Gradual Program Verification (with Implicit Dynamic Frames)

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```
int getFour(int i)
    requires ?; // not sure what this should be yet
    ensures result = 4;
{
    i = i + 1;
    return i;
}
```

Motivation

- Program verification (against some specification)
- Two flavors: dynamic & static

```
// spec: callable only if (this.balance >= amount)
void withdrawCoins(int amount)
{
    // business logic
    this.balance -= amount;
}
```

Dynamic Verification

- runtime checks
- testing techniques
- guarantee compliance at run time

```
void withdrawCoins(int amount)
{
   assert this.balance >= amount;
   // business logic
   this.balance -= amount;
}
```

Dynamic Verification – Drawbacks

- runtime checks
 runtime overhead
- testing techniques additional effort
- guarantee compliance at run time late detection

```
void withdrawCoins(int amount)
{
   assert this.balance >= amount;
   // business logic
   this.balance -= amount;
}
```

Static Verification

- declarative
- formal logic
- guarantee compliance in advance

```
void withdrawCoins(int amount)
    requires this.balance >= amount;
{
    // business logic
    this.balance -= amount;
}
```

Static Verification – Drawbacks

- declarative
- formal logic
- guarantee compliance in advance

```
limited expressiveness and/or decidability
```

annotation overhead (viral)

```
void withdrawCoins(int amount)
   requires this.balance >= amount;
   ensures this.balance == old(this.balance) - amount;
{
   // business logic
   this.balance -= amount;
}
```

Viral Specifications

```
void withdrawCoins(int amount)
   requires this.balance >= amount;
   ensures this.balance == old(this.balance) - amount;
{
   // business logic
   this.balance -= amount;
}
```

```
acc.balance = 100;
acc.withdrawCoins(50); // statically checks OK!
acc.withdrawCoins(30); // oops, don't know balance!
```

Can only remove false warnings by adding specifications

Specification becomes almost **all-or-nothing**; keep getting warnings until spec is highly complete.

Want **gradual** return on investment—reasonable behavior at every level of specification.!

Solution: Combining Static + Dynamic

Hybrid approach

- Static checking, but failure is only a warning
- Run-time assertions catch anything missed statically

Benefits

- + Catch some errors early
- + Still catch remaining errors dynamically
- + Can eliminate run-time overhead if an assertion is statically discharged

Drawbacks

- Still false positive warnings / viral specification problem
- Run-time checking may still impose too much overhead, and/or is an open problem (e.g. for implicit dynamic frames)

Challenges / opportunities

- Can we warn statically only if there is a definite error, and avoid viral specifications?
- Can we reduce run-time overhead when we have partial information?
- How to support dynamic checks for more powerful specification approaches (e.g. implicit dynamic frames)

Engineering Verification

- Ideal: an engineering approach to verification
 - Choose what to specify based on costs, benefits
 - May focus on critical components
 - Leave others unspecified
 - May focus on certain properties
 - Those most critical to users
 - Those easiest to verify
 - May add more specifications over time
 - Want incremental costs/rewards
- Viral nature of static checkers makes this difficult
 - Warnings when unspecified code calls specified code
 - May have to write many extra specifications to verify the ones you care about

A verification approach that supports **gradually** adding specifications to a program

Novel feature: support unknown and imprecise specs

```
void withdrawCoins(int amount)
    requires amount > 0 && this.balance >= amount;
    ensures this.balance = old(this.balance) - amount;
```

Analogous to Gradual Typing [Siek & Taha, 2006]

A verification approach that supports **gradually** adding specifications to a program

• Novel feature: support unknown and imprecise specs

```
void withdrawCoins(int amount)
    requires this.balance >= amount;
    ensures ? && this.balance < old(this.balance);</pre>
```

- Warning if we statically detect an inconsistency
 - The spec above would be statically OK with a ? added to the precondition, or an assertion that amount > 0
 - But the given precondition alone can't assure the part of the postcondition that we know

A verification approach that supports **gradually** adding specifications to a program

• Novel feature: support unknown and imprecise specs

```
void withdrawCoins(int amount)
    requires ? && this.balance >= amount;
    ensures ? && this.balance < old(this.balance);</pre>
```

- Warning if we statically detect an inconsistency
- Warning if spec is violated at run time

