

Assessing Energy Efficiency of Fault Tolerance Protocols for HPC Systems

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Exascale

Energy

- Power management
(20MW budget)
- Administrative considerations
(1MW → \$1M/year)
- System codesign
(architectural features)

Fault Tolerance

- Size of the machine
(200,000 sockets → MTBF)
- Types of failures
(memory, accelerator, network)
- Different strategies

Energy Efficiency of Fault Tolerance Protocols

Agenda

- 1 Fault Tolerance Protocols
- 2 Experimental Setup
- 3 Experimental Results
- 4 Analytical Model
- 5 Discussion
- 6 Conclusions and Future Work

• Checkpoint/Restart

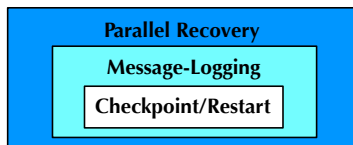
- State is saved periodically
- Coordinated global checkpoint
- Checkpoint stored locally
- Failure → global rollback

• Message-Logging

- Messages are stored at sender
- Non-determinism logged
- Determinants in causal path
- Failure → local rollback

• Parallel Recovery

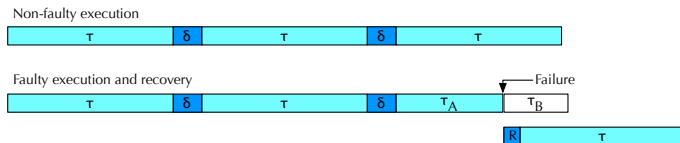
- Tasks are migratable
- Failure → recovery in parallel



Caveat

- Many variants of checkpoint/restart
- Several message-logging protocols
- Hybrid schemes

Optimum Checkpoint Period



Daly's modified model:

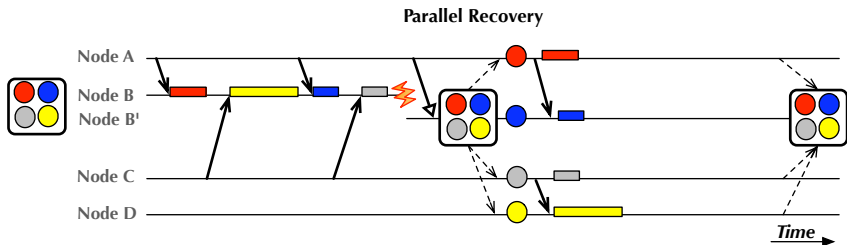
$$\tau = \sqrt{2\delta(M + R)} - \delta$$

Questions

- Optimum τ for message-logging and parallel recovery?
- Optimum τ to minimize energy?
- Execution time vs energy consumption?

Charm++ Runtime System

- Migratable Objects Model
- Asynchronous Method Invocation
- Adaptive MPI → each rank becomes an object
- Application-level checkpoint
- One process per *logical* node
- Failure injection: `kill -9 pid`
- Failure detection → automatic restart on replacement node
- Fault tolerance protocols at object-level



- **General Features**

- 40 single-socket nodes
- Each node has a four-core Intel Xeon and 4GB of main memory
- Gigabit ethernet switch

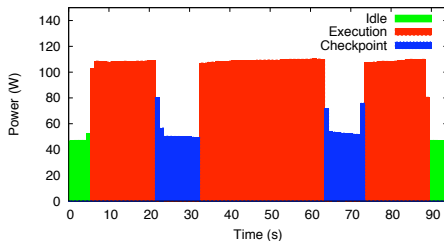
- **Power Measuring**

- Liebert power distribution unit (PDU)
- Power measurement per-node
- 1-second interval frequency



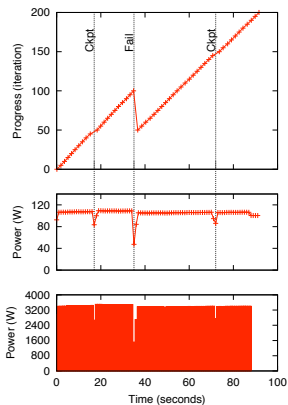
Checkpoint/Restart

- Test program
 - 7-point stencil
 - Nearest neighbor in 3D
 - Barrier after each step
 - Virtualization ratio = 32
 - 200 steps (checkpoints at 50 and 150)
- Local disk checkpoint

