_query\_levels, KHR\_debug\_output)  
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Michael Gold, NVIDIA (ARB\_copy\_image)  
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Richard Schreyer, Apple  
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Thomas Volk, NVIDIA  
Tim Johansson, Opera  
Vladimir Vukicevic, Mozilla  
Yaki Tebeka, Graphic Remedy  
Yuan Wang, IMG

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The “pipeline metro” cover image was created by Dominic Agoro-Ombaka of Gold Standard Group.

## Appendix G

# OpenGL Registry, Header Files, and ARB Extensions

### G.1 OpenGL Registry

Many extensions to the OpenGL API have been defined by vendors, groups of vendors, and the OpenGL ARB. In order not to compromise the readability of the OpenGL Specification, such extensions are not integrated into the core language; instead, they are made available online in the *OpenGL Registry*, together with extensions to window system binding APIs, such as GLX and WGL, and with specifications for OpenGL, GLX, and related APIs.

Extensions are documented as changes to a particular version of the Specification. The Registry is available on the World Wide Web at URL

<http://www.opengl.org/registry/>

### G.2 Header Files

Historically, C and C++ source code calling OpenGL was to `#include` a single header file, `<GL/gl.h>`. In addition to the core OpenGL API, the APIs for all extensions provided by an implementation were defined in this header.

When platforms became common where the OpenGL SDK (library and header files) were not necessarily obtained from the same source as the OpenGL driver, such as Microsoft Windows and Linux, `<GL/gl.h>` could not always be kept in sync with new core API versions and extensions supported by drivers. At this time the OpenGL ARB defined a new header, `<GL/glext.h>`, which could be obtained directly from the OpenGL Registry (see section [G.1](#)). The combination

of `<GL/gl.h>` and `<GL/glext.h>` always defines all APIs for all profiles of the latest OpenGL version, as well as for all extensions defined in the Registry.

`<GL/glcorearb.h>` defines APIs for the core profile of OpenGL, together with ARB extensions compatible with the core profile. It does not include APIs for features only in the compatibility profile or for other extensions.

There is currently no Khronos-supported mechanism for using vendor extensions together with `<GL/glcorearb.h>`, due to lack of demand and lack of knowledge on which vendor extensions are compatible with the core profile. In the future, this may be addressed by a hypothetical header `<GL/glcext.h>` which would define APIs for additional EXT and vendor extensions compatible with the core profile, but not defined in `<GL/glcorearb.h>`. Most older extensions are not compatible with the core profile.

Applications using the compatibility profile (see appendix D) should `#include` the traditional `<GL/gl.h>` and `<GL/glext.h>` headers.

Applications using the core profile, and which do not need to use vendor extensions, may instead `#include` the `<GL/glcorearb.h>` header.

By using `<GL/glcorearb.h>`, instead of the legacy `<GL/gl.h>` and `<GL/glext.h>`, newly developed applications are given increased protection against accidentally using a legacy feature that has been removed from the core profile, and against using a less portable EXT or vendor extension. This can assist in developing applications on a GL implementation that supports the compatibility profile when the application is also intended to run on other platforms supporting only the core profile.

Developers should always be able to download `<GL/glcorearb.h>` from the Registry, with this headers replacing, or being used in place of older versions that may be provided by a platform SDK.

### G.3 ARB and Khronos Extensions

OpenGL extensions that have been approved by the Khronos OpenGL Architectural Review Board Working Group (ARB), or jointly approved by the ARB and the Khronos OpenGL ES Working Group (KHR), are summarized in this section. ARB and KHR extensions are not required to be supported by a conformant OpenGL implementation, but are expected to be widely available; they define functionality that is likely to move into the required feature set in a future revision of the specification.

### G.3.1 Naming Conventions

To distinguish ARB and KHR extensions from core OpenGL features and from vendor-specific extensions, the following naming conventions are used:

- A unique *name string* of the form "GL\_ARB\_name" or "GL\_KHR\_name" is associated with each extension. If the extension is supported by an implementation, this string will be among the EXTENSIONS strings returned by **GetStringi**, as described in section 22.2.
- All functions defined by the extension will have names of the form **FunctionARB** or **FunctionKHR**, respectively.
- All enumerants defined by the extension will have names of the form NAME\_ARB. or NAME\_KHR, respectively.
- In addition to OpenGL extensions, there are also ARB extensions to the related GLX and WGL APIs. Such extensions have name strings prefixed by "GLX\_" and "WGL\_" respectively. Not all GLX and WGL ARB extensions are described here, but all such extensions are included in the registry.

### G.3.2 Promoting Extensions to Core Features

Extensions can be *promoted* to required core features in later revisions of OpenGL. When this occurs, the extension specifications are merged into the core specification. Functions and enumerants that are part of such promoted extensions will have the **ARB**, **KHR**, **EXT**, or vendor affix removed.

Implementations of such later revisions should continue to export the name strings of promoted extensions in the EXTENSIONS strings and continue to support the affixed versions of functions and enumerants as a transition aid.

For descriptions of extensions promoted to core features in OpenGL 1.3 and beyond, see the corresponding version of the OpenGL specification, or the descriptions of that version in version-specific appendices to later versions of the specification.

### G.3.3 Extension Summaries

This section describes each ARB and KHR extension briefly. In most cases, the functionality of these extensions also was added to a version of the OpenGL Specification, and in these cases only the extension string is described, together with the corresponding OpenGL version.

**G.3.3.1 Multitexture**

The name string for multitexture is `GL_ARB_multitexture`. It was promoted to a core feature in OpenGL 1.3.

**G.3.3.2 Transpose Matrix**

The name string for transpose matrix is `GL_ARB_transpose_matrix`. It was promoted to a core feature in OpenGL 1.3.

**G.3.3.3 Multisample**

The name string for multisample is `GL_ARB_multisample`. It was promoted to a core feature in OpenGL 1.3.

**G.3.3.4 Texture Add Environment Mode**

The name string for texture add mode is `GL_ARB_texture_env_add`. It was promoted to a core feature in OpenGL 1.3.

**G.3.3.5 Cube Map Textures**

The name string for cube mapping is `GL_ARB_texture_cube_map`. It was promoted to a core feature in OpenGL 1.3.

**G.3.3.6 Compressed Textures**

The name string for compressed textures is `GL_ARB_texture_compression`. It was promoted to a core feature in OpenGL 1.3.

**G.3.3.7 Texture Border Clamp**

The name string for texture border clamp is `GL_ARB_texture_border_clamp`. It was promoted to a core feature in OpenGL 1.3.

**G.3.3.8 Point Parameters**

The name string for point parameters is `GL_ARB_point_parameters`. It was promoted to a core features in OpenGL 1.4.



### **G.3.3.9 Vertex Blend**

Vertex blending replaces the single model-view transformation with multiple vertex units. Each unit has its own transform matrix and an associated current weight. Vertices are transformed by all the enabled units, scaled by their respective weights, and summed to create the eye-space vertex. Normals are similarly transformed by the inverse transpose of the model-view matrices.

The name string for vertex blend is `GL_ARB_vertex_blend`.

### **G.3.3.10 Matrix Palette**

Matrix palette extends vertex blending to include a palette of model-view matrices. Each vertex may be transformed by a different set of matrices chosen from the palette.

The name string for matrix palette is `GL_ARB_matrix_palette`.

### **G.3.3.11 Texture Combine Environment Mode**

The name string for texture combine mode is `GL_ARB_texture_env_combine`. It was promoted to a core feature in OpenGL 1.3.

### **G.3.3.12 Texture Crossbar Environment Mode**

The name string for texture crossbar is `GL_ARB_texture_env_crossbar`. It was promoted to a core features in OpenGL 1.4.

### **G.3.3.13 Texture Dot3 Environment Mode**

The name string for DOT3 is `GL_ARB_texture_env_dot3`. It was promoted to a core feature in OpenGL 1.3.

### **G.3.3.14 Texture Mirrored Repeat**

The name string for texture mirrored repeat is `GL_ARB_texture_mirrored_repeat`. It was promoted to a core feature in OpenGL 1.4.

### **G.3.3.15 Depth Texture**

The name string for depth texture is `GL_ARB_depth_texture`. It was promoted to a core feature in OpenGL 1.4.

### G.3.3.16 Shadow

The name string for shadow is `GL_ARB_shadow`. It was promoted to a core feature in OpenGL 1.4.

### G.3.3.17 Shadow Ambient

Shadow ambient extends the basic image-based shadow functionality by allowing a texture value specified by the `TEXTURE_COMPARE_FAIL_VALUE_ARB` texture parameter to be returned when the texture comparison fails. This may be used for ambient lighting of shadowed fragments and other advanced lighting effects.

The name string for shadow ambient is `GL_ARB_shadow_ambient`.

### G.3.3.18 Window Raster Position

The name string for window raster position is `GL_ARB_window_pos`. It was promoted to a core feature in OpenGL 1.4.

### G.3.3.19 Low-Level Vertex Programming

Application-defined *vertex programs* may be specified in a new low-level programming language, replacing the standard fixed-function vertex transformation, lighting, and texture coordinate generation pipeline. Vertex programs enable many new effects and are an important first step towards future graphics pipelines that will be fully programmable in an unrestricted, high-level shading language.

The name string for low-level vertex programming is `GL_ARB_vertex_program`.

### G.3.3.20 Low-Level Fragment Programming

Application-defined *fragment programs* may be specified in the same low-level language as `GL_ARB_vertex_program`, replacing the standard fixed-function vertex texturing, fog, and color sum operations.

The name string for low-level fragment programming is `GL_ARB_fragment_program`.

### G.3.3.21 Buffer Objects

The name string for buffer objects is `GL_ARB_vertex_buffer_object`. It was promoted to a core feature in OpenGL 1.5.

**G.3.3.22 Occlusion Queries**

The name string for occlusion queries is `GL_ARB_occlusion_query`. It was promoted to a core feature in OpenGL 1.5.

**G.3.3.23 Shader Objects**

The name string for shader objects is `GL_ARB_shader_objects`. It was promoted to a core feature in OpenGL 2.0.

**G.3.3.24 High-Level Vertex Programming**

The name string for high-level vertex programming is `GL_ARB_vertex_shader`. It was promoted to a core feature in OpenGL 2.0.

**G.3.3.25 High-Level Fragment Programming**

The name string for high-level fragment programming is `GL_ARB_fragment_shader`. It was promoted to a core feature in OpenGL 2.0.

**G.3.3.26 OpenGL Shading Language**

The name string for the OpenGL Shading Language is `GL_ARB_shading_language_100`. The presence of this extension string indicates that programs written in version 1 of the Shading Language are accepted by OpenGL. It was promoted to a core feature in OpenGL 2.0.

**G.3.3.27 Non-Power-Of-Two Textures**

The name string for non-power-of-two textures is `GL_ARB_texture_non_power_of_two`. It was promoted to a core feature in OpenGL 2.0.

**G.3.3.28 Point Sprites**

The name string for point sprites is `GL_ARB_point_sprite`. It was promoted to a core feature in OpenGL 2.0.

**G.3.3.29 Fragment Program Shadow**

Fragment program shadow extends low-level fragment programs defined with `GL_ARB_fragment_program` to add shadow 1D, 2D, and 3D texture targets, and remove the interaction with `GL_ARB_shadow`.

The name string for fragment program shadow is `GL_ARB_fragment_program_shadow`.

### G.3.3.30 Multiple Render Targets

The name string for multiple render targets is `GL_ARB_draw_buffers`. It was promoted to a core feature in OpenGL 2.0.

### G.3.3.31 Rectangle Textures

Rectangle textures define a new texture target `TEXTURE_RECTANGLE_ARB` that supports 2D textures without requiring power-of-two dimensions. Rectangle textures are useful for storing video images that do not have power-of-two sizes (POTS). Resampling artifacts are avoided and less texture memory may be required. They are also useful for shadow maps and window-space texturing. These textures are accessed by dimension-dependent (aka non-normalized) texture coordinates.

Rectangle textures are a restricted version of non-power-of-two textures. The differences are that rectangle textures are supported only for 2D; they require a new texture target; and the new target uses non-normalized texture coordinates.

The name string for texture rectangles is `GL_ARB_texture_rectangle`. It was promoted to a core feature in OpenGL 3.1.

### G.3.3.32 Floating-Point Color Buffers

Floating-point color buffers can represent values outside the normal  $[0, 1]$  range of colors in the fixed-function OpenGL pipeline. This group of related extensions enables controlling clamping of vertex colors, fragment colors throughout the pipeline, and pixel data read back to client memory, and also includes WGL and GLX extensions for creating frame buffers with floating-point color components (referred to in GLX as *framebuffer configurations*, and in WGL as *pixel formats*).

The name strings for floating-point color buffers are `GL_ARB_color_buffer_float`, `GLX_ARB_fbconfig_float`, and `WGL_ARB_pixel_format_float`. `GL_ARB_color_buffer_float` was promoted to a core feature in OpenGL 3.0.

### G.3.3.33 Half-Precision Floating Point

This extension defines the representation of a 16-bit floating-point data format, and a corresponding *type* argument which may be used to specify and read back pixel and texture images stored in this format in client memory. Half-precision floats are

smaller than full precision floats, but provide a larger dynamic range than similarly sized (`short`) data types.

The name string for half-precision floating-point is `GL_ARB_half_float_pixel`. It was promoted to a core feature in OpenGL 3.0.

#### **G.3.3.34 Floating-Point Textures**

Floating-point textures stored in both 32- and 16-bit formats may be defined using new *internalformat* arguments to commands which specify and read back texture images.

The name string for floating-point textures is `GL_ARB_texture_float`. It was promoted to a core feature in OpenGL 3.0.

#### **G.3.3.35 Pixel Buffer Objects**

The buffer object interface is expanded by adding two new binding targets for buffer objects, the pixel pack and unpack buffers. This permits buffer objects to be used to store pixel data as well as vertex array data. Pixel-drawing and -reading commands using data in pixel buffer objects may operate at greatly improved performance compared to data in client memory.

The name string for pixel buffer objects is `GL_ARB_pixel_buffer_object`. It was promoted to a core feature in OpenGL 2.1.

#### **G.3.3.36 Floating-Point Depth Buffers**

The name string for floating-point depth buffers is `GL_ARB_depth_buffer_float`. This extension is equivalent to new core functionality introduced in OpenGL 3.0, based on the earlier `GL_NV_depth_buffer_float` extension, and is provided to enable this functionality in older drivers.

#### **G.3.3.37 Instanced Rendering**

The name string for instanced rendering is `GL_ARB_draw_instanced`. It was promoted to a core feature in OpenGL 3.1.

#### **G.3.3.38 Framebuffer Objects**

The name string for framebuffer objects is `GL_ARB_framebuffer_object`. This extension is equivalent to new core functionality introduced in OpenGL 3.0, based

on the earlier `GL_EXT_framebuffer_object`, `GL_EXT_framebuffer_multisample`, and `GL_EXT_framebuffer_blit` extensions, and is provided to enable this functionality in older drivers.

#### **G.3.3.39 sRGB Framebuffers**

The name string for sRGB framebuffers is `GL_ARB_framebuffer_sRGB`. It was promoted to a core feature in OpenGL 3.0. This extension is equivalent to new core functionality introduced in OpenGL 3.0, based on the earlier `GL_EXT_framebuffer_sRGB` extension, and is provided to enable this functionality in older drivers.

To create sRGB format surfaces for use on display devices, an additional pixel format (config) attribute is required in the window system integration layer. The name strings for the GLX and WGL sRGB pixel format interfaces are `GLX_ARB_framebuffer_sRGB` and `WGL_ARB_framebuffer_sRGB` respectively.

#### **G.3.3.40 Geometry Shaders**

This extension defines a new shader type called a *geometry shader*. Geometry shaders are run after vertices are transformed, but prior to the remaining fixed-function vertex processing, and may generate new vertices for, or remove vertices from the primitive assembly process.

The name string for geometry shaders is `GL_ARB_geometry_shader4`. It was promoted to a core feature in OpenGL 3.2.

#### **G.3.3.41 Half-Precision Vertex Data**

The name string for half-precision vertex data is `GL_ARB_half_float_vertex`. This extension is equivalent to new core functionality introduced in OpenGL 3.0, based on the earlier `GL_NV_half_float` extension, and is provided to enable this functionality in older drivers.

#### **G.3.3.42 Instanced Rendering**

This instanced rendering interface is a less-capable form of `GL_ARB_draw_instanced` which can be supported on older hardware.

The name string for instanced rendering is `GL_ARB_instanced_arrays`. It was promoted to a core feature in OpenGL 3.3.

#### **G.3.3.43 Flexible Buffer Mapping**

The name string for flexible buffer mapping is `GL_ARB_map_buffer_range`. This extension is equivalent to new core functionality introduced in OpenGL 3.0, based on the earlier `GL_APPLE_flush_buffer_range` extension, and is provided to enable this functionality in older drivers.

#### **G.3.3.44 Texture Buffer Objects**

The name string for texture buffer objects is `GL_ARB_texture_buffer_object`. It was promoted to a core feature in OpenGL 3.1.

#### **G.3.3.45 RGTC Texture Compression Formats**

The name string for RGTC texture compression formats is `GL_ARB_texture_compression_rgtc`. This extension is equivalent to new core functionality introduced in OpenGL 3.0, based on the earlier `GL_EXT_texture_compression_rgtc` extension, and is provided to enable this functionality in older drivers.

It was promoted to a core feature in OpenGL 3.0.

#### **G.3.3.46 One- and Two-Component Texture Formats**

The name string for one- and two-component texture formats is `GL_ARB_texture_rg`. It was promoted to a core feature in OpenGL 3.0. This extension is equivalent to new core functionality introduced in OpenGL 3.0, and is provided to enable this functionality in older drivers.

#### **G.3.3.47 Vertex Array Objects**

The name string for vertex array objects is `GL_ARB_vertex_array_object`. This extension is equivalent to new core functionality introduced in OpenGL 3.0, based on the earlier `GL_APPLE_vertex_array_object` extension, and is provided to enable this functionality in older drivers.

It was promoted to a core feature in OpenGL 3.0.

#### **G.3.3.48 Versioned Context Creation**

Starting with OpenGL 3.0, a new context creation interface is required in the window system integration layer. This interface specifies the context version required as well as other attributes of the context.

The name strings for the GLX and WGL context creation interfaces are `GLX_ARB_create_context` and `WGL_ARB_create_context` respectively.

#### **G.3.3.49 Uniform Buffer Objects**

The name string for uniform buffer objects is `GL_ARB_uniform_buffer_object`. This extension is equivalent to new core functionality introduced in OpenGL 3.1 and is provided to enable this functionality in older drivers.

#### **G.3.3.50 Restoration of features removed from OpenGL 3.0**

OpenGL 3.1 removes a large number of features that were marked deprecated in OpenGL 3.0. GL implementations needing to maintain these features to support existing applications may do so, following the deprecation model, by exporting an extension string indicating those features are present. Applications written for OpenGL 3.1 should not depend on any of the features corresponding to this extension, since they will not be available on all platforms with 3.1 implementations.

The name string for restoration of features deprecated by OpenGL 3.0 is `GL_ARB_compatibility`.

The profile terminology introduced with OpenGL 3.2 eliminates the necessity for evolving this extension. Instead, interactions between features removed by OpenGL 3.1 and new features introduced in later OpenGL versions are defined by the compatibility profile corresponding to those versions.

#### **G.3.3.51 Fast Buffer-to-Buffer Copies**

The name string for fast buffer-to-buffer copies is `GL_ARB_copy_buffer`. This extension is equivalent to new core functionality introduced in OpenGL 3.1 and is provided to enable this functionality in older drivers.

#### **G.3.3.52 Shader Texture Level of Detail Control**

The name string for shader texture level of detail control is `GL_ARB_shader_texture_lod`. This extension is equivalent to new core functions introduced in OpenGL Shading Language 1.30 and is provided to enable this functionality in older versions of the shading language.

#### **G.3.3.53 Depth Clamp Control**

The name string for depth clamp control is `GL_ARB_depth_clamp`. This extension is equivalent to new core functionality introduced in OpenGL 3.2 and is provided to enable this functionality in older drivers.



**G.3.3.54 Base Vertex Offset Drawing Commands**

The name string for base vertex offset drawing commands is `GL_ARB_draw_elements_base_vertex`. This extension is equivalent to new core functionality introduced in OpenGL 3.2 and is provided to enable this functionality in older drivers.

**G.3.3.55 Fragment Coordinate Convention Control**

The name string for fragment coordinate convention control is `GL_ARB_fragment_coord_conventions`. This extension is equivalent to new core functionality introduced in OpenGL 3.2 and is provided to enable this functionality in older drivers.

**G.3.3.56 Provoking Vertex Control**

The name string for provoking vertex control is `GL_ARB_provoking_vertex`. This extension is equivalent to new core functionality introduced in OpenGL 3.2 and is provided to enable this functionality in older drivers.

**G.3.3.57 Seamless Cube Maps**

The name string for seamless cube maps is `GL_ARB_seamless_cube_map`. This extension is equivalent to new core functionality introduced in OpenGL 3.2 and is provided to enable this functionality in older drivers.

**G.3.3.58 Fence Sync Objects**

The name string for fence sync objects is `GL_ARB_sync`. This extension is equivalent to new core functionality introduced in OpenGL 3.2 and is provided to enable this functionality in older drivers.

**G.3.3.59 Multisample Textures**

The name string for multisample textures is `GL_ARB_texture_multisample`. This extension is equivalent to new core functionality introduced in OpenGL 3.2 and is provided to enable this functionality in older drivers.

### G.3.3.60 BGRA Attribute Component Ordering

The name string for BGRA attribute component ordering is `GL_ARB_vertex_array_bgra`. This extension is equivalent to new core functionality introduced in OpenGL 3.2 and is provided to enable this functionality in older drivers.

### G.3.3.61 Per-Buffer Blend Control

The blending interface is extended to specify blend equation and blend function on a per-draw-buffer basis.

The name string for per-buffer blend control is `GL_ARB_draw_buffers_blend`. It was promoted to a core feature in OpenGL 4.0.

### G.3.3.62 Sample Shading Control

Sample shading control adds the ability to request that an implementation use a minimum number of unique sets of fragment computation inputs when multisampling a pixel.

