Statistical Debugging

Benjamin Robert Liblit. Cooperative Bug Isolation. PhD Dissertation, University of California, Berkeley, 2004.

ACM Dissertation Award (2005)

Thomas D. LaToza 17-654 Analysis of Software Artifacts

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Despite the best QA efforts software will ship with bugs

Why would software be released with bugs?

Despite the best QA efforts software will ship with bugs

Why would software be released with bugs?

Value in getting user feedback early (betas)

Value in releasing ahead of competitors

Value in releasing to meet a planned launch date

Bug doesn't hurt the user all that much

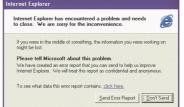
Even with much better analysis, will likely be attributes or problems hard to assure for some time

=> Free(1) testing by users!

With real test cases (not the ones developers thought users would experience)

By many users (might even find really rare bugs)

Result: Send Error Report Dialog



(1) For company writing software, not users....

Δ

Bugs produced by error reporting tools must be bucketed and prioritized

Company (e.g. Microsoft) buckets traces into distinct bugs Automated tool takes stack trace and assigns trace to bug bucket Bug buckets: count of number of traces, stack trace for each

All bugs are not equal - can make tradeoffs

Automated test coverage assumes all bugs are equal

Bug that corrupts Word docs, resulting in unrecoverable work, for 10% of users

Unlikely bug that causes application to produce wrong number in Excel spreadsheet

Limited time to fix bugs - which should you fix?

Frequency of bug (how many users? How frequently per user?) Importance of bug (what bad thing happened?)

But there are problems with the standard bug submission process

User hits bug and program crashes Program (e.g. Microsoft Watson) logs stack trace Stack trace sent to developers Tool classifies trace into bug buckets

Problems

WAY too many bug reports => way too many open bugs => can't spend a lot of time examining all of them Mozilla has 35,622 open bugs plus 81,168 duplicates (in 2004)

Stack trace not good bug predictor for some systems (e.g. event based systems)

 \Rightarrow bugs may be in multiple buckets or multiple bugs in single bucket

Stack trace may not have enough information to debug => hard to find the problem to fix

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What's wrong with debugging from a stack trace?

```
main()
   exif_data_save_data()
     exif_data_save_data_content()
        exif_data_save_data_content()
           exif_data_save_data_entry()
              exif_mnote_data_save()
                exif_mnote_data_canon_save()
                   memcpy()
                                                CRASH HERE SOMETIMES
// snippet of exif_mnote_data_canon_save()
for (i = 0; i < n->count; i++) {
  memcpy(*buf + doff, n->entries[i].data, s);
                                               CRASH HERE SOMETIMES
Scenario A – Bug assigned to bucket using stack trace
       What happens when other bugs produce crash with this trace?
   Scenario B - Debugging
       Seems to be a problem allocating memory
       Where is it allocated?
       Not in any of the functions in the stack trace....
       Arg..... It's going to be a long day.....
                                                                       7
```

Statistical debugging solves the problem - find predicates that predict bug!

```
Extra methods!
 exif_loader_get_data()
   exif_data_load_data()
                                     (o + s > buf_size) strong predictor
      exif_mnote_data_canon_load()
  exif_data_save_data()
    exif_data_save_data_content()
      exif_data_save_data_content()
         exif_data_save_data_entry()
           exif_mnote_data_save()
              exif_mnote_data_canon_save()
              memcpy() CRASH HERE SOMETIMES
// snippet of exif_mnote_data_canon_load()
for. (i = 0; i < c; i++) {
  n\rightarrow count = i + 1;
  if (o + s > buf_size) return;
                                   (o + s > buf_size) strong predictor
  n->entries[i].data = malloc(s);
                                                                          8
```

The goal of statistical debugging

Given set of program runs

Each run contains counters of predicates sampled at program points

Find

- Distinct bugs in code distinct problems occurring in program runs
- 2. For each bug, predicate that best predicts the bug

Statistical bugging technique sends reports for failing and successful runs Program runs on user computer Crashes or exhibits bug (failure)

Exits without exhibiting bug (success)