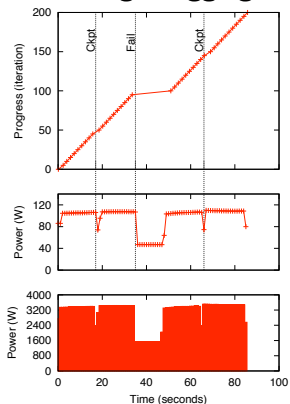


Total Energy Consumed

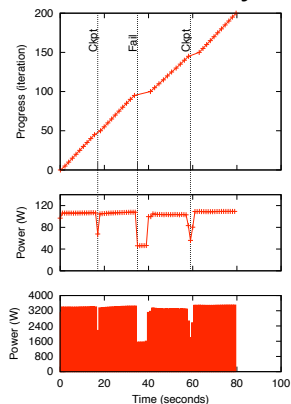
Checkpoint/Restart



Message-Logging

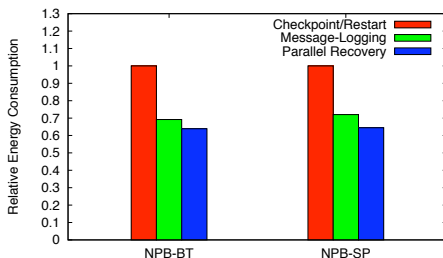


Parallel Recovery



Energy Consumption in Recovery

- Test programs
 - NAS Parallel Benchmarks
 - Block Tridiagonal (BT) and Scalar Pentadiagonal (SP)
 - Virtualization ratio = 4



Summary

	Jacobi3D	NPB-BT	NPB-SP
Language	Charm++	MPI	MPI
Problem size	1024 ³	class C	class C
Number of cores	128	100	100
Virtualization ratio	32	4	4
Recovery parallelism	8	4	4
Message-logging overhead	1.0%	3.6%	4.1%
Max power (C)	106	102	95
Max power (M)	106	102	96
Max power (P)	106	102	96

Message-logging does NOT increase power draw

Execution Time and Energy Model

Parameter	Description	Value
V	Optimal virtualization ratio	> 8
W	Time to solution with V	25 h
M	Mean-time-to-interrupt of the system	-
S	Total number of sockets in the system	-
δ	Checkpoint time	180 s
τ	Optimum checkpoint period	-
R	Restart time	30 s
T	Total execution time	-
E	Total energy consumption	-
μ	Message-logging slowdown	1.02
P	Available parallelism during recovery	8
ϕ	Message-logging recovery speedup	1.2
σ	Parallel recovery speedup	P
λ	Parallel recovery slowdown	$\frac{P+1}{P}$
H	Max power of each socket	100 W
L	Base power of each socket	40 W

Execution Time and Energy Formulas

$$T = T_{Solve} + T_{Checkpoint} + T_{Recover} + T_{Restart}$$

$$E = E_{Solve} + E_{Checkpoint} + E_{Recover} + E_{Restart}$$

Execution Time (Parallel Recovery)

$$T = W\mu + \left(\frac{W\mu}{\tau} - 1\right)\delta + \frac{T}{M} \left(\delta + \frac{\tau - \delta}{2\sigma} + \frac{\tau + \delta}{2}(\lambda - 1)\right) + \frac{T}{M}R$$

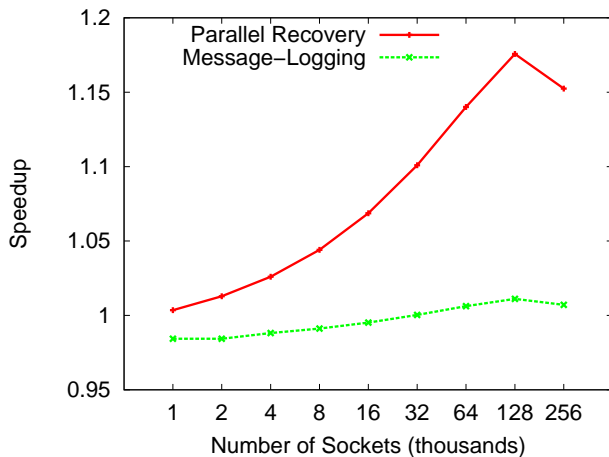
Energy (Parallel Recovery)

$$E = W\mu SH + \left(\frac{W\mu}{\tau} - 1\right)\delta SL + \frac{T}{M} \left(\delta SL + \frac{\tau - \delta}{2\sigma} (PH + (S - P)L) + \frac{\tau + \delta}{2}(\lambda - 1)SH\right) + \frac{T}{M}RSL$$

Time-optimum τ

Energy-optimum τ

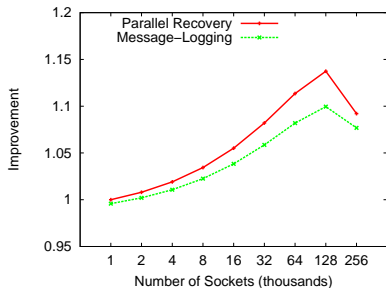
Improvement in Execution Time



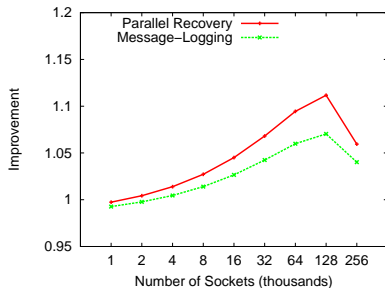
Up to 17% improvement

Improvement in Energy

Time-optimum τ



Energy-optimum τ



Up to 13% improvement

- Trend in ratio of base to maximum power

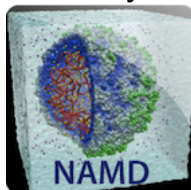
Processor	Release Date	Max Power	Base Power	Base/Max Ratio
Intel Xeon (E5520)	Q1,09	125	60	0.48
Intel Nehalem (i7 860)	Q3,09	151	52	0.34
Intel Sandy Bridge (i7 2600)	Q1,11	101	21	0.21