The name string for sample shading control is `GL_ARB_sample_shading`. It was promoted to a core feature in OpenGL 4.0.

### G.3.3.63 Cube Map Array Textures

A cube map array texture is a two-dimensional array texture that may contain many cube map layers. Each cube map layer is a unique cube map image set.

The name string for cube map array textures is `GL_ARB_texture_cube_map_array`. It was promoted to a core feature in OpenGL 4.0.

### G.3.3.64 Texture Gather

Texture gather adds a new set of texture functions (`textureGather`) to the OpenGL Shading Language that determine the  $2 \times 2$  footprint used for linear filtering in a texture lookup, and return a vector consisting of the first component from each of the four texels in the footprint.

The name string for texture gather is `GL_ARB_texture_gather`. It was promoted to a core feature in OpenGL 4.0.

### G.3.3.65 Texture Level-Of-Detail Queries

Texture level-of-detail queries adds a new set of fragment shader texture functions (`textureLOD`) to the OpenGL Shading Language that return the results of au-

automatic level-of-detail computations that would be performed if a texture lookup were to be done.

The name string for texture level-of-detail queries is `GL_ARB_texture_query_lod`.

### **G.3.3.66 Profiled Context Creation**

Starting with OpenGL 3.2, API profiles are defined. Profiled context creation extends the versioned context creation interface to specify a profile which must be implemented by the context.

The name strings for the GLX and WGL profiled context creation interfaces are `GLX_ARB_create_context_profile` and `WGL_ARB_create_context_profile` respectively.

### **G.3.3.67 Shading Language Include**

Shading language include adds support for `#include` directives to shaders, and a named string API for defining the text corresponding to `#include` pathnames.

The name string for shading language include is `GL_ARB_shading_language_include`.

### **G.3.3.68 BPTC texture compression**

BPTC texture compression provides new block compressed specific texture formats which can improve quality in images with sharp edges and strong chrominance transitions, and support high dynamic range floating-point formats.

The name string for bptc texture compression is `GL_ARB_texture_compression_bptc`.

### **G.3.3.69 Extended Blend Functions**

The name string for extended blend functions is `GL_ARB_blend_func_extended`. This extension is equivalent to new core functionality introduced in OpenGL 3.3, and is provided to enable this functionality in older drivers.

### **G.3.3.70 Explicit Attribute Location**

The name string for explicit attribute location is `GL_ARB_explicit_attrib_location`. This extension is equivalent to new core functionality introduced in OpenGL 3.3 and is provided to enable this functionality in older drivers.

**G.3.3.71 Boolean Occlusion Queries**

The name string for boolean occlusion queries is `GL_ARB_occlusion_query2`. This extension is equivalent to new core functionality introduced in OpenGL 3.3 and is provided to enable this functionality in older drivers.

**G.3.3.72 Sampler Objects**

The name string for sampler objects is `GL_ARB_sampler_objects`. This extension is equivalent to new core functionality introduced in OpenGL 3.3 and is provided to enable this functionality in older drivers.

**G.3.3.73 Shader Bit Encoding**

The name string for shader bit encoding is `GL_ARB_shader_bit_encoding`. This extension is equivalent to new core functionality introduced in OpenGL 3.3 and is provided to enable this functionality in older drivers.

**G.3.3.74 RGB10A2 Integer Textures**

The name string for RGB10A2 integer textures is `GL_ARB_texture_rgb10_a2ui`. This extension is equivalent to new core functionality introduced in OpenGL 3.3 and is provided to enable this functionality in older drivers.

**G.3.3.75 Texture Swizzle**

The name string for texture swizzle is `GL_ARB_texture_swizzle`. This extension is equivalent to new core functionality introduced in OpenGL 3.3 and is provided to enable this functionality in older drivers.

**G.3.3.76 Timer Queries**

The name string for timer queries is `GL_ARB_timer_query`. This extension is equivalent to new core functionality introduced in OpenGL 3.3 and is provided to enable this functionality in older drivers.

**G.3.3.77 Packed 2.10.10.10 Vertex Formats**

The name string for packed 2.10.10.10 vertex formats is `GL_ARB_vertex_type_2_10_10_10_rev`. This extension is equivalent to new core functionality introduced in OpenGL 3.3 and is provided to enable this functionality in older drivers.

**G.3.3.78 Draw Indirect**

The name string for draw indirect is `GL_ARB_draw_indirect`. This extension is equivalent to new core functionality introduced in OpenGL 4.0 and is provided to enable this functionality in older drivers.

**G.3.3.79 GPU Shader5 Miscellaneous Functionality**

The name string for gpu shader5 miscellaneous functionality is `GL_ARB_gpu_shader5`. This extension is equivalent to new core functionality introduced in OpenGL 4.0 and is provided to enable this functionality in older drivers.

**G.3.3.80 Double-Precision Floating-Point Shader Support**

The name string for double-precision floating-point shader support is `GL_ARB_gpu_shader_fp64`. This extension is equivalent to new core functionality introduced in OpenGL 4.0 and is provided to enable this functionality in older drivers.

**G.3.3.81 Shader Subroutines**

The name string for shader subroutines is `GL_ARB_shader_subroutine`. This extension is equivalent to new core functionality introduced in OpenGL 4.0 and is provided to enable this functionality in older drivers.

**G.3.3.82 Tessellation Shaders**

The name string for tessellation shaders is `GL_ARB_tessellation_shader`. This extension is equivalent to new core functionality introduced in OpenGL 4.0 and is provided to enable this functionality in older drivers.

**G.3.3.83 RGB32 Texture Buffer Objects**

The name string for RGB32 texture buffer objects is `GL_ARB_texture_buffer_object_rgb32`. This extension is equivalent to new core functionality introduced in OpenGL 4.0 and is provided to enable this functionality in older drivers.

**G.3.3.84 Transform Feedback 2**

The name string for transform feedback 2 is `GL_ARB_transform_feedback2`. This extension is equivalent to new core functionality introduced in OpenGL 4.0 and is provided to enable this functionality in older drivers.

**G.3.3.85 Transform Feedback 3**

The name string for transform feedback 3 is `GL_ARB_transform_feedback3`. This extension is equivalent to new core functionality introduced in OpenGL 4.0 and is provided to enable this functionality in older drivers.

**G.3.3.86 OpenGL ES 2.0 Compatibility**

The name string for OpenGL ES 2.0 compatibility is `GL_ARB_ES2_compatibility`. This extension is equivalent to new core functionality introduced in OpenGL 4.1 and is provided to enable this functionality in older drivers.

**G.3.3.87 Program Binary Support**

The name string for program binary support is `GL_ARB_get_program_binary`. This extension is equivalent to new core functionality introduced in OpenGL 4.1 and is provided to enable this functionality in older drivers.

**G.3.3.88 Separate Shader Objects**

The name string for separate shader objects is `GL_ARB_separate_shader_objects`. This extension is equivalent to new core functionality introduced in OpenGL 4.1 and is provided to enable this functionality in older drivers.

**G.3.3.89 Shader Precision Restrictions**

The name string for shader precision restrictions is `GL_ARB_shader_precision`. This extension is equivalent to new core functionality introduced in OpenGL 4.1 and is provided to enable this functionality in older drivers.

**G.3.3.90 Double Precision Vertex Shader Inputs**

The name string for double precision vertex shader inputs is `GL_ARB_vertex_attrib_64bit`. This extension is equivalent to new core functionality introduced in OpenGL 4.1 and is provided to enable this functionality in older drivers.

**G.3.3.91 Viewport Arrays**

The name string for viewport arrays is `GL_ARB_viewport_array`. This extension is equivalent to new core functionality introduced in OpenGL 4.1 and is provided to enable this functionality in older drivers.

### G.3.3.92 Robust Context Creation

Robust context creation allows creating an OpenGL context supporting robust buffer access behavior and a specified graphics reset notification behavior exposed through the `GL_ARB_robustness` extension (see section [G.3.3.95](#)).

The name strings for GLX and WGL robust context creation are `GLX_ARB_create_context_robustness` and `WGL_ARB_create_context_robustness`, respectively.

### G.3.3.93 OpenCL Event Sharing

OpenCL event sharing allows creating OpenGL sync objects linked to OpenCL event objects, potentially improving efficiency of sharing images and buffers between the two APIs.

The name string for OpenCL event sharing is `GL_ARB_cl_event`

### G.3.3.94 Debug Output Notification

Debug output notification enables GL to inform the application when various events occur that may be useful during development and debugging.

The name string for debug output notification is `GL_ARB_debug_output`

### G.3.3.95 Context Robustness

Context robustness provides “safe” APIs that limit data written to application memory to a specified length, provides a mechanism to learn about graphics resets affecting the context, and defines guarantee that out-of-bounds buffer object accesses will have deterministic behavior precluding instability or termination. Some of these behaviors are controlled at context creation time via the companion `GLX_ARB_create_context_robustness` or `WGL_ARB_create_context_robustness` extensions (see section [G.3.3.92](#)).

The name string for context robustness is `GL_ARB_robustness`

### G.3.3.96 Shader Stencil Export

Shader stencil export enables shaders to generate a stencil reference value, allowing stencil testing to be performed against per-shader-invocation values.

The name string for shader stencil export is `GL_ARB_shader_stencil_export`

**G.3.3.97 Base Instanced Rendering**

The name string for base instanced rendering is `GL_ARB_base_instance`. This extension is equivalent to new core functionality introduced in OpenGL 4.2 and is provided to enable this functionality in older drivers.

**G.3.3.98 OpenGL Shading Language 4.20 Feature Pack**

The name string for the OpenGL Shading Language 4.20 feature pack is `GL_ARB_shading_language_420pack`. This extension is equivalent to new core functionality introduced in OpenGL 4.2 and is provided to enable this functionality in older drivers.

**G.3.3.99 Instanced Transform Feedback**

The name string for instanced transform feedback is `GL_ARB_transform_feedback_instanced`. This extension is equivalent to new core functionality introduced in OpenGL 4.2 and is provided to enable this functionality in older drivers.

**G.3.3.100 Compressed Texture Pixel Storage**

The name string for compressed texture pixel storage is `GL_ARB_compressed_texture_pixel_storage`. This extension is equivalent to new core functionality introduced in OpenGL 4.2 and is provided to enable this functionality in older drivers.

**G.3.3.101 Conservative Depth**

The name string for conservative depth is `GL_ARB_conservative_depth`. This extension is equivalent to new core functionality introduced in OpenGL 4.2 and is provided to enable this functionality in older drivers.

**G.3.3.102 Internal Format Query**

The name string for internal format query is `GL_ARB_internalformat_query`. This extension is equivalent to new core functionality introduced in OpenGL 4.2 and is provided to enable this functionality in older drivers.



**G.3.3.103 Map Buffer Alignment**

The name string for map buffer alignment is `GL_ARB_map_buffer_alignment`. This extension is equivalent to new core functionality introduced in OpenGL 4.2 and is provided to enable this functionality in older drivers.

**G.3.3.104 Shader Atomic Counters**

The name string for shader atomic counters is `GL_ARB_shader_atomic_counters`. This extension is equivalent to new core functionality introduced in OpenGL 4.2 and is provided to enable this functionality in older drivers.

**G.3.3.105 Shader Image Load/Store**

The name string for shader image load/store is `GL_ARB_shader_image_load_store`. This extension is equivalent to new core functionality introduced in OpenGL 4.2 and is provided to enable this functionality in older drivers.

**G.3.3.106 Shading Language Packing**

The name string for shading language packing is `GL_ARB_shading_language_packing`. This extension is equivalent to new core functionality introduced in OpenGL 4.2 and is provided to enable this functionality in older drivers.

**G.3.3.107 Texture Storage**

The name string for texture storage is `GL_ARB_texture_storage`. This extension is equivalent to new core functionality introduced in OpenGL 4.2 and is provided to enable this functionality in older drivers.

**G.3.3.108 ASTC Texture Compression**

The name string for ASTC texture compression is `GL_KHR_texture_compression_astc_ldr`. This extension is equivalent to new core functionality introduced in OpenGL 4.3, and is provided to enable this functionality in older drivers.

**G.3.3.109 Debug Contexts**

This KHR extension defines debugging features and combines the functionality of `GL_ARB_debug_output`, `GL_ARB_debug_output2`, `GL_ARB_debug_group`,

and `GL_ARB_debug_label`. It is intended primarily to bring this debug functionality to OpenGL ES implementations.

The name string for debug contexts is `GL_KHR_debug`.

#### **G.3.3.110 Shader Array of Arrays**

The name string for shader array of arrays is `GL_ARB_arrays_of_arrays`. This extension is equivalent to new core functionality introduced in OpenGL 4.3, and is provided to enable this functionality in older drivers.

#### **G.3.3.111 Clear Buffer Object**

The name string for clear buffer object is `GL_ARB_clear_buffer_object`. This extension is equivalent to new core functionality introduced in OpenGL 4.3, and is provided to enable this functionality in older drivers.

#### **G.3.3.112 Compute Shaders**

The name string for compute shaders is `GL_ARB_compute_shader`. This extension is equivalent to new core functionality introduced in OpenGL 4.3, and is provided to enable this functionality in older drivers.

#### **G.3.3.113 Copy Image**

The name string for copy image is `GL_ARB_copy_image`. This extension is equivalent to new core functionality introduced in OpenGL 4.3, and is provided to enable this functionality in older drivers.

#### **G.3.3.114 Debug Groups**

The name string for debug groups is `GL_ARB_debug_group`. This extension is equivalent to new core functionality introduced in OpenGL 4.3, and is provided to enable this functionality in older drivers.

#### **G.3.3.115 Object Debug Labels**

The name string for object debug label is `GL_ARB_debug_label`. This extension is equivalent to new core functionality introduced in OpenGL 4.3, and is provided to enable this functionality in older drivers.

**G.3.3.116 Extended Debug Output**

The name string for extended debug output is `GL_ARB_debug_output2`. This extension is equivalent to new core functionality introduced in OpenGL 4.3, and is provided to enable this functionality in older drivers.

**G.3.3.117 OpenGL ES 3.0 Compatibility**

The name string for OpenGL ES 3.0 compatibility is `GL_ARB_ES3_compatibility`. This extension is equivalent to new core functionality introduced in OpenGL 4.3, and is provided to enable this functionality in older drivers.

**G.3.3.118 Shader Explicit Uniform Location**

The name string for shader explicit uniform location is `GL_ARB_explicit_uniform_location`. This extension is equivalent to new core functionality introduced in OpenGL 4.3, and is provided to enable this functionality in older drivers.

**G.3.3.119 Fragment Layer Viewport**

The name string for fragment layer viewport is `GL_ARB_fragment_layer_viewport`. This extension is equivalent to new core functionality introduced in OpenGL 4.3, and is provided to enable this functionality in older drivers.

**G.3.3.120 Binding a Framebuffer Without Attachments**

The name string for binding a framebuffer without attachments is `GL_ARB_framebuffer_no_attachments`. This extension is equivalent to new core functionality introduced in OpenGL 4.3, and is provided to enable this functionality in older drivers.

**G.3.3.121 Extended Internal Format Query**

The name string for extended internal format query is `GL_ARB_internalformat_query2`. This extension is equivalent to new core functionality introduced in OpenGL 4.3, and is provided to enable this functionality in older drivers.

**G.3.3.122 Invalidate SubData**

The name string for invalidate subdata is `GL_ARB_invalidate_subdata`. This extension is equivalent to new core functionality introduced in OpenGL 4.3, and is provided to enable this functionality in older drivers.

**G.3.3.123 Multi Draw Indirect**

The name string for multi draw indirect is `GL_ARB_multi_draw_indirect`. This extension is equivalent to new core functionality introduced in OpenGL 4.3, and is provided to enable this functionality in older drivers.

**G.3.3.124 Program Interface Queries**

The name string for program interface queries is `GL_ARB_program_interface_query`. This extension is equivalent to new core functionality introduced in OpenGL 4.3, and is provided to enable this functionality in older drivers.

**G.3.3.125 Robust Buffer Access Behavior**

The name string for robust buffer access behavior is `GL_ARB_robust_buffer_access_behavior`. This extension is equivalent to new core functionality introduced in OpenGL 4.3, and is provided to enable this functionality in older drivers.

**G.3.3.126 Shader Image Size Query**

The name string for shader image size query is `GL_ARB_shader_image_size`. This extension is equivalent to new core functionality introduced in OpenGL 4.3, and is provided to enable this functionality in older drivers.

**G.3.3.127 Shader Storage in Buffer Objects**

The name string for shader storage in buffer objects is `GL_ARB_shader_storage_buffer_object`. This extension is equivalent to new core functionality introduced in OpenGL 4.3, and is provided to enable this functionality in older drivers.

**G.3.3.128 Stencil Texturing**

The name string for stencil texturing is `GL_ARB_stencil_texturing`. This extension is equivalent to new core functionality introduced in OpenGL 4.3, and is provided to enable this functionality in older drivers.

**G.3.3.129 Texture Buffer Range**

The name string for texture buffer range is `GL_ARB_texture_buffer_range`. This extension is equivalent to new core functionality introduced in OpenGL 4.3, and is provided to enable this functionality in older drivers.

**G.3.3.130 Texture Query Levels**

The name string for texture query levels is `GL_ARB_texture_query_levels`. This extension is equivalent to new core functionality introduced in OpenGL 4.3, and is provided to enable this functionality in older drivers.

**G.3.3.131 Texture Storage Multisample**

The name string for texture storage multisample is `GL_ARB_texture_storage_multisample`. This extension is equivalent to new core functionality introduced in OpenGL 4.3, and is provided to enable this functionality in older drivers.

**G.3.3.132 Texture Views**

The name string for texture views is `GL_ARB_texture_view`. This extension is equivalent to new core functionality introduced in OpenGL 4.3, and is provided to enable this functionality in older drivers.

**G.3.3.133 Vertex Attribute Binding**

The name string for vertex attribute binding is `GL_ARB_vertex_attrib_binding`. This extension is equivalent to new core functionality introduced in OpenGL 4.3, and is provided to enable this functionality in older drivers.

**G.3.3.134 Robustness Isolation**

The name string for robustness isolation is `GL_ARB_robustness_isolation`. This extension is equivalent to new core functionality introduced in OpenGL 4.3, and is provided to enable this functionality in older drivers.

**G.3.3.135 Robustness Application Isolation Context Creation**

These extensions allow creation of OpenGL contexts which support robustness isolation through OpenGL 4.3 or the equivalent functionality in the `GL_ARB_robustness_isolation` extension (see [G.3.3.134](#)), and may also define addi-

tional constraints around how OpenGL context reset notification affects other contexts in the share group, or other applications on the system. There are equivalent sets of extensions for both GLX and WGL window-system binding layers.

The name strings for GLX robustness application isolation context creation are `GLX_ARB_robustness_application_isolation` and `GLX_ARB_robustness_share_group_isolation`.

The name strings for WGL robustness application isolation context creation are `WGL_ARB_robustness_application_isolation` and `WGL_ARB_robustness_share_group_isolation`.