```
acc.balance = 100;
acc.withdrawCoins(50); // statically guaranteed safe
acc.withdrawCoins(30); // dynamic check OK
acc.withdrawCoins(30); // dynamic check: error!
Johannes Bader
```

A verification approach that supports **gradually** adding specifications to a program

- Novel feature: support unknown and imprecise specs
- Engineering properties
 - Same as dynamic verification when specs fully imprecise
 - Same as static verification when specs fully precise
 - Applies to any part of the program whose code and libraries used are specified precisely
 - Smooth path from dynamic to static checking (non-viral)
 - Gradual Guarantee [Siek et al. 2015]: Given a verified program and correct input, no static or dynamic errors will be raised for the same program and input with a less-precise specification

True ≠?

- Prior verifiers are not "gradual"
 - No support for imprecise/unknown specifications
- Treating missing specs as "true" is insufficient

```
class Account {
   void withdrawCoins(int amount)
      requires this.balance >= amount;
   ensures true;
   ... }

Account a = new Account(100)
a.withdrawCoins(40);
a.withdrawCoins(30); // error: only know "true" here
```

True ≠?

- Prior verifiers are not "gradual"
 - No support for imprecise/unknown specifications
- Treating missing specs as "true" is insufficient

```
class Account {
    void withdrawCoins(int amount)
        requires this.balance >= amount;
    ensures ?;
    ... }

Account a = new Account(100)
a.withdrawCoins(40);
a.withdrawCoins(30); // OK: ? consistent with precondition
```

Gradual Verification Roadmap

- Motivation and Intuition
 - Engineering: need good support for partial specs
 - Key new idea: a (partly) unknown spec: "?"
- Overview: Abstracting Gradual Verification
- A static verification system
- Deriving a gradual verification system
- Demonstration!
- Extension to Implicit Dynamic Frames

Gradual Verification Roadmap

- Motivation and Intuition
 - Engineering: need good support for partial specs
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- Overview: Abstracting Gradual Verification
- A static verification system
- Deriving a gradual verification system
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Inspiration: Gradual Typing [Siek & Taha, 2006]

- Allows programmers to selectively omit types
 - Mixing dynamically-typed code (e.g. as in Python) with statically-typed code
 - Missing types denoted with a "?" or "dynamic" keyword
 - Can have "partly dynamic" types like "? -> int"

Abstracting Gradual Typing [Garcia et al., 2016]

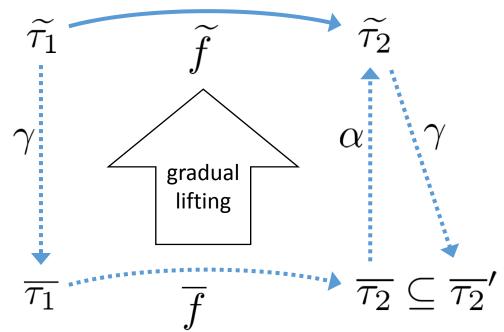
- Semantic foundation for Gradual Typing
 - Gradual types represent sets of possible static types
 - Use abstract interpretation to derive gradual type system from static type system

Gradual System

$$\gamma(\tau) = \{ \tau \}$$

$$\gamma(?) = \text{Types}$$

Static System



How does this relate to Verification?

```
int getFour(int i)
    requires ?; // not sure what this should be yet
    ensures / result = 4;

