

Flare-On 4: Challenge 9 Solution

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Overview

This solution takes a couple of different approaches for solving the challenge. The first section covers how to solve the challenge using only static analysis with `radare2`. The second section covers dynamic analysis with `simavr` and the final section covers solving using an Arduino UNO.

Initial Analysis

This challenge is an ASCII file that each line starts with a colon character followed by HEX characters as shown in Figure 1. The file is an Intel HEX file, a file format that is commonly used to program microcontrollers. A detailed write-up on the Intel HEX file format can be found on Wikipedia¹.

```
:100000000C9462000C948A000C948A000C948A0070
:100010000C948A000C948A000C948A000C948A0038
:100020000C948A000C948A000C948A000C948A0028
:100030000C948A000C948A000C948A000C948A0018
<- truncated ->
```

Figure 1 - Intel HEX of `remorse_09.ino.hex`

Now that we know the challenge is an Intel HEX file, the first thing we'd like to do is convert the file to binary to see if we can extract any additional information. One way to accomplish this is to use `avr-objcopy` from `toolchain-avr`². `avr-objcopy` is a useful utility that converts between various file types such as binary, elf and Intel Hex. An example command line is shown in Figure 2.

```
avr-objcopy -I ihex -O binary remorse_09.ino.hex remorse_09.ino.bin
```

Figure 2 - `avr-objcopy` syntax

Once the challenge is converted to binary, we can run `strings` and get the results shown in Figure 3.

```
#+$+%+a
/_'1
Correct Pin State:
```

¹ https://en.wikipedia.org/wiki/Intel_HEX

² <https://github.com/arduino/toolchain-avr>

```
Flare-On 2017 Aduino UNO Digital Pin state:
```

Figure 3 - Strings output

Taking a look at the strings, we are provided with a hint indicating the challenge is for an Arduino UNO³ based on the string “Flare-On 2017 Aduino UNO Digital Pin state:”.

AVR Quick Overview

The Arduino UNO is built around an 8-bit ATmega328p processor that uses the Atmel AVR instruction set. The processor has 32 general purpose registers, labeled `r0-r31`, along with a few special registers we need to be aware of: stack pointer (`SP`), status register (`SREG`) and program counter (`PC`).

Register labels	Description
<code>r0-r31</code>	General purpose registers
<code>SP</code>	Stack pointer
<code>PC</code>	Program counter
<code>SREG</code>	Status register
<code>x</code>	Memory access register based on <code>r27:r26</code>
<code>y</code>	Memory access register based on <code>r29:r28</code>
<code>z</code>	Memory access register based on <code>r31:r30</code>

Table 1 - AVR registers of interest

The ATmega328p processor equipped with 2KB of SRAM. To overcome the limitation of referencing memory with only an 8-bit register, the processor has three special registers that combine two general purpose registers (`x`, `y` and `z` from Table 1). These registers have an interesting property in which they can be incremented or decremented after accessing. Take for example the instruction “`ld r25, z+`”. This instruction loads the value stored at the memory address pointed to by the `z` register (`r31:r30`) into `r25` and then increments the value contained in `z`.

³ <https://store.arduino.cc/usa/arduino-uno-rev3>

Another important property of the ATmega328p is that it uses a modified Harvard architecture, meaning data and code are stored in different memory locations (Flash for code and SRAM for data). For example, the data stored at memory location 0x500, is not the same as the code located at address 0x500.

When calling functions, the arguments to the function are placed in the registers starting with r25 down through r8. The registers containing a function return value depends on the data type. Bytes are stored in r24, words in registers 25:24, 32-bits in r22-r25 and 64-bit in r18-r25⁴.

Static Analysis with Radare2

For static analysis, the one way to get started is radare2⁵. Radare2 is an open source reverse engineering framework that supports a wide range of architectures, file formats and operating systems. The challenge can be loaded into radare2 using the command line `r2 -a avr remorse.bin` and initial analysis can be performed using the `aaaaa` command. The output is shown in Figure 4.

```
[0x000000c4]> aaaaa
[opcode st @de returned 0 cycles.th sym. and entry0 (aa)
[x] Analyze all flags starting with sym. and entry0 (aa)
[ ]
[Value from 0x00000000 to 0x00001156
aav: from 0x0 to 0x1156
[x] Analyze len bytes of instructions for references (aar)
[opcode lds @c12 returned 0 cycles.
opcode std @1b0 returned 0 cycles.
[x] Analyze function calls (aac)
[x] Emulate code to find computed references (aae)
[Cannot find section boundaries in here
[x] Analyze consecutive function (aat)
[x] Constructing a function name for fcn.* and sym.func.* functions (aan)
[x] Type matching analysis for all functions (afta)
```

