

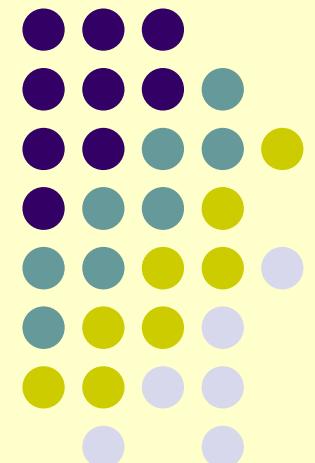
# Declarative Static Program Analysis with Doop

Jonathan Aldrich

17-355/17-665/17-819: Program Analysis

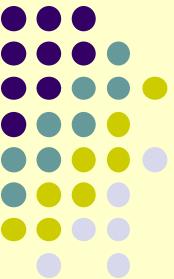
Slides adapted by permission from Yannis Smaragdakis

Based on work with Martin Bravenboer,  
George Kastrinis,  
George Balatsouras



European Research Council  
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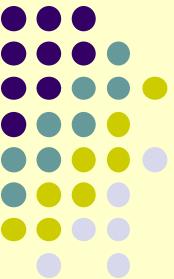




# Overview

- Declarative pointer analysis
  - Specified as logical rules in Datalog
  - Supports various forms of context-sensitivity
- Efficient implementation
  - Datalog execution model
  - Optimization of Datalog queries
- Why do we care?
  - Easy to understand, modify, and optimize
  - Best analysis performance available today





# Pointer Analysis

- What objects can a variable point to?

program

```
void foo() {  
    Object a = new A1();  
    Object b = id(a);  
}
```

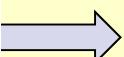
```
void bar() {  
    Object a = new A2();  
    Object b = id(a);  
}
```

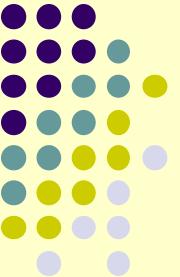
```
Object id(Object a) {  
    return a;  
}
```

points-to

foo:a	new A1()
bar:a	new A2()

objects represented  
by allocation sites





# Pointer Analysis

- What objects can a variable point to?

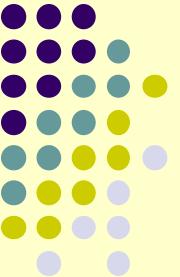
program

```
void foo() {  
    Object a = new A1();  
    Object b = id(a);  
}  
  
void bar() {  
    Object a = new A2();  
    Object b = id(a);  
}  
  
Object id(Object a) {  
    return a;  
}
```

points-to

foo:a	new A1()
bar:a	new A2()
id:a	new A1(), new A2()





# Pointer Analysis

- What objects can a variable point to?

program

```
void foo() {  
    Object a = new A1();  
    Object b = id(a);  
}  
  
void bar() {  
    Object a = new A2();  
    Object b = id(a);  
}  
  
Object id(Object a) {  
    return a;  
}
```

points-to

foo:a	new A1()
bar:a	new A2()
id:a	
foo:b	
bar:b	

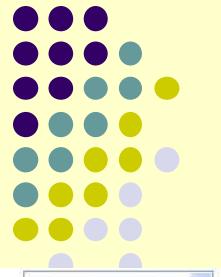
remember for later:  
context-sensitivity is what  
makes an analysis precise

context-sensitive points-to

foo:a	new A1()
bar:a	new A2()
id:a (foo)	new A1()
id:a (bar)	new A2()
foo:b	new A1()
bar:b	new A2()



# Pointer Analysis: A Complex Domain



flow-sensitive  
field-sensitive  
heap cloning  
context-sensitive  
binary decision diagrams  
inclusion-based  
unification-based  
on-the-fly call graph  
k-cfa  
object sensitive  
field-based  
demand-driven



Results 1 - 20 of 2,343  

[Save results to a Binder](#) Sort by relevance in expanded form  

Result page: 1 2 3 4 5 6 7 8 9 10 next >>

**1 Semi-sparse flow-sensitive pointer analysis**  
January 2009 **POPL '09: Proceedings of the 36th annual ACM SIGPLAN-SIGACT symposium on Principles of programming languages**  
**Publisher:** ACM  
Full text available: [Pdf](#) (246.09 KB) Additional Information: [full citation](#), [abstract](#), [references](#), [index terms](#)  
**Bibliometrics:** Downloads (6 Weeks): 34, Downloads (12 Months): 34, Citation Count: 0

Pointer analysis is a prerequisite for many program analyses, and the effectiveness of these analyses depends on the precision of the pointer information they receive. Two major axes of pointer analysis precision are flow-sensitivity and context-sensitivity, ...

**Keywords:** alias analysis, pointer analysis

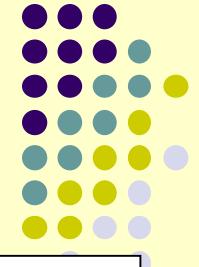
**2 Efficient field-sensitive pointer analysis of C**  
David J. Pearce, Paul M.J. Kelly, Chris Hankin  
November 2007 **Transactions on Programming Languages and Systems (TOPLAS)**, Volume 30 Issue 1  
**Publisher:** ACM  
Full text available: [Pdf](#) (924.64 KB) Additional Information: [full citation](#), [abstract](#), [references](#), [index terms](#)  
**Bibliometrics:** Downloads (6 Weeks): 31, Downloads (12 Months): 282, Citation Count: 1

The subject of this article is flow- and context-insensitive pointer analysis. We present a novel approach for precisely modelling struct variables and indirect function calls. Our method emphasises efficiency and simplicity and is based on a simple ...

**Keywords:** Set-constraints, pointer analysis

**3 Cloning-based context-sensitive pointer alias analysis using binary decision diagrams**  
John Whaley, Monica S. Lam  
June 2004 **PLDI '04: Proceedings of the ACM SIGPLAN 2004 conference on Programming language design and implementation**  
**Publisher:** ACM  
Full text available: [Pdf](#) (277.07 KB)

# Algorithms Found In a 10-Page Pointer Analysis Paper



procedure *exhaustive\_aliasing(G)*

*G:*  
begin

proc  
*G*  
*N*  
begin

1.    1.  
2.    2.  
3.    3.  
4.    4.  
end

Figure 1:  
addit  
3.3 e  
3.4 e

variation points  
unclear

every variant a  
new algorithm

correctness  
unclear

incomparable in  
precision

*E:*  
begin  
1.    end  
2.    proc  
3.    end  
4.    begin  
end

Figure 1: Ex



step 1 in Figure 2 \*/  
binding to step 3 in Figure 2 \*/  
binding to step 4 in Figure 2 \*/  
worklist(*worklist,value*)  
for keeping the aliases to process  
will be given to (*N,AA,PA*);  
not empty do  
    (*AA,PA*) from *worklist*;  
    node  
    *propagated\_at\_call(N,AA,PA,*  
    an exit node  
    *alias\_implies(N,AA,PA,value*)  
    with *M*  $\in$  *successor(N)*  
    if *M* is a pointer assignment  
        *alias\_implies\_thru\_assign(*  
            *AA,PA,value*);  
    else if *value* is YES  
        *make\_true(M,AA,PA)*;  
    else /\* *value* is FALSIFIED  
        *make\_false(M,AA,PA)*;

1.4.2    1.4.3

Figure 5: Reiteration for the incremental algorithm

add (*N,AA,PA*) to *worklist*;

Figure 4: Reintroduce aliases for naive falsification

Yannis Smaragdakis  
University of Athens

/\* Alias falsification for deleting a pointer assignment  
corresponding to step 1 in Figure 2 \*/

procedure *falsify\_for\_deleting\_assign(N)*  
*N*: a pointer assignment to be deleted;

begin procedure *update\_for\_adding\_assign(N,M)*

1.    *N*: a pointer assignment to be added;  
*M*: the statement after which statement *N* is added;
2.    begin
3.    1. make *N* as a successor of *M*, and leave *N* without  
any successors;
4.    2. create an empty *worklist*;
5.    3. *aliases\_intro\_by\_assignment(N,YES)*;
6.    4. *repropagate\_aliases(M,worklist)*;
7.    5. *reiterate\_worklist(worklist,YES)*;
8.    6. for each *may\_hold(M,AA,PA = (o<sub>1</sub>, o<sub>2</sub>) = YES,*  
and *may\_hold(N,AA,PA) = NO*  
add (*M,AA,PA*) to *worklist*;
9.    7. *reiterate\_worklist(worklist,FALSIFIED)*;

1.    Figure 8: Procedure for falsifying aliases that are po-  
tentially affected by adding a pointer assignment
2.    exit node of the function called by *N* respectively;

3.    *aliases\_propagated\_at\_call(N,∅,FALSIFIED)*;

4.    for each *may\_hold(N,AA,PA) = YES*

/\* If the called function may generate new aliases  
from the reaching aliases implied by *PA* \*/  
if  $\exists AA' \in bind(N,E,PA)$ , such that some  
*PA'* ( $\neq AA'$ ) is generated from *AA'* at exit *X*  
*aliases\_propagated\_at\_call(N,AA,PA,*  
*FALSIFIED)*;

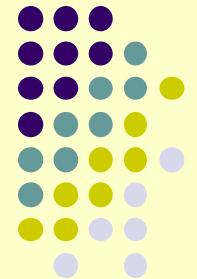
5.    if a function becomes unreachable from the main pro-  
gram after the call node is deleted, steps 3 and 4  
are repeated on those calls within each of the  
reachable functions.