# Index

- #version, 4, 5, 490, 645, 648
- Accum, 634
- ACCUM\_BUFFER\_BIT, 634
- ACTIVE\_ATOMIC\_COUNTER\_-  
BUFFERS, 143, 543
- ACTIVE\_ATTRIBUTE\_MAX\_-  
LENGTH, 142, 537
- ACTIVE\_ATTRIBUTES, 142, 537
- ACTIVE\_PROGRAM, 144, 145, 535
- ACTIVE\_RESOURCES, 90, 544
- ACTIVE\_SUBROUTINE\_MAX\_-  
LENGTH, 149, 542
- ACTIVE\_SUBROUTINE\_UNIFORM\_-  
LOCATIONS, 130, 133, 149,  
542
- ACTIVE\_SUBROUTINE\_UNIFORM\_-  
MAX\_LENGTH, 149, 542
- ACTIVE\_SUBROUTINE\_UNI-  
FORMS, 149, 542
- ACTIVE\_SUBROUTINES, 130, 131,  
133, 149, 542
- ACTIVE\_TEXTURE, 153, 155, 209,  
523
- ACTIVE\_UNIFORM\_BLOCK\_-  
MAX\_NAME\_LENGTH, 143,  
539
- ACTIVE\_UNIFORM\_BLOCKS, 142,  
539
- ACTIVE\_UNIFORM\_MAX\_LENGTH,  
142, 537
- ACTIVE\_UNIFORMS, 142, 537
- ACTIVE\_VARIABLES, 93, 100, 117,  
118, 545
- ActiveShaderProgram, 105, 119, 650
- ActiveTexture, 134, 153
- ALIASED\_LINE\_WIDTH\_RANGE,  
558
- ALL\_ATTRIB\_BITS, 635
- ALL\_BARRIER\_BITS, 140
- ALL\_SHADER\_BITS, 105
- ALPHA, 208, 240, 413, 436, 518, 520,  
529, 633
- ALPHA\_BITS, 634
- ALPHA\_TEST, 634
- AlphaFunc, 634
- ALREADY\_SIGNALED, 35
- ALWAYS, 208, 242, 429, 430, 524
- AND, 440
- AND\_INVERTED, 440
- AND\_REVERSE, 440
- Antialiasing, 403
- ANY\_SAMPLES\_PASSED, 40–43,  
319, 320, 430, 431
- ANY\_SAMPLES\_PASSED\_CON-  
SERVATIVE, 40–43, 319, 320,  
430, 431
- ARB\_arrays\_of\_arrays, 644, 654
- ARB\_base\_instance, 637, 641
- ARB\_clear\_buffer\_object, 644, 653
- ARB\_compressed\_texture\_pixel\_stor-  
age, 636, 641
- ARB\_compute\_shader, 644, 653
- ARB\_conservative\_depth, 637, 641

- ARB\_copy\_image, 644, 653, 654
- ARB\_debug\_group, 644, 653
- ARB\_debug\_label, 644, 653
- ARB\_debug\_output, 644, 654
- ARB\_debug\_output2, 644, 654
- ARB\_ES3\_compatibility, 644, 654
- ARB\_explicit\_uniform\_location, 644, 654
- ARB\_fragment\_layer\_viewport, 644, 654
- ARB\_framebuffer\_no\_attachments, 644, 654
- ARB\_internalformat\_query, 637, 641
- ARB\_internalformat\_query2, 644, 653
- ARB\_invalidate\_subdata, 644, 654
- ARB\_map\_buffer\_alignment, 637, 641
- ARB\_multi\_draw\_indirect, 644, 653
- ARB\_program\_interface\_query, 644, 654
- ARB\_robust\_buffer\_access\_behavior, 644, 654
- ARB\_robustness, 654
- ARB\_robustness\_isolation, 654
- ARB\_shader\_atomic\_counters, 636, 641
- ARB\_shader\_image\_load\_store, 637, 641
- ARB\_shader\_image\_size, 644, 653
- ARB\_shader\_storage\_buffer\_object, 644, 654
- ARB\_shading\_language\_420pack, 637, 641
- ARB\_shading\_language\_packing, 641
- ARB\_stencil\_texturing, 644, 654
- ARB\_texture\_buffer\_range, 645, 653
- ARB\_texture\_compression\_bptc, 636, 641
- ARB\_texture\_query\_levels, 645, 653
- ARB\_texture\_storage, 636, 641
- ARB\_texture\_storage\_multisample, 645, 653
- ARB\_texture\_view, 645, 654
- ARB\_transform\_feedback\_instanced, 637, 641
- ARB\_vertex\_attrib\_binding, 645, 654
- AreTexturesResident, 634
- ARRAY\_BUFFER, 55, 299, 300, 303, 304
- ARRAY\_BUFFER\_BINDING, 304, 509
- ARRAY\_SIZE, 89, 93, 99, 115, 116, 324, 329, 545
- ARRAY\_STRIDE, 93, 99, 116, 545
- ATOMIC\_COUNTER\_BARRIER\_BIT, 139
- ATOMIC\_-
  - COUNTER\_BUFFER, 55, 56, 86, 88, 90–93, 117, 118, 127
- ATOMIC\_COUNTER\_BUFFER\_ACTIVE\_ATOMIC\_COUNTER\_INDICES, 118, 543
- ATOMIC\_COUNTER\_BUFFER\_ACTIVE\_ATOMIC\_COUNTERS, 118, 543
- ATOMIC\_COUNTER\_-
  - BUFFER\_BINDING, 71, 118, 543, 550
- ATOMIC\_COUNTER\_BUFFER\_-
  - DATA\_SIZE, 118, 127, 543
- ATOMIC\_COUNTER\_BUFFER\_INDEX, 93, 99, 116, 545
- ATOMIC\_COUNTER\_BUFFER\_REFERENCED\_BY\_COMPUTE\_SHADER, 118, 543
- ATOMIC\_COUNTER\_BUFFER\_REFERENCED\_BY\_FRAGMENT\_SHADER, 118, 543
- ATOMIC\_COUNTER\_BUFFER\_REFERENCED\_BY\_GEOMETRY\_SHADER, 118, 543
- ATOMIC\_COUNTER\_BUFFER\_REF-



- ERENCED\_BY\_TESS\_CONTROL\_SHADER, 118, 543
- ATOMIC\_COUNTER\_BUFFER\_REFERENCED\_BY\_TESS\_EVALUATION\_SHADER, 118
- ATOMIC\_COUNTER\_BUFFER\_REFERENCED\_BY\_TESS\_EVALUATION\_SHADER, 543
- ATOMIC\_COUNTER\_BUFFER\_REFERENCED\_BY\_VERTEX\_SHADER, 118, 543
- ATOMIC\_COUNTER\_BUFFER\_SIZE, 71, 550
- ATOMIC\_COUNTER\_BUFFER\_START, 71, 550
- atomic\_uint, 98, 127
- atomicCounter, 584
- atomicCounterDecrement, 584
- atomicCounterIncrement, 584
- ATTACHED\_SHADERS, 142, 145, 536
- AttachShader, 78
- ATTRIB\_STACK\_DEPTH, 635
- AUX<sub>*i*</sub>, 634
- BACK, 404, 428, 432, 442, 443, 445–447, 449, 456, 514, 633
- BACK\_LEFT, 260, 443, 444, 451
- BACK\_RIGHT, 260, 443, 444, 451
- barrier, 346
- Begin, 631
- BeginConditionalRender, 319, 320
- BeginQuery, 39, 41, 45, 430
- BeginQueryIndexed, 39–41, 43, 380
- BeginTransformFeedback, 374–377
- BGR, 164, 457, 459
- BGR\_INTEGER, 164
- BGRA, 164, 168, 173, 297–299, 303, 457
- BGRA\_INTEGER, 164, 168
- BindAttribLocation, 110, 323
- BindBuffer, 25, 53, 54, 56, 206, 304, 305, 637, 649
- BindBufferBase, 56, 57, 70, 125, 127, 129, 376, 378, 638, 646, 649
- BindBufferRange, 48, 56, 57, 70, 125–127, 129, 130, 376–378, 638, 646, 649, 650
- BindFragDataLocation, 110, 419
- BindFragDataLocationIndexed, 418–420, 437
- BindFramebuffer, 254, 255, 257, 278
- BindImageTexture, 48, 244–246, 493, 499, 640
- binding, 129
- BindProgramPipeline, 83, 104–106, 133, 144, 339, 378
- BindRenderbuffer, 262–264
- BindSampler, 25, 156, 158
- BindTexture, 134, 153–155, 241
- BindTransformFeedback, 373, 374
- BindVertexArray, 306, 307
- BindVertexBuffer, 298, 304
- BITMAP, 633
- Bitmap, 633
- BLEND, 431, 432, 438, 439, 525
- BLEND\_COLOR, 525
- BLEND\_DST\_ALPHA, 525
- BLEND\_DST\_RGB, 525
- BLEND\_EQUATION\_ALPHA, 525
- BLEND\_EQUATION\_RGB, 525
- BLEND\_SRC\_ALPHA, 525
- BLEND\_SRC\_RGB, 525
- BlendColor, 434, 437
- BlendEquation, 432
- BlendEquationi, 432
- BlendEquationSeparate, 432
- BlendEquationSeparatei, 432
- BlendFunc, 434, 435
- BlendFunci, 435

- BlendFuncSeparate, 434, 435
- BlendFuncSeparatei, 435
- BlitFramebuffer, 274, 453, 461, 463, 648, 651
- BLOCK\_INDEX, 93, 99, 116, 545
- BLUE, 164, 208, 240, 413, 457, 459, 518, 520, 529
- BLUE\_BITS, 634
- BLUE\_INTEGER, 164
- BOOL, 95
- bool, 95, 122
- BOOL\_VEC2, 95
- BOOL\_VEC3, 95
- BOOL\_VEC4, 95
- boolean, 120, 646
- BPTC\_FLOAT, 231
- BPTC\_UNORM, 231
- BUFFER, 479
- BUFFER\_ACCESS, 55, 59, 63, 510
- BUFFER\_ACCESS\_FLAGS, 55, 59, 63, 65, 510
- BUFFER\_BINDING, 93, 99, 117, 118, 545
- BUFFER\_DATA\_SIZE, 93, 99, 117, 118, 545
- BUFFER\_MAP\_LENGTH, 55, 59, 63, 65, 510
- BUFFER\_MAP\_OFFSET, 55, 59, 63, 65, 510
- BUFFER\_MAP\_POINTER, 55, 59, 63, 65, 68, 69, 510
- BUFFER\_MAPPED, 55, 59, 63, 65, 510
- BUFFER\_SIZE, 55, 59–61, 63, 64, 67, 69, 130, 204, 510
- BUFFER\_UPDATE\_BARRIER\_BIT, 139
- BUFFER\_USAGE, 55, 59, 62, 510
- BUFFER\_VARIABLE, 87, 93, 94
- BufferData, 50, 57, 58, 65, 649
- BufferSubData, 49, 59, 137, 140
- bvec2, 95, 120
- bvec3, 95
- bvec4, 95
- BYTE, 163, 251, 296, 460, 461
- callback, 474
- CallList, 635
- CallLists, 635
- CAVEAT\_SUPPORT, 492, 496–502
- CCW, 143, 404, 514, 541
- ccw, 349
- centroid, 412
- centroid in, 412
- CHANGED\_ITEMS, 57, 68, 134, 151, 191, 192, 207, 241, 243, 244, 355, 356, 458, 461, 463
- CHANGED\_ITEMS (OLD), 56, 57, 70, 100, 120, 123, 179–181, 209, 259, 266, 275, 279, 385, 386, 443, 445, 446, 448, 451, 476, 504, 567
- CheckFramebufferStatus, 277–279
- CLAMP, 633
- CLAMP\_FRAGMENT\_COLOR, 632
- CLAMP\_READ\_COLOR, 458, 512
- CLAMP\_TO\_BORDER, 208, 216, 220
- CLAMP\_TO\_EDGE, 208, 215, 220, 240, 462
- CLAMP\_VERTEX\_COLOR, 632
- ClampColor, 458, 632
- CLEAR, 440
- Clear, 282, 320, 390, 448–450, 634
- CLEAR\_BUFFER, 502
- ClearAccum, 634
- ClearBuffer, 450
- ClearBuffer{if ui}v, 449
- ClearBufferData, 61, 492
- ClearBufferfi, 449, 450
- ClearBufferfv, 449, 450
- ClearBufferiv, 449, 450

- ClearBufferSubData, 60, 61, 492, 649
- ClearBufferuiv, 449
- ClearColor, 448, 449
- ClearDepth, 448–450, 647
- ClearDepthf, 448
- ClearStencil, 448–450
- CLIENT\_ALL\_ATTRIB\_BITS, 635
- CLIENT\_ATTRIB\_STACK\_DEPTH, 635
- ClientActiveTexture, 631
- ClientWaitSync, 33–37, 48
- CLIP\_DISTANCE<sub>*i*</sub>, 382, 511
- CLIP\_DISTANCE0, 382
- ClipPlane, 632
- coherent, 140
- COLOR, 189, 449–451
- COLOR\_ATTACHMENT<sub>*i*</sub>, 268, 276, 443, 444, 456
- COLOR\_ATTACHMENT<sub>*n*</sub>, 256
- COLOR\_ATTACHMENT0, 256, 443, 446, 456
- COLOR\_BUFFER\_BIT, 448, 450, 461–463
- COLOR\_CLEAR\_VALUE, 526
- COLOR\_COMPONENTS, 495
- COLOR\_ENCODING, 498
- COLOR\_INDEX, 631
- COLOR\_LOGIC\_OP, 439, 525
- COLOR\_MATERIAL, 632
- COLOR\_RENDERABLE, 496
- COLOR\_SUM, 634
- COLOR\_WRITEMASK, 447, 526
- ColorMask, 446, 447
- ColorMask<sub>*i*</sub>, 446
- ColorMaterial, 632
- ColorPointer, 631
- COMMAND\_BARRIER\_BIT, 139
- COMPARE\_REF\_TO\_TEXTURE, 207, 242
- COMPATIBLE\_SUBROUTINES, 94, 132, 542, 546
- COMPILE\_STATUS, 76, 85, 141, 142, 534
- CompileShader, 76
- COMPRESSED\_R11\_EAC, 183, 602, 614, 616–618
- COMPRESSED\_RED, 183
- COMPRESSED\_RED\_RGTC1, 183, 231, 466, 589, 590
- COMPRESSED\_RG, 183
- COMPRESSED\_RG11\_EAC, 183, 602, 617
- COMPRESSED\_RG\_RGTC2, 183, 231, 466, 590
- COMPRESSED\_RGB, 183
- COMPRESSED\_RGB8\_ETC2, 183, 600, 602–605, 609–612
- COMPRESSED\_RGB8\_-PUNCHTHROUGH\_ALPHA1\_ETC2, 183, 602, 604, 621, 625, 627, 628
- COMPRESSED\_RGB\_-BPTC\_SIGNED\_FLOAT, 183, 231, 466, 591, 598
- COMPRESSED\_RGB\_BPTC\_UNSIGNED\_FLOAT, 183, 231, 466, 591, 598
- COMPRESSED\_RGBA, 183
- COMPRESSED\_RGBA8\_ETC2\_EAC, 183, 600, 602, 604, 611, 612, 614, 616, 617
- COMPRESSED\_RGBA\_BPTC\_UNORM, 183, 231, 466, 591–593
- COMPRESSED\_SIGNED\_R11\_EAC, 183, 602, 618, 621
- COMPRESSED\_SIGNED\_-RED\_RGTC1, 183, 231, 466, 590, 591
- COMPRESSED\_SIGNED\_RG11\_EAC,

- 183, 602, 621
- COMPRESSED\_SIGNED\_RG\_-  
RGTC2, 183, 231, 466, 591
- COMPRESSED\_SRGB, 183, 243
- COMPRESSED\_SRGB8\_AL-  
PHA8\_ETC2\_EAC, 183, 243,  
602, 604, 614
- COMPRESSED\_SRGB8\_ALPHA8\_-  
ETC2\_EAC, 614
- COMPRESSED\_SRGB8\_ETC2, 183,  
243, 600, 604, 611
- COMPRESSED\_SRGB8\_-  
PUNCHTHROUGH\_AL-  
PHA1\_ETC2, 183, 243, 602,  
604, 628
- COMPRESSED\_SRGB\_ALPHA, 183,  
243
- COMPRESSED\_SRGB\_ALPHA\_-  
BPTC\_UNORM, 183, 231,  
243, 466, 591–593
- COMPRESSED\_TEXTURE\_FOR-  
MATS, 176, 559, 631, 637
- CompressedTexImage, 201
- CompressedTexImage\*D, 160
- CompressedTexImage1D, 195, 197–  
200, 492
- CompressedTexImage2D, 195, 197–  
200, 492, 602
- CompressedTexImage3D, 195, 197–  
200, 214, 492
- CompressedTexSubImage\*D, 160
- CompressedTexSubImage1D, 199–201
- CompressedTexSubImage2D, 199–201,  
603, 604
- CompressedTexSubImage3D, 199–201
- COMPUTE\_SHADER, 75, 131, 468
- COMPUTE\_SHADER\_BIT, 105
- COMPUTE\_SUBROUTINE, 87, 131
- COMPUTE\_SUBROU-  
TINE\_UNIFORM, 87, 91, 93, 94, 101, 131
- COMPUTE\_TEXTURE, 499
- COMPUTE\_WORK\_GROUP\_SIZE,  
143, 144, 469, 536
- CONDITION\_SATISFIED, 35
- CONSTANT\_ALPHA, 436
- CONSTANT\_COLOR, 436
- CONTEXT\_COMPATIBILITY\_PRO-  
FILE\_BIT, 489
- CONTEXT\_CORE\_PROFILE\_BIT, 489
- CONTEXT\_FLAG\_DEBUG\_BIT, 471,  
489
- CONTEXT\_FLAG\_FORWARD\_COM-  
PATIBLE\_BIT, 489
- CONTEXT\_FLAGS, 471, 489, 560
- CONTEXT\_PROFILE\_MASK, 489
- COPY, 440, 441, 525
- COPY\_INVERTED, 440
- COPY\_READ\_BUFFER, 55, 67, 637,  
638, 649
- COPY\_READ\_BUFFER\_BINDING,  
578, 638
- COPY\_WRITE\_BUFFER, 55, 67, 637,  
638, 649
- COPY\_WRITE\_BUFFER\_BINDING,  
578, 638
- CopyBufferSubData, 67
- CopyImageSubData, 464–466
- CopyPixels, 189, 634
- CopyTexImage, 634
- CopyTexImage1D, 190, 192, 194, 195,  
224, 492
- CopyTexImage2D, 189, 190, 192, 194,  
195, 224, 492
- CopyTexImage3D, 192
- CopyTexSubImage1D, 191–195
- CopyTexSubImage2D, 191–195
- CopyTexSubImage3D, 191, 192, 194,  
195
- CreateProgram, 25, 78

- CreateShader, 74, 75
- CreateShaderProgramv, 84, 85
- CULL\_FACE, 404, 514
- CULL\_FACE\_MODE, 514
- CullFace, 404, 408
- CURRENT\_PROGRAM, 536
- CURRENT\_QUERY, 43, 578
- CURRENT\_VERTEX\_ATTRIB, 317, 318, 547, 639
- CW, 143, 404
- cw, 349
- DEBUG\_CALLBACK\_FUNCTION, 475, 481, 488, 571
- DEBUG\_CALLBACK\_USER\_PARAM, 481, 488, 571
- DEBUG\_GROUP\_STACK\_DEPTH, 571
- DEBUG\_LOGGED\_MESSAGES, 475, 571
- DEBUG\_NEXT\_LOGGED\_MESSAGE\_LENGTH, 475, 571
- DEBUG\_OUTPUT, 471, 475–477, 571
- DEBUG\_OUTPUT\_SYNCHRONOUS, 480, 481, 571
- DEBUG\_SEVERITY\_HIGH, 473
- DEBUG\_SEVERITY\_LOW, 473, 474
- DEBUG\_SEVERITY\_MEDIUM, 473
- DEBUG\_SEVERITY\_NOTIFICATION, 473, 478
- DEBUG\_SOURCE\_API, 17, 472, 492
- DEBUG\_SOURCE\_APPLICATION, 472, 477, 478
- DEBUG\_SOURCE\_OTHER, 472
- DEBUG\_SOURCE\_SHADER\_COMPILER, 472
- DEBUG\_SOURCE\_THIRD\_PARTY, 472, 477, 478
- DEBUG\_SOURCE\_WINDOW\_SYSTEM, 472
- DEBUG\_TYPE\_DEPRECATED\_BEHAVIOR, 473
- DEBUG\_TYPE\_ERROR, 17, 473
- DEBUG\_TYPE\_MARKER, 473
- DEBUG\_TYPE\_OTHER, 473
- DEBUG\_TYPE\_PERFORMANCE, 473, 492
- DEBUG\_TYPE\_POP\_GROUP, 473, 478
- DEBUG\_TYPE\_PORTABILITY, 473
- DEBUG\_TYPE\_PUSH\_GROUP, 473, 478
- DEBUG\_TYPE\_UNDEFINED\_BEHAVIOR, 473
- DebugMessageCallback, 474, 475, 481
- DebugMessageControl, 474, 476, 648
- DebugMessageInsert, 477
- DECR, 429
- DECR\_WRAP, 429
- DELETE\_STATUS, 77, 141, 142, 534, 536
- DeleteBuffers, 25, 48, 53, 54, 56, 57, 649
- DeleteFramebuffers, 255, 257
- DeleteLists, 635
- DeleteProgram, 84
- DeleteProgramPipelines, 103–106, 145, 339
- DeleteQueries, 39, 41, 45
- DeleteRenderbuffers, 48, 263, 278
- DeleteSamplers, 157, 158
- DeleteShader, 77
- DeleteSync, 34, 35, 38
- DeleteTextures, 48, 155, 245, 278
- DeleteTransformFeedbacks, 373, 374, 639, 652
- DeleteVertexArrays, 306, 307
- DEPTH, 189, 260, 449–451, 520, 529
- DEPTH24\_STENCIL8, 178, 182

- DEPTH32F\_STENCIL8, 178, 182
- DEPTH\_ATTACHMENT, 256, 268, 276
- DEPTH\_BITS, 634
- DEPTH\_BUFFER\_BIT, 448, 450, 461, 463
- DEPTH\_CLAMP, 382, 511
- DEPTH\_CLEAR\_VALUE, 526
- DEPTH\_COMPONENT, 164, 175, 176, 182, 207, 212, 213, 241, 275, 334, 414, 454, 456, 457, 519
- DEPTH\_COMPONENT16, 178, 182
- DEPTH\_COMPONENT24, 178, 182
- DEPTH\_COMPONENT32, 182
- DEPTH\_COMPONENT32F, 178, 182
- DEPTH\_COMPONENTS, 496
- DEPTH\_FUNC, 524
- DEPTH\_RANGE, 511
- DEPTH\_RENDERABLE, 496
- DEPTH\_STENCIL, 161, 164, 168, 173–176, 182, 189, 212, 213, 227, 228, 241, 267, 272, 275, 334, 414, 450, 455–457
- DEPTH\_STENCIL\_ATTACHMENT, 260, 267, 268, 272, 647
- DEPTH\_STENCIL\_-  
TEXTURE\_MODE, 207, 227, 228, 241, 334, 519
- DEPTH\_TEST, 429, 524
- DEPTH\_TEXTURE\_MODE, 633
- DEPTH\_WRITEMASK, 526
- DepthFunc, 430
- DepthMask, 447
- DepthRange, 14, 15, 385, 386
- DepthRangeArrayv, 385
- DepthRangef, 385
- DepthRangeIndexed, 385, 386
- DetachShader, 79
- dFdx, 485
- dFdy, 485
- Disable, 215, 302, 382, 390, 393–395, 398, 403, 404, 408, 424–426, 428, 429, 432, 439, 471, 480, 632–634
- DisableClientState, 631
- Disablei, 425, 431, 432
- DisableVertexArray, 300, 317
- DISPATCH\_INDIRECT\_BUFFER, 55, 139, 305, 469, 649
- DISPATCH\_INDIRECT\_BUFFER\_-  
BINDING, 556
- DispatchCompute, 468, 469
- DispatchComputeIndirect, 139, 305, 469, 649
- DITHER, 439, 525
- dmatC, 123
- dmatCxR, 123
- dmat\*, 638, 640
- dmat2, 95, 322
- dmat2x3, 95, 322, 325
- dmat2x4, 95, 322, 325
- dmat3, 95, 120, 322, 325
- dmat3x2, 95, 322
- dmat3x4, 95, 322, 325
- dmat4, 95, 322, 325
- dmat4x2, 95, 322
- dmat4x3, 95, 325
- dmat4x3), 322
- DONT\_CARE, 476, 485, 555
- DOUBLE, 95, 296
- double, 95, 108, 122, 322, 385, 645
- DOUBLE\_MAT2, 95
- DOUBLE\_MAT2x3, 95
- DOUBLE\_MAT2x4, 95
- DOUBLE\_MAT3, 95
- DOUBLE\_MAT3x2, 95
- DOUBLE\_MAT3x4, 95
- DOUBLE\_MAT4, 95
- DOUBLE\_MAT4x2, 95
- DOUBLE\_MAT4x3, 95