Counters count # times predicates hit

Counters sent back to developer for failing and successful runs

Statistical debugging finds predicates that predict bugs 100,000s to millions of predicates for small applications Finds the best bug predicting predicates amongst these

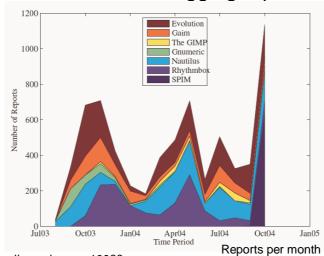
Problems to solve

Reports shouldn't overuse network bandwidth (esp ~2003) Logging shouldn't kill performance Interesting predicates need to be logged (fair sampling) Find good bug predictors from runs Handle multiple bugs in failure runs

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Deployment and Sampling

OSS users downloaded binaries submitting statistical debugging reports



Small user base ~ 100?? And only for small applications Got press on CNet, Slashdot in Aug 2003

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Data collected in predicate counters

Fundamental predicates sampled on user computer

"x < y on line 319 of utils.c" was observed to be true 25 times

"x = y on line 319 of utils.c" was observed to be true 3 times, and

"x > y on line 319 of utils.c" was observed to be true 1 time.

Infer predicates on developer's computer from fundamental predicates

"x \geq y on line 319 of utils.c" would have been observed to be true 3+1

" $x \neq y$ on line 319 of utils.c" would have been observed to be true 25+1 times and

" $x \le y$ on line 319 of utils.c" would have been observed to be true 25+3 times.

Predicates sampled at distinguished instrumentation site program points

Branches

if (condition) while(condition) for(; condition;)
Predicates – condition,!condition

Function entry

Predicate - count of function entries

Returns

Predicates - retVal < 0, retVal = 0, retVal > 0

Scalar pairs - assignment

x = y

Predicates x > z, x < z, x = z for all local / global variables z in scope

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Sampling techniques can be evaluated by several criteria

Minimize runtime overhead for user

Execution time

Memory footprint

Sample all predicates enough to find bugs

Maximize number of distinct predicates sampled

Maximize number of times predicate sampled

Make sample statistically fair – chance of sampling each instrumentation site each time encountered is the same

What's wrong with conventional sampling?

```
Approach 1: Every n executions of a statement
Approach 2: Sample every n statements
{
    if (counter == 100) { check(p != NULL); counter++}
        p = p->next

    if (counter == 100) { check(i < max); counter++}
        total += sizes[i]
    }

Approach 3: Toss a coin with probability of heads 1/100 ("Bernoulli trial")

{
    if (rnd(100) == 0) { check(p != NULL); counter++}
        p = p->next

    if (rnd(100) == 0) { check(i < max); counter++}
    total += sizes[i]
    }
```

Instead of testing whether to sample at every instrumentation site, keep countdown timer till next sample

Consider execution trace - at each instrumentation site

If 0, came up tails and don't sample

If 1, came up heads and sample predicates at instrumentation site Let the probability of heads (sampling) be p=1/5

Example execution trace



Time till next sample

Idea - keep countdown timer till next sample instead of generating each time

How to generate number to countdown from to sample with probability p = 1/5 at every instrumentation site?

Instead of testing whether to sample at every instrumentation site, keep countdown timer till next sample

Consider execution trace that hits list of instrumentation sites

If 0, came up tails and don't sample

If 1, came up heads and sample predicates at instrumentation site Let the probability of heads (sampling) be p=1/5

Example execution trace



Time till next sample

What's the probability that the next sample is at time t+k?

Time t: (1/5)

Time t+1 (4/5) * (1/5)

Time t+2 (4/5)^2 * (1/5)

Time t+3 (4/5)^3 * (1/5)

Time t+k (4/5)^k * (1/5)

 $=> p * (1 - p)^k => Geometric distribution$ Expected arrival time of a Bernoulli trial

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Generate a geometrically distributed countdown timer

 $=> p * (1 - p)^k => Geometric distribution$ Expected arrival time of a Bernoulli trial

When we sample at an instrumentation site Generate counter of instrumentation sites till next sample