Figure 4: Initial analysis using r2

The `afl` command lists the functions identified by radare2. The results are shown in Figure 5. We can see that 29 functions are identified and the entry point is labeled `entry0`.

```
[0x000000c4]> afl
0x000000c4 12 3108 -> 84 entry0
0x000001d8 1 24 fcn.000001d8
0x000001f0 3 20 fcn.000001f0
0x000002ce 4 66 fcn.000002ce
0x000003e2 5 20 -> 24 fcn.000003e2
```

⁴ http://www.atmel.com/webdoc/avrilibreferencemanual/FAQ_1faq_reg_usage.html

⁵ <http://rada.re/r/>

0x000003f6	18	82		fcn.000003f6
0x00000448	7	82		fcn.00000448
0x0000049a	9	96		fcn.0000049a
0x000004fa	9	120		fcn.000004fa
0x00000572	1	26	-> 64	fcn.00000572
0x00000596	3	38		loc.00000596
0x000005bc	6	116		fcn.000005bc
0x00000630	5	6	-> 208	fcn.00000630
0x0000063a	5	42		fcn.0000063a
0x00000664	1	40		fcn.00000664
0x0000068c	11	170		fcn.0000068c
0x00000736	1	4		fcn.00000736
0x0000087e	6	46		fcn.0000087e
0x000008ac	3	58		fcn.000008ac
0x000008e6	6	92		fcn.000008e6
0x00000942	7	40	-> 60	fcn.00000942
0x0000096a	9	118	-> 132	fcn.0000096a
0x000009e0	8	140		fcn.000009e0
0x00000a6c	9	212		fcn.00000a6c
0x00000b40	5	94		fcn.00000b40
0x00000bf8	2	138	-> 148	fcn.00000bf8
0x00000c8c	5	68		fcn.00000c8c
0x00000cd0	1	12		fcn.00000cd0
0x00000cdc	3	12	-> 14	fcn.00000cdc

Figure 5: Functions identified by r2

Let's take a closer look at the entry point by disassembling it with the command `pd @ entry0`. In Figure 6, we can see `entry0` initializing memory starting at addresses `0xdc` with the `lpm` instruction. The `lpm` instruction loads a byte from program memory and stores it to data memory.

```
[0x00000c4]> pd @ entry0
/ (fcn) entry0 84
|   entry0 ();
|           ; JMP XREF from 0x00000000 (fcn.000003e2)
|           0x000000c4    1124      clr r1
|           0x000000c6    1fbc      out 0x3f, r1    ;IO SREG: flags
|           0x000000c8    cfef      ser r28
|           0x000000ca    d8e0      ldi r29, 0x08
|           0x000000cc    debf      out 0x3e, r29  ;IO SPH: Stack higher bits SP8-SP10
|           0x000000ce    cdbf      out 0x3d, r28  ;IO SPL: Stack lower bits SP0-SP7
|           0x000000d0    15e0      ldi r17, 0x05
|           0x000000d2    a0e0      ldi r26, 0x00
|           0x000000d4    b1e0      ldi r27, 0x01
|           0x000000d6    eaae      ldi r30, 0xea
|           0x000000d8    fce0      ldi r31, 0x0c
|           ,=< 0x000000da    02c0      rjmp 0xe0
|           .--> 0x000000dc    0590      lpm r0, z+
|           || 0x000000de    0d92      st x+, r0
|           !!           ; JMP XREF from 0x000000da (entry0)
```

```

|      | \--> 0x000000e0      ac36      cpi r26, 0x6c
|      | 0x000000e2      b107      cpc r27, r17
|      | \==< 0x000000e4      d9f7      brne 0xdc
|      |      0x000000e6      26e0      ldi r18, 0x06
|      |      0x000000e8      ace6      ldi r26, 0x6c
|      |      0x000000ea      b5e0      ldi r27, 0x05
|      | ,=< 0x000000ec      01c0      rjmp 0xf0
|      | .--> 0x000000ee      1d92      st x+, r1
|      | !!      ; JMP XREF from 0x000000ec (entry0)
|      | \--> 0x000000f0      ac32      cpi r26, 0x2c
|      | 0x000000f2      b207      cpc r27, r18
|      | \==< 0x000000f4      e1f7      brne 0xee
|      |      0x000000f6      10e0      ldi r17, 0x00
|      |      0x000000f8      c2e6      ldi r28, 0x62
|      |      0x000000fa      d0e0      ldi r29, 0x00
|      | ,=< 0x000000fc      ~ 04c0      rjmp 0x106
|      | |      ;-- r30:
|      | |      0x000000fd      c0      unaligned
|      | .--> 0x000000fe      ~ 2197      sbiw r28, 0x01
|      | ||      ;-- r1:
|      | ||      ;-- r8:
|      | ||      0x000000ff      97      unaligned
|      | ||      0x00000100      fe01      movw r30, r28
|      | ||      0x00000102      0e946806      call fcn.00000cd0
|      | !!      ; JMP XREF from 0x000000fc (entry0)
|      | \--> 0x00000106      c136      cpi r28, 0x61
|      | 0x00000108      d107      cpc r29, r17
|      | \==< 0x0000010a      c9f7      brne 0xfe
|      |      0x0000010c      0e94fc05      call fcn.00000bf8
|      | ,=< 0x00000110      0c947306      jmp 0xce6