6.    *reiterate\_worklist(worklist,FALSIFIED)*;

end

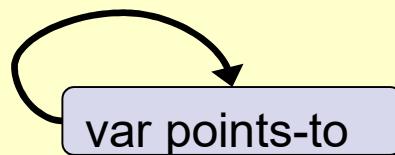
Figure 7: Procedures for falsifying aliases which are no-

# Program Analysis: a Domain of Mutual Recursion

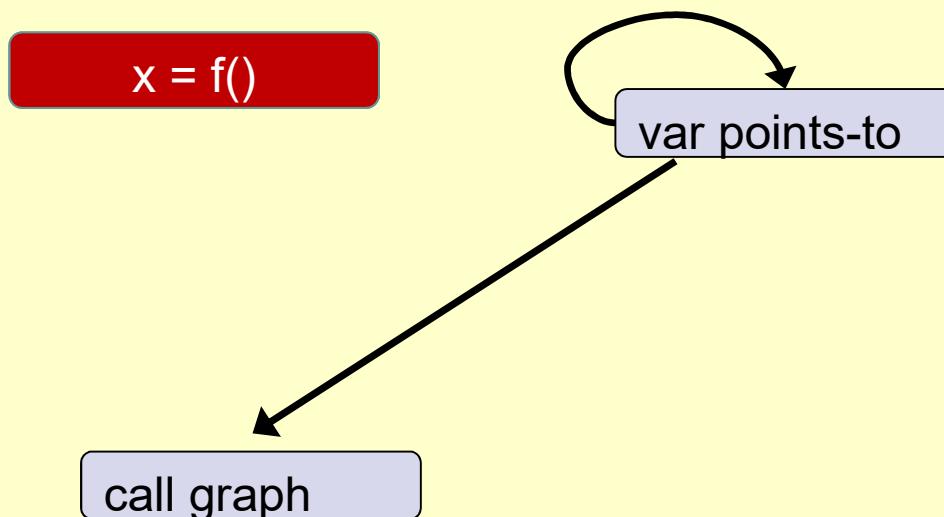
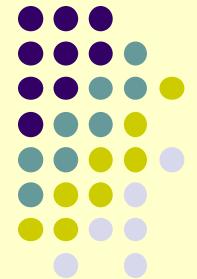


x = y

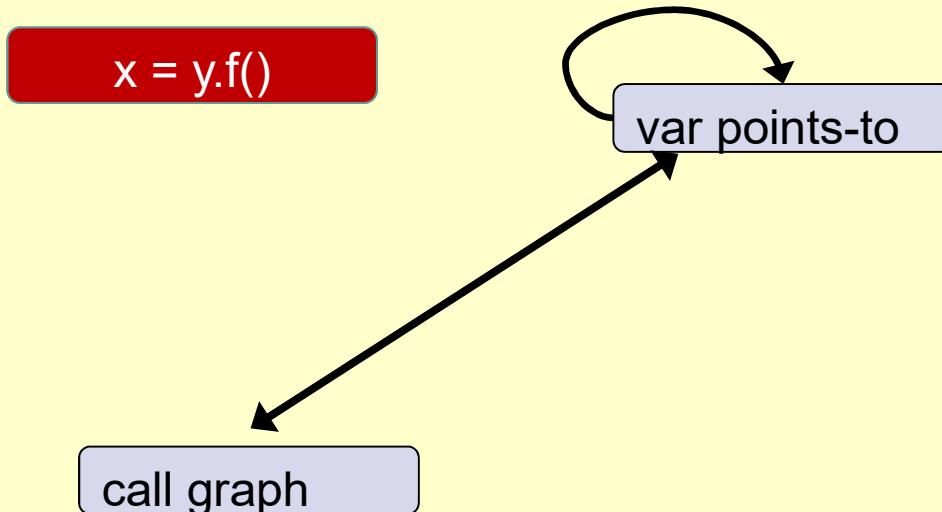
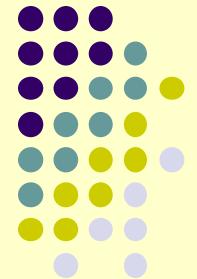
var points-to



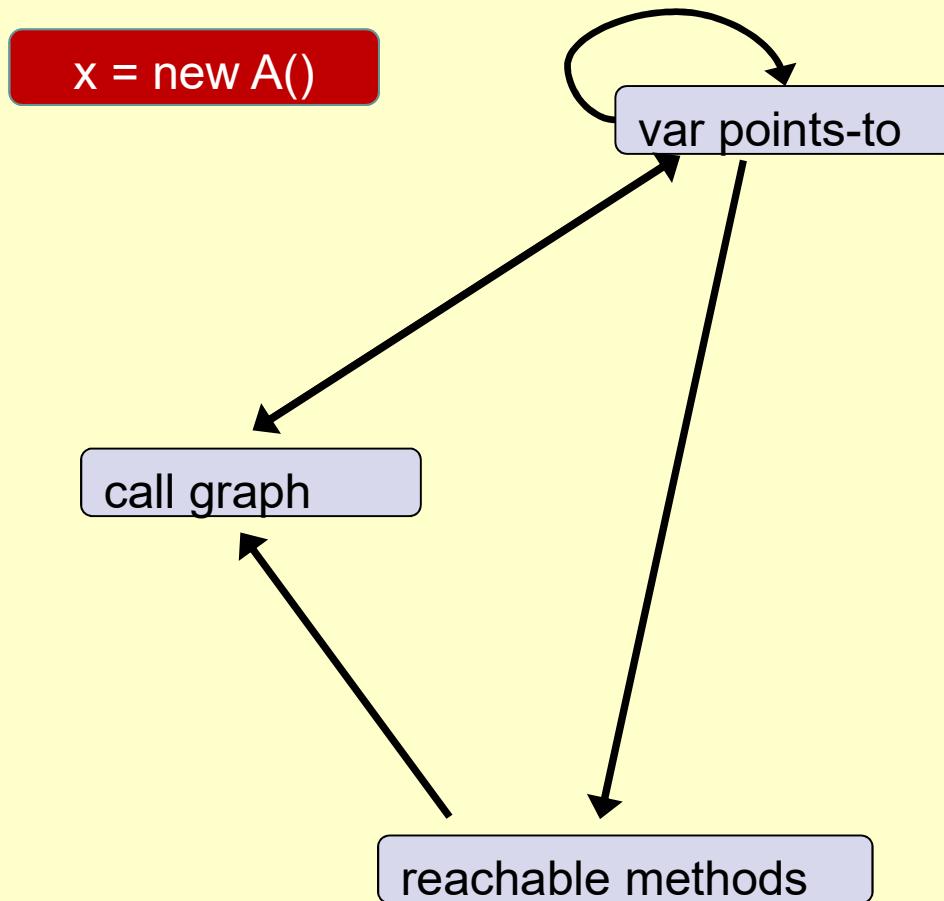
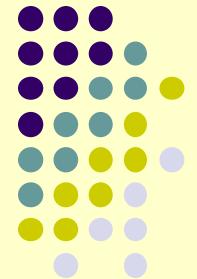
# Program Analysis: a Domain of Mutual Recursion



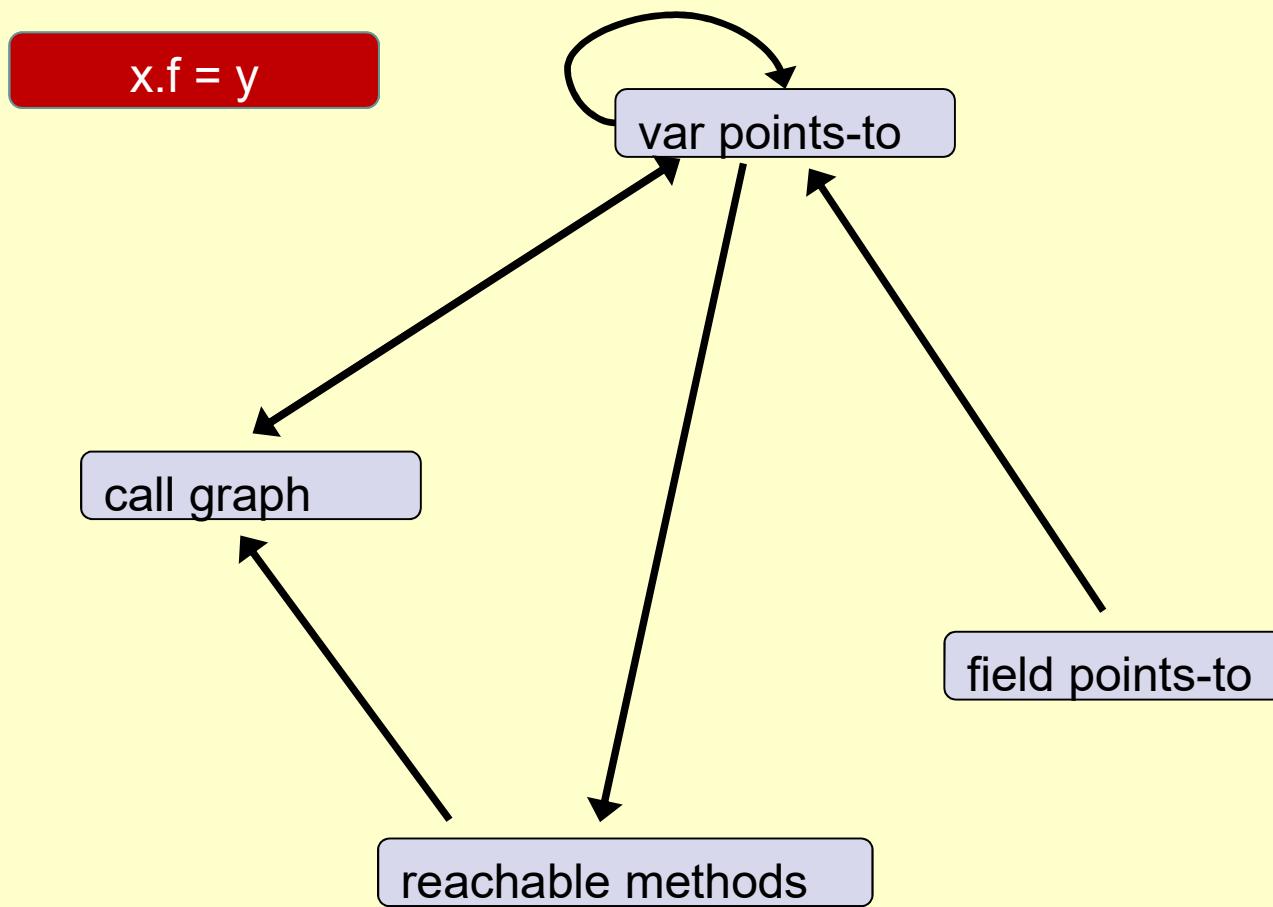
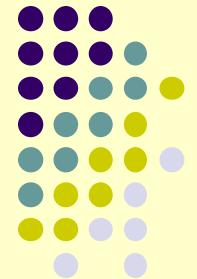
# Program Analysis: a Domain of Mutual Recursion