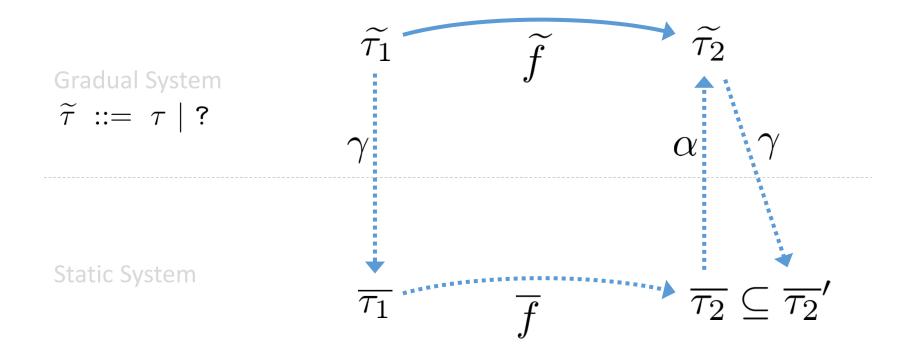
i = i + 1;
    return i;
}
```

Types restrict which **values** are valid for a certain variable

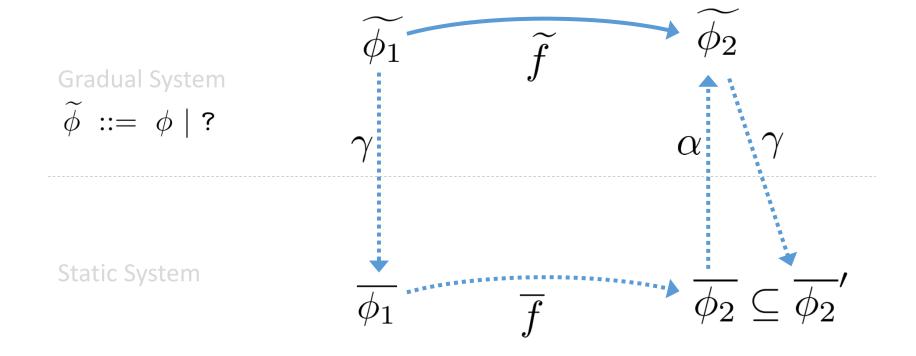
Formulas restrict which program states are valid at a certain point during execution

Abstracting Gradual Typing

Ronald Garcia, Alison M. Clark, and Éric Tanter



Abstracting Gradual Typing Ronald Garcia, Alison M. Clark, and Éric Tanter Verification



Abstracting Gradual Typing Ronald Garcia, Alison M. Clark, and Éric Tanter Verification

Gradual System

$$\widetilde{\phi} ::= \phi \mid ?$$

 $\widetilde{\phi_1}$ \widetilde{f} $\widetilde{\phi_2}$ γ to create a

Benefits: if we choose f, α , and γ to create a sound abstraction, we automatically get:

- The gradual guarantee: a smooth path from dynamic to static verification
- A principled approach to optimizing runtime assertion checking

 \overline{f} $\overline{\phi_2} \subseteq \overline{\phi_2}$

erification

Gradualization - Overview

Syntax

 $s \in Stmt$

 $\phi \in \text{Formula}$

Program State

 $\pi \in \mathsf{PROGRAMSTATE}$

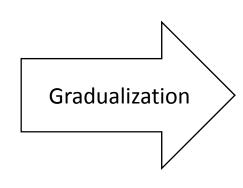
Semantics

Static $\vdash \{\phi\} \ s \ \{\phi\}$

Dynamic $\pi \longrightarrow \pi$

Formula $\pi \models \phi$

Soundness



Syntax

 $\widetilde{s} \in \widetilde{\mathbf{S}}$ TMT

 $\widetilde{\phi} \in \widetilde{F}ORMULA$

Program State

 $\widetilde{\pi} \in \widetilde{P}_{ROGRAM}$ STATE

Semantics

Static $\widetilde{\vdash} \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi}\}$

Dynamic $\widetilde{\pi} \longrightarrow \widetilde{\pi}$

Formula $\widetilde{\pi} \stackrel{\sim}{\models} \widetilde{\phi}$

Syntax

 $s \in Stmt$

 $\phi \in \text{Formula}$

Program State

 $\pi \in \mathsf{PROGRAMSTATE}$

Semantics

Static $\vdash \{\phi\} \ s \ \{\phi\}$

Dynamic $\pi \longrightarrow \pi$

Formula $\pi \models \phi$

$$s$$
 ::= skip | x := e | assert ϕ | s_1 ; s_2 ϕ ::= true | $(e_1 = e_2)$ | $\phi_1 \wedge \phi_2$

=
$$(VAR \rightarrow N_0) \times STMT$$

 $\langle [x \mapsto 6, y \mapsto 3], x := y; assert (x = 3) \rangle$

Syntax

 $s \in STMT$

 $\phi \in \text{Formula}$

Program State

 $\pi \in PROGRAMSTATE$

Semantics

Static
$$\vdash \{\phi\} \ s \ \{\phi\}$$

Dynamic $\pi \longrightarrow \pi$

Formula $\pi \models \phi$

$$\overline{ \; \vdash \{\phi\} \; \mathrm{skip} \; \{\phi\} } \; \mathrm{HSkip}$$

$$\frac{}{\;\vdash\; \{\phi[e/x]\}\; x\; :=\; e\; \{\phi\}} \; \operatorname{HAssign}$$

Syntax

 $s \in Stmt$

 $\phi \in \text{Formula}$

Program State

 $\pi \in PROGRAMSTATE$

Semantics

Static $\vdash \{\phi\} \ s \ \{\phi\}$

Dynamic $\pi \longrightarrow \pi$

Formula $\pi \models \phi$

$$\langle [\mathtt{x} \mapsto 6, \mathtt{y} \mapsto 3], \mathtt{x} := \mathtt{y}; \; \mathtt{assert} \; (\mathtt{x} = 3) \rangle$$

$$\longrightarrow^*$$

$$\langle [\mathtt{x} \mapsto 3, \mathtt{y} \mapsto 3], \mathtt{skip} \rangle$$

Syntax

 $s \in Stmt$

 $\phi \in \text{Formula}$

Program State

 $\pi \in \mathsf{PROGRAMSTATE}$

Semantics

Static $\vdash \{\phi\} \ s \ \{\phi\}$

Dynamic $\pi \longrightarrow \pi$

Formula $\pi \models \phi$

$$\langle [x \mapsto 3], s \rangle \vDash (x = 3)$$

 $\langle [x \mapsto 4, y \mapsto 4], s \rangle \vDash (y = x)$

Syntax

 $s \in Stmt$

 $\phi \in \text{Formula}$

Program State

 $\pi \in \mathsf{PROGRAMSTATE}$

Semantics

Static
$$\vdash \{\phi\} \ s \ \{\phi\}$$

Dynamic $\pi \longrightarrow \pi$

Formula $\pi \models \phi$

$$\overline{\vdash \{\phi\} \text{ skip } \{\phi\}}$$
 HSKIP

$$\vdash \{\phi[e/x]\}\ x := e\ \{\phi\}$$
 HASSIGN