```

Figure 6 – Disassembly of entry point function entry0

Notice two functions are called from entry0: fcn.00000cd0 and fcn.00000bf8. Taking a closer look at fcn.00000bf8, disassembly shown in Figure 7, we can see some initial processor setup by configuring timers and at the end of the function there is an infinite loop calling two functions fcn.00000b40 and fcn.000003e2.

```

[0x000000c4]> pd @ fcn.00000bf8
/ (fcn) fcn.00000bf8 148
|      fcn.00000bf8 ();
|      ; CALL XREF from 0x0000010c (entry0)
|      0x00000bf8      7894      sei
|      0x00000bfa      84b5      in r24, 0x24 ; IO TCNT2: Timer/Counter2 (8 bits).
|      0x00000bfc      8260      ori r24, 0x02
|      0x00000bfe      84bd      out 0x24, r24 ; IO TCNT2: Timer/Counter2 (8 bits).
|      0x00000c00      84b5      in r24, 0x24 ; IO TCNT2: Timer/Counter2 (8 bits).
|      0x00000c02      8160      ori r24, 0x01
|      0x00000c04      84bd      out 0x24, r24 ; IO TCNT2: Timer/Counter2 (8 bits).
|      0x00000c06      85b5      in r24, 0x25 ; IO TCCR2: Timer/Counter2 Control
|      Register (8 bits).
|      0x00000c08      8260      ori r24, 0x02

```

```

|           0x0000c0a      85bd           out 0x25, r24 ; IO TCCR2: Timer/Counter2 Control
Register (8 bits).
|           0x0000c0c      85b5           in r24, 0x25 ; IO TCCR2: Timer/Counter2 Control
Register (8 bits).
|           0x0000c0e      8160           ori r24, 0x01
|           0x0000c10      85bd           out 0x25, r24 ; IO TCCR2: Timer/Counter2 Control
Register (8 bits).
<...>
|           0x0000c76      80937a00       sts 0x7a, r24
|           0x0000c7a      1092c100       sts 0xc1, r1
\          0x0000c7e      0e945604       call fcn.000008ac
|                                     ; JMP XREF from 0x0000c8a (fcn.00000bf8)
|           .-> 0x0000c82      0e94a005       call fcn.00000b40
|           | 0x0000c86      0e94f101       call fcn.000003e2
|           `=< 0x0000c8a      fbcf           rjmp 0xc82