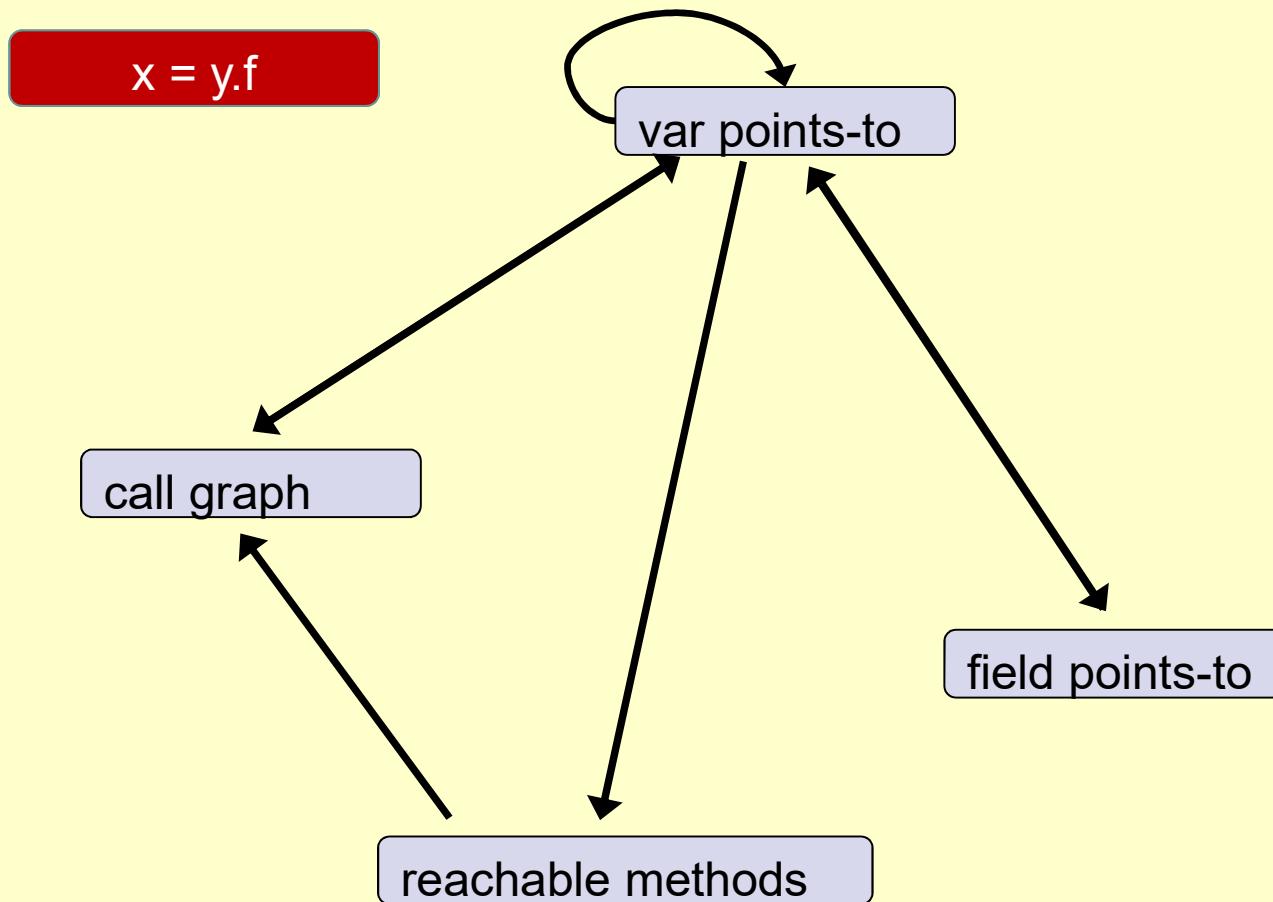
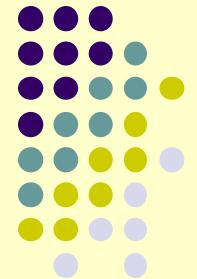
# Program Analysis: a Domain of Mutual Recursion



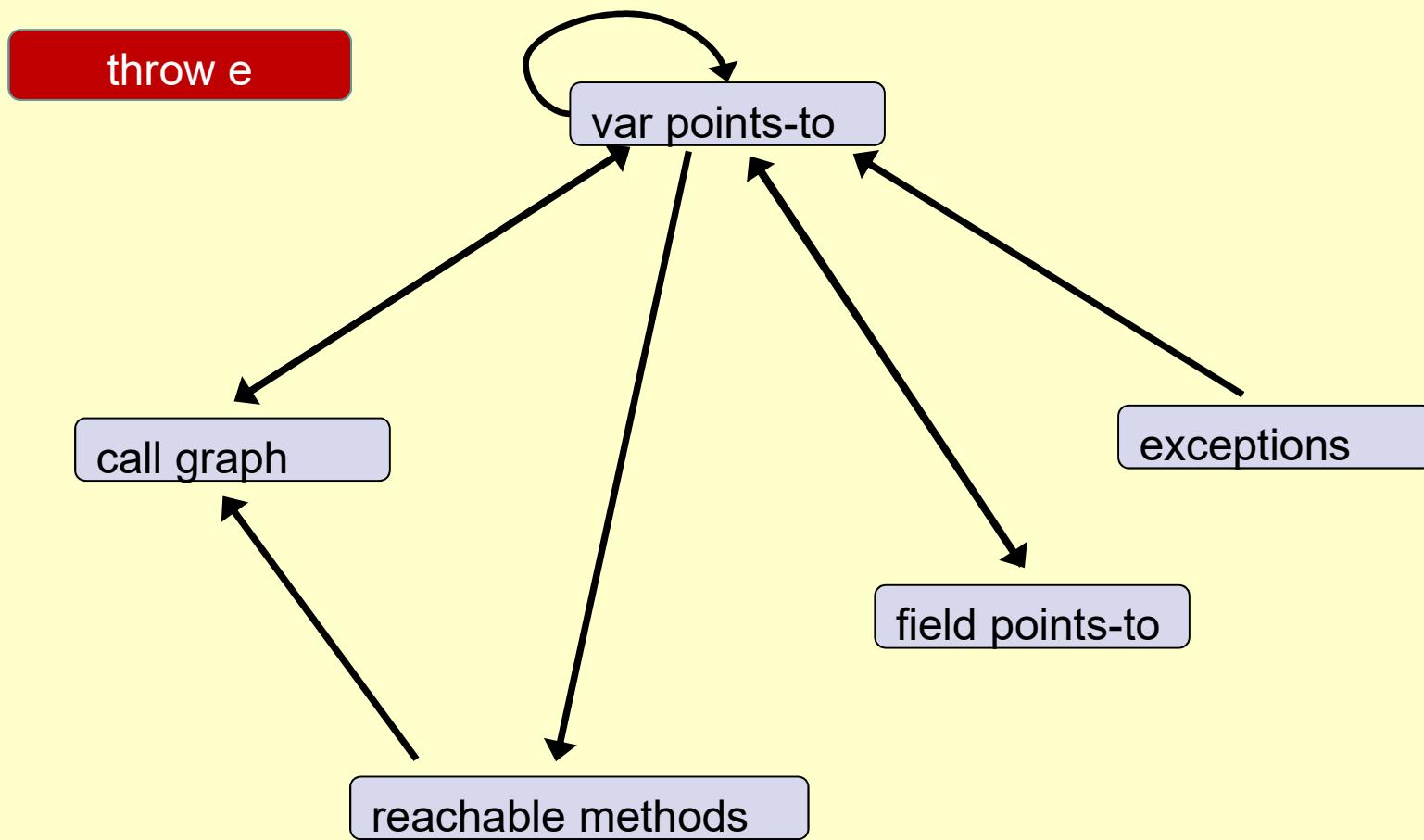
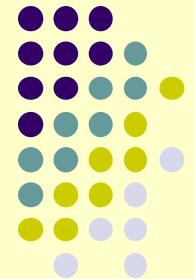
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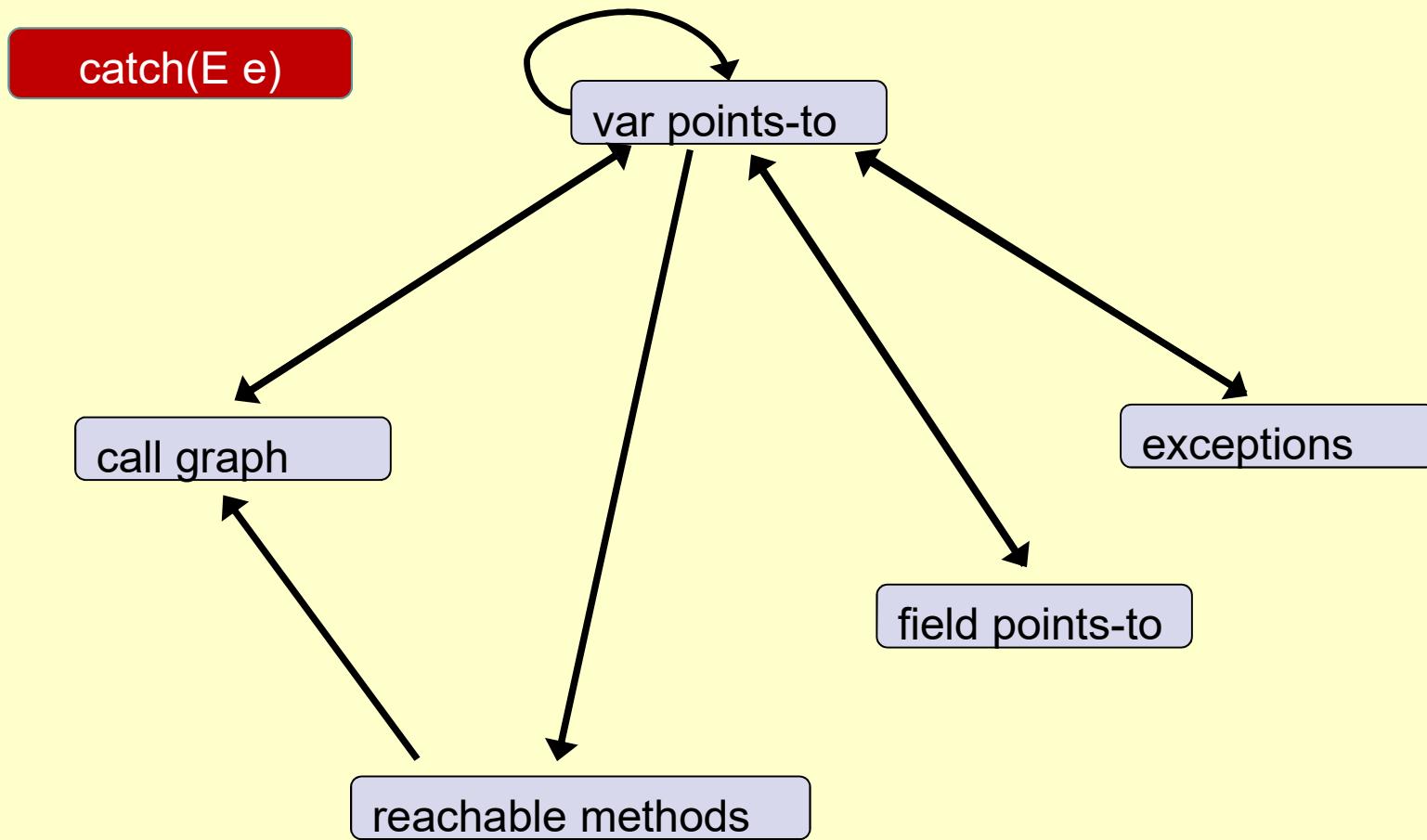
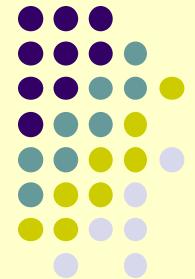
# Program Analysis: a Domain of Mutual Recursion