$$\frac{\phi \Rightarrow \phi_a}{\vdash \{\phi\} \text{ assert } \phi_a \{\phi\}} \text{ HASSERT}$$

$$\frac{\phi_{q1} \Rightarrow \phi_{q2}}{\vdash \{\phi_p\} \ s_1 \ \{\phi_{q1}\} \ \vdash \{\phi_{q2}\} \ s_2 \ \{\phi_r\}} + \{\phi_p\} \ s_1; \ s_2 \ \{\phi_r\}$$
 HSEQ

Syntax

 $s \in STMT$

 $\phi \in \text{Formula}$

Program State

 $\pi \in \mathsf{PROGRAMSTATE}$

Semantics

Static $\vdash \{\phi\} \ s \ \{\phi\}$

Dynamic $\pi \longrightarrow \pi$

Formula $\pi \models \phi$

Soundness

Semantic validity of Hoare triples

$$\vDash \{\phi\} \ s \ \{\phi'\}$$

$$\stackrel{\mathsf{def}}{\Longleftrightarrow}$$

$$\forall \pi, \pi'. \ \pi \stackrel{s}{\longrightarrow} \pi' \land \pi \vDash \phi \implies \pi' \vDash \phi'$$

$$\vdash \{\phi\} \ s \ \{\phi'\}$$

$$\vDash \{\phi\} \ s \ \{\phi'\}$$
Soundness

Gradualization – Overview

Syntax

 $s \in Stmt$

 $\phi \in \text{Formula}$

Program State

 $\pi \in \mathsf{PROGRAMSTATE}$

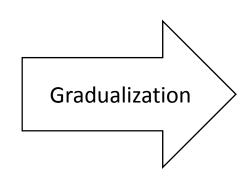
Semantics

Static $\vdash \{\phi\} \ s \ \{\phi\}$

Dynamic $\pi \longrightarrow \pi$

Formula $\pi \models \phi$

Soundness



Syntax

 $\widetilde{s} \in \widetilde{\mathbf{S}}$ TMT

 $\widetilde{\phi} \in \widetilde{F}ORMULA$

Program State

 $\widetilde{\pi} \in \widetilde{P}_{ROGRAM}STATE$

Semantics

Static $\widetilde{\vdash} \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi}\}$

Dynamic $\widetilde{\pi} \longrightarrow \widetilde{\pi}$

Formula $\widetilde{\pi} \stackrel{\sim}{\models} \widetilde{\phi}$

Gradualization – Approach

Syntax

 $s \in Stmt$

 $\phi \in \text{Formula}$

Program State

 $\pi \in \mathsf{PROGRAMSTATE}$

 $\widetilde{s} \in$

syntax extension

 $\widetilde{s} \in \widetilde{\mathbf{S}}\mathbf{TMT}$

Syntax

 $\widetilde{\phi} \in \widetilde{F}ORMULA$

Program State

 $\widetilde{\pi} \in \widetilde{\mathbf{P}}\mathbf{ROGRAMSTATE}$

Design Principles

Formula $\subset \widetilde{F}$ ormula

 $? \in \widetilde{F}ORMULA$

? ∉ Formula

Concrete Design

$$\widetilde{\phi} ::= \phi \mid ?$$

$$\gamma(\phi) = \{ \phi \}$$

$$\phi := \phi \mid \phi$$

$$\gamma(?) = \text{SATFORMULA}$$

$$\text{where} = ?\{ \overrightarrow{\phi} \mid \overrightarrow{\phi} \mid A \neq \emptyset \}$$

Gradualization – Approach

Syntax

 $s \in Stmt$

 $\phi \in \text{Formula}$

Program State

 $\pi \in \mathsf{PROGRAMSTATE}$

Syntax

 $\widetilde{s} \in \widetilde{\mathbf{S}} \mathbf{TMT}$

 $\widetilde{\phi} \in \widetilde{F}ORMULA$

Program State

 $\widetilde{\pi} \in \widetilde{\mathbf{P}}\mathbf{ROGRAMSTATE}$

Design Principles

Formula $\subset \widetilde{F}$ ormula

Concrete Design

$$\widetilde{\phi} ::= \phi \mid ? * \phi$$

$$\gamma(\phi) = \{ \phi \}$$

$$\gamma(?*\phi) = \{ \phi' \in \text{SatFormula} \mid \phi' \Rightarrow \phi \} \quad \text{if } \phi \in \text{SatFormula}$$

syntax extension

$$\gamma(?*\phi)$$
 undefined otherwise

Sidebar: Why Must? Be Satisfiable?

$$\gamma(\phi) = \{ \phi \}$$

$$\gamma(?*\phi) = \{ \phi' \in \text{SatFormula} \mid \phi' \Rightarrow \phi \} \quad \text{if } \phi \in \text{SatFormula}$$

$$\gamma(?*\phi) \quad \text{undefined otherwise}$$

- Should "? \land (x = 3)" imply "x = 2"?
 - Intuitively, no
 - But if we choose ? to be 0=1, the implication would (vacuously) hold
 - (x = 2) would be similarly problematic
 - Thus the completed formula must be satisfiable

Gradualization – Approach

Syntax

 $s \in Stmt$

 $\phi \in \text{Formula}$

Program State

 $\pi \in \mathsf{PROGRAMSTATE}$

syntax extension

syntax extension

Syntax

 $\widetilde{s} \in \widetilde{\mathbf{S}}_{\mathsf{TMT}}$

 $\widetilde{\phi} \in \widetilde{\mathrm{F}}$ ormula