Using geometric distribution

At every instrumentation site

Decrement counter

Check if counter is 0

If yes, sample

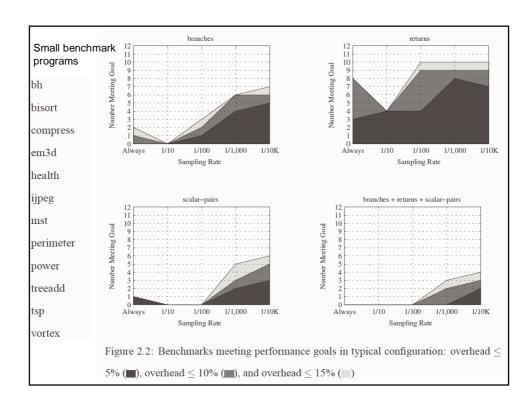
 \Rightarrow Achieve "statistically fair" sampling without overhead of random number generation at each instrumentation site

Yet more tricks - instead of checking countdown every sample, use fast & slow paths

```
if (countdown > 2) {
    /* fast path: no sample ahead */
    countdown -= 2;
    p = p->next;
    total += sizes[i];
} else {
    /* slow path: sample is imminent */
    if (--countdown == 0) {
        check(p != NULL);
        countdown = getNextCountdown();
    }
    p = p->next;

if (--countdown == 0) {
        check(i < max);
        countdown = getNextCountdown();
    }
    total += sizes[i];
}</pre>
```

More to do to make it work for loops and procedure calls Doubles memory footprint



Built a technique for sampling predicates cheaply!

How do we find bugs?

Statistical debugging

Predicate counters -> bugs & bug predictors

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There are several challenges from going from predicate counters to bugs and predictors

Feedback report R:

(x > y) at line 33 of util.c 55 times

... 100,000s more similar predicate counters

Label for report

F - fail (e.g. it crashes), or S succeeds (e.g. it doesn't crash)

Challenges

Lots of predicates - 100,000s

Bug is deterministic with respect to program predicate iff given predicate, bug must occur predicate soundly predicts bug Bugs may be nondeterministic & only occur sometimes

All we have is sampled data

Even if a predicate deterministically predicts bug We may not have sampled it on a particular run

=> Represent everything in probabilities rather than deterministic abstractions Instead of e.g. lattices, model checking state, Daikon true invariants, ...

Notation

Uppercase variables denote sets; lower case denotes item in set

- P set of fundamental and inferred predicates
- R feedback report

One bit – succeeded or failed Counter for each predicate p in P

R(p) - counter value for predicate p in feedback report R

R(p) > 0 – saw predicate in run

R(p) = 0 – never saw predicate in run

- $R(S)-counter\ value\ for\ instrumentation\ site\ S$ in feedback report R Sum of R(p) where p is sampled at S
- B bug profile set of feedback reports caused by a single bug Failing runs may be in more than one bug profile if they have more than one bug
- p is predictor iff R(p) > 0 ~> R in B Where ~> means statistically likely
- Goal : find minimal subset A of P such that A predicts all bugs; rank importance of p in A Looking at this predicate will help you find a whole bunch of bugs!

Approach

Prune away most predicates – totally irrelevant & worthless for any bug (98 – 99%) – really quickly Deal with other predicates in more detail

Deterministic bug example

Assume R(S) > 0 for all sites – i.e. all sites observed for all runs

R1: Succeeds (x > 5) at 3562 : R(P) = 23 (y > 23) at 1325 : R(P) = 0

R2: Fails (x > 5) at 3562 : R(P) = 13 (y > 23) at 1325: R(P) = 5

R3: Succeeds (x > 5) at 3562 : R(P) = 287 (y > 23) at 1325: R(P) = 0

Intuitively

Which predicate is the best predictor?