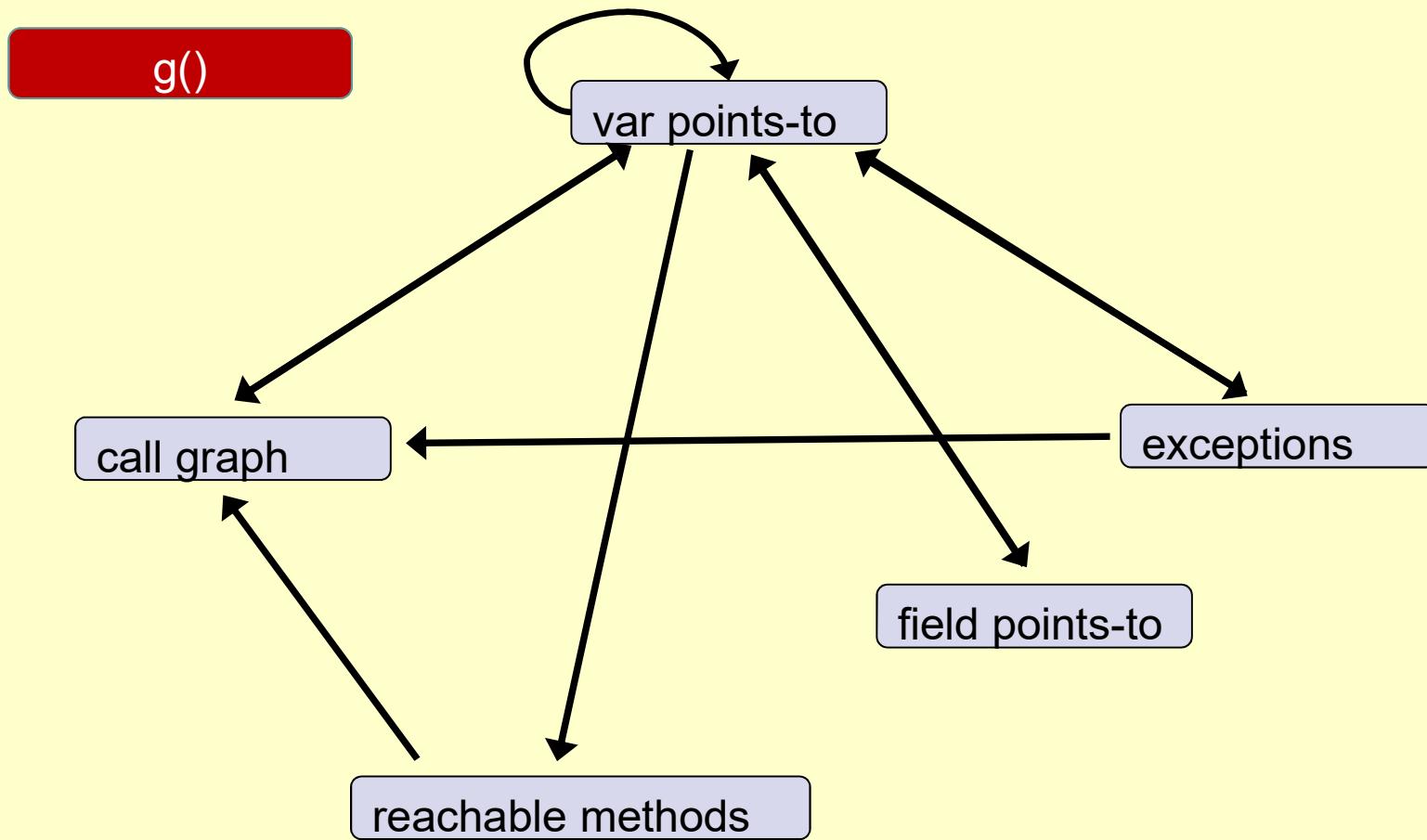
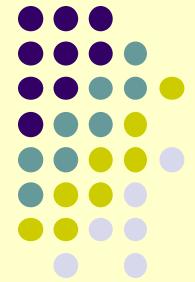
# Program Analysis: a Domain of Mutual Recursion



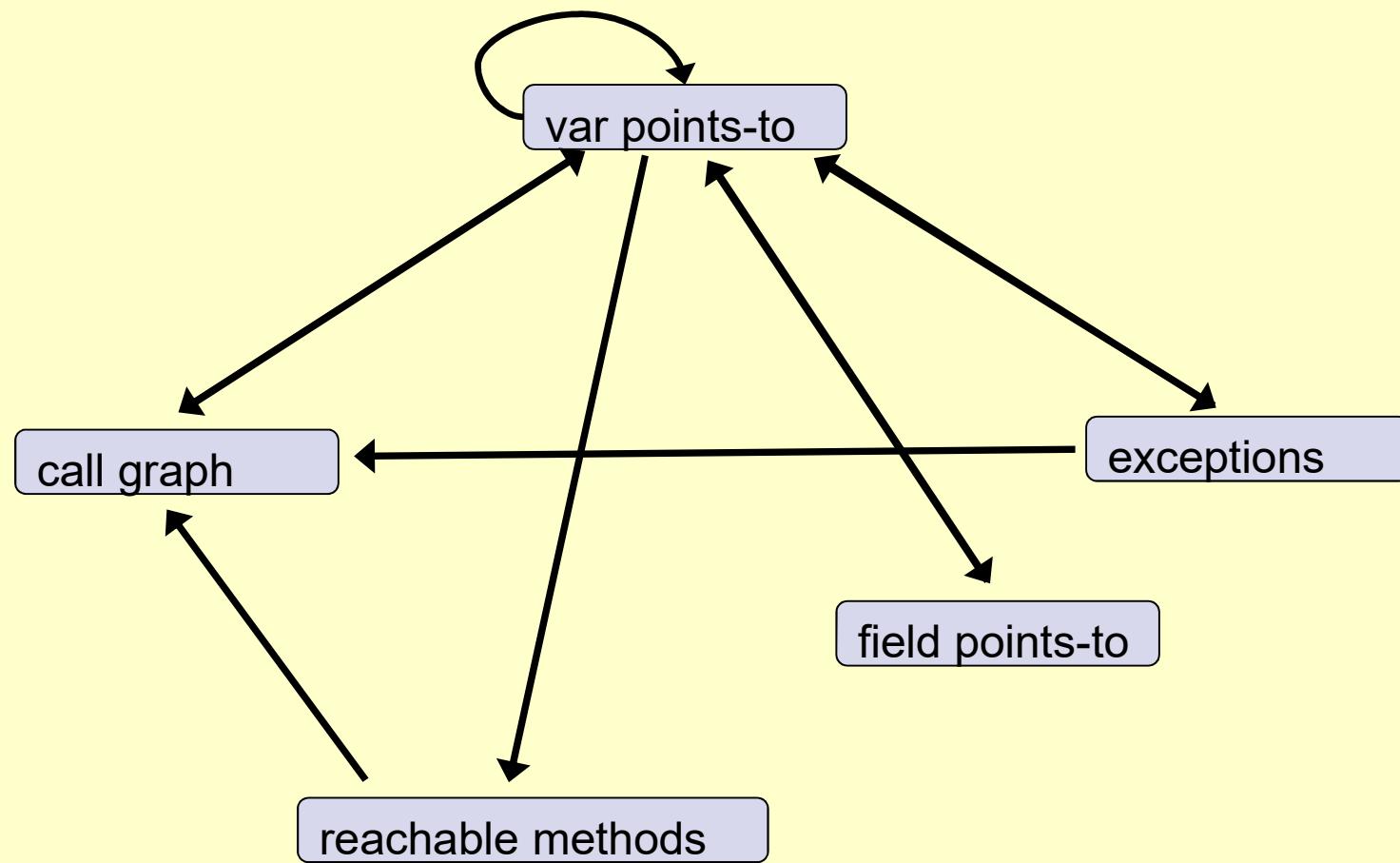
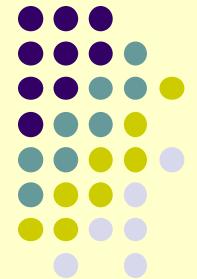
# Program Analysis: a Domain of Mutual Recursion