Program State

 $\widetilde{\pi} \in \widetilde{\mathbf{P}}\mathbf{ROGRAMSTATE}$

Design Principles

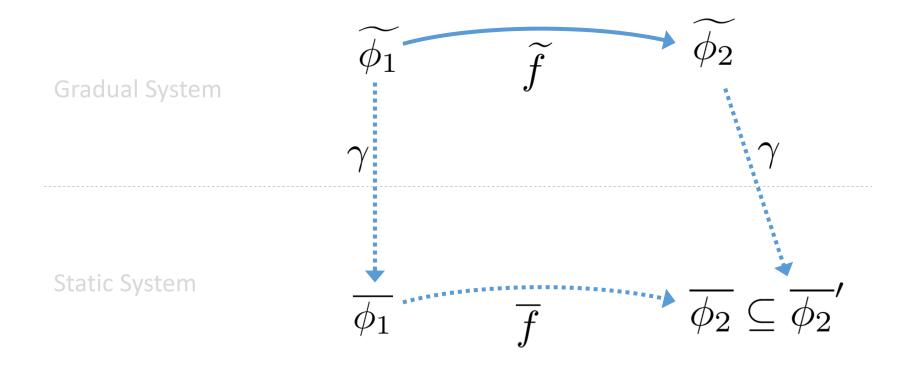
 $STMT \subseteq \widetilde{S}TMT$

Concrete Design

$$egin{aligned} \widetilde{s} &::= x := e \mid \text{assert } \widetilde{\phi} \mid \widetilde{s_1}; \ \widetilde{s_2} \ \gamma : \widetilde{\mathrm{S}}_{\mathrm{TMT}} & o \mathcal{P}^{\mathrm{S}_{\mathrm{TMT}}} \ \gamma (\text{assert } \widetilde{\phi}) = \{ \text{ assert } \phi \mid \phi \in \gamma(\widetilde{\phi}) \} \end{aligned}$$

...

Gradual Lifting



Gradualization – Approach

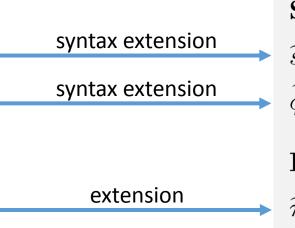
Syntax

 $s \in Stmt$

 $\phi \in \text{Formula}$

Program State

 $\pi \in PROGRAMSTATE$



Syntax

 $\widetilde{s} \in \widetilde{\mathrm{S}}_{\mathrm{TMT}}$

 $\widetilde{\phi} \in \widetilde{\mathrm{F}}$ ORMULA

Program State

 $\widetilde{\pi} \in \widetilde{\mathbf{P}}$ ROGRAMSTATE

Design Principles

PROGRAMSTATE

 \subseteq

PROGRAMSTATE

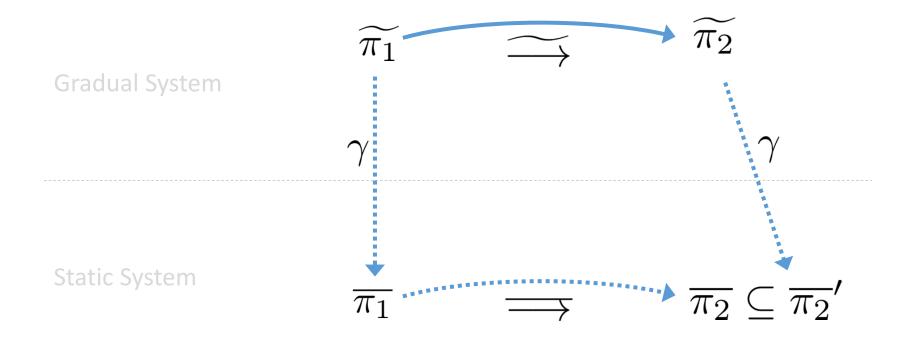
Concrete Design

PROGRAMSTATE =
$$(VAR \rightarrow N_0) \times STMT$$

$$\widetilde{P}_{ROGRAM}STATE = (VAR \rightharpoonup \mathbb{N}_0) \times \widetilde{S}_{TMT}$$

$$\gamma(\langle \sigma, \widetilde{s} \rangle) = \{\sigma\} \times \gamma(\widetilde{s})$$

Gradual Lifting



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Gradual Lifting

$$\begin{array}{c|c} \langle \sigma, \operatorname{assert} \ \phi_a \rangle \vDash \phi_a \\ \hline \langle \sigma, \operatorname{assert} \ \phi_a \rangle & \longrightarrow \langle \sigma, \operatorname{skip} \rangle \end{array} \widetilde{\operatorname{SsAssert1}} \quad \overline{\langle \sigma, \operatorname{assert} \ ? \rangle} \xrightarrow{} \langle \sigma, \operatorname{skip} \rangle \\ \hline \langle \sigma, \operatorname{assert} \ \phi_a \rangle & \longrightarrow \langle \sigma, \operatorname{skip} \rangle \\ \hline Gradual \, \operatorname{System} \qquad \qquad \gamma \\ \hline \\ Static \, \operatorname{System} \qquad \qquad \langle \sigma, \operatorname{assert} \ \phi_a \rangle & \longrightarrow \langle \sigma, \operatorname{assert} \ \phi_a \rangle \vDash \phi_a \\ \hline \langle \sigma, \operatorname{assert} \ \phi_a \rangle \vDash \phi_a \\ \hline \langle \sigma, \operatorname{assert} \ \phi_a \rangle \vDash \phi_a \\ \hline \langle \sigma, \operatorname{assert} \ \phi_a \rangle \vDash \phi_a \\ \hline \langle \sigma, \operatorname{assert} \ \phi_a \rangle = \langle \sigma, \operatorname{skip} \rangle \end{array} \widetilde{\operatorname{SsAssert2}}$$

Gradual Lifting

Gradual Verification - Approach

Syntax

 $s \in Stmt$

 $\phi \in \text{Formula}$

Program State

 $\pi \in PROGRAMSTATE$

Semantics

Static $\vdash \{\phi\} \ s \ \{\phi\}$

Dynamic $\pi \longrightarrow \pi$

Formula $\pi \models \phi$

Soundness

syntax extension

syntax extension

extension

predicate lifting function lifting

predicate lifting

Syntax

 $\widetilde{s} \in \widetilde{\mathbf{S}}$ TMT

 $\widetilde{\phi} \in \widetilde{F}ORMULA$

Program State

 $\widetilde{\pi} \in \widetilde{\mathbf{P}}_{\mathbf{ROGRAMSTATE}}$

Semantics

Static $\widetilde{\vdash} \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi}\}$

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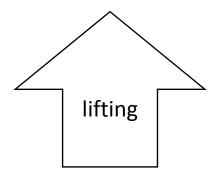
Dynamic $\widetilde{\pi} \longrightarrow \widetilde{\pi}$

Formula $\widetilde{\pi} \stackrel{\sim}{\models} \widetilde{\phi}$

Soundness

Predicate Lifting in a Nutshell

 $\widetilde{P} \subseteq \widetilde{\operatorname{Formula}} \times \widetilde{\operatorname{S}}$ tmt × $\widetilde{\operatorname{Formula}}$