- Migratability and over-decomposition in scientific applications

- “*Minimize execution time \implies minimize energy*” (not true)
 - Increase checkpoint frequency
 - Recovery is more energy-efficient with message logging
- Energy overhead of message-logging
 - It does not increase power draw
 - It increases energy consumption on the forward path
- Parallel recovery leverages message-logging
 - It provides the minimum execution time (users happy)
 - It offers the minimum energy consumed (administrators happy)
 - The model predicts 17% reduction in execution time, 13% reduction in energy consumed

- Particle-simulation applications:

Molecular Dynamics



Quantum Chemistry



Cosmology



- Enhancements to analytical model:
 - Different failure distributions: Weibull, log-normal
 - No upper bound for checkpoint period
- Energy-aware fault tolerance protocols

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- **Prof. Tarek F. Abdelzaher.** The experimental results of this work come from the *Energy Cluster* in the University of Illinois at Urbana-Champaign.

Obrigado!

Q&A

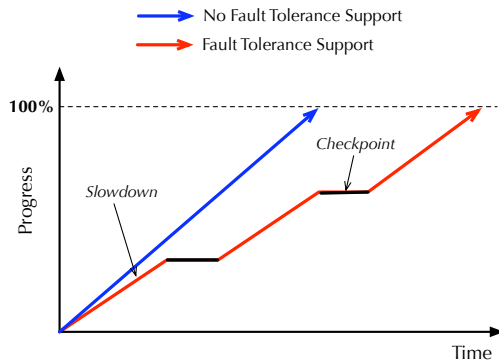
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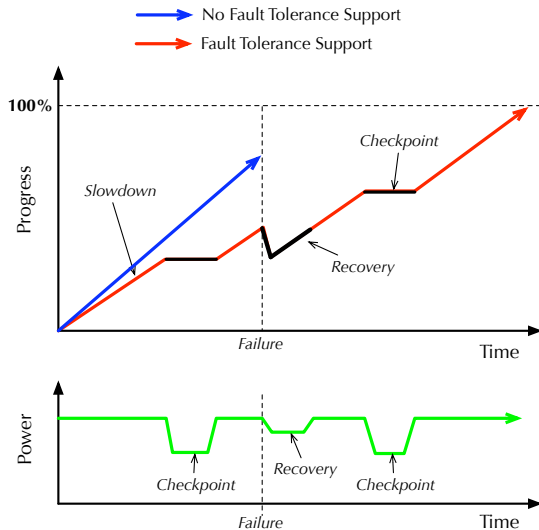
Columbia University

Progress Diagram

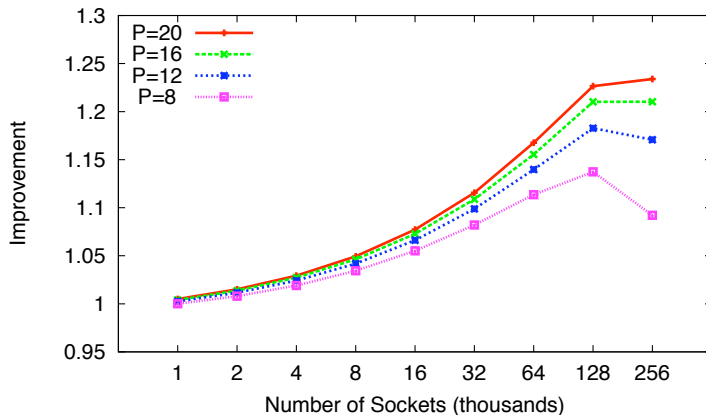


Performance Overhead

Progress Diagram for Energy Efficient Fault Tolerance



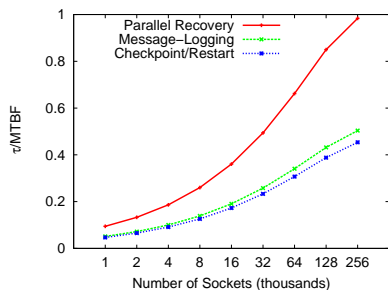
Effect of Higher Parallelism During Recovery



Optimum Checkpoint Period

- Optimum checkpoint period (τ) vs MTBF

Time-optimum τ



Energy-optimum τ