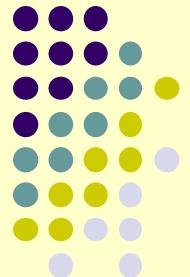
# Program Analysis: a Domain of Mutual Recursion



# Program Analysis: a Domain of Mutual Recursion

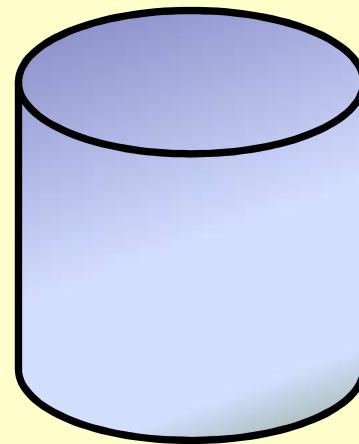
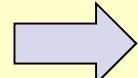


# Datalog: Declarative Mutual Recursion

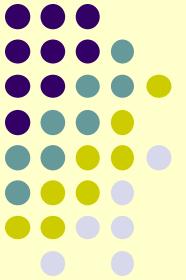


source

```
a = new A();  
b = new B();  
c = new C();  
a = b;  
b = a;  
c = b;
```



# Datalog: Declarative Mutual Recursion



source

```
a = new A();  
b = new B();  
c = new C();  
a = b;  
b = a;  
c = b;
```

Alloc

a	new A()
b	new B()
c	new C()

Move

a	b
b	a
c	b

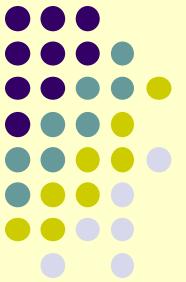
rules

```
VarPointsTo(var, obj) <-  
    Alloc(var, obj).
```

```
VarPointsTo(to, obj) <-  
    Move(to, from),  
    VarPointsTo(from, obj).
```



# Datalog: Declarative Mutual Recursion



source

```
a = new A();  
b = new B();  
c = new C();  
a = b;  
b = a;  
c = b;
```

Alloc

a	new A()
b	new B()
c	new C()

Move

a	b
b	a
c	b

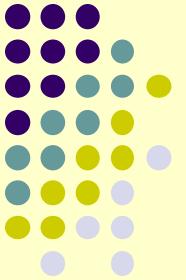
head

```
VarPointsTo(var, obj) <-  
    Alloc(var, obj).
```

```
VarPointsTo(to, obj) <-  
    Move(to, from),  
    VarPointsTo(from, obj).
```



# Datalog: Declarative Mutual Recursion



source

```
a = new A();  
b = new B();  
c = new C();  
a = b;  
b = a;  
c = b;
```

Alloc

a	new A()
b	new B()
c	new C()

VarPointsTo

head relation

Move

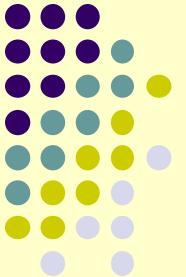
a	b
b	a
c	b

```
VarPointsTo(var, obj) <-  
    Alloc(var, obj).
```

```
VarPointsTo(to, obj) <-  
    Move(to, from),  
    VarPointsTo(from, obj).
```



# Datalog: Declarative Mutual Recursion



source

```
a = new A();  
b = new B();  
c = new C();  
a = b;  
b = a;  
c = b;
```

Alloc

a	new A()
b	new B()
c	new C()

VarPointsTo

Move

a	b
b	a
c	b

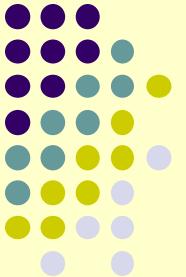
bodies

```
VarPointsTo(var, obj) <-  
    Alloc(var, obj).
```

```
VarPointsTo(to, obj) <-  
    Move(to, from),  
    VarPointsTo(from, obj).
```



# Datalog: Declarative Mutual Recursion



source

```
a = new A();  
b = new B();  
c = new C();  
a = b;  
b = a;  
c = b;
```

Alloc

a	new A()
b	new B()
c	new C()

VarPointsTo

Move

a	b
b	a
c	b

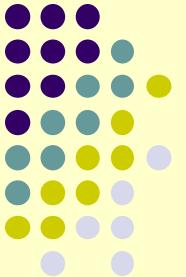
body relations

```
VarPointsTo(var, obj) <-  
    Alloc(var, obj).
```

```
VarPointsTo(to, obj) <-  
    Move(to, from),  
    VarPointsTo(from, obj).
```



# Datalog: Declarative Mutual Recursion



source

```
a = new A();  
b = new B();  
c = new C();  
a = b;  
b = a;  
c = b;
```

Alloc

a	new A()
b	new B()
c	new C()

VarPointsTo

Move

a	b
b	a
c	b

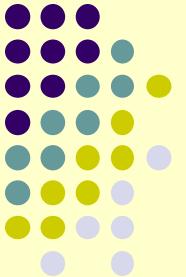
join variables

```
VarPointsTo(var, obj) <-  
    Alloc(var, obj).
```

```
VarPointsTo(to, obj) <-  
    Move(to, from),  
    VarPointsTo(from, obj).
```



# Datalog: Declarative Mutual Recursion



source

```
a = new A();  
b = new B();  
c = new C();  
a = b;  
b = a;  
c = b;
```

Alloc

a	new A()
b	new B()
c	new C()

VarPointsTo

Move

a	b
b	a
c	b

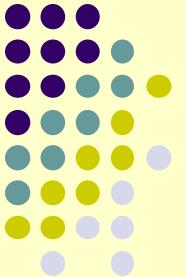
recursion

```
VarPointsTo(var, obj) <-  
    Alloc(var, obj).
```

```
VarPointsTo(to, obj) <-  
    Move(to, from),  
    VarPointsTo(from, obj).
```



# Datalog: Declarative Mutual Recursion



## source

```
a = new A();  
b = new B();  
c = new C();  
a = b;  
b = a;  
c = b;
```

## Alloc

a	new A()
b	new B()
c	new C()

## VarPointsTo

a	new A()
b	new B()
c	new C()

## Move

a	b
b	a
c	b

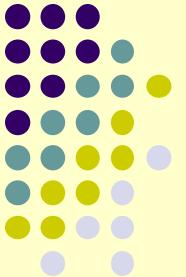
1<sup>st</sup> rule result

```
VarPointsTo(var, obj) <-  
    Alloc(var, obj).
```

```
VarPointsTo(to, obj) <-  
    Move(to, from),  
    VarPointsTo(from, obj).
```



# Datalog: Declarative Mutual Recursion



## source

```
a = new A();  
b = new B();  
c = new C();  
a = b;  
b = a;  
c = b;
```

## Alloc

a	new A()
b	new B()
c	new C()

## VarPointsTo

a	new A()
b	new B()
c	new C()

## Move

a	b
b	a
c	b

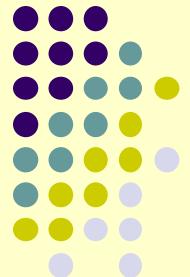
2<sup>nd</sup> rule evaluation

```
VarPointsTo(var, obj) <-  
    Alloc(var, obj).
```

```
VarPointsTo(to, obj) <-  
    Move(to, from),  
    VarPointsTo(from, obj).
```



# Datalog: Declarative Mutual Recursion



## source

```
a = new A();  
b = new B();  
c = new C();  
a = b;  
b = a;  
c = b;
```

## Alloc

a	new A()
b	new B()
c	new C()

## Move

a	b
b	a
c	b

## VarPointsTo

a	new A()
b	new B()
c	new C()
a	new B()

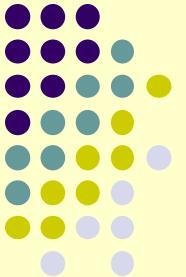
2<sup>nd</sup> rule result

```
VarPointsTo(var, obj) <-  
    Alloc(var, obj).
```

```
VarPointsTo(to, obj) <-  
    Move(to, from),  
    VarPointsTo(from, obj).
```



# Datalog: Declarative Mutual Recursion



## source

```
a = new A();  
b = new B();  
c = new C();  
a = b;  
b = a;  
c = b;
```

## Alloc

a	new A()
b	new B()
c	new C()