Approach 1 - Eliminate candidate predicates using strategies

Universal falsehood

R(P) = 0 on all runs R It is never the case that the predicate is true

Lack of failing coverage

R(S) = 0 on all failed runs in R The site is never sampled on failed runs

Lack of failing example

R(P) = 0 on all failed runs in R The predicate is not true whenever run fails

Successful counterexample

R(P) > 0 on at least one successful run in R P can be true without causing failure (assumes deterministic bug)

=>Predictors should be true in failing runs and false in succeeding runs

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Problems with Approach 1

Universal falsehood

R(P) = 0 on all runs R It is never the case that the predicate is true

Lack of failing coverage

R(S) = 0 on all failed runs in R The site is never sampled on failed runs

Lack of failing example

R(P) = 0 on all failed runs in R The predicate is not true whenever run fails

Successful counterexample

R(P) > 0 on at least one successful run in R P can be true without causing failure (assumes deterministic bug)

Assumes

Only one bug

May be no deterministic predictor for all bugs At least one deterministic predictor of bug Even a single counterexample will eliminate predicate If no deterministic predictor, all predicates eliminated

Iterative bug isolation and elimination algorithm

Infer which predicates correspond to which bugs
 Rank predicates in importance

Fix B and repeat
 Discard runs where R(p) > 0 for chosen predictor

2 increases the importance of predictors of less frequently bugs (occur in less runs)

Combination of assigning predicates to bugs and discarding runs handles multiple bugs!

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How to find the cause of the most important bug?

Consider the probability that p being true implies failing run Denote failing runs by Crash Assume there is only a single bug (for the moment)

Fail(P) = Pr(Crash | P observed to be true)

Conditional probability

Given that P happens, what's probability of crash

Can estimate Fail(P) for predicates Fail(P) = F(P) / (S(P) + F(P))Count of failing runs / (Count of all runs)

> Not the true probability it's a random variable we can never know But something that helps us best use observations to infer probability

What does Fail(P) mean?

Fail(P) = Pr(Crash | P observed to be true)

Fail(P) < 1.0

Nondeterministic with respect to P Lower scores -> less predictive of bug

Fail(P) = 1.0

Deterministic bug

Predicate true -> bug!

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But not quite enough....

```
f = ...;
if (f == NULL) {
    x = 0;
    *f;
}
(a)
(b)
(c)
(c)
(d)
```

Consider

```
Predicate (f == NULL) at (b)
Fail(f == NULL) = 1.0
Good predictor of bug!
```

Predicate (x == 0) at (c) Fail(x ==0) = 1.0 too! S(X == 0) = 0, F(X ==0) > 0 if the bug is ever hit

Not very interesting!

Execution is already doomed when we hit this predicate

Bug has nothing to do with this predicate

Would really like a predicate that fails as soon as the execution goes wrong

Instead of Fail(P), what is the increase of P?

```
f = ...; (a)

if (f == NULL) { (b)

    x = 0; (c)

    *f; (d)

Given that we've reached (c)
```

How much difference does it make that (x == 0) is true? None – at (c), probability of crash is 1.0!

Fail(P) = Pr(Crash | P observed to be true)

Estimate with

Fail(P) = F(P) / (S(P) + F(P))

Context(P) = Pr(Crash | P observed at all)

Estimate with

Context(P) = F(P observed) / (S(P observed) + F(P observed)

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Instead of Fail(P), what is the increase of P?

```
f = ...;
if (f == NULL) {
    x = 0;
    *f;
    (a)
    (b)
    (c)
    *f;
    (d)
```

Context(P) = Pr(Crash | P observed at all)

Estimate with

Context(P) = F(P observed) / (S(P observed) + F(P observed)

Increase(P) = Fail(P) - Context(P)

How much does P being true increase the probability of failure vs. P being observed? Fail(x == 0) = Context(x == 0) = 1.0 Increase(X == 0) = 1.0 - 1.0 = 0!

Increase(P) < 0 implies the predict isn't interesting and can be discarded

Eliminates invaraints, unreachable statements, other uninteresting predicates Localizes bugs at where program goes wrong, not crash site So much more useful than Fail(P)!