```

Figure 7 - Disassembly of function `fcn.00000bf8`

Inspecting the disassembly of `fcn.00000b40`, shown in Figure 8, we can see a call to another function `fcn.0000087e` at address `0xb42`. The code at address `0xb4c` compares the return value from this function with a value stored in memory at address `0x585`. If the values are different, the challenge continues executing through address `0xb50`. At this point we don't know what `fcn.0000087e` does but we do know the return value significantly affects program flow. Looking further down in the function, we can see the return value is passed as a single argument to the function `fcn.00000a6c` at offset `0xb7c`.

```

[0x000000c4]> pd @ fcn.00000b40
/ (fcn) fcn.00000b40 94
|   fcn.00000b40 ();
|   !           ; CALL XREF from 0x0000c82 (fcn.00000bf8)
|   |           | 0x0000b40      cf93           push r28
|   |           | 0x0000b42      0e943f04       call fcn.0000087e
|   |           | 0x0000b46      c82f           mov r28, r24
|   |           | 0x0000b48      80918505       lds r24, 0x585
|   |           | 0x0000b4c      c817           cp r28, r24
|   |           ,==< 0x0000b4e      01f1           breq 0xb90
|   |           || 0x0000b50      60910005       lds r22, 0x500
|   |           || 0x0000b54      70910105       lds r23, 0x501
|   |           || 0x0000b58      8fe8           ldi r24, 0x8f
|   |           || 0x0000b5a      95e0           ldi r25, 0x05
|   |           || 0x0000b5c      0e949b03       call fcn.00000736
|   |           || 0x0000b60      42e0           ldi r20, 0x02
|   |           || 0x0000b62      50e0           ldi r21, 0x00
|   |           || 0x0000b64      6c2f           mov r22, r28
|   |           || 0x0000b66      8fe8           ldi r24, 0x8f
|   |           || 0x0000b68      95e0           ldi r25, 0x05
|   |           || 0x0000b6a      0e944603       call fcn.0000068c
|   |           || 0x0000b6e      64e2           ldi r22, 0x24
|   |           || 0x0000b70      75e0           ldi r23, 0x05

```

```

|      | 0x0000b72 8fe8      ldi r24, 0x8f
|      | 0x0000b74 95e0      ldi r25, 0x05
|      | 0x0000b76 0e943203  call fcn.00000664
|      | 0x0000b7a 8c2f      mov r24, r28
|      | 0x0000b7c 0e943605  call fcn.00000a6c
|      | 0x0000b80 0197      sbiw r24, 0x01
|      | ,==< 0x0000b82 21f0      breq 0xb8c
|      | ||| 0x0000b84 60e0      ldi r22, 0x00
|      | ||| 0x0000b86 8de0      ldi r24, 0x0d
|      | ||| 0x0000b88 0e944d02  call fcn.0000049a
|      | \---> 0x0000b8c c0938505  sts 0x585, r28
|      | \--> 0x0000b90 68ee      ldi r22, 0xe8
|      | | 0x0000b92 73e0      ldi r23, 0x03
|      | | 0x0000b94 80e0      ldi r24, 0x00
|      | | 0x0000b96 90e0      ldi r25, 0x00
|      | | 0x0000b98 cf91      pop r28
|      | \< 0x0000b9a 0c94de02  jmp fcn.000005bc
|
| [0x00000c4]>

```

Figure 8 - Disassembly of function fcn.00000b40

After inspecting function fcn.00000a6c, we can see the function starts by initializing the stack at address 0xa74 by decrementing the value obtained from the SPH register (the higher 8 bits of the stack pointer) by one and storing the result back with the instruction at address 0xa7a. The disassembly for fcn.00000a6c is shown in Figure 9.

```

[0x0000a6c]> pdf @fcn.00000a6c
/ (fcn) fcn.00000a6c 212
|   fcn.00000a6c ();
|       ; CALL XREF from 0x0000b7c (fcn.00000b40)
|   0x0000a6c  cf93      push r28
|   0x0000a6e  df93      push r29
|   0x0000a70  cdb7      in r28, 0x3d ; IO SPL: Stack lower bits SP0-SP7
|   0x0000a72  deb7      in r29, 0x3e ; IO SPH: Stack higher bits SP8-SP10
|   0x0000a74  da95      dec r29
|   0x0000a76  0fb6      in r0, 0x3f ; IO SREG: flags
|   0x0000a78  f894      cli
|   0x0000a7a  debf      out 0x3e, r29 ; IO SPH: Stack higher bits SP8-SP10
|   0x0000a7c  0fbe      out 0x3f, r0 ; IO SREG: flags
|   0x0000a7e  cdbf      out 0x3d, r28 ; IO SPL: Stack lower bits SP0-SP7
|   0x0000a80  fe01      movw r30, r28
|   0x0000a82  3196      adiw r30, 0x01
|   0x0000a84  df01      movw r26, r30
|   0x0000a86  9fef      ser r25
|   0x0000a88  9e0f      add r25, r30
|       ; JMP XREF from 0x0000a8e (fcn.00000a6c)
|   .-> 0x0000a8a  1d92      st x+, r1
|   ,==< 0x0000a8c  9a13      cpse r25, r26
|   |`< 0x0000a8e  fdcf      rjmp 0xa8a