## Move

a	b
b	a
c	b

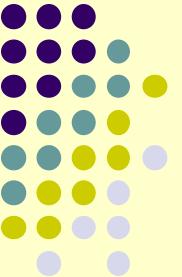
## VarPointsTo

a	new A()
b	new B()
c	new C()
a	new B()
b	new A()
c	new B()
c	new A()

```
VarPointsTo(var, obj) <-  
    Alloc(var, obj).
```

```
VarPointsTo(to, obj) <-  
    Move(to, from),  
    VarPointsTo(from, obj).
```



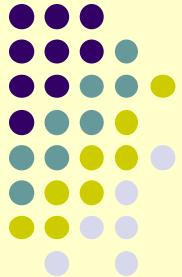


# Datalog: Properties

- Limited logic programming
  - SQL with recursion
  - Prolog without complex terms (constructors)
- Captures PTIME complexity class
- Strictly declarative
  - as opposed to Prolog
    - conjunction commutative
    - rules commutative
  - increases algorithm space
    - enables different execution strategies, aggressive optimization

Less programming, more specification



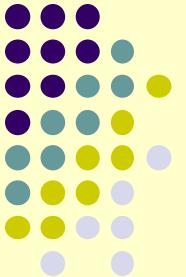


# The DoOP Framework

- Datalog-based pointer analysis framework for Java
- Declarative: what, not how
- Sophisticated, very rich set of analyses
  - subset-based analysis, fully on-the-fly call graph discovery, field-sensitivity, context-sensitivity, call-site sensitive, object sensitive, thread sensitive, context-sensitive heap, abstraction, type filtering, precise exception analysis
- Support for full semantic complexity of Java
  - jvm initialization, reflection analysis, threads, reference queues, native methods, class initialization, finalization, cast checking, assignment compatibility

**<http://doop.program-analysis.org>**

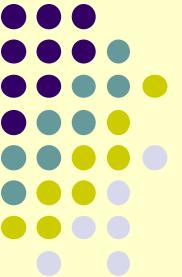




# Some Doop Contributions

- Expressed complete, complex pointer analyses in Datalog
  - core specification: ~1500 logic rules
  - parameterized by a handful of rules per analysis flavor
- Synthesized efficient algorithms from specification
  - order of magnitude performance improvement
  - allowed to explore more analyses than past literature
- Approach: heuristics for searching algorithm space
  - targeted at recursive problem domains
- Demonstrated scalability with explicit representation
  - Contrast: previous work used BDDs (bddbddb, Paddle)





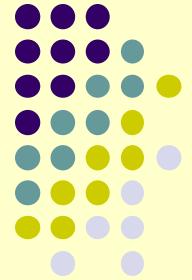
# Not Expected

- Expressed complete, complex pointer analyses in Datalog

*“[E]ncoding all the details of a complicated program analysis problem [on-the-fly call graph construction, handling of Java features] purely in terms of subset constraints may be difficult or impossible.” (Lhotak)*
- Scalability and Efficiency

*“Efficiently implementing a 1H-object-sensitive analysis without BDDs will require new improvements in data structures and algorithms”*

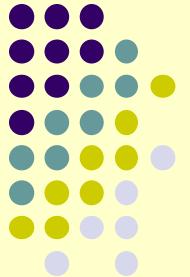




# How Datalog Executes\*

\*Note: we will focus on bottom-up execution, as used in Doop. A top-down execution strategy is possible, and is useful for other applications of Datalog

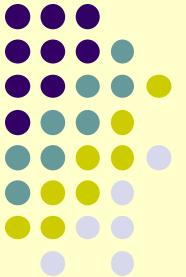




# Naïve Datalog Execution

- Execute each rule against all facts in the current database
  - Add the resulting facts to the database
  - Repeat until no more facts are added
- 
- Efficiency problem
    - Facts inferred in the first iteration are re-inferred in all subsequent iterations
    - In second iteration, need only consider rule instantiations based on at least one new fact





# Semi-Naïve Datalog Execution

- Execute program incrementally
  - For each rule  $r$ , for each fact  $f$  produced in relation  $R$  in the previous round, generate all facts inferable via rule  $r$ , fact  $f$ , and all current facts for relations other than  $R$

- Example

- Original program

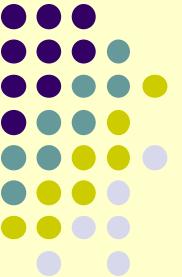
```
VarPointsTo(to, obj) <-
    Move(to, from),
    VarPointsTo(from, obj).
```

- Semi-Naïve rewriting

```
Δ VarPointsTo(to, obj) <-
    Move(to, from),
    ΔVarPointsTo(from, obj).
```

- Note that we don't have a similar  $\Delta$  rule for `Move`, because `Move` represents program text and we never get more facts there





# Semi-Naïve Datalog Execution

- Rewritten program

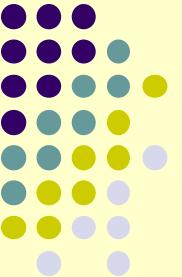
```
VarPointsTo(var, obj) <-
    AssignHeapAllocation(var, obj).
Δ VarPointsTo(to, obj) <-
    Move(to, from),
    ΔVarPointsTo(from, obj).
```

- Initial facts

```
AssignHeapAllocation("y", "o1").
AssignHeapAllocation("z", "o2").

Move("x", "y").
Move("y", "z").
```





# Practice: Semi-Naïve Execution

```
VarPointsTo(var, obj) <-
    AssignHeapAllocation(var, obj).

VarPointsTo(to, obj) <-
    LoadField(base, field, to),
    VarPointsTo(base, baseobj),
    FieldPointsTo(baseobj, field, obj).

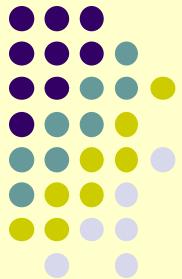
FieldPointsTo(baseobj, field, obj) <-
    StoreField(base, field, from),
    VarPointsTo(base, baseobj),
    VarPointsTo(from, obj).
```

```
AssignHeapAllocation("x", "o1").
AssignHeapAllocation("y", "o2").
```

```
LoadField("x", "f", "x"). % x.f = x
StoreField("x", "f", "y"). % y = x.f
```

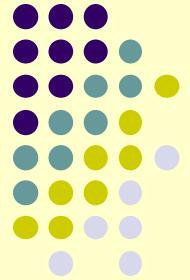


# Practice: Writing Reachability Analysis



- `Reachable(meth)` % method implementation meth is reachable
  - `VarPointsTo(var, obj)` % var may point to an object allocated at obj
  - `Alloc(var, obj, meth)` % obj: var = new ...(...) in meth
  - `VCall(base, sig, inMeth)` % virtual call: base.sig(...) in "inMeth"
  - `Lookup(obj, sig, meth)` % looks up the method implementation for allocation site obj and method signature sig
- 
- var, base - variable
  - obj - object allocation site
  - meth, inMeth - method implementation
  - sig - method name and signature
- 
- Give rules for `Reachable` and `VarPointsTo`, assuming `Alloc`, `VCall`, and `Lookup` are given



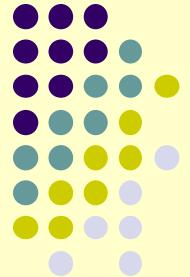


# Encoding Context-Sensitive Pointer Analysis in Datalog

[PLDI'10, POPL'11, CC'13, PLDI'13, PLDI'14]



# Recall: Context-Sensitivity (call-site sensitivity)



- What objects can a variable point to?

## program

```
void foo() {  
    Object a = new A1();  
    Object b = id(a);  
}  
  
void bar() {  
    Object a = new A2();  
    Object b = id(a);  
}  
  
Object id(Object a) {  
    return a;  
}
```

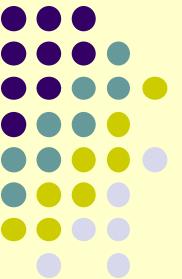
## points-to

foo:a	new A1()
bar:a	new A2()
id:a	new A1(), new A2()
foo:b	new A1(), new A2()
bar:b	new A1(), new A2()

## call-site-sensitive points-to

foo:a	new A1()
bar:a	new A2()
id:a (foo)	new A1()
id:a (bar)	new A2()
foo:b	new A1()
bar:b	new A2()





# Object-Sensitivity

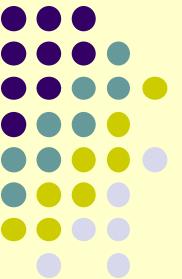
program

```
class S {  
    Object id(Object a) { return a; }  
    Object id2(Object a) { return id(a); }  
}  
class C extends S {  
    void fun1() {  
        Object a1 = new A1();  
        Object b1 = id2(a1);  
    }  
}  
class D extends S {  
    void fun2() {  
        Object a2 = new A2();  
        Object b2 = id2(a2);  
    }  
}
```

1-call-site-sensitive points-to

fun1:a1	new A1()
fun2:a2	new A2()
id2:a (fun1)	new A1()
id2:a (fun2)	new A2()
id:a (id2)	new A1(), new A2()
id2:ret (*)	new A1(), new A2()
fun1:b1	new A1(), new A2()
fun2:b2	new A1(), new A2()





# Object-Sensitivity

program

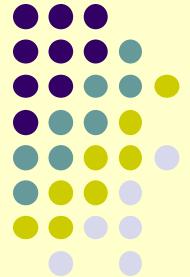
```
class S {  
    Object id(Object a) { return a; }  
    Object id2(Object a) { return id(a); }  
}  
class C extends S {  
    void fun1() {  
        Object a1 = new A1();  
        Object b1 = id2(a1);  
    }  
}  
class D extends S {  
    void fun2() {  
        Object a2 = new A2();  
        Object b2 = id2(a2);  
    }  
}
```

1-object-sensitive points-to

fun1:a1	new A1()
fun2:a2	new A2()
id2:a (C1)	new A1()
id2:a (D1)	new A2()
id:a (C1)	new A1()
id:a (D1)	new A2()
id2:ret (C1)	new A1()
fun1:b1	new A1()
fun2:b2	new A2()

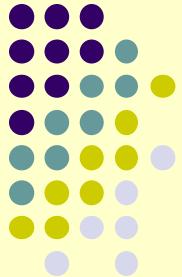


# A General Formulation of Context-Sensitive Analyses



- *Every context-sensitive flow-insensitive analysis there is* (ECSFIATI)
  - ok, almost every
    - most not handled are strictly less sophisticated
  - and also many more than people ever thought
- Also with on-the-fly call-graph construction
- In 9 easy rules!