Instead of Fail(P), what is the increase of P?

```
f = ...;
if (f == NULL) {
    x = 0;
    *f;
    (d)
```

Increase(P) = Fail(P) - Context(P)

But Increase(P) may be based on few observations Estimate may be unreliable

Use 95% confidence interval

95% chance that estimate falls within confidence interval Throw away predicates where this interval is not strictly above 0

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Statistical interpretation of Increase(P) is likelihood ratio test

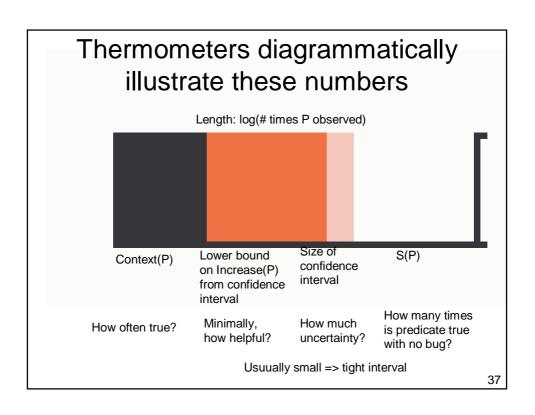
One of the most useful applications of statistics

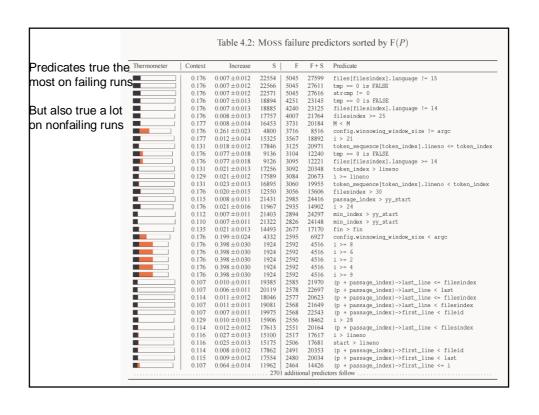
Two hypotheses

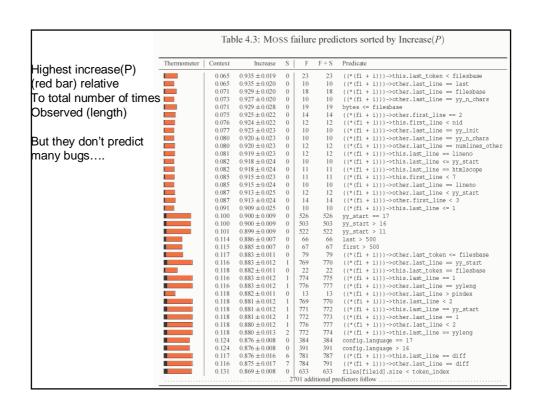
- Null Hypothesis: Fail(P) <= Context(P)
 <p>Alpha <= Beta</p>
- Alternative Hypothesis: Fail(P) > Context(P)
 Alpha > Beta

Fail P and Context P are really just ratios Alpha = F(P) / F(P observed) Beta = S(P) / S(P observed)

LRT compares hypotheses taking into account uncertainty from number of observations







How do we rank bugs by importance?

Approach 1 - Importance(P) = Fail(P)

failing runs for which P is true Maximum soundness – find lots of bugs!

May be true a lot on successful runs Large white bands

Approach 2 – Importance(P) = Increase(P)

How much does P true increase probability of failure?

Large red bands

Maximum precision – very few false positives!

Number of failing runs is small

Sub bug predictors – predict subset of a bug's set of failing runs Large black bands

How do we balance precision and soundness in this analysis?

Information retrieval interpretation Recall / precision

Soundness = recall

Match all the failing runs / bugs!

Preciseness = precision
Don't match successful runs / no bug!

Information retrieval solution - harmonic mean

$$Importance(P) = \frac{2}{\frac{1}{Increase(P)} + \frac{1}{log(F(P))/log(NumF)}}$$