```

Figure 9 - Allocating space on the stack

At address 0xa90, shown in Figure 10, we can see bytes being placed into a local variable in what appears to be populating a stack string.

```

|--> 0x0000a90 95eb ldi r25, 0xb5
      0x0000a92 9983 std y+1, r25
      0x0000a94 9a83 std y+2, r25
      0x0000a96 96e8 ldi r25, 0x86
      0x0000a98 9b83 std y+3, r25
      0x0000a9a 94eb ldi r25, 0xb4
      0x0000a9c 9c83 std y+4, r25
      0x0000a9e 94ef ldi r25, 0xf4
      0x0000aa0 9d83 std y+5, r25
      0x0000aa2 93eb ldi r25, 0xb3
      0x0000aa4 9e83 std y+6, r25
      0x0000aa6 91ef ldi r25, 0xf1
      0x0000aa8 9f83 std y+7, r25
      0x0000aaa 20eb ldi r18, 0xb0
      0x0000aac 2887 std y+8, r18
      0x0000aae 2987 std y+9, r18
      0x0000ab0 9a87 std y+10, r25
      0x0000ab2 9dee ldi r25, 0xed
      0x0000ab4 9b87 std y+11, r25
      0x0000ab6 90e8 ldi r25, 0x80
      0x0000ab8 9c87 std y+12, r25
      0x0000aba 9beb ldi r25, 0xbb
      0x0000abc 9d87 std y+13, r25
      0x0000abe 9fe8 ldi r25, 0x8f
      0x0000ac0 9e87 std y+14, r25
      0x0000ac2 9feb ldi r25, 0xbf
      0x0000ac4 9f87 std y+15, r25
      0x0000ac6 9de8 ldi r25, 0x8d
      0x0000ac8 988b std y+16, r25
      0x0000aca 96ec ldi r25, 0xc6
      0x0000acc 998b std y+17, r25
      0x0000ace 95e8 ldi r25, 0x85
      0x0000ad0 9a8b std y+18, r25
      0x0000ad2 97e8 ldi r25, 0x87
      0x0000ad4 9b8b std y+19, r25
      0x0000ad6 90ec ldi r25, 0xc0
      0x0000ad8 9c8b std y+20, r25
      0x0000ada 94e9 ldi r25, 0x94
      0x0000adc 9d8b std y+21, r25
      0x0000ade 91e8 ldi r25, 0x81
      0x0000ae0 9e8b std y+22, r25
      0x0000ae2 9ce8 ldi r25, 0x8c
      0x0000ae4 9f8b std y+23, r25
      0x0000ae6 ace6 ldi r26, 0x6c
      0x0000ae8 b5e0 ldi r27, 0x05
      0x0000aea 20e0 ldi r18, 0x00

```

Figure 10 - Initializing stack string

After the local variable is initialized, we can see a loop that is loading a byte from the stack variable at

address `0xae6`. This loop is shown in Figure 11. The byte is XORed with the function argument stored in register `r24` and the loop index counter is added to it. The result is stored in data memory starting at address `0x56c` (the `x` register is set at address `0xae6`).

	0x0000ae6	ace6	ldi r26, 0x6c
	0x0000ae8	b5e0	ldi r27, 0x05
	.-> 0x0000aec	9191	ld r25, z+
	0x0000aee	9827	eor r25, r24
	0x0000af0	920f	add r25, r18
	0x0000af2	9d93	st x+, r25
	0x0000af4	2f5f	subi r18, 0xff
	0x0000af6	2731	cpi r18, 0x17
	`=< 0x0000af8	c9f7	brne 0xae6

Figure 11 - Decode loop

Once the loop completes, the challenge compares the value stored at memory address `0x576` with the byte value `0x40` ('@'). Being this far along in the Flare-On challenge, seeing a check for this character should be very interesting to us.