- DOUBLE\_VEC2, 95
- DOUBLE\_VEC3, 95
- DOUBLE\_VEC4, 95
- DOUBLEBUFFER, 577
- DRAW\_BUFFER, 443, 446, 456
- DRAW\_BUFFER*i*, 431, 432, 435, 446, 449, 528
- DRAW\_BUFFER0, 446
- DRAW\_FRAMEBUFFER, 254, 255, 257, 258, 260, 262, 267–270, 278, 279, 451, 527, 647
- DRAW\_FRAMEBUFFER\_BINDING, 223, 257, 279, 280, 442, 444, 463, 527
- DRAW\_INDIRECT, 310, 315
- DRAW\_INDIRECT\_BUFFER, 55, 139, 305, 309, 315, 470
- DRAW\_INDIRECT\_BUFFER\_BINDING, 509
- DrawArrays, 279, 284, 286, 301, 304, 306, 308, 336
- DrawArraysIndirect, 305, 309, 310, 651
- DrawArraysInstanced, 309, 310, 379, 651
- DrawArraysInstancedBaseInstace, 312
- DrawArraysInstancedBaseInstance, 308, 651
- DrawArraysOneInstance, 307, 308
- DrawBuffer, 441–445, 447, 450, 647
- DrawBuffers, 442, 444, 445, 647
- DrawElements, 136, 301, 304, 306, 312–314
- DrawElementsBaseVertex, 304, 314, 316
- DrawElementsIndirect, 305, 315, 651
- DrawElementsInstanced, 304, 313, 651
- DrawElementsInstancedBaseInstance, 312, 313, 651
- DrawElementsInstancedBaseVertex, 304, 314, 651
- DrawElementsInstancedBaseVertexBaseInstance, 314, 651
- DrawElementsOneInstance, 311, 312
- DrawPixels, 633
- DrawRangeElements, 304, 313, 314, 558
- DrawRangeElementsBaseVertex, 304, 314
- DrawTransformFeedback, 379
- DrawTransformFeedbackInstanced, 379, 651
- DrawTransformFeedbackStream, 379
- DrawTransformFeedbackStreamInstanced, 379, 651
- DST\_ALPHA, 436
- DST\_COLOR, 436
- dvec2, 95, 322
- dvec3, 95, 322, 325, 638, 640
- dvec4, 95, 322, 323, 325, 638, 640
- DYNAMIC\_COPY, 55, 58
- DYNAMIC\_DRAW, 55, 58
- DYNAMIC\_READ, 55, 58
- early\_fragment\_tests, 420
- EdgeFlagPointer, 631
- ELEMENT\_ARRAY\_BARRIER\_BIT, 138
- ELEMENT\_ARRAY\_BUFFER, 55, 138, 304
- ELEMENT\_ARRAY\_BUFFER\_BINDING, 508
- EmitStreamVertex, 365
- Enable, 215, 301, 382, 390, 393–395, 398, 403, 404, 408, 424–426, 428, 429, 432, 439, 471, 480, 487, 632–634
- EnableClientState, 631
- Enablei, 425, 431, 432
- EnableVertexAttribArray, 300, 306, 317
- End, 631

- EndConditionalRender, 319, 320
- EndList, 635
- EndPrimitive, 282, 364
- EndQuery, 41, 42, 45, 430, 431
- EndQueryIndexed, 41
- EndStreamPrimitive, 364
- EndTransformFeedback, 50, 51, 374, 375, 378–380
- EQUAL, 143, 208, 242, 429, 430, 541
- equal\_spacing, 347, 349, 355
- EQUIV, 440
- EXTENSIONS, 490, 560, 635, 658
- FALSE, 14, 15, 38, 42, 44, 54, 55, 59, 65, 66, 76, 77, 80, 83–85, 104, 110, 119, 120, 141–143, 150, 151, 155, 158, 160, 239, 240, 244–247, 257, 262, 264, 272, 298, 307, 317, 319, 337, 338, 373, 390, 415, 427, 431, 455, 458, 471, 476, 480, 492, 495–497, 501, 507, 509–511, 513–515, 519, 521, 524, 525, 529, 532–536, 541, 543, 547–549, 552, 571, 578
- FASTEST, 485
- FeedbackBuffer, 634
- FenceSync, 25, 33, 34, 37, 50
- FILL, 406, 408, 409, 514, 586
- FILTER, 498
- Finish, 18, 33, 50, 586
- FIRST\_VERTEX\_CONVENTION, 368, 381
- FIXED, 296
- FIXED\_ONLY, 458, 467, 512
- flat, 363, 381
- FLOAT, 94, 163, 211, 248, 250, 261, 296, 319, 458–460, 494, 507
- float, 94, 108, 122, 322
- FLOAT\_32\_UNSIGNED\_INT\_24\_8\_REV, 161, 163, 165, 167, 168, 172, 455, 456, 460, 461
- FLOAT\_MAT2, 95
- FLOAT\_MAT2x3, 95
- FLOAT\_MAT2x4, 95
- FLOAT\_MAT3, 95
- FLOAT\_MAT3x2, 95
- FLOAT\_MAT3x4, 95
- FLOAT\_MAT4, 95
- FLOAT\_MAT4x2, 95
- FLOAT\_MAT4x3, 95
- FLOAT\_VEC2, 94
- FLOAT\_VEC3, 94
- FLOAT\_VEC4, 95
- Flush, 18, 37, 586
- FlushMappedBufferRange, 50, 62, 64, 65
- FOG, 634
- Fog, 634
- FOG\_HINT, 635
- FogCoordPointer, 631
- FRACTIONAL\_EVEN, 143
- fractional\_even\_spacing, 347, 349
- FRACTIONAL\_ODD, 143
- fractional\_odd\_spacing, 347, 349
- FRAGMENT\_INTERPOLATION\_OFFSET\_BITS, 412, 574
- FRAGMENT\_SHADER, 75, 131, 147, 148, 535
- FRAGMENT\_SHADER\_BIT, 105
- FRAGMENT\_SHADER\_DERIVATIVE\_HINT, 485, 555
- FRAGMENT\_SUBROUTINE, 87, 131
- FRAGMENT\_SUBROUTINE\_UNIFORM, 87, 90, 93, 94, 101, 131
- FRAGMENT\_TEXTURE, 499
- FRAMEBUFFER, 255, 257, 258, 260, 262, 267–270, 278, 279, 451,



- 479, 647
- FRAMEBUFFER\_ATTACHMENT\_x\_-  
SIZE, 529
- FRAMEBUFFER\_ATTACHMENT\_-  
ALPHA\_SIZE, 261
- FRAMEBUFFER\_ATTACHMENT\_-  
BLUE\_SIZE, 261
- FRAMEBUFFER\_ATTACHMENT\_-  
COLOR\_ENCODING,  
190, 261, 433, 438, 439, 462,  
529
- FRAMEBUFFER\_ATTACHMENT\_-  
COMPONENT\_TYPE, 261,  
529
- FRAMEBUFFER\_ATTACHMENT\_-  
DEPTH\_SIZE, 261
- FRAMEBUFFER\_ATTACHMENT\_-  
GREEN\_SIZE, 261
- FRAMEBUFFER\_ATTACH-  
MENT\_LAYERED, 262, 272,  
529
- FRAMEBUFFER\_ATTACH-  
MENT\_OBJECT\_NAME, 261,  
262, 267, 271, 275, 529
- FRAMEBUFFER\_ATTACH-  
MENT\_OBJECT\_TYPE, 260,  
261, 267, 271, 275, 280, 529
- FRAMEBUFFER\_ATTACHMENT\_-  
RED\_SIZE, 261
- FRAMEBUFFER\_ATTACHMENT\_-  
STENCIL\_SIZE, 261
- FRAMEBUFFER\_ATTACHMENT\_-  
TEXTURE\_-  
CUBE\_MAP\_FACE, 262, 272,  
529
- FRAMEBUFFER\_ATTACHMENT\_-  
TEXTURE\_LAYER, 262, 271,  
272, 281, 529
- FRAMEBUFFER\_ATTACHMENT\_-  
TEXTURE\_LEVEL, 223, 262,  
271, 273, 274, 529
- FRAMEBUFFER\_BARRIER\_BIT, 139
- FRAMEBUFFER\_BINDING, 257
- FRAMEBUFFER\_BLEND, 496
- FRAMEBUFFER\_COMPLETE, 279
- FRAMEBUFFER\_DEFAULT, 260
- FRAMEBUFFER\_DEFAULT\_FIXED\_-  
SAMPLE\_LOCATIONS, 258,  
260
- FRAMEBUFFER\_DEFAULT\_-  
HEIGHT, 258, 260, 277
- FRAMEBUFFER\_DEFAULT\_LAY-  
ERS, 258, 260
- FRAMEBUFFER\_DEFAULT\_SAM-  
PLES, 258, 260
- FRAMEBUFFER\_DEFAULT\_WIDTH,  
258, 260, 277
- FRAMEBUFFER\_INCOMPLETE\_AT-  
TACHMENT, 276
- FRAMEBUFFER\_INCOMPLETE\_-  
LAYER\_TARGETS, 277
- FRAMEBUFFER\_INCOMPLETE\_-  
MISSING\_ATTACHMENT,  
277
- FRAMEBUFFER\_INCOMPLETE\_-  
MULTISAMPLE, 277
- FRAMEBUFFER\_RENDERABLE,  
496
- FRAMEBUFFER\_RENDERABLE\_-  
LAYERED, 496
- FRAMEBUFFER\_SRGB, 433, 438,  
439, 498, 525
- FRAMEBUFFER\_UNDEFINED, 276
- FRAMEBUFFER\_UNSUPPORTED,  
277, 278
- FramebufferParameteri, 257
- FramebufferRenderbuffer, 267, 278
- FramebufferTexture, 48, 268, 271, 272
- FramebufferTexture1D, 269, 270
- FramebufferTexture2D, 269, 270, 272

- FramebufferTexture3D, 269–272
- FramebufferTextureLayer, 270, 272
- FRONT, 404, 428, 432, 442, 443, 445–447, 449, 456, 633
- FRONT\_AND\_BACK, 404, 406, 428, 432, 443, 445–447, 449, 456
- FRONT\_FACE, 514
- FRONT\_LEFT, 260, 443, 444, 451
- FRONT\_RIGHT, 260, 443, 444, 451
- FrontFace, 404, 415, 632
- Frustum, 631
- FULL\_SUPPORT, 492, 496–502
- FUNC\_ADD, 434, 437, 525
- FUNC\_REVERSE\_SUBTRACT, 434
- FUNC\_SUBTRACT, 434
- fwidth, 485
  
- GenBuffers, 25, 53, 54, 56, 57
- GENERATE\_MIPMAP, 634
- GENERATE\_MIPMAP\_HINT, 635
- GenerateMipmap, 225
- GenFramebuffers, 254–257
- GenLists, 635
- GenProgramPipelines, 103–106, 144, 339
- GenQueries, 39–41, 45
- GenRenderbuffers, 262–264
- GenSamplers, 156–159
- GenTextures, 154, 155, 232, 638
- GenTransformFeedbacks, 372–374
- GenVertexArrays, 306, 307
- GEOMETRY\_INPUT\_TYPE, 143, 144, 361, 538
- GEOMETRY\_OUTPUT\_TYPE, 143, 144, 363, 538
- GEOMETRY\_SHADER, 75, 131, 361, 535
- GEOMETRY\_SHADER\_BIT, 105
- GEOMETRY\_SHADER\_INVOCATIONS, 143, 144, 538
- GEOMETRY\_SUBROUTINE, 87, 131
- GEOMETRY\_SUBROUTINE\_UNIFORM, 87, 90, 93, 94, 101, 131
- GEOMETRY\_TEXTURE, 498
- GEOMETRY\_VERTICES\_OUT, 143, 144, 363, 366, 538
- GEQUAL, 208, 242, 429, 430
- GET\_TEXTURE\_IMAGE\_FORMAT, 497
- GET\_TEXTURE\_IMAGE\_TYPE, 497
- GetActiveAtomicCounterBufferiv, 117, 118, 543
- GetActiveAttrib, 324, 537, 652
- GetActiveSubroutineName, 131, 542
- GetActiveSubroutineUniformiv, 132, 542
- GetActiveSubroutineUniformName, 132, 542
- GetActiveUniform, 115, 120, 537
- GetActiveUniformBlockiv, 116, 117, 540, 541
- GetActiveUniformBlockName, 116
- GetActiveUniformName, 114
- GetActiveUniformsiv, 115, 116, 539, 540, 543
- GetAttachedShaders, 145, 536
- GetAttribLocation, 323, 324, 537
- GetBooleani\_v, 447, 487, 526, 549
- GetBooleanv, 14, 427, 447, 486, 504, 515, 526, 532, 533, 552, 559, 577
- GetBufferParameteri64v, 68, 510
- GetBufferParameteriv, 68, 510
- GetBufferPointerv, 69, 510
- GetBufferSubData, 68, 510
- GetCompressedTexImage, 198–200, 211, 213, 214, 455, 485
- GetDebugMessageLog, 475, 481, 482

- GetDoublei\_v, 487, 511
- GetDoublev, 15, 486, 504
- GetError, 15, 16, 578
- GetFloati\_v, 487, 511
- GetFloatv, 11, 15, 387, 394, 427, 486, 504, 506, 513–515, 525, 526, 557, 558, 574
- GetFragDataIndex, 419, 420
- GetFragDataLocation, 419, 420
- GetFramebufferAttachmentParameteriv, 260, 280, 529
- GetFramebufferParameteriv, 259, 647
- GetInteger, 438, 564
- GetInteger64i\_v, 70, 487, 508, 550–553
- GetInteger64v, 14, 36, 45, 311, 486, 504, 557, 568, 573, 638
- GetIntegeri\_v, 70, 427, 438, 469, 487, 508, 515, 524, 525, 549–553, 566
- GetIntegerv, 14, 15, 45, 112, 122, 125–128, 153, 157, 176, 257, 263, 313, 368, 392, 393, 435, 445, 446, 454, 469, 486, 489, 504, 506, 508, 509, 511–514, 516, 517, 523–528, 530, 532, 533, 536, 550–553, 555–574, 576–578
- GetInternalformati64v, 491, 495
- GetInternalformativ, 203, 265, 490, 575
- GetMultisamplefv, 332, 393, 577
- GetObjectLabel, 482, 483, 507, 510, 519, 522, 528, 531, 534–536, 548, 552
- GetObjectPtrLabel, 483, 554
- GetPointerv, 481, 488, 571, 645
- GetProgramBinary, 109–111, 536
- GetProgramInfoLog, 81, 110, 145, 146, 536
- GetProgramInterfaceiv, 89, 92, 544
- GetProgramiv, 80, 109, 110, 142, 145, 146, 338, 342, 361, 363, 366, 469, 536–539, 541, 543
- GetProgramPipelineInfoLog, 145, 146
- GetProgramPipelineiv, 144, 146, 339, 535
- GetProgramPiplineInfoLog, 535
- GetProgramResourceIndex, 91
- GetProgramResourceiv, 92–94, 116–118, 123, 545, 546
- GetProgramResourceLocation, 101, 102
- GetProgramResourceLocationIndex, 101, 102
- GetProgramResourceName, 91
- GetProgramStageiv, 149, 542
- GetQueryIndexediv, 43
- GetQueryiv, 43, 573, 578
- GetQueryObjecti64v, 44
- GetQueryObjectiv, 44, 548
- GetQueryObjectui64v, 44
- GetQueryObjectuiv, 44, 548
- GetRenderbufferParameteriv, 266, 280, 531
- GetSamplerParameter, 159, 522
- GetSamplerParameterfv, 522
- GetSamplerParameterI{i ui}v, 159
- GetSamplerParameterIiv, 159
- GetSamplerParameterIuiv, 159
- GetSamplerParameteriv, 522
- GetShaderInfoLog, 76, 145, 146, 534
- GetShaderiv, 76, 77, 141, 146, 534
- GetShaderPrecisionFormat, 76, 147
- GetShaderSource, 146, 534
- GetString, 488, 489, 560, 635
- GetStringi, 489, 560, 658
- GetSubroutineIndex, 131
- GetSubroutineUniformLocation, 132, 650
- GetSynciv, 34, 37, 38, 554
- GetTexImage, 139, 212, 214, 241, 248,

- 250, 455, 497, 517
- GetTexLevelParameter, 210, 211, 520, 521
- GetTexParameter, 210, 233, 249, 280, 500, 518, 519
- GetTexParameterfv, 241, 518
- GetTexParameterI, 210
- GetTexParameterIiv, 210
- GetTexParameterIuiv, 210
- GetTexParameteriv, 241, 519
- GetTransformFeedbackVarying, 329, 538
- GetUniform, 537
- GetUniformBlockIndex, 116
- GetUniformdv, 148
- GetUniformfv, 148
- GetUniformIndices, 115
- GetUniformiv, 148
- GetUniformLocation, 114, 134, 135, 537
- GetUniformSubroutineuiv, 148
- GetUniformuiv, 148
- GetVertexAttribdv, 317, 318
- GetVertexAttribfv, 317, 318, 547
- GetVertexAttribIiv, 317, 318
- GetVertexAttribIuiv, 317, 318
- GetVertexAttribiv, 317, 318, 507, 508
- GetVertexAttribLdv, 317, 318
- GetVertexAttribPointerv, 318, 507
- gl\_, 89
- GL\_APPLE\_flush\_buffer\_range, 666
- GL\_APPLE\_vertex\_array\_object, 666
- GL\_ARB\_arrays\_of\_arrays, 677
- GL\_ARB\_base\_instance, 675
- GL\_ARB\_blend\_func\_extended, 670
- GL\_ARB\_cl\_event, 674
- GL\_ARB\_clear\_buffer\_object, 677
- GL\_ARB\_color\_buffer\_float, 663
- GL\_ARB\_compatibility, 630, 667
- GL\_ARB\_compressed\_texture\_pixel\_storage, 675
- GL\_ARB\_compute\_shader, 677
- GL\_ARB\_conservative\_depth, 675
- GL\_ARB\_copy\_buffer, 667
- GL\_ARB\_copy\_image, 677
- GL\_ARB\_debug\_group, 676, 677
- GL\_ARB\_debug\_label, 677
- GL\_ARB\_debug\_output, 674, 676
- GL\_ARB\_debug\_output2, 676, 678
- GL\_ARB\_depth\_buffer\_float, 664
- GL\_ARB\_depth\_clamp, 667
- GL\_ARB\_depth\_texture, 660
- GL\_ARB\_draw\_buffers, 663
- GL\_ARB\_draw\_buffers\_blend, 669
- GL\_ARB\_draw\_elements\_base\_vertex, 668
- GL\_ARB\_draw\_indirect, 672
- GL\_ARB\_draw\_instanced, 664, 665
- GL\_ARB\_ES2\_compatibility, 673
- GL\_ARB\_ES3\_compatibility, 678
- GL\_ARB\_explicit\_attrib\_location, 670
- GL\_ARB\_explicit\_uniform\_location, 678
- GL\_ARB\_fragment\_coord\_conventions, 668
- GL\_ARB\_fragment\_layer\_viewport, 678
- GL\_ARB\_fragment\_program, 661, 662
- GL\_ARB\_fragment\_program\_shadow, 663
- GL\_ARB\_fragment\_shader, 662
- GL\_ARB\_framebuffer\_no\_attachments, 678
- GL\_ARB\_framebuffer\_object, 664
- GL\_ARB\_framebuffer\_sRGB, 665
- GL\_ARB\_geometry\_shader4, 665
- GL\_ARB\_get\_program\_binary, 673
- GL\_ARB\_gpu\_shader5, 672
- GL\_ARB\_gpu\_shader\_fp64, 672
- GL\_ARB\_half\_float\_pixel, 664

- GL\_ARB\_half\_float\_vertex, 665
- GL\_ARB\_instanced\_arrays, 665
- GL\_ARB\_internalformat\_query, 675
- GL\_ARB\_internalformat\_query2, 678
- GL\_ARB\_invalidate\_subdata, 679
- GL\_ARB\_map\_buffer\_alignment, 676
- GL\_ARB\_map\_buffer\_range, 666
- GL\_ARB\_matrix\_palette, 660
- GL\_ARB\_multi\_draw\_indirect, 679
- GL\_ARB\_multisample, 659
- GL\_ARB\_multitexture, 659
- GL\_ARB\_occlusion\_query, 662
- GL\_ARB\_occlusion\_query2, 671
- GL\_ARB\_pixel\_buffer\_object, 664
- GL\_ARB\_point\_parameters, 659
- GL\_ARB\_point\_sprite, 662
- GL\_ARB\_program\_interface\_query, 679
- GL\_ARB\_provoking\_vertex, 668
- GL\_ARB\_robust\_buffer\_access\_behavior, 679
- GL\_ARB\_robustness, 674
- GL\_ARB\_robustness\_isolation, 680
- GL\_ARB\_sample\_shading, 669
- GL\_ARB\_sampler\_objects, 671
- GL\_ARB\_seamless\_cube\_map, 668
- GL\_ARB\_separate\_shader\_objects, 673
- GL\_ARB\_shader\_atomic\_counters, 676
- GL\_ARB\_shader\_bit\_encoding, 671
- GL\_ARB\_shader\_image\_load\_store, 676
- GL\_ARB\_shader\_image\_size, 679
- GL\_ARB\_shader\_objects, 662
- GL\_ARB\_shader\_precision, 673
- GL\_ARB\_shader\_stencil\_export, 674
- GL\_ARB\_shader\_storage\_buffer\_object, 679
- GL\_ARB\_shader\_subroutine, 672
- GL\_ARB\_shader\_texture\_lod, 667
- GL\_ARB\_shading\_language\_100, 662
- GL\_ARB\_shading\_language\_420pack, 675
- GL\_ARB\_shading\_language\_include, 670
- GL\_ARB\_shading\_language\_packing, 676
- GL\_ARB\_shadow, 661, 662
- GL\_ARB\_shadow\_ambient, 661
- GL\_ARB\_stencil\_texturing, 679
- GL\_ARB\_sync, 668
- GL\_ARB\_tessellation\_shader, 672
- GL\_ARB\_texture\_border\_clamp, 659
- GL\_ARB\_texture\_buffer\_object, 666
- GL\_ARB\_texture\_buffer\_object\_rgb32, 672
- GL\_ARB\_texture\_buffer\_range, 680
- GL\_ARB\_texture\_compression, 659
- GL\_ARB\_texture\_compression\_bptc, 670
- GL\_ARB\_texture\_compression\_rgtc, 666
- GL\_ARB\_texture\_cube\_map, 659
- GL\_ARB\_texture\_cube\_map\_array, 669
- GL\_ARB\_texture\_env\_add, 659
- GL\_ARB\_texture\_env\_combine, 660
- GL\_ARB\_texture\_env\_crossbar, 660
- GL\_ARB\_texture\_env\_dot3, 660
- GL\_ARB\_texture\_float, 664
- GL\_ARB\_texture\_gather, 669
- GL\_ARB\_texture\_mirrored\_repeat, 660
- GL\_ARB\_texture\_multisample, 668
- GL\_ARB\_texture\_non\_power\_of\_two, 662
- GL\_ARB\_texture\_query\_levels, 680
- GL\_ARB\_texture\_query\_lod, 670
- GL\_ARB\_texture\_rectangle, 663
- GL\_ARB\_texture\_rg, 666
- GL\_ARB\_texture\_rgb10\_a2ui, 671
- GL\_ARB\_texture\_storage, 676
- GL\_ARB\_texture\_storage\_multisample, 680
- GL\_ARB\_texture\_swizzle, 671