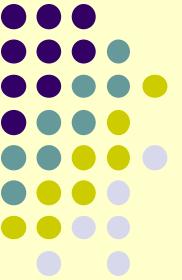




# Simple Intermediate Language

- We consider Java-bytecode-like language
  - allocation instructions (Alloc)
  - local assignments (Move)
  - virtual and static calls (VCall, SCall)
  - field access, assignments (Load, Store)
  - standard type system and symbol table info (Type, Subtype, FormalArg, ActualArg, etc.)



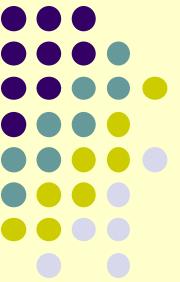


# Rule 1: Allocating Objects (Alloc)

```
VarPointsTo(var, ctx, obj, hctx)
<-
    Alloc(var, obj, meth),
    Reachable(meth, ctx).
where hctx = Record(obj, ctx)
```

*obj:* var = new Something();



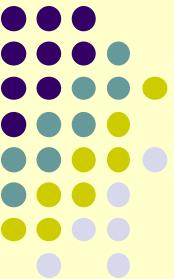


# Rule 2: Variable Assignment (Move)

```
VarPointsTo(to, ctx, obj, hctx)
<-
  Move(to, from),
  VarPointsTo(from, ctx, obj, hctx).
```

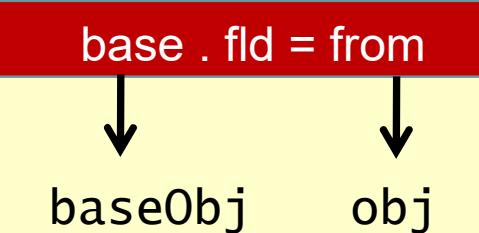
to = from

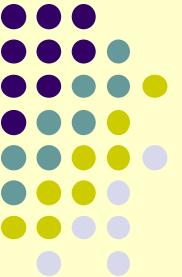




# Rule 3: Object Field Write (Store)

```
FldPointsTo(baseObj, baseHCtx, fld, obj, hctx)
<-
  Store(base, fld, from),
  VarPointsTo(from, ctx, obj, hctx),
  VarPointsTo(base, ctx, baseObj, baseHCtx).
```





# Rule 4: Object Field Read (Load)

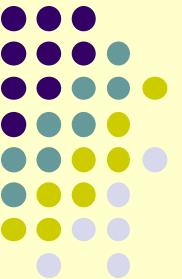
```
VarPointsTo(to, ctx, obj, hctx)
<-
    Load(to, base, fld),
    FldPointsTo(baseObj, baseHCtx, fld, obj, hctx),
    VarPointsTo(base, ctx, baseObj, baseHCtx).
```

to = base.fld

baseObj

↓  
fld  
obj



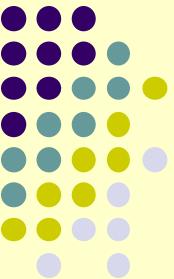


# Rule 5: Static Method Calls (SCall)

```
Reachable(toMeth, calleectx),  
CallGraph(invocation, callerctx, toMeth, calleectx)  
<-  
  SCall(toMeth, invocation, inMethod),  
  Reachable(inMethod, callerctx).  
where calleectx = MergeStatic(invocation, callerctx)
```

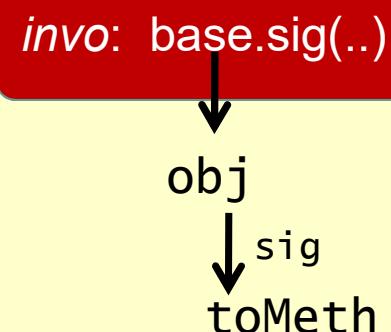
invocation: toMeth(..)

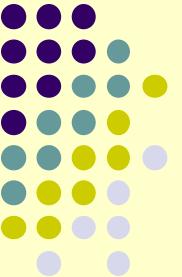




# Rule 6: Virtual Method Calls (VCall)

```
Reachable(toMeth, calleectx),  
VarPointsTo(this, calleectx, obj, hctx),  
CallGraph(invocation, callerctx, toMeth, calleectx)  
<-  
  VCall(base, sig, invocation, inMethod),  
  Reachable(inMethod, callerctx),  
  VarPointsTo(base, callerctx, obj, hctx),  
  LookUp(obj, sig, toMeth),  
  ThisVar(toMeth, this).  
where calleectx = Merge(obj, hctx, invocation, callerctx)
```



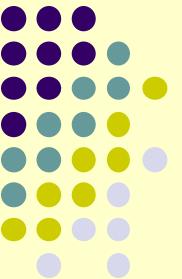


# Rule 7: Parameter Passing

```
InterProcAssign(to, calleeCtx, from, callerCtx)
<-
  CallGraph(invocation, callerCtx, method, calleeCtx),
  ActualArg(invocation, i, from),
  FormalArg(method, i, to).
```

*invocation: method(.., from, ..) → method(.., to, ..)*





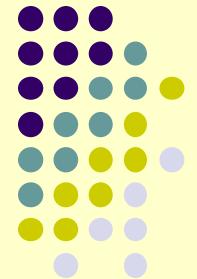
# Rule 8: Return Value Passing

```
InterProcAssign(to, callerCtx, from, calleeCtx)
<-
  CallGraph(invocation, callerCtx, method, calleeCtx),
  ActualReturn(invocation, to),
  FormalReturn(method, from).
```

*invocation: to = method(..) → method(..) { .. return from; }*



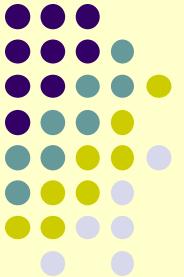
# Rule 9: Parameter/Result Passing as Assignment



```
VarPointsTo(to, toCtx, obj, hctx)
<-
  InterProcAssign(to, toCtx, from, fromCtx),
  VarPointsTo(from, fromCtx, obj, hctx).
```



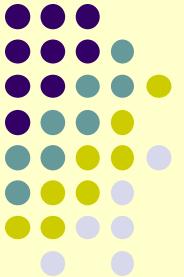
# Can Now Express Past Analyses Nicely



- 1-call-site-sensitive with context-sensitive heap:
  - $Context = HContext = \text{Instr}$
- Functions:
  - $\text{Record}(\text{obj}, \text{ctx}) = \text{ctx}$
  - $\text{Merge}(\text{obj}, \text{hctx}, \text{invo}, \text{callerCtx}) = \text{invo}$
  - $\text{MergeStatic}(\text{invo}, \text{callerCtx}) = \text{invo}$



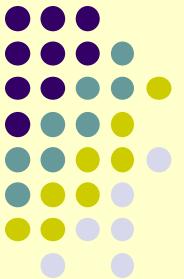
# Can Now Express Past Analyses Nicely



- 1-object-sensitive+heap:
  - $\text{Context} = H\text{Context} = \text{Instr}$
- Functions:
  - $\text{Record}(\text{obj}, \text{ctx}) = \text{ctx}$
  - $\text{Merge}(\text{obj}, \text{hctx}, \text{invo}, \text{callerCtx}) = \text{obj}$
  - $\text{MergeStatic}(\text{invo}, \text{callerCtx}) = \text{callerCtx}$



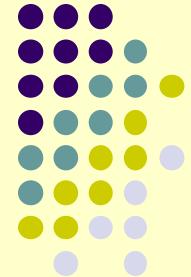
# Can Now Express Past Analyses Nicely



- PADDLE-style 2-object-sensitive+heap:
  - $Context = \text{Instr}^2$  ,  $HContext = \text{Instr}$
- Functions:
  - $Record(\text{obj}, \text{ctx}) = \text{first}(\text{ctx})$
  - $Merge(\text{obj}, \text{hctx}, \text{invo}, \text{callerCtx}) = \text{pair}(\text{obj}, \text{first}(\text{callerCtx}))$
  - $MergeStatic(\text{invo}, \text{callerCtx}) = \text{callerCtx}$

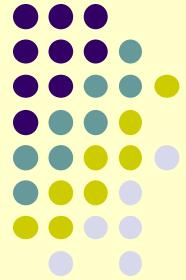


# Lots of Insights and New Algorithms (all with major benefits)



- Discovered that the same name was used for two past algorithms with very different behavior
- Proposed a new kind of context (*type-sensitivity*), easily implemented by uniformly tweaking **Record/Merge** functions
- Found connections between analyses in functional/OO languages
- Showed that merging different kinds of contexts works great (*hybrid context-sensitivity*)

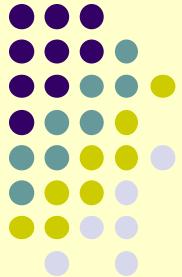




# Impressive Performance, Implementation Insights

[OOPSLA'09, ISSTA'09]