At this point we've identified a stack string, decoding loop and sanity check. The next step is to determine a value for the key, the first argument to the function, that results in a '@' character in memory location `0x576`. After recreating the stack variable, we get the value shown in Figure 12.

```
\xb5\xb5\x86\xb4\xf4\xb3\xf1\xb0\xb0\xf1\xed\x80\xbb\x8f\xbf\x8d\xc6\x85\x87\xc0\x94\x81\x8c
```

Figure 12 - Stack string

We are interested in getting the 10th byte (`0xED`) to equal `0x40`. The offset 10 is calculated by subtracting the start of the string `0x56c` with `0x576`, the address of the sanity check character '@'. A simple solution is to brute force all values for the key (`r24`) because the key space is limited to only 256 possible keys (8-bit processor). A sample script is shown in Figure 13.

```
ctext =
bytearray("\xb5\xb5\x86\xb4\xf4\xb3\xf1\xb0\xb0\xf1\xed\x80\xbb\x8f\xbf\x8d\xc6\x85\x87\xc0\x94\x81\x8c")

def decrypt(ctext, key):
    rvalue = bytearray()

    for x in range(len(ctext)):
        rvalue.append(((ctext[x] ^ key) + x) & 0xff)
    return str(rvalue)
```

```

for x in range(255):
    r = decrypt(ctext, x)

    if r[0x0a] == '@':
        print "Decrypt key: 0x%02X" % x
        print "Plaintext: %s" % r
        break

```

Figure 13 - Example brute force script

The output from running the script in Figure 13 shows the decryption key is 0xDB and the decoded string is no_r3m0rs3@flare-on.com. An alternative to brute force would involve subtracting the index (0x0A) with the plaintext character 0x40 ('@') and XORing the encrypted text (0xED) to get the key (0x40 - 0x0A ^ 0xED = 0xDB).

Dynamic Analysis with Simavr

Another approach to solving the Arduino challenge is to use the GDB functionality included in `simavr`⁶. `Simavr` is an open source AVR simulator that enables us to execute and debug without any of the hardware. `Simavr` also supports executing Intel HEX file. The challenge can be executed with the command line shown in Figure 14.

```
run_avr -m atmega328p -f 160000000 --gdb remorse_09.ino.hex
```

Figure 14 - Example `run_avr` command line

After `simavr` loads, it pauses waiting for a remote debugger to attach to it.

```

GNU gdb (GDB) 7.10.1
(gdb) target remote :1234
Remote debugging using :1234
0x00000000 in ?? ()
(gdb)

```

As seen in Figure 15, we set a breakpoint at 0xb48, where the return of `fcn.0000087e` is compared with the value stored in memory at 0x585. One thing to be aware of with `avr-gdb` and `simavr` is that setting breakpoints using the instruction address (`break *addr`) does not work. This is possibly a result of a bug or configuration issue. There are a couple solutions to this problem. The first option is to set the breakpoint relative to the `pc` register using the command format `break * $pc + <addr>`. This is the easiest solution when starting analysis because the program counter is set to zero. Another workaround is to treat the address as a function pointer using the format `break *(void(*)()) <addr>`.

⁶ <https://github.com/buserror/simavr>

```
(gdb) break * $pc + 0xb48
Breakpoint 1 at 0xb48
(gdb) c
Continuing.
```

Figure 15 - Example breakpoint

Once the breakpoint hits, we can inspect the register `r28` to see the return value of `fcn.0000087e` is `0xFF`. We can also show the value stored at address `0x585` that the return value is compared against. An example is shown in Figure 16.

```
Breakpoint 1, 0x00000b48 in ?? ()
(gdb) info reg $r28
r28                0xff
(gdb) x/u 0x585
0x800585: 0
```

Figure 16 – Inspecting the return value of `fcn.0000087e`

Knowing register `r28` and the value stored at memory address `0x585` are different, the branch at address `0xb4e` will not be taken. The next portion of interest are the instructions at addresses `0xb50` and `0xb54` that load bytes from memory addresses `0x500` and `0x501`. These registers are then passed as arguments to the function call `fcn.00000736` at address `0xb5c` as shown in Figure 17.

```
[0x000000c4]> pd @ fcn.00000b40
/ (fcn) fcn.00000b40 94
|   fcn.00000b40 ();
|   !           ; CALL XREF from 0x00000c82 (fcn.00000bf8)
|   |           0x00000b40    cf93          push r28
|   |           0x00000b42    0e943f04    call fcn.0000087e
|   |           0x00000b46    c82f        mov r28, r24
|   |           0x00000b48    80918505    lds r24, 0x585
|   |           0x00000b4c    c817        cp r28, r24           ; Return value (key)
|   |           ,==< 0x00000b4e    01f1        breq 0xb90
|   ||          0x00000b50    60910005    lds r22, 0x500       ; Loading memory address
|   ||          0x00000b54    70910105    lds r23, 0x501       ; Loading memory address
|   ||          0x00000b58    8fe8        ldi r24, 0x8f
|   ||          0x00000b5a    95e0        ldi r25, 0x05
|   ||          0x00000b5c    0e949b03    call fcn.00000736
```