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Thermometer	Context	Increase	S	F	F + S	Predicate
	0.176	0.824 ± 0.009	0	1585	1585	files[filesindex].language > 16
	0.176	0.824 ± 0.009	0	1584	1584	strcmp > 0
	0.176	0.824 ± 0.009	0	1580	1580	strcmp == 0
	0.176	0.824 ± 0.009	0	1577	1577	files[filesindex].language == 17
	0.176	0.824 ± 0.009	0	1576	1576	tmp == 0 is TRUE
	0.176	0.824 ± 0.009	0	1573	1573	strcmp > 0
	0.116	0.883 ± 0.012	1	774	775	((*(fi + i)))->this.last_line == 1
	0.116	0.883 ± 0.012	1	776	777	((*(fi + i)))->other.last_line == yyleng
	0.111	0.832 ± 0.027	73	1203	1276	config.match_comment is TRUE
	0.116	0.883 ± 0.012	1	769	770	((*(fi + i)))->other.last line == vv start
	0.118	0.880 ± 0.012	1	776	777	((*(fi + i)))->other.last_line < 2
	0.118	0.881 ± 0.012	1	772	773	((*(fi + i)))->other.last line == 1
	0.118	0.881 ± 0.012	1	771	772	((*(fi + i)))->this.last_line == yy_start
	0.118	0.881 ± 0.012	1	769	770	((*(fi + i)))->this.last_line < 2
	0.118	0.880 ± 0.013	2	772	774	((*(fi + i)))->this.last_line == yyleng
	0.117	0.876 ± 0.016	6	781	787	((*(fi + i)))->this.last line == diff
	0.116	0.875 ± 0.017	7	784	791	((*(fi + i)))->other.last_line == diff
	0.115	0.866 ± 0.021	16	826	842	((*(fi + i)))->other.last_line <= 3
	0.117	0.855 ± 0.024	25	864	889	((*(fi + i)))->this.last_line <= 4
	0.131	0.810 ± 0.026	79	1258	1337	token_sequence[token_index].val >= 100
	0.118	0.863 ± 0.021	15	798	813	((*(fi + i)))->other.last_line <= 2
	0.118	0.865 ± 0.021	14	787	801	((*(fi + i)))->this.last_line <= 2
	0.116	0.851 ± 0.026	30	862	892	((*(fi + i)))->other.last_line <= 4
	0.118	0.855 ± 0.025	22	776	798	((*(fi + i)))->this.last_line == nextstate
	0.131	0.859 ± 0.016	7	711	718	token_index > 500
	0.131	0.869 ± 0.008	0	639	639	files[fileid].size < token_count
	0.119	0.849 ± 0.027	26	779	805	((*(fi + i)))->other.last_line == nextstate
	0.131	0.869 ± 0.008	0	633	633	files[fileid].size < token_index
	0.100	0.900 ± 0.009	0	526	526	yy_start == 17
	0.101	0.899 ± 0.009	0	522	522	yy_start > 11
	0.117	0.844 ± 0.028	32	794	826	config.match_comment is TRUE
	0.118	0.829 ± 0.031	49	876	925	((*(fi + i)))->this.last_line < nid
	0.115	0.796 ± 0.032	115	1171	1286	<pre>(p + passage_index)->last_line < 2</pre>
	0.100	0.900 ± 0.009	0	503	503	yy_start > 16
	0.117	0.828 ± 0.031	52	879	931	((*(fi + i)))->other.last_line < nid
	0.116	0.839 ± 0.030	37	794	831	((*(fi + i)))->other.last_line <= diff
	0.117	0.840 ± 0.030	36	788	824	((*(fi + i)))->this.last_line <= diff
	0.116	0.818 ± 0.033	65	914	979	((*(fi + i)))->this.last_line < 8
	0.118	0.833 ± 0.031	40	778	818	((*(fi + i)))->this.last line <= nextstate

Statistical Debugging Algorithm

- 1. Rank predicates by Importance.
- 2. Remove the top-ranked predicate P and discard all runs R (feedback reports) where R(P)>0.
- 3. Repeat these steps until the set of runs is empty or the set of predicates is empty.

		Run	s		Predicate Counts			
	Lines of Code	Successful	Failing	Sites	Initial	Increase > 0	Elimination	
Moss	6,001	26,299	5,598	35,223	202,998	2,740	21	
CCRYPT	5,276	20,684	10,316	9,948	58,720	50	2	
BC	14,288	23,198	7,802	50,171	298,482	147	2	
R HYTHMBOX	56,484	12,530	19,431	145,176	857,384	537	15	
EXIF	10,588	30,789	2,211	27,380	156,476	272	3	

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Questions

- How much better is this than release build asserts? How many of these predicates would never have been added as asserts?
- How much more useful are the predicates than just the bug stack? How much better do they localize the bug?