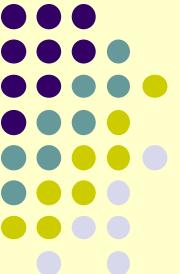




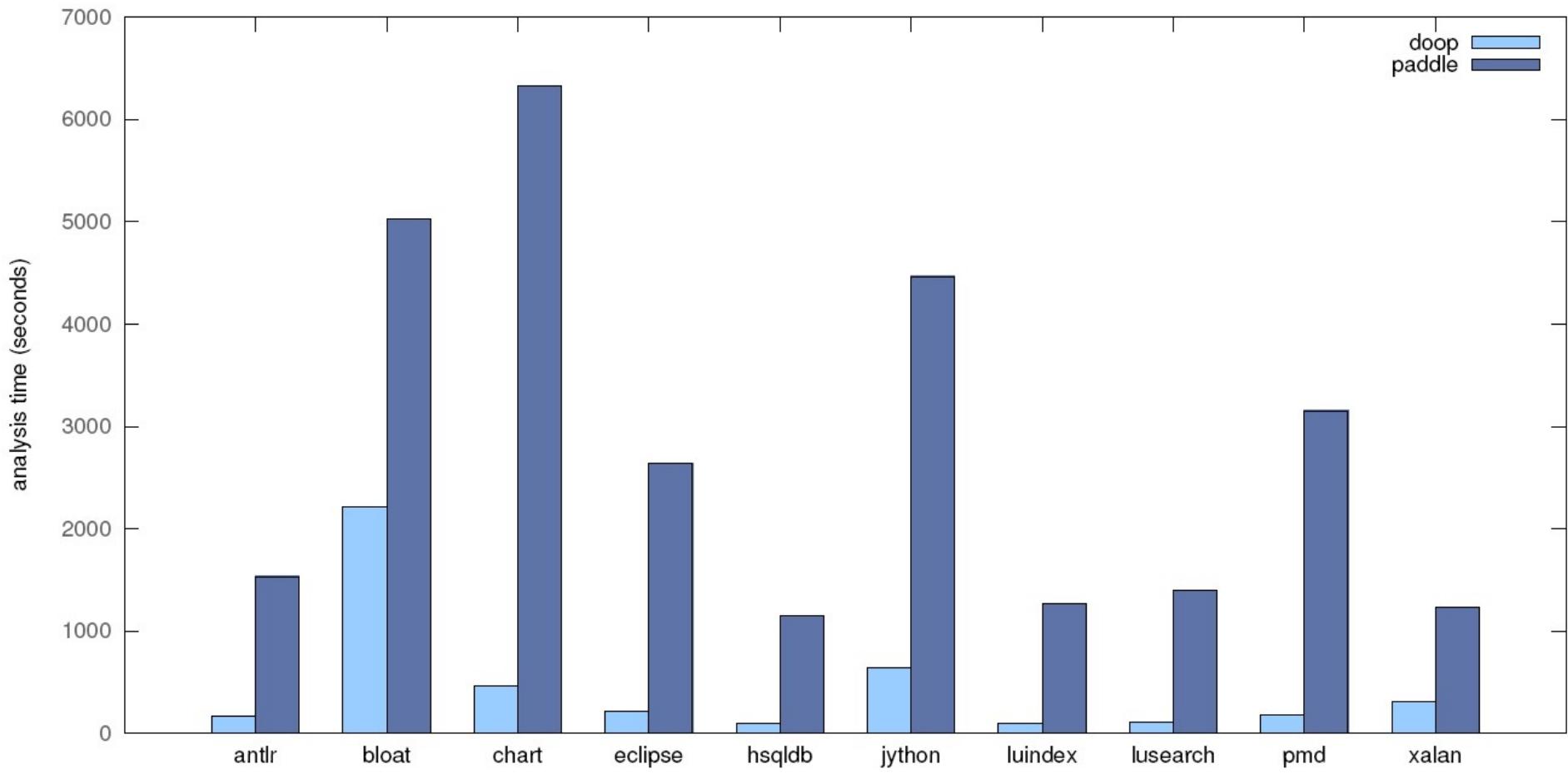
# Impressive Performance

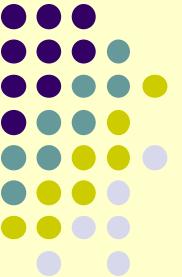
- Compared to Paddle
  - most complete, scalable past framework
    - includes analyses with a context sensitive heap
- Large speedup for fully equivalent results!
  - 15.2x faster for 1-obj, 16.3x faster for 1-call, 7.3x faster for 1-call+heap, 6.6x faster for 1-obj+heap
- Large speedup for more precise results!
  - 9.7x for 1-call, 12.3x for 1-call+heap, 3x for 1-obj+heap
- Scaling to analyses Paddle cannot handle
  - 2-call+1-heap, 2-object+1-heap, 2-call+2-heap





# 1-call-site-sensitive+heap



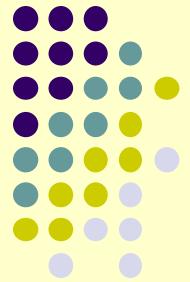


# Where Is The Magic?

- Surprisingly, in very few places
  - 4 orders of magnitude via optimization methodology for highly recursive Datalog!
    - straightforward data processing optimization (indexes), but with an understanding of how Datalog does recursive evaluation
  - no BDDs
    - are they needed for pointer analysis?
  - simple domain-specific enhancements that increase both precision and performance in a direct (non-BDD) implementation



# Identifying Performance Problems



- Inefficient Datalog:

```
VarPointsTo(?var, ?obj) <-  
    AssignObjectAllocation(?var, ?obj).
```

```
VarPointsTo(?to, ?obj) <-  
    Assign(?from, ?to), VarPointsTo(?from, ?obj).
```

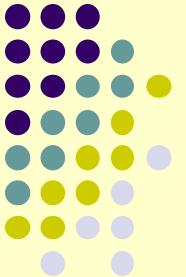
- LogicBlox Datalog indexes on the *last* variable in a relation
- This code joins on the *first* variables of Assign, VarPointsTo

- After re-ordering variables:

```
VarPointsTo(?obj, ?var) <-  
    AssignObjectAllocation(?obj, ?var).
```

```
VarPointsTo(?obj, ?to) <-  
    Assign(?to, ?from), VarPointsTo(?obj, ?from).
```





# More Challenging

- Specification

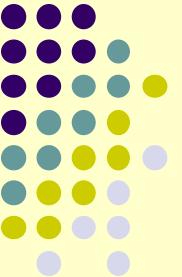
```
FieldPointsTo(?obj, ?field, ?baseobj) <-
  StoreField(?from, ?field, ?base),
  VarPointsTo(?baseobj, ?base),
  VarPointsTo(?obj, ?from).
```

- Semi-naïve executions

```
ΔFieldPointsTo(?obj, ?field, ?baseobj) <-
  StoreField(?from, ?field, ?base),
  ΔVarPointsTo(?baseobj, ?base),
  VarPointsTo(?obj, ?from).
```

```
ΔFieldPointsTo(?obj, ?field, ?baseobj) <-
  StoreField(?from, ?field, ?base),
  VarPointsTo(?baseobj, ?base),
  ΔVarPointsTo(?obj, ?from).
```





# Folding

- Original

```
FieldPointsTo(?obj, ?field, ?baseobj) <-
  StoreField(?from, ?field, ?base),
  VarPointsTo(?baseobj, ?base),
  VarPointsTo(?obj, ?from).
```

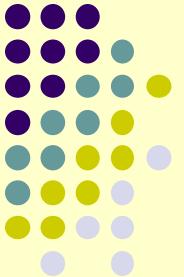
- Implemented with an extra relation

- and an extra index

```
FieldPointsTo(?obj, ?field, ?baseobj) <-
  StoreObjectField(?baseobj, ?field, ?from)
  VarPointsTo(?obj, ?from).
```

```
StoreObjectField(?baseobj, ?field, ?from)
  StoreField(?from, ?field, ?base),
  VarPointsTo(?baseobj, ?base),
```





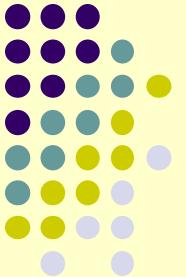
# Optimization Practice

- Original

```
VarPointsTo(?obj, ?to) <-
    LoadField(?to, ?base, ?field),
    VarPointsTo(?baseobj, ?base),
    FieldPointsTo(?obj, ?field, ?baseobj).
```

- Optimize the variable order of LoadField and add folds
  - You may not change variable order in other relations

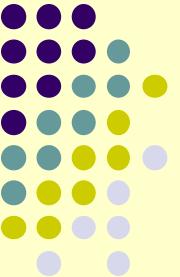




# Optimization Insight

- For highly recursive Datalog programs,  
***relation deltas produced by semi-naive evaluation should bind all the variables needed to index into other relations***
- Can require complex reasoning
  - whole program optimization
  - human needs to be in the loop in the search of algorithm space!

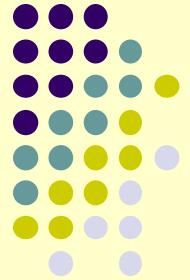




# Algorithmic Enhancements

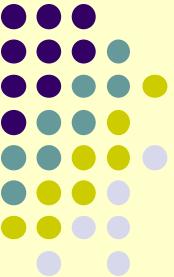
- BDDs are necessary if one is not careful about precision
- We introduced simple algorithmic enhancements to avoid redundancy
  - static initializers handled context-insensitively
  - on-the-fly exception handling
- Better analyses, as well as faster!





# Conclusions, Future Work





# Declarative Program Analysis

- Doop is probably the most complete points-to analysis framework for Java
  - aids exploration
  - competitive performance
- Already yielded new algorithms, implementation techniques
- Latest: flow-sensitive, LLVM, client analyses
- Future: commercialization as program comprehension service