- GL\_ARB\_texture\_view, 680
- GL\_ARB\_timer\_query, 671
- GL\_ARB\_transform\_feedback2, 672
- GL\_ARB\_transform\_feedback3, 673
- GL\_ARB\_transform\_feedback\_instanced, 675
- GL\_ARB\_transpose\_matrix, 659
- GL\_ARB\_uniform\_buffer\_object, 667
- GL\_ARB\_vertex\_array\_bgra, 669
- GL\_ARB\_vertex\_array\_object, 666
- GL\_ARB\_vertex\_attrib\_64bit, 673
- GL\_ARB\_vertex\_attrib\_binding, 680
- GL\_ARB\_vertex\_blend, 660
- GL\_ARB\_vertex\_buffer\_object, 661
- GL\_ARB\_vertex\_program, 661
- GL\_ARB\_vertex\_shader, 662
- GL\_ARB\_vertex\_type\_2\_10\_10\_10\_rev, 671
- GL\_ARB\_viewport\_array, 673
- GL\_ARB\_window\_pos, 661
- GL\_ARB\_name, 658
- gl\_BackColor, 632
- gl\_BackSecondaryColor, 632
- gl\_ClipDistance, 337, 343, 344, 358, 360, 367
- gl\_ClipDistance[], 107, 365, 382
- gl\_ClipVertex, 343
- GL\_EXT\_framebuffer\_blit, 665
- GL\_EXT\_framebuffer\_multisample, 665
- GL\_EXT\_framebuffer\_object, 665
- GL\_EXT\_framebuffer\_sRGB, 665
- GL\_EXT\_texture\_compression\_rgtc, 666
- gl\_FragCoord, 415
- gl\_FragCoord.z, 581
- gl\_FragDepth, 417, 418, 581
- gl\_FrontFacing, 415
- gl\_in, 343, 358
- gl\_in[], 365
- gl\_InstanceID, 308, 311, 324, 336, 652
- gl\_InvocationID, 342, 343, 345, 364
- GL\_KHR\_debug, 677
- GL\_KHR\_texture\_compression\_astc\_ldr, 676
- GL\_KHR\_name, 658
- gl\_Layer, 282, 367, 368, 558
- gl\_MaxPatchVertices, 343, 344, 358, 359
- gl\_NextBuffer, 89, 91, 377
- gl\_NumSamples, 416
- gl\_NumWorkGroups, 469
- GL\_NV\_depth\_buffer\_float, 664
- GL\_NV\_half\_float, 665
- gl\_out, 344, 345
- gl\_PatchVerticesIn, 343, 358
- gl\_PerVertex, 108
- gl\_PointCoord, 396
- gl\_PointSize, 337, 343, 344, 358, 360, 365, 367, 395
- gl\_Position, 327, 337, 343, 344, 358, 360, 365, 367, 384, 587
- gl\_PrimitiveID, 343, 358, 367, 415, 416
- gl\_PrimitiveIDIn, 365
- gl\_SampleID, 416
- gl\_SampleMask, 417, 427
- gl\_SampleMaskIn, 416
- gl\_SamplePosition, 417
- gl\_SkipComponents, 377
- gl\_SkipComponents1, 89, 91
- gl\_SkipComponents2, 89, 91
- gl\_SkipComponents3, 89, 91
- gl\_SkipComponents4, 89, 91
- gl\_TessCoord, 348, 358, 584
- gl\_TessLevelInner, 344, 345, 358, 359
- gl\_TessLevelInner[1], 359
- gl\_TessLevelOuter, 344, 345, 358, 359
- gl\_TessLevelOuter[2], 359
- gl\_TessLevelOuter[3], 359
- gl\_VertexID, 324, 336, 416, 652

- gl\_VerticesOut, 638
- gl\_ViewportIndex, 367, 368, 385, 558
- GLX\_ARB\_create\_context, 471, 666
- GLX\_ARB\_create\_context\_profile, 630, 670
- GLX\_ARB\_create\_context\_robustness, 674
- GLX\_ARB\_fbconfig\_float, 663
- GLX\_ARB\_framebuffer\_sRGB, 665
- GLX\_ARB\_robustness\_application\_isolation, 681
- GLX\_ARB\_robustness\_share\_group\_isolation, 681
- GREATER, 208, 242, 429, 430
- GREEN, 164, 208, 240, 413, 457, 459, 518, 520, 529
- GREEN\_BITS, 634
- GREEN\_INTEGER, 164
- HALF\_FLOAT, 163, 250, 296, 458–460
- HIGH\_FLOAT, 147
- HIGH\_INT, 147
- Hint, 484, 635
- if, 86
- iimage1D, 97
- iimage1DArray, 98
- iimage2D, 97
- iimage2DArray, 98
- iimage2DMS, 98
- iimage2DMSArray, 98
- iimage2DRect, 97
- iimage3D, 97
- iimageBuffer, 98
- iimageCube, 97
- iimageCubeArray, 98
- image1D, 97
- image1DArray, 97
- image2D, 97
- image2DArray, 97
- image2DMS, 97
- image2DMSArray, 97
- image2DRect, 97
- image3D, 97
- IMAGE\_1D, 97
- IMAGE\_1D\_ARRAY, 97
- IMAGE\_2D, 97
- IMAGE\_2D\_ARRAY, 97
- IMAGE\_2D\_MULTISAMPLE, 97
- IMAGE\_2D\_MULTISAMPLE\_ARRAY, 97
- IMAGE\_2D\_RECT, 97
- IMAGE\_3D, 97
- IMAGE\_BINDING\_ACCESS, 549
- IMAGE\_BINDING\_FORMAT, 549
- IMAGE\_BINDING\_LAYER, 549
- IMAGE\_BINDING\_LAYERED, 549
- IMAGE\_BINDING\_LEVEL, 549
- IMAGE\_BINDING\_NAME, 549
- IMAGE\_BUFFER, 97
- IMAGE\_CLASS\_10\_10\_10\_2, 500
- IMAGE\_CLASS\_11\_11\_10, 500
- IMAGE\_CLASS\_1\_X\_16, 500
- IMAGE\_CLASS\_1\_X\_32, 500
- IMAGE\_CLASS\_1\_X\_8, 500
- IMAGE\_CLASS\_2\_X\_16, 500
- IMAGE\_CLASS\_2\_X\_32, 500
- IMAGE\_CLASS\_2\_X\_8, 500
- IMAGE\_CLASS\_4\_X\_16, 500
- IMAGE\_CLASS\_4\_X\_32, 500
- IMAGE\_CLASS\_4\_X\_8, 500
- IMAGE\_COMPATIBILITY\_CLASS, 500
- IMAGE\_CUBE, 97
- IMAGE\_CUBE\_MAP\_ARRAY, 97
- IMAGE\_FORMAT\_COMPATIBILITY\_BY\_CLASS, 249, 500
- IMAGE\_FORMAT\_COMPATIBILITY\_BY\_SIZE, 249, 500

- IMAGE\_FORMAT\_COMPATIBILITY\_TYPE, 210, 249, 500, 519
- IMAGE\_PIXEL\_FORMAT, 500
- IMAGE\_PIXEL\_TYPE, 500
- IMAGE\_TEXEL\_SIZE, 500
- imageBuffer, 97
- imageCube, 97
- imageCubeArray, 97
- IMPLEMENTATION\_COLOR\_READ\_FORMAT, 454, 557, 652
- IMPLEMENTATION\_COLOR\_READ\_TYPE, 454, 557, 652
- in, 359
- INCR, 429
- INCR\_WRAP, 429
- IndexPointer, 631
- INFO\_LOG\_LENGTH, 141, 142, 144–146, 534–536
- InitNames, 634
- INT, 95, 163, 211, 248, 250, 251, 261, 296, 460, 461, 494
- int, 95, 108, 122, 322
- INT\_2\_10\_10\_10\_REV, 294, 296, 298, 303
- INT\_IMAGE\_1D, 97
- INT\_IMAGE\_1D\_ARRAY, 98
- INT\_IMAGE\_2D, 97
- INT\_IMAGE\_2D\_ARRAY, 98
- INT\_IMAGE\_2D\_MULTISAMPLE, 98
- INT\_IMAGE\_2D\_MULTISAMPLE\_ARRAY, 98
- INT\_IMAGE\_2D\_RECT, 97
- INT\_IMAGE\_3D, 97
- INT\_IMAGE\_BUFFER, 98
- INT\_IMAGE\_CUBE, 97
- INT\_IMAGE\_CUBE\_MAP\_ARRAY, 98
- INT\_SAMPLER\_1D, 96
- INT\_SAMPLER\_1D\_ARRAY, 96
- INT\_SAMPLER\_2D, 96
- INT\_SAMPLER\_2D\_ARRAY, 96
- INT\_SAMPLER\_2D\_MULTISAMPLE, 96
- INT\_SAMPLER\_2D\_MULTISAMPLE\_ARRAY, 96
- INT\_SAMPLER\_2D\_RECT, 96
- INT\_SAMPLER\_3D, 96
- INT\_SAMPLER\_BUFFER, 96
- INT\_SAMPLER\_CUBE, 96
- INT\_SAMPLER\_CUBE\_MAP\_ARRAY, 96
- INT\_VEC2, 95
- INT\_VEC3, 95
- INT\_VEC4, 95
- INTENSITY, 633
- INTERLEAVED\_ATTRIBS, 142, 151, 327–329, 376, 538
- InterleavedArrays, 631
- INTERNALFORMAT\_ALPHA\_SIZE, 494
- INTERNALFORMAT\_ALPHA\_TYPE, 494
- INTERNALFORMAT\_BLUE\_SIZE, 494
- INTERNALFORMAT\_BLUE\_TYPE, 494
- INTERNALFORMAT\_DEPTH\_SIZE, 494
- INTERNALFORMAT\_DEPTH\_TYPE, 494
- INTERNALFORMAT\_GREEN\_SIZE, 494
- INTERNALFORMAT\_GREEN\_TYPE, 494
- INTERNALFORMAT\_PREFERRED, 493
- INTERNALFORMAT\_RED\_SIZE, 494
- INTERNALFORMAT\_RED\_TYPE, 494



- INTERNALFORMAT\_SHARED\_-  
SIZE, 494
- INTERNALFORMAT\_STENCIL\_-  
SIZE, 494
- INTERNALFORMAT\_STENCIL\_-  
TYPE, 494
- INTERNALFORMAT\_SUPPORTED, 491, 492
- interpolateAtCentroid, 412
- interpolateAtOffset, 412, 574
- interpolateAtSample, 412
- INVALID\_ENUM, 16, 17, 34, 38, 40, 41, 43–45, 56, 57, 59, 60, 64, 65, 68, 69, 75, 78, 83, 85, 90–92, 101, 102, 111, 133, 141, 143, 145, 148, 149, 153, 154, 158–161, 186, 189, 196, 199, 201, 204, 209, 213, 226, 234–237, 241, 258, 260, 262, 265–270, 279, 293, 298, 308, 312, 318, 328, 349, 374, 375, 396, 443, 445, 450, 451, 456, 463, 465, 476–479, 483, 487, 488, 490, 502
- INVALID\_FRAMEBUFFER\_OPERATION, 17, 190, 194, 279, 456, 463
- INVALID\_INDEX, 91, 148
- INVALID\_OPERATION, 17, 41, 42, 44, 45, 56–60, 63, 65–69, 76–79, 81–84, 90–92, 101, 102, 104–106, 109, 111, 120, 121, 126, 129, 133–135, 141, 143–149, 154, 157–159, 165, 167, 176, 185, 189, 190, 194, 195, 197–201, 203, 204, 209, 211, 213, 214, 226, 232–237, 255, 258, 260, 261, 263, 265, 266, 268–271, 298–301, 305, 307–309, 312, 315, 318, 320, 323–325, 328, 337–339, 341, 361, 368, 373–375, 377, 378, 380, 418–420, 435, 443, 445, 451, 454, 456, 457, 459, 463, 465, 466, 469, 470, 476, 604, 630–632, 647, 650, 651
- INVALID\_VALUE, 16, 17, 34–36, 38–43, 53, 54, 57–61, 63, 65, 67–70, 75–79, 81–85, 90–92, 101–103, 105, 106, 109, 111, 120, 121, 126, 129, 133–135, 141, 143, 145–149, 154–158, 160, 175, 184–186, 189–193, 196, 197, 201, 203, 204, 211–214, 224, 232, 234–238, 244, 245, 256–258, 263–265, 269–271, 293, 295, 298–301, 306, 308, 311, 314, 316, 318, 320, 323–325, 328, 338, 372, 373, 380, 386–388, 393, 395, 396, 398, 418, 424, 425, 427, 432, 433, 435, 441, 445, 446, 448, 450, 451, 463, 466, 469, 470, 476–480, 482, 483, 487, 488, 490, 503, 630, 632, 634, 647, 648, 650
- InvalidateBufferData, 67
- InvalidateBufferSubData, 67
- InvalidateFramebuffer, 451, 452
- InvalidateSubFramebuffer, 451, 647
- InvalidateTexImage, 239
- InvalidateTexSubImage, 238, 239
- INVERT, 429, 440
- IS\_PER\_PATCH, 94, 101, 546
- IS\_ROW\_MAJOR, 93, 99, 116, 545
- isampler1D, 96
- isampler1DArray, 96
- isampler2D, 96
- isampler2DArray, 96
- isampler2DMS, 96

- isampler2DMSArray, 96
- isampler2DRect, 96
- isampler3D, 96
- isamplerBuffer, 96
- isamplerCube, 96
- isamplerCubeArray, 96
- IsBuffer, 54
- IsEnabled, 425, 426, 438, 487, 488, 504, 509, 511, 513–515, 524, 525, 547, 571, 578
- IsEnabledi, 425, 432, 438, 488, 524, 525
- IsFramebuffer, 257
- IsList, 635
- ISOLINES, 143
- isolines, 347, 355, 358
- IsProgram, 84
- IsProgramPipeline, 103, 104
- IsQuery, 42
- IsRenderbuffer, 264
- IsSampler, 156, 158
- IsShader, 77
- IsSync, 38
- IsTexture, 155, 638
- IsTransformFeedback, 373
- IsVertexArray, 307
- ivec2, 95, 322
- ivec3, 95, 322
- ivec4, 95, 247, 248, 322
  
- KEEP, 429, 524
- KHR\_debug\_output, 653
  
- LABEL, 507, 510, 519, 522, 528, 531, 534–536, 548, 552, 554
- LAST\_VERTEX\_CONVENTION, 368, 381, 382, 512
- LAYER\_PROVOKING\_VERTEX, 368, 558
- Layered images, 259
  
- layout, 89, 100, 106, 108, 122, 124, 125, 127–129, 247, 248, 341, 361, 363, 364, 415, 420, 469
- LEFT, 432, 442, 443, 445, 446, 449, 456
- LEQUAL, 208, 240, 242, 429, 430, 519, 522
- LESS, 208, 242, 429, 430, 524
- LIGHT*i*, 632
- LIGHTING, 632
- LINE, 406, 408, 514
- LINE\_LOOP, 286, 362, 369, 376
- LINE\_SMOOTH, 398, 403, 513
- LINE\_SMOOTH\_HINT, 485, 555
- LINE\_STIPPLE, 632
- LINE\_STRIP, 143, 286, 362, 369, 376
- LINE\_STRIP\_ADJACENCY, 290, 362, 369
- LINE\_WIDTH, 513
- LINEAR, 190, 208, 216, 220, 221, 223, 225, 226, 228, 240, 261, 273, 331, 462, 463, 498, 518, 522
- LINEAR\_MIPMAP\_LINEAR, 208, 223, 225, 273
- LINEAR\_MIPMAP\_NEAREST, 208, 223, 224, 273
- LINES, 143, 286, 362, 369, 374–376
- lines, 362
- LINES\_ADJACENCY, 143, 288, 362, 369
- lines\_adjacency, 362
- LineStipple, 632
- LineWidth, 397, 630, 632
- LINK\_STATUS, 80, 110, 142, 536
- LinkProgram, 78, 80–83, 88, 107, 110, 111, 125, 134, 323, 328, 337, 367, 378, 419, 652
- ListBase, 635
- LoadIdentity, 631
- LoadMatrix, 631
- LoadName, 634

- LoadTransposeMatrix, 631
- LOCATION, 94, 100, 102, 546
- location, 89
- LOCATION\_INDEX, 94, 101, 102, 546
- LOGIC\_OP\_MODE, 525
- LogicOp, 439, 440
- LOW\_FLOAT, 147
- LOW\_INT, 147
- LOWER\_LEFT, 396
- LUMINANCE, 633
- LUMINANCE\_ALPHA, 633
- main, 346
- MAJOR\_VERSION, 489, 560
- MANUAL\_GENERATE\_MIPMAP, 497
- MAP\_FLUSH\_EXPLICIT\_BIT, 62, 64, 65
- MAP\_INVALIDATE\_BUFFER\_BIT, 62, 64
- MAP\_INVALIDATE\_RANGE\_BIT, 62, 64
- MAP\_READ\_BIT, 61–64
- MAP\_UNSYNCHRONIZED\_BIT, 63, 64
- MAP\_WRITE\_BIT, 61–64
- MapBuffer, 56, 59, 60, 64, 67, 378
- MapBufferRange, 59–64, 67
- mat $C$ , 123
- mat $C \times R$ , 123
- mat2, 95, 322
- mat2x3, 95, 322
- mat2x4, 95, 322
- mat3, 95, 322
- mat3x2, 95, 322
- mat3x4, 95, 322
- mat4, 95, 322
- mat4x2, 95, 322
- mat4x3, 95, 322
- MATRIX\_STRIDE, 93, 99, 116, 123, 545
- MatrixMode, 631
- MAX, 434
- MAX\_3D\_TEXTURE\_SIZE, 185, 270, 271, 557
- MAX\_ARRAY\_TEXTURE\_LAYERS, 185, 271, 557
- MAX\_ATOMIC\_COUNTER\_BUFFER\_BINDINGS, 71, 127, 568
- MAX\_ATOMIC\_COUNTER\_BUFFER\_SIZE, 568, 640
- MAX\_ATOMIC\_COUNTER\_BUFFERS, 127
- MAX\_ATTRIB\_STACK\_DEPTH, 635
- MAX\_CLIENT\_ATTRIB\_STACK\_DEPTH, 635
- MAX\_CLIP\_DISTANCES, 557
- MAX\_COLOR\_ATTACHMENTS, 254, 268, 279, 443–445, 451, 574
- MAX\_COLOR\_TEXTURE\_SAMPLES, 493, 573
- MAX\_COMBINED\_ATOMIC\_COUNTER\_BUFFERS, 568
- MAX\_COMBINED\_ATOMIC\_COUNTERS, 335, 568
- MAX\_COMBINED\_COMPUTE\_UNIFORM\_COMPONENTS, 113, 566
- MAX\_COMBINED\_DIMENSIONS, 495
- MAX\_COMBINED\_FRAGMENT\_UNIFORM\_COMPONENTS, 113, 570
- MAX\_COMBINED\_GEOMETRY\_UNIFORM\_COMPONENTS, 113, 570
- MAX\_COMBINED\_IMAGE\_UNIFORMS, 336, 569, 640