 $P \subseteq \text{Formula} \times \text{Stmt} \times \text{Formula}$

Predicate Lifting in a Nutshell

all gradually lifted predicates satisfy

$$\frac{\phi_1 \in \gamma(\widetilde{\phi_1}) \qquad \phi_2 \in \gamma(\widetilde{\phi_2}) \qquad P(\phi_1, \phi_2)}{\widetilde{P}(\widetilde{\phi_1}, \widetilde{\phi_2})}$$

- $\cdot \models \cdot \subseteq PROGRAMSTATE \times FORMULA$
- $\cdot \stackrel{\sim}{\vdash} \cdot \subseteq \stackrel{\sim}{P}_{ROGRAMSTATE} \times \stackrel{\sim}{F}_{ORMULA}$

$$\langle [x \mapsto 3], s \rangle \vDash (x = 3)$$

$$\langle [x \mapsto 3], s \rangle \stackrel{\sim}{\vDash} (x = 3)$$

$$\langle [x \mapsto 3], s \rangle \stackrel{\sim}{\vDash} ?$$

Predicate Lifting in a Nutshell

all gradually lifted predicates satisfy

$$\frac{\phi_1 \in \gamma(\widetilde{\phi_1}) \qquad \phi_2 \in \gamma(\widetilde{\phi_2}) \qquad \phi_3 \in \gamma(\widetilde{\phi_3}) \qquad P(\phi_1, \phi_2, \phi_3)}{\widetilde{P}(\widetilde{\phi_1}, \widetilde{\phi_2}, \widetilde{\phi_3})}$$

Lifting Dynamic Semantics

- We borrow the idea of evidence from AGT
 - Intuitively, a witness for why a judgment holds, e.g.
 - The contents of variables witnesses a well-formed configuration
 - A pair of representative concrete formulas witnesses that one gradual formula can imply another

Want evidence for
$$?*(x = 4) \Rightarrow ?*(y = 3)$$

Example evidence:
$$\varepsilon_1 = \langle (x = 4) * (y = 3), (y = 3) \rangle$$

Want *most general* evidence – a valid piece of evidence that generalizes all others (e.g. pre- and post-states are implied by those of other valid evidence). The evidence above is the most general evidence for the example implication.

Lifting Dynamic Semantics

- We borrow the idea of evidence from AGT
 - Intuitively, a witness for why a judgment holds, e.g.
 - The contents of variables witnesses a well-formed configuration
 - A pair of representative concrete formulas witnesses that one gradual formula can imply another
- When program executes, we combine evidence
 - E.g. combine the evidence for the current program configuration with the evidence for the next statement, to yield the next program configuration
 - Or an error if the next program configuration is not wellformed – could happen if gradual spec was too approximate
 - Conveniently, combining evidence is equivalent to checking assertions in program text!

Optimization: Checking Residuals

- If we know some information statically, we may not need to verify all of an assertion
- We compute the residual of a run-time check
 - Assume we are checking ϕ_B and we know ϕ_A . Assume ϕ_B is in conjuctive normal form. Example:
 - $\phi_A = (x > 5)$
 - $\phi_B = (y > x \land y > 4)$
 - We remove any conjunct of ϕ_B that is implied by ϕ_A and the remaining conjuncts of ϕ_B .
- Example: residual is (y > x)
- Best case: static verification (ϕ_A implies ϕ_B)
 - All run-time checking is removed!

Some Theorems

(stated formally in our draft paper, but have not laid the groundwork here)

- Soundness: standard progress and preservation
 - Note: run-time errors may occur due to assertion failures
- Static gradual guarantee: if a program checks statically, it will still do so if the precision of its specifications is reduced
- Dynamic gradual guarantee: if a program executes without error, it will still do so if the precision of its specifications is reduced
- We get the last two "for free" based on the properties of abstract interpretation

Demonstration

http://olydis.github.io/GradVer/impl/HTML5wp/

The Challenge of Aliasing