Figure 17 - Argument for `fcn.00000736`

The two bytes stored in memory at address `0x500` is a pointer to a string at address `0x53e` (shown in Figure 18). The string at address `0x53e` is "Flare-On 2017 Arduino UNO Digital Pin state:". Recall that the ATmega328P is an 8-bit processor that requires two registers to store a pointer.

```
Breakpoint 1, 0x00000b48 in ?? ()
(gdb) x/2bx 0x500
0x800500: 0x3e 0x05
(gdb) x/s 0x53e
0x80053e: "Flare-On 2017 Aduino UNO Digital Pin state:"
```

Figure 18 - Identifying argument to fcn.00000736

At this point if we continue execution we will see the emulator displays the output shown in Figure 19.

```
Flare-On 2017 Aduino UNO Digital Pin state:11111111..
```

Figure 19 - Emulator output

Now we have a general idea function `fcn.00000736` is likely responsible for printing the string "Flare-On 2017 Aduino UNO Digital Pin state:" to the serial port, the function `fcn.0000068c` prints the digital pin state and the function `fcn.0000087e` obtains the digital pin state. This leads to the indication that `fcn.00000a6c`, which takes the digital pin state as the only argument, is the function we should focus on to solve the challenge.

```
[0x000000c4]> pd @ fcn.00000b40
/ (fcn) fcn.00000b40 94
| fcn.00000b40 ();
| ! ; CALL XREF from 0x00000c82 (fcn.00000bf8)
| | 0x00000b40 cf93 push r28
| | 0x00000b42 0e943f04 call fcn.0000087e
| | 0x00000b46 c82f mov r28, r24 ; Possible as return value
| | 0x00000b48 80918505 lds r24, 0x585
| | 0x00000b4c c817 cp r28, r24
| | ,==< 0x00000b4e 01f1 breq 0xb90
| | | 0x00000b50 60910005 lds r22, 0x500
| | | 0x00000b54 70910105 lds r23, 0x501 ; Pointer to "Flare-On 2017..."
| | | 0x00000b58 8fe8 ldi r24, 0x8f
| | | 0x00000b5a 95e0 ldi r25, 0x05
| | | 0x00000b5c 0e949b03 call fcn.00000736 ; print to serial
| | | 0x00000b60 42e0 ldi r20, 0x02
| | | 0x00000b62 50e0 ldi r21, 0x00
| | | 0x00000b64 6c2f mov r22, r28 ; Possible key passed as arg
| | | 0x00000b66 8fe8 ldi r24, 0x8f
| | | 0x00000b68 95e0 ldi r25, 0x05
| | | 0x00000b6a 0e944603 call fcn.0000068c ; print pin state
| | | 0x00000b6e 64e2 ldi r22, 0x24
| | | 0x00000b70 75e0 ldi r23, 0x05
| | | 0x00000b72 8fe8 ldi r24, 0x8f
| | | 0x00000b74 95e0 ldi r25, 0x05
| | | 0x00000b76 0e943203 call fcn.00000664
| | | 0x00000b7a 8c2f mov r24, r28 ; Possible key passed as arg
| | | 0x00000b7c 0e943605 call fcn.00000a6c ; Function of interest
| | | 0x00000b80 0197 sbiw r24, 0x01
| | | ,===< 0x00000b82 21f0 breq 0xb8c
```

```

|      ||| 0x00000b84    60e0    ldi r22, 0x00
|      ||| 0x00000b86    8de0    ldi r24, 0x0d
|      ||| 0x00000b88    0e944d02 call fcn.0000049a
|      |--> 0x00000b8c    c0938505 sts 0x585, r28
|      |--> 0x00000b90    68ee    ldi r22, 0xe8
|      | 0x00000b92    73e0    ldi r23, 0x03
|      | 0x00000b94    80e0    ldi r24, 0x00
|      | 0x00000b96    90e0    ldi r25, 0x00
|      | 0x00000b98    cf91    pop r28
|      |<= 0x00000b9a    0c94de02 jmp fcn.000005bc
|
|[0x000000c4]>

```

Figure 20 - Disassembly with annotations

At this point, we have a couple options to get to a solution. One option is to brute force using the debugger to set the digital pin state and the other is to do static analysis of the function shown in the above section. Since we are reverse engineers, let's assume we chose the latter and determined the key is 0xdb. We can set another breakpoint at 0xafc after the decoding loop to verify the results (Figure 21).

```

(gdb) info reg $r28
r28      0xff
(gdb) set $r28=0xdb
(gdb) info reg $r28
r28      0xdb
(gdb) break *(void(*)()) 0xafc
Breakpoint 2 at 0xafc
(gdb) c
Continuing.