- MAX\_COMBINED\_IMAGE\_UNITS\_-  
 AND\_FRAGMENT\_OUT-  
 PUTS, 646
- MAX\_COMBINED\_SHADER\_OUT-  
 PUT\_RESOURCES, 251, 569,  
 646
- MAX\_COMBINED\_SHADER\_STOR-  
 AGE\_BLOCKS, 129, 336,  
 338, 568
- MAX\_COMBINED\_TESS\_CON-  
 TROL\_UNI-  
 FORM\_COMPONENTS, 113,  
 570
- MAX\_COMBINED\_TESS\_EVALUA-  
 TION\_UNI-  
 FORM\_COMPONENTS, 113,  
 570
- MAX\_COMBINED\_TEXTURE\_IM-  
 AGE\_UNITS, 134, 153, 157,  
 333, 567, 650
- MAX\_COMBINED\_UNIFORM\_-  
 BLOCKS, 122, 567, 652
- MAX\_COMBINED\_VERTEX\_UNI-  
 FORM\_COMPONENTS, 113,  
 570
- MAX\_COMPUTE\_ATOMIC\_-  
 COUNTER\_BUFFERS, 126,  
 566
- MAX\_COMPUTE\_ATOMIC\_COUN-  
 TERS, 335, 566
- MAX\_COMPUTE\_IMAGE\_UNI-  
 FORMS, 336, 566
- MAX\_COMPUTE\_SHADER\_STOR-  
 AGE\_BLOCKS, 128, 336, 566
- MAX\_COMPUTE\_SHARED\_MEM-  
 ORY\_SIZE, 470, 566, 652
- MAX\_COMPUTE\_TEXTURE\_IM-  
 AGE\_UNITS, 333, 566
- MAX\_COMPUTE\_UNIFORM\_-  
 BLOCKS, 122, 566, 652
- MAX\_COMPUTE\_UNI-  
 FORM\_COMPONENTS, 112,  
 566
- MAX\_COMPUTE\_WORK\_GROUP\_-  
 COUNT, 469, 566
- MAX\_COMPUTE\_WORK\_GROUP\_-  
 INVOCATIONS, 469, 566
- MAX\_COMPUTE\_WORK\_GROUP\_-  
 SIZE, 469, 566
- MAX\_CUBE\_MAP\_TEXTURE\_SIZE,  
 185, 232, 270, 557
- MAX\_DEBUG\_GROUP\_STACK\_-  
 DEPTH, 478, 572
- MAX\_DEBUG\_LOGGED\_MES-  
 SAGES, 475, 572
- MAX\_DEBUG\_MESSAGE\_LENGTH,  
 474, 477, 478, 572
- MAX\_DEPTH, 495
- MAX\_DEPTH\_TEXTURE\_SAMPLES,  
 493, 573
- MAX\_DRAW\_BUFFERS, 418, 419,  
 432, 433, 435, 445, 446, 450,  
 574
- MAX\_DUAL\_SOURCE\_-  
 DRAW\_BUFFERS, 418, 419,  
 435, 437, 574
- MAX\_ELEMENT\_INDEX, 311, 557
- MAX\_ELEMENTS\_INDICES, 313,  
 558
- MAX\_ELEMENTS\_VERTICES, 313,  
 558
- MAX\_FRAGMENT\_ATOMIC\_-  
 COUNTER\_BUFFERS, 126,  
 565
- MAX\_FRAGMENT\_ATOMIC\_COUN-  
 TERS, 335, 565
- MAX\_FRAGMENT\_IMAGE\_UNI-  
 FORMS, 336, 569, 640
- MAX\_FRAGMENT\_-  
 INPUT\_COMPONENTS, 416,

- 565
- MAX\_FRAGMENT\_INTERPOLATION\_OFFSET, 412, 574
- MAX\_FRAGMENT\_SHADER\_STORAGE\_BLOCKS, 128, 336, 565
- MAX\_FRAGMENT\_UNIFORM\_BLOCKS, 122, 565, 652
- MAX\_FRAGMENT\_UNIFORM\_COMPONENTS, 112, 565
- MAX\_FRAGMENT\_UNIFORM\_VECTORS, 112, 565
- MAX\_FRAMEBUFFER\_HEIGHT, 258, 276
- MAX\_FRAMEBUFFER\_LAYERS, 258, 276
- MAX\_FRAMEBUFFER\_SAMPLES, 258, 276
- MAX\_FRAMEBUFFER\_WIDTH, 258, 276
- MAX\_GEOMETRY\_ATOMIC\_COUNTER\_BUFFERS, 126, 564
- MAX\_GEOMETRY\_ATOMIC\_COUNTERS, 335, 564
- MAX\_GEOMETRY\_IMAGE\_UNIFORMS, 335, 569
- MAX\_GEOMETRY\_INPUT\_COMPONENTS, 366, 564
- MAX\_GEOMETRY\_OUTPUT\_COMPONENTS, 367, 564
- MAX\_GEOMETRY\_OUTPUT\_VERTICES, 366, 564
- MAX\_GEOMETRY\_SHADER\_INVOCATIONS, 564
- MAX\_GEOMETRY\_SHADER\_STORAGE\_BLOCKS, 128, 336, 564
- MAX\_GEOMETRY\_TEXTURE\_IMAGE\_UNITS, 333, 564
- MAX\_GEOMETRY\_TOTAL\_OUTPUT\_COMPONENTS, 367, 564
- MAX\_GEOMETRY\_UNIFORM\_BLOCKS, 122, 564, 652
- MAX\_GEOMETRY\_UNIFORM\_COMPONENTS, 112, 564
- MAX\_HEIGHT, 494, 495
- MAX\_IMAGE\_SAMPLES, 247, 569
- MAX\_IMAGE\_UNITS, 135, 244, 569
- MAX\_INTEGER\_SAMPLES, 266, 493, 573
- MAX\_LABEL\_LENGTH, 480, 572
- MAX\_LAYERS, 495
- MAX\_NAME\_LENGTH, 90, 92, 544
- MAX\_NUM\_ACTIVE\_VARIABLES, 90, 544
- MAX\_NUM\_COMPATIBLE\_SUBROUTINES, 90, 544
- MAX\_PATCH\_VERTICES, 293, 562
- MAX\_PROGRAM\_TEXEL\_OFFSET, 218, 567
- MAX\_PROGRAM\_TEXTURE\_GATHER\_OFFSET, 218, 565
- MAX\_RECTANGLE\_TEXTURE\_SIZE, 186, 559
- MAX\_RENDERBUFFER\_SIZE, 265, 557
- MAX\_SAMPLE\_MASK\_WORDS, 428, 573
- MAX\_SAMPLES, 266, 493, 573
- MAX\_SERVER\_WAIT\_TIMEOUT, 36, 573
- MAX\_SHADER\_STORAGE\_BLOCK\_SIZE, 128, 568
- MAX\_SHADER\_STORAGE\_BUFFER\_BINDINGS, 71, 129, 568
- MAX\_SUBROUTINE\_UNIFORM-

- LOCATIONS, 130, 567
- MAX\_SUBROUTINES, 130, 567
- MAX\_TESS\_CONTROL\_ATOMIC\_-  
COUNTER\_BUFFERS, 126,  
562
- MAX\_TESS\_CONTROL\_ATOMIC\_-  
COUNTERS, 335, 562
- MAX\_TESS\_CONTROL\_IMAGE\_-  
UNIFORMS, 335, 569
- MAX\_TESS\_CONTROL\_-  
INPUT\_COMPONENTS, 344,  
562
- MAX\_TESS\_CONTROL\_OUTPUT\_-  
COMPONENTS, 345, 562
- MAX\_TESS\_CONTROL\_SHADER\_-  
STORAGE\_BLOCKS, 128,  
336, 562
- MAX\_TESS\_CONTROL\_TEXTURE\_-  
IMAGE\_UNITS, 333, 562
- MAX\_TESS\_CONTROL\_TOTAL\_-  
OUTPUT\_COMPONENTS,  
346, 562
- MAX\_TESS\_CONTROL\_UNIFORM\_-  
BLOCKS, 122, 562, 652
- MAX\_TESS\_CONTROL\_UNI-  
FORM\_COMPONENTS, 112,  
562
- MAX\_TESS\_EVALUATION\_-  
ATOMIC\_COUNTER\_-  
BUFFERS, 126, 563
- MAX\_TESS\_EVALUATION\_-  
ATOMIC\_COUNTERS, 335,  
563
- MAX\_TESS\_EVALUATION\_IMAGE\_-  
UNIFORMS, 335, 569
- MAX\_TESS\_EVALUATION\_-  
INPUT\_COMPONENTS, 359,  
563
- MAX\_TESS\_EVALUATION\_OUT-  
PUT\_COMPONENTS, 360,  
563
- MAX\_TESS\_EVALUATION\_-  
SHADER\_STORAGE\_-  
BLOCKS, 128, 336, 563
- MAX\_TESS\_EVALUATION\_TEX-  
TURE\_IMAGE\_UNITS, 333,  
563
- MAX\_TESS\_EVALUATION\_UNI-  
FORM\_BLOCKS, 122, 563,  
652
- MAX\_TESS\_EVALUATION\_UNI-  
FORM\_COMPONENTS, 112,  
563
- MAX\_TESS\_GEN\_LEVEL, 349, 562
- MAX\_TESS\_PATCH\_COMPONENTS,  
345, 359, 562
- MAX\_TEXTURE\_BUFFER\_SIZE,  
205, 559
- MAX\_TEXTURE\_COORDS, 634
- MAX\_TEXTURE\_IMAGE\_UNITS,  
333, 414, 565
- MAX\_TEXTURE\_LOD\_BIAS, 217,  
557
- MAX\_TEXTURE\_SIZE, 185, 203, 270,  
557
- MAX\_TEXTURE\_UNITS, 634
- MAX\_TRANSFORM\_FEEDBACK\_-  
BUFFERS, 71, 328, 576
- MAX\_TRANSFORM\_FEEDBACK\_-  
INTERLEAVED\_COMPO-  
NENTS, 329, 576
- MAX\_TRANSFORM\_FEEDBACK\_-  
SEPARATE\_ATTRIBS, 328,  
377, 576
- MAX\_TRANSFORM\_FEEDBACK\_-  
SEPARATE\_COMPONENTS,  
329, 576
- MAX\_UNIFORM\_BLOCK\_SIZE, 567
- MAX\_UNIFORM\_BUFFER\_BIND-  
INGS, 71, 125, 126, 567, 648

- MAX\_UNIFORM\_LOCATIONS, 113, 567
- MAX\_VARYING\_COMPONENTS, 327, 567, 631
- MAX\_VARYING\_FLOATS, 631
- MAX\_VARYING\_VECTORS, 327, 567
- MAX\_VERTEX\_ATOMIC\_COUNTER\_BUFFERS, 126, 561
- MAX\_VERTEX\_ATOMIC\_COUNTERS, 335, 561
- MAX\_VERTEX\_ATTRIB\_BINDINGS, 298, 299, 301, 318, 559
- MAX\_VERTEX\_ATTRIB\_RELATIVE\_OFFSET, 298, 559
- MAX\_VERTEX\_ATTRIBS, 293, 295, 296, 298–301, 318, 323–325, 561
- MAX\_VERTEX\_IMAGE\_UNIFORMS, 335, 569
- MAX\_VERTEX\_OUTPUT\_COMPONENTS, 326, 344, 346, 360, 366, 367, 417, 561
- MAX\_VERTEX\_SHADER\_STORAGE\_BLOCKS, 128, 336, 561
- MAX\_VERTEX\_STREAMS, 39, 41–43, 380, 564
- MAX\_VERTEX\_TEXTURE\_IMAGE\_UNITS, 333, 561
- MAX\_VERTEX\_UNIFORM\_BLOCKS, 122, 561, 652
- MAX\_VERTEX\_UNIFORM\_COMPONENTS, 112, 561
- MAX\_VERTEX\_UNIFORM\_VECTORS, 112, 561
- MAX\_VIEWPORT\_DIMS, 387, 452, 558
- MAX\_VIEWPORTS, 385–387, 424–426, 558
- MAX\_WIDTH, 494
- MEDIUM\_FLOAT, 147
- MEDIUM\_INT, 147
- MemoryBarrier, 138, 140, 141
- memoryBarrier(), 137, 141
- MIN, 434
- MIN/MAG, 498
- MIN\_FRAGMENT\_INTERPOLATION\_OFFSET, 412, 574
- MIN\_MAP\_BUFFER\_ALIGNMENT, 62, 64, 559, 640
- MIN\_PROGRAM\_TEXEL\_OFFSET, 218, 567
- MIN\_PROGRAM\_TEXTURE\_GATHER\_OFFSET, 218, 565
- MIN\_SAMPLE\_SHADING\_VALUE, 394, 515
- MINOR\_VERSION, 489, 560
- MinSampleShading, 394
- MIPMAP, 497
- MIRRORED\_REPEAT, 157, 208, 220
- MultiDrawArrays, 310, 651
- MultiDrawArraysIndirect, 305, 310, 651
- MultiDrawElements, 304, 313, 651
- MultiDrawElementsBaseVertex, 304, 316, 651
- MultiDrawElementsIndirect, 305, 315, 651
- MULTISAMPLE, 393, 394, 397, 403, 408, 412, 426, 441, 515
- MultMatrix, 632
- MultTransposeMatrix, 632
- NAME\_LENGTH, 93, 94, 116, 117, 545
- NAND, 440
- NEAREST, 208, 215, 219, 221, 223, 225–228, 242, 273, 331, 332, 462, 463, 498

- NEAREST\_MIPMAP\_-
  - LINEAR, 208, 223, 225, 226, 240, 273
- NEAREST\_MIPMAP\_NEAREST, 208, 223, 224, 226, 228, 242, 273, 498
- NEVER, 208, 242, 429, 430
- NewList, 635
- NICEST, 485
- NO\_ERROR, 16
- NONE, 89, 195, 207, 211, 239, 240, 242, 260, 261, 272, 275, 330, 334, 414, 437, 441, 443–446, 450, 456, 492, 494, 496–502, 519, 520, 522, 529, 647
- NOOP, 440
- noperspective, 384
- NOR, 440
- NORMALIZE, 632
- NormalPointer, 631
- NOTEQUAL, 208, 242, 429, 430
- NULL, 474, 479, 482, 507, 510, 571
- NUM\_ACTIVE\_VARIABLES, 93, 100, 117, 118, 545
- NUM\_COMPATIBLE\_SUBROUTINES, 94, 132, 542, 546
- NUM\_COMPRESSED\_TEXTURE\_FORMATS, 176, 559, 631, 637
- NUM\_EXTENSIONS, 490, 560
- NUM\_PROGRAM\_BINARY\_FORMATS, 111, 559
- NUM\_SAMPLE\_COUNTS, 493, 575
- NUM\_SHADER\_BINARY\_FORMATS, 73, 77, 559
- NUM\_SHADING\_LANGUAGE\_VERSIONS, 490, 560, 648
- OBJECT\_TYPE, 34, 38, 554
- ObjectLabel, 479, 480, 482
- ObjectPtrLabel, 480
- OES\_compressed\_ETC1\_RGB8\_texture, 600
- OFFSET, 93, 99, 116, 545
- ONE, 208, 413, 434, 436, 437, 525
- ONE\_MINUS\_CONSTANT\_ALPHA, 436
- ONE\_MINUS\_CONSTANT\_COLOR, 436
- ONE\_MINUS\_DST\_ALPHA, 436
- ONE\_MINUS\_DST\_COLOR, 436
- ONE\_MINUS\_SRC1\_ALPHA, 435, 436
- ONE\_MINUS\_SRC1\_COLOR, 435, 436
- ONE\_MINUS\_SRC\_ALPHA, 436
- ONE\_MINUS\_SRC\_COLOR, 436
- OR, 440
- OR\_INVERTED, 440
- OR\_REVERSE, 440
- Ortho, 632
- out, 345
- OUT\_OF\_MEMORY, 16, 17, 59, 64, 203, 233, 265
- PACK\_ALIGNMENT, 455, 533
- PACK\_COMPRESSED\_BLOCK\_DEPTH, 214, 455, 533
- PACK\_COMPRESSED\_BLOCK\_HEIGHT, 214, 455, 533
- PACK\_COMPRESSED\_BLOCK\_SIZE, 214, 455, 533
- PACK\_COMPRESSED\_BLOCK\_WIDTH, 214, 455, 533
- PACK\_IMAGE\_HEIGHT, 212, 214, 455, 533
- PACK\_LSB\_FIRST, 455, 533, 631, 645, 653
- PACK\_ROW\_LENGTH, 214, 455, 533
- PACK\_SKIP\_IMAGES, 212, 214, 455, 533



- PACK\_SKIP\_PIXELS, 214, 455, 533
- PACK\_SKIP\_ROWS, 214, 455, 533
- PACK\_SWAP\_BYTES, 455, 533
- PassThrough, 634
- patch, 101, 341
- patch in, 359
- patch out, 345
- PATCH\_DE-
  - FAULT\_INNER\_LEVEL, 347, 349, 506
- PATCH\_DEFAULT\_OUTER\_LEVEL, 347, 349, 506
- PATCH\_VERTICES, 292, 293, 506
- PATCHES, 292, 341
- PatchParameterfv, 347
- PatchParameteri, 292, 357
- PauseTransformFeedback, 375
- PERSPECTIVE\_CORRECTION\_-
  - HINT, 635
- PIXEL\_BUFFER\_BARRIER\_BIT, 139
- PIXEL\_PACK\_BUFFER, 55, 139, 161, 453
- PIXEL\_PACK\_BUFFER\_BINDING, 212, 459, 533
- PIXEL\_UNPACK\_BUFFER, 55, 139, 161
- PIXEL\_UNPACK\_BUFFER\_BIND-
  - ING, 164, 196, 532
- PixelStore, 159, 160, 455, 467
- PixelZoom, 633
- POINT, 406, 408, 514
- POINT\_FADE\_THRESHOLD\_SIZE, 396, 513
- point\_mode, 349
- POINT\_SIZE, 513
- POINT\_SIZE\_GRANULARITY, 558
- POINT\_SIZE\_RANGE, 558
- POINT\_SMOOTH, 632
- POINT\_SMOOTH\_HINT, 635
- POINT\_SPRITE, 632
- POINT\_SPRITE\_COORD\_ORIGIN, 396, 513
- PointParameter, 396
- POINTS, 143, 286, 362, 368, 374–376, 406
- points, 361, 365
- PointSize, 395
- POLYGON, 633
- POLYGON\_MODE, 514
- POLYGON\_OFFSET\_FACTOR, 514
- POLYGON\_OFFSET\_FILL, 408, 514
- POLYGON\_OFFSET\_LINE, 408, 514
- POLYGON\_OFFSET\_POINT, 408, 514
- POLYGON\_OFFSET\_UNITS, 514
- POLYGON\_SMOOTH, 403, 408, 514
- POLYGON\_SMOOTH\_HINT, 485, 555
- POLYGON\_STIPPLE, 633
- PolygonMode, 406, 408, 409, 633
- PolygonOffset, 407
- PolygonStipple, 633
- PopAttrib, 635
- PopClientAttrib, 635
- PopDebugGroup, 478
- PopMatrix, 632
- PopName, 634
- PRIMITIVE\_RESTART, 302, 509
- PRIMITIVE\_RESTART\_FIXED\_IN-
  - DEX, 302
- PRIMITIVE\_RESTART\_INDEX, 509
- PrimitiveRestartIndex, 302
- PRIMITIVES\_GENERATED, 38, 40–43, 380
- PrioritizeTextures, 634
- PROGRAM, 479
- PROGRAM\_BINARY\_FORMATS, 111, 559
- PROGRAM\_BINARY\_LENGTH, 109, 110, 536
- PROGRAM\_BINARY\_RE-
  - TRIEVABLE\_HINT, 83, 111,

- 143, 536
- PROGRAM\_INPUT, 86, 89, 93, 94, 101, 324, 325, 652
- PROGRAM\_OUTPUT, 86, 89, 93, 94, 101, 420, 652
- PROGRAM\_PIPELINE, 479
- PROGRAM\_PIPELINE\_BINDING, 536
- PROGRAM\_POINT\_SIZE, 365, 395, 547
- PROGRAM\_SEPARABLE, 83, 85, 105, 143, 337, 536, 639
- ProgramBinary, 82, 83, 110, 111, 378, 652
- ProgramParameteri, 83, 111
- ProgramUniform, 121
- ProgramUniform{1234}ui, 121
- ProgramUniform{1234}uiv, 121
- ProgramUniformMatrix{234}, 121
- ProgramUniformMatrix{2x3,3x2,2x4,4x2,3x4,4x3}, 121
- PROVOKING\_VERTEX, 368, 512
- ProvokingVertex, 368, 381
- PROXY\_TEXTURE\_1D, 176, 187, 210, 234, 240
- PROXY\_TEXTURE\_1D\_ARRAY, 176, 186, 210, 235, 241
- PROXY\_TEXTURE\_2D, 176, 186, 210, 234, 240
- PROXY\_TEXTURE\_2D\_ARRAY, 174, 176, 210, 236, 241
- PROXY\_TEXTURE\_2D\_MULTISAMPLE, 202, 210, 237, 241
- PROXY\_TEXTURE\_2D\_MULTISAMPLE\_ARRAY, 202, 210, 237, 241
- PROXY\_TEXTURE\_3D, 174, 210, 236, 240
- PROXY\_TEXTURE\_CUBE\_MAP, 176, 186, 210, 234, 241
- PROXY\_TEXTURE\_CUBE\_MAP\_ARRAY, 174, 176, 210, 236, 241
- PROXY\_TEXTURE\_RECTANGLE, 176, 186, 196, 201, 210, 234, 241
- PushAttrib, 635
- PushClientAttrib, 635
- PushDebugGroup, 477, 478
- PushMatrix, 632
- PushName, 634
- QUAD\_STRIP, 633
- QUADS, 143, 541, 633
- quads, 347, 349, 352, 358
- QUERY, 479
- QUERY\_BY\_REGION\_NO\_WAIT, 320
- QUERY\_BY\_REGION\_WAIT, 320
- QUERY\_COUNTER\_BITS, 43, 573
- QUERY\_NO\_WAIT, 320
- QUERY\_RESULT, 44, 548
- QUERY\_RESULT\_AVAILABLE, 44, 548
- QUERY\_WAIT, 320
- QueryCounter, 39, 45
- R11F\_G11F\_B10F, 177, 178, 181, 231, 248, 250
- r11f\_g11f\_b10f, 248
- R16, 178, 179, 205, 231, 249, 251
- r16, 249
- R16\_SNORM, 178, 179, 231, 249, 251
- r16\_snorm, 249
- R16F, 178, 180, 205, 231, 248, 250
- r16f, 248
- R16I, 178, 181, 205, 231, 249, 251
- r16i, 249
- R16UI, 178, 181, 205, 231, 248, 250
- r16ui, 248
- R32F, 178, 180, 205, 231, 248, 250