```
\{(p1.age = 19) \land (p2.age = 19)\}\
p1.age++
\{(p1.age = 20) \land (p2.age = 19)\}
Not valid if p1 = p2!
```

Traditional Hoare Logic solution

$$\{(p1.age = 19) \land (p2.age = 19) \land p1 \neq p2\}$$

p1.age++
 $\{(p1.age = 20) \land (p2.age = 19) \land p1 \neq p2\}$

Issue: scalability. What if we have 4 pointers?

$$\{\ldots \land p1 \neq p2 \land p1 \neq p3 \land p1 \neq p4 \land p2 \neq p3 \land p2 \neq p4 \land p3 \neq p4\}$$

Alias information scales quadratically (n * n-1) with the number of pointer variables!

Implicit Dynamic Frames [Smans et al. 2009]

Implicit Dynamic Frames rules:

- acc(p1.age) denotes permission to access p1.age
- if p1.age is used in a formula, acc(p1.age) must appear earlier ('self-framing')
- acc(x.f) may only appear once for each object/field combination

```
{ P } S { Q } R is self-framed
{ P * R } S { Q * R }
```

• Example application

```
{ acc(p1.age) * p1.age = 19 * acc(p2.age) * p2.age = 19 }
p1.age++
{ /* what goes here? */ }
```