```

Figure 21 - Setting breakpoint on decoding validation

Once the breakpoint at 0xafc hits, we can see the instructions at addresses 0xae6 and 0xae8 are setting the x register to 0x56c in Figure 22.

```

|      0x00000ae6    ace6    ldi r26, 0x6c ; Low byte of x register
|      0x00000ae8    b5e0    ldi r27, 0x05 ; High byte of x register
|      0x00000aea    20e0    ldi r18, 0x00
|      .-> 0x00000aec    9191    ld r25, z+
|      | 0x00000aee    9827    eor r25, r24
|      | 0x00000af0    920f    add r25, r18
|      | 0x00000af2    9d93    st x+, r25
|      | 0x00000af4    2f5f    subi r18, 0xff
|      | 0x00000af6    2731    cpi r18, 0x17
|      |<= 0x00000af8    c9f7    brne 0xaec
|      0x00000afa    80917605 lds r24, 0x576
|      0x00000afe    8034    cpi r24, 0x40 ; Validate results

```

Figure 22 - Setting the x register for decoding loop

Now we can dump the decoded key from memory using the gdb command `x/s 0x56c` and see the key `no_r3m0rs3@flare-on.com`, as shown in Figure 23.

```
Breakpoint 4, 0x00000afe in ?? ()
(gdb) x/s 0x56c
0x80056c: "no_r3m0rs3@flare-on.com"
```

Figure 23 - Displaying key from `simavr`

Executing on Arduino UNO

This section covers how to load and solve the challenge on a genuine Arduino UNO. There are many clones of Arduino hardware and different boot loaders available that may not program correctly using these instructions. If you choose to test this challenge on an Arduino UNO, make sure you are testing on a genuine Arduino UNO with the default bootloader installed.

To program the Arduino, we can use `avrdude` from the `toolchain-avr`. The easiest method to obtain the `avrdude` command line arguments for your environment is to use the Arduino IDE with verbose output. To enable verbose output, under `Preferences->Settings`, check `upload for Show verbose output during`. Then compile and upload a simple script to your Arduino. The output window will show the `avrdude` command line used to upload the script. An example command line is shown in Figure 24.

```
avrdude -C<conf path> -v -patmega328p -carduino -P<Arduino device> -b115200 -D -
Uflash:w:remorse_09.ino.hex:i
```

Figure 24 - Example `avrdude` to program Arduino UNO

Once the challenge is uploaded and running on the Arduino UNO, we can now use the serial monitor from the Arduino IDE to see the output shown in Figure 25 displayed by the challenge.

```
Flare-On 2017 Aduino UNO Digital Pin state:11111111
```

Figure 25 - Serial output from Arduino UNO

After connecting the digital pins two and five to ground, as shown in Figure 26, we can see the solution output in the serial monitor shown in Figure 27.

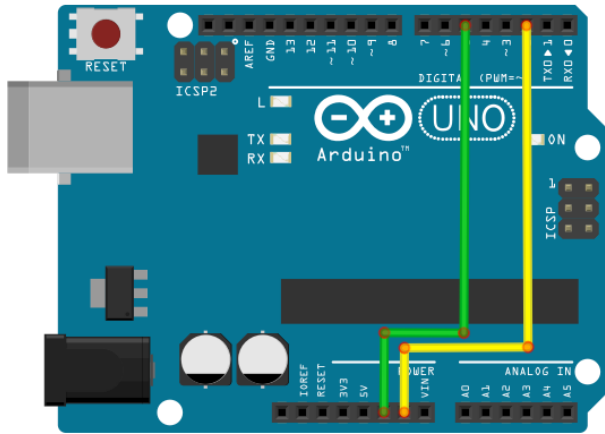


Figure 26 - Arduino UNO solution wiring diagram

```
Flare-On 2017 Adruino UNO Digital Pin state:11111111
Flare-On 2017 Adruino UNO Digital Pin state:11011111
Flare-On 2017 Adruino UNO Digital Pin state:11011011
Correct Pin State:
. . . . .
. . . . .
no_r3m0rs3@flare-on.com
```

Figure 27 - Arduino UNO solution serial monitor output