- r32f, 248
- R32I, 178, 181, 205, 231, 249, 251
- r32i, 249
- R32UI, 178, 181, 205, 231, 248, 250
- r32ui, 248
- R3\_G3\_B2, 180
- R8, 178, 179, 205, 231, 249, 251, 520, 549
- r8, 249
- R8\_SNORM, 178, 179, 231, 249, 251
- r8\_snorm, 249
- R8I, 178, 181, 205, 231, 249, 251
- r8i, 249
- R8UI, 178, 181, 205, 231, 248, 250
- r8ui, 248
- RASTERIZER\_DISCARD, 280, 390, 513
- READ\_BUFFER, 195, 456, 528
- READ\_FRAMEBUFFER, 254, 255, 257, 258, 260, 262, 267–270, 278, 279, 451, 527
- READ\_FRAMEBUFFER\_BINDING, 190, 195, 257, 454, 456, 457, 463, 527
- READ\_ONLY, 55, 63, 64, 245, 549
- READ\_PIXELS, 496
- READ\_PIXELS\_FORMAT, 496
- READ\_PIXELS\_TYPE, 497
- READ\_WRITE, 55, 59, 63, 64, 245, 510
- ReadBuffer, 443, 444, 455, 456
- ReadPixels, 139, 159, 160, 166, 189, 212, 279, 282, 378, 453–457, 459, 461, 496, 497, 633
- RED, 164, 176, 179–181, 183, 208, 213, 214, 240, 250, 251, 275, 413, 414, 457, 459, 518, 520, 529
- RED\_BITS, 634
- RED\_INTEGER, 164, 250, 251
- REFERENCED\_BY\_COMPUTE\_SHADER, 93, 100, 117, 118, 546
- REFERENCED\_BY\_FRAGMENT\_SHADER, 93, 100, 117, 118, 546
- REFERENCED\_BY\_GEOMETRY\_SHADER, 93, 100, 117, 118, 546
- REFERENCED\_BY\_TESS\_CONTROL\_SHADER, 93, 100, 117, 118, 546
- REFERENCED\_BY\_TESS\_EVALUATION\_SHADER, 93, 100, 117, 118, 546
- REFERENCED\_BY\_VERTEX\_SHADER, 93, 100, 117, 118, 546
- ReleaseShaderCompiler, 76
- RENDERBUFFER, 260–268, 280, 464, 465, 479, 491, 493, 530
- RENDERBUFFER\_ALPHA\_SIZE, 266, 531
- RENDERBUFFER\_BINDING, 263, 530
- RENDERBUFFER\_BLUE\_SIZE, 266, 531
- RENDERBUFFER\_DEPTH\_SIZE, 266, 531
- RENDERBUFFER\_GREEN\_SIZE, 266, 531
- RENDERBUFFER\_HEIGHT, 264, 266, 531
- RENDERBUFFER\_INTERNAL\_FORMAT, 264, 266, 531
- RENDERBUFFER\_RED\_SIZE, 266, 531
- RENDERBUFFER\_SAMPLES, 264, 266, 277, 279, 531
- RENDERBUFFER\_STENCIL\_SIZE, 266, 531
- RENDERBUFFER\_WIDTH, 264, 266,

- 531
- RenderbufferStorage, 265, 278, 492
- RenderbufferStorageMultisample, 258, 264, 265, 492
- renderbuffertarget, 267
- RENDERER, 488, 560
- RenderMode, 634
- REPEAT, 157, 208, 220, 240
- REPLACE, 429
- RESCALE\_NORMAL, 632
- ResumeTransformFeedback, 374, 375, 378
- RG, 164, 176, 180, 181, 183, 213, 250, 251, 275, 414, 457, 459
- RG16, 178, 180, 205, 231, 249, 251
- rg16, 249
- RG16\_SNORM, 178, 180, 231, 249, 251
- rg16\_snorm, 249
- RG16F, 178, 180, 205, 231, 248, 250
- rg16f, 248
- RG16I, 178, 181, 206, 231, 248, 251
- rg16i, 248
- RG16UI, 178, 181, 206, 231, 248, 250
- rg16ui, 248
- RG32F, 178, 180, 205, 231, 248, 250, 466
- rg32f, 248
- RG32I, 178, 181, 206, 231, 248, 251, 466
- rg32i, 248
- RG32UI, 178, 181, 206, 231, 248, 250, 466
- rg32ui, 248
- RG8, 178, 180, 205, 231, 249, 251
- rg8, 249
- RG8\_SNORM, 178, 180, 231, 249, 251
- rg8\_snorm, 249
- RG8I, 178, 181, 206, 231, 248, 251
- rg8i, 248
- RG8UI, 178, 181, 206, 231, 248, 250
- rg8ui, 248
- RG\_INTEGER, 164, 250, 251
- RGB, 164, 168, 173, 176, 179–181, 183, 213, 250, 275, 414, 436, 457–459
- RGB10, 180
- RGB10\_A2, 177, 180, 231, 249, 251
- rgb10\_a2, 249
- RGB10\_A2UI, 177, 180, 231, 248, 250
- rgb10\_a2ui, 248
- RGB12, 180
- RGB16, 178, 180, 231
- RGB16\_SNORM, 178, 180, 231
- RGB16F, 178, 180, 231
- RGB16I, 178, 181, 231
- RGB16UI, 178, 181, 231
- RGB32F, 178, 180, 206, 231
- RGB32I, 178, 181, 206, 231
- RGB32UI, 178, 181, 206, 231
- RGB4, 180
- RGB5, 180
- RGB565, 177, 180
- RGB5\_A1, 177, 180
- RGB8, 178, 180, 231
- RGB8\_SNORM, 178, 180, 231
- RGB8I, 178, 181, 231
- RGB8UI, 178, 181, 231
- RGB9\_E5, 178, 181, 231, 243, 458, 647
- RGB\_INTEGER, 164, 168
- RGBA, 164, 168, 173, 176, 180, 181, 183, 213, 239, 248, 250, 251, 275, 414, 454, 457, 520, 531, 557, 592, 633
- RGBA12, 180
- RGBA16, 177, 180, 206, 231, 249, 251, 466
- rgba16, 249
- RGBA16\_SNORM, 178, 180, 231, 249, 251, 466

- rgba16\_snorm, 249
- RGBA16F, 177, 180, 206, 231, 248, 250, 466
- rgba16f, 248
- RGBA16I, 177, 181, 206, 231, 248, 251, 466
- rgba16i, 248
- RGBA16UI, 177, 181, 206, 231, 248, 250, 466
- rgba16ui, 248
- RGBA2, 180
- RGBA32F, 177, 181, 206, 231, 248, 250, 466
- rgba32f, 248
- RGBA32I, 177, 181, 206, 231, 248, 250, 466
- rgba32i, 248
- RGBA32UI, 177, 181, 206, 231, 248, 250, 466
- rgba32ui, 248
- RGBA4, 177, 180
- RGBA8, 177, 180, 206, 231, 249, 251, 593
- rgba8, 249
- RGBA8\_ETC2\_EAC, 614
- RGBA8\_SNORM, 178, 180, 231, 249, 251
- rgba8\_snorm, 249
- RGBA8I, 177, 181, 206, 231, 248, 251
- rgba8i, 248
- RGBA8UI, 177, 181, 206, 231, 248, 250
- rgba8ui, 248
- RGBA\_INTEGER, 164, 168, 248, 250, 251
- RGTC1\_RED, 231
- RGTC2\_RG, 231
- RIGHT, 432, 442, 443, 445, 446, 449, 456
- Rotate, 632
- sample, 412, 416
- sample in, 394, 412
- SAMPLE\_ALPHA\_TO\_COVERAGE, 426, 515
- SAMPLE\_ALPHA\_TO\_ONE, 426, 427, 515
- SAMPLE\_BUFFERS, 136, 190, 195, 279, 392, 397, 403, 408, 426, 430, 441, 447, 454, 455, 463, 577
- SAMPLE\_COVERAGE, 416, 426, 427, 515
- SAMPLE\_COVERAGE\_INVERT, 426, 427, 515
- SAMPLE\_COVERAGE\_VALUE, 426, 427, 515
- SAMPLE\_MASK, 416, 426, 427, 515
- SAMPLE\_MASK\_VALUE, 15, 426, 427, 515, 639
- SAMPLE\_POSITION, 393, 577
- SAMPLE\_SHADING, 394, 515
- SampleCoverage, 427
- SampleMaski, 427
- SAMPLER, 479
- sampler\*, 134
- sampler\*Shadow, 334, 414
- samplerID, 96
- samplerIDArray, 96
- samplerIDArrayShadow, 96
- samplerIDShadow, 96
- sampler2D, 96, 134
- sampler2DArray, 96
- sampler2DArrayShadow, 96
- sampler2DMS, 96
- sampler2DMSArray, 96
- sampler2DRect, 96
- sampler2DRectShadow, 96
- sampler2DShadow, 96
- sampler3D, 96
- SAMPLER\_1D, 96

- SAMPLER\_1D\_ARRAY, 96
- SAMPLER\_1D\_ARRAY\_SHADOW, 96
- SAMPLER\_1D\_SHADOW, 96
- SAMPLER\_2D, 96
- SAMPLER\_2D\_ARRAY, 96
- SAMPLER\_2D\_ARRAY\_SHADOW, 96
- SAMPLER\_2D\_MULTISAMPLE, 96
- SAMPLER\_2D\_MULTISAMPLE\_ARRAY, 96
- SAMPLER\_2D\_RECT, 96
- SAMPLER\_2D\_RECT\_SHADOW, 96
- SAMPLER\_2D\_SHADOW, 96
- SAMPLER\_3D, 96
- SAMPLER\_BINDING, 157, 517
- SAMPLER\_BUFFER, 96
- SAMPLER\_CUBE, 96
- SAMPLER\_CUBE\_MAP\_ARRAY, 96
- SAMPLER\_CUBE\_MAP\_ARRAY\_SHADOW, 96
- SAMPLER\_CUBE\_SHADOW, 96
- samplerBuffer, 96
- samplerCube, 96
- samplerCubeArray, 96
- samplerCubeArrayShadow, 96
- samplerCubeShadow, 96
- SamplerParameter, 157
- SamplerParameterI{*i ui*}v, 157
- SamplerParameterIv, 157
- SamplerParameterIuiv, 157
- SamplerParameteriv, 157
- SAMPLES, 203, 279, 393, 394, 430, 463, 493, 575, 577
- SAMPLES\_PASSED, 40–43, 319, 320, 430
- Scale, 632
- Scissor, 424, 425
- SCISSOR\_BOX, 524
- SCISSOR\_TEST, 424–426, 524
- ScissorArrayv, 424
- ScissorIndexed, 424, 425
- ScissorIndexedv, 424, 425
- SecondaryColorPointer, 631
- SelectBuffer, 634
- SEPARATE\_ATTRIBS, 142, 327–329, 376, 377
- SET, 440
- ShadeModel, 632
- SHADER, 479
- SHADER\_BINARY\_FORMATS, 78, 559
- SHADER\_COMPILER, 73, 559
- SHADER\_IMAGE\_ACCESS\_BARRIER\_BIT, 138, 141
- SHADER\_IMAGE\_ATOMIC, 499
- SHADER\_IMAGE\_LOAD, 499
- SHADER\_IMAGE\_STORE, 499
- SHADER\_SOURCE\_LENGTH, 141, 142, 146, 534
- SHADER\_STORAGE\_BARRIER\_BIT, 139
- SHADER\_STORAGE\_BLOCK, 87, 90, 93, 130
- SHADER\_STORAGE\_BUFFER, 55, 56, 129
- SHADER\_STORAGE\_BUFFER\_BINDING, 71, 551
- SHADER\_STORAGE\_BUFFER\_OFFSET\_ALIGNMENT, 71, 568
- SHADER\_STORAGE\_BUFFER\_SIZE, 71, 551
- SHADER\_STORAGE\_BUFFER\_START, 71, 551
- SHADER\_TYPE, 141, 150, 534
- ShaderBinary, 77, 78, 650
- ShaderSource, 75, 76, 146
- ShaderStorageBinding, 129
- ShaderStorageBlockBinding, 129
- SHADING\_LANGUAGE\_VERSION,

- 488–490, 560, 648
- shared, 470
- SHORT, 163, 251, 296, 460, 461
- SIGNALLED, 34, 38
- SIGNED, 598
- SIGNED\_NORMALIZED, 211, 261, 494
- SIMULTANEOUS\_TEXTURE\_AND\_DEPTH\_TEST, 500
- SIMULTANEOUS\_TEXTURE\_AND\_DEPTH\_WRITE, 501
- SIMULTANEOUS\_TEXTURE\_AND\_STENCIL\_TEST, 501
- SIMULTANEOUS\_TEXTURE\_AND\_STENCIL\_WRITE, 501
- SMOOTH\_LINE\_WIDTH\_GRANULARITY, 558
- SMOOTH\_LINE\_WIDTH\_RANGE, 558
- SRC1\_ALPHA, 435–437
- SRC1\_COLOR, 435–437
- SRC\_ALPHA, 436, 437
- SRC\_ALPHA\_SATURATE, 436
- SRC\_COLOR, 436, 437
- SRGB, 190, 243, 261, 433, 438, 439, 462, 498
- SRGB8, 178, 180, 231, 243
- SRGB8\_ALPHA8, 177, 180, 231, 243, 593
- SRGB\_ALPHA, 243, 592
- SRGB\_READ, 498
- SRGB\_WRITE, 498
- STACK\_OVERFLOW, 17, 478, 645, 649
- STACK\_UNDERFLOW, 17, 478, 645, 649
- STATIC\_COPY, 55, 58
- STATIC\_DRAW, 55, 58, 510
- STATIC\_READ, 55, 58
- std140, 124, 125, 128
- std430, 125, 128
- STENCIL, 260, 449, 450, 452, 520, 529
- STENCIL\_ATTACHMENT, 256, 268, 276
- STENCIL\_BACK\_FAIL, 524
- STENCIL\_BACK\_FUNC, 524
- STENCIL\_BACK\_PASS\_DEPTH\_FAIL, 524
- STENCIL\_BACK\_PASS\_DEPTH\_PASS, 524
- STENCIL\_BACK\_REF, 524
- STENCIL\_BACK\_VALUE\_MASK, 524
- STENCIL\_BACK\_WRITEMASK, 526
- STENCIL\_BITS, 634
- STENCIL\_BUFFER\_BIT, 448, 450, 461, 463
- STENCIL\_CLEAR\_VALUE, 526
- STENCIL\_COMPONENT, 334
- STENCIL\_COMPONENTS, 496
- STENCIL\_FAIL, 524
- STENCIL\_FUNC, 524
- STENCIL\_INDEX, 164, 174, 207, 213, 227, 228, 241, 265, 275, 334, 455–457
- STENCIL\_INDEX1, 265
- STENCIL\_INDEX16, 265
- STENCIL\_INDEX4, 265
- STENCIL\_INDEX8, 265, 266, 647
- STENCIL\_PASS\_DEPTH\_FAIL, 524
- STENCIL\_PASS\_DEPTH\_PASS, 524
- STENCIL\_REF, 524
- STENCIL\_RENDERABLE, 496
- STENCIL\_TEST, 428, 524
- STENCIL\_VALUE\_MASK, 524
- STENCIL\_WRITEMASK, 15, 526
- StencilFunc, 428, 429, 586
- StencilFuncSeparate, 428, 429
- StencilMask, 447, 586
- StencilMaskSeparate, 447

- StencilOp, 428, 429
- StencilOpSeparate, 428, 429
- STEREO, 577
- STREAM\_COPY, 55, 58
- STREAM\_DRAW, 55, 58
- STREAM\_READ, 55, 58
- SUBPIXEL\_BITS, 557
- SYNC\_CONDITION, 34, 38, 554
- SYNC\_FENCE, 34, 38, 554
- SYNC\_FLAGS, 34, 38, 554
- SYNC\_FLUSH\_COMMANDS\_BIT, 35–37
- SYNC\_GPU\_COMMANDS\_COMPLETE, 34, 38, 554
- SYNC\_STATUS, 34, 38, 554
  
- TESS\_CONTROL\_OUTPUT\_VERTICES, 143, 144, 342, 541
- TESS\_CONTROL\_SHADER, 75, 131, 342, 535
- TESS\_CONTROL\_SHADER\_BIT, 105
- TESS\_CONTROL\_SUBROUTINE, 87, 131
- TESS\_CONTROL\_SUBROUTINE\_UNIFORM, 87, 90, 93, 94, 101, 131
- TESS\_CONTROL\_TEXTURE, 498
- TESS\_EVALUATION\_SHADER, 75, 131, 355, 535
- TESS\_EVALUATION\_SHADER\_BIT, 105
- TESS\_EVALUATION\_SUBROUTINE, 87, 131
- TESS\_EVALUATION\_SUBROUTINE\_UNIFORM, 87, 90, 93, 94, 101, 131
- TESS\_EVALUATION\_TEXTURE, 498
- TESS\_GEN\_MODE, 143, 144, 541
- TESS\_GEN\_POINT\_MODE, 143, 144, 541
  
- TESS\_GEN\_SPACING, 143, 144, 541
- TESS\_GEN\_VERTEX\_ORDER, 143, 144, 541
- TexBuffer, 204, 492
- TexBufferRange, 203
- TexCoordPointer, 631
- TexEnv, 634
- TexImage, 153, 192
- TexImage\*D, 159–161, 196
- TexImage1D, 182, 187, 190, 192, 196, 199, 224, 240, 492
- TexImage2D, 182, 186, 187, 189, 191, 192, 196, 199, 224, 240, 241, 248, 492, 602
- TexImage2DMultisample, 202, 237, 241, 258, 493
- TexImage3D, 174, 175, 182, 184, 186, 187, 191, 192, 196, 199, 212, 224, 240, 241, 493
- TexImage3DMultisample, 202, 237, 241, 493
- TexParameter, 49, 153, 158, 207, 634
- TexParameterI, 207
- TexParameterIiv, 207
- TexParameterIuiv, 207
- TexParameteriv, 207
- TexStorage1D, 234, 493
- TexStorage2D, 234, 493
- TexStorage2DMultisample, 237, 493
- TexStorage3D, 235, 493
- TexStorage3DMultisample, 237, 493
- TexSubImage, 139, 192, 238
- TexSubImage\*D, 160
- TexSubImage1D, 191–194, 200
- TexSubImage2D, 191–194, 200, 231
- TexSubImage3D, 190–192, 194, 200, 238, 250
- TEXTURE, 260, 261, 271, 280, 479
- TEXTURE<sub>*i*</sub>, 153
- TEXTURE0, 153, 523



- TEXTURE\_*x*\_SIZE, 520  
 TEXTURE\_*x*\_TYPE, 520  
 TEXTURE\_*x*D, 516, 517  
 TEXTURE\_1D, 154, 175, 187, 190, 191, 207, 210, 212, 225, 226, 230, 232, 234, 246, 270, 491, 634  
 TEXTURE\_1D\_ARRAY, 154, 175, 186, 189, 191, 207, 210, 212, 225, 226, 230, 233, 235, 246, 465, 491, 516, 517, 634  
 TEXTURE\_2D, 134, 154, 175, 186, 189, 191, 207, 210, 212, 225, 226, 230, 232, 234, 246, 270, 491, 634  
 TEXTURE\_2D\_ARRAY, 154, 174, 176, 184, 191, 199, 201, 207, 210, 212, 225, 226, 230, 232, 233, 236, 246, 465, 491, 516, 517, 634  
 TEXTURE\_2D\_MULTISAMPLE, 154, 202, 207, 209, 210, 230, 232, 237, 238, 246, 270, 491, 493, 516  
 TEXTURE\_2D\_MULTISAMPLE\_ARRAY, 154, 202, 207, 209, 210, 230, 233, 237, 238, 246, 491, 493, 516  
 TEXTURE\_3D, 154, 174, 184, 191, 207, 210, 212, 225, 226, 230, 232, 236, 240, 246, 270, 465, 491, 634  
 TEXTURE\_ALPHA\_SIZE, 211  
 TEXTURE\_ALPHA\_TYPE, 211  
 TEXTURE\_BASE\_LEVEL, 207, 209, 224, 229, 240, 273, 274, 518  
 TEXTURE\_BINDING\_*x*D, 516  
 TEXTURE\_BINDING\_1D\_ARRAY, 516  
 TEXTURE\_BINDING\_2D\_ARRAY, 516  
 TEXTURE\_BINDING\_2D\_MULTISAMPLE, 516  
 TEXTURE\_BINDING\_2D\_MULTISAMPLE\_ARRAY, 516  
 TEXTURE\_BINDING\_BUFFER, 516  
 TEXTURE\_BINDING\_CUBE\_MAP, 516  
 TEXTURE\_BINDING\_CUBE\_MAP\_ARRAY, 516  
 TEXTURE\_BINDING\_RECTANGLE, 516  
 TEXTURE\_BLUE\_SIZE, 211  
 TEXTURE\_BLUE\_TYPE, 211  
 TEXTURE\_BORDER\_COLOR, 157, 159, 207, 209, 210, 219, 220, 239, 240, 518, 522  
 TEXTURE\_BUFFER, 55, 154, 204, 206, 211, 230, 238, 246, 465, 491, 516  
 TEXTURE\_BUFFER\_DATA\_STORE\_BINDING, 521  
 TEXTURE\_BUFFER\_OFFSET, 521  
 TEXTURE\_BUFFER\_OFFSET\_ALIGNMENT, 204, 559  
 TEXTURE\_BUFFER\_SIZE, 521  
 TEXTURE\_COMPARE\_FAIL\_VALUE\_ARB, 661  
 TEXTURE\_COMPARE\_FUNC, 208, 240, 241, 519, 522  
 TEXTURE\_COMPARE\_MODE, 207, 240–242, 334, 414, 519, 522  
 TEXTURE\_COMPONENTS, 633  
 TEXTURE\_COMPRESSED, 501, 521  
 TEXTURE\_COMPRESSED\_BLOCK\_HEIGHT, 502  
 TEXTURE\_COMPRESSED\_BLOCK\_SIZE, 502  
 TEXTURE\_COMPRESSED\_BLOCK\_