```
{ P * R } S { Q * R } R is self-framed
{ P * R } S { Q * R }
```

• Example application

```
p1.age++
{ /* what goes here? */ }
```

note: R is self-framed!

{ acc(p1.age) * p1.age = 19 * acc(p2.age) * p2.age = 19 }

• Example application

Apply the normal assignment rule

• Example application

```
{ acc(p1.age) * p1.age = 19 * acc(p2.age) * p2.age = 19 }
p1.age++
{ acc(p1.age) * p1.age = 20 * acc(p2.age) * p2.age = 19 }
```

Frame back on the rest of the formula

```
{ P * R } S { Q * R } R is self-framed
{ P * R } S { Q * R }
```

R is not self-framed.
Cannot apply the frame rule!

• Anti-example

```
{ acc(p1.age) * p1.age = 19 * p2.age = 19 } p1.age++ { /* what goes here? */ }
```

```
{ P * R } S { Q * R } R is self-framed
{ P * R } S { Q * R }
```

R is not self-framed.
Cannot apply the frame rule!

Anti-example

```
{ acc(p1.age) * p1.age = 19 * p2.age = 19 } p1.age++ { acc(p1.age) * p1.age = 20 }
```

The best we can do is drop the unframed information from the formula

Gradual Implicit Dynamic Frames

```
\{(p1.age = 19) \land (p2.age = 19)\}
p1.age++
                                          Not valid if p1 = p2!
\{(p1.age = 20) \land (p2.age = 19)\}
\{acc(p1.age) * acc(p2.age) * (p1.age = 19) * (p2.age = 19)\}
p1.age++
                                             OK! p1 and p2 may not overlap
\{acc(p1.age) * acc(p2.age) * (p1.age = 20) * (p2.age = 19)\}
{?*(p1.age = 19)*(p2.age = 19)}
p1.age++
                                        OK statically; requires run-time check
                                        Useful if you don't want to specify
{?*(p1.age = 20)*(p2.age = 19)}
                                        whether p1 and p2 alias:
                                        ? could be "acc(p1.age) && p1 = p2"
```

Consequences of Implicit Dynamic Frames

- Gradual types can help with self-framing
 - We can ignore frames just by writing "? $\land P$ " where P does not include acc(...)
 - Any invalid assumptions due to framing will be caught at run time
 - We can always add framing later
- Evidence: must track ownership of heap in the runtime
 - Allows for testing acc(x.f) in assertions
 - Of course, in statically verified code we can optimize this away!
- Residual testing gets more interesting. Example:
 - $\phi_A = (? \land x.f = 2)$
 - $\phi_B = (acc(x.f) \land x.f = 2 \land y = 5)$
 - Residual is y = 5
 - Don't need to check acc(x.f) because ? must include acc(x.f) for the x.f = 2 statement to be well-formed

Demonstration: Implicit Dynamic Frames

Gradual Verification

- Engineering approach to verification
 - Choose what properties & components to specify
- Support for unknown formulas ?
 - Model partly specified properties, components
 - Semantically: replace with anything that leaves the formula satisfiable
- Gradual Verification
 - Derived as an abstraction of static verification
 - Gradual guarantee: making formulas less precise will not cause compile-time or run-time failures
- Future work
 - Efficient implementation
 - Richer verification system