- WIDTH, 502
- TEXTURE\_COMPRESSED\_-
  - IMAGE\_SIZE, 198, 200, 211, 214, 521
- TEXTURE\_COMPRESSION\_HINT, 485, 555
- TEXTURE\_CUBE\_MAP, 154, 176, 186, 187, 207, 210, 211, 225, 226, 230–233, 235, 246, 465, 491, 516, 634
- TEXTURE\_CUBE\_MAP\_ARRAY, 154, 174, 176, 184, 185, 187, 191, 207, 210, 212, 225, 226, 230–233, 236, 246, 465, 491, 516, 517
- TEXTURE\_CUBE\_MAP\_NEGATIVE\_X, 215, 283, 517
- TEXTURE\_CUBE\_MAP\_NEGATIVE\_Y, 215, 283, 517
- TEXTURE\_CUBE\_MAP\_NEGATIVE\_Z, 215, 283, 517
- TEXTURE\_CUBE\_-
  - MAP\_POSITIVE\_X, 215, 283, 517
- TEXTURE\_CUBE\_-
  - MAP\_POSITIVE\_Y, 215, 283, 517
- TEXTURE\_CUBE\_-
  - MAP\_POSITIVE\_Z, 215, 283, 517
- TEXTURE\_CUBE\_MAP\_SEAMLESS, 215, 578
- TEXTURE\_DEPTH, 198, 200, 211, 520
- TEXTURE\_DEPTH\_SIZE, 211
- TEXTURE\_DEPTH\_TYPE, 211
- TEXTURE\_ENV, 634
- TEXTURE\_FETCH\_BARRIER\_BIT, 138
- TEXTURE\_FILTER\_CONTROL, 634
- TEXTURE\_FIXED\_SAMPLE\_LOCA-
  - TIONS, 203, 277, 520
- TEXTURE\_GATHER, 499
- TEXTURE\_GATHER\_SHADOW, 499
- TEXTURE\_GREEN\_SIZE, 211
- TEXTURE\_GREEN\_TYPE, 211
- TEXTURE\_HEIGHT, 194, 198, 200, 202, 203, 211, 520
- TEXTURE\_IMAGE\_FORMAT, 497
- TEXTURE\_IMAGE\_TYPE, 497
- TEXTURE\_IMMUTABLE\_FORMAT, 209, 210, 229, 232, 233, 237, 240, 519
- TEXTURE\_IMMUTABLE\_LEVELS, 209, 210, 229, 233, 240, 519
- TEXTURE\_INTERNAL\_FORMAT, 198, 200, 203, 211, 520, 633
- TEXTURE\_LOD\_BIAS, 208, 217, 518, 522, 634
- TEXTURE\_MAG\_FILTER, 208, 226, 240, 242, 518, 522
- TEXTURE\_MAX\_LEVEL, 208, 209, 224, 229, 240, 274, 518
- TEXTURE\_MAX\_LOD, 208, 209, 217, 240, 518, 522
- TEXTURE\_MIN\_FILTER, 208, 219, 220, 223, 226, 228, 240, 242, 273, 518, 522
- TEXTURE\_MIN\_LOD, 208, 209, 217, 240, 518, 522
- TEXTURE\_PRIORITY, 634
- TEXTURE\_RECTANGLE, 154, 176, 186, 189, 191, 196, 199, 201, 207, 210, 212, 213, 230, 232, 234, 238, 246, 270, 491, 516, 517
- TEXTURE\_RECTANGLE\_ARB, 663
- TEXTURE\_RED\_SIZE, 211
- TEXTURE\_RED\_TYPE, 211
- TEXTURE\_SAMPLES, 202, 203, 277, 279, 520

- TEXTURE\_SHADOW, 499  
 TEXTURE\_SHARED\_SIZE, 211, 520  
 TEXTURE\_STENCIL\_SIZE, 211  
 TEXTURE\_SWIZZLE\_A, 207, 208, 240, 413, 518  
 TEXTURE\_SWIZZLE\_B, 207, 208, 240, 413, 518  
 TEXTURE\_SWIZZLE\_G, 207, 208, 240, 413, 518  
 TEXTURE\_SWIZZLE\_R, 207, 208, 240, 413, 518  
 TEXTURE\_SWIZZLE\_RGBA, 207–209  
 TEXTURE\_UPDATE\_BARRIER\_BIT, 139  
 TEXTURE\_VIEW, 502  
 TEXTURE\_VIEW\_MIN\_LAYER, 210, 230, 240, 519  
 TEXTURE\_VIEW\_MIN\_LEVEL, 210, 230, 231, 240, 519  
 TEXTURE\_VIEW\_NUM\_LAYERS, 210, 230, 233, 240, 519  
 TEXTURE\_VIEW\_NUM\_LEVELS, 210, 230, 233, 240, 519  
 TEXTURE\_WIDTH, 194, 198, 200, 202, 203, 211, 520  
 TEXTURE\_WRAP\_R, 157, 208, 220, 518, 522, 633  
 TEXTURE\_WRAP\_S, 157, 208, 220, 518, 522, 633  
 TEXTURE\_WRAP\_T, 157, 208, 220, 518, 522, 633  
 textureGather, 218, 221, 222, 565, 669  
 textureGatherOffset, 221  
 textureLOD, 669  
 textureQueryLevels(), 332  
 textureSize(), 332  
 TextureView, 209, 229–231, 493, 502, 651  
 TIME\_ELAPSED, 40–43, 45, 649  
 TIMEOUT\_EXPIRED, 35  
 TIMEOUT\_IGNORED, 36  
 TIMESTAMP, 40, 43, 45, 46, 649  
 TOP\_LEVEL\_ARRAY\_SIZE, 94, 100, 546  
 TOP\_LEVEL\_ARRAY\_STRIDE, 94, 100, 546  
 TRANSFORM\_FEEDBACK, 373, 374, 479  
 TRANSFORM\_FEEDBACK\_ACTIVE, 552, 638  
 TRANSFORM\_FEEDBACK\_BARRIER\_BIT, 139  
 TRANSFORM\_FEEDBACK\_BINDING, 511  
 TRANSFORM\_FEEDBACK\_BUFFER, 55, 56, 376, 378  
 TRANSFORM\_FEEDBACK\_BUFFER\_ACTIVE, 638  
 TRANSFORM\_FEEDBACK\_BUFFER\_BINDING, 71, 552  
 TRANSFORM\_FEEDBACK\_BUFFER\_MODE, 142, 538  
 TRANSFORM\_FEEDBACK\_BUFFER\_PAUSED, 638  
 TRANSFORM\_FEEDBACK\_BUFFER\_SIZE, 71, 552  
 TRANSFORM\_FEEDBACK\_BUFFER\_START, 71, 552  
 TRANSFORM\_FEEDBACK\_PAUSED, 552, 638  
 TRANSFORM\_FEEDBACK\_PRIMITIVES\_WRITTEN, 39–43, 377, 380  
 TRANSFORM\_FEEDBACK\_VARYING, 87–89, 91, 93, 329  
 TRANSFORM\_FEEDBACK\_VARYING\_MAX\_LENGTH, 142,

- 538
- TRANSFORM\_FEED-  
BACK\_VARYINGS, 142, 329, 538
- TransformFeedbackVaryings, 88, 91, 327–329, 377
- Translate, 632
- TRIANGLE\_FAN, 288, 293, 362, 369, 376
- TRIANGLE\_STRIP, 143, 287, 293, 362, 369, 376, 385, 538
- TRIANGLE\_STRIP\_-  
ADJACENCY, 291, 293, 362, 369
- TRIANGLES, 143, 288, 293, 362, 369, 374–376, 538
- triangles, 347, 349, 350, 362
- TRIANGLES\_ADJACENCY, 143, 290, 293, 362, 369
- triangles\_adjacency, 362
- TRUE, 14, 15, 38, 42, 44, 54, 55, 63, 65, 73, 76, 77, 80, 83–85, 104, 110, 111, 120, 141–143, 155, 158, 160, 202, 209, 229, 232, 233, 237, 244, 246, 247, 257, 262, 264, 272, 277, 294, 297, 307, 317, 338, 373, 415, 427, 431, 446, 455, 458, 471, 476, 492, 495–497, 501, 515, 520, 525, 526, 571, 632
- TYPE, 89, 93, 94, 99, 115, 116, 324, 329, 545
- uimage1D, 98
- uimage1DArray, 98
- uimage2D, 98
- uimage2DArray, 98
- uimage2DMS, 98
- uimage2DMSArray, 98
- uimage2DRect, 98
- uimage3D, 98
- uimageBuffer, 98
- uimageCube, 98
- uimageCubeArray, 98
- uint, 95, 108, 122, 127, 322
- UNDEFINED\_VERTEX, 368
- UNIFORM, 86, 89, 93, 94, 101, 114, 115
- Uniform, 11
- Uniform1f, 11
- Uniform1i, 11
- Uniform2f, 11
- Uniform2i, 11
- Uniform3f, 11
- Uniform3i, 11
- Uniform4f, 11, 12
- Uniform4f{v}, 120
- Uniform4i, 12
- UNIFORM\_ARRAY\_-  
STRIDE, 116, 123, 127, 540, 650
- UNIFORM\_ATOMIC\_COUNTER\_-  
BUFFER\_INDEX, 116, 543
- UNIFORM\_BARRIER\_BIT, 138
- UNIFORM\_BLOCK, 86, 90, 93, 116, 117
- UNIFORM\_BLOCK\_ACTIVE\_UNIFORM\_INDICES, 117, 540
- UNIFORM\_BLOCK\_ACTIVE\_UNIFORMS, 117, 540
- UNIFORM\_BLOCK\_BINDING, 117, 540
- UNIFORM\_BLOCK\_DATA\_SIZE, 117, 126, 540
- UNIFORM\_BLOCK\_INDEX, 116, 539
- UNIFORM\_BLOCK\_NAME\_-  
LENGTH, 117
- UNIFORM\_BLOCK\_REFERENCED\_BY\_COMPUTE\_SHADER, 117, 541

- UNIFORM\_BLOCK\_REFERENCED\_-  
BY\_FRAGMENT\_SHADER, 117, 541
- UNIFORM\_BLOCK\_REFERENCED\_-  
BY\_GEOMETRY\_SHADER, 117, 541
- UNIFORM\_BLOCK\_REFERENCED\_-  
BY\_TESS\_CONTROL\_-  
SHADER, 117, 540
- UNIFORM\_BLOCK\_REFERENCED\_-  
BY\_TESS\_EVALUATION\_-  
SHADER, 117
- UNIFORM\_BLOCK\_REFERENCED\_-  
BY\_TESS\_EVALUTION\_-  
SHADER, 540
- UNIFORM\_BLOCK\_REFERENCED\_-  
BY\_VERTEX\_SHADER, 117, 540
- UNIFORM\_BUFFER, 55, 56, 125
- UNIFORM\_BUFFER\_BINDING, 71, 553
- UNIFORM\_BUFFER\_OFFSET\_-  
ALIGNMENT, 71, 567
- UNIFORM\_BUFFER\_SIZE, 71, 553
- UNIFORM\_BUFFER\_START, 71, 553
- UNIFORM\_IS\_ROW\_MAJOR, 116, 540
- UNIFORM\_MATRIX\_STRIDE, 116, 540
- UNIFORM\_NAME\_LENGTH, 116, 539, 542
- UNIFORM\_OFFSET, 116, 539
- UNIFORM\_SIZE, 116, 539, 542
- UNIFORM\_TYPE, 116, 539
- Uniform{1234}{ifd ui}, 119
- Uniform{1234}{ifd ui}v, 119
- UniformBlockBinding, 125, 126
- UniformMatrix2x4fv, 120
- UniformMatrix3dv, 120
- UniformMatrix{234}, 119
- UniformMatrix{2x3,3x2,2x4,4x2,3x4,4x3}, 119
- UniformSubroutinesuiv, 133
- UnmapBuffer, 50, 53, 58, 63, 65
- UNPACK\_ALIGNMENT, 160, 166, 175, 198, 532
- UNPACK\_COMPRESSED\_BLOCK\_-  
DEPTH, 160, 196, 532
- UNPACK\_COMPRESSED\_BLOCK\_-  
HEIGHT, 160, 196, 532
- UNPACK\_COMPRESSED\_BLOCK\_-  
SIZE, 160, 196, 532
- UNPACK\_COMPRESSED\_BLOCK\_-  
WIDTH, 160, 196, 532
- UNPACK\_IMAGE\_HEIGHT, 160, 175, 196, 198, 532
- UNPACK\_LSB\_FIRST, 160, 532, 631, 645, 653
- UNPACK\_ROW\_LENGTH, 160, 165, 166, 175, 196, 197, 532
- UNPACK\_SKIP\_IMAGES, 160, 175, 186, 196–198, 532
- UNPACK\_SKIP\_PIXELS, 160, 166, 196–198, 532
- UNPACK\_SKIP\_ROWS, 160, 166, 196–198, 532
- UNPACK\_SWAP\_BYTES, 160, 165, 532
- UNSIGNED, 34, 38, 554
- UNSIGNED, 598
- UNSIGNED\_BYTE, 163, 250, 251, 296, 298, 302, 311, 454, 460, 461, 557
- UNSIGNED\_BYTE\_2\_3\_3\_REV, 163, 168, 169, 460
- UNSIGNED\_BYTE\_3\_3\_2, 163, 168, 169, 460
- UNSIGNED\_INT, 95, 163, 211, 248, 250, 261, 296, 302, 311, 460, 461, 494

- UNSIGNED\_INT\_10\_10\_10\_2, 163, 168, 171, 460
- UNSIGNED\_INT\_10F\_11F\_11F\_REV, 163, 168, 171, 173, 250, 458, 460
- UNSIGNED\_INT\_24\_8, 161, 163, 168, 171, 455, 456, 460, 461
- UNSIGNED\_INT\_2\_10\_10\_10\_REV, 163, 168, 171, 250, 251, 294, 296, 298, 303, 460
- UNSIGNED\_INT\_5\_9\_9\_9\_REV, 163, 168, 171, 173, 179, 458, 460
- UNSIGNED\_INT\_8\_8\_8\_8, 163, 168, 171, 460
- UNSIGNED\_INT\_8\_8\_8\_8\_REV, 163, 168, 171, 460
- UNSIGNED\_INT\_ATOMIC\_COUNTER, 98
- UNSIGNED\_INT\_IMAGE\_1D, 98
- UNSIGNED\_INT\_IMAGE\_1D\_ARRAY, 98
- UNSIGNED\_INT\_IMAGE\_2D, 98
- UNSIGNED\_INT\_IMAGE\_2D\_ARRAY, 98
- UNSIGNED\_INT\_IMAGE\_2D\_MULTISAMPLE, 98
- UNSIGNED\_INT\_IMAGE\_2D\_MULTISAMPLE\_ARRAY, 98
- UNSIGNED\_INT\_IMAGE\_2D\_RECT, 98
- UNSIGNED\_INT\_IMAGE\_3D, 98
- UNSIGNED\_INT\_IMAGE\_BUFFER, 98
- UNSIGNED\_INT\_IMAGE\_CUBE, 98
- UNSIGNED\_INT\_IMAGE\_CUBE\_MAP\_ARRAY, 98
- UNSIGNED\_INT\_SAMPLER\_1D, 96
- UNSIGNED\_INT\_SAMPLER\_1D\_ARRAY, 97
- UNSIGNED\_INT\_SAMPLER\_2D, 97
- UNSIGNED\_INT\_SAMPLER\_2D\_ARRAY, 97
- UNSIGNED\_INT\_SAMPLER\_2D\_MULTISAMPLE, 97
- UNSIGNED\_INT\_SAMPLER\_2D\_MULTISAMPLE\_ARRAY, 97
- UNSIGNED\_INT\_SAMPLER\_2D\_RECT, 97
- UNSIGNED\_INT\_SAMPLER\_3D, 97
- UNSIGNED\_INT\_SAMPLER\_BUFFER, 97
- UNSIGNED\_INT\_SAMPLER\_CUBE, 97
- UNSIGNED\_INT\_SAMPLER\_CUBE\_MAP\_ARRAY, 97
- UNSIGNED\_INT\_VEC2, 95
- UNSIGNED\_INT\_VEC3, 95
- UNSIGNED\_INT\_VEC4, 95
- UNSIGNED\_NORMALIZED, 211, 261, 494
- UNSIGNED\_SHORT, 163, 250, 251, 296, 302, 311, 460, 461
- UNSIGNED\_SHORT\_1\_5\_5\_5\_REV, 163, 168, 170, 460
- UNSIGNED\_SHORT\_4\_4\_4\_4, 163, 168, 170, 460
- UNSIGNED\_SHORT\_4\_4\_4\_4\_REV, 163, 168, 170, 460
- UNSIGNED\_SHORT\_5\_5\_5\_1, 163, 168, 170, 460
- UNSIGNED\_SHORT\_5\_6\_5, 163, 168, 170, 460
- UNSIGNED\_SHORT\_5\_6\_5\_REV, 163, 168, 170, 460
- UPPER\_LEFT, 396, 513
- usampler1D, 96
- usampler1DArray, 97
- usampler2D, 97
- usampler2DArray, 97

- usampler2DMS, 97
- usampler2DMSArray, 97
- usampler2DRect, 97
- usampler3D, 97
- usamplerBuffer, 97
- usamplerCube, 97
- usamplerCubeArray, 97
- UseProgram, 82, 83, 104, 119, 133, 337–339, 378, 650
- UseProgramStages, 83, 104, 105, 133, 143, 337, 378, 650
- uvec2, 95, 322
- uvec3, 95, 322
- uvec4, 95, 247, 248, 322
- VALIDATE\_STATUS, 142, 144, 145, 338, 339, 535, 536
- ValidateProgram, 142, 338
- ValidateProgramPipeline, 144, 339
- vec2, 94, 322
- vec3, 94, 322
- vec4, 95, 120, 125, 247, 248, 322
- VENDOR, 488, 560
- VERSION, 488, 489, 560
- VERTEX\_ARRAY, 479
- VERTEX\_ARRAY\_BINDING, 317, 509
- VERTEX\_ATTRIB\_ARRAY\_BARRIER\_BIT, 138
- VERTEX\_ATTRIB\_ARRAY\_BUFFER\_BINDING, 138
- VERTEX\_ATTRIB\_ARRAY\_BUFFER\_BINDING, 304, 317, 508
- VERTEX\_ATTRIB\_ARRAY\_DIVISOR, 317, 507
- VERTEX\_ATTRIB\_ARRAY\_ENABLED, 317, 507
- VERTEX\_ATTRIB\_ARRAY\_INTEGER, 317, 507
- VERTEX\_ATTRIB\_ARRAY\_LONG, 317, 507, 645, 650
- VERTEX\_ATTRIB\_ARRAY\_NORMALIZED, 317, 507
- VERTEX\_ATTRIB\_ARRAY\_POINTER, 318, 507
- VERTEX\_ATTRIB\_ARRAY\_SIZE, 317, 507
- VERTEX\_ATTRIB\_ARRAY\_STRIDE, 300, 317, 507
- VERTEX\_ATTRIB\_ARRAY\_TYPE, 317, 507
- VERTEX\_ATTRIB\_BINDING, 508
- VERTEX\_ATTRIB\_RELATIVE\_OFFSET, 508
- VERTEX\_BINDING\_OFFSET, 508
- VERTEX\_BINDING\_STRIDE, 300, 508
- VERTEX\_PROGRAM\_TWO\_SIDE, 632
- VERTEX\_SHADER, 75, 131, 147, 148, 535
- VERTEX\_SHADER\_BIT, 105
- VERTEX\_SUBROUTINE, 87, 131
- VERTEX\_SUBROUTINE\_UNIFORM, 87, 90, 93, 94, 101, 131
- VERTEX\_TEXTURE, 498
- VertexAttrib, 294, 320
- VertexAttrib4, 294
- VertexAttrib4N, 294
- VertexAttrib4Nub, 294
- VertexAttribBinding, 299, 304
- VertexAttribDivisor, 301, 307, 308, 311, 314
- VertexAttribFormat, 296, 297
- VertexAttribI, 294
- VertexAttribIi, 322
- VertexAttribIui, 322
- VertexAttribI2i, 322

- VertexAttribI2ui, 322
- VertexAttribI3i, 322
- VertexAttribI3ui, 322
- VertexAttribI4, 294
- VertexAttribI4i, 322
- VertexAttribI4ui, 322
- VertexAttribIFormat, 296, 297
- VertexAttribIPointer, 297, 299, 317
- VertexAttribL1d, 322
- VertexAttribL2d, 322
- VertexAttribL3d, 322
- VertexAttribL3dv, 323
- VertexAttribL4d, 322
- VertexAttribL{1234}d, 294
- VertexAttribL{1234}dv, 294
- VertexAttribLFormat, 296, 297
- VertexAttribLPointer, 297, 299, 322, 323
- VertexAttribP\*uiv, 294
- VertexAttribP1ui, 294
- VertexAttribP2ui, 294
- VertexAttribP3ui, 294
- VertexAttribP4ui, 294
- VertexAttribPointer, 297, 299, 303, 306, 317, 632
- VertexBindingDivisor, 301
- VertexPointer, 631
- vertices, 341
- VIEW\_CLASS\_128\_BITS, 502
- VIEW\_CLASS\_16\_BITS, 502
- VIEW\_CLASS\_24\_BITS, 502
- VIEW\_CLASS\_32\_BITS, 502
- VIEW\_CLASS\_48\_BITS, 502
- VIEW\_CLASS\_64\_BITS, 502
- VIEW\_CLASS\_8\_BITS, 502
- VIEW\_CLASS\_96\_BITS, 502
- VIEW\_CLASS\_BPTC\_FLOAT, 502
- VIEW\_CLASS\_BPTC\_UNORM, 502
- VIEW\_CLASS\_RGTC1\_RED, 502
- VIEW\_CLASS\_RGTC2\_RG, 502
- VIEW\_COMPATIBILITY\_CLASS, 502
- VIEWPORT, 511
- Viewport, 386, 387
- VIEWPORT\_BOUNDS\_RANGE, 387, 558
- VIEWPORT\_INDEX\_-  
PROVOKING\_VERTEX, 368, 558
- VIEWPORT\_SUBPIXEL\_BITS, 388, 558
- ViewportArrayv, 386
- ViewportIndexedf, 386, 387
- ViewportIndexedfv, 386, 387
- WAIT\_FAILED, 35
- WaitSync, 33–37, 48, 50, 573
- WGL\_ARB\_create\_context, 471, 666
- WGL\_ARB\_create\_context\_profile, 630, 670
- WGL\_ARB\_create\_context\_robustness, 674
- WGL\_ARB\_framebuffer\_sRGB, 665
- WGL\_ARB\_pixel\_format\_float, 663
- WGL\_ARB\_robustness\_application\_isolation, 681
- WGL\_ARB\_robustness\_share\_group\_isolation, 681
- WRITE\_ONLY, 55, 63, 64, 245
- XOR, 440
- ZERO, 208, 413, 429, 434, 436, 437